

# Flight Loads: DroneVLA aircraft



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## Chapter 1. Introduction

This document defines the SUBPART C - Structure - Flight Loads of the:DroneVLA.The boundaries of the flight envelope will be defined within this document. All speeds are calibrated airspeeds (CAS) (requirement 4.4 [1])and given in knots if not stated otherwise.All other units used are metric (SI units).The weights are given in mass units (kg) but the formulas require force units as input,therefore these are calculated in place wherever they are used.Note: The speeds defined within this document should be used for the placards,speed markings, aeroplane flight manual (limitations), load calculations and need to be verified by flight test.

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## Chapter 2. References

1. ASTM F2245-12d," ASTM."ASTM F2245-12d, ASTM.
2. ABCD-FL-57-00 Wing Load Calculation, EASA.
3. ISO 2533:1975, International Standardization Organization, 1975.
4. CS-LSA Certification Specifications and Acceptable Means of Compliance, Amnd.1 29.Jul.2013, EASA, 2013.
5. "ABCD-FTR-01-00 Flight Test Report," EASA.
6. L. Smith, "NACA technical note 1945, 'Aerodynamic characteristics of 15 NACA airfoil sections at seven Reynolds numbers from  $0.7 \times 10^6$  to  $9 \times 10^6$ ," 1949.
7. ABCD-WB-08-00 Weight and Balance Report, EASA.

HERE BELOW AN EXAMPLE OF REFERENCES TO BE EDITED

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## Chapter 3. List of Abbreviations

- CL = lift coefficient
- CD....
- ...
- ...
- ...
- ...
- ...

ADD HERE list of abbreviations as a formatted table....to be created



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## Chapter 4. Aircraft data

The aircraft geometrical, masses, inertial and aerodynamic data, useful for flight loads estimation are summarized in this chapter.

### 4.1. Geometry

The aircraft reference geometrical characteristics are summarized in the following tables.[Wing parameters](#)

**Table 4.1. Wing parameters**

Wing parameters	Value	Measure unit
b	5.2	m
S	2.589	m <sup>2</sup>
AR	10.446	-
taper	NaN	-
sweep	0	deg
sweep_location	0	percentage
secondary_sweep_location	0	percentage
croot	0.498	m
ctip	0.498	m
xle	1.638	m
yle	0	m
zle	0.165	m
xtip_le	NaN	% fuselage length
dihedral	0	deg
mac	0.498	m
xmac	NaN	% fuselage length
ymac	NaN	% semispan
ypos	NaN	% semispan
zpos	NaN	% fuselage diameter
camberloc	0.15	Percentage
thickchord	0.18	Percentage
type	Rectangular	flag
twist_angle	3	deg
chord_kink_one	0.498	m
chord_kink_two	0.498	m
mgc	0.49788	m
taper_ratio	1	Non dimensional

**Table 4.2. Horizontal Tail parameters**

Horizontal parameters	Value	Measure unit
S	0.529	m <sup>2</sup>
l	1.492	m
camber	0	percentage
camberloc	NaN	percentage
thickchord	0.12	percentage
twist	0	deg
twistloc	0.25	percentage
xloc0	1.49	m
xloc	3.128	m
yloc	0	m
zloc	0.15	m
xrot	0	m
yrot	0	m
zrot	0	m
b	1.496	m
ctip	0.3136	m
croot	0.3929	m
sweep	15	deg
sweeploc	0	percentage
secsweeploc	1	percentage
dihedral	0	deg
location_of_camber	0.2	percentage
secondary_sweep_location	1	percentage
ce_c_root	0.34	Non dimensional
ce_c_tip	0.36	Non dimensional

**Table 4.3. Vertical Tail parameters**

Vertical parameters	Value	Measure unit
xle	0.95	% of fuselage length
croot	0.3136	m
ctip	0.15347	m
xtip_le	1	% of fuselage length
b	0.4375	m
zpos	1	% of df
S	0.1022	m <sup>2</sup>

Vertical parameters	Value	Measure unit
chord	0.3136	m
MAC	0.23354	m
l_vt	1.65	m

**Table 4.4. Fuselage parameters**

Fuselage parameters	Value	Measure unit
length	3.64	Non dimensional
diameter	0.42	Non dimensional
Non_dim_radius_of_gyration	0.34	Non dimensional
Radius_of_gyration	NaN	m

**Table 4.5. Elevator parameters**

Elevator parameters	Value	Measure unit
S	0.14749	m <sup>2</sup>
chord	0.12324	m
chord_ratio_ce_c	0.35	Non dimensional
overhang	0.12	Non dimensional
span_ratio	0.8	Non dimensional
S_hinge	0.126	m <sup>2</sup>
eta_inner	0.1	percentage
eta_outer	0.9	percentage
cf_c_inner	0.3	percentage
cf_c_outer	0.3	percentage
y_inner	0.0748	m
y_outer	0.6732	m
cf	0.10845	m
moment_arm	0.016021	m

**Table 4.6. Rudder parameters**

Rudder parameters	Value	Measure unit
S	0.019062	m <sup>2</sup>
chord	0.10893	m
chord_ratio_cf_c	0.35	Non dimensional
overhang	0.12	Non dimensional
span_ratio	0.8	Non dimensional
cr_c_root	0.45	Non dimensional
cr_c_tip	0.5	Non dimensional

Rudder parameters	Value	Measure unit
eta_inner	0.1	Non dimensional
eta_outer	0.9	Non dimensional
croot	0.14112	m
ctip	0.076735	m
y_inner	0.021875	m
y_outer	0.19688	m
moment_arm	0.014161	m

**Table 4.7. Aileron parameters**

Aileron parameters	Value	Measure unit
S	0.14018	m <sup>2</sup>
b	0.908	m
ca	0.15438	m
cb	0.019	m
y_inner	1.63	m
y_outer	2.538	m
eta_inner	0.627	Non dimensional
eta_outer	0.976	Non dimensional
ca_c_inner	0.31	Non dimensional
ca_c_outer	0.31	Non dimensional
croot	0.15438	m
ctip	0.15438	m
cf	0.13538	m
moment_arm	0.016928	m

## 4.2. Masses and inertia

The aircraft reference masses and inertia are summarized in this subsection

The Aircraft masses and inertia are summarized in Table: [Weight parameters](#)

**Table 4.8. Weight parameters**

Weight	Value	Measure unit
W_maxTakeOff	100	kg
W_OperativeEmpty	NaN	kg
W_Payload	NaN	kg
W_Fuel	NaN	kg
W_Crew	NaN	kg
IY	100	kg * m <sup>2</sup>

### 4.3. Aerodynamic

The aircraft reference aerodynamic is in figure: [Wing-Body reference Aerodynamics](#)

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## Chapter 5. Design Airspeeds

This chapter defines the operating and design airspeeds as required for certification-CSVLA

### 5.1. Maximum speed in level flight VH

Data not yet available...to be added Available and Required Power.

### 5.2. Stall speeds VS, VS0, VS1

These speeds will be verified by flight test according to certification requirements. In order to calculate the stall speed, the maximum lift coefficient of the aeroplane as a whole is determined first. The maximum lift coefficient of the aeroplane has been calculated from high fidelity CFD. In landing configuration computed with full flap,  $CL_{MAX\text{ landing}} = 2.1$  in take-off configuration leading to  $CL_{MAX\text{ takeoff}} = 1.9$ , and in clean configuration, leading to  $CL_{MAX\text{ clean}} = 1.58$ , also considering the horizontal tail balancing force.

Flaps retracted(clean configuration):

$$V_S = \sqrt{\frac{2 W_{MTOM}}{\rho_0 C_{L_{MAX\text{Clean}}} S}} = \sqrt{\frac{2 * 981}{1.225 * 1.58 * 2.589}} = 19.7839 m/s$$

Flaps extended(Landing configuration):

$$V_{S_0} = \sqrt{\frac{2 W_{MTOM}}{\rho_0 C_{L_{MAX\text{Landing}}} S}} = \sqrt{\frac{2 * 981}{1.225 * 2.1 * 2.589}} = 17.1606 m/s$$

Flaps extended(Take-off configuration):

$$V_{S_1} = \sqrt{\frac{2 W_{MTOM}}{\rho_0 C_{L_{MAX\text{Takeoff}}} S}} = \sqrt{\frac{2 * 981}{1.225 * 1.9 * 2.589}} = 18.0412 m/s$$

Add here comments if necessary

Note: These speeds are estimates. The methods for the estimation can be various. It is important that these estimations are as precise as possible. Flight tests will be used to validate the stall speeds. In case the flight tests show different values, this might have an impact on the speeds used for design and ultimately might impair the compliance to the CSVLA

### 5.3. Design manoeuvring speed VA

According to requirement-CSVLA-335,

the maneuvering speed VA cannot be less than:

$$V_A \geq V_S \sqrt{n_{max}} = 19.7839 * \sqrt{3.8} = 38.566m/s$$

Add here comments if necessary

#### 5.4. Flaps maximum operating speed VF

According to requirement-CSVLA -345,

such speed shall be not less than the greater of 1.4VS and 1.8VS0

The speed has been selected as the greater between 1.4VS =27.6975m/s and 1.8 VSF =24.0248m/s, where VSF is the computed stalling speed with flaps fully extended at the design weight.

The flaps operating speeds is:

$$V_F = 27.6975m/s$$

#### 5.5. Flaps maximum extension speed VFE

On this aeroplane the maximum flap extension speed is identical to the flap operating speed VF. This speed is the maximum speed for flaps in take-off and landing configuration.

$$V_{FE} = 27.6975m/s$$

#### 5.6. Design cruising speed VC

According to requirement-CSVLA-335.

- VC (in m/s) may not be less than -

$$2.4 \sqrt{\frac{Mg}{S}} \left( V_C(kt) = 4.7 \sqrt{\frac{Mg}{S}} \right) \rightarrow 2.4 * \sqrt{\frac{100 * 9.8066}{2.589}} = 46.7095m/s$$

where M/S is the wing loading in kg/m2 and g is the acceleration due to gravity in m/s2.

- VC need not be more than 0.9 VH at sea level.

VH must be available. Otherwise previous value is considered!!!

$$V_C = 46.7095m/s$$

#### 5.7. Design dive speed VD

According to requirement-CSVLA-335.

