

# EE4C5 Digital Signal Processing

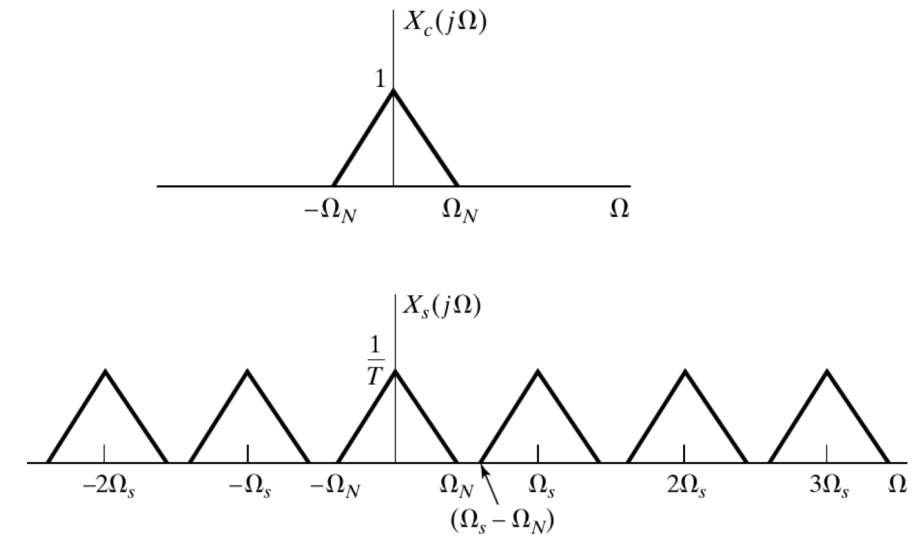
## Lecture 5 – Decimation and Interpolation

# This lecture

- Based on Chapter 4 of O&S
- All images from O&S book unless otherwise stated

# Recall...

- The impulse train approximation  $x_s(t)$  of the original continuous time signal  $x_c(t)$  has (continuous) Fourier Transform:
- $X_s(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s))$
- With  $T$  the sampling period,  $\Omega$  is the continuous-time frequency in radians/s, and  $\Omega_s (= 2\pi f_s)$  is the angular sampling frequency in radians/s
- Saw that  $X_s(j\Omega)$  comprises copies of  $X_c(j\Omega)$  shifted by  $k\Omega_s$  and scaled by  $\frac{1}{T}$



# Pay attention – discrete or continuous FT

- Can show that (how?)
  - $X_s(j\Omega) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\Omega nT}$
- The DTFT gives
  - $X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$
- So:
  - $X_s(j\Omega) = X(e^{j\omega}) \Big|_{\omega=\Omega T} = X(e^{j\Omega T})$
- Thus the DTFT  $X(e^{j\omega})$  is a frequency scaled version of  $X_s(j\Omega)$ , with the scaling specified by  $\omega = \Omega T$
- The above relates the CTFT to the DTFT

# Useful for later...

- Combining we get:
- $X(e^{j\Omega T}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\Omega - k\Omega_s))$
- Or equivalently
- $X(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c\left(j\left(\frac{\omega}{T} - \frac{2\pi k}{T}\right)\right)$

# Resampling a discrete-time sequence

- A continuous time signal  $x_c(t)$  can be represented by the discrete sequence  $x[n]$  where
  - $x[n] = x_c(nT), \quad -\infty < n < \infty$
- Often wish to change the sampling rate of  $x[n]$  such that
  - $x_1[n] = x_c(nT_1), \quad T_1 \neq T$
- This is resampling
- Could we reconstruct original  $x_c(t)$  and use new period  $T_1$ ?
  - Not practical
  - Restrict to discrete time operations

# Reduce sampling rate by integer factor M

- $x_d[n] = x[nM] = x_c(nMT)$
- With  $X_c(j\Omega)$  bandlimited to  $\pm\Omega_N$  then  $x_d[n]$  will be exact representation if  $\pi/T_d \geq \Omega_N$  or equivalently  $\pi/MT \geq \Omega_N$
- Can avoid aliasing if:
  - Original sampling rate is at least  $M$  times the Nyquist rate
  - Bandwidth of the sequence is first reduced by factor  $M$  by discrete-time filtering

