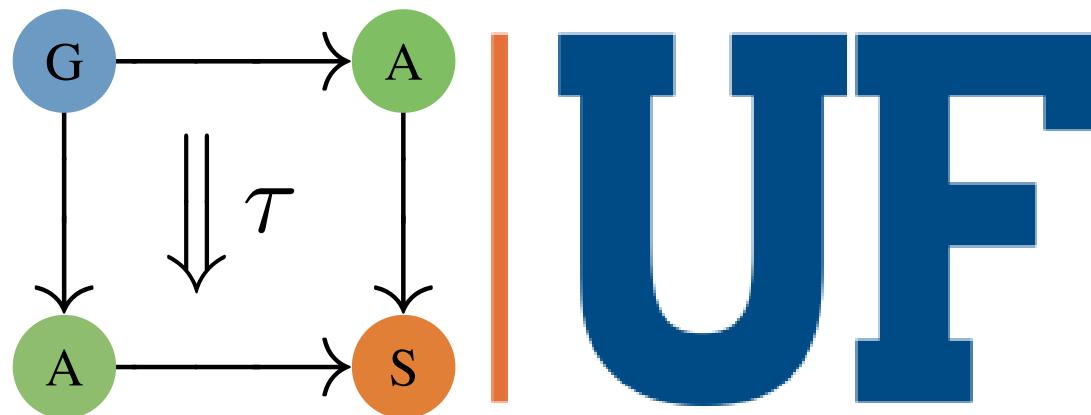


# Scientific Modeling with Categories

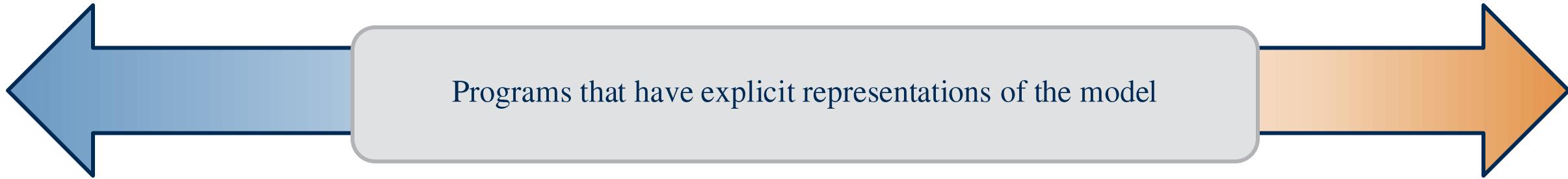
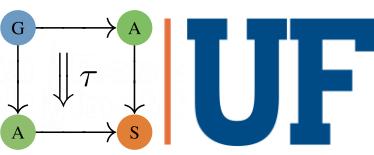
7/7/2025

James Fairbanks



UF

# Spectrum of Scientific Computing Technology

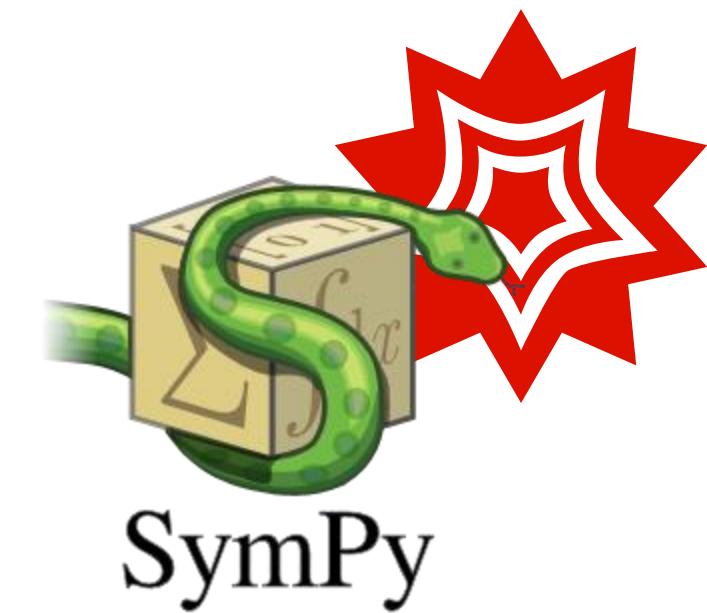
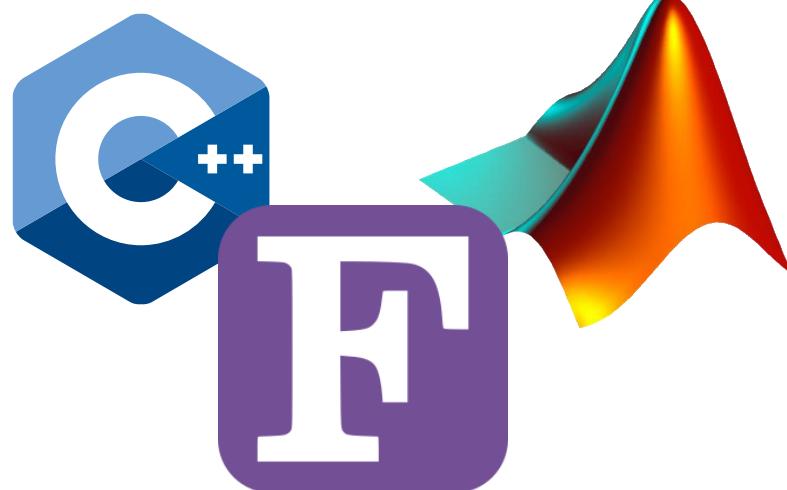


Arbitrary  
Code

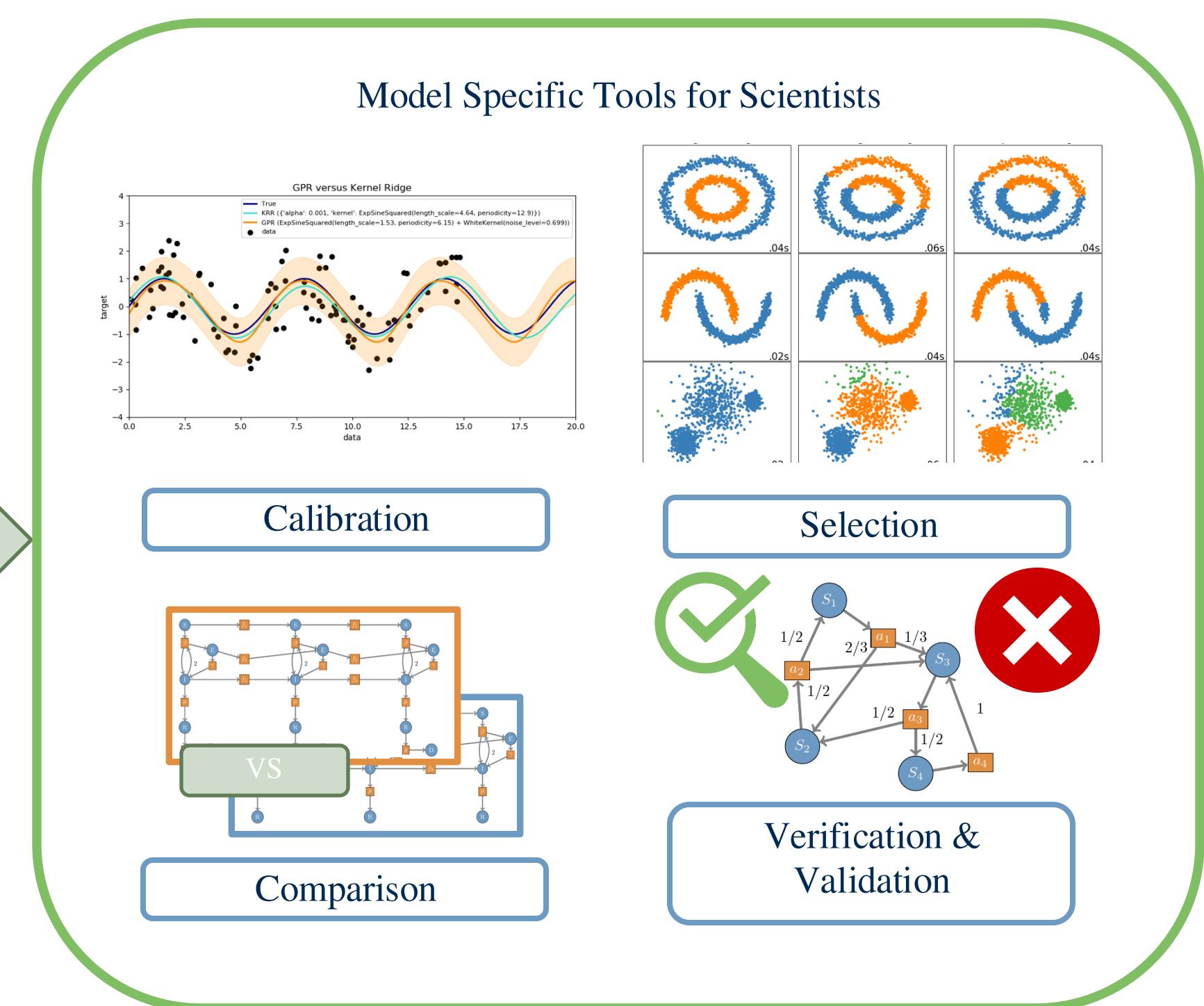
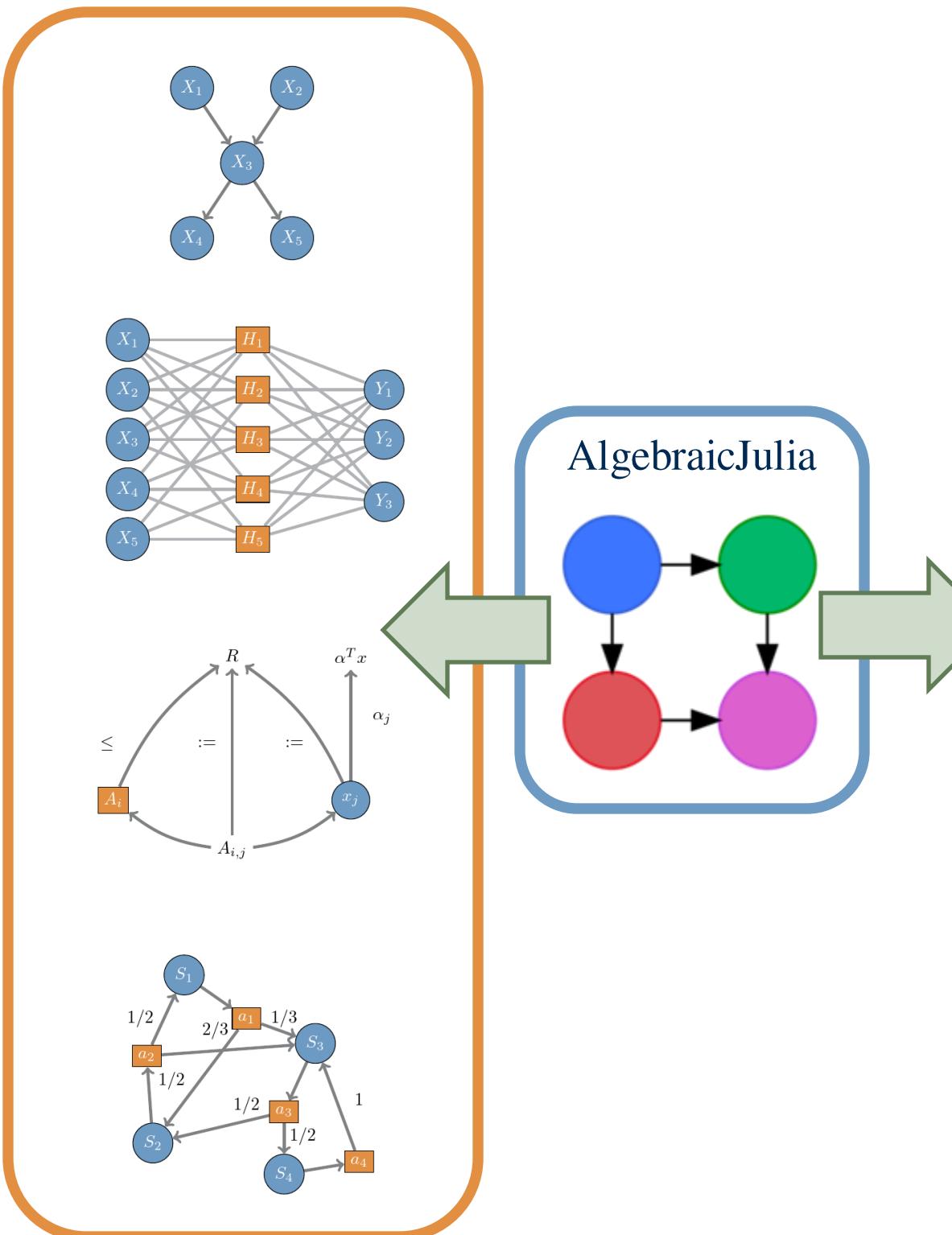
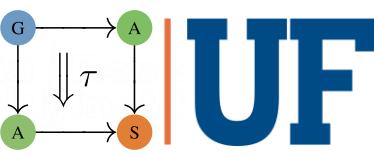
Domain  
Specific  
Languages

Modeling  
Frameworks

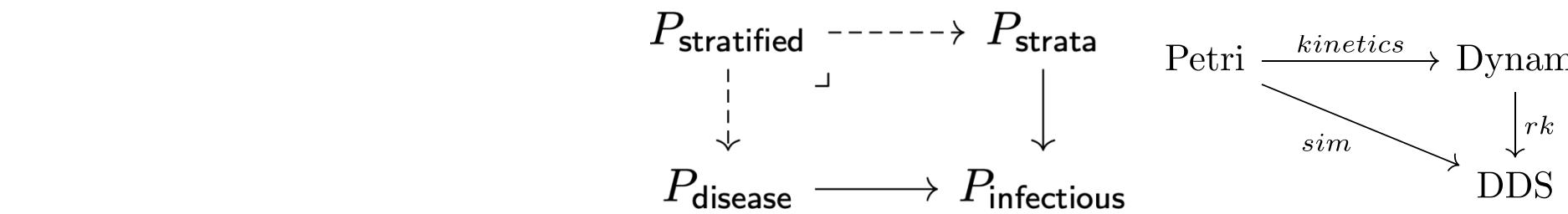
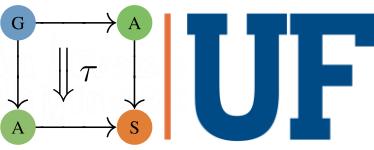
Computer  
Algebra  
Systems



# Vision: Model Aware Scientific Computing with Categories



# Two Paths to Applying Category Theory to Scientific Computing



Math  $\xrightarrow{\text{ACT}}$  CT

formalization

$$\frac{x : \sigma \in \Gamma}{\Gamma \vdash_D x : \sigma}$$

$$\frac{\Gamma \vdash_D e_0 : \tau \rightarrow \tau' \quad \Gamma \vdash_D e_1 : \tau}{\Gamma \vdash_D e_0 e_1 : \tau'}$$

$$\frac{\Gamma, x : \tau \vdash_D e : \tau'}{\Gamma \vdash_D \lambda x . e : \tau \rightarrow \tau'}$$

Logic  $\xrightarrow{\text{Func. Prog.}}$  Code

```

rungekutta:: Float -> Float -> Float
f:: Float -> Float -> Float
scanl::(a -> a -> a) -> (a,a) -> List a -> List a
rungekutta (t, y) t' = (t', y + h*(k1 + 2.0*k2 + 2.0*k3 + k4)/6.0)
  where
    h = t' - t
    k1 = f t y
    k2 = f (t + 0.5*h) (y + 0.5*h*k1)
    k3 = f (t + 0.5*h) (y + 0.5*h*k2)
    k4 = f (t + 1.0*h) (y + 1.0*h*k3)

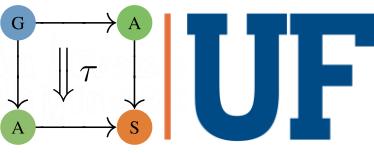
f t y = (t**2 - y**2)*sin(y)
scanl rungekutta (0, -1) [0.01, 0.03, 0.04, 0.06]
  
```

```

function stratify(disease::Petri, strata::Petri)
  stratified = pullback(disease, strata)
  return object(stratified)
end
function sim(P::Petri)
  prob = ODEProblem(kinetics(P))
  return solve(prob, (t₀,tᵑ), alg=RungeKutta())
end
  
```

AlgebraicJulia

# Operad Algebras of Dynamical Systems



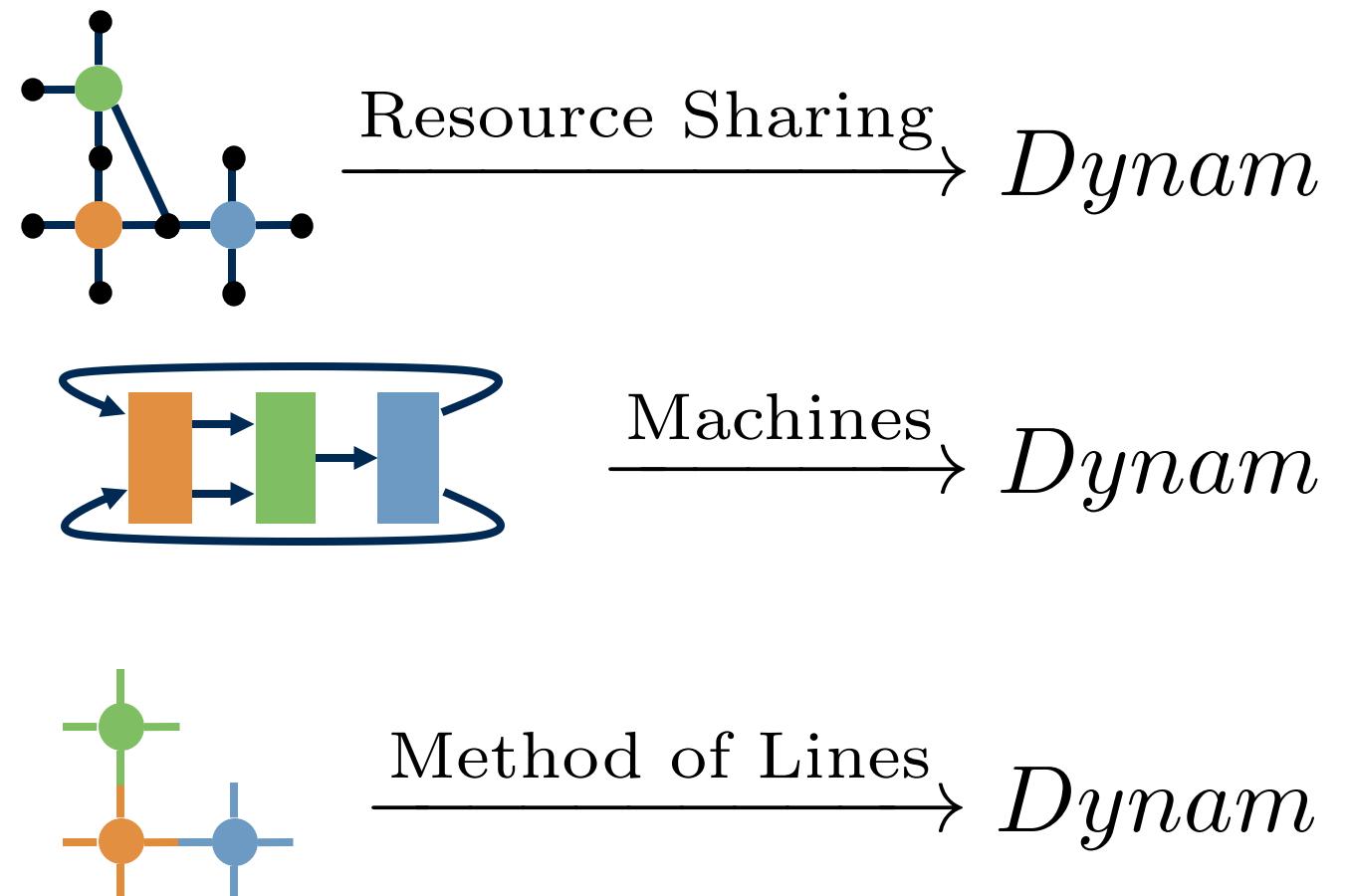
## Operad Algebra

*Compose and then Apply*  
=

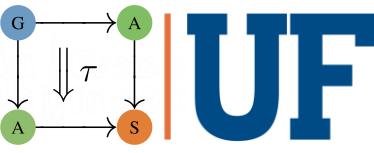
*Apply and then Compose*

- An Operad defines a *way of composing*
- Operads form a Category
- Functors from an Operad  $O$  to Set are *Operad Algebras or Algebras of  $O$*
- $Dynam \subset Set$  has sets of dynamical systems as objects
- Analogous to *Group Actions*