(1) VD may not be less than 1.25 VC; and (2) with VCmin, the required minimum design cruising speed, VD may not be less than 1.40 VCmin.

$$(1) 1.25VC = 58.3869m/s$$

(2)  $1.4V_{Cmin} = 40\text{m/s}$

$$V_C = 1.25 * 46.7095 = 58.3869\text{m/s}$$

### 5.8. Demonstrated dive speed VDF

VDF is not a design airspeeds for this category.

### 5.9. Never exceed speed VNE

VNE is not a design airspeeds. It must be checked into sec. CS-VLA 1505 Airspeed limitations.

### 5.10. Design Airspeeds summary

Design airspeeds summary is resumed in Table:[Design airspeeds](#)

**Table 5.1. Design airspeeds**

Design airspeeds	Value	Measure unit
VS	19.78	m/s
VS0	17.16	m/s
VS1	18.04	m/s
VA	38.57	m/s
VC	46.71	m/s
VD	58.39	m/s
VE	58.39	m/s
VG	30.46	m/s
VS_inv	24.87	m/s
VF	30.89	m/s



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## Chapter 6. Altitude

The maximum permissible operational altitude for the aircraft is 1300m. Despite the CSVLA requirements do not require to account for the effects of altitude, such effects have been considered up to 1300m. In fact the gust load factor have been calculated at such altitude. This is considered acceptable since it covers the operational range within which the aeroplane will fly most of the time.

(Note: the CSVLA requirement does not require to account for the effects of altitude. Calculating the loads at sea level would be acceptable. In this case, the choice to consider such effect up to 1300m is a decision of a designer, which would be accepted by the team.)

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## Chapter 7. Manoeuvring and Gust load factors n

According to CSVLA 337(a) , the positive limit manoeuvring load factor n may not be less than 3.8, while according to CSVLA 337(b) , the negative limit manoeuvring load factor may not be less than -1.5.

The following value will be considered:

1.  $n_{max} = 3.8$
2.  $n_{min} = -1.5$

### 7.1. Gust envelope

Gust load factors need to be considered because they can exceed the prescribed maximum load factors at different weights and altitudes. Since gust loads depend on air density and aircraft mass they will be calculated for Compliance with the flight load requirements of this subpart to show:

- (1) At each critical altitude within the range in which the aeroplane may be expected to operate from sea level up to maximum operative altitude equal to: 1300 m
- (2) At each practicable combination of weight and disposable load within the operating limitations specified in the Flight Manual according to requirement CSVLA 321 and fully extended (requirement CSVLA 345(b) at VF).

The calculation is based on CSVLA 341 . To calculate the gust loads at altitudes other than at sea level the following equation is altered to include the density at any altitude.

$$n = 1 + \frac{1/2 \rho_0 V a K_g U_{de}}{Mg/S}$$

where:

- $K_g = \frac{0.88\mu_g}{5.3 + \mu_g}$
- $\mu_g = \frac{2(M/S)}{\rho \bar{C} a}$
- $U_{de}$  = derived gust velocities referred to in CSVLA 333(c) (m/s)
- $\rho_0$  = density of air at sea level (kg/m<sup>3</sup>)
- $\rho$  = density of air (kg/m<sup>3</sup>)
- $M/S$  = wing loading (kg/m<sup>2</sup>)
- $\bar{c}$  = mean geometric chord (m);  $g$  = acceleration due to gravity (m/s<sup>2</sup>);
- $a$  = slope of the aeroplane normal force coefficient curve C<sub>N</sub> per radian

Since the gust loads on the wing and tail have been chosen to be treated together,  $a$  is the slope of the lift-curve of the aeroplane is equal to  $a = 5.2341/\text{rad}$  and  $0.09131/\text{deg}$ .

The gust speed at VC is equal to: 15.24m/s

The gust speed at VD is equal to: 7.62m/s

TABLE TO BE CHECKED!!!

**Table 7.1. Gust load factor, different Speeds and Altitude**

ID	V(m/s)	M(kg)	M/S(kg/m <sup>2</sup> )	Altitude(m)	rho(kg/m <sup>3</sup> )	mug	Kg	Ude(m/s)	n
1	46.71	100	38.62	1300	1.079	27.47	0.7377	15.24	5.444

(Note: the applicant should provide the method for the calculation of the slope of the lift-curve of the aeroplane)



