

# Neural Networks

Raphael Cóbé

[raphael.cobe@sprace.org.br](mailto:raphael.cobe@sprace.org.br)

# Neural Networks

# Neural Networks

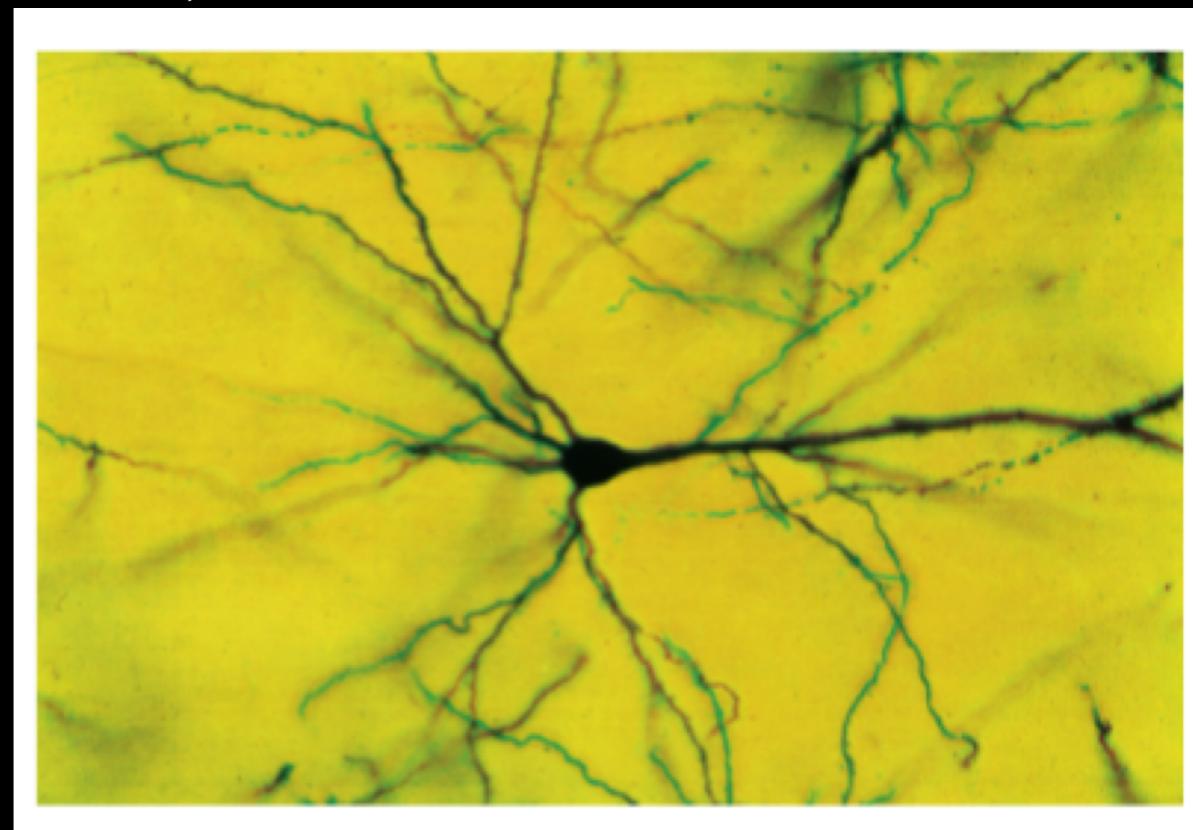
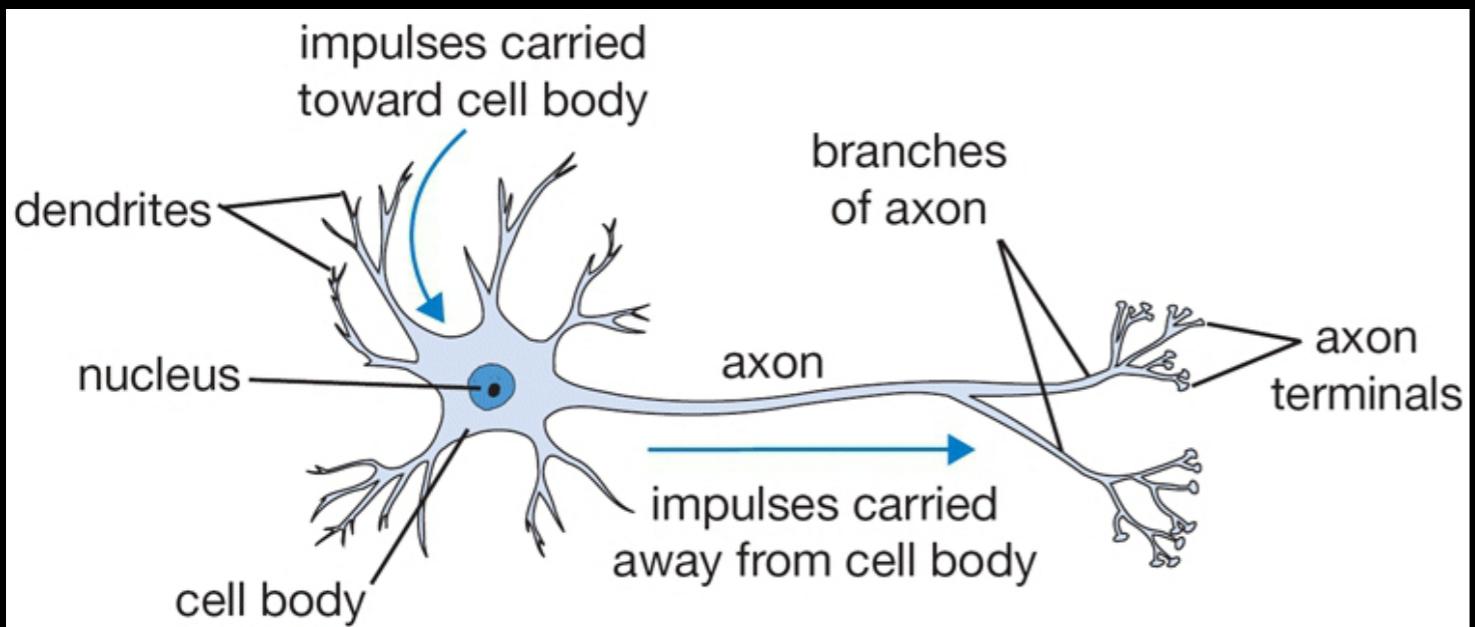
- Neurons as structural constituents of the brain [Ramón y Cajál, 1911]
- Five to six orders of magnitude slower than silicon logic gates
- In a silicon chip happen in the nanosecond (on chip) vs millisecond range (neural events)
- A truly staggering number of neurons (nerve cells) with massive interconnections between them.

# Neural Networks

- Receive input from other units and decides whether or not to fire.
- approximately 10 billion neurons in the human cortex, and 60 trillion synapses or connections [Shepherd and Koch, 1990]
- Energy efficiency of the brain is approximately  $10^{-16}$  joules per operation per second against  $\sim 10^{-8}$

