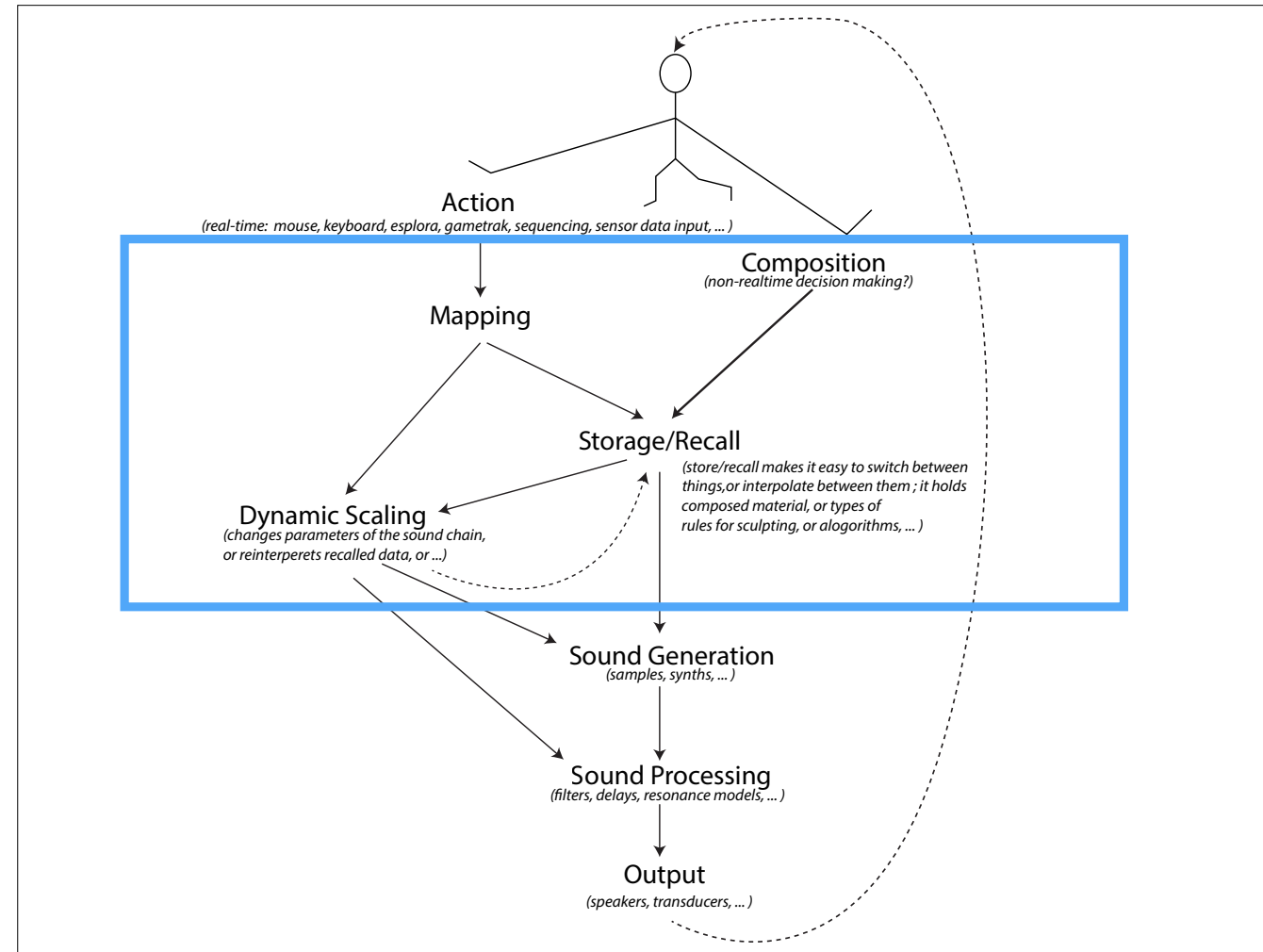