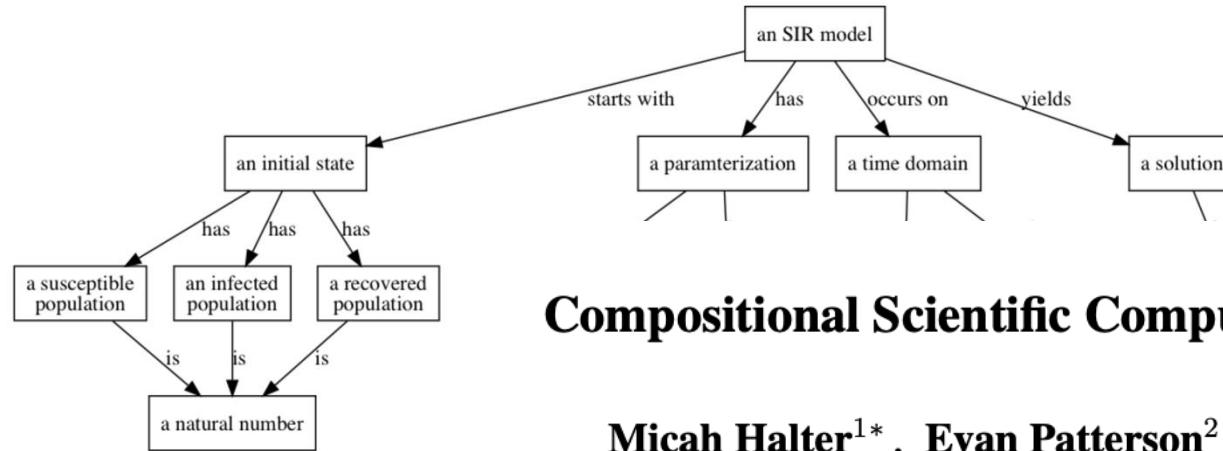
$$O \xrightarrow{F} Set$$



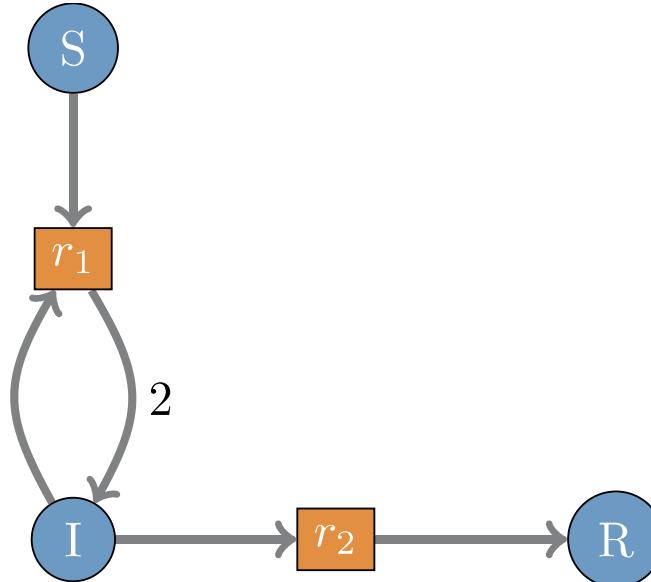
# DARPA ASKE: Layers of Modeling



## 1) Structural knowledge layer



## 2) System



## 3) Model semantics layer

$$\dot{u}_1 = -r_1 u_1 u_2$$

$$\dot{u}_2 = r_1 u_1 u_2 - r_3 u_2$$



## Compositional Scientific Computing with Catlab and SemanticModels

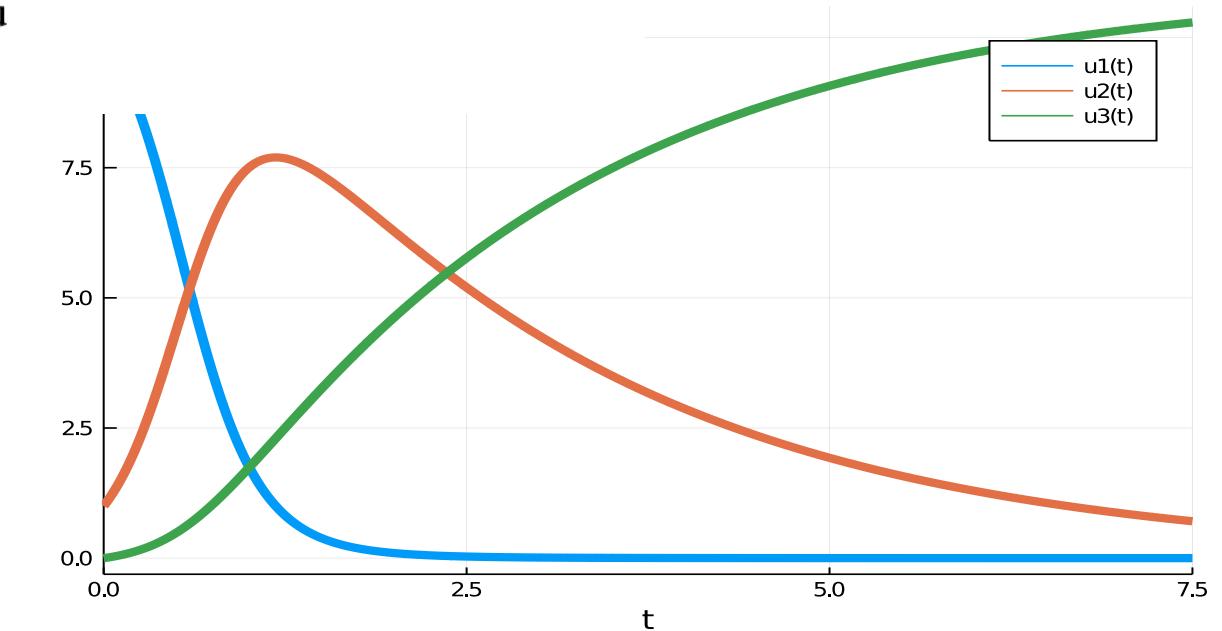
Micah Halter<sup>1\*</sup>, Evan Patterson<sup>2</sup>, Andrew Baas<sup>1</sup> and James P. Fairbanks<sup>1</sup>

<sup>1</sup>Georgia Tech Research Institute, Atlanta, GA USA

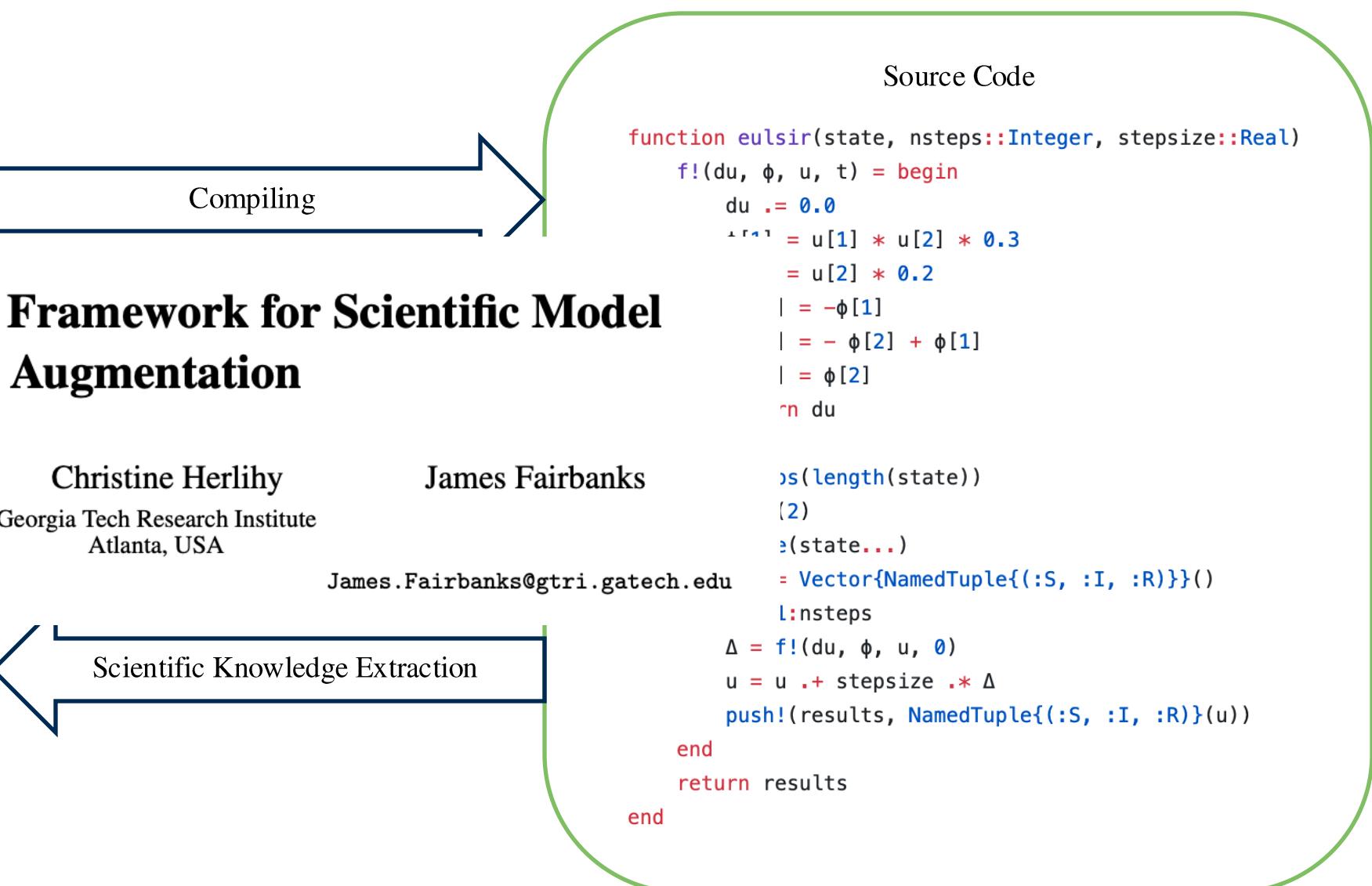
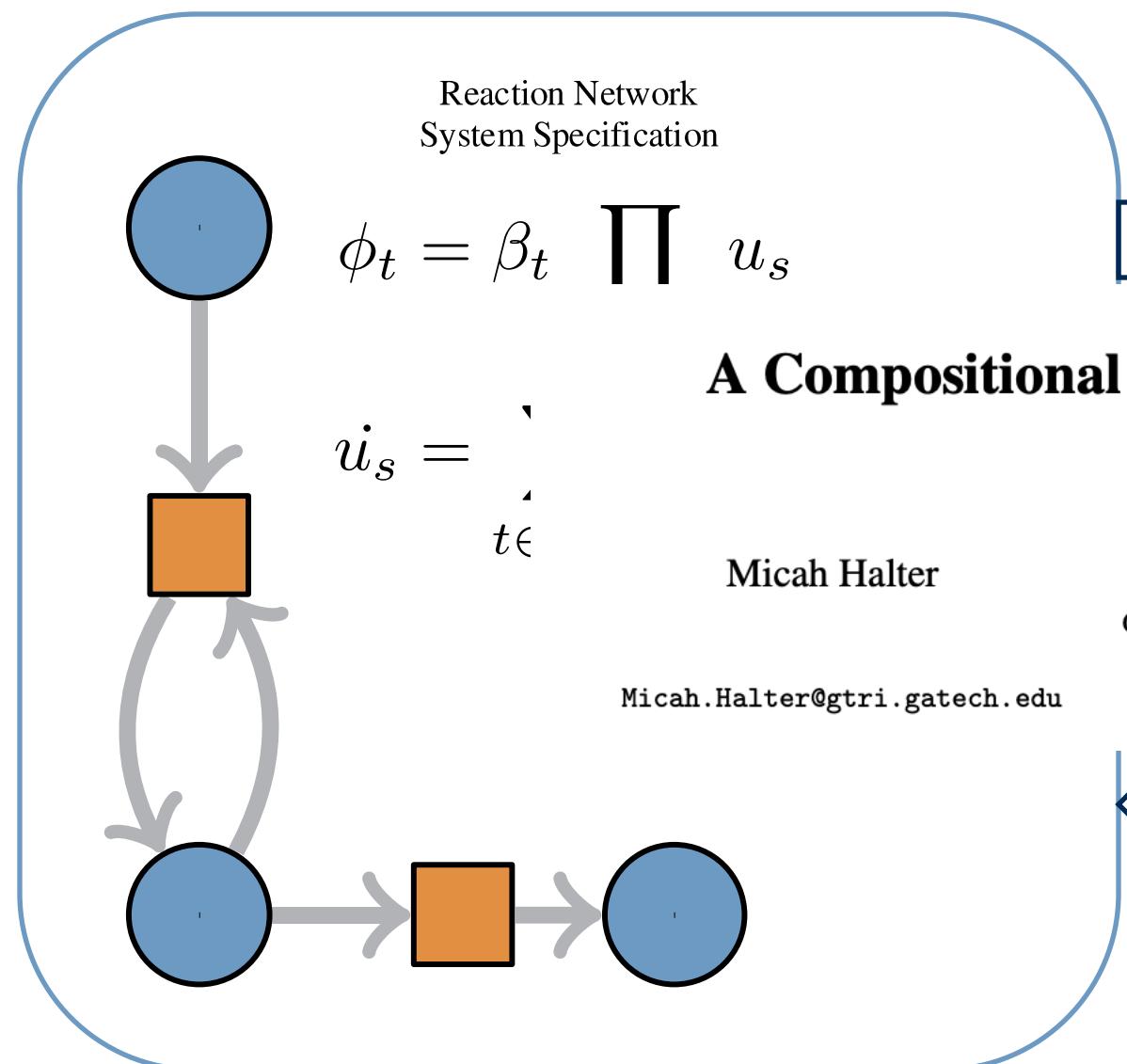
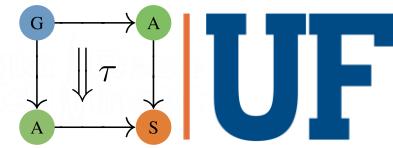
<sup>2</sup>Stanford University, Stanford, CA USA

micah.halter@gtri.gatech.edu

## solution layer

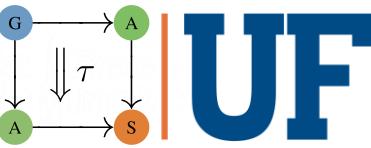


# DARPA ASKE: Scientific Knowledge Extraction

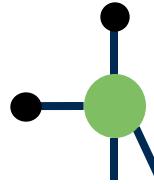


Extracting Knowledge from legacy simulators  
to accelerate adaptation and discovery

# Landscape of Composition



Operads implemented with ACSets



## Operadic Modeling of Dynamical Systems: Mathematics and Computation

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James Fairbanks

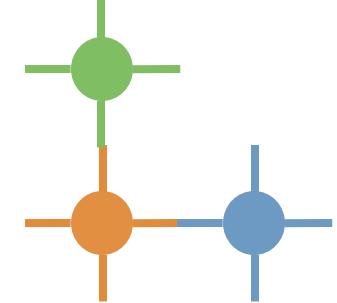
University of Florida  
Gainesville, Florida, USA  
[fairbanksj@ufl.edu](mailto:fairbanksj@ufl.edu)

Operad Algebras

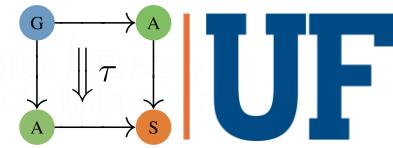
Dynamical Systems (ODEs)

A large blue curved arrow points from the 'Operadic Modeling...' section towards a mathematical equation. The equation is:
$$\begin{bmatrix} \dot{u}_1 \\ \dot{u}_2 \\ \dot{u}_3 \end{bmatrix} = f \left( \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix} \right)$$

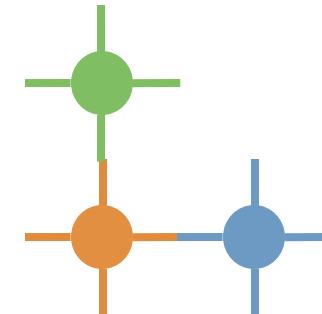
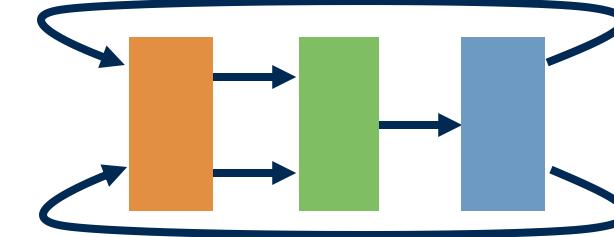
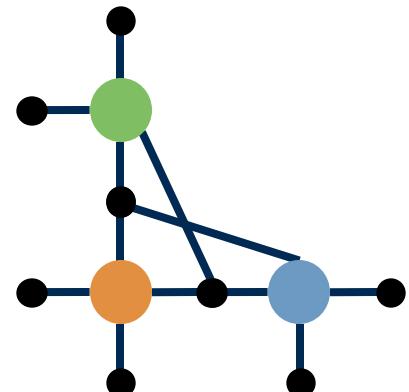
ines  
FDTD



# Application Achievement: Solving ODEs and PDEs

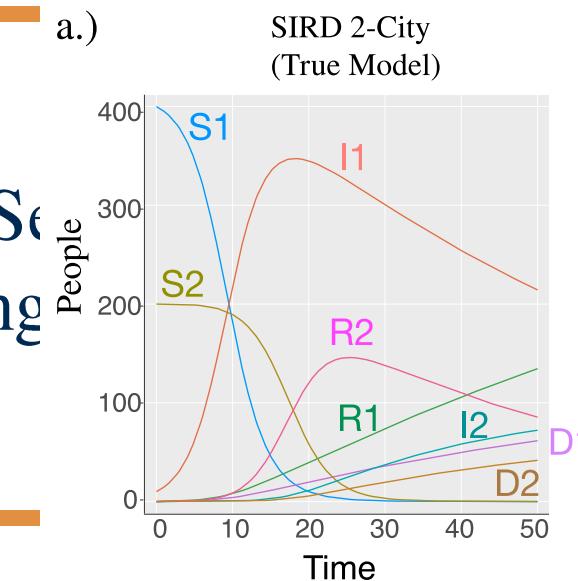


Languages for  
Hierarchical System  
Descriptions



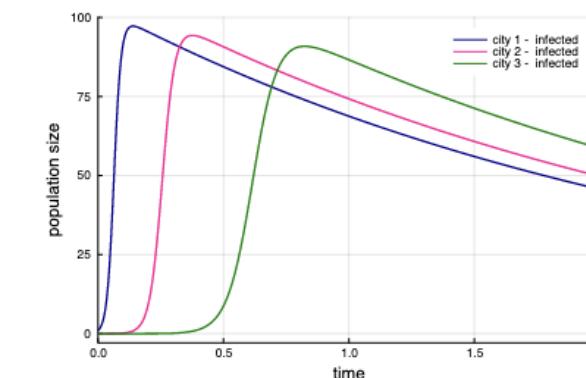
Mathematical Interpreters

Variable Sharing  
(Biology)

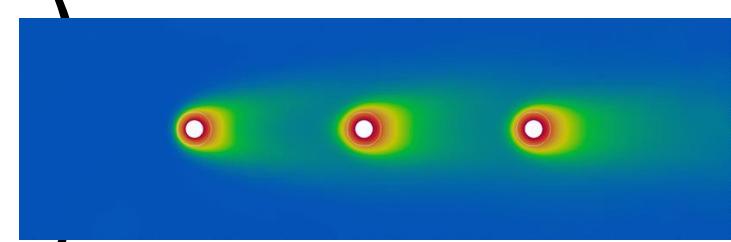


Common Dynamical Systems  
Support simulation with existing

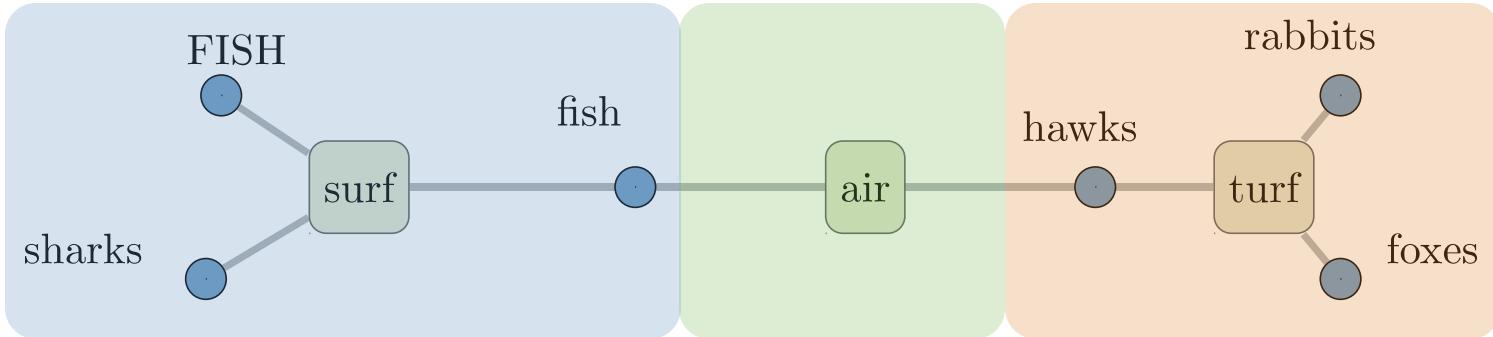
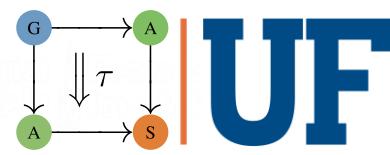
Signal Flow  
(Electronics / Controls)



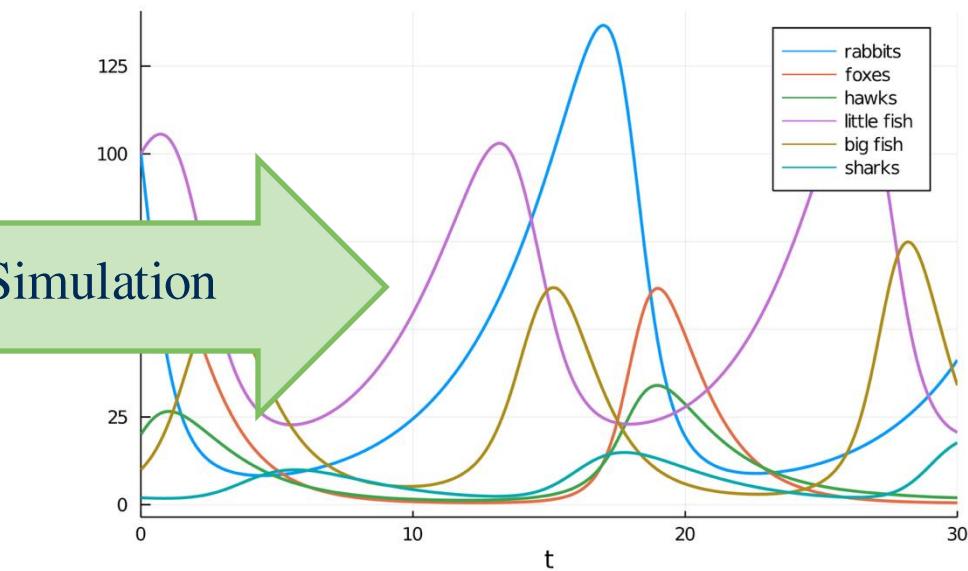
FEM/Stencils  
(Physics)