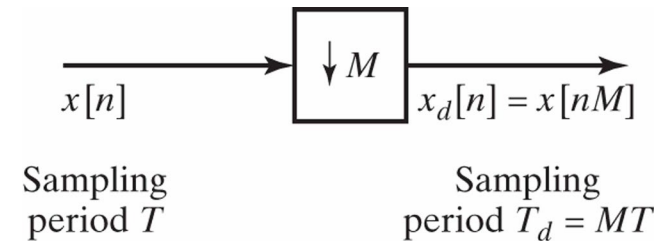


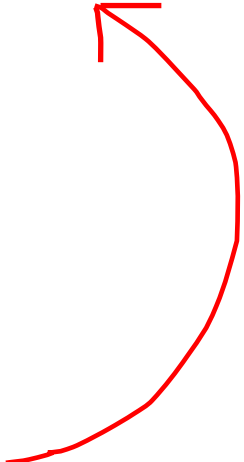
Figure 4.19 Representation of a compressor or discrete-time sampler.

# Reduce sampling rate by integer factor M

- Using  $X(e^{j\omega}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c \left( j \left( \frac{\omega}{T} - \frac{2\pi k}{T} \right) \right)$  (slide #5)
- DTFT of  $x_d[n] = x[nM] = x_c(nMT)$ 
  - $X_d(e^{j\omega}) = \frac{1}{T_d} \sum_{r=-\infty}^{\infty} X_c \left( j \left( \frac{\omega}{T_d} - \frac{2\pi r}{T_d} \right) \right)$
- But with  $T_d = MT$  can rewrite:
  - $X_d(e^{j\omega}) = \frac{1}{MT} \sum_{r=-\infty}^{\infty} X_c \left( j \left( \frac{\omega}{MT} - \frac{2\pi r}{MT} \right) \right)$



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  - DTFT of  $x_d[n] = x[nM] = x_c(nMT)$ 
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    - $X_d(e^{j\omega}) = \frac{1}{MT} \sum_{r=-\infty}^{\infty} X_c \left( j \left( \frac{\omega}{MT} - \frac{2\pi r}{MT} \right) \right)$
  - The summation index  $r$  is related as
    - $r = i + kM$
  - $k$  and  $i$  integers,  $-\infty < k < \infty$  and  $0 \leq i \leq M - 1$
- 
- Want to relate back

# Reduce sampling rate by integer factor M

- $X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} \left\{ \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c \left( j \left( \frac{\omega}{MT} - \frac{2\pi k}{T} - \frac{2\pi i}{MT} \right) \right) \right\}$
- Recognising that
  - $X(e^{j(\omega-2\pi i/M)}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c \left( j \left( \frac{\omega-2\pi i}{MT} - \frac{2\pi k}{T} \right) \right)$
- Can arrive at:
  - $X_d(e^{j\omega}) = \frac{1}{M} \sum_{i=0}^{M-1} X(e^{j(\omega-2\pi i/M)})$
- Expresses FT of  $x_d[n]$  in terms of FT of  $x[n]$
- $X_d(e^{j\omega})$  consists of copies of  $X(e^{j\omega})$  scaled by  $\frac{1}{M}$ , and frequency scaled by  $\frac{1}{M}$  and shifted by  $2\pi i$ .

# Avoid aliasing...

- $X_d(e^{j\omega})$  periodic with period  $2\pi$  (like all DTFT!!)
- Can avoid aliasing if  $X(e^{j\omega})$  is bandlimited, i.e.
- $X(e^{j\omega}) = 0 \quad \omega_N \leq |\omega| \leq \pi$
- And  $2\pi/M \geq 2\omega_N$
- Example shown opposite has  $M=2$ , at the limit to avoid aliasing here