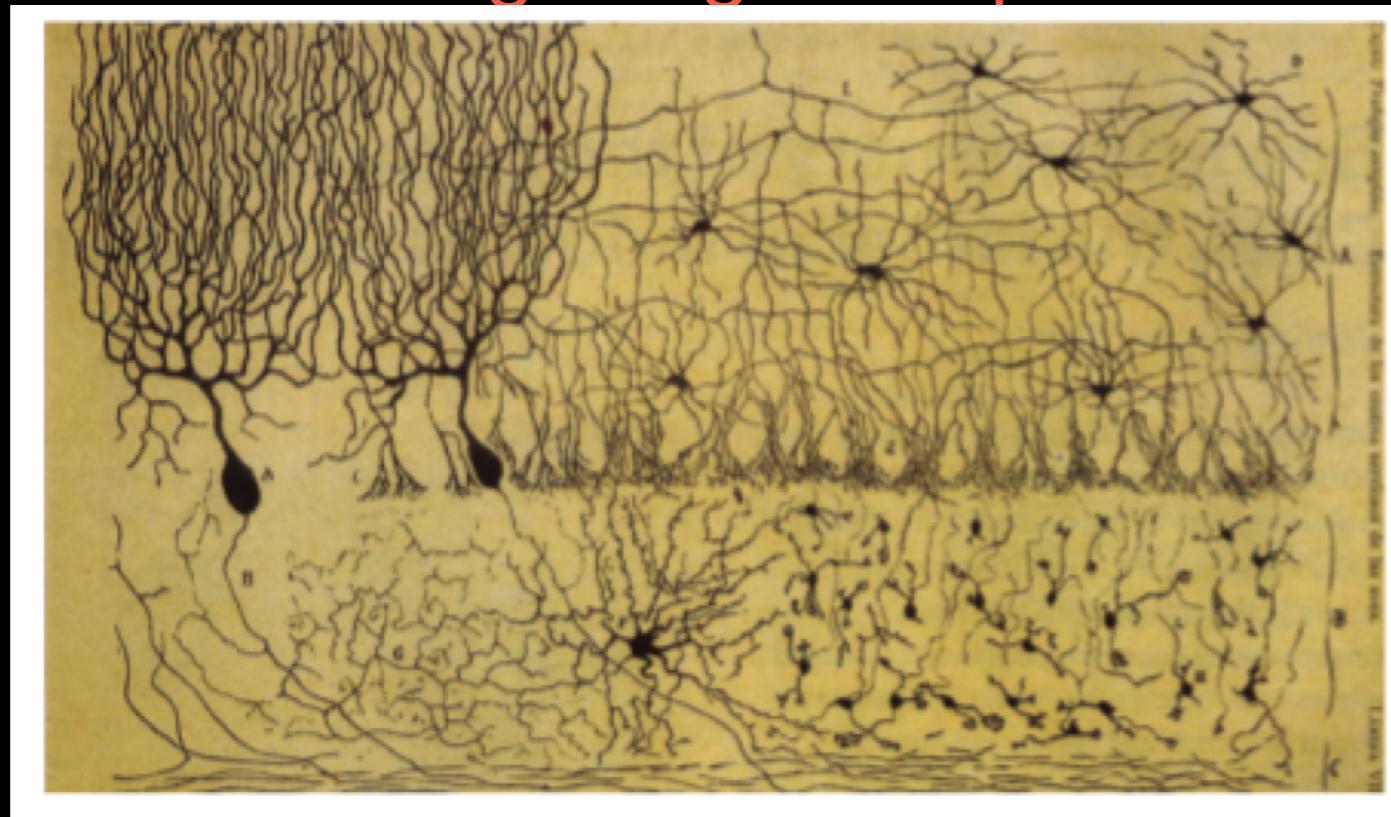
# Neural Networks

- input signals from its **dendrites**;
- output signals along its (single) **axon**;



# Neural Networks

- It appears that one reason why the human brain is **so powerful** is the sheer complexity of connections between neurons;
- The brain exhibits **huge degree of parallelism**;

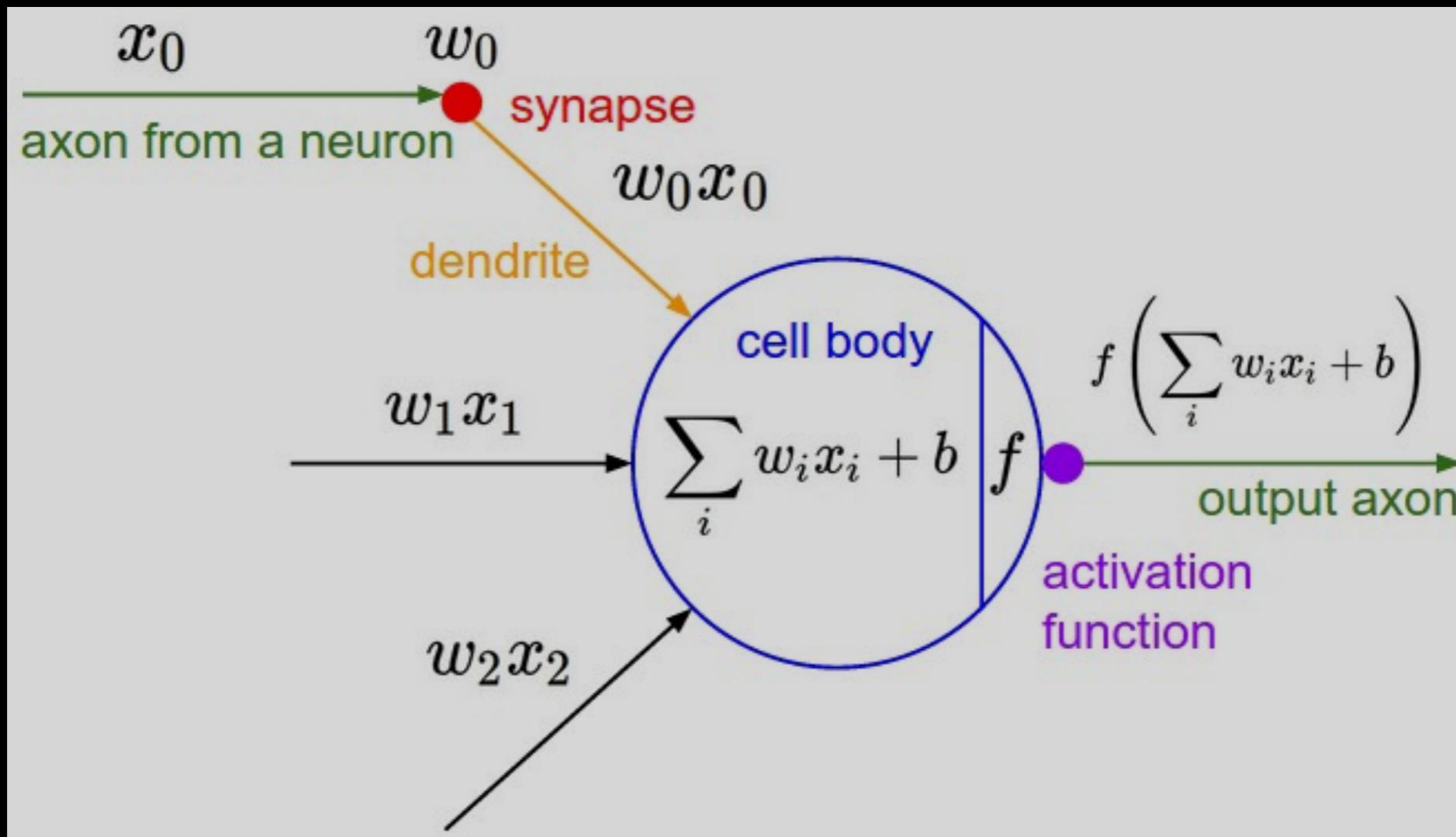


Sesquicentennial of the birthday of Santiago Ramon y Cajal, the father of modern neuroscience.  
Trends of Neuroscience, 25(9), 481-484 (2002).

# Neural Networks

- control the influence from one neuron on another:
  - excitatory when weight is positive; or
  - inhibitory when weight is negative;
- nucleus is responsible for summing the incoming signals;
  - if the sum is above some threshold, then **fire!**

# Neural Networks



# Neural Networks

- model each part of the neuron and interactions;
- interact multiplicatively (e.g.  $w_0 x_0$ ) with the dendrites of the other neuron based on the synaptic strength at that synapse (e.g.  $w_0$ );
- **learn synapses strengths;**

# Neural Networks

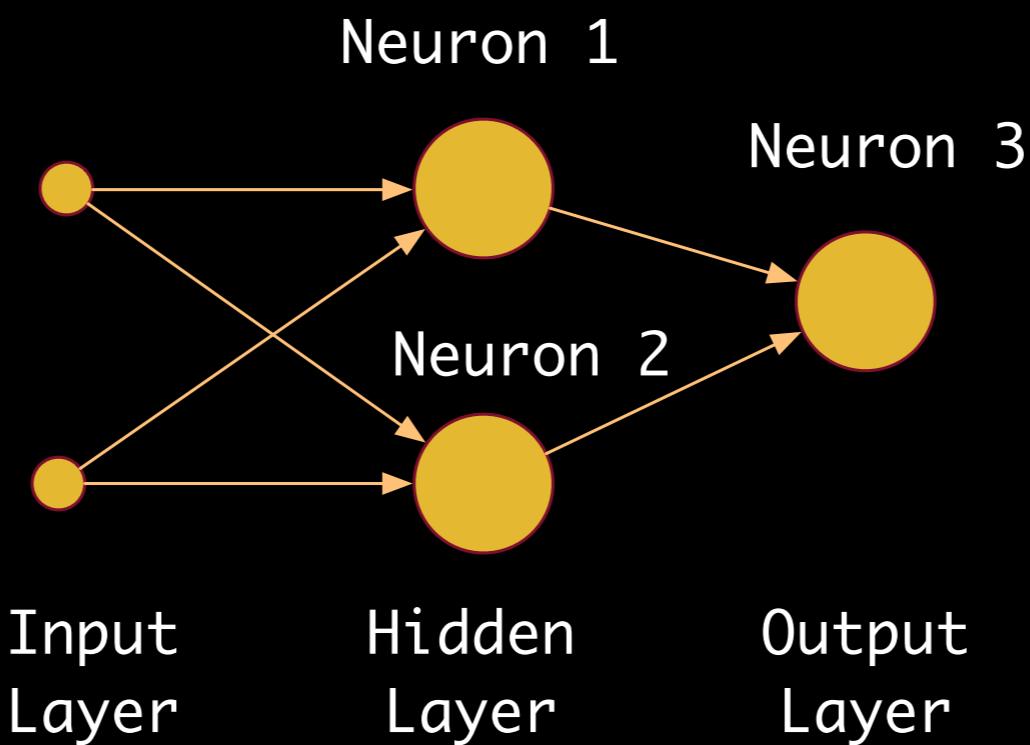
- Function approximation machines;
- $y = f^*(x)$ 
  - maps  $x$  input to a category  $y$
- $y = f(x; w)$ 
  - learn the value of the parameters  $w$

# (Artificial) Neural Networks

- can be seen as a directed graph with units (or neurons) situated at the vertices;
- Some are **input units**
  - receive signal from the outside world;
- The remaining are named **computation units**;
- Each unit produces an output
  - transmitted to other units along the arcs of the directed graph;

