Lecture 18: Concolic Testing

17-355/17-665/17-819: Program Analysis

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Recap: Symbolic Execution

```
int x=0, y=0, z=0;

2 if(a) {

x = -2;

4 }

5 if (b < 5) {

z = 2;

z = 2;

8 }

Sug-finding of assert(Q):

\exists x : P \land \neg Q
```

line	g	$\mid E \mid$
0	true	$a \mapsto \alpha, b \mapsto \beta, c \mapsto \gamma$
1	true	$\ldots, x \mapsto 0, y \mapsto 0, z \mapsto 0$
2	$\neg \alpha$	$\ldots, x \mapsto 0, y \mapsto 0, z \mapsto 0$
5	$\neg \alpha \land \beta \geqslant 5$	$\ldots, x \mapsto 0, y \mapsto 0, z \mapsto 0$
9	$\neg \alpha \land \beta \geqslant 5 \land 0 + 0 + 0 \neq 3$	$ \ldots, x \mapsto 0, y \mapsto 0, z \mapsto 0$

Recap: Soundness and Completeness

- Soundness = "Doesn't lie" or "all claims are true"
- Completeness = "All truths are claimed"
- For Verification (claim is "program is correct")
 - Soundness: Reasoning along all possible paths (over-approximation)
- For Bug-Finding (claim is "a bug exists")
 - Soundness: Reasoning along feasible paths only (under-approximation)
- Soundness & Completeness is impossible in general (Rice's theorem)
 - Most systems are sound but incomplete (e.g. can't prove all programs, or can't find all bugs)

Recap: Bugs and Reachability

Common trick: convert error case into reachability problem

- assert(p) \rightarrow if(!p) **ERROR**;
- *x \rightarrow if(x == NULL) { **ERROR**; } return *x;
- $a[i] \rightarrow if(i < 0 \mid | i > a.length) {$ **ERROR** $; } return <math>a[i]$;

"Bug finding" is now just about finding inputs that execute every program path

Gotchas: Halting problem and infinite loops

```
int double (int v) {
        return 2*v;
    void bar(int x, int y) {
        z = double (y);
        if (z == x) {
            if (x > y+10) {
                  ERROR;
12
```

Exercise: Under what path constraints do we hit ERROR?

```
5  void bar(int x, int y) {
6     z = double (y);
7     if (z == x) {
8        if (x > y+10) {
9          ERROR;
10     }
11     }
12  }
```

Consider: What if we could not (or did not want to) analyze the external function?

```
5  void bar(int x, int y) {
6     z = double (y);
7     if (z == x) {
8        if (x > y+10) {
9          ERROR;
10      }
11     }
12  }
```

Consider: What if we could not (or did not want to) analyze the external function?

```
int foo(int v) {
        return v*v%50;
   void baz(int x, int y) {
        z = foo(y);
        if (z == x) {
            if (x > y+10) {
                  ERROR;
12
```

Consider: What if our solver cannot handle non-linear arithmetic or modulo?

```
int foo(int v) {
    return v*v%50;
void baz(int x, int y) {
    z = foo(y);
    if (z == x) {
        if (x > y+10) {
              ERROR;
```

Option 1: Set $\Sigma(z)$ to be a fresh symbolic var

Option 2: Set $\Sigma(z)$ to be a concrete value by "executing" foo(y) for some y that satisfies path constraint seen so far.

Exercise: How do these options differ in terms of under- or over-approximation? Recall: soundness/completeness or bug finding or verification

Concolic Execution (= Concrete + Symbolic)

- Instrument program to collect path constraints during concrete execution (concrete + symbolic store updates simultaneously)
- 2. Run program with concrete inputs (initially random) to collect path constraint *g*
 - Sanity check: Inputs should always be a valid solution to g
- 3. Negate last clause in g and solve for model
- 4. If SAT, then get satisfying assignment as new input and repeat from 2
- 5. If UNSAT, then pop off last clause and repeat from 3

```
int double (int v) {
        return 2*v;
    void bar(int x, int y) {
        z = double (y);
        if (z == x) {
            if (x > y+10) {
                  ERROR;
12
```

```
int double (int v) {
       return 2*v;
   void bar(int x, int y) {
       z = double (y);
    if (z == x) {
           if (x > y+10) {
                 ERROR;
12 }
```

- 1. Input: x=0, y=1
 - Path: (2*y != x)
 - Next: (2*y == x) :: SAT
- 2. Input: x=2, y=1
 - Path: (2*y == x) && (x <= y+10)
 - Next: (2*y == x) && (x > y+10) :: SAT
- 3. Input: x=22, y=11
 - Path: (2*y == x) && (x > y+10)
 - Bug found!!

Concolic Execution

- Key advantage: Always have a concrete input in parallel
- When constraint cannot be modeled (e.g. external function, features not handled by solver), **replace with concrete value**.
- **Soundness**: Concrete replacement is a true underapproximation

```
int foo(int v) {
        return v*v%50;
   void baz(int x, int y) {
        z = foo(y);
        if (z == x) {
            if (x > y+10) {
                  ERROR;
12 }
```

- 1. Input: x=22, y=7
 - Path: (49 != x). // y*y%50 = 49%50 = 49
 - Next: (49 == x) :: SAT
- 2. Input: x=49, y=7
 - Path: (49 == x) && (x > y+10)
 - Bug found!!

Concolic Path Condition Soundness

• When is substitution sound?

```
int foo(int v) {
        return v*v%50;
   void baz(int x, int y) {
        z = foo(y);
        if (z == x) {
            if (x > y+10) {
                  ERROR;
12 }
```

- 1. Input: x=0, y=8
 - Path: (14 != x) // y*y%50 = 64%50 = 14
 - Next: (14 == x) :: SAT
- 2. Input: x=14, y=8
 - Path: (14 == x) && (x <= y+10)
 - Next: (14 == x) && (x > y+10) :: SAT
- 3. Input: x=14, y=2
 - Path: (4 != x)
 - Unsoundness!

Popular Symbolic/Concolic Tools

- DART (Directed Automated Random Testing)
- CUTE (Concolic Unit Testing Engine)
- KLEE ("dynamic symbolic execution")
- SAGE (Scalable, Automated, Guided Execution aka "whitebox fuzzing
- Java PathFinder
- Angr
- PyExZ3
- Jalangi