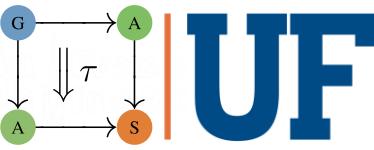
# Hierarchy is a Fundamental Tool for Understanding



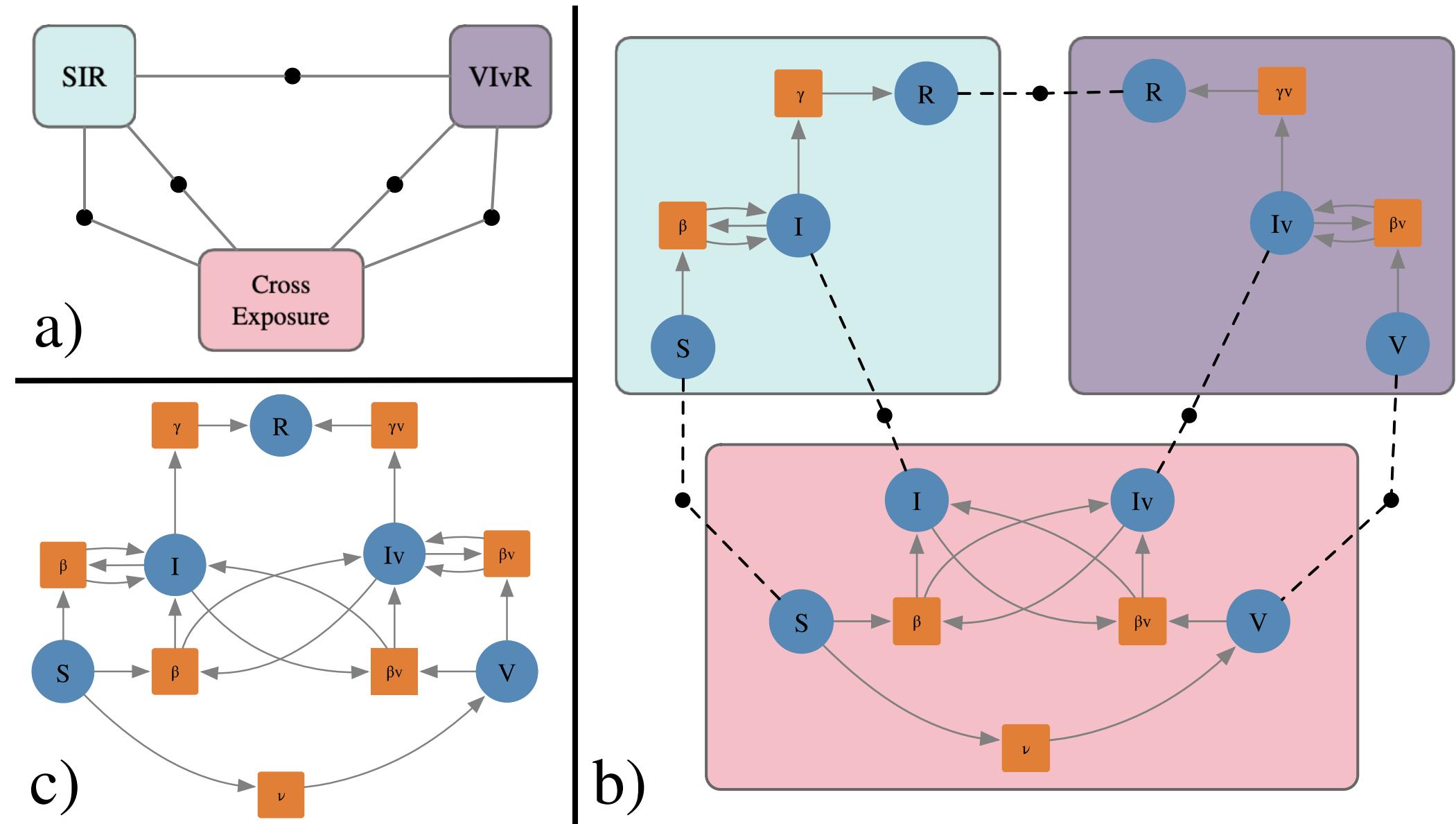
Can we combine denotational semantics and network science to understand hierarchical structures in complex systems?



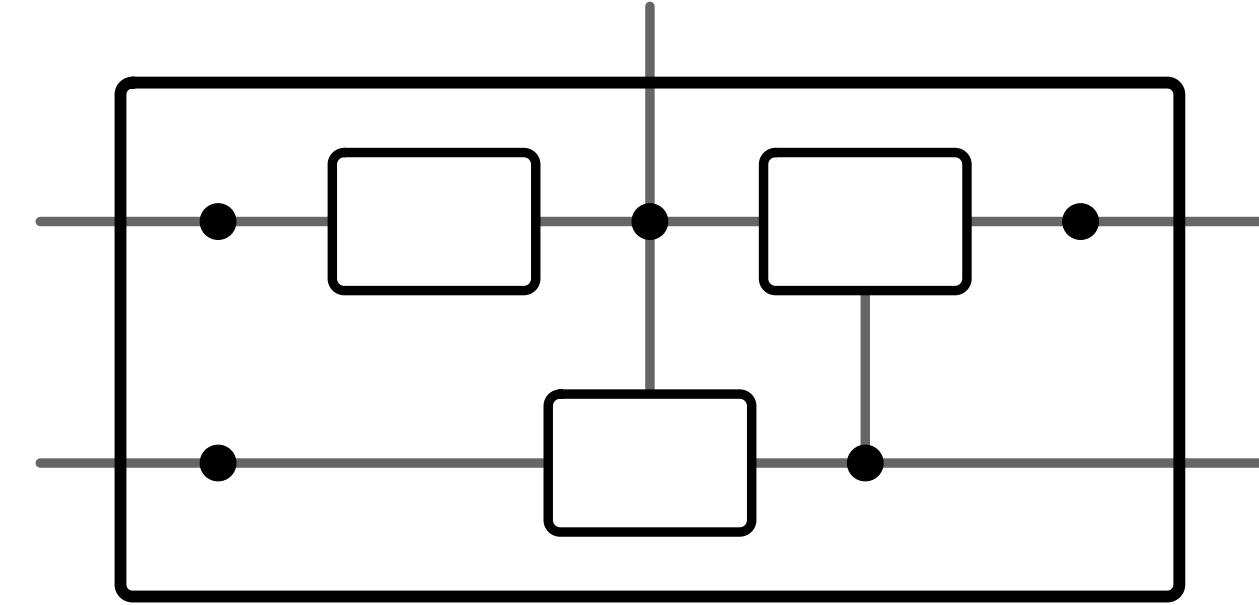
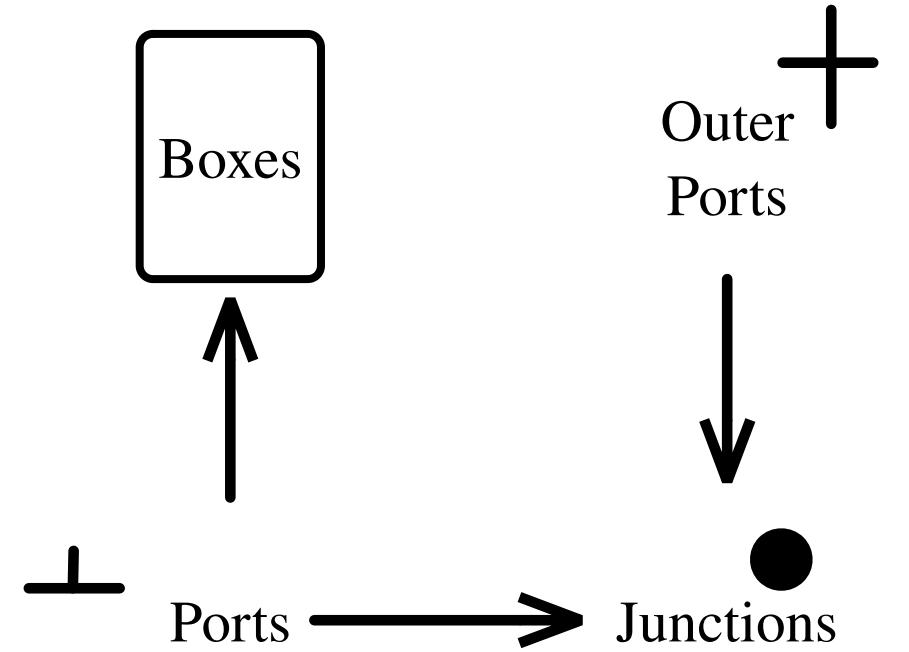
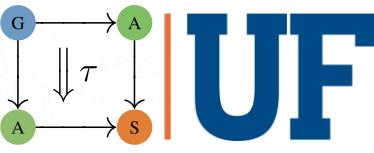
# Composing Compartmental Models with UWDs



- a) Pattern of shared variables between subsystems
- b) The component subsystems
- c) The composite system

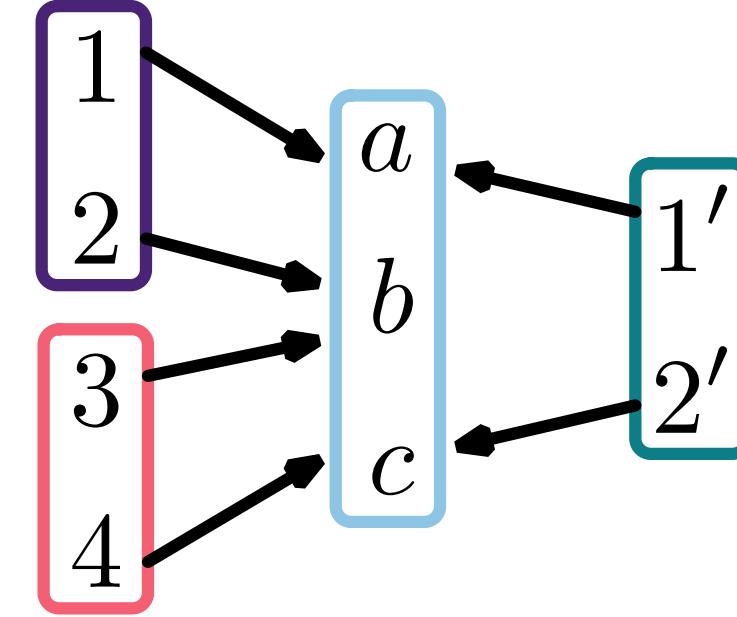
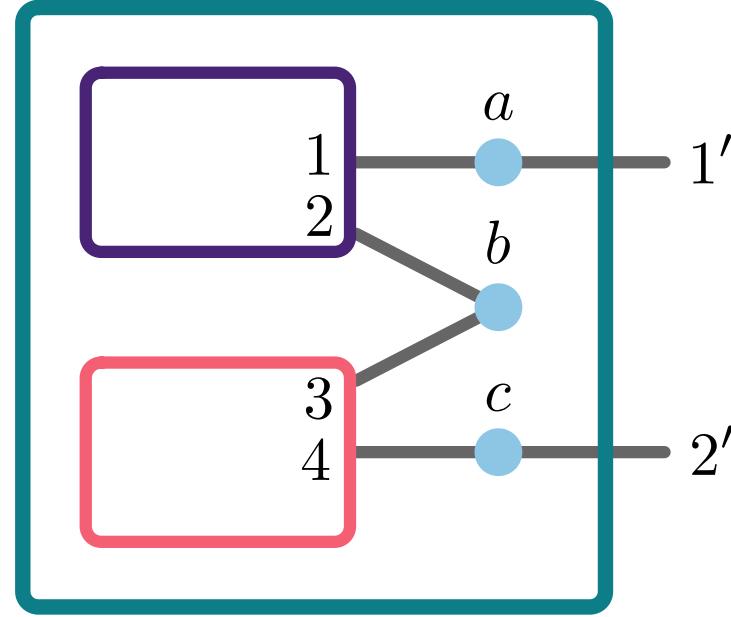
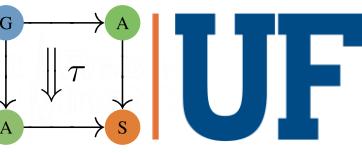


# Undirected Wiring Diagrams



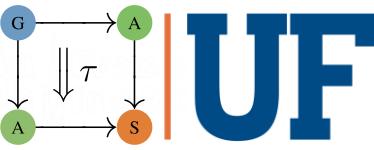
- UWDs provide a syntax for systems that compose without orientation
- No distinction between inputs vs outputs just interfaces

# Undirected Wiring Diagrams



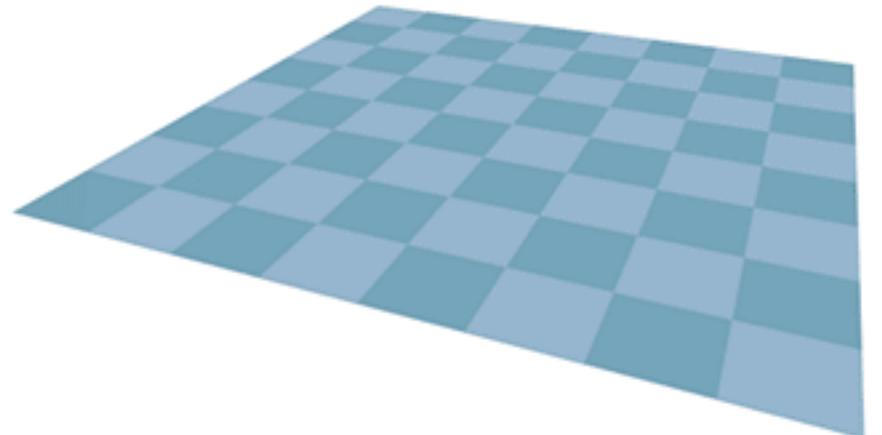
- UWDs provide a syntax for systems that compose without orientation
- No distinction between inputs vs outputs just interfaces

# Colimits build large objects by gluing



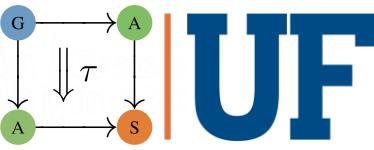
- The torus is a colimit by gluing the edges together with coequalizers
- Coequalizers are a standard form of merging parts of an object together with an equivalence relation

$$\begin{array}{ccccc} & & \text{top} & & \\ [0, 1] & \xrightarrow{\hspace{3cm}} & [0, 1]^2 & \xrightarrow{K} & [0, 1] \times S_1 \\ & \xrightarrow{\hspace{3cm}} & & & \\ & bottom & & & \\ \\ S_1 & \xrightarrow{\hspace{3cm}} & [0, 1] \times S_1 & \longrightarrow & \mathbb{T} = S_1 \times S_1 \\ & \xrightarrow{\hspace{3cm}} & & & \\ & left & & & \\ & & & & \\ & right & & & \end{array}$$

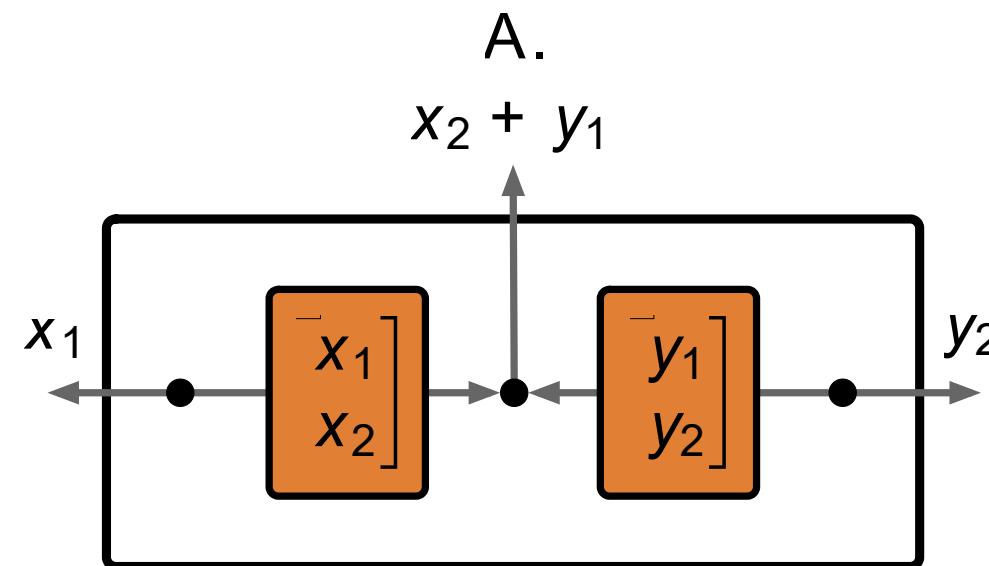


[https://upload.wikimedia.org/wikipedia/commons/6/60/Torus\\_from\\_rectangle.gif](https://upload.wikimedia.org/wikipedia/commons/6/60/Torus_from_rectangle.gif)

# Information Flow For Composite Systems

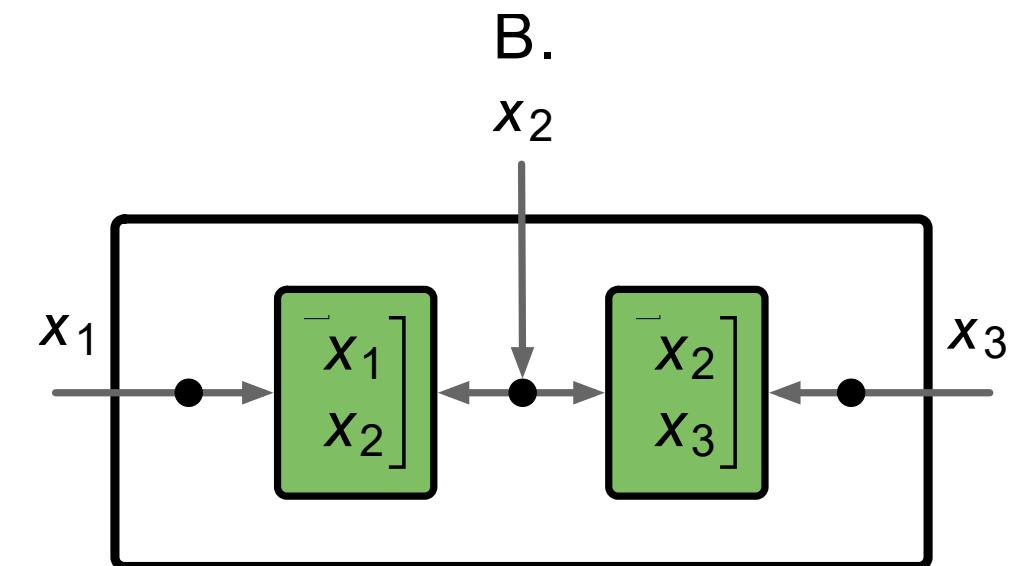


- The simplest notion of system on  $n$  variables is just vectors
- We combine systems with linear maps that merge/share information



$$\Phi_{\leftarrow} (x_1, x_2), (y_1, y_2) = (x_1, x_2 + y_1, y_2)$$

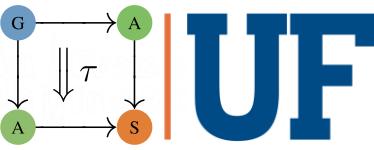
$$M(\Phi_{\leftarrow}) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



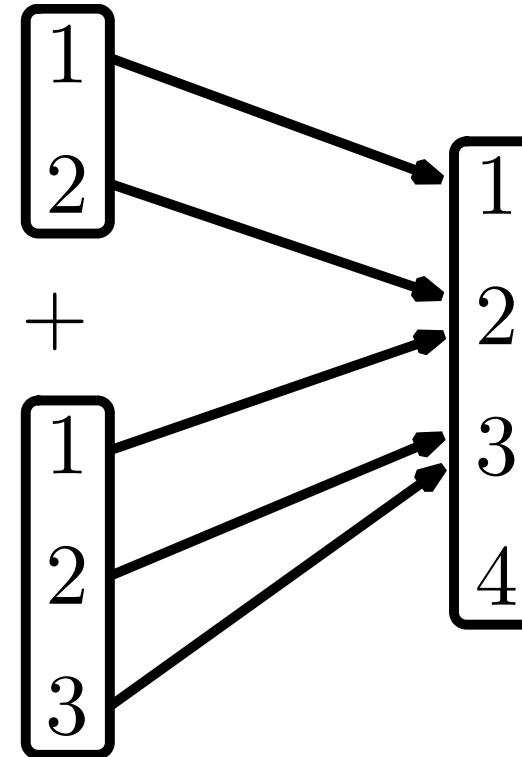
$$\Phi^{\leftarrow}(x_1, x_2, x_3) = (x_1, x_2, x_3)$$

$$M(\Phi^{\leftarrow}) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = M(\Phi_{\leftarrow})^T$$

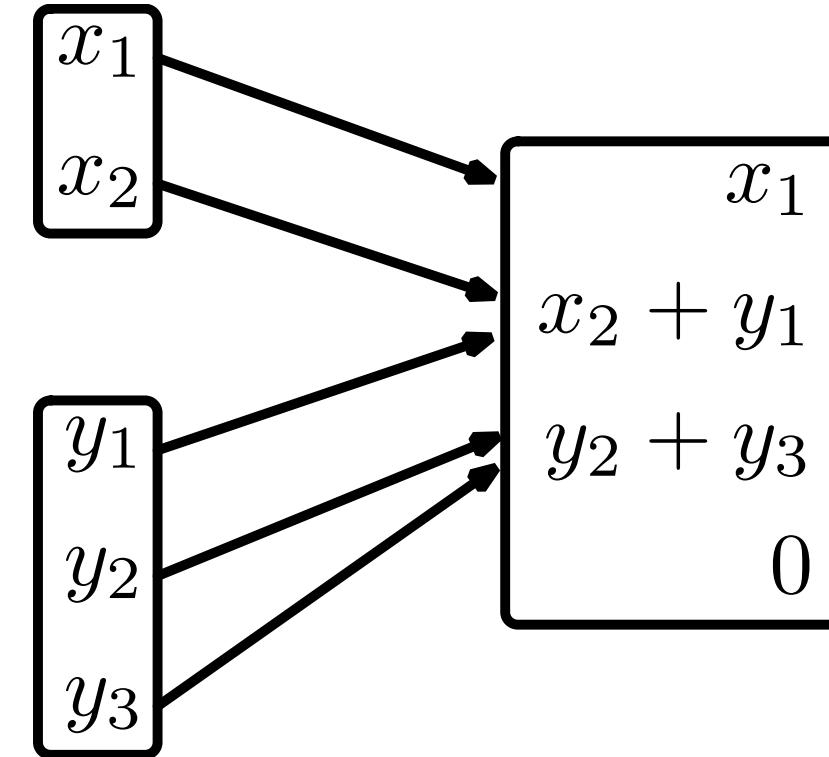
# Information Flow For Composite Systems