# Neural Networks

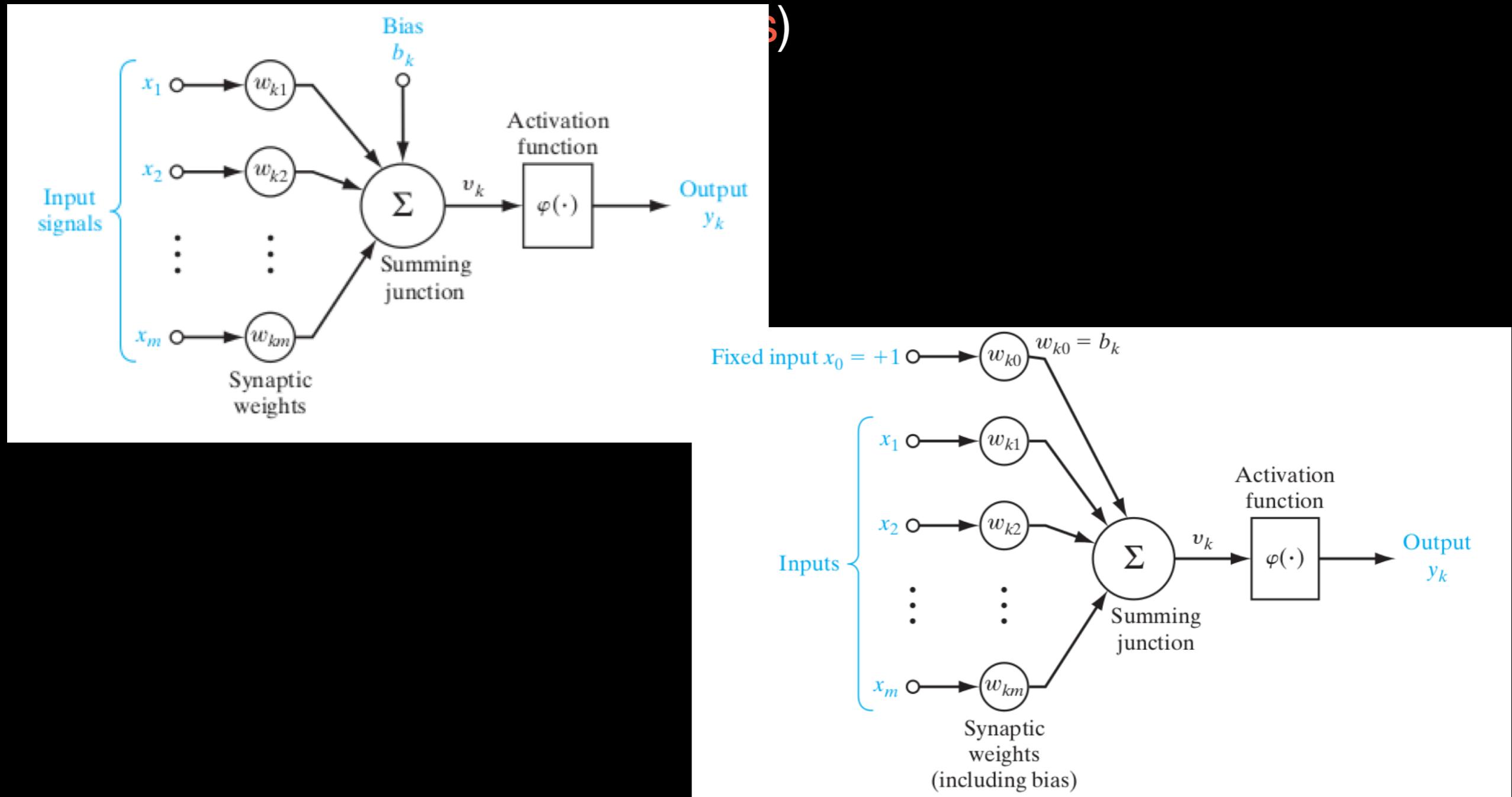
- Input, Output, and Hidden layers;
- Hidden as in "not defined by the output";
- Approximate  $y = f(x; w)$  to  $y = f^*(x)$  (training)



# Neural Networks

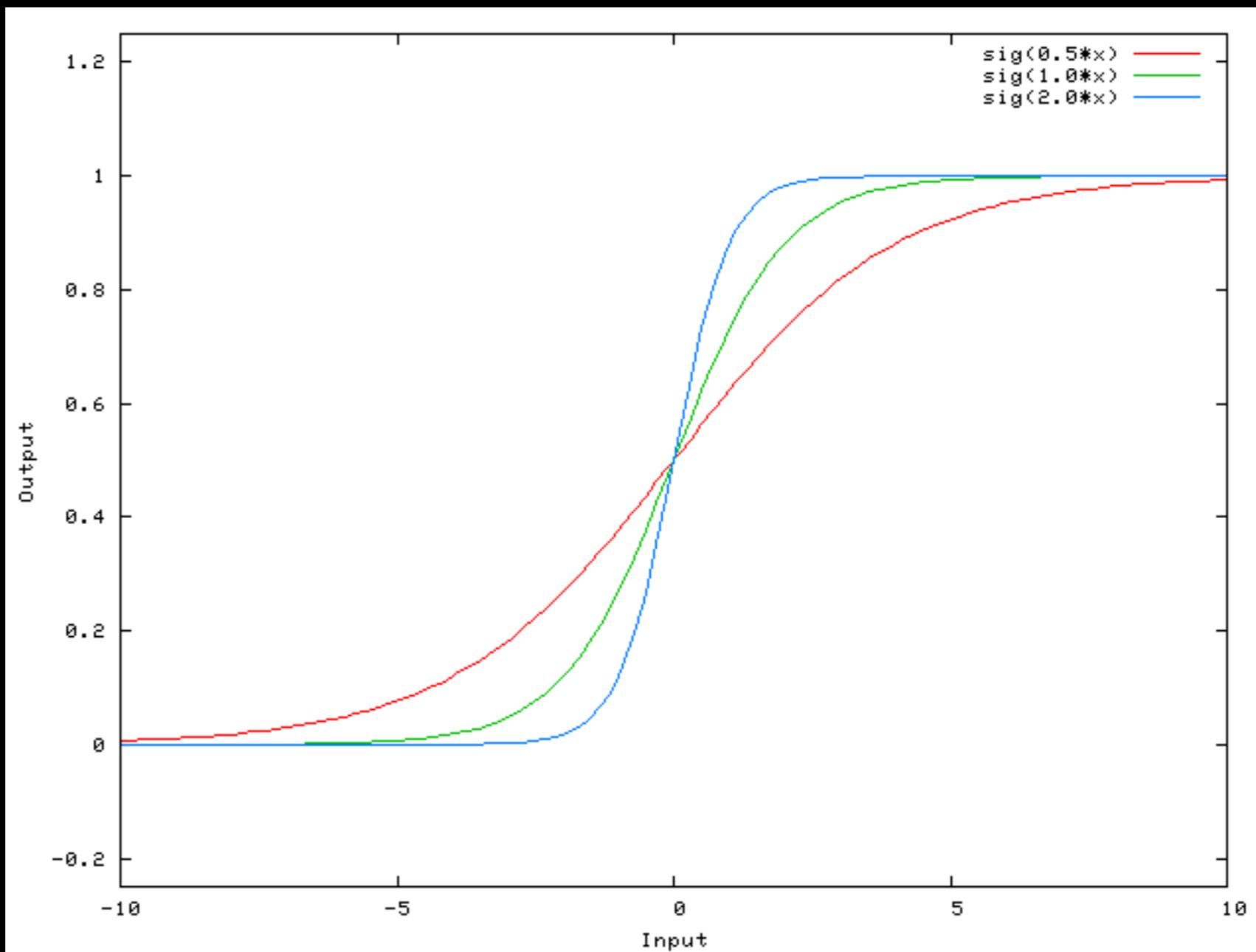
- Activation Function:
  - Describes whether or not the neuron fires, i.e., if it forwards its value for the next neuron layer;
  - multiply the input by its weights, add the bias and apply the non-linearity;
  - Sigmoid, Hyperbolic Tangent, Rectified Linear Unit;