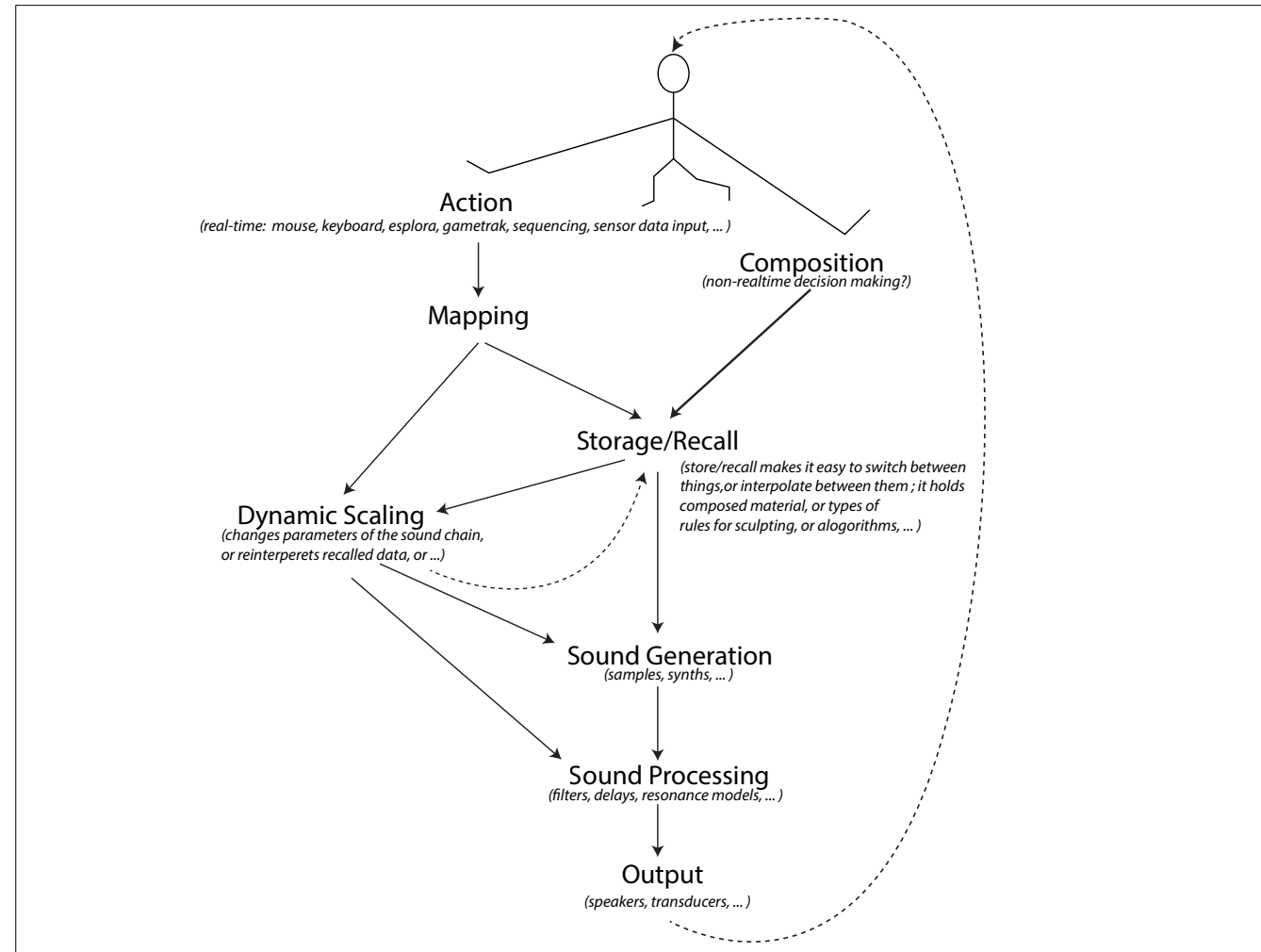