Figure 7.1. V-n diagram



Figure 7.2. Gust diagram

## Chapter 8. V-n Envelope



Figure 8.1. Maneuver and Gust load factors and diagram



Figure 8.2. Maneuver and Gust load factors and diagram

ADD HERE V-n Envelope

---

## Chapter 9. Loads on the aeroplane

ADD HERE details for balancing Equation

ADD HERE details for balancing Equation

### 9.1. Reference axes and sign convention

#### 9.1.1. aaaaa

ADD HERE details for balancing Equation

### 9.2. Symmetrical flight conditions

ADD HERE details for balancing Equation

### 9.3. Aerodynamic centre

ADD HERE details for balancing Equation

### 9.4. Pitching moment of the wing

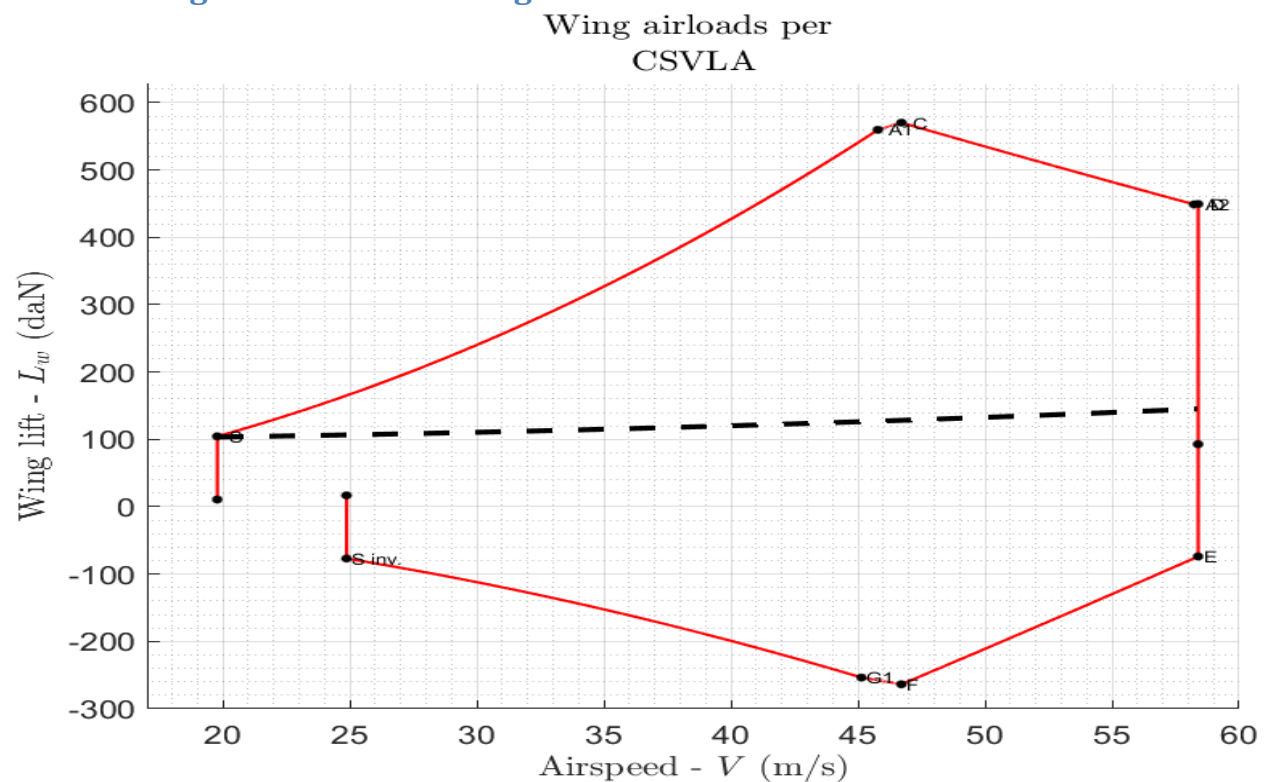


Figure 9.1. Wing airloads

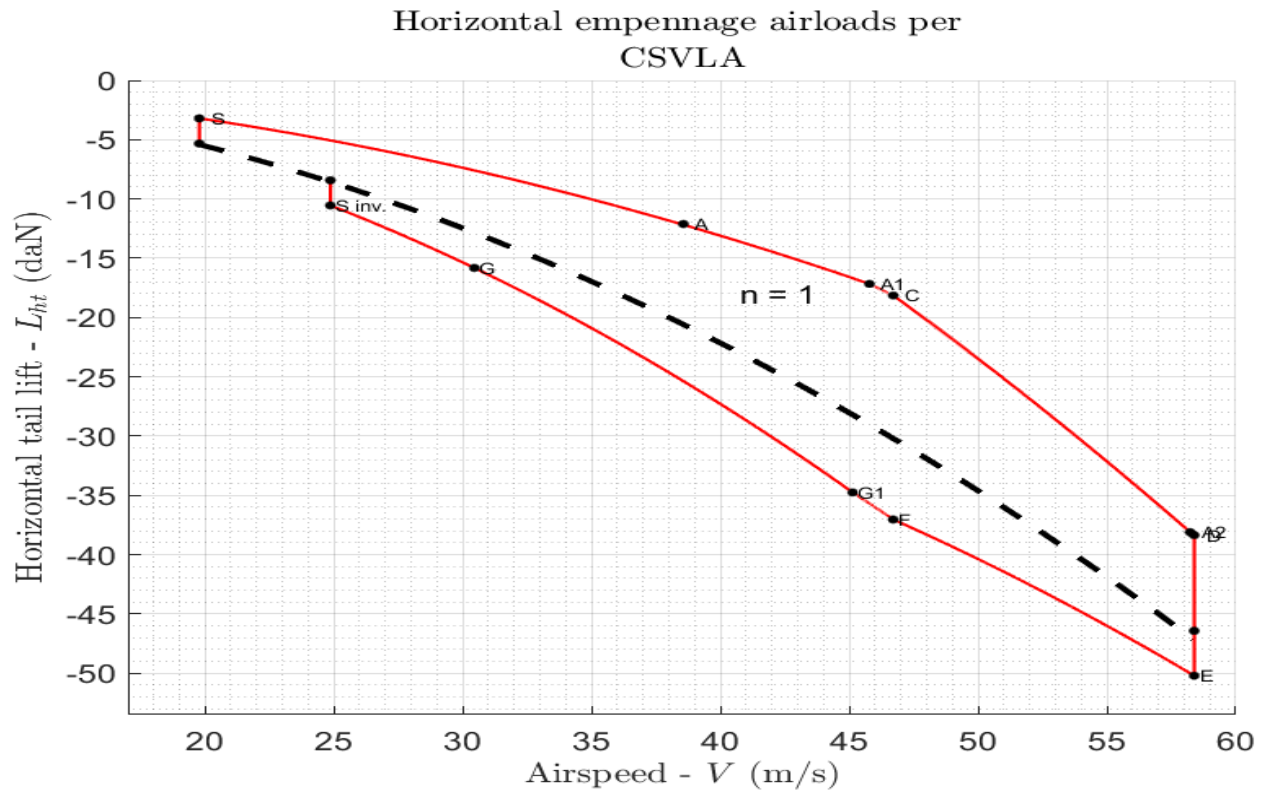


Figure 9.2. Balancing loads



---

## Chapter 10. Loads on the wing

ADD HERE details for balancing Equation

ADD HERE details for fuselage effect how are they accounted?