# Neural Networks



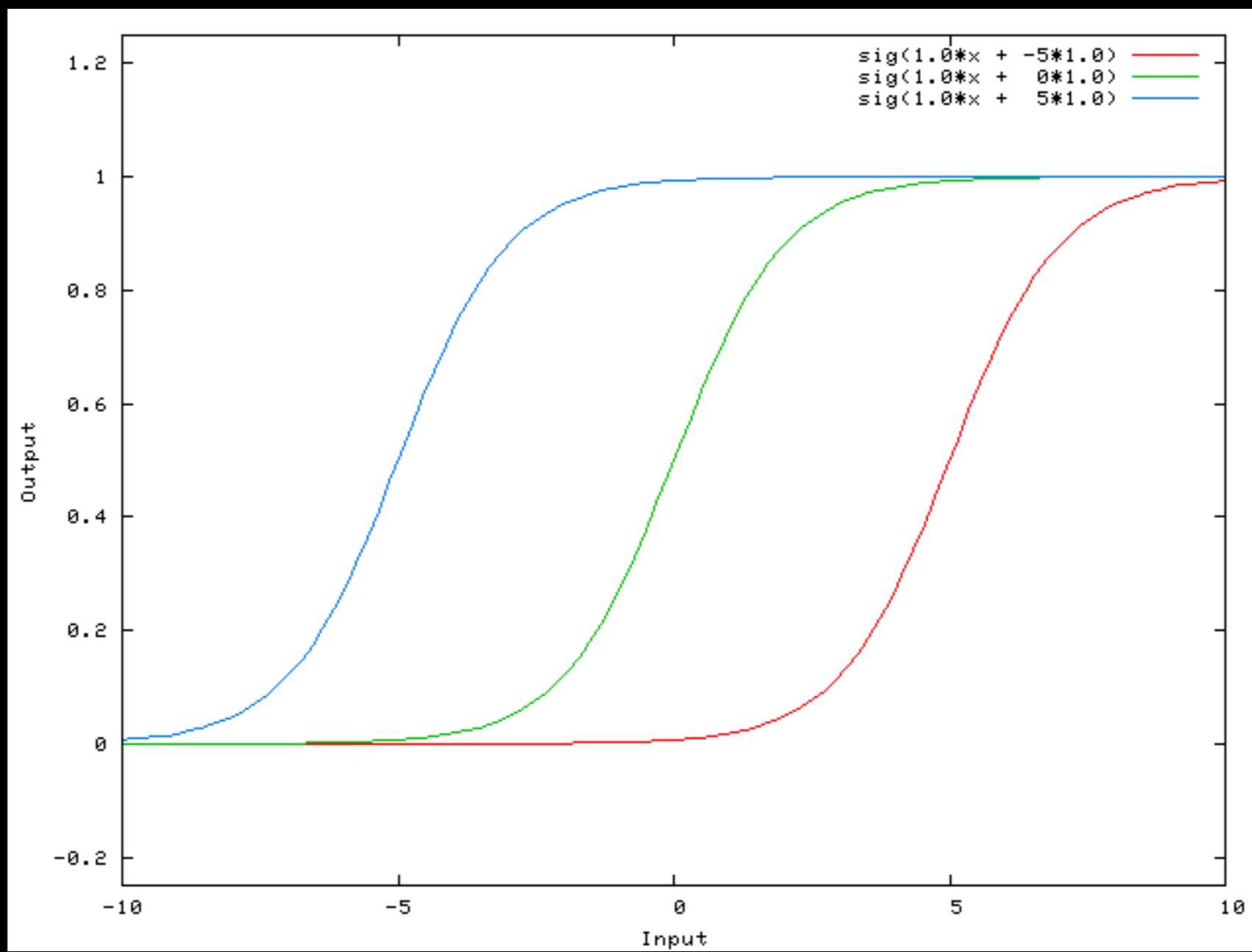
# Neural Networks

- The Artificial Neuron (the bias)



# Neural Networks

- The Artificial Neuron (the bias)



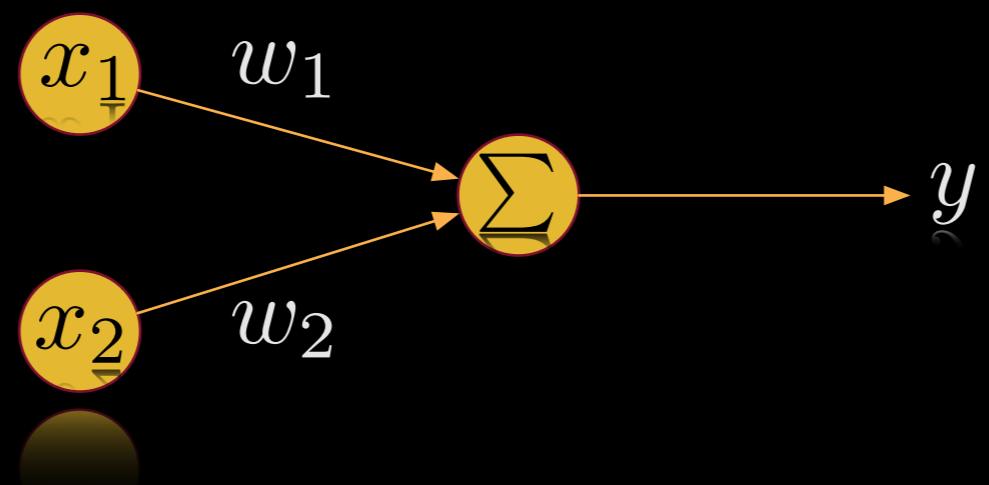
# Perceptron

# Perceptron

- In 1958, Frank Rosenblatt proposed an algorithm for training the **perceptron**.
- Simplest form of Neural Network;
- One unique neuron;
- Adjustable Synaptic weights;
- Simple activation function;

# Perceptron

- Classifies inputs into two classes, with neuron output of either -1 or 1;



# Perceptron

- Where  $\phi$  is the activation function and  $J_1$  the number of inputs
- Always converge on linearly separable classes;

$$net = \sum_{i=1}^{J_1} w_i x_i - \theta = w^T x - \theta$$

$$y = \phi(net)$$

# Perceptron

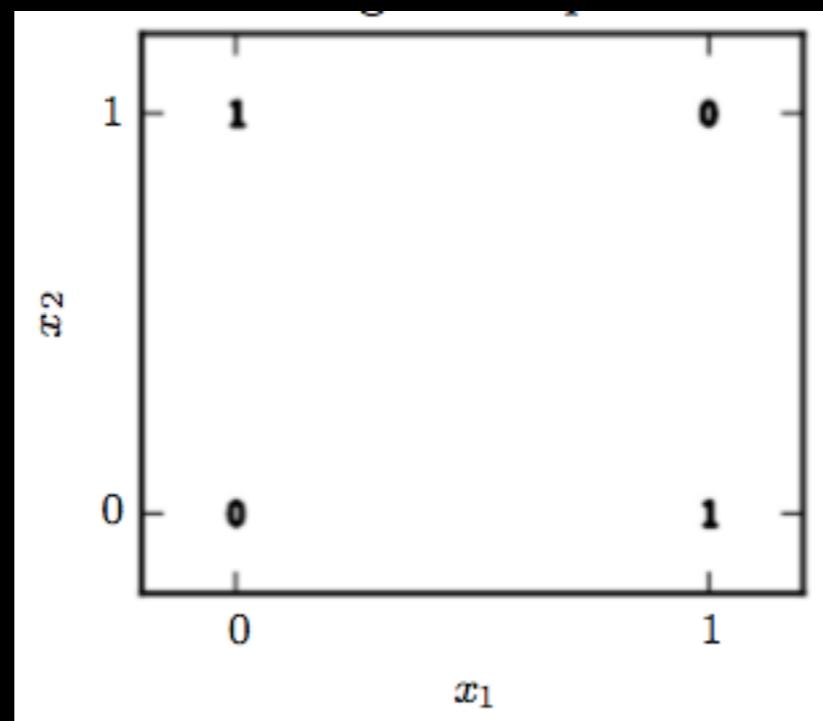
- Training Procedure:
- $\eta$  is the learning rate;
- finds a linear function that separates the classes;

$$e_p = y_p - \hat{y}_p$$

$$w_i(t+1) = w_i(t) + \eta x_{p,i} e_i$$

# Perceptron

- Can't do:
  - separate non linear classes;
  - XOR function:



# Feedforward networks

# Feedforward Networks

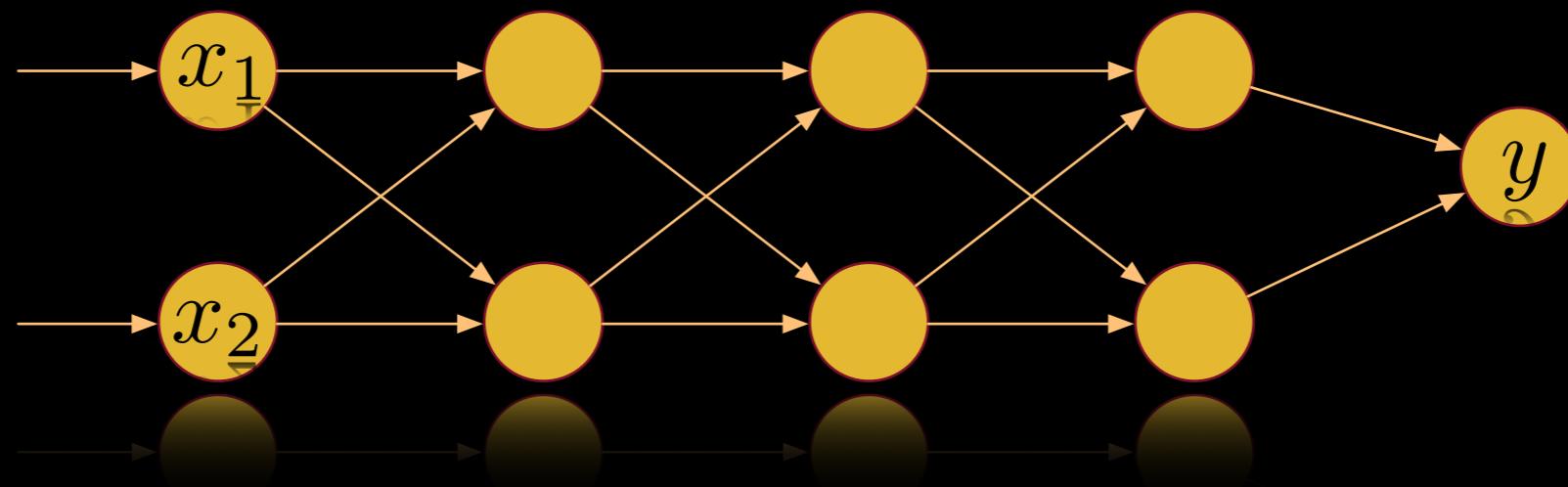
- typically represented by composing many different functions:

$$f(x) = f^{(3)}(f^{(2)}(f^{(1)}(x)))$$

- the **depth** of the network - the **deep** in deep learning!  
(-;

# Feedforward Networks

- Information flows from  $x$ , through  $f$  computations and finally to  $y$
- No feedback!