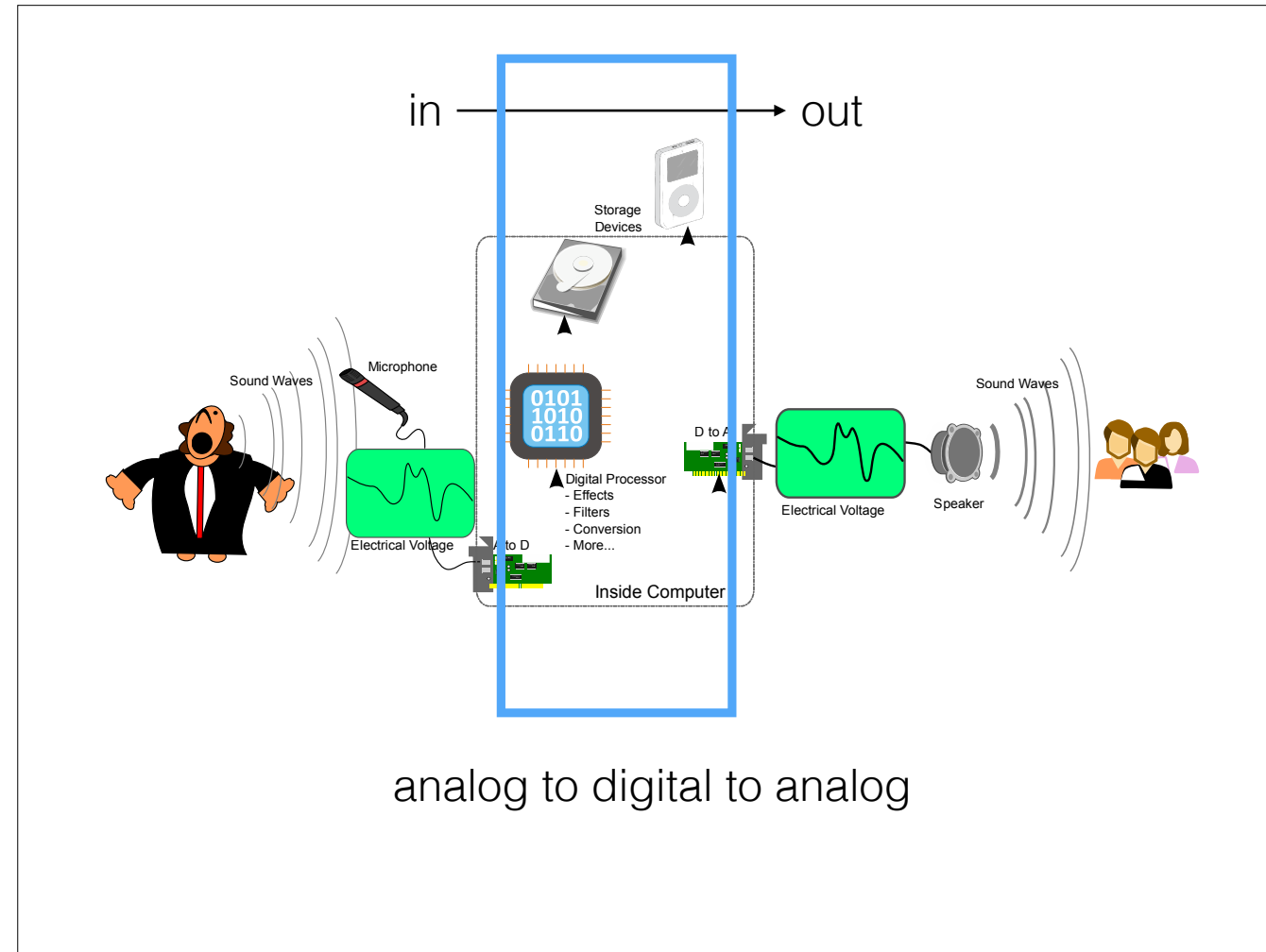
data mediation



today we're going to focus on the data mediation aspect of instrument design

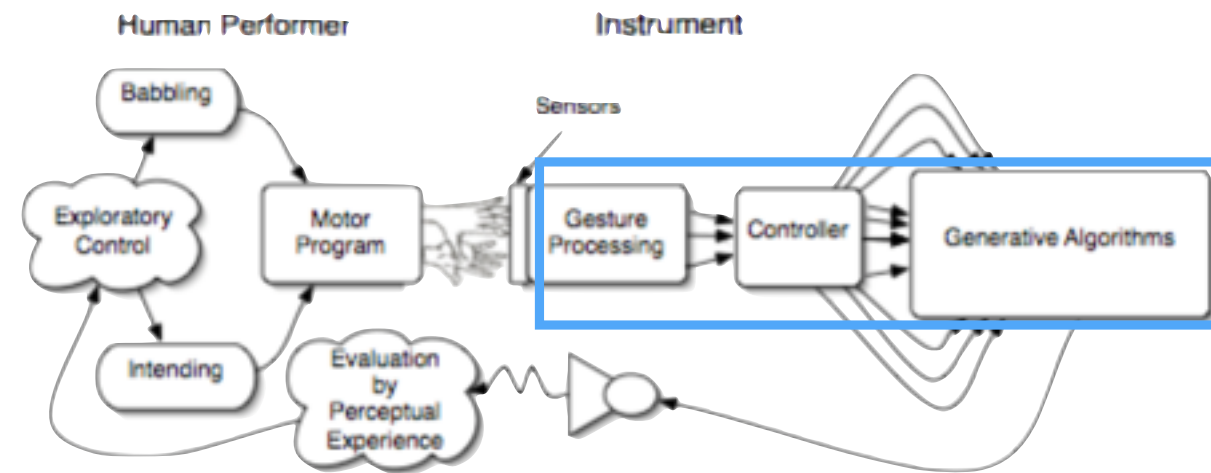


which completes the picture of the system that we're working through



this is the part of the system that really defines the nature of how we experience the results of the inputs

## A framework for reasoning about computer-based musical instrumentation



what is data mediation?

what is data mediation?

... let's start with mapping



the mapping we're talking about is the way information is translated from one form to another  
in the case of a cartography, the image is meant to represent the location of streets and rivers so that we can know where they are.



$$f(x) = y$$