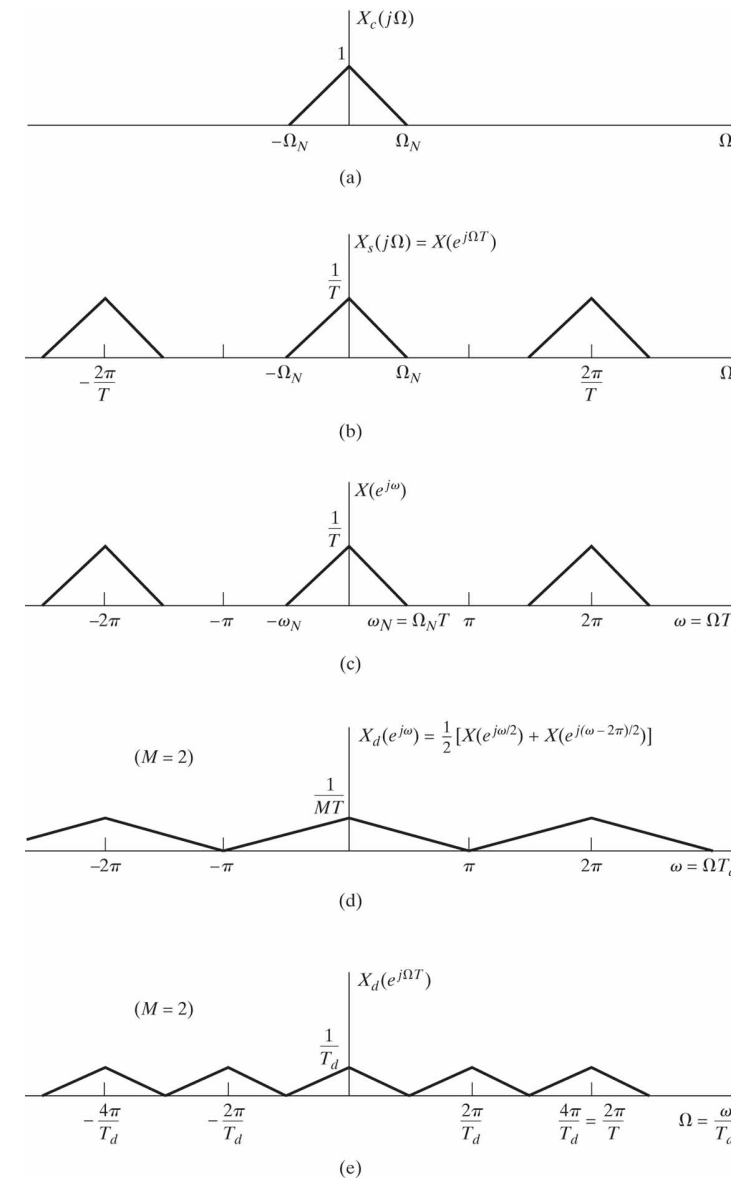


Figure 4.20 Frequency-domain illustration of downsampling.

# Aliasing with M=3

- Will get aliasing with M=3
- Prefilter to avoid this and bandlimit the signal

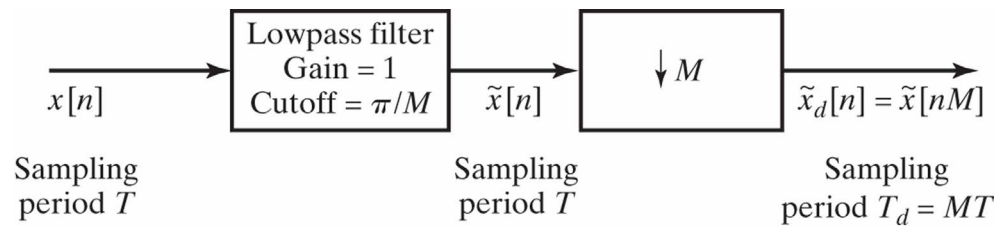


Figure 4.22 General system for sampling rate reduction by  $M$ .