# Feedforward Networks

- Train using a back-propagation algorithm from 1969;
  - fixes the weights in an output-to-input direction;
- each level plays a specific role in the classification;
- detect the features in the input patterns;

# Feedforward Networks

- The output of a Feedforward Network:

$$\hat{y}_p = o_p^{(M)}, o_p^1 = x_p$$

- The output of the  $m$  layer:

$$net_p^{(m)} = [W^{(m-1)}]^T o_p^{(m-1)} + \theta^{(m)}$$

$$o_p^{(m)} = \phi^{(m)}(net_p^{(m)})$$

# Feedforward Network

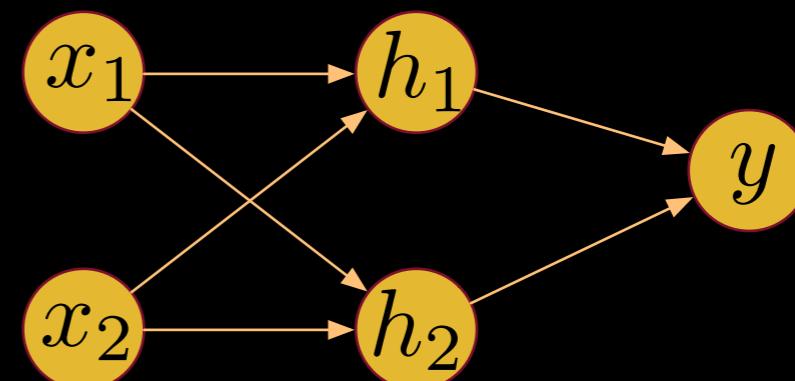
- suppose we want to learn the behavior of the binary XOR operator:
- the input will be a pair of signals with value either 0 or 1.
- The output should be classified also into 0 or 1;

# Feedforward Network

- The dataset:

$x_1$	$x_2$	$y$
0	0	0
0	1	1
1	0	1
1	1	0

The network:



# Feedforward Network

- The architecture: 2 layer network (one hidden and one for output)
- Rectified linear Unit as activation function, i.e.

$$\phi(\text{net}_p^{(1)}) = \max(\text{net}_p^{(1)}, 0)$$

- Why not a linear function?

# Feedforward Network

- The full expanded solution:

$$y = W_2^T (\max(0, W_1^T x + \theta_1)) + \theta_2$$

# Feedforward Network

- Running the example:

$$W_1 = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\theta_1 = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

$$X = \begin{bmatrix} 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \end{bmatrix}$$

$$W_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$$

$$\theta_2 = 0$$

# Feedforward Network

- Running the example:

$$net^{(1)} = W_1^T X + \theta_1 = \begin{bmatrix} 0 & 1 & 1 & 2 \\ -1 & 0 & 0 & 1 \end{bmatrix}$$

$$\phi(net^{(1)}) = \begin{bmatrix} 0 & 1 & 1 & 2 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

# Feedforward Network

- Running the example:

$$o^{(2)} = net^{(2)} = W_2^T o^{(1)} + \theta_2 = [0 \quad 1 \quad 1 \quad 0]$$

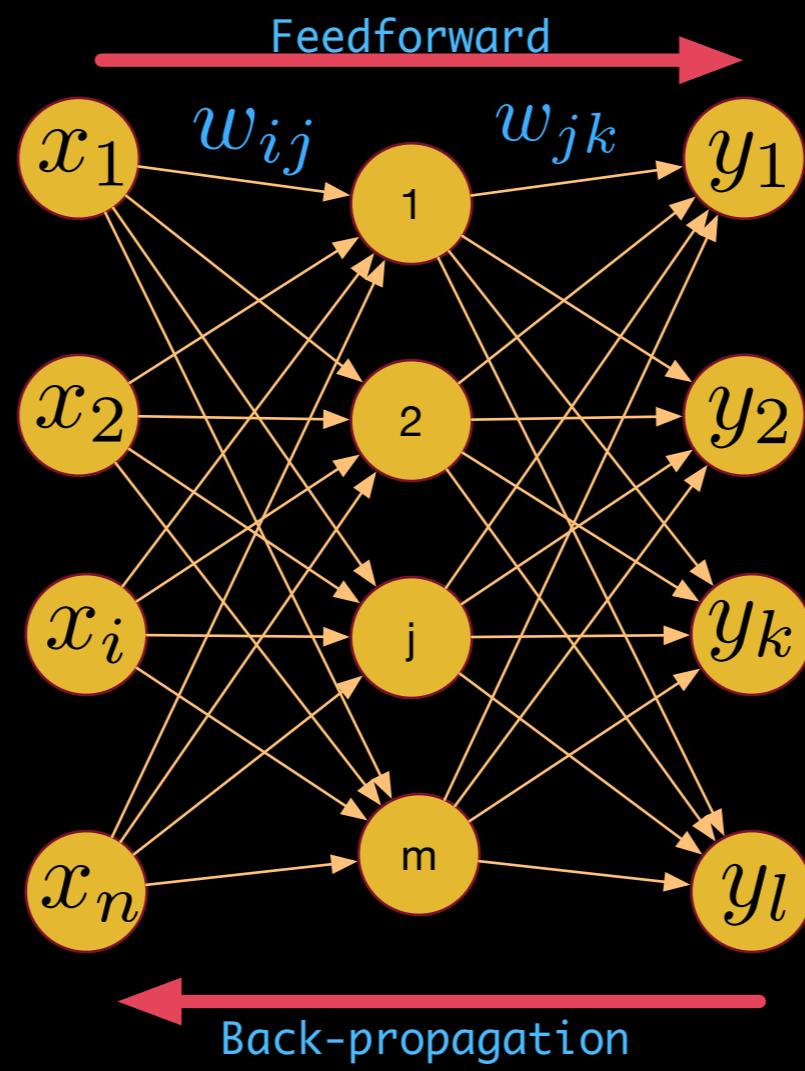
$$o = \phi(net^{(2)})$$

# Feedforward Networks

- most popular learning rule for performing supervised learning tasks;
- Not only used in Feedforward learning;
- propagates backward the error between the signal and the network output through the network;
- continuous, nonlinear, differentiable activation function
  - sigmoid functions, hyperbolic tangent;

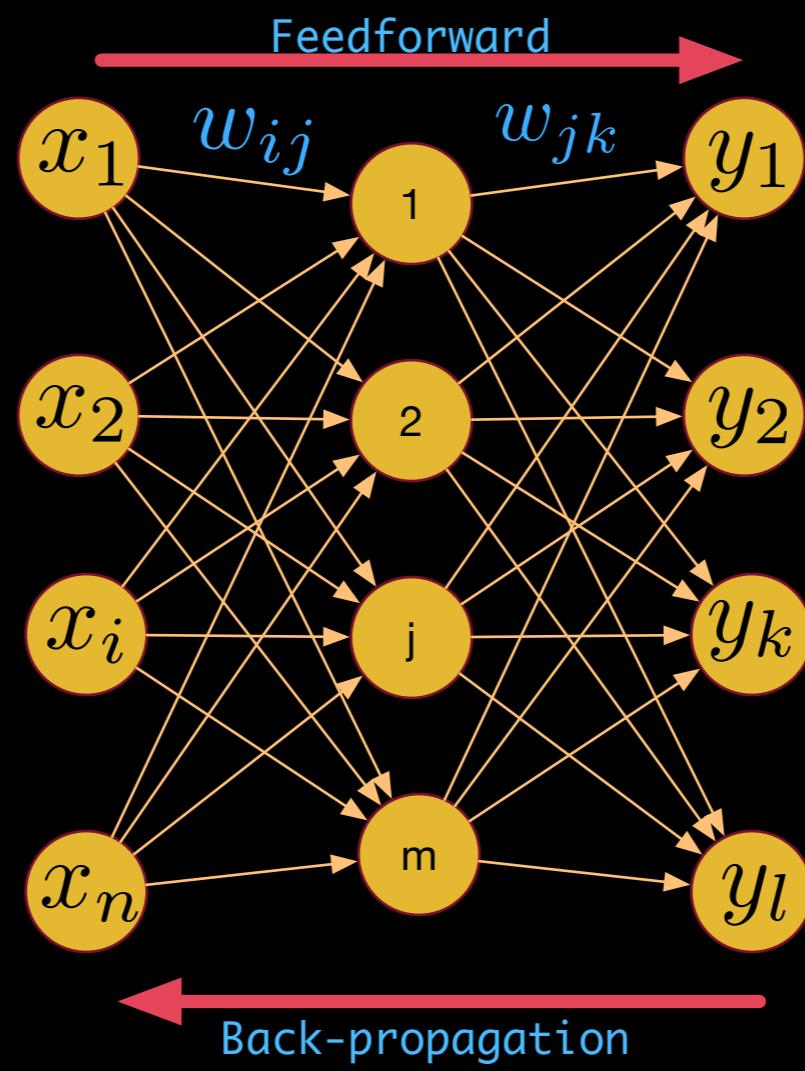
# Feedforward Networks

- Indexes i,j,k refer to neurons in input, hidden and output layers;