**mapping**

mapping can also thought of as a function, that transforms a number from the input to the output.

$$f(x) = y$$

$$\textit{cartography}(\textit{place}) = \textit{representation}$$

**mapping**

so in the case of the geographic map, we could say that cartography maps the information about a place to a readable visual representation

**Andy Hunt , Marcelo Wanderley, and Matthew Paradis:  
“The Importance of Parameter Mapping in Electronic Instrument Design”**

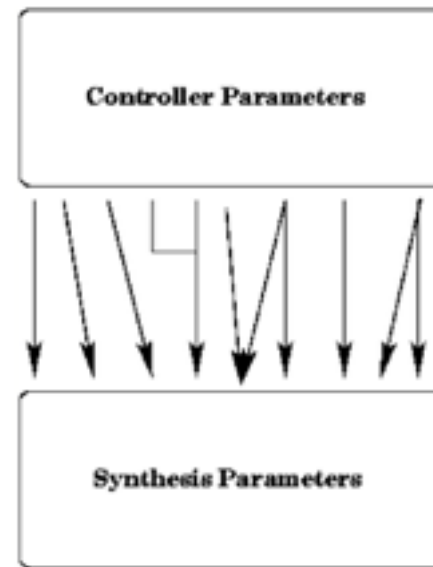


Fig. 1. A generic model of the mapping problem.

**mapping**

in the case of computer music instrument design, we are talking about how we “map,” or create relationships, between control parameters (i.e. sensor data) and the parameters of our sound engines.

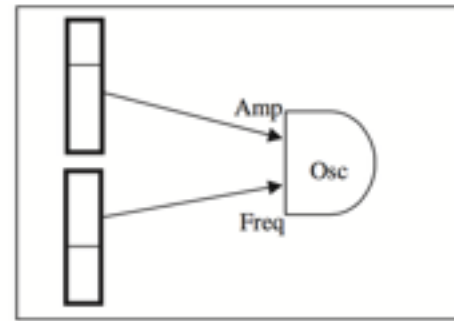


Fig. 2. Simple Mapping for Experiment 1.