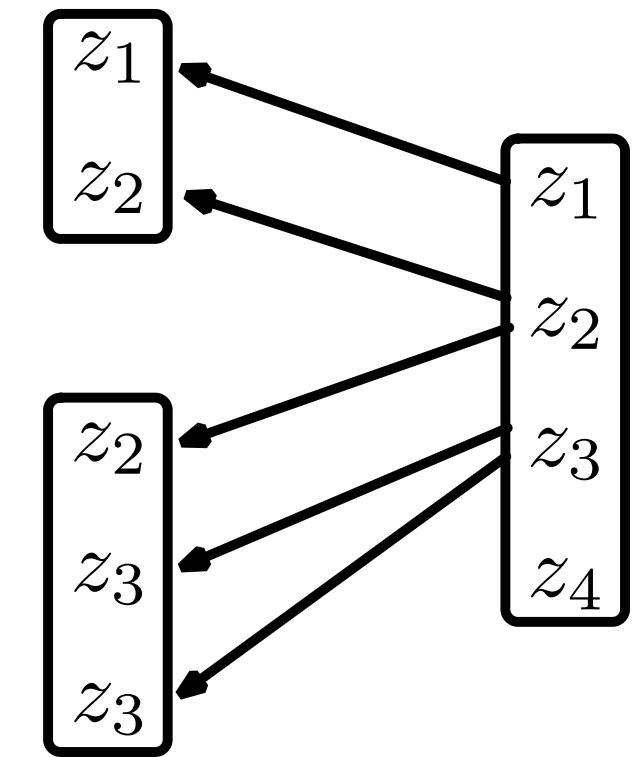
- The simplest notion of system on  $n$  variables is just vectors
- We combine systems with linear maps that merge/share information



$$\phi: [2] + [3] \rightarrow [4]$$

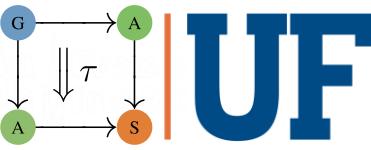


$$\phi_*(x, y): \mathbb{R}^2 \times \mathbb{R}^3 \rightarrow \mathbb{R}^4$$



$$\phi^*(z): \mathbb{R}^4 \rightarrow \mathbb{R}^2 \times \mathbb{R}^3$$

# Composing Dynamical Systems



**Example 2.12** (Composing Dynamical Systems). There is a finset algebra  $\text{Dynam}: (\text{FinSet}, +) \rightarrow (\text{Set}, \times)$  given by the following maps:

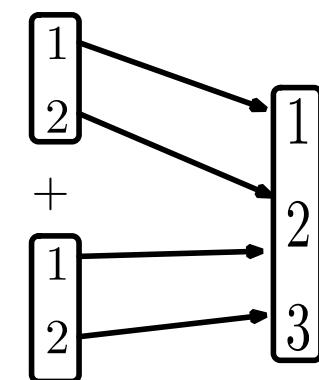
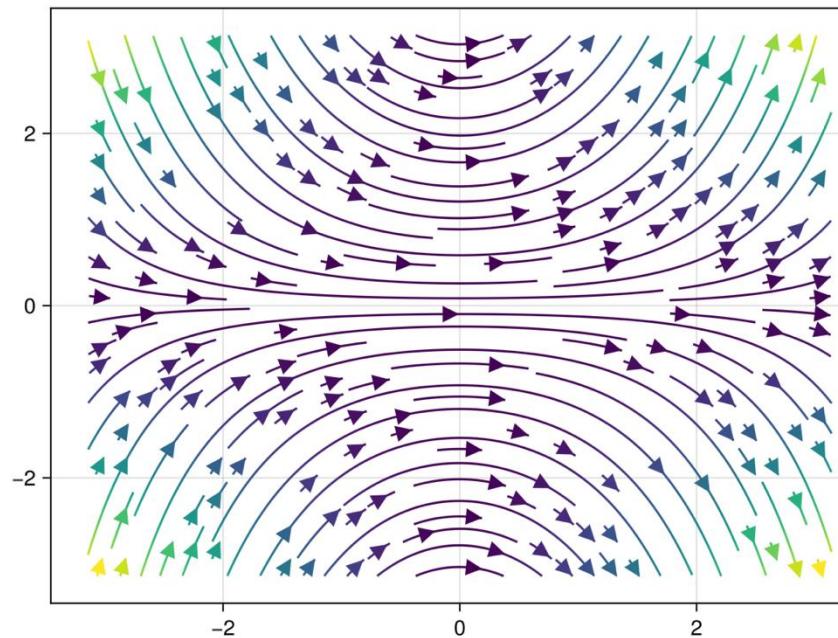
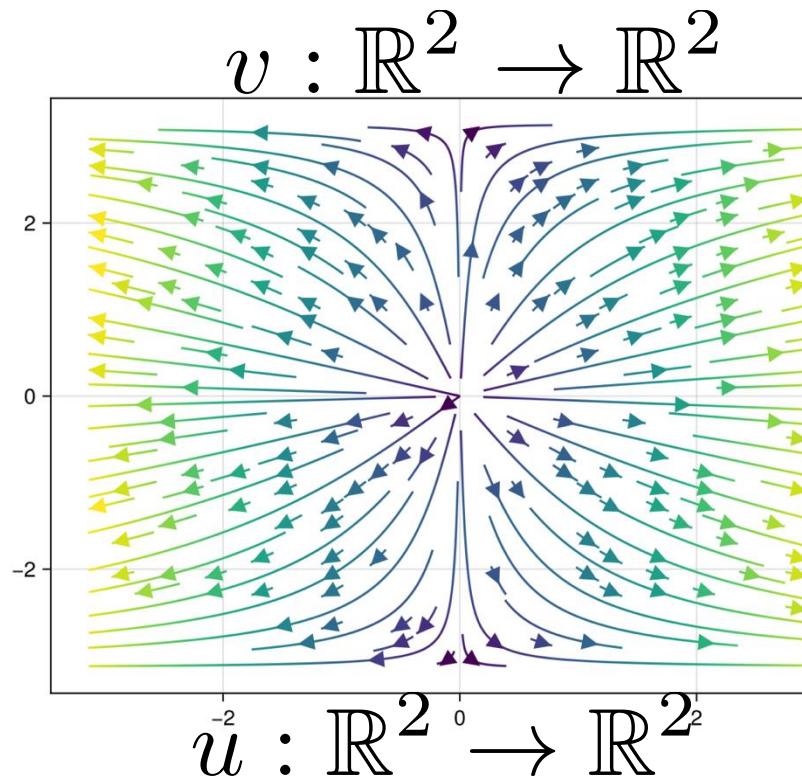
- On objects,  $\text{Dynam}$  takes a finite set  $N$  to the set of smooth maps  $\{v: \mathbb{R}^N \rightarrow \mathbb{R}^N\}$ .
- Given a morphism  $\phi: N \rightarrow M$  in  $\text{FinSet}$ ,  $\text{Dynam}(\phi): \text{Dynam}(N) \rightarrow \text{Dynam}(M)$  is defined by the function  $v \mapsto \phi_* \circ v \circ \phi^*$ .
- Given finite sets  $N$  and  $M$ , the product comparison  $\varphi_{N,M}: \text{Dynam}(N) \times \text{Dynam}(M) \rightarrow \text{Dynam}(N+M)$  is given by the function

$$(v, \rho) \mapsto \iota_{N*} \circ v \circ \iota_N^* + \iota_{M*} \circ \rho \circ \iota_M^*, \quad (25)$$

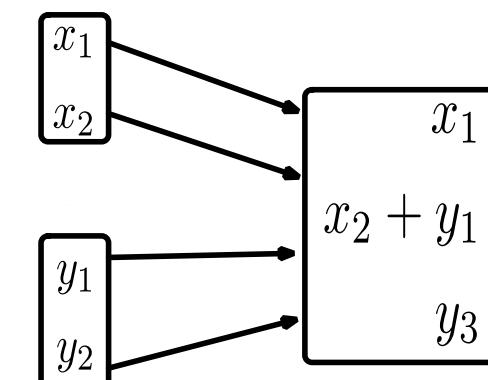
where  $\iota_N: N \rightarrow N+M$  and  $\iota_M: M \rightarrow N+M$  are the natural inclusions.

- The unit comparison  $\varphi_0: \{\ast\} \rightarrow \text{Dynam}(\emptyset)$  is uniquely determined because the set of maps  $\{\mathbb{R}^0 \rightarrow \mathbb{R}^0\}$  is a singleton.
- Share variables by copying their values
- Compose tangent vectors by adding them

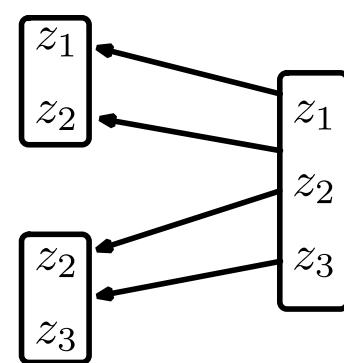
# Superposition in Composite Systems



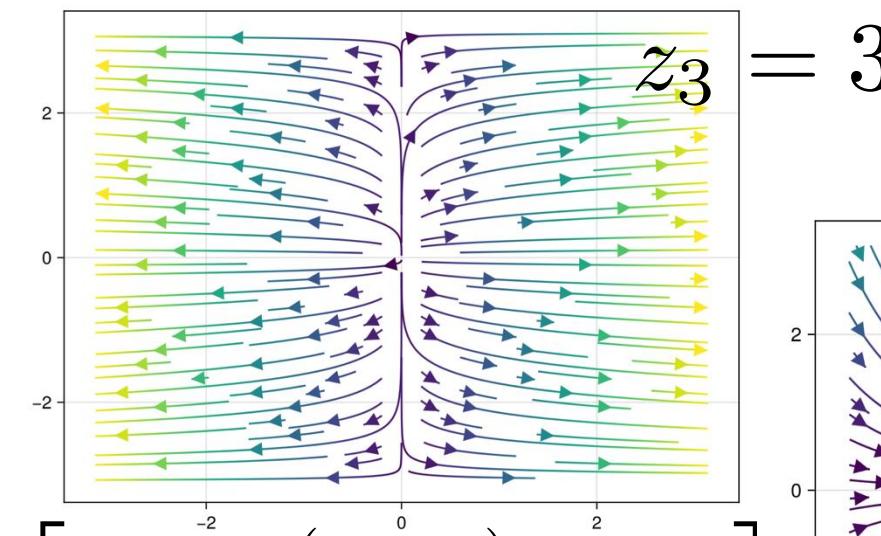
$$\phi: [2] + [2] \rightarrow [3]$$



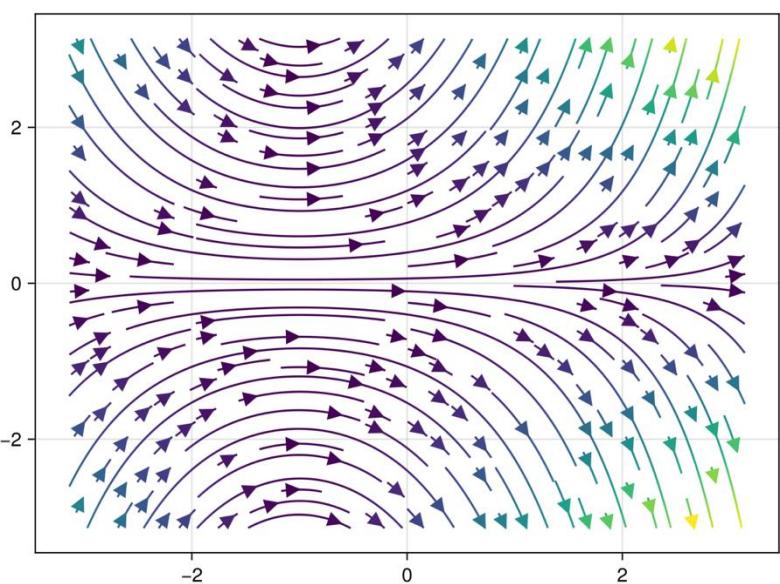
$$\phi_*(x, y): \mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}^3$$



$$\phi^*(z): \mathbb{R}^3 \rightarrow \mathbb{R}^2 \times \mathbb{R}^2$$

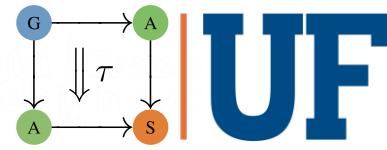


$$\begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix} \mapsto \begin{bmatrix} v(z_1, z_2)_1 \\ v(z_1, z_2)_2 + u(z_2, z_3)_1 \\ u(z_2, z_3)_2 \end{bmatrix}$$

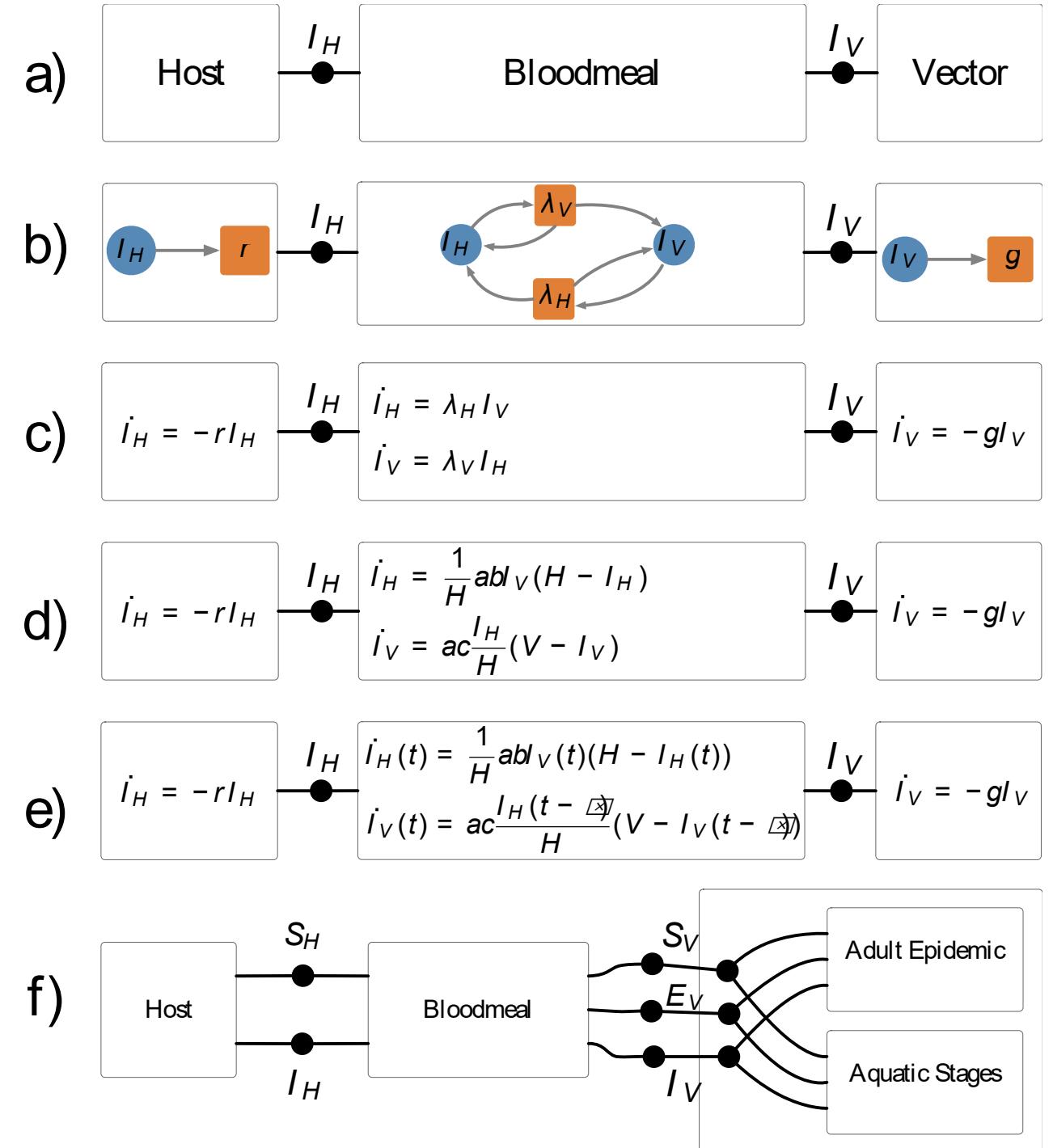


$$z_1 = 3$$

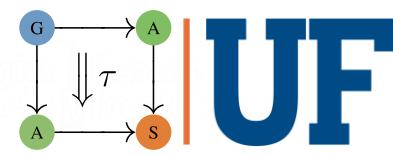
# Composing Compartmental Models with UWDs



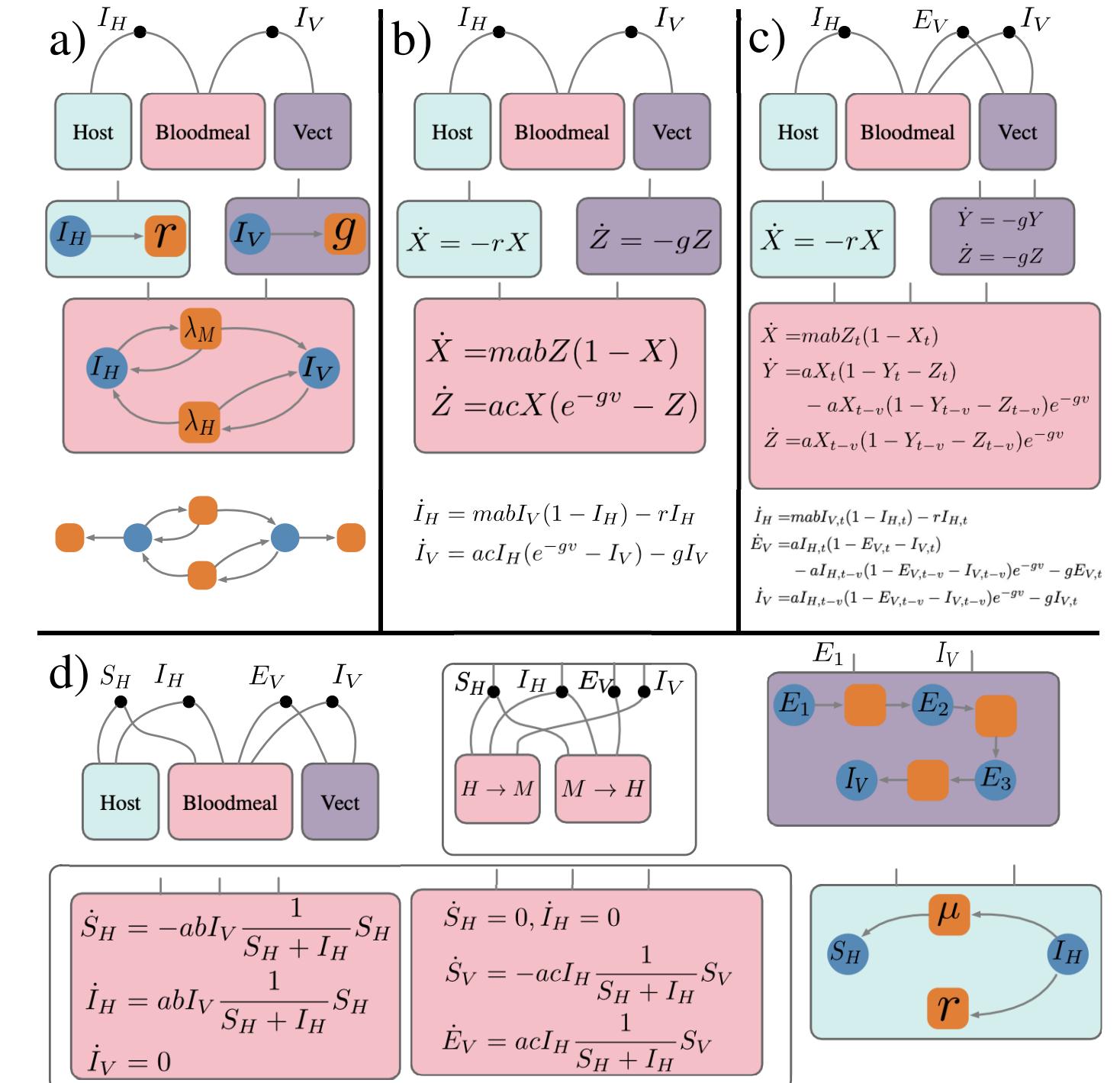
- Easy to build complex models
- Subsystems can be modified independently
- CT gives rigorous language to compare models
- Easy to compare many models to the same data for quality of fit



# Composing Compartmental Models with UWDs



- Easy to build complex models
- Subsystems can be modified independently
- CT gives rigorous language to compare models
- Easy to compare many models to the same data for quality of fit

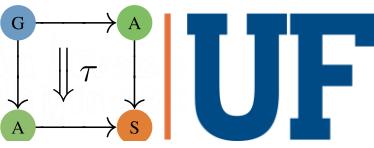


# Euler's Method is Functorial

For each fixed step size  $h$ , Euler's method

$$x_{k+1} = x_k + h f(x)$$

is a functor for UWD composition of dynamical systems



## Operadic Modeling of Dynamical Systems: Mathematics and Computation

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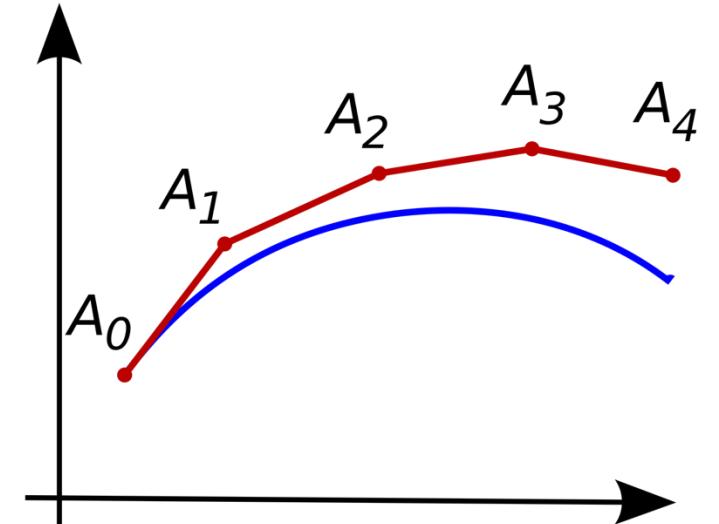
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<https://arxiv.org/pdf/2105.12282v2.pdf>