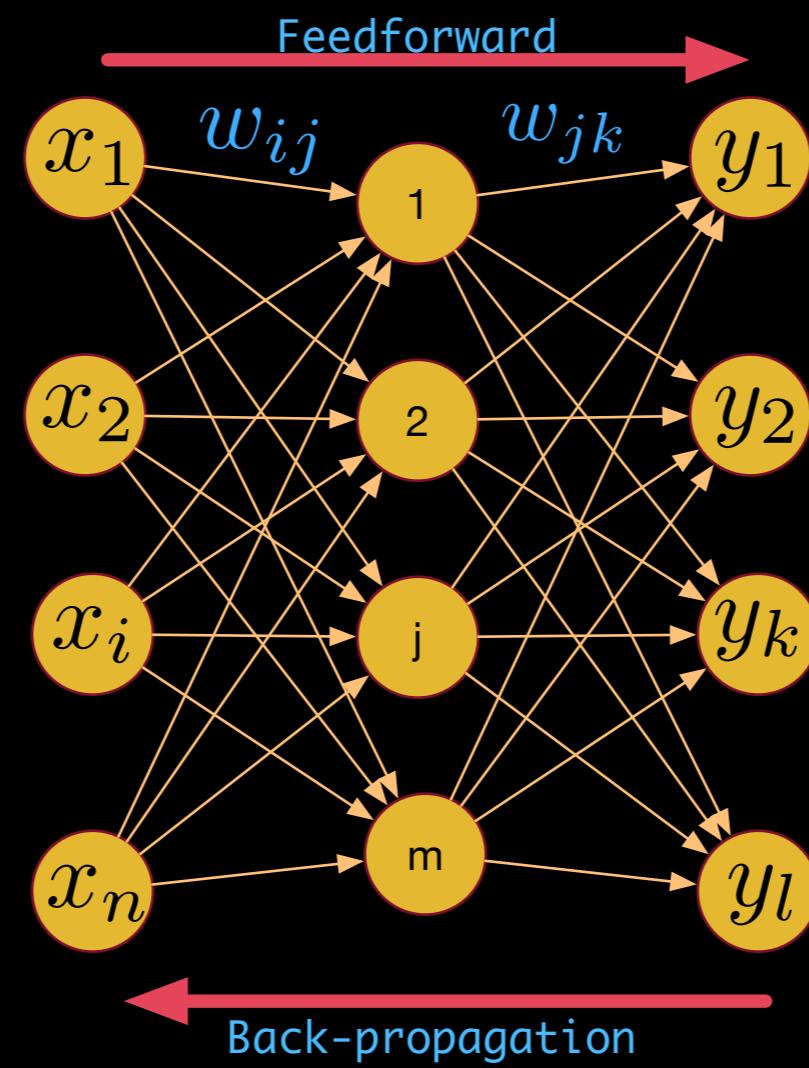
# Feedforward Networks

- Input signals flow from left to right and error signals from right to left;



# Feedforward Networks

- $w_{ij}$  represents the weight that connects the input neuron i and the neuron in the hidden layer j
- $w_{jk}$  the weight between the neuron j in the hidden layer and the neuron k in the output layer



# Feedforward Networks

- objective function for optimization is defined as the MSE between the  $y_p$  and the desired output  $\hat{y}_p$ :

$$e_{p,k} = \hat{y}_{p,k} - y_{p,k}$$

# Feedforward Networks

- first step is to correct the weight between j and k by minimizing the error;
  - error gradient, learning rate;

$$w_{p+1,jk} = w_{p,jk} + \Delta w_{p,jk}$$

$$\Delta w_{p,jk} = \alpha y_{p,j} \delta(\hat{y}_{p,k})$$

$$\Delta w_{p,ij} = \alpha x_{p,i} \delta(\hat{y}_{p,j})$$

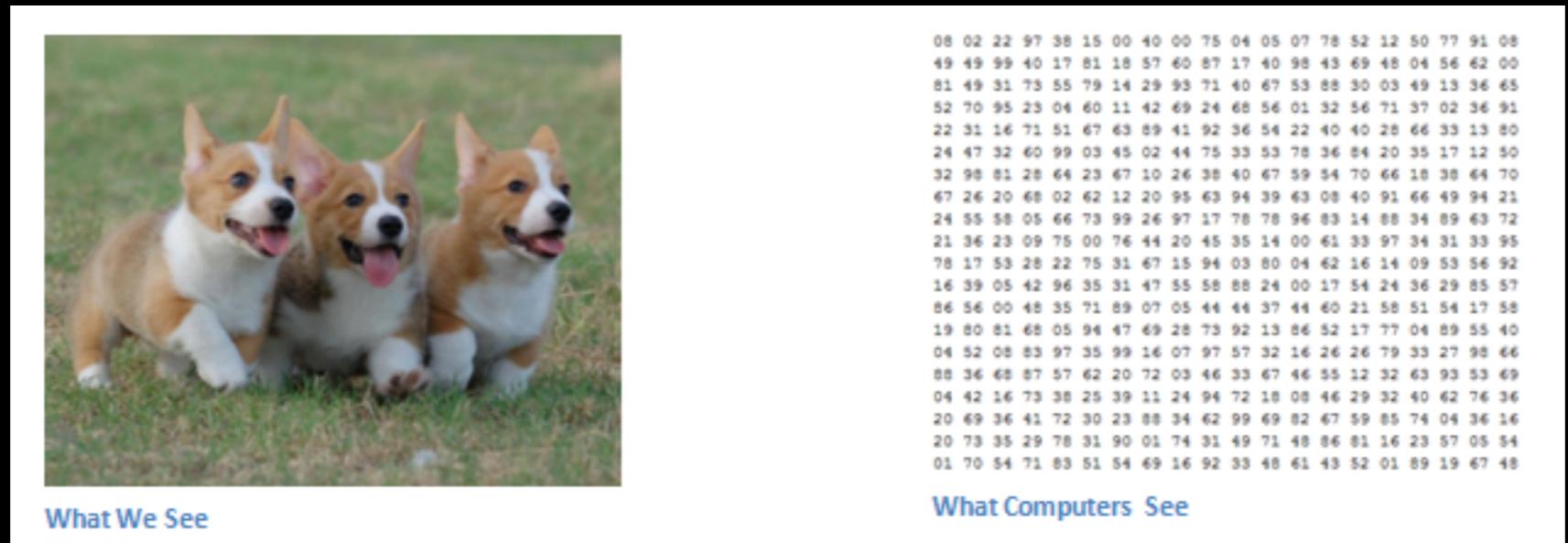
# Convolutional Neural Networks

# Convolutional Neural Nets

- image processing:
  - taking an input image and outputting a class (a cat, dog, etc)
- one of the first skills we learn from the moment we are born;
- being able to quickly recognize patterns, generalize from **prior knowledge**;

# Convolutional Neural Nets

- computer "sees" an array of pixel values;