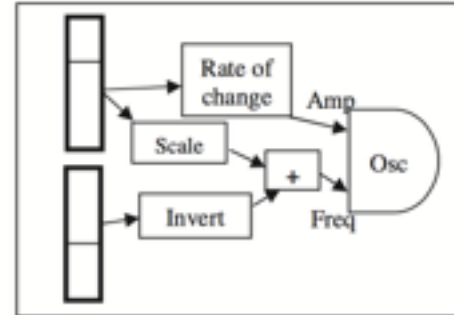


Fig. 3. Complex Mapping for Experiment 2.

**mapping**

examples of direct, one-to-one mapping, and a more complex interrelated mapping space

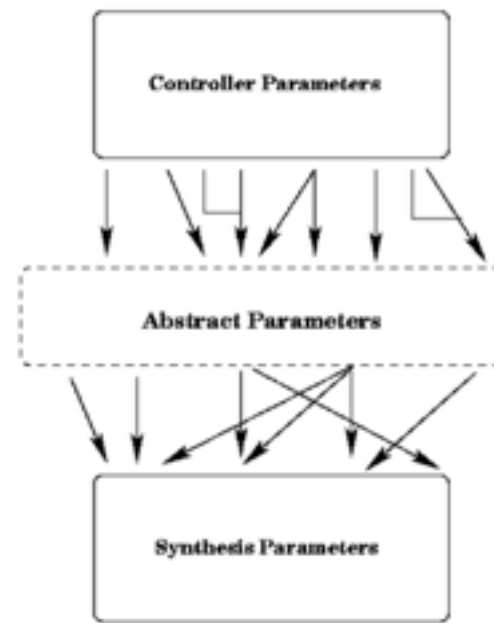


Fig. 11. Two-layer mapping model showing intermediate layer of abstract parameters.

## mapping

in Wanderly's first layer of abstraction in mapping, you abstract the low-level synthesis parameters, to more abstract musical values, like: pitch, vibrato, tremolo, brightness, etc.

for example, the "feedback" parameter in a delay system is really a scaling of the delay as it is fed back into the delay loop, but the perceptual result is "feedback"

