**A-Team Documentation**

Initial Idea

-Elevator

-Bus

-Crane/collector

-Glide + 4-wheel drive car

Idea implemented

A robotic guide dog to assist people with partial vision loss. The dog would detect obstacle in front and alert the user through LED lights and buzzing sound.

Possible features for further development

-Control speed and direction of robots through a remote

-Voice feedback instead of a buzz sounds e.g. “Stop, safe, warning”

-Haptic feedback using a wearable