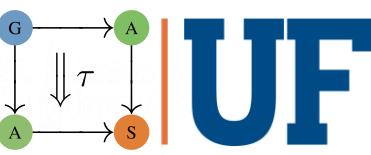
Composing dynamical systems then  
discretizing in time

is

Discretizing the composite system



# Slice Categories



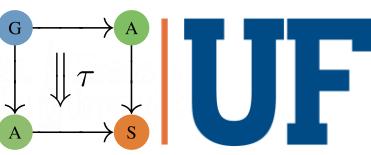
- Maps  $f:X \rightarrow R$  are data over a space
- Given  $f:X \rightarrow R$  and  $g:Y \rightarrow R$  you can ask about maps  $y:X \rightarrow Y$  that preserve  $f,g$
- Objects in the slice are “typed object”
- Morphisms are commuting triangles (right)

$$\forall x \quad f(x) = g(y(x))$$
$$X \xrightarrow{y} Y$$
$$f \searrow \qquad \swarrow g$$
$$\mathbb{R}$$

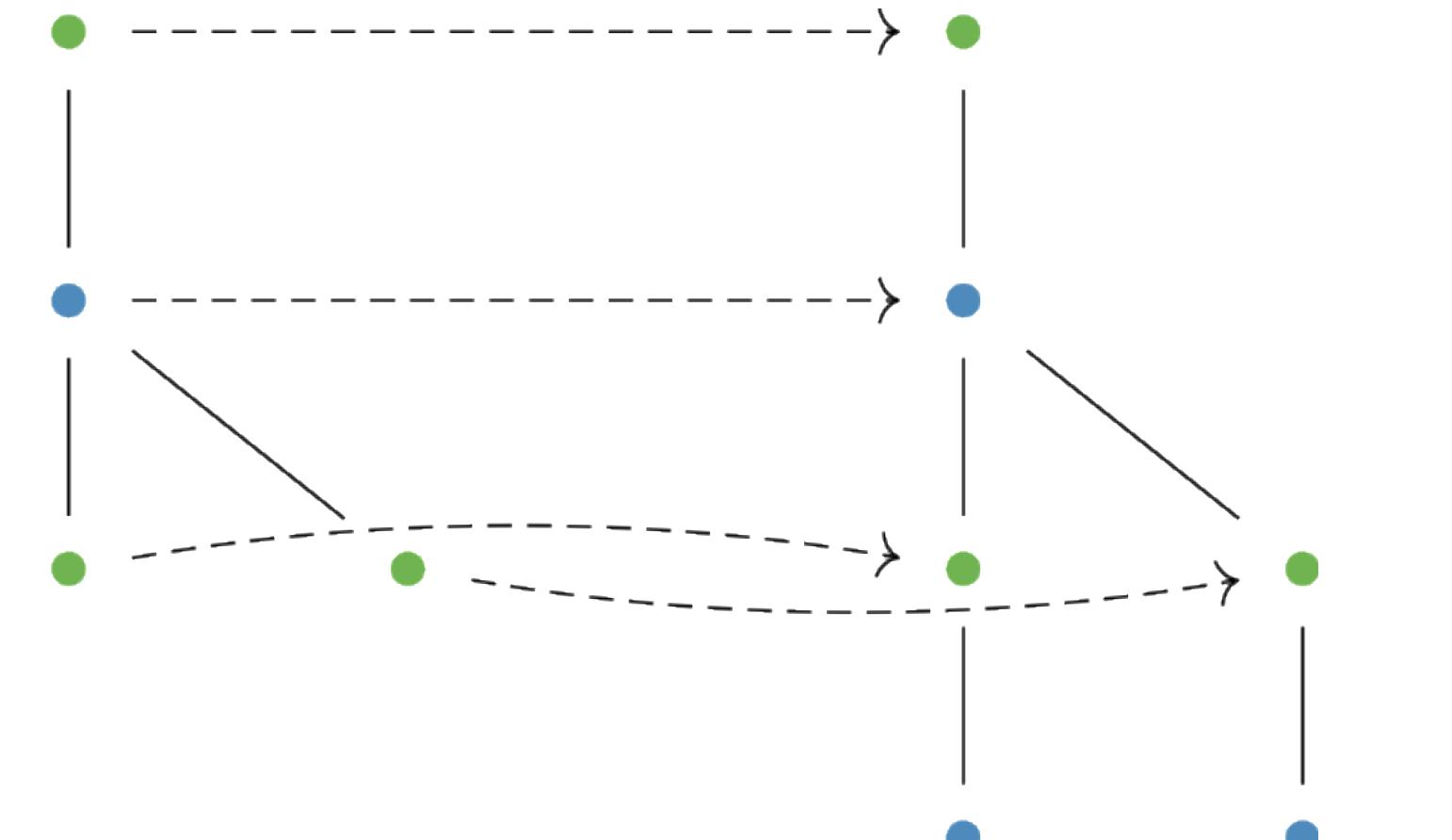
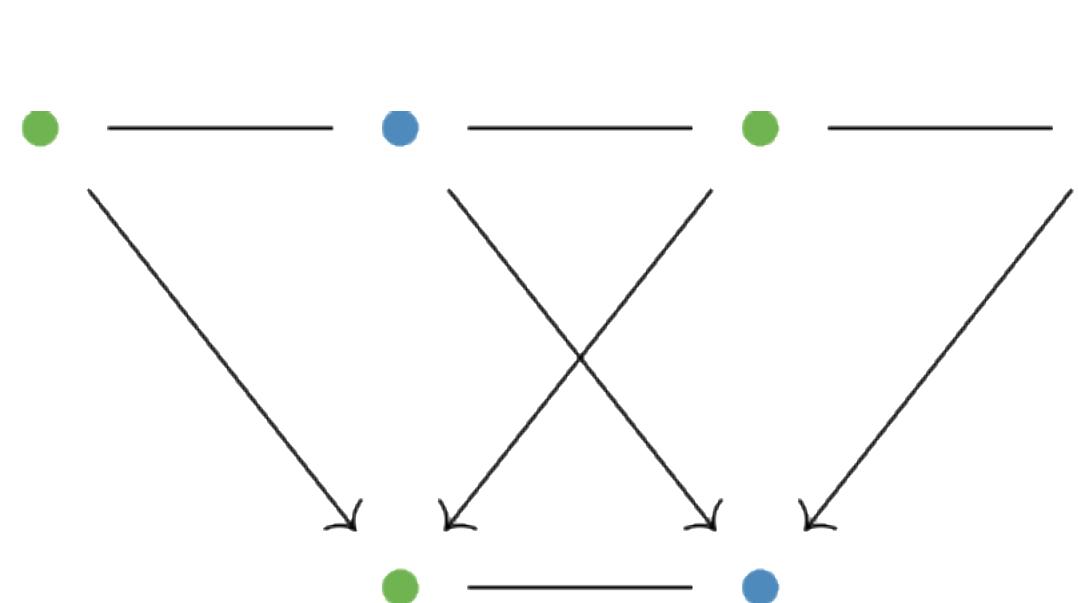
$$X \xrightarrow{y} Y \xrightarrow{z} Z$$
$$f \searrow \qquad \downarrow g \qquad \swarrow h$$
$$\mathbb{R}$$

$$f(x) = g(y(x)) \quad h(z(y)) = g(y)$$
$$\implies h(z(y(x))) = f(x)$$

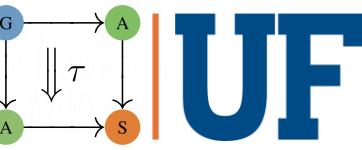
# Slice Categories



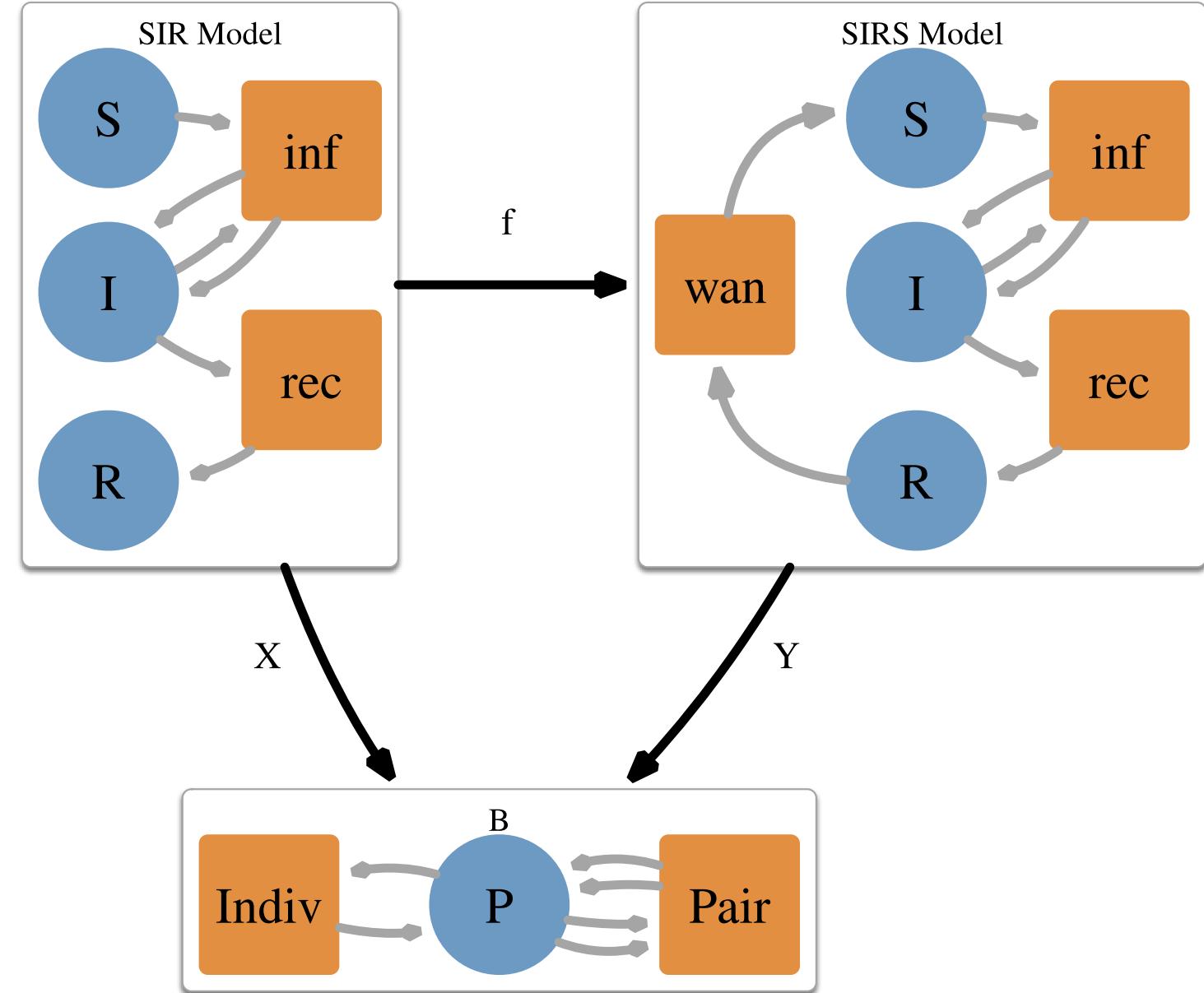
- The new objects are maps into a fixed object called the base point
- The new maps are maps in the original category that preserve the maps into the base point
- We use color coding to represent the map into the base point



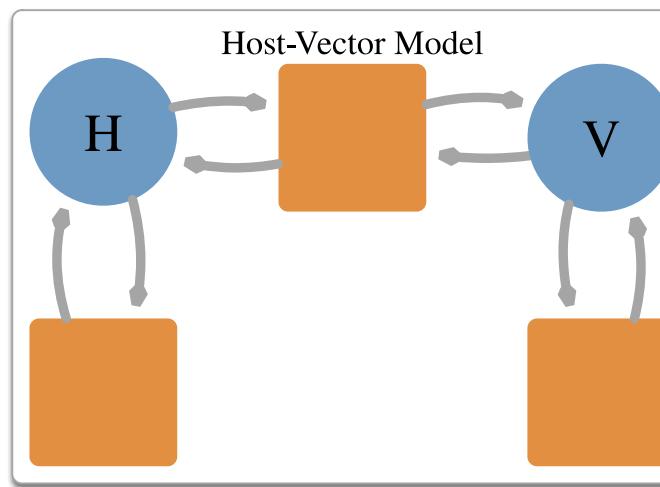
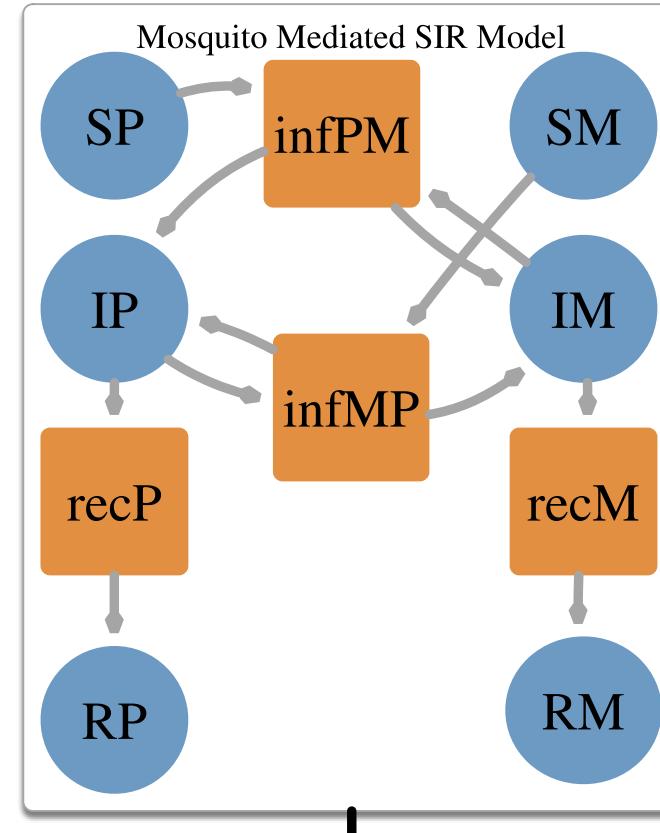
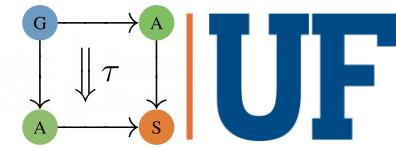
# Epi = Petri/B



- Define a category of epidemiological models as Petri nets where each reaction has either 1 input 1 output or 2 inputs and 2 outputs.
- These models conserve population and have only binary effects
- Objects in the slice are “typed reaction networks”
- Morphisms are commuting triangles (right)

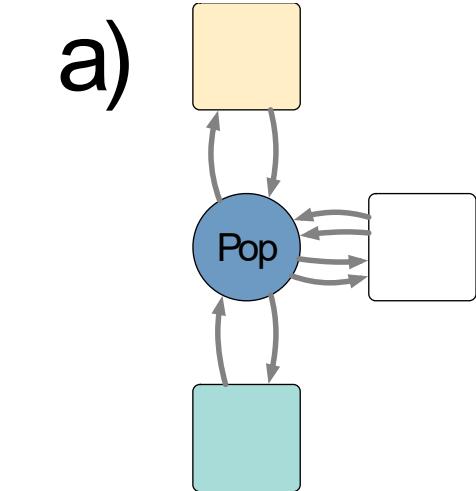


# Formalizing Scientific Knowledge as Types

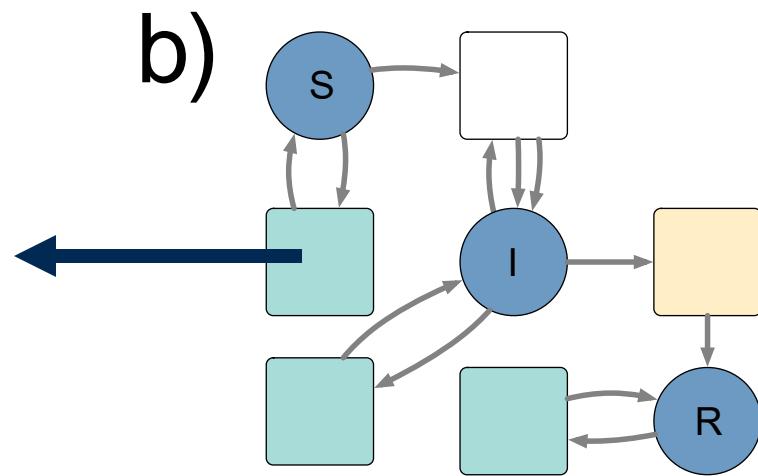


- We can statically prove that any model in this slice satisfies both a conservation of hosts and conservation of vectors
- No process is allowed to convert people into mosquitos
- Model morphisms must preserve types (hosts to hosts and vectors to vectors)

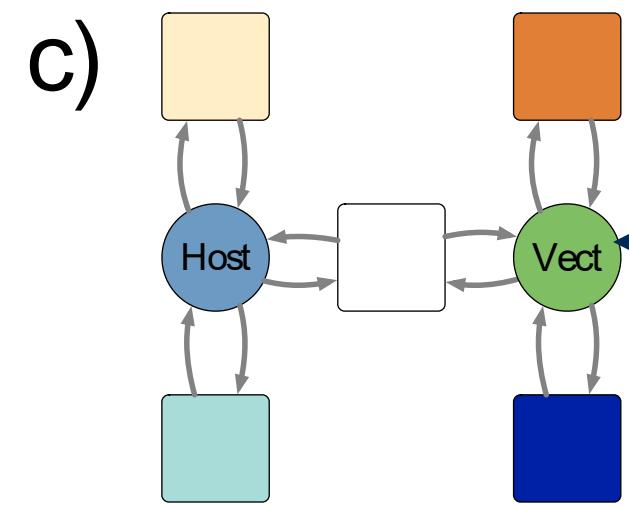
# Formalizing Scientific Knowledge as Rules



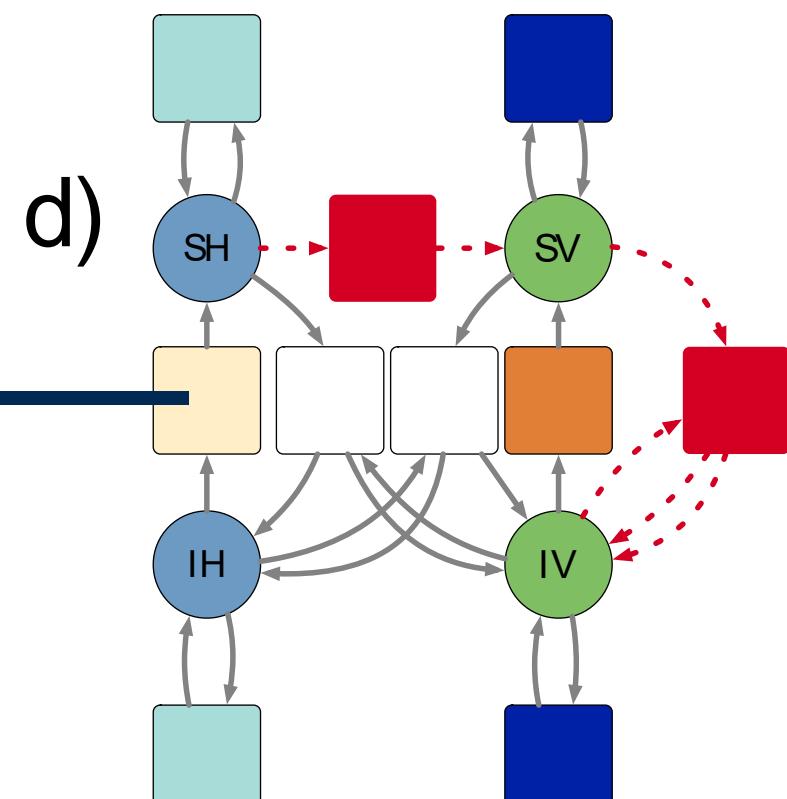
Generic epi. model



SIR model



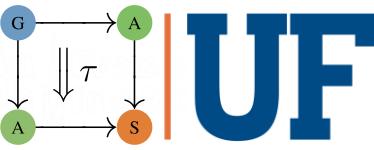
Generic vector borne illness



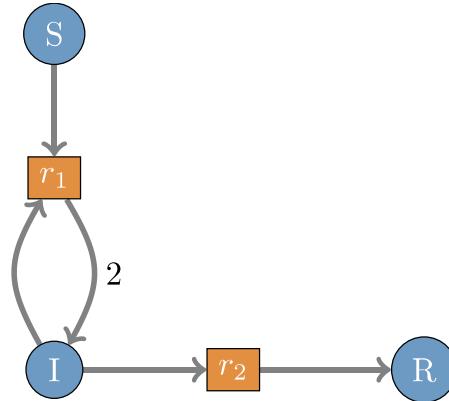
Vector Borne SIS

- An Algebraic Framework for Structured Epidemic Modeling, S. Libkind, A. Baas, M. Halter, E. Patterson, and J. Fairbanks, *The Royal Society Phil. Trans. A*
- We can statically prove that any model following the rules satisfies both a conservation of hosts/vectors law
- No process is allowed to convert people into mosquitos (red processes forbidden)
- Supports “conceptual inheritance” for these scientific types
- Modeling operations must respect the Host-Vector distinction
- Basis for automating model stratification (take SEIR dynamics over 5 age groups and 15 cities arranged in a transit network)
- Successful composition/stratification implies conceptual validity as a scientific model