mapping

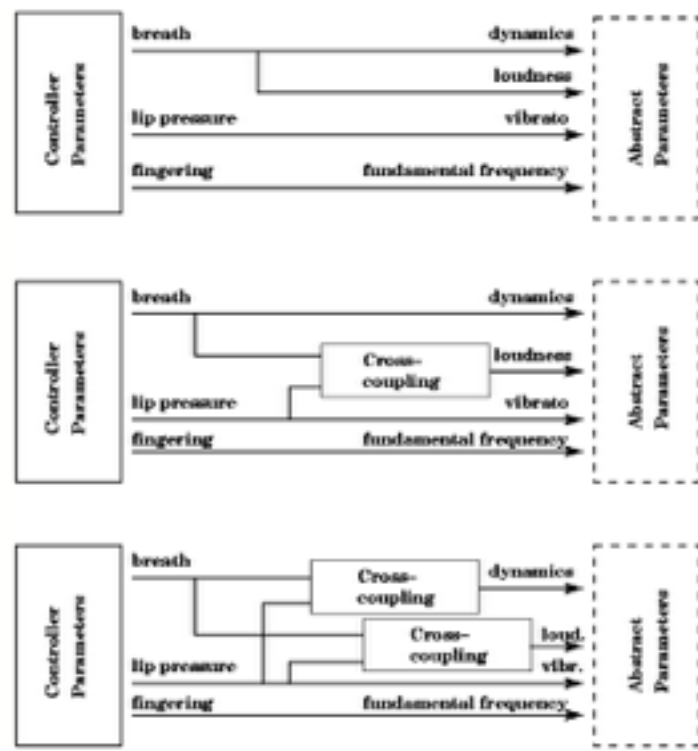
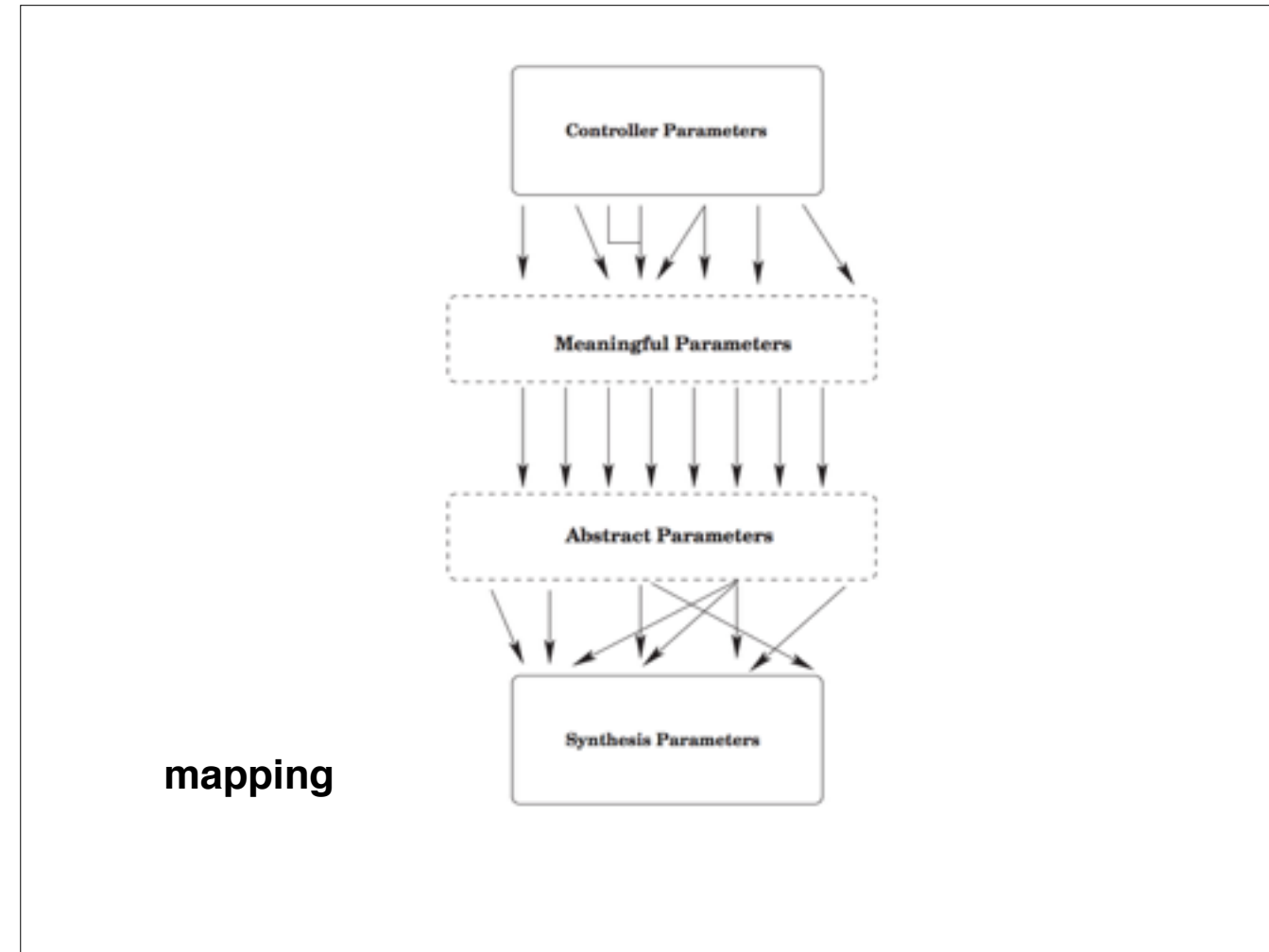


Fig. 10. The three mappings used in the clarinet simulation presented in Rovin (1997).