### 10.1. Influence of the fuselage

ADD HERE details for balancing Equation

### 10.2. Forces and moments acting on the wings

#### 10.2.1. SpanWise Airloads Distribution

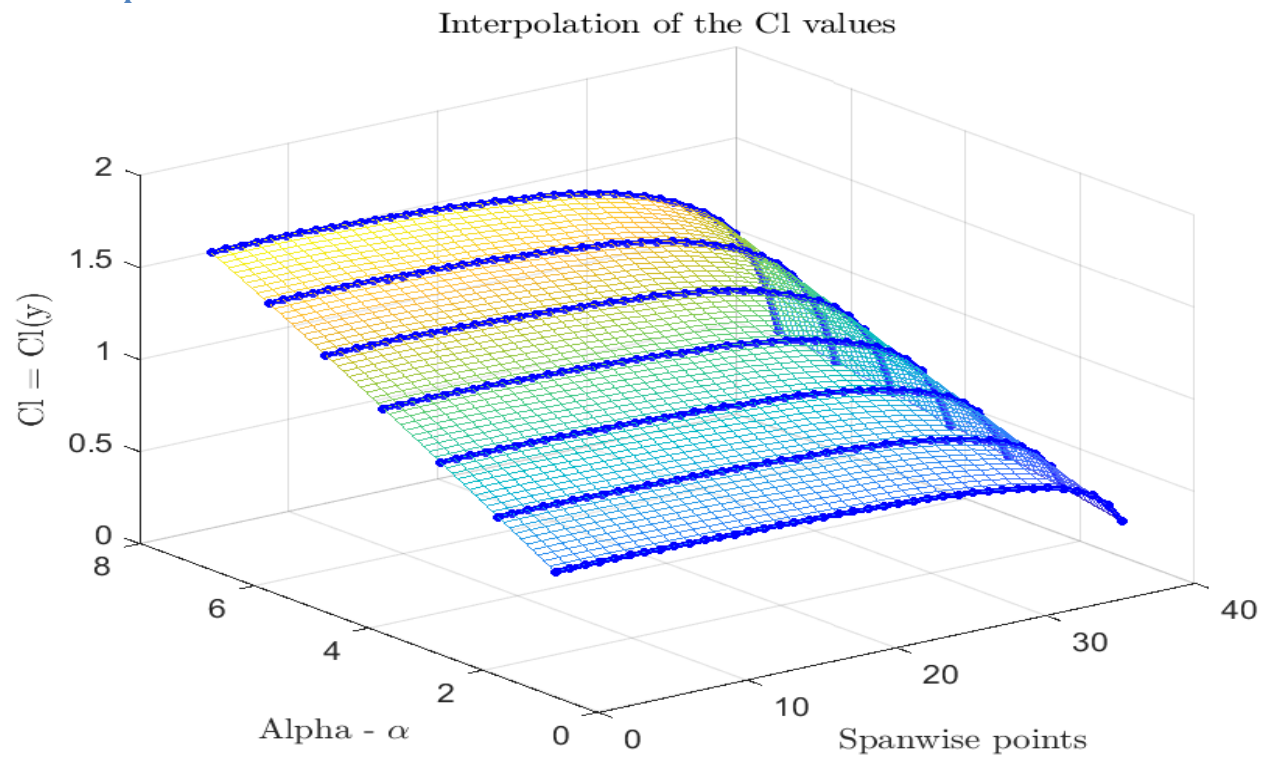


Figure 10.1. Wing lift coefficient spanwise distribution

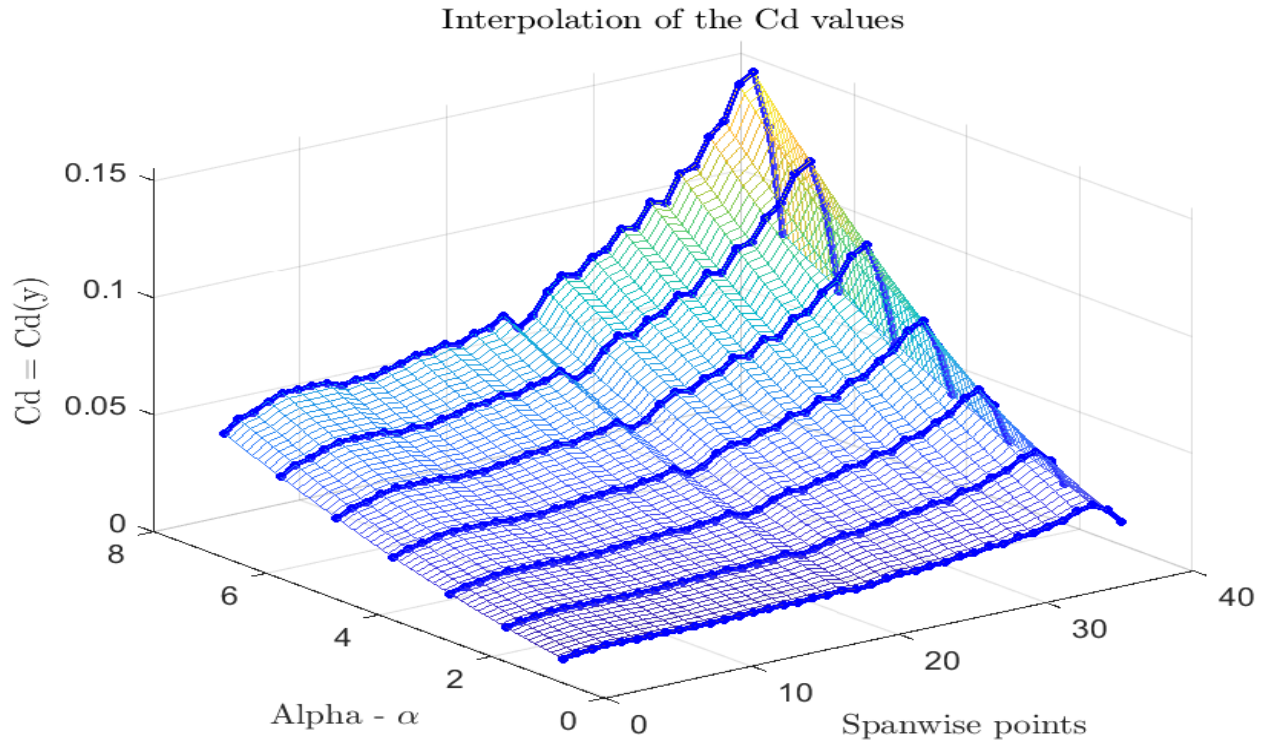


Figure 10.2. Wing drag coefficient spanwise distribution

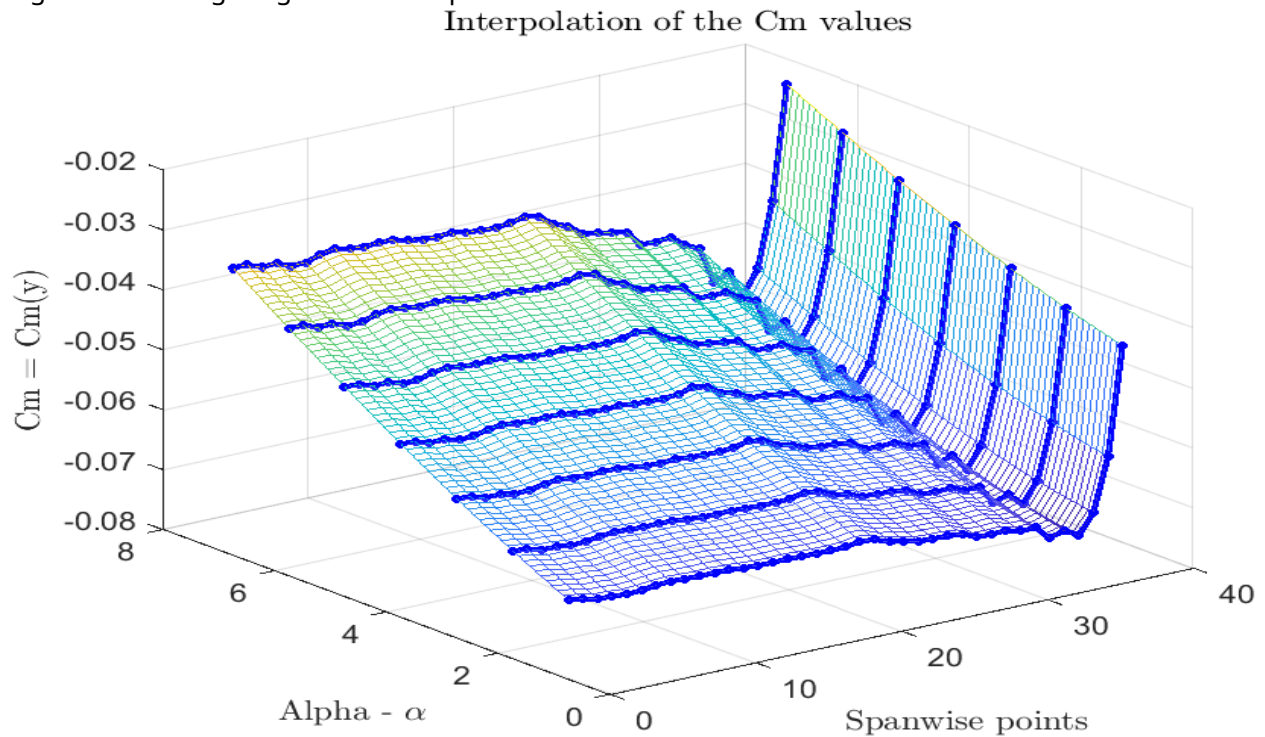


Figure 10.3. Wing pitching moment coefficient (0.25mac) spanwise distribution