# Automated Model Exploration for Epidemics



## 1) System specification



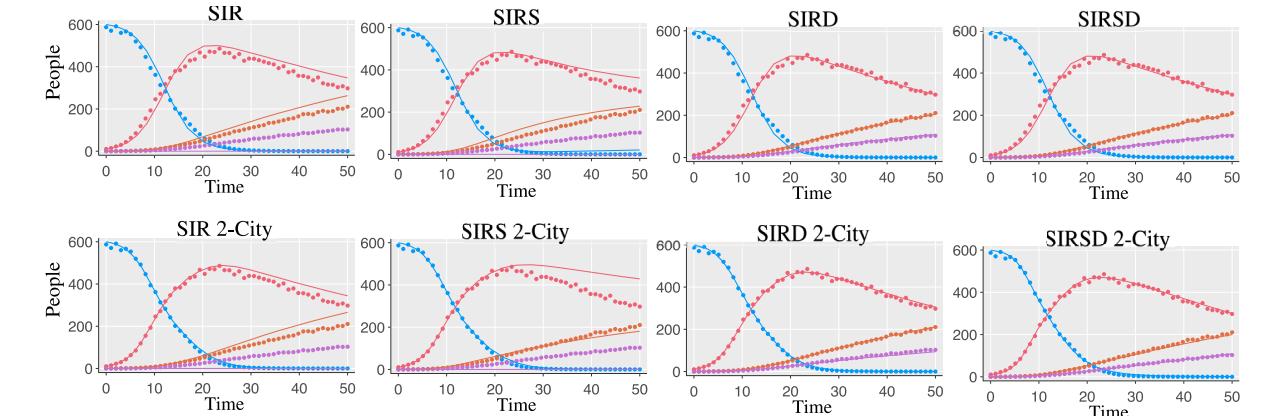
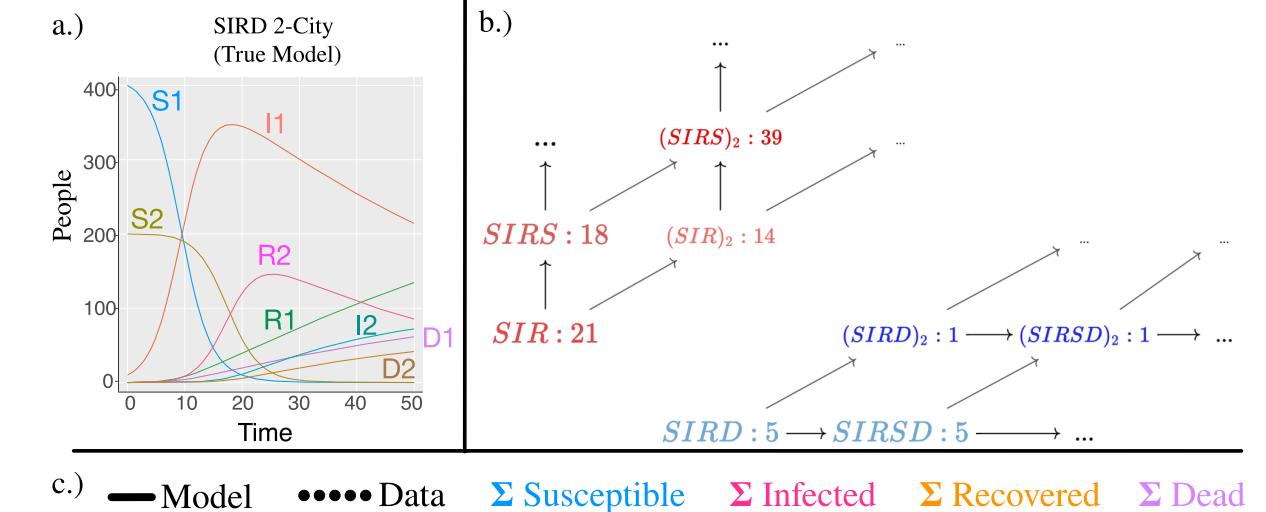
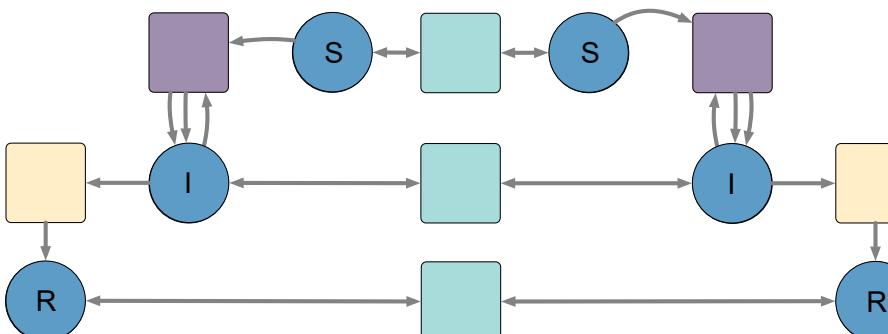
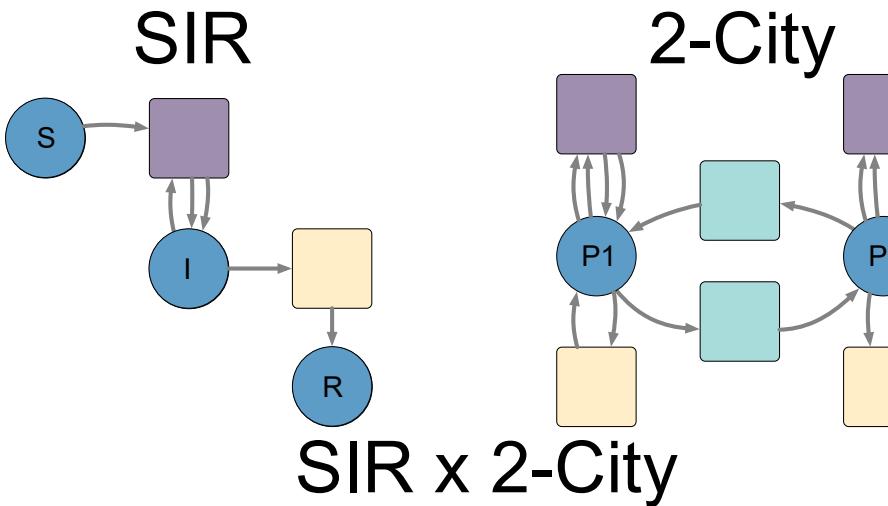
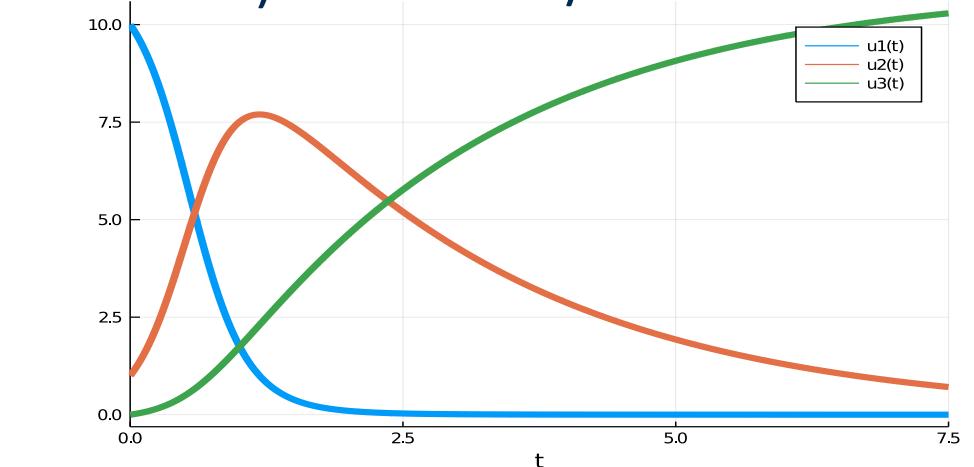
## 2) Model semantics

$$\dot{u}_1 = -r_1 u_1 u_2$$

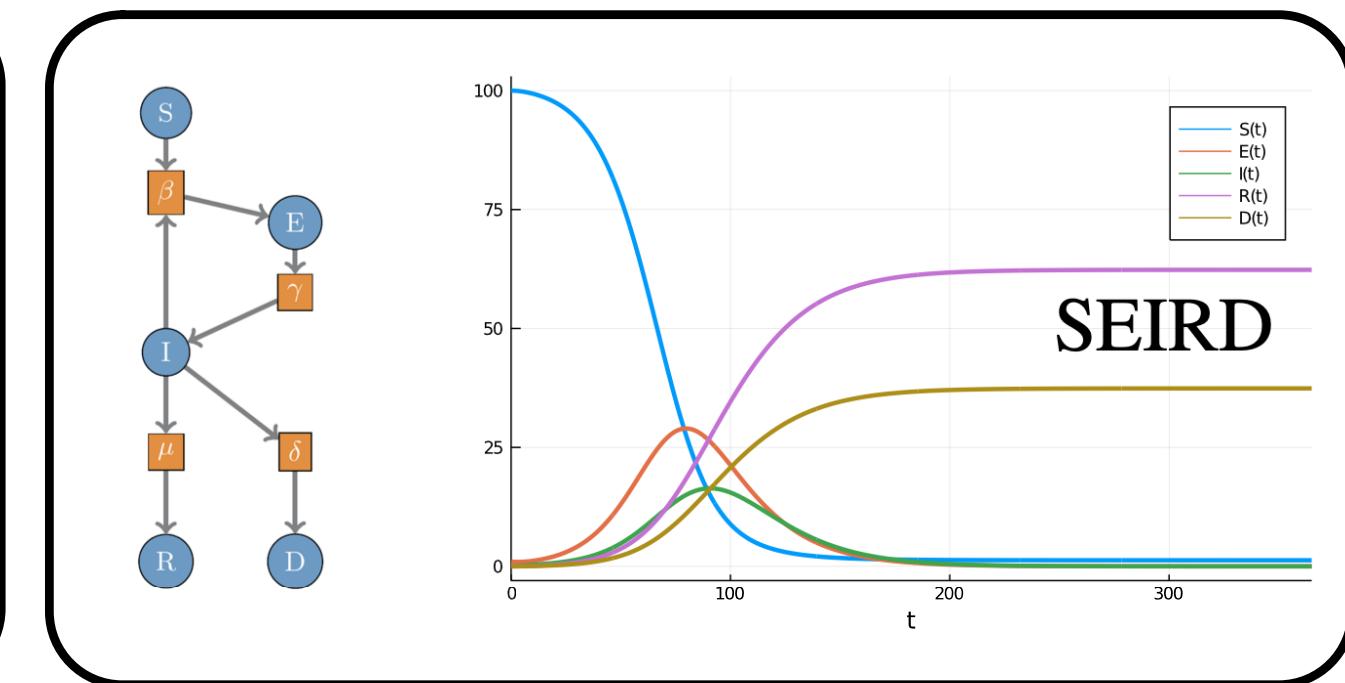
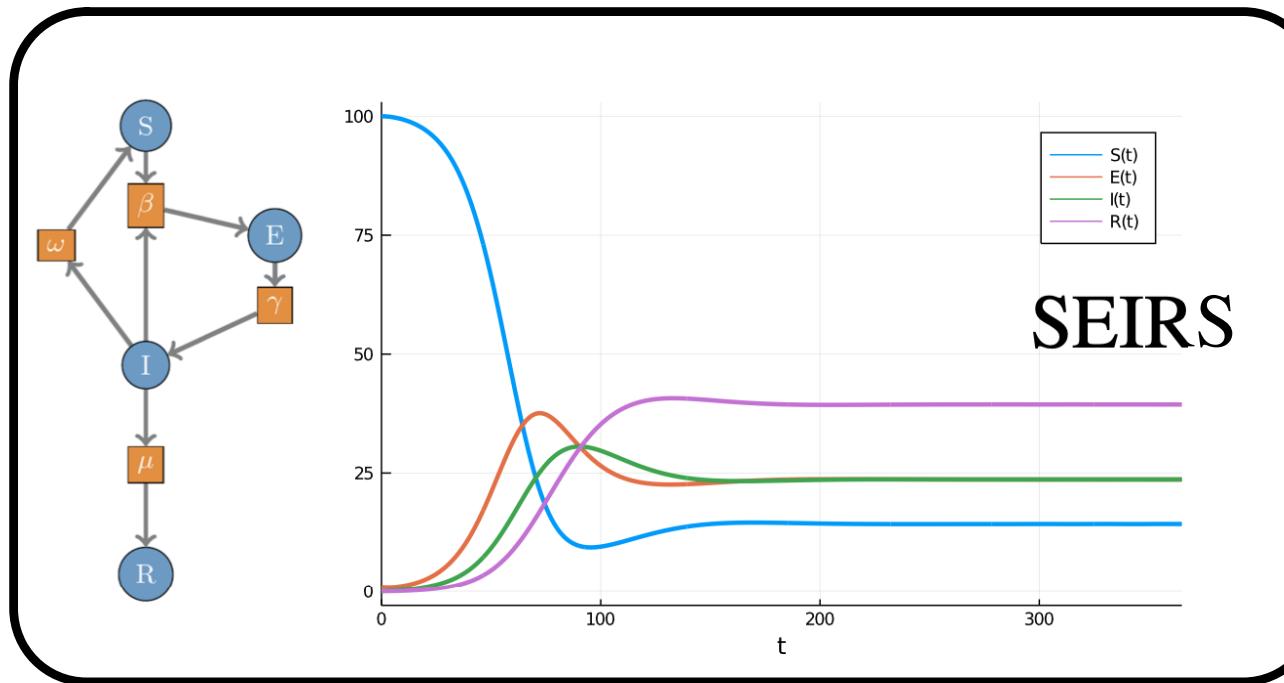
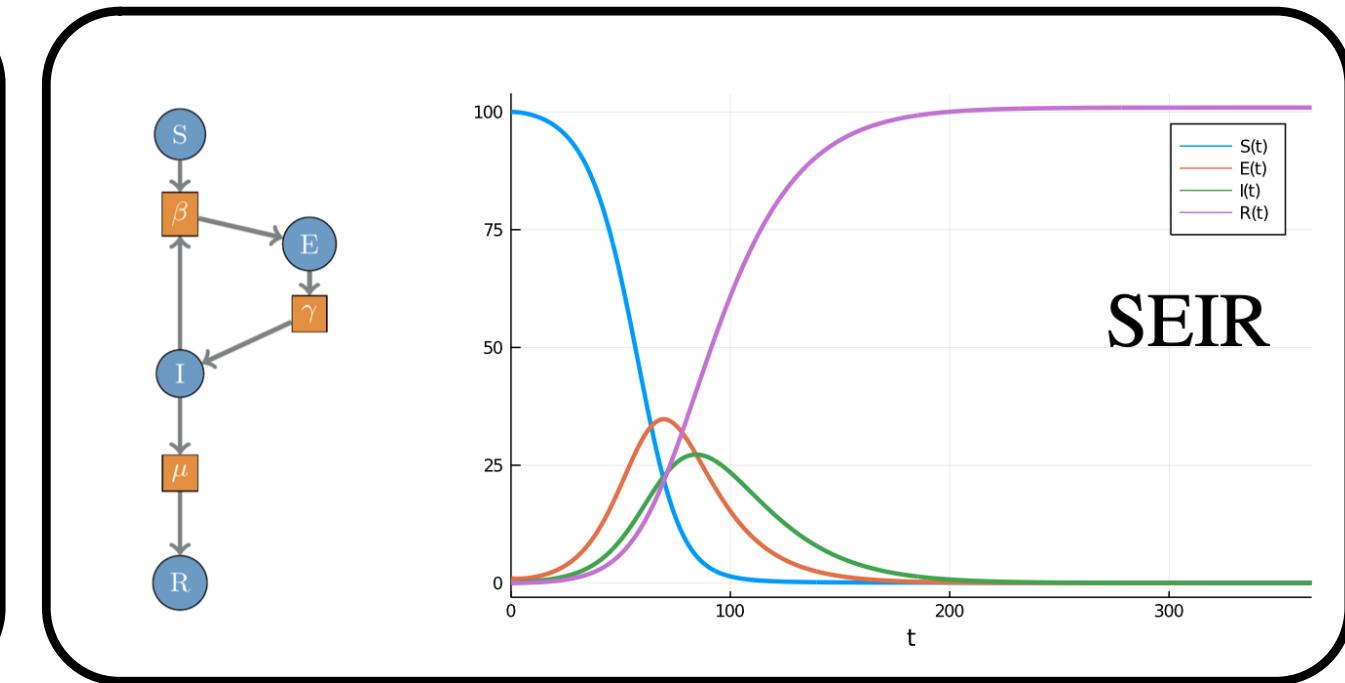
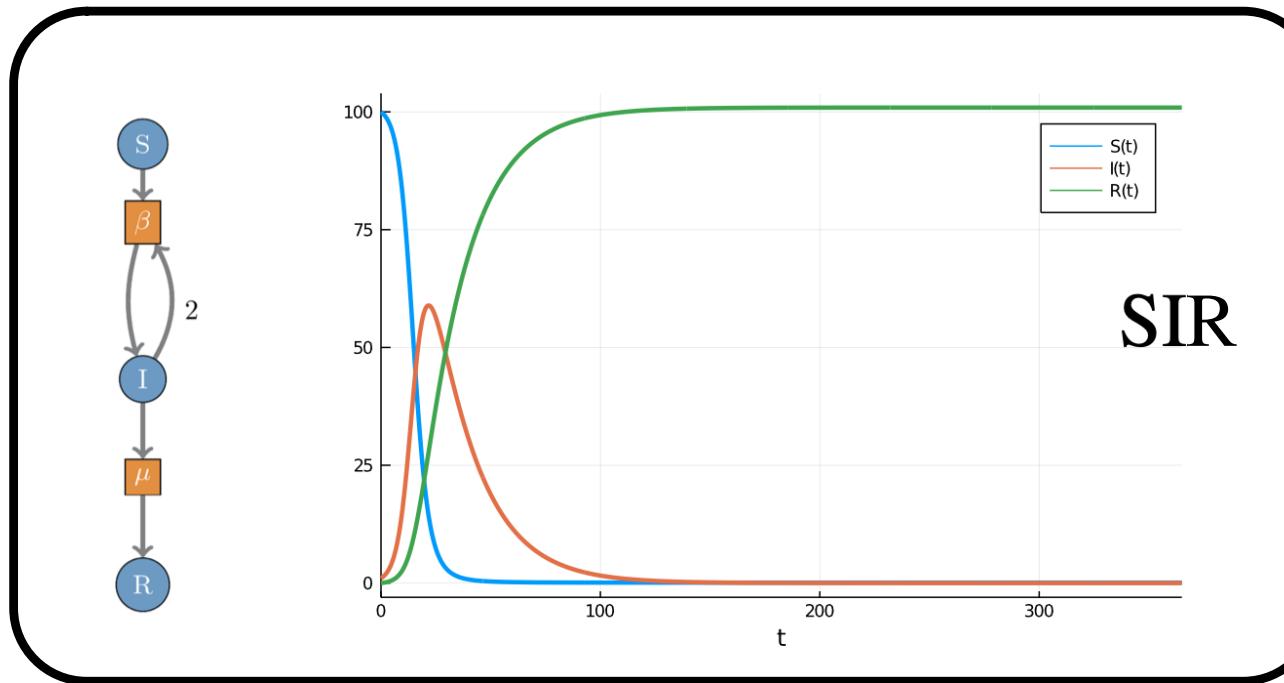
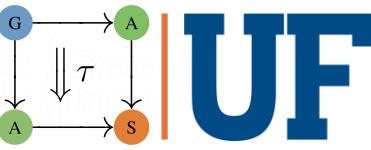
$$\dot{u}_2 = r_1 u_1 u_2 - r_3 u_2$$

$$\dot{u}_3 = r_3 u_2$$

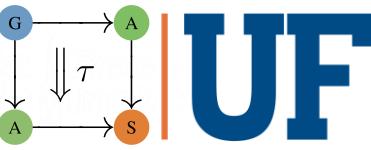
## 3) Simulation/solution



# Model Spaces for Comparison and Selection



# Composing Equations is Hard



SIR Model

$$\frac{dS}{dt} = -\beta \frac{SI}{N}$$

$$\frac{dI}{dt} = \beta \frac{SI}{N} - \gamma I.$$

$$\frac{dR}{dt} = \gamma I$$

Flux Transport Model

$$\frac{dN_i}{dt} = - \sum_{j=1}^K f_{i,j} N_i + \sum_{j=1}^K f_{j,i} N_j,$$

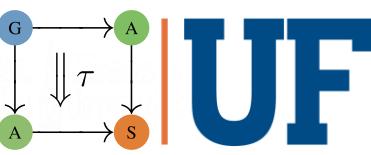
$$\frac{dS_i}{dt} = -\beta_i \frac{S_i I_i}{N_i} - \sum_{j=1}^K f_{i,j} S_i + \sum_{j=1}^K f_{j,i} S_j$$

$$\frac{dI_i}{dt} = \beta_i \frac{S_i I_i}{N_i} - \gamma I_i - \sum_{j=1}^K f_{i,j} I_i + \sum_{j=1}^K f_{j,i} I_j.$$

$$\frac{dR_i}{dt} = \gamma I_i - \sum_{j=1}^K f_{i,j} R_i + \sum_{j=1}^K f_{j,i} R_j$$