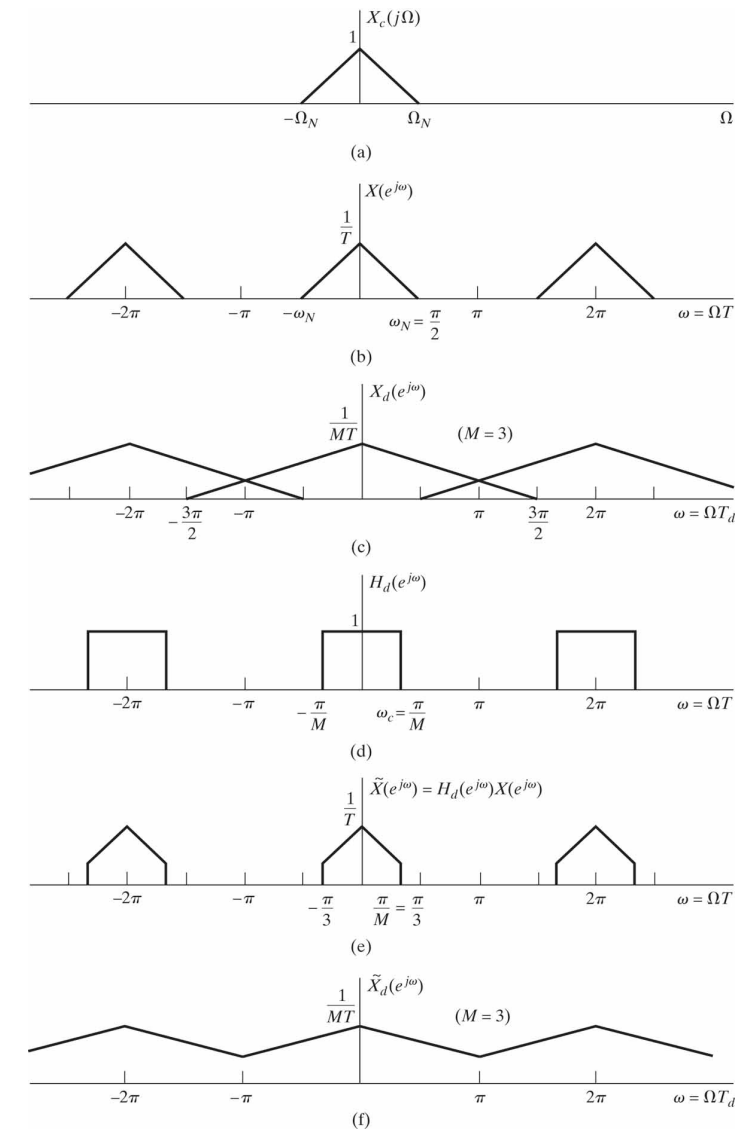


Figure 4.21 (a)–(c) Downsampling with aliasing. (d)–(f) Downsampling with prefiltering to avoid aliasing.

# Increase sampling rate by integer factor

- Increase sampling rate of  $x[n]$  by integer factor  $L$
- Want
  - $x_i[n] = x_c(nT_i), \quad T_i = T/L$
- Where you can take the samples from
  - $x[n] = x_c(nT)$
- This is upsampling
  - $x_i[n] = x[n/L] = x_c(nT/L), \quad n = 0, \pm L, \pm 2L, \dots$
-

# System

- Note distinction between  $x_i[n]$  and  $x_e[n]$
- $x_e[n] = \sum_{k=-\infty}^{\infty} x[k] \delta[n - kL]$
- $x_e[n] = \begin{cases} x[n/L], & n = 0, \pm L, \pm 2L, \dots \\ 0, & \text{otherwise} \end{cases}$
- Expander
- LPF the reconstructs the sequence

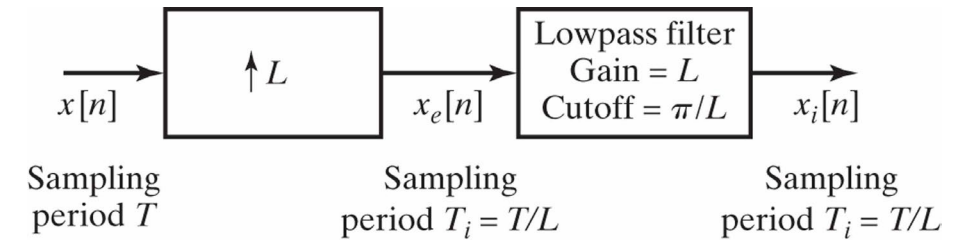
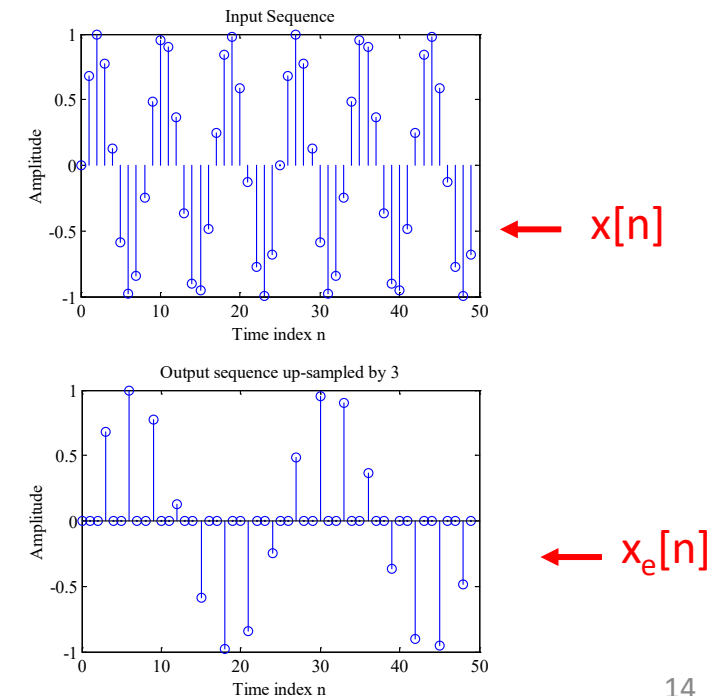