### 10.2.2. Normal and parallel component

### 10.2.3. Shear, Bending and Torsion

## Point A

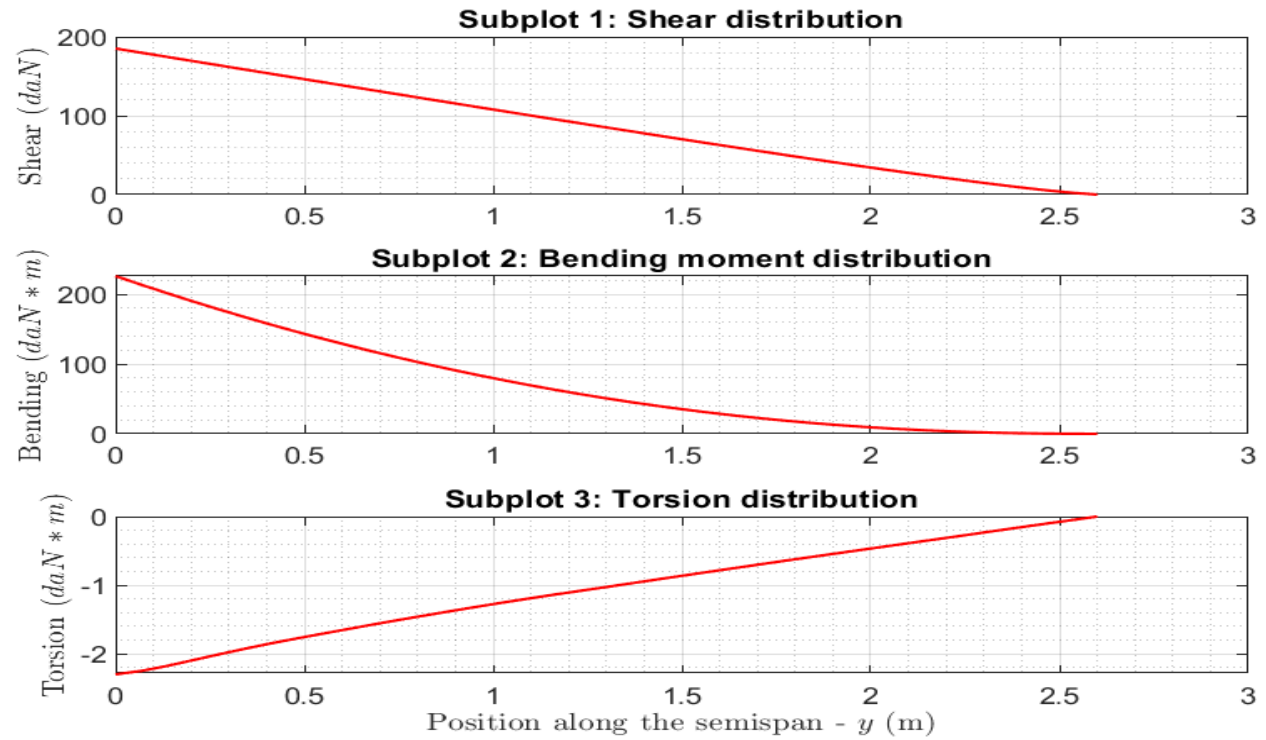


Figure 10.4. Shear, Bending and Torsion due to airloads - POINT A

## Point C

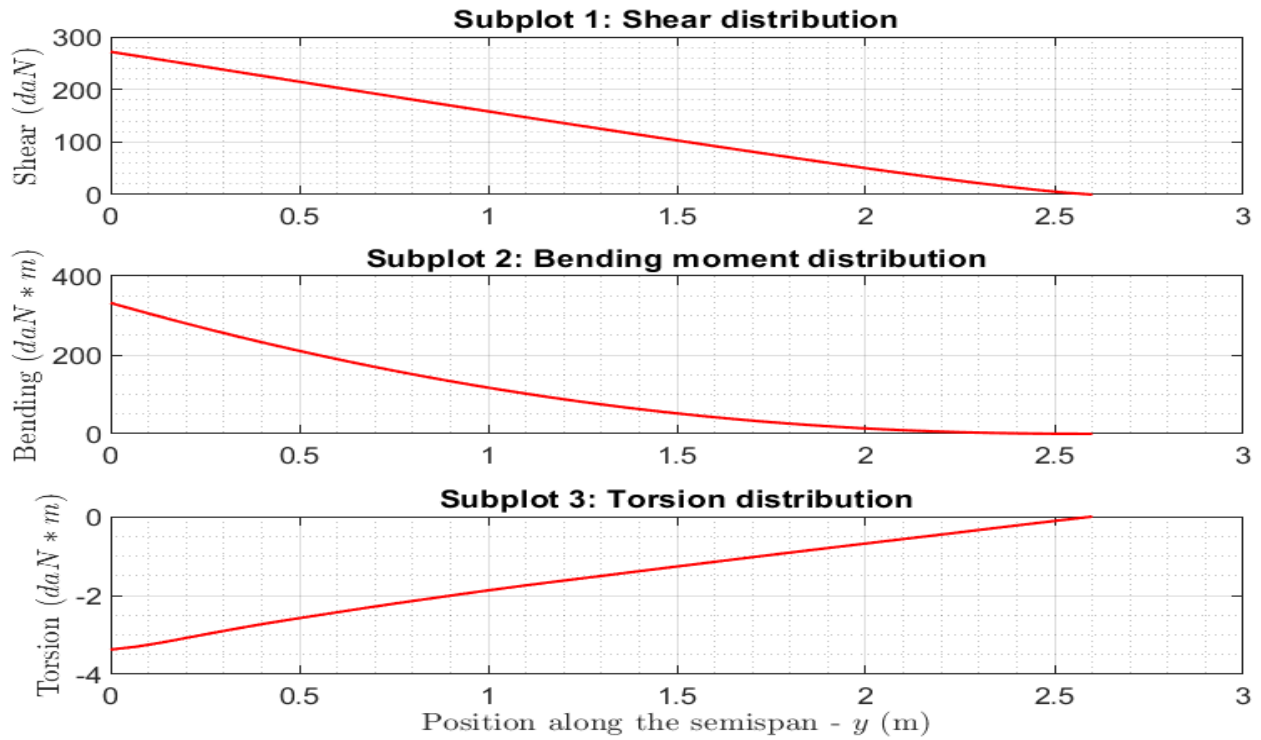


Figure 10.5. Shear, Bending and Torsion due to airloads - POINT C

## Point D

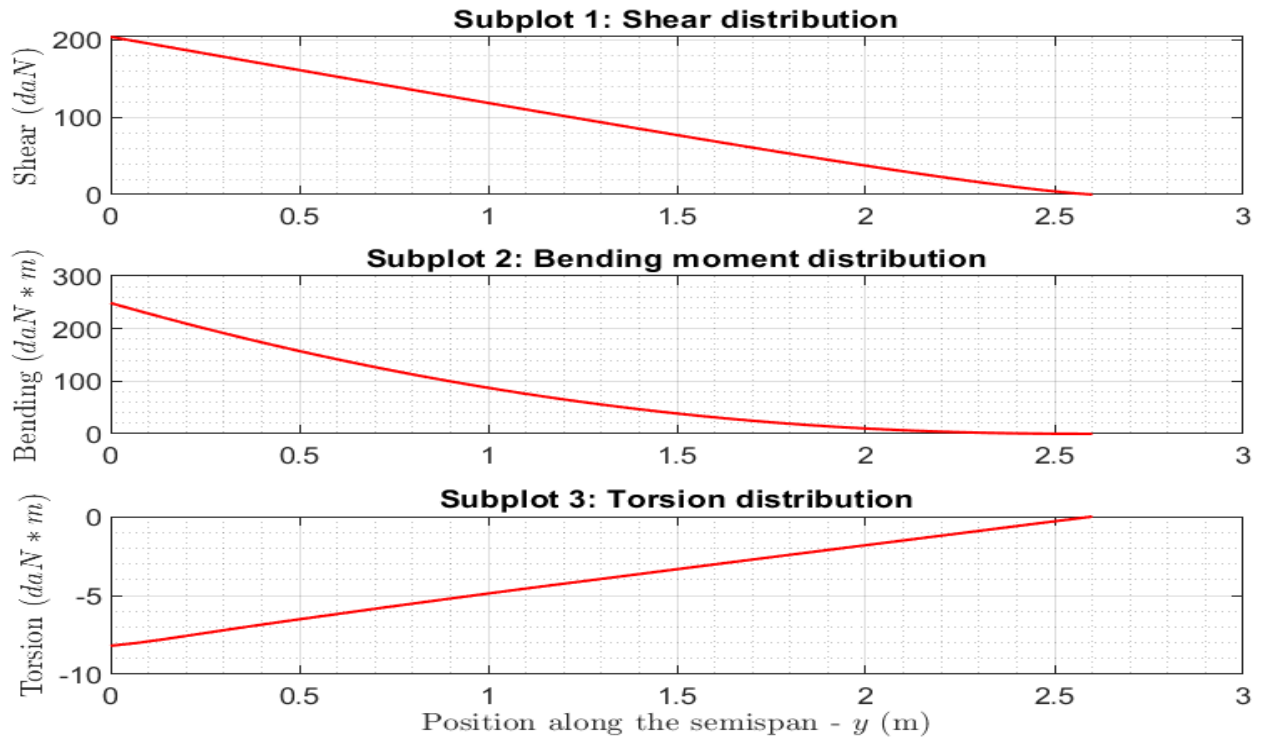


Figure 10.6. Shear, Bending and Torsion due to airloads - POINT D

## 10.2.4. Critical load condition

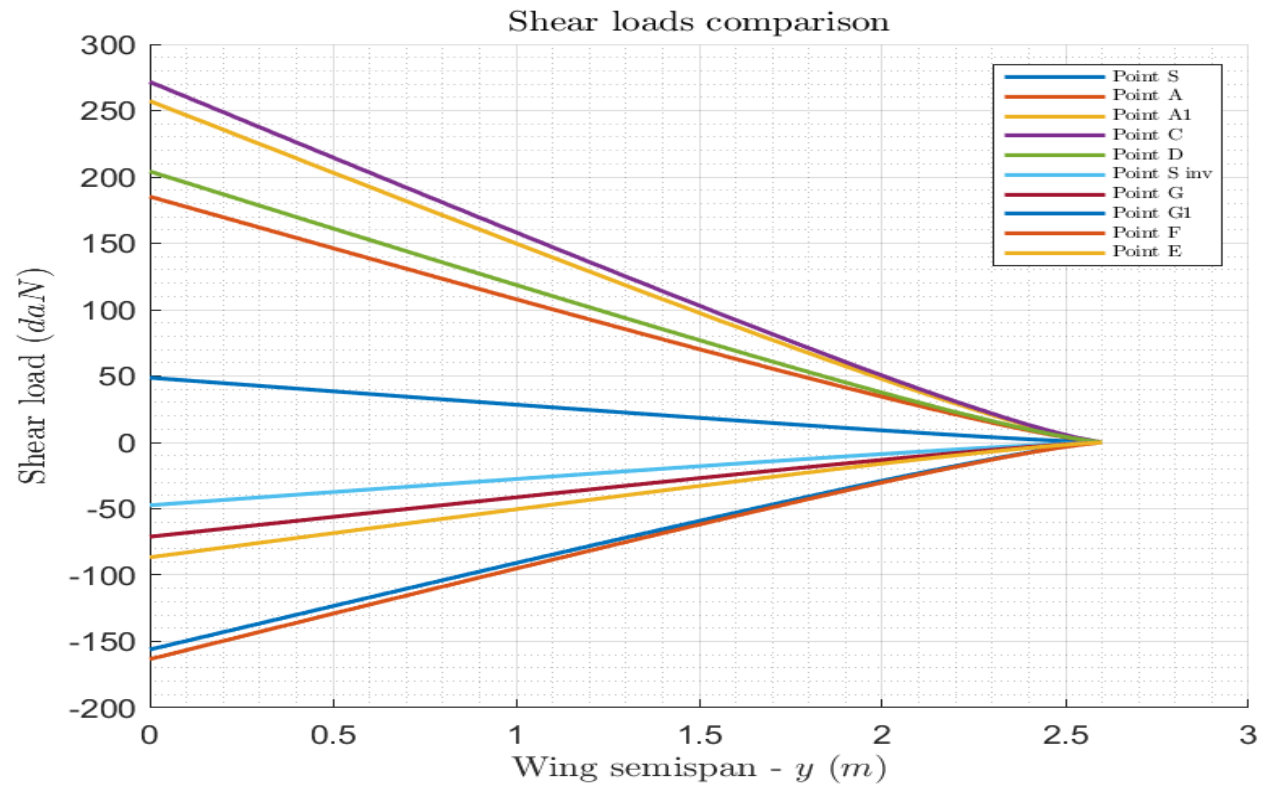


Figure 10.7. Shear comparison