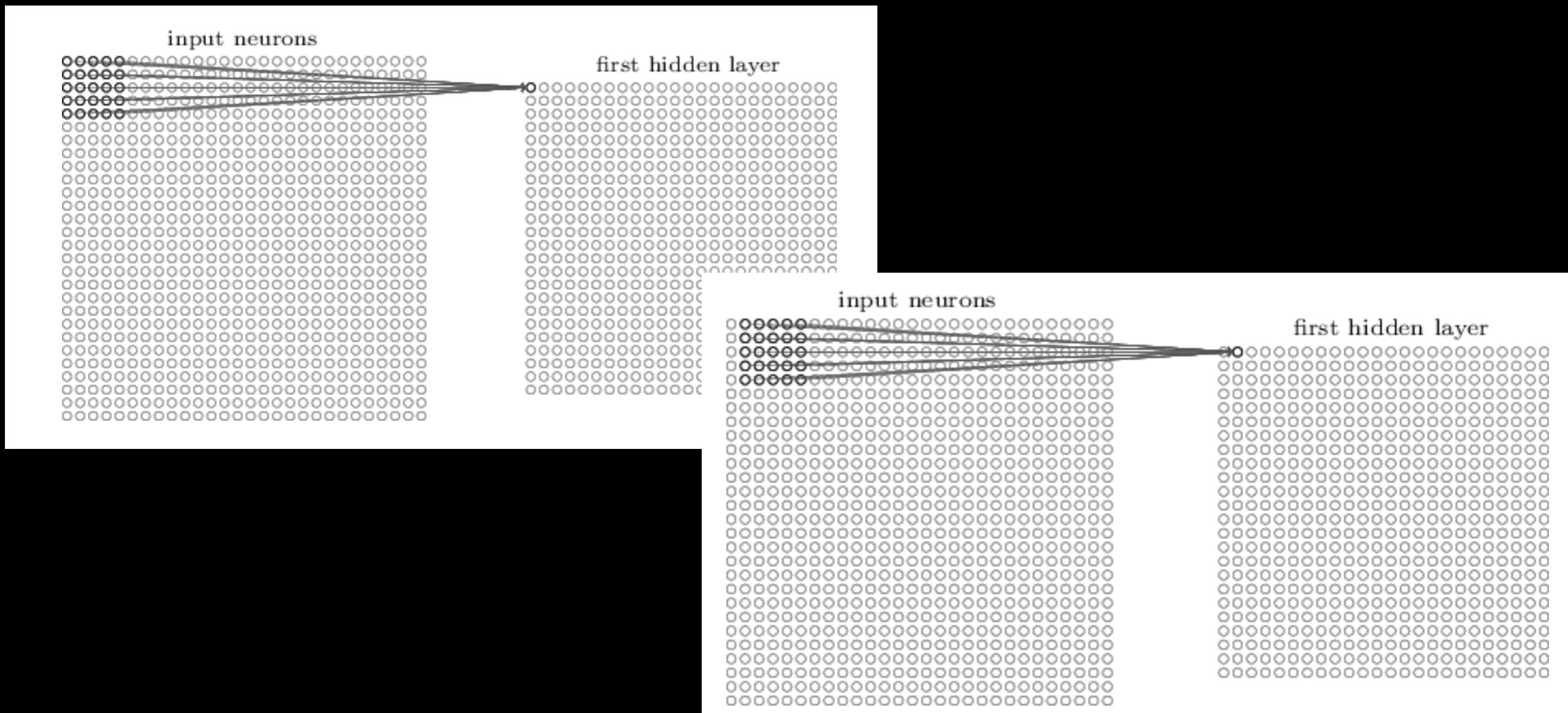
- give the computer this array of numbers and it will output numbers that describe the probability of the image being a certain class;

# Convolutional Neural Nets

- Convolutional Layer:
  - filter sub-images;
  - slide over the image;
  - this filter is also an array of numbers (the numbers are called **weights** or **parameters**);
  - has the same depth as the input;
  - receptive field;

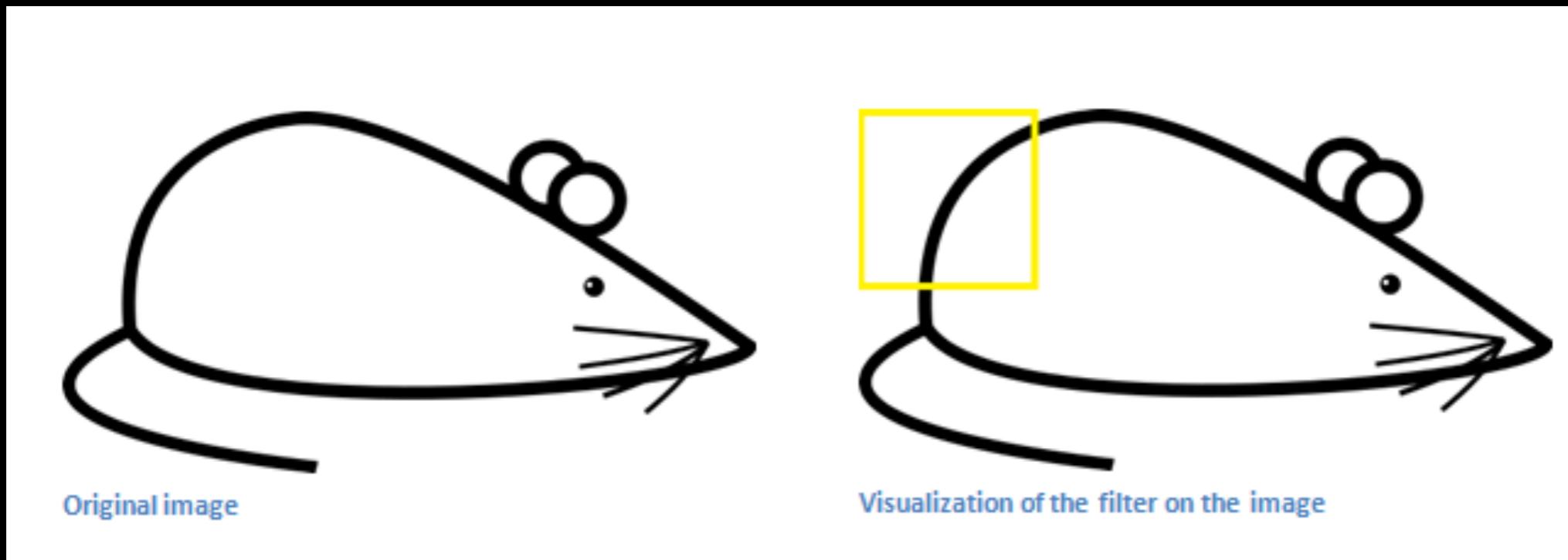
# Convolutional Neural Nets

- Sliding the receptive field:

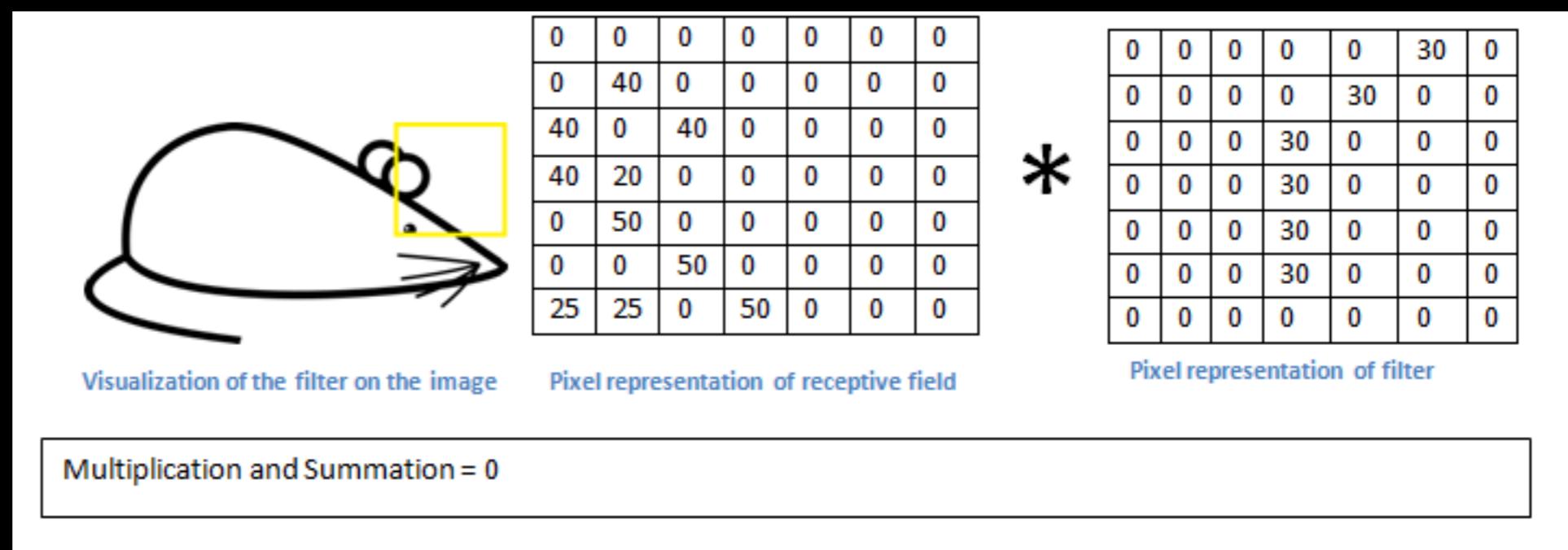
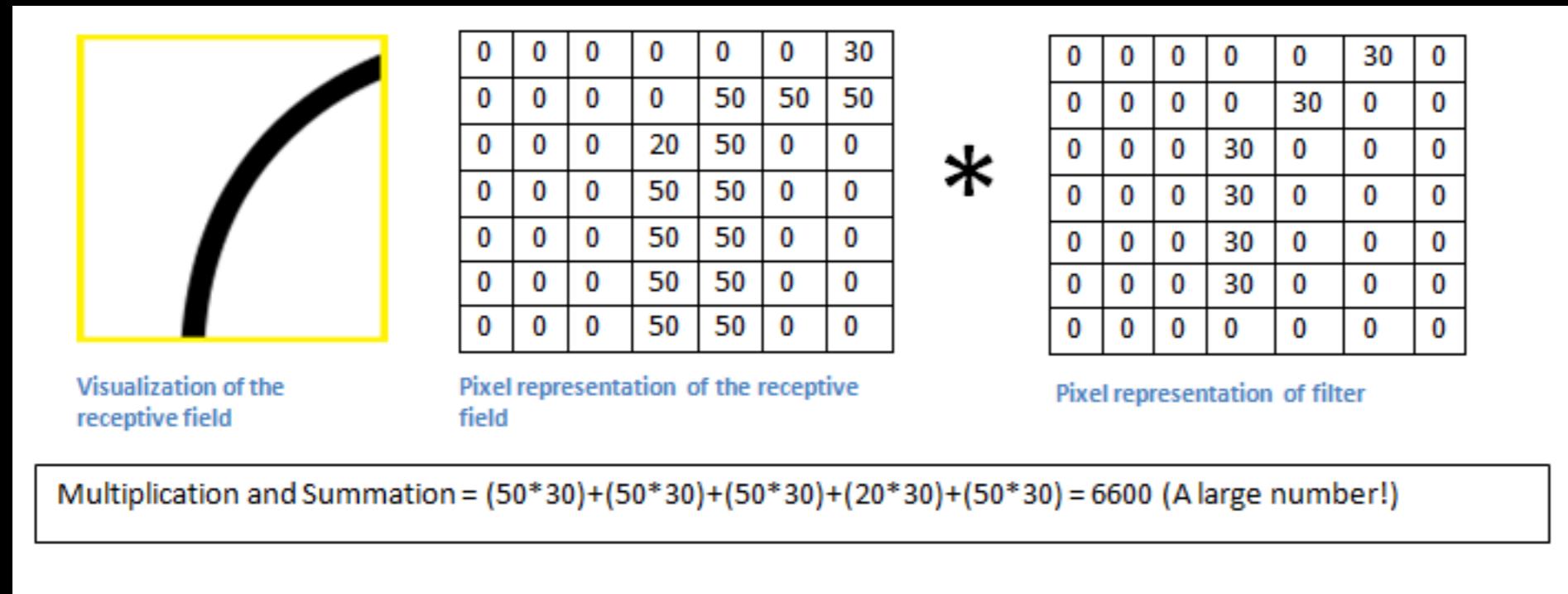