Figure 4.23 General system for sampling rate increase by  $L$ .



# Increase sampling rate by integer factor

- Frequency domain interpretation, can express the FT as:
- $X_e(e^{j\omega}) = \sum_{n=-\infty}^{\infty} (\sum_{k=-\infty}^{\infty} x[k] \delta[n - kL]) e^{-j\omega n}$
- $= \sum_{k=-\infty}^{\infty} x[k] e^{-j\omega Lk} = X_e(e^{j\omega L})$
- So FT of output of expander is a frequency scaled version of FT of the input,  $\omega \rightarrow \omega L$  with  $\omega$  now normalised by
- $\omega = \Omega T_i$

# Get the desired signal

- $X_i(e^{j\omega})$  can be obtained from  $X_e(e^{j\omega})$  by correcting the amplitude scaling from  $1/T$  to  $1/T_i$  and removing all frequency-scaled images of  $X_c(j\Omega)$  except at integer multiples of  $2\pi$
- This requires a lowpass filter, gain of  $L$  and cut-off frequency  $\pi/L$

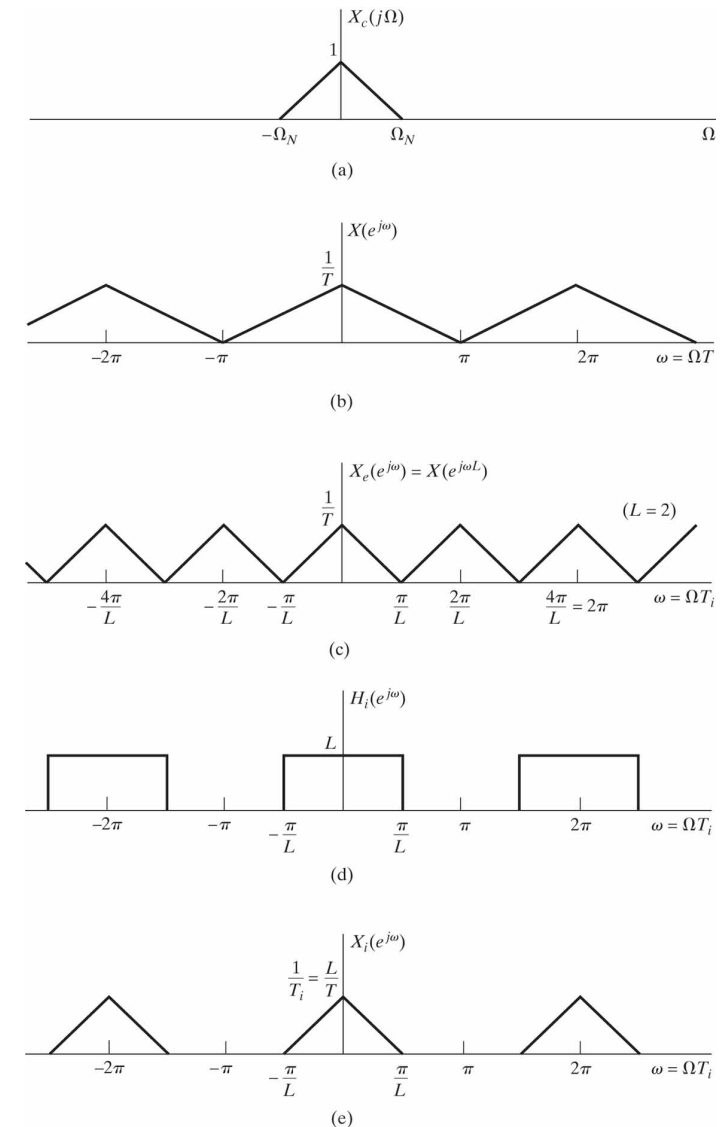


Figure 4.24 Frequency-domain illustration of interpolation.