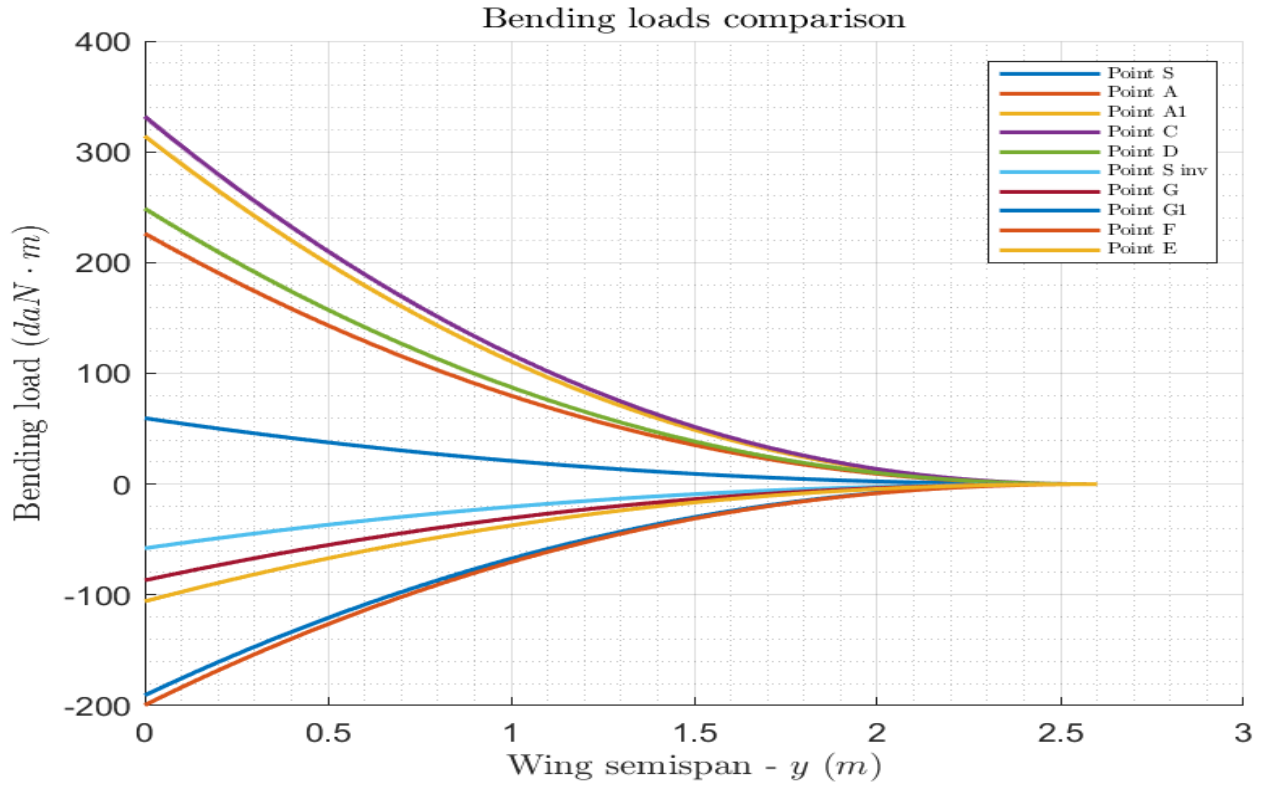


Figure 10.8. Bending comparison

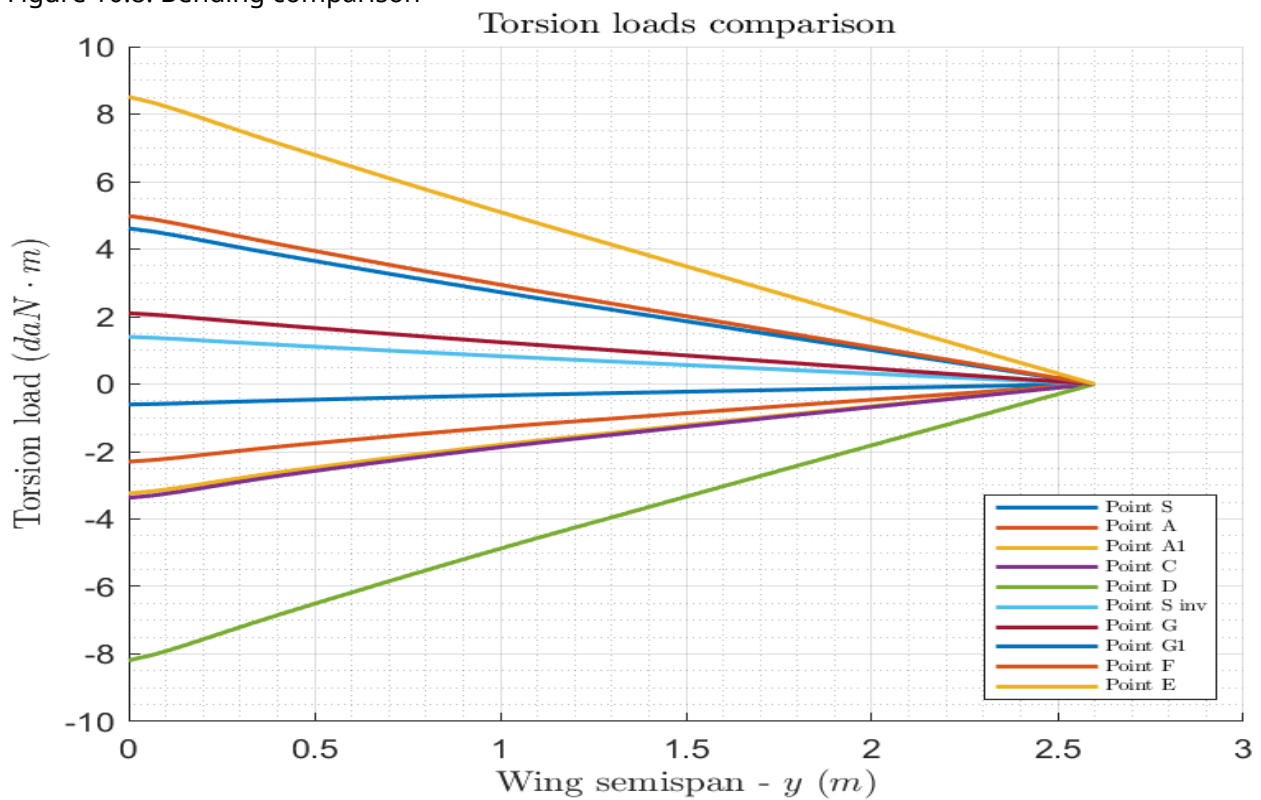


Figure 10.9. Torsion comparison

ADD HERE details for uns loads

### 10.3. Unsymmetrical loads

#### 10.3.1. Rolling condition

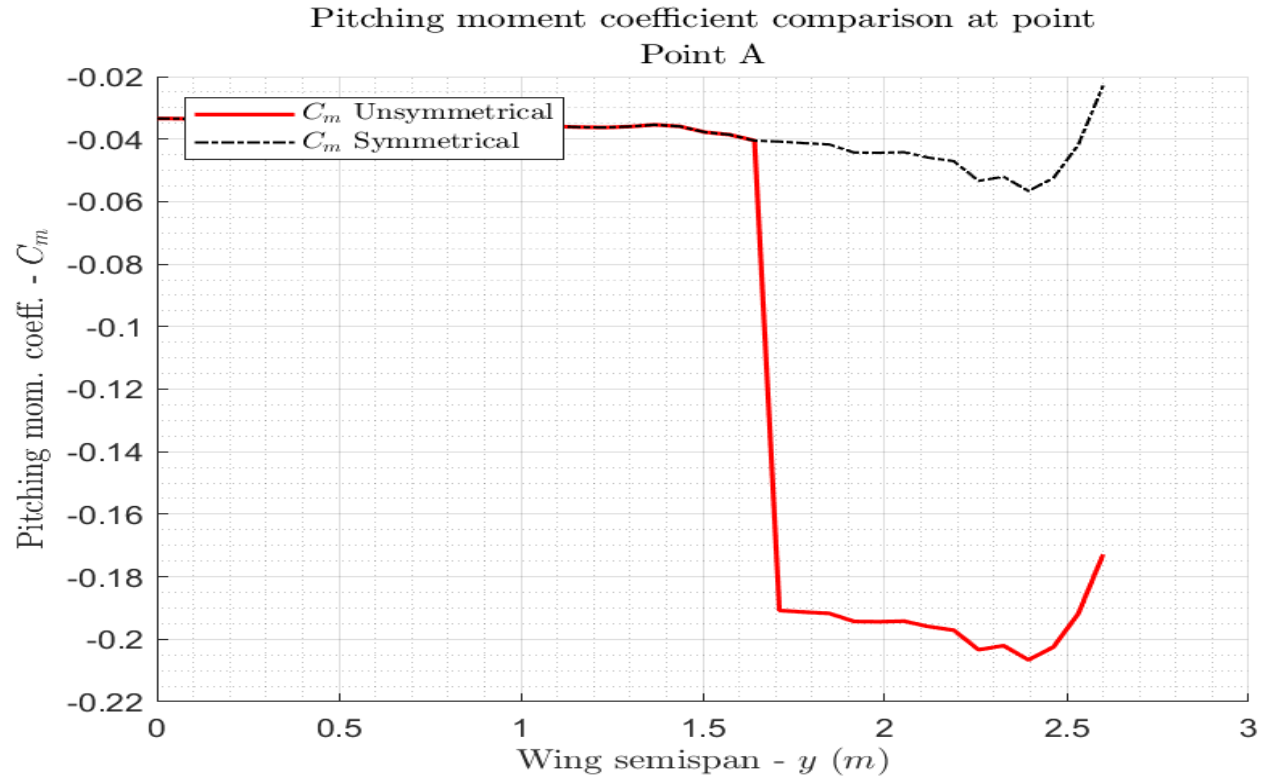


Figure 10.10. Pitching moment coefficient - POINT A



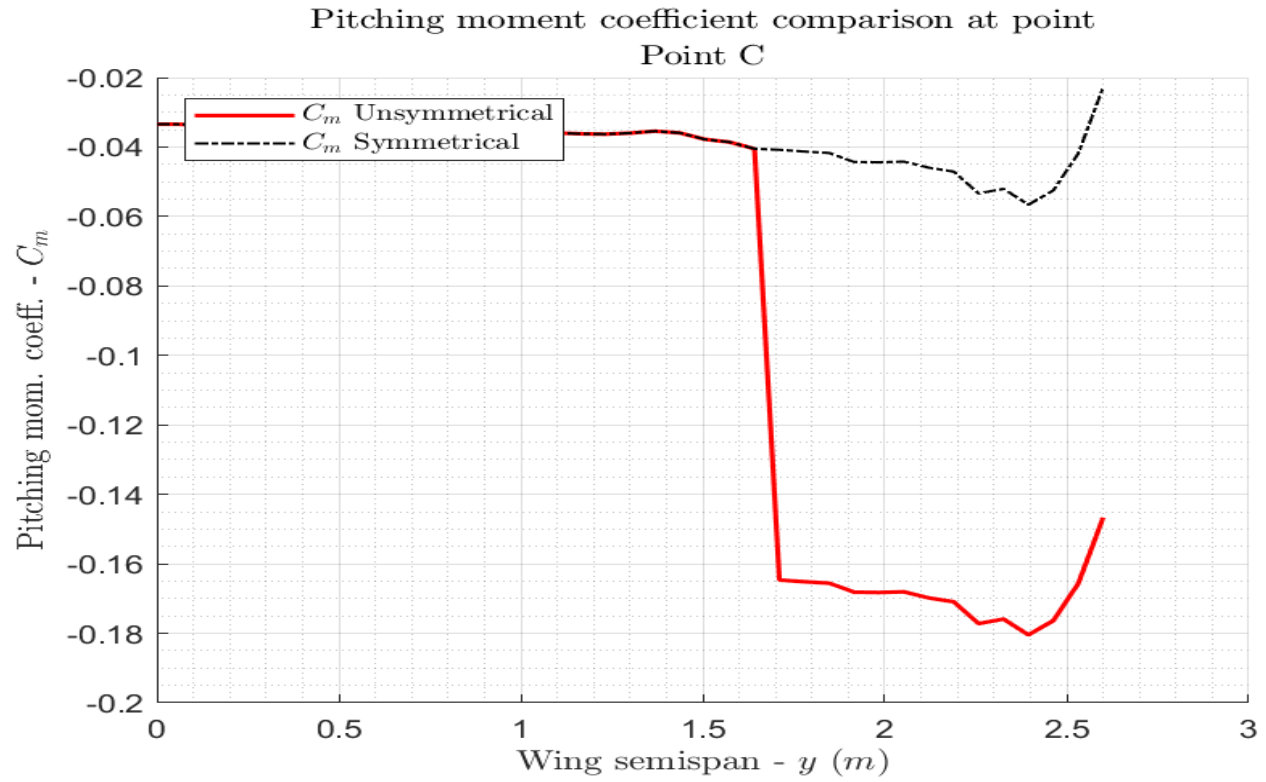


Figure 10.11. Pitching moment coefficient - POINT C

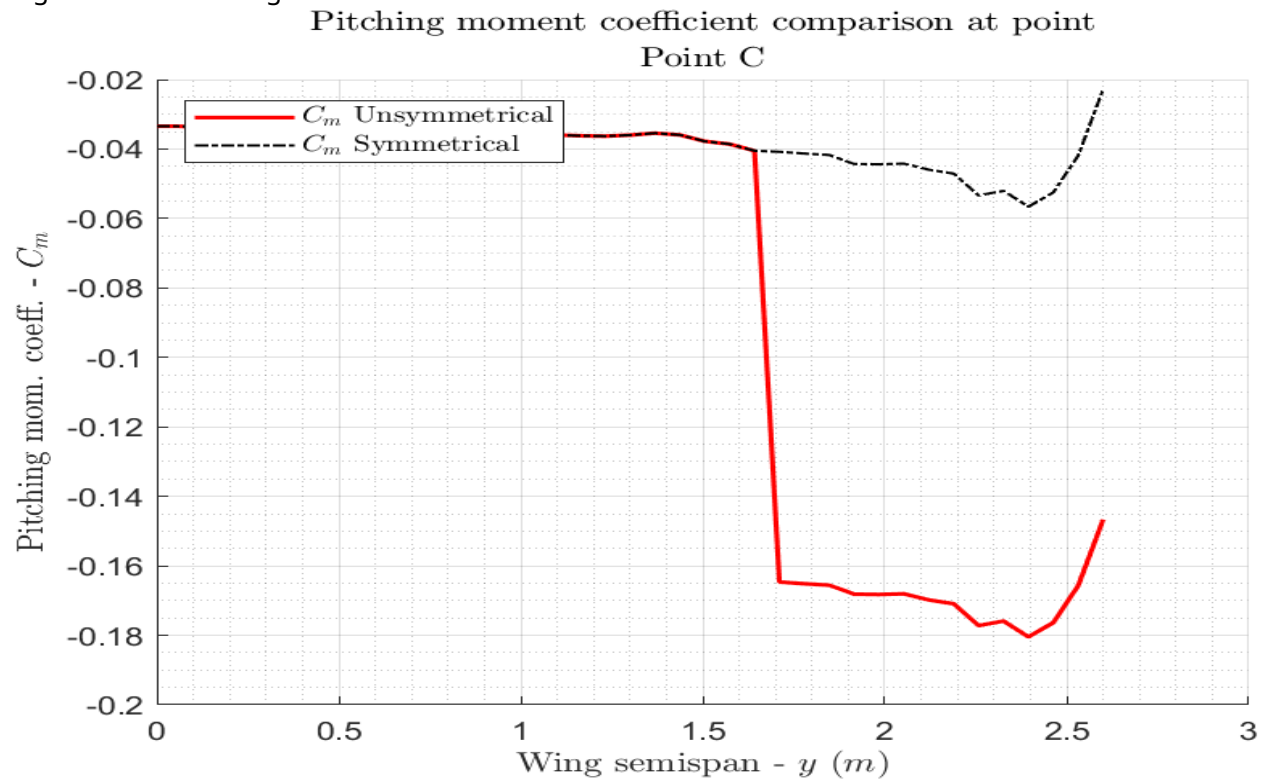


Figure 10.12. Pitching moment coefficient - POINT D