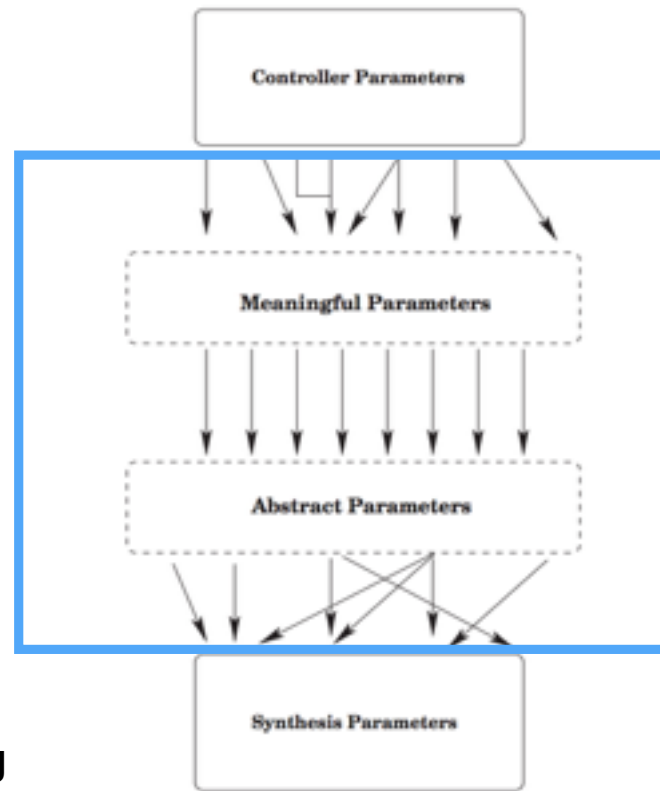


in a  
through mapping we translate control parameters into a meaningful representation, and then use these parameters to control synthesis parameters.

**o.**

**mapping**

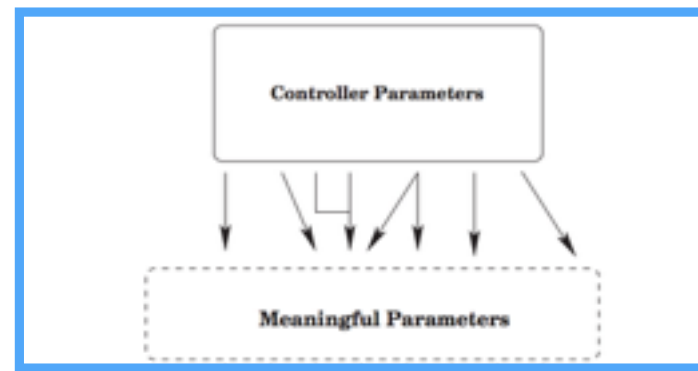
OpenSoundControl (OSC) & o.expr



OSC and the odot expression language was created in order to simplify this process, allowing us to think in terms of meaningful parameters, as well as a stateless programming model (more on this later).