Composite Model

# Composing Equations is Hard



## SIR Model

$$\begin{aligned}\frac{dS}{dt} &= -\beta \frac{SI}{N} \\ \frac{dI}{dt} &= \beta \frac{SI}{N} - \gamma I \\ \frac{dR}{dt} &= \gamma I\end{aligned}$$

$$\begin{aligned}\frac{dS_{i,i}}{dt} &= -\beta_i \frac{S_{i,i} \sum_{k=1}^K I_{k,i}}{\sum_{k=1}^K N_{k,i}} - \sum_{k=1}^K \phi_{i,k} S_{i,i} + \sum_{k=1}^K \tau_{i,k} S_{i,k} \\ \frac{dS_{i,j}}{dt} &= -\beta_j \frac{S_{i,j} \sum_{k=1}^K I_{k,j}}{\sum_{k=1}^K N_{k,j}} + \phi_{i,j} S_{i,i} - \tau_{i,j} S_{i,j} \\ \frac{dI_{i,i}}{dt} &= \beta_i \frac{S_{i,i} \sum_{k=1}^K I_{k,i}}{\sum_{k=1}^K N_{k,i}} - \gamma I_{i,i} - \sum_{k=1}^K \phi_{i,k} I_{i,i} + \sum_{k=1}^K \tau_{i,k} I_{i,k} \\ \frac{dI_{i,j}}{dt} &= \beta_j \frac{S_{i,j} \sum_{k=1}^K I_{k,j}}{\sum_{k=1}^K N_{k,j}} - \gamma I_{i,j} + \phi_{i,j} I_{i,i} - \tau_{i,j} I_{i,j} \\ \frac{dR_{i,i}}{dt} &= \gamma I_{i,i} - \sum_{k=1}^K \phi_{i,k} R_{i,i} + \sum_{k=1}^K \tau_{i,k} R_{i,k} \\ \frac{dR_{i,j}}{dt} &= \gamma I_{i,j} + \phi_{i,j} R_{i,i} - \tau_{i,j} I_{i,j}\end{aligned}$$

## Simple Trip Transport Model

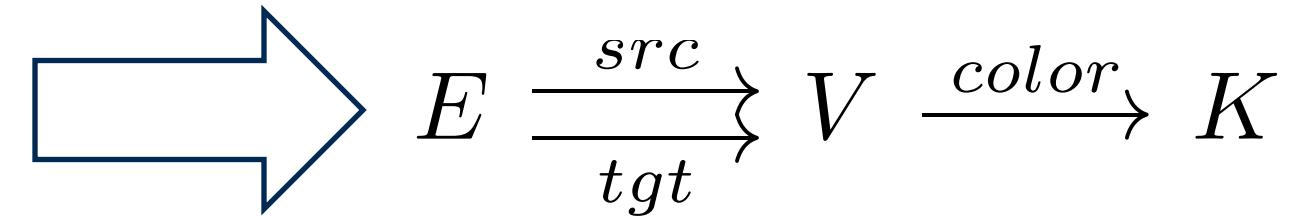
$$\begin{aligned}\frac{dN_{i,i}}{dt} &= - \sum_{j=1}^K \phi_{i,j} N_{i,i} + \sum_{j=1}^K \tau_{i,j} N_{i,j} \\ \frac{dN_{i,j}}{dt} &= -\tau_{i,j} N_{i,j} + \phi_{i,j} N_{i,i}\end{aligned}.$$

Composite Model

# Example: Colored Graphs

Colored Graphs

$$G = (V, E \subseteq V \times V, \phi: V \rightarrow K)$$

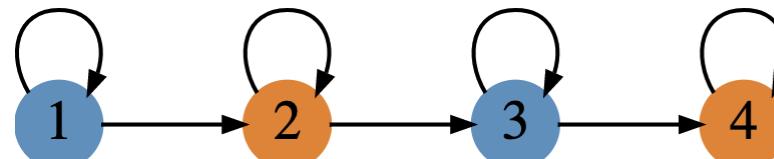


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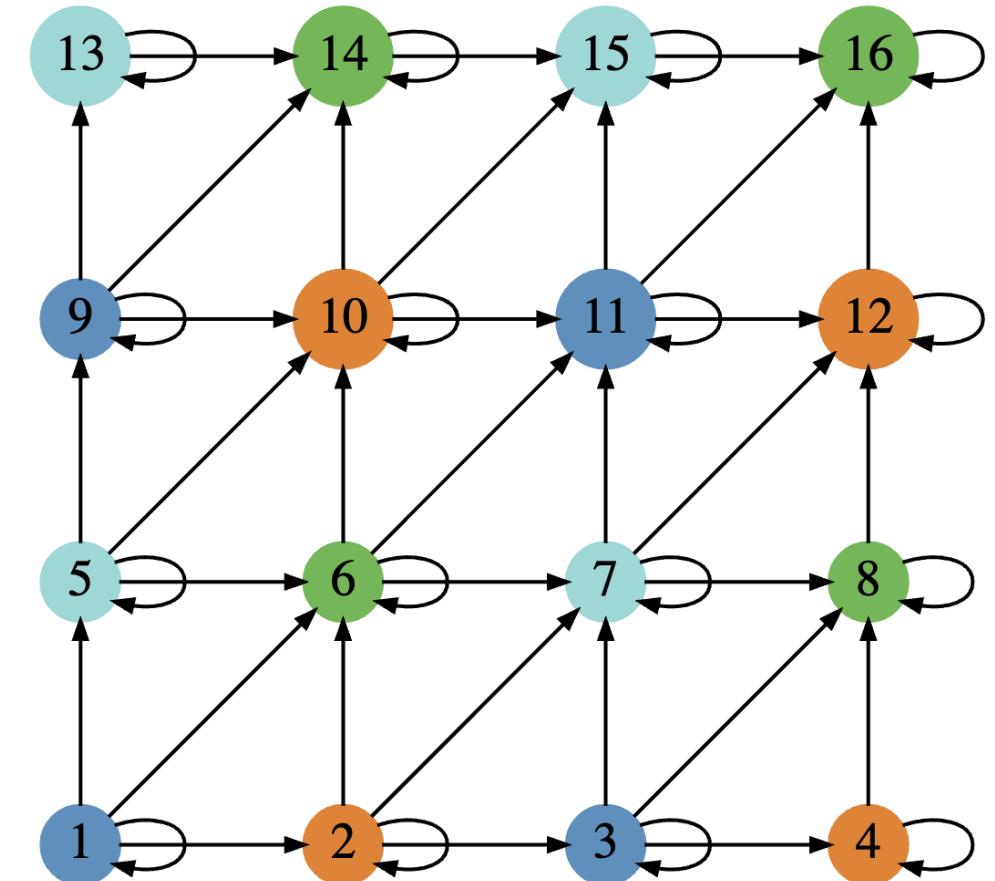
```
rp4 = @acset ColoredGraph begin
    V = 4
    E = 7
    K = 2
    src = [1,2,3,1,2,3,4]
    tgt = [2,3,4,1,2,3,4]
    color = [1,2,1,2]
end

draw(rp4)
```

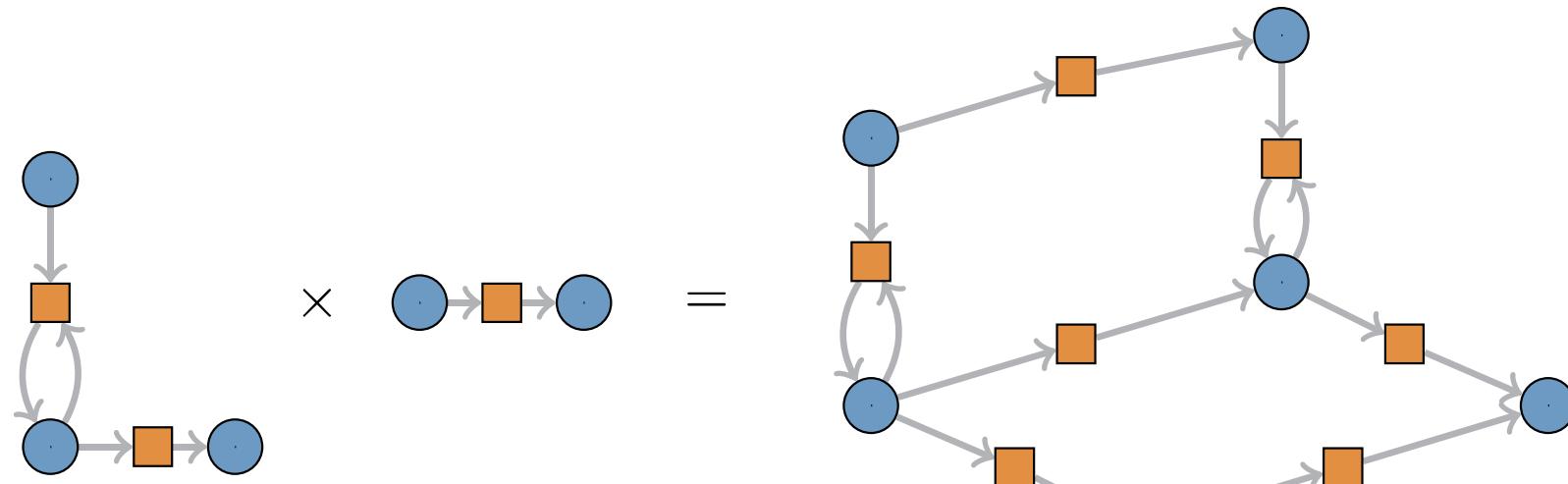
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$rp4 \times rp4$



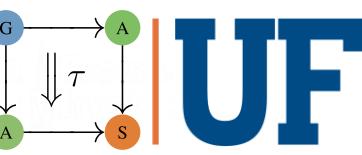
# Model Transformation in Rxn-Set



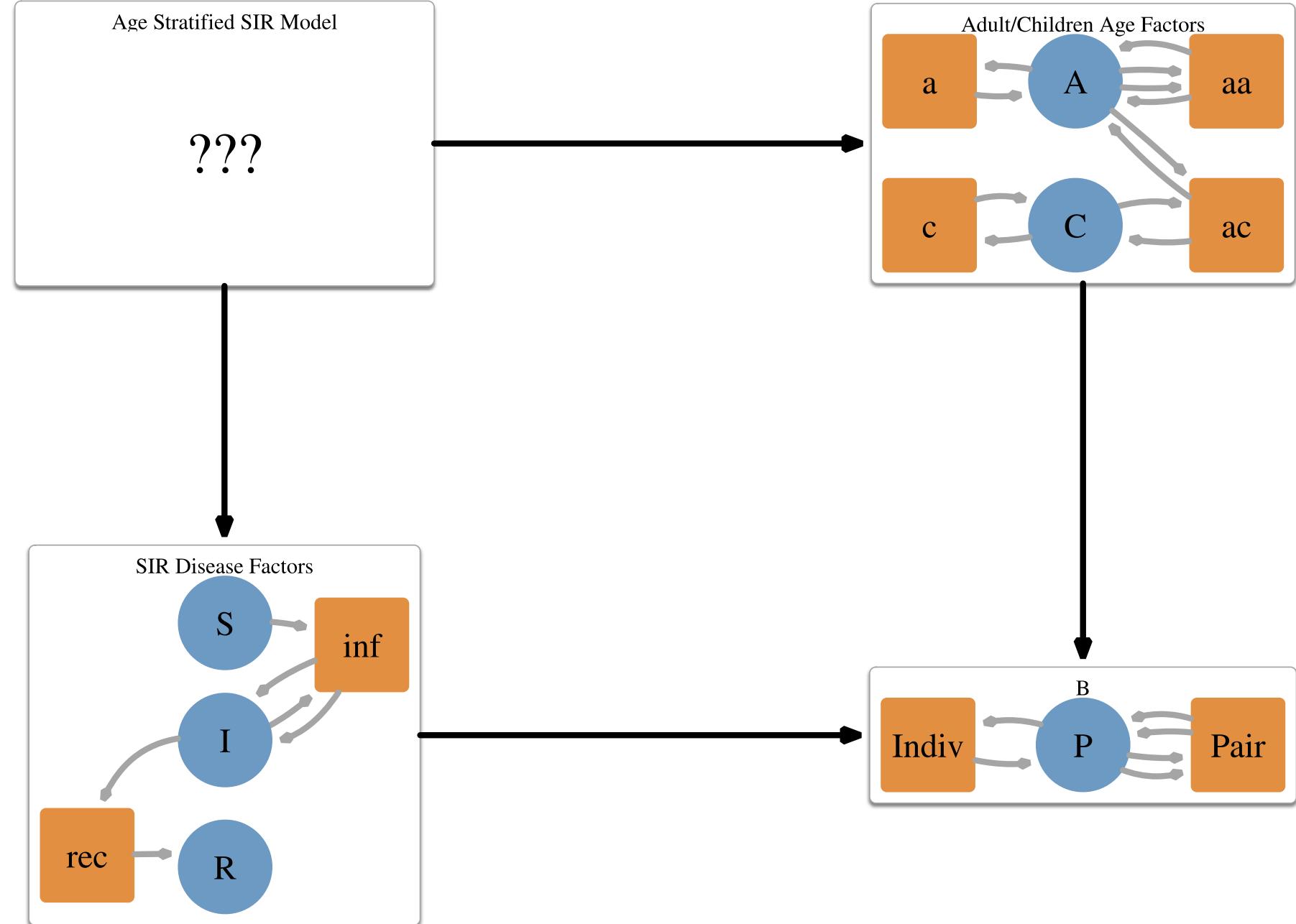
$$\dot{u} = \begin{bmatrix} -\beta_1 u_1 u_2 - \beta_3 u_1 \\ \beta_1 u_1 u_2 - \beta_3 u_2 - \beta_4 u_2 \\ \beta_2 u_2 - \beta_6 u_3 \\ -\beta_1 u_4 u_5 + \beta_3 u_4 \\ \beta_1 u_4 u_5 - \beta_3 u_5 + \beta_4 u_2 \\ \beta_2 u_5 + \beta_6 u_3 \end{bmatrix}$$

- Simple operations on the compartmental model is a complex operation on the differential equations
- Above:  $SIR \times AB$  has two regions undergoing  $SIR$  with a flow  $A \rightarrow B$

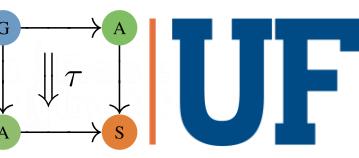
# Model Stratification by Universal Property



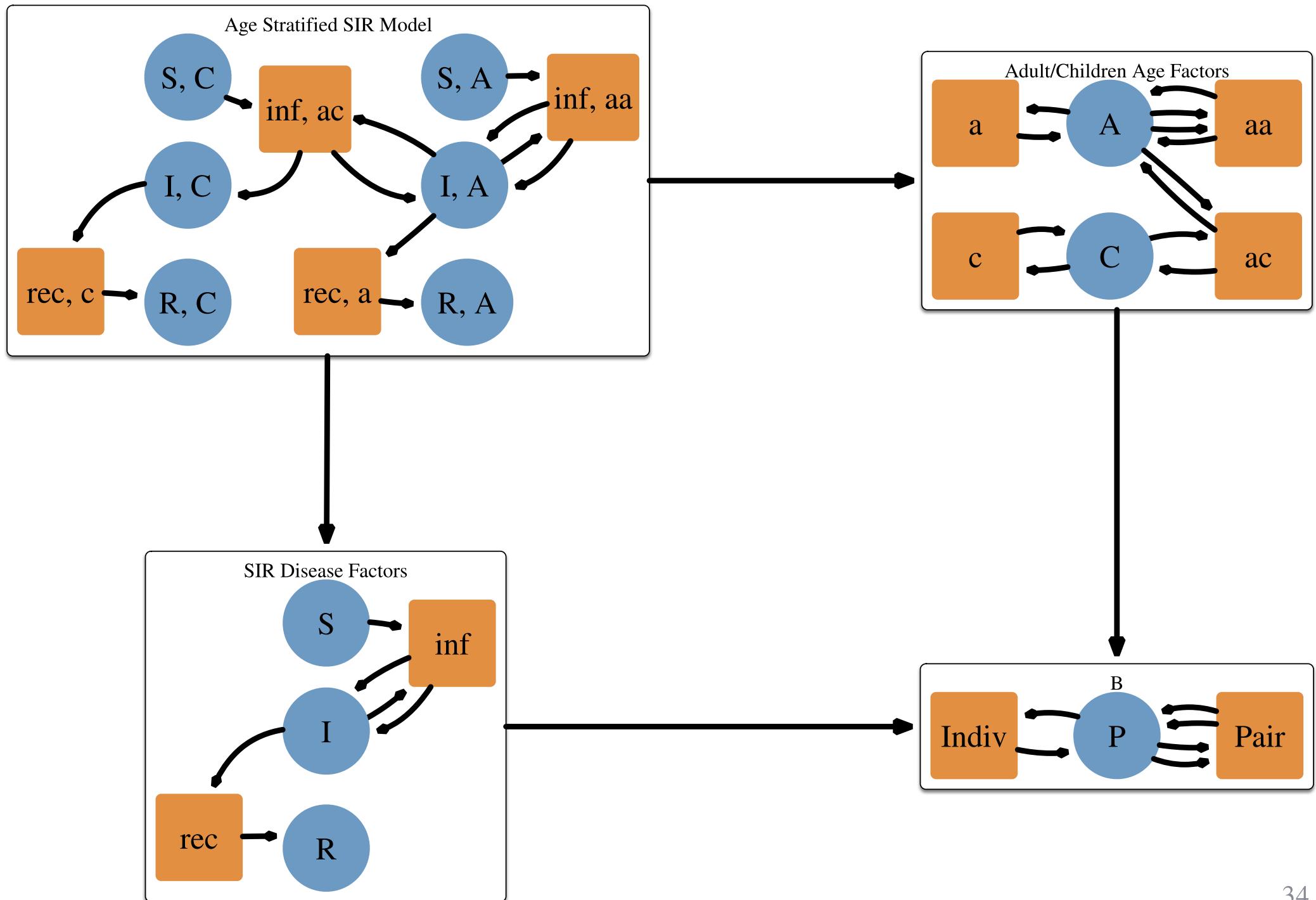
What is the unique model that factors into SIR disease factors and Adult/Children Age Factors, such that any other model with those factors factors through our model?



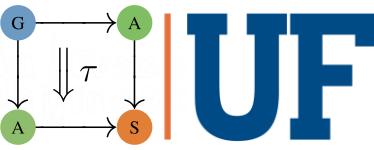
# Model Stratification with Pullbacks!



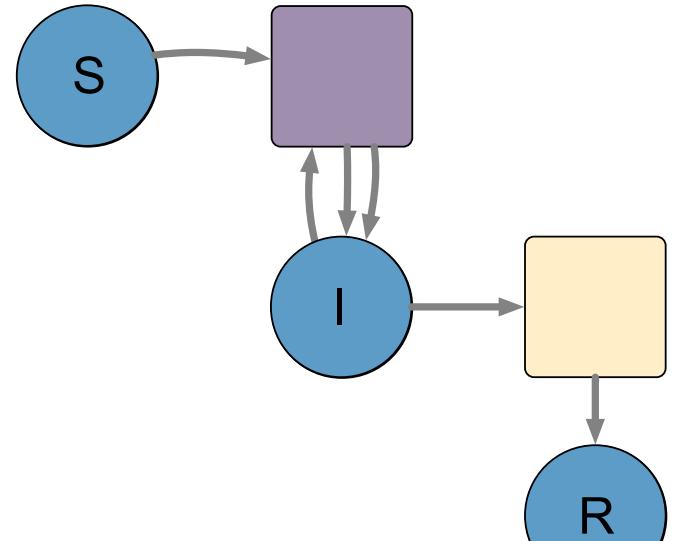
- Pullbacks let you specify model stratification, a basic pattern of compositional modeling in Epidemiology
- Defining this operation on models without using its universal mapping property (UMP) would be ad hoc.
- UMPs imply properties of model constructions, ie. stratification is an associative, commutative (up to isomorphism) binary operation.