# Convolutional Neural Nets

- Sliding the receptive field:



# Convolutional Neural Nets

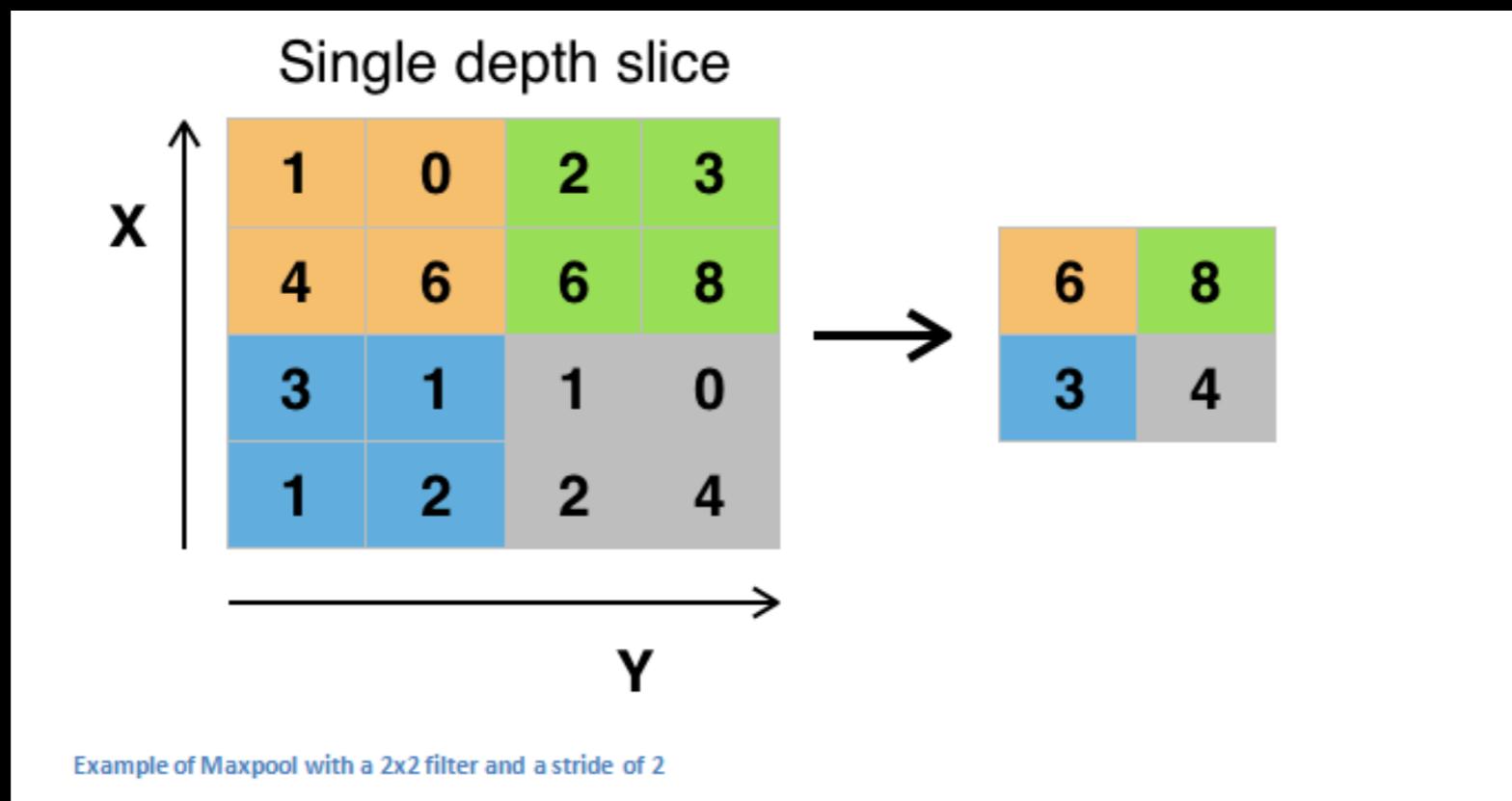


# Convolutional Neural Nets

- **Stride:** amount of pixels the filter slides over at a time;
  - Watch for integer output instead of fractions;
- **Padding;**
- Introduce Non Linearity (activation function);

# Convolutional Neural Nets

- Pooling for downsampling;
  - MaxPooling, Average;
- drastically reduces the spatial dimension



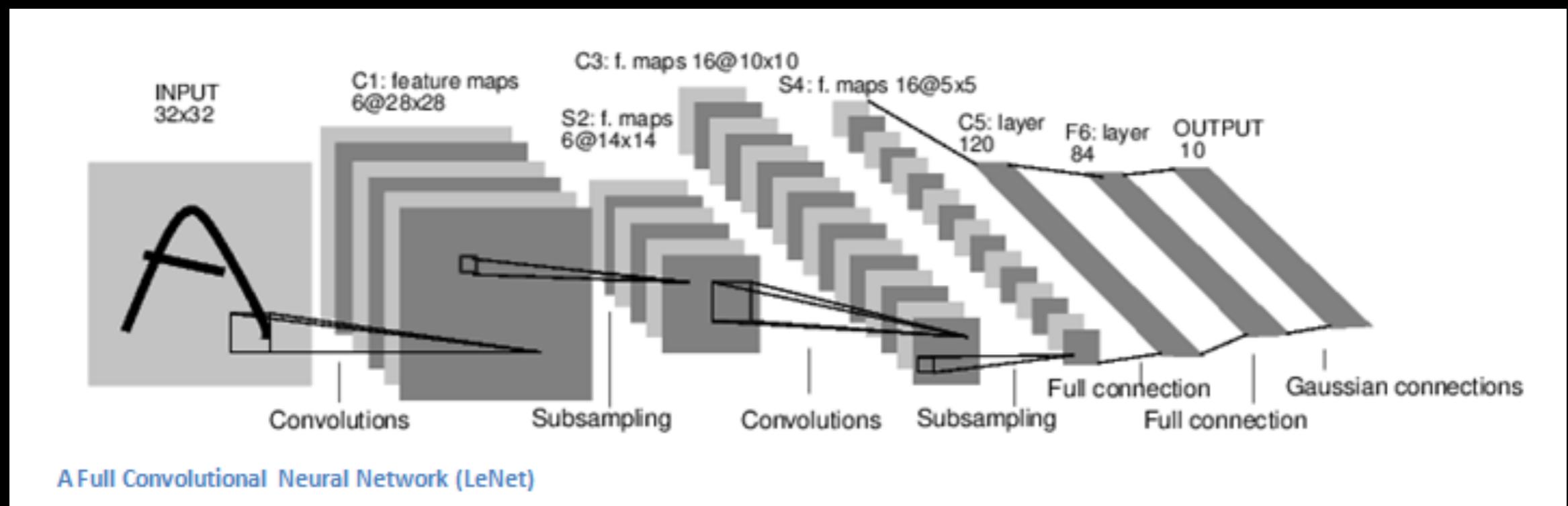
# Convolutional Neural Nets

- Dropout layers:
  - “drops out” a random set of activations in that layer by setting them to zero;
  - forces the network to be redundant;
  - the net should be able to provide the right classification for a specific example even if some of the activations are dropped out;
  - Prevents overfitting;

# Convolutional Neural Nets

- Fully Connected Layers:
  - Classification;
  - looks at the output of the previous layer and determines which features most correlate to a particular class;

# Convolutional Neural Nets



# Artificial Neural Networks

- It gets uglier!
  - Recurrent NN;
  - Long Short-Term Memory NN;
  - Generative Adversarial NN;
  - Radial bases function NN;
  - ...

# Questions?