**10.3.2. Effect of aileron displacement on the wing torsion**

Unsymmetrical Torsion load due to aileron deflection at  
Point A

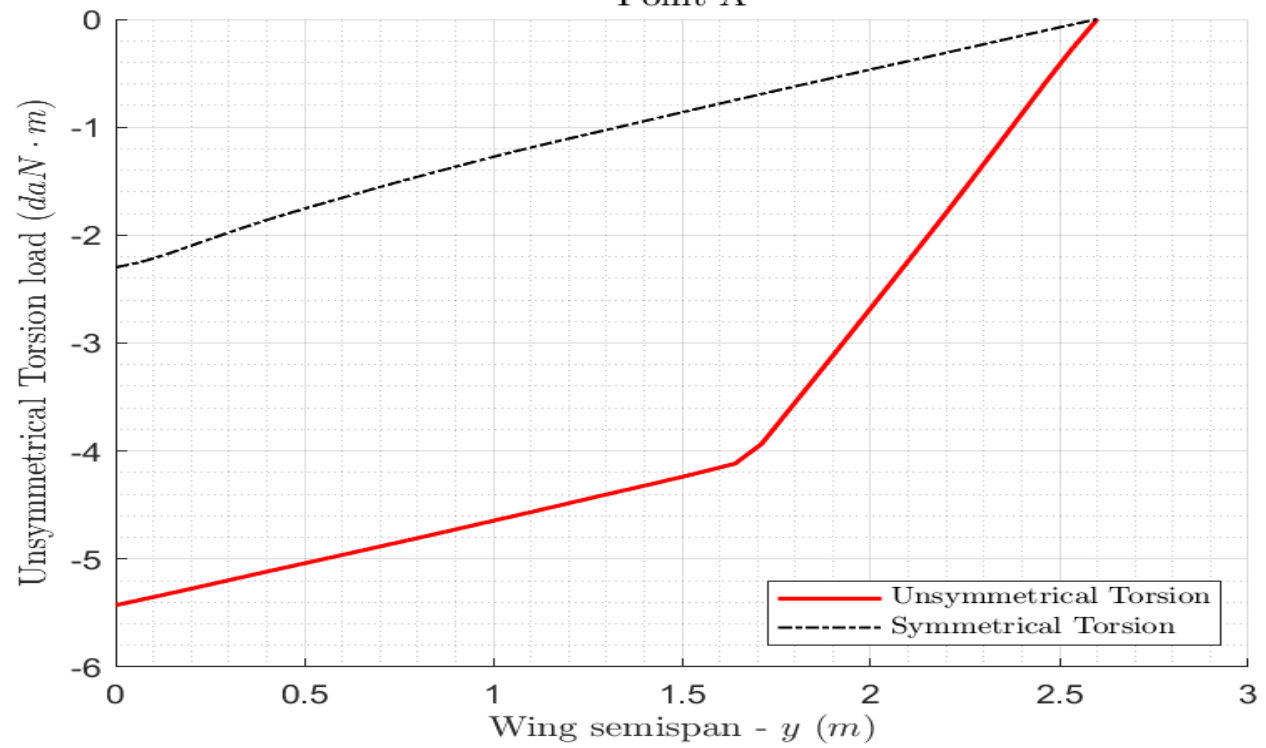


Figure 10.13. Torsion distribution full loads - POINT A

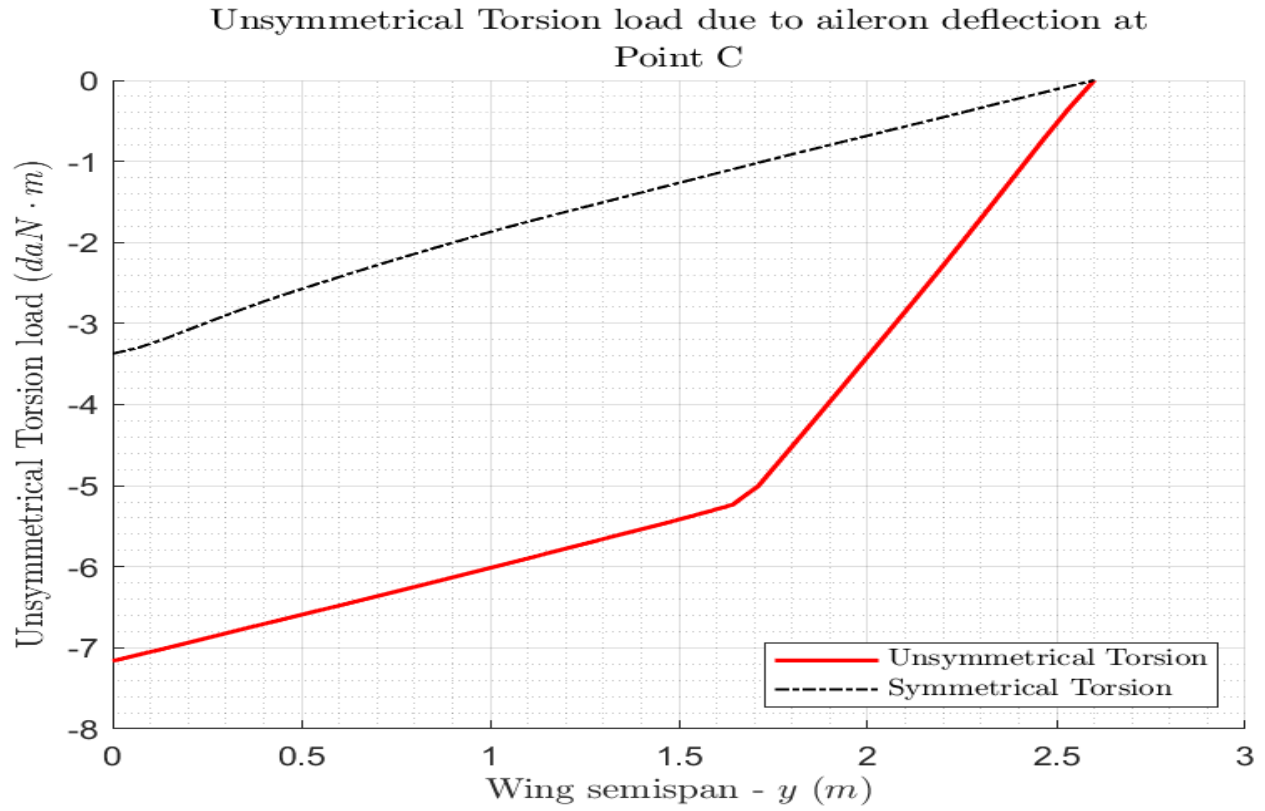


Figure 10.14. Torsion distribution full loads - POINT C

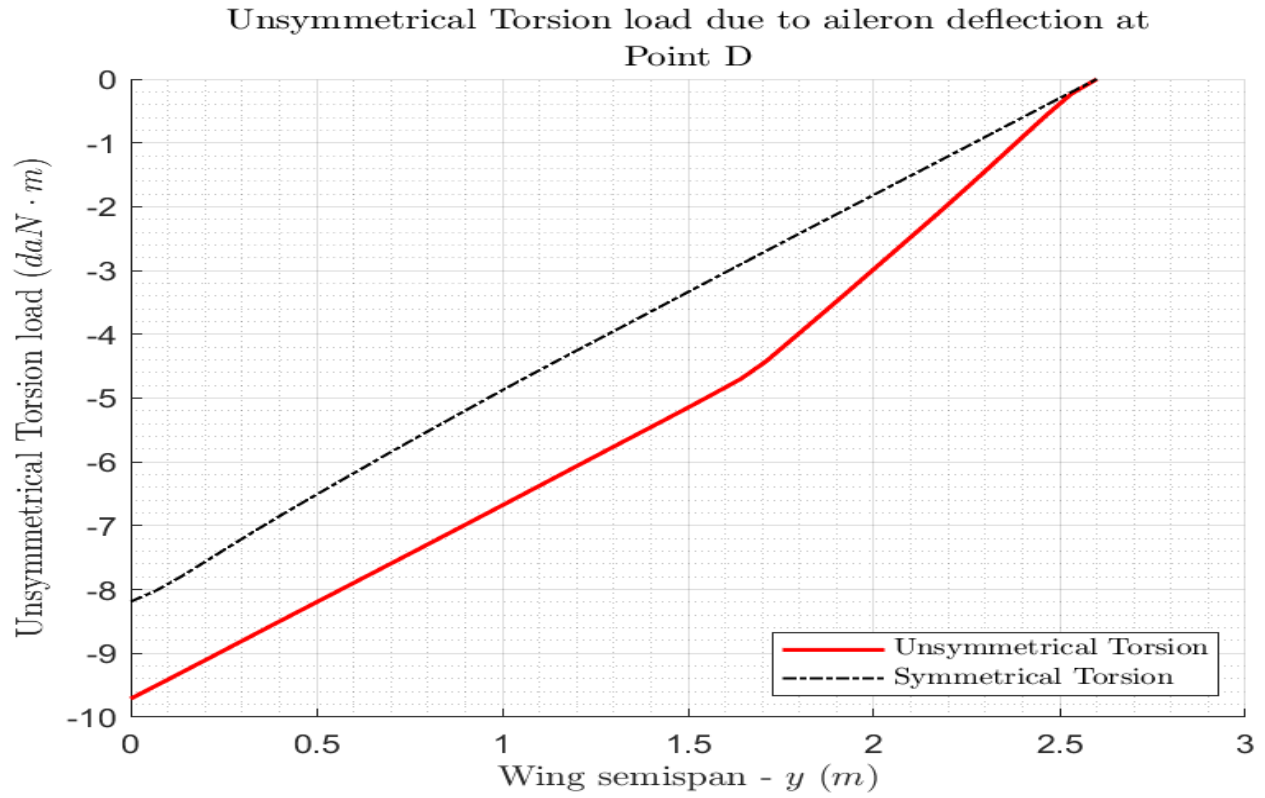


Figure 10.15. Torsion distribution full loads - POINT D

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## Chapter 11. Loads on the horizontal tail