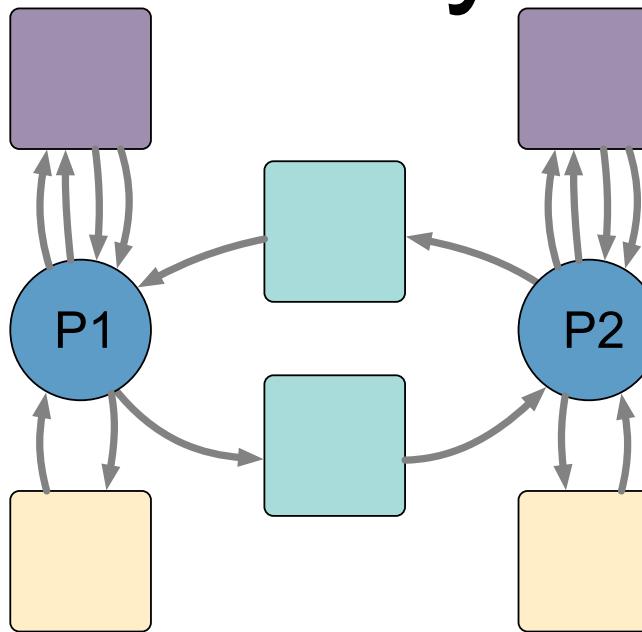
# Spatial Models with Disease x Transport



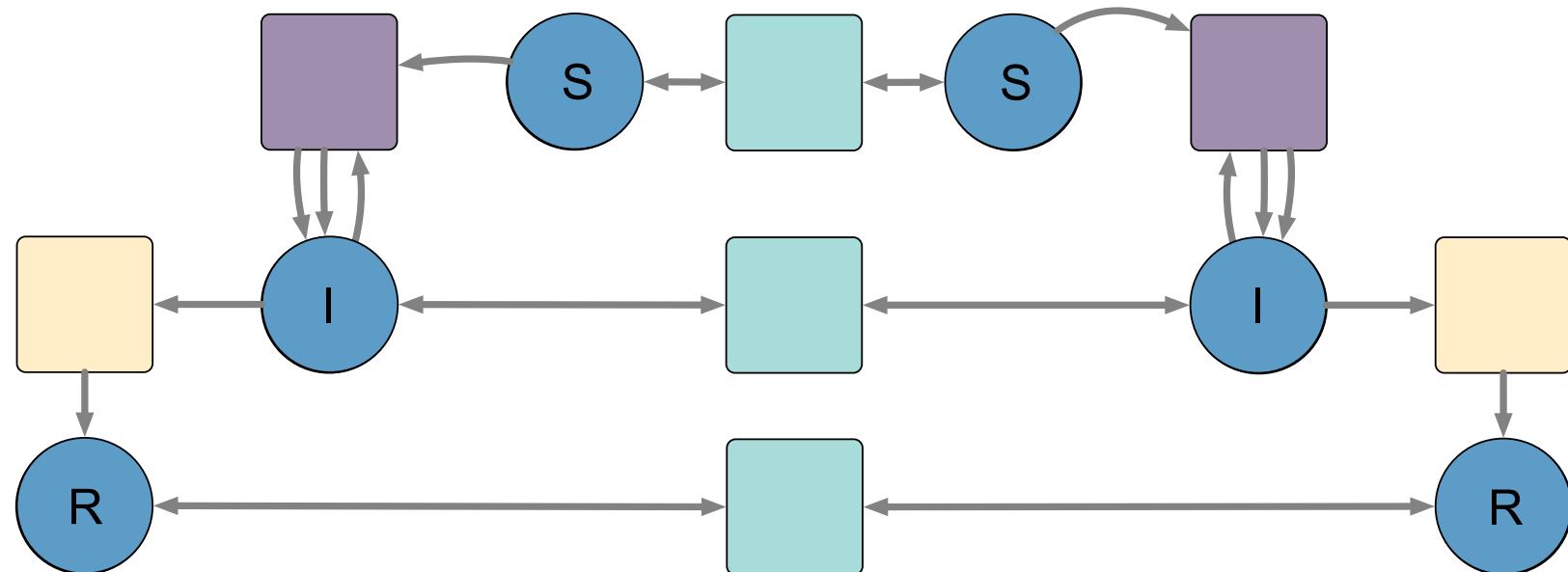
## SIR



## 2-City

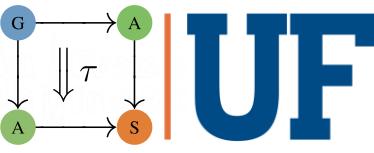


## SIR x 2-City

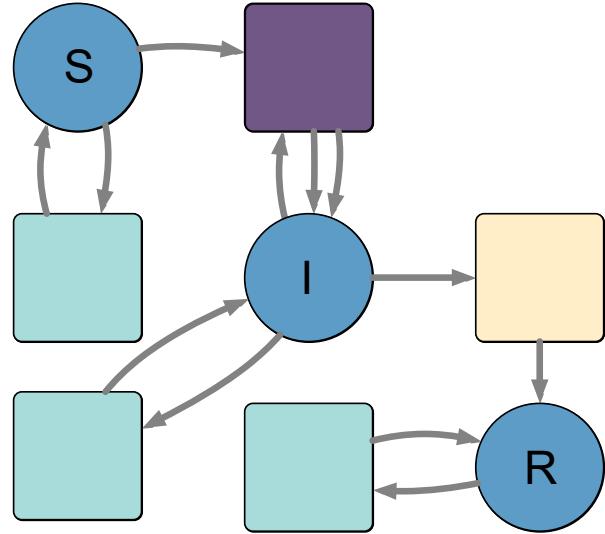


- Models Migration or Commuting of Populations
- People travel between cities
- Can only infect people in the same city

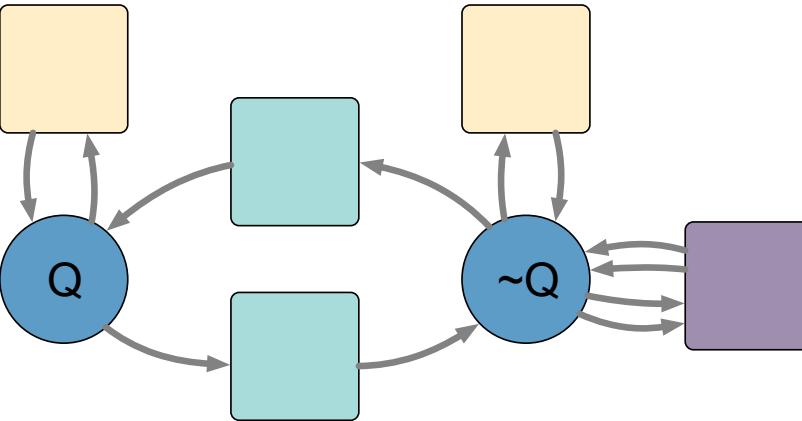
# Example of adding Quarantine to SIR



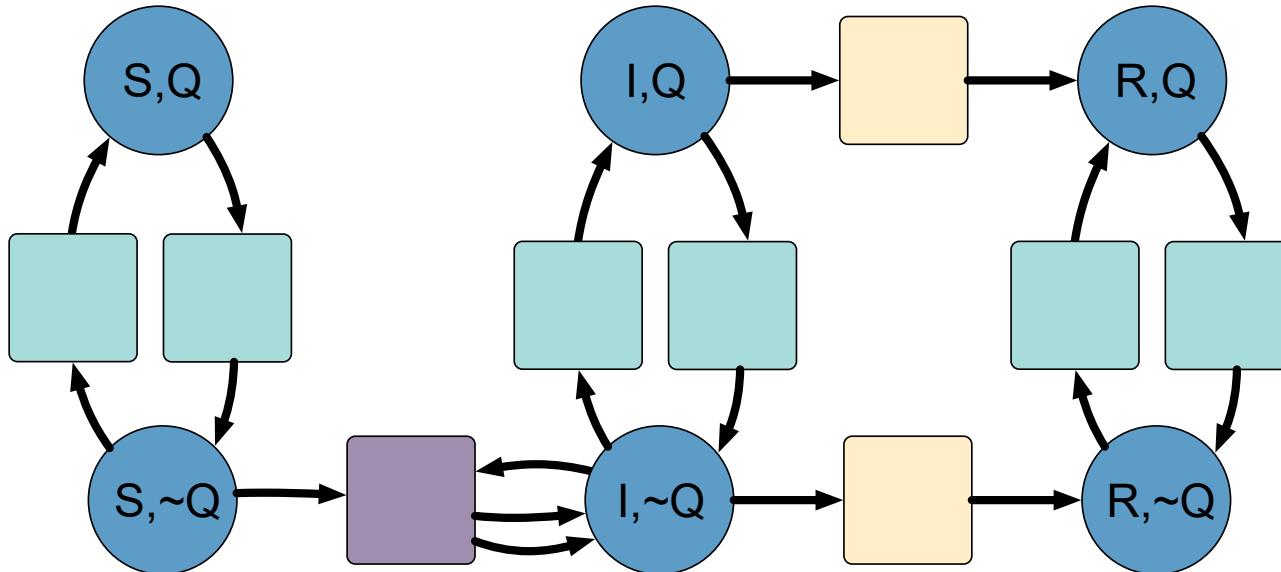
## SIR



## Quarantine



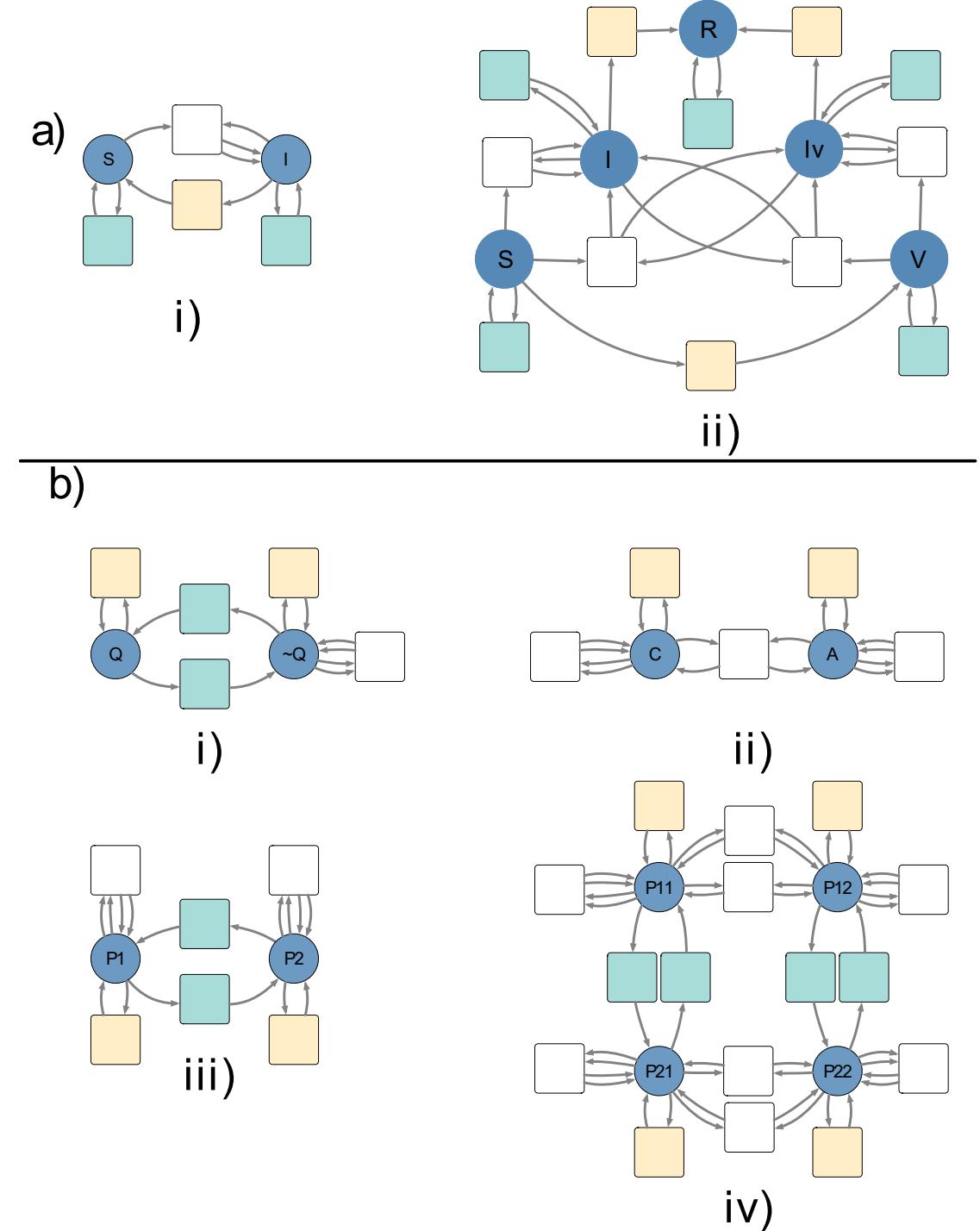
## SIR x Quarantine



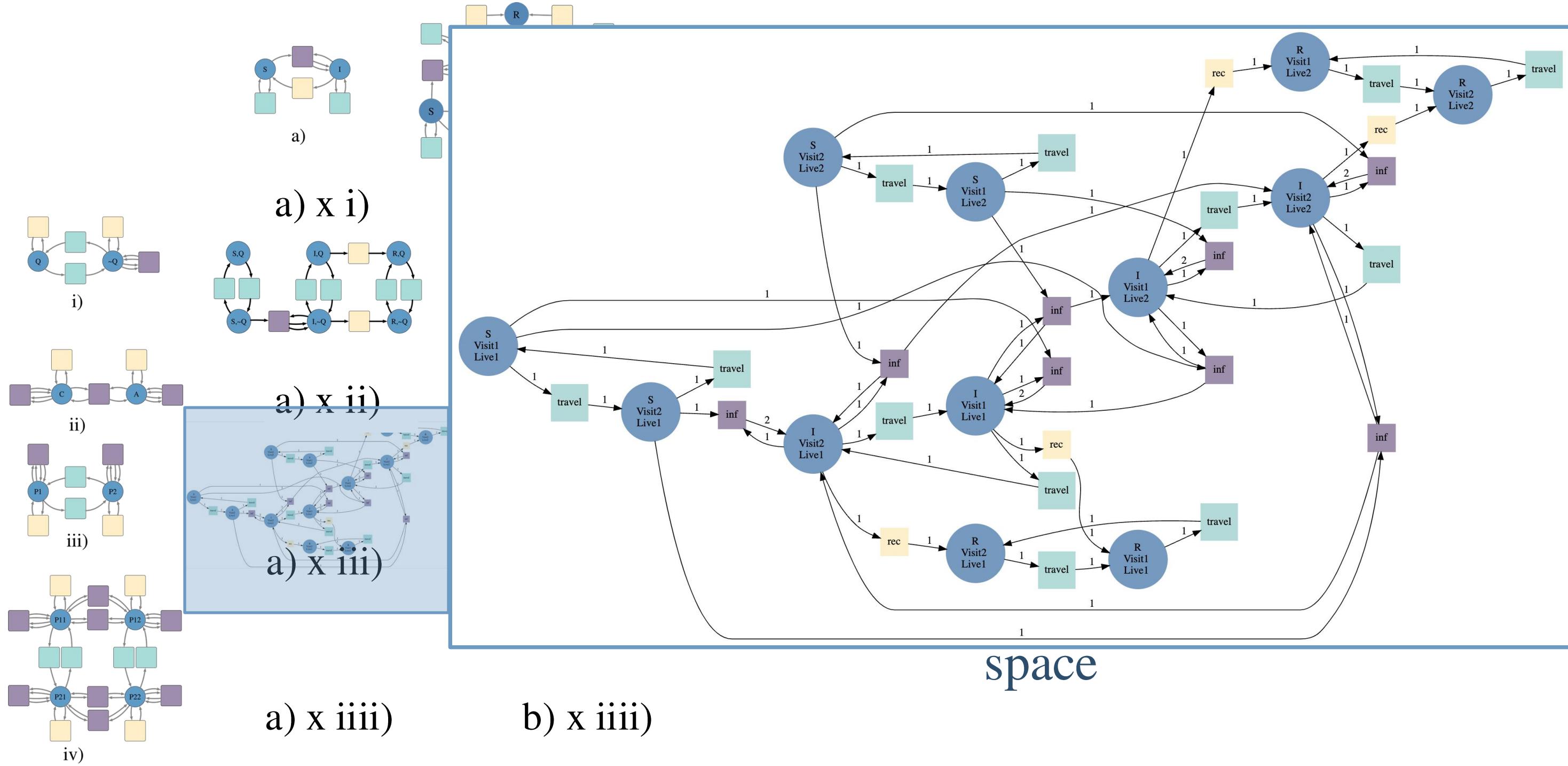
- Each pair  $a \times b$  gives a new model.
- We can easily generate new models for scientists
- What is this space of all possible products?

# Stratifying Compartmental Models with Pullbacks

- Choose a disease model (a)
- Choose a stratification scheme (b)
- AlgebraicJulia computes the (b)-stratified version of model (a)
- Benefits
  - Easy to build complex models
  - Factors can be modified independently
  - CT gives rigorous language to articulate structural model comparisons
- Easy to compare many models to the same data for testing assumptions about disease or demographic dynamics

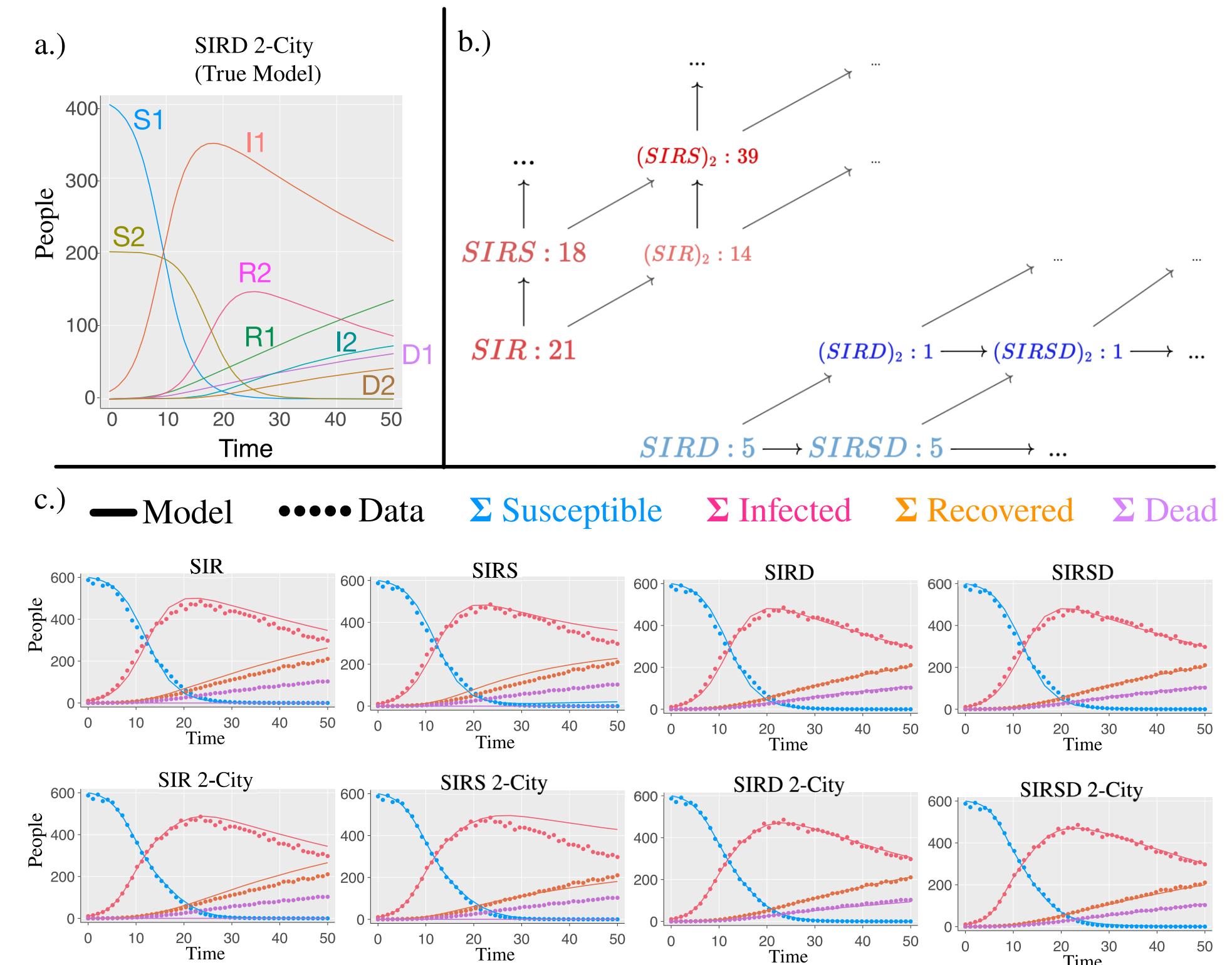


# Defining Spaces of Models

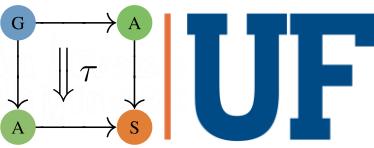


# Automated Model Selection

- a) Trajectory of true phenomena
- b) Space of considered models color coded by RMSE
- c) Trajectories of best fit models compared to observed noisy sample from a)

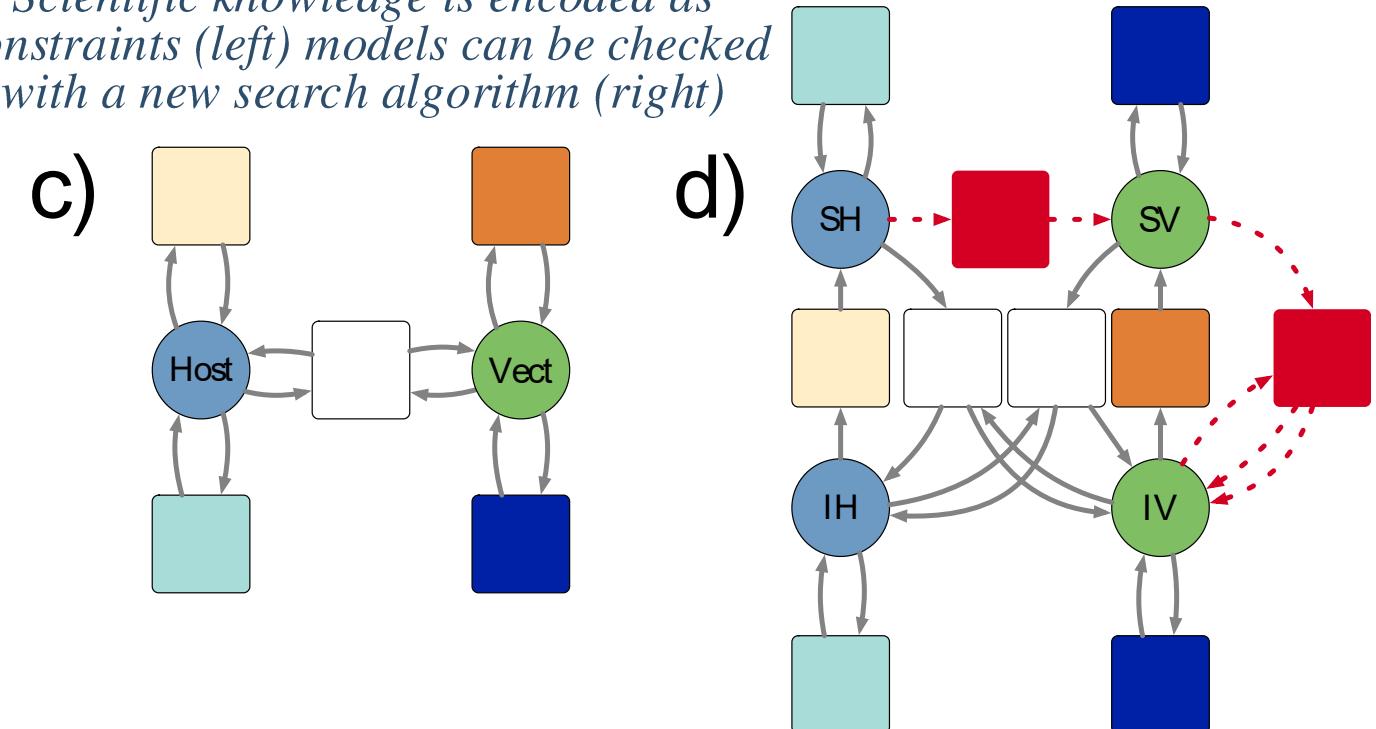


# Automating Model V&V and Selection



- Automated V&V uses the math of type theory to capture scientific theories as constraints on valid models, verification reduces to checking the constraints are satisfied. Efficient algorithm with a novel CSP solver.
- These types (shown as colors) are used again for compositional model construction to automate model comparison
- [1] *The Royal Society Phil. Trans. A*
- Automated model selection required the definition of Model Spaces which allows tools from topology and geometry to be applied to the space of governing equations
- Addresses Model Augmentation and Multi-perspective Modeling goals from proposal
- [2] *Applied Category Theory Proceedings 2022*

*Scientific knowledge is encoded as constraints (left) models can be checked with a new search algorithm (right)*



*Model spaces represent possible assumptions about the world. All models can be checked efficiently for fitness for purpose*