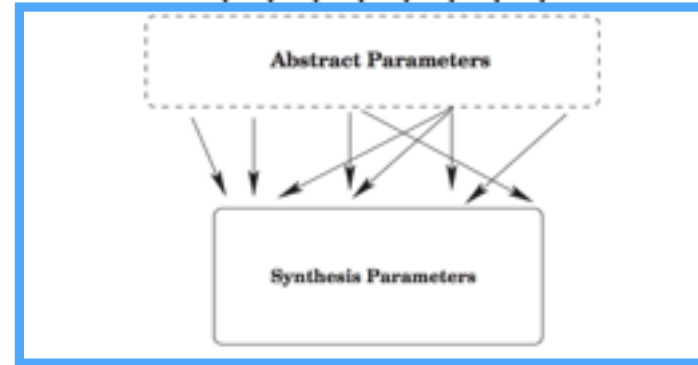


**o.io.wrapper**



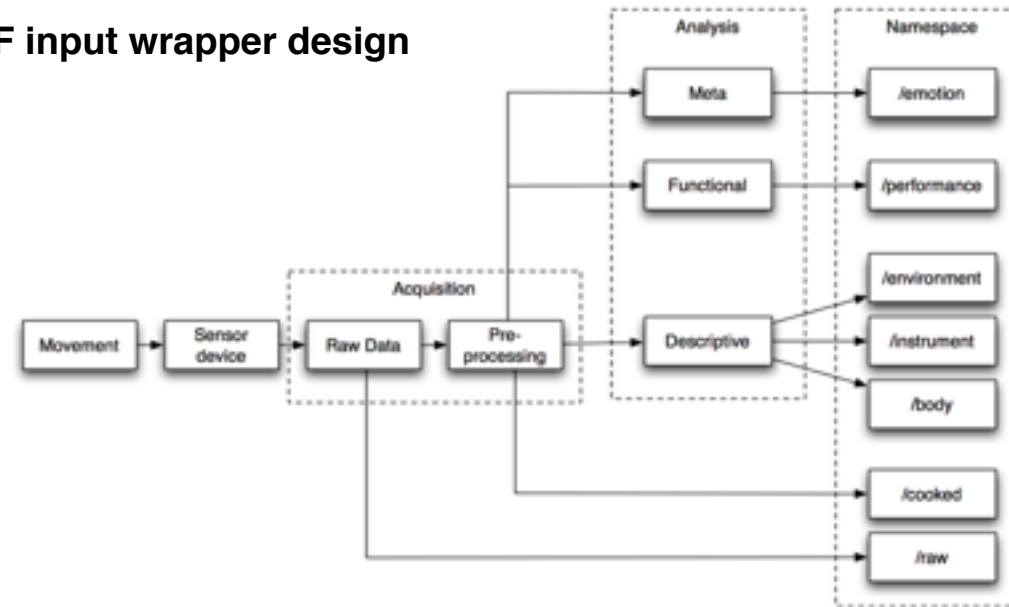
**mapping**

**o.io.wrapper**



o.io.wrappers function to handle translating OSC bundles into individual numbers that the synthesis engine understand.

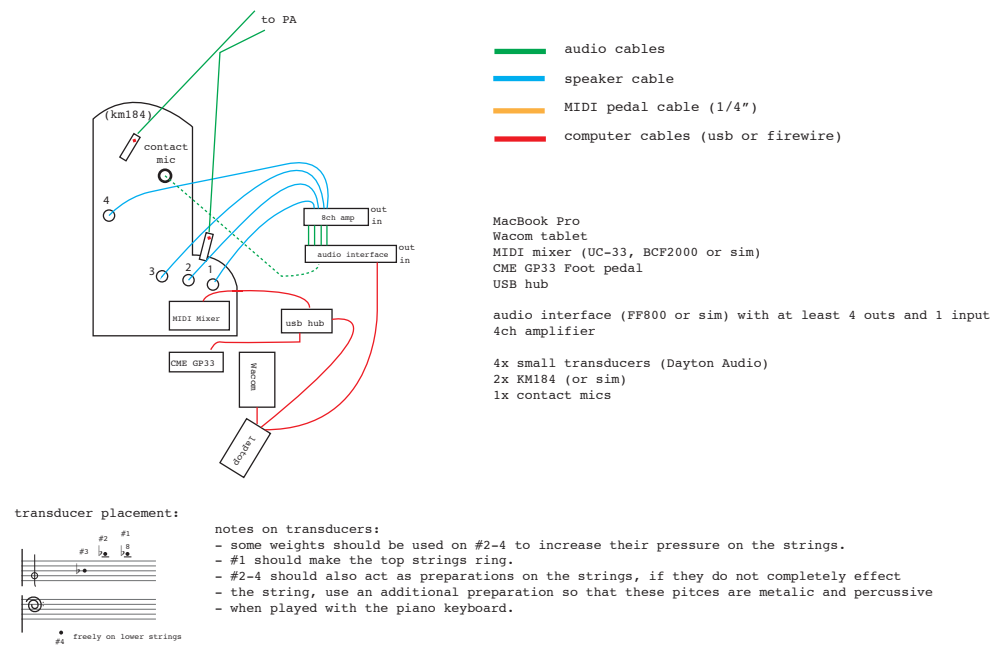
## GDIF input wrapper design



**Figure 9.3:** Sketch of the multilayered approach suggested for the GDIF OSC namespace.

Alexander Jensenius, a former student at CNMAT from Wanderly’s lab at McGill, developed the Gesture Description Interchange Format for his PhD thesis.

This approach is very closely related to the o.io.wrapper, where sensor data is translated into meaningful names, and analysis is applied to gather higher order information, like velocity, relative position, etc.



case study:

“spark” wacom-transducer-feedback instrument by rama gottfried