ADD HERE details

ADD HERE details

### 11.1. Balancing loads

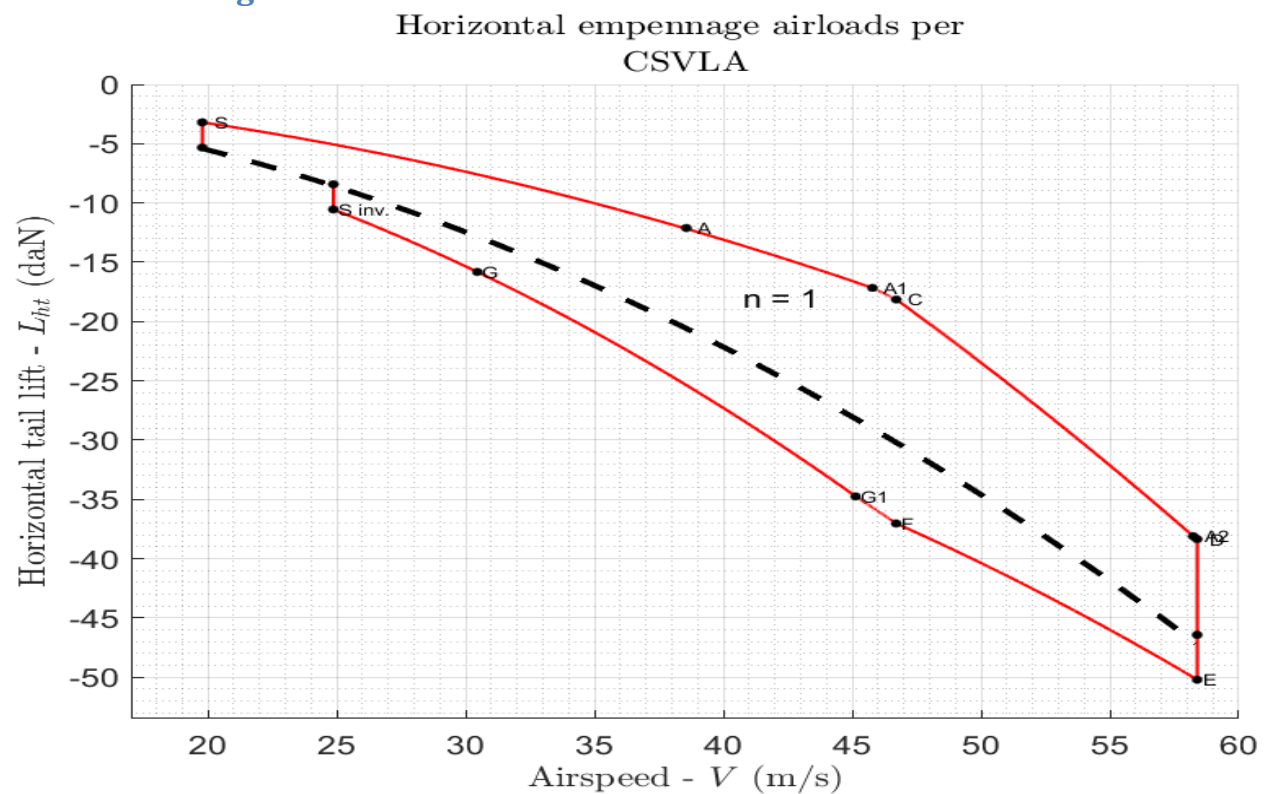


Figure 11.1. Balancing loads

ADD HERE details

### 11.2. Manoeuvring loads

#### 11.2.1. Unchecked manoeuvre

#### 11.2.2. Checked manoeuvre

#### 11.2.3. Gust loads

ADD HERE details

### 11.3. Horizontal tail loads summary

ADD HERE details

### 11.4. Unsymmetrical loads

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## **Chapter 12. Loads on the vertical tail**

ADD HERE details

ADD HERE details

### **12.1. Manoeuvring loads**

**12.1.1. a(1)**

**12.1.2. a(2)**

**12.1.3. a(3)**

**12.1.4. Gust loads**

ADD HERE details

### **12.2. Vertical tail loads summary**

ADD HERE details on h-v combined loads

### **12.3. Combined loads**

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## Chapter 13. Loads on the wing flaps

According to CSVLA the vertical tail must withstand several manoeuvring loads. In this chapter, all these load case will be illustrated.

### 13.1. Manoeuvring load

At speeds up to  $V_A$ , the vertical tail surfaces must be designed to withstand the following condition. In computing the tail loads, the yawing velocity may be assumed to be zero.

#### 13.1.1. CSVLA 441(a)(1)

With the aeroplane in unaccelerated flight at zero yaw, it is assumed that the rudder control is suddenly displaced to the maximum deflection, as limited by the control stops or by limit pilot forces. The control stops are  $\pm 30$  deg. The lateral force coefficient acting on the rudder when at maximum deflection angle is given by the following simple equation:

$$C_Y = C_{Y,0} + \frac{d C_Y}{d \delta_r} * \delta_{r,max}$$

where:

- $C_Y$  = lateral force coefficient;
- $C_{Y,0}$  = lateral force coefficient at  $\beta = \delta = 0$  , equal to zero for symmetrical airfoil;
- $\frac{d C_Y}{d \delta_r}$  = lateral force curve slope per deg of rudder deflection;
- $\delta_{r,max}$  = rudder control stop.

Assuming no deflection of the control cable (the control system is infinitely rigid), the maximum value of the lateral force coefficient is:

$$(C_Y)_{\delta_r = 30} = 0.000644 * 30 = 0.019356$$

#### 13.1.2. CSVLA 441(a)(2)

With the rudder deflected as specified in sub-paragraph CSVLA 441(a)(1) of this paragraph, it is assumed that the aeroplane yaws to the resulting sideslip angle. In lieu of a rational analysis, an overswing angle equal to 1.3 times the static sideslip angle of sub-paragraph CSVLA 441(a)(3) of this paragraph may be assumed.

#### 13.1.3. CSVLA 441(a)(3)

A yaw angle of 15 degrees with the rudder control maintained in the neutral position (except as limited by pilot strength).

### 13.2. Manoeuvring and gust envelope

ADD HERE details

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## **Chapter 14. Loads on the control surfaces**

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### **14.1. Ailerons**

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### **14.2. Elevator**

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### **14.3. Rudder**



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## Chapter 15. Power plant

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### 15.1. Engine torque

The engine takeoff power is 11.19 kW at 5800 RPM. The rotational speed of the propeller is  $5800/2.429 = 2388$  RPM. The maximum continuous power is 9.321 kW. The mean engine torque is  $44.73 \text{ N} \cdot \text{m}$ . Using a factor of 2 for a four cylinder engine, the limit torque will be  $89.45 \text{ N} \cdot \text{m}$ . This limit torque acts simultaneously with the 75 % of the inertia limit load. The mean engine torque at max continuous power is  $39.3 \text{ N} \cdot \text{m}$ . Using a factor of 2 for a four cylinder engine, the limit torque will be  $78.61 \text{ N} \cdot \text{m}$  which acts simultaneously with the 100 % of the inertia limit load.

$$MT_{continuous} = P_{continuous} * \frac{1000}{\frac{2\pi * RPM_{prop}}{60}} = 9.321 * \frac{1000}{\frac{2 * 3.14 * 2388}{60}} = 39.3042 \text{ N} \cdot \text{m}$$

$$LT_{continuous} = RR_{prop} * MT_{continuous} = 2.429 * 39.3 = 78.6084 \text{ N} \cdot \text{m}$$

$$MT_{takeoff} = P_{takeoff} * \frac{1000}{\frac{2\pi * RPM_{prop}}{60}} = 11.19 * \frac{1000}{\frac{2 * 3.14 * 2388}{60}} = 44.7255 \text{ N} \cdot \text{m}$$

$$LT_{takeoff} = RR_{prop} * MT_{takeoff} = 2.429 * 44.73 = 89.4509 \text{ N} \cdot \text{m}$$

- $MT_{takeoff}$  = mean torque at takeoff power ( $\text{N} \cdot \text{m}$ ); and
- $LT_{takeoff}$  = limit torque at takeoff power ( $\text{N} \cdot \text{m}$ ); and
- $MT_{continuous}$  = mean torque at max continuous power ( $\text{N} \cdot \text{m}$ ); and
- $LT_{continuous}$  = limit torque at max continuous power ( $\text{N} \cdot \text{m}$ ).

### 15.2. Side load on engine mount

The limit load factor in a lateral direction is 1.33. The mass of the engine group is 24.4 kg. The side load results is  $1.33 * 24.4 * 9.807 * (1/10) = 31.82 \text{ daN}$

### 15.3. Inertia load on engine mount

The inertia load is equal to the maximum limit load factor times the engine group weight:  $5.357 * 24.4 * 9.807 * (1/10) = 170.5 \text{ daN}$

### 15.4. Gyroscopic loads

According to AMC 23.371(a) , for a two blade propeller, the maximum gyroscopic couple is given by:

$$2 * I_p * \omega_1 * \omega_2$$

Where:

- $I_p$  = polar moment of inertia of the propeller ( $\text{kg} \cdot \text{m}^2$ ); and
- $\omega_1$  = propeller rotation speed (rad / sec); and
- $\omega_2$  = rate of pitch or yaw (rad / sec).

The asymmetric flow through the propeller disc is discounted because the propeller diameter is less than 2.74 m as established by AMC 23.371(a). The polar moment of inertia of the propeller is  $0.37 \text{ kg} \cdot \text{m}^2$ . The rate of pitch or yaw is established as 1.0 rad/sec and 2.5 rad/sec respectively, the load factor is 2.5 and the power condition is max continuous power as prescribed in AMC 23.371(a). Therefore, the inertial load is equal to  $2.5 \cdot 24.4 = 61 \text{ daN}$ . The rotation of the propeller at maximum continuous power is  $5500/2.4286 = 2264.6792$ . The gyroscopic couple is:

1. Yaw case:  $2 \cdot 0.37 \cdot 2.5 \cdot (2 \cdot 3.14/60) \cdot 2264.6792 = 69.8276 \text{ daN} \cdot \text{m}$
2. Pitch case:  $2 \cdot 0.37 \cdot 1.0 \cdot (2 \cdot 3.14/60) \cdot 2264.6792 = 27.931 \text{ daN} \cdot \text{m}$