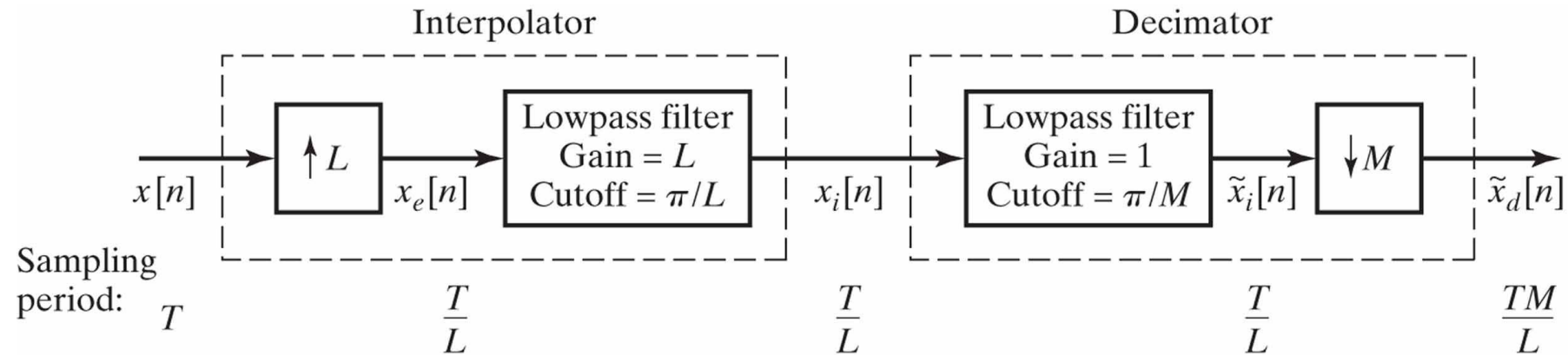
# Interpolation

- Can view this as interpolation in the time domain
- Impulse response of the LPF is
  - $h_i[n] = \frac{\sin(\pi n/L)}{\pi n/L}$
- Can see that:
  - $x_i[n] = \sum_{k=-\infty}^{\infty} x[k] \frac{\sin(\pi(n-kL)/L)}{\pi(n-kL)/L}$
- Ideal case  $h_i[0] = 1$  and  $h_i[n] = 0$   $n = \pm L, \pm 2L, \dots$
- Can show (you should try!) this gives:
  - $x_i[n] = x[n/L] = x_c[nT/L] = x_c(nT_i)$

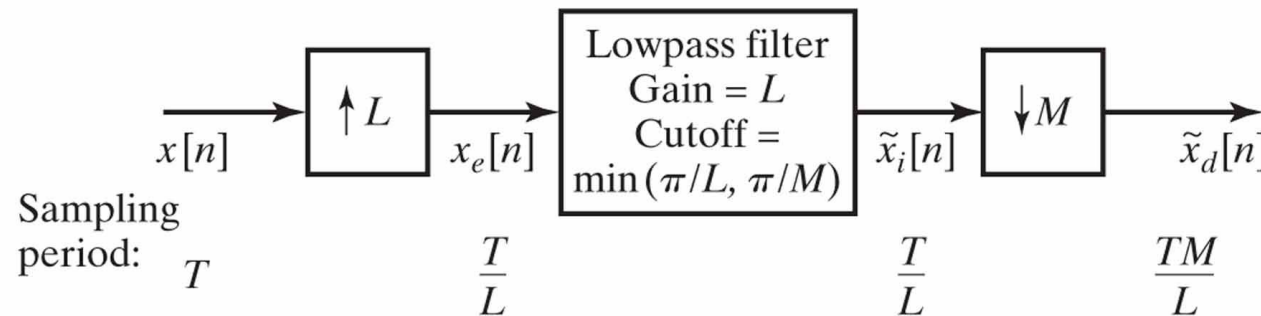
# Practical Interpolation

- We looked at the ideal LPF
- Can only be approximated in reality
- Linear interpolation can be useful
  - Simplicity/accuracy tradeoff

# Change sample rate by non-integer factor



(a)



(b)

Combine decimation  
and interpolation

Figure 4.29 (a) System for changing the sampling rate by a noninteger factor. (b) Simplified system in which the decimation and interpolation filters are combined.

# Required Reading & other material

- Oppenheim & Schafer, Chapter 4, particularly 4.6