



WWW.ECCV2020.EU





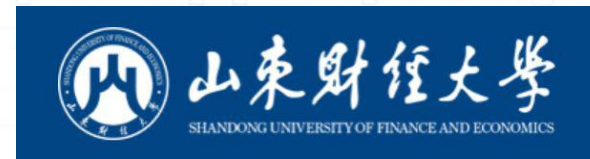
ACVR 2020

Eighth International Workshop on Assistive Computer Vision and Robotics

Glasgow, UK - August 28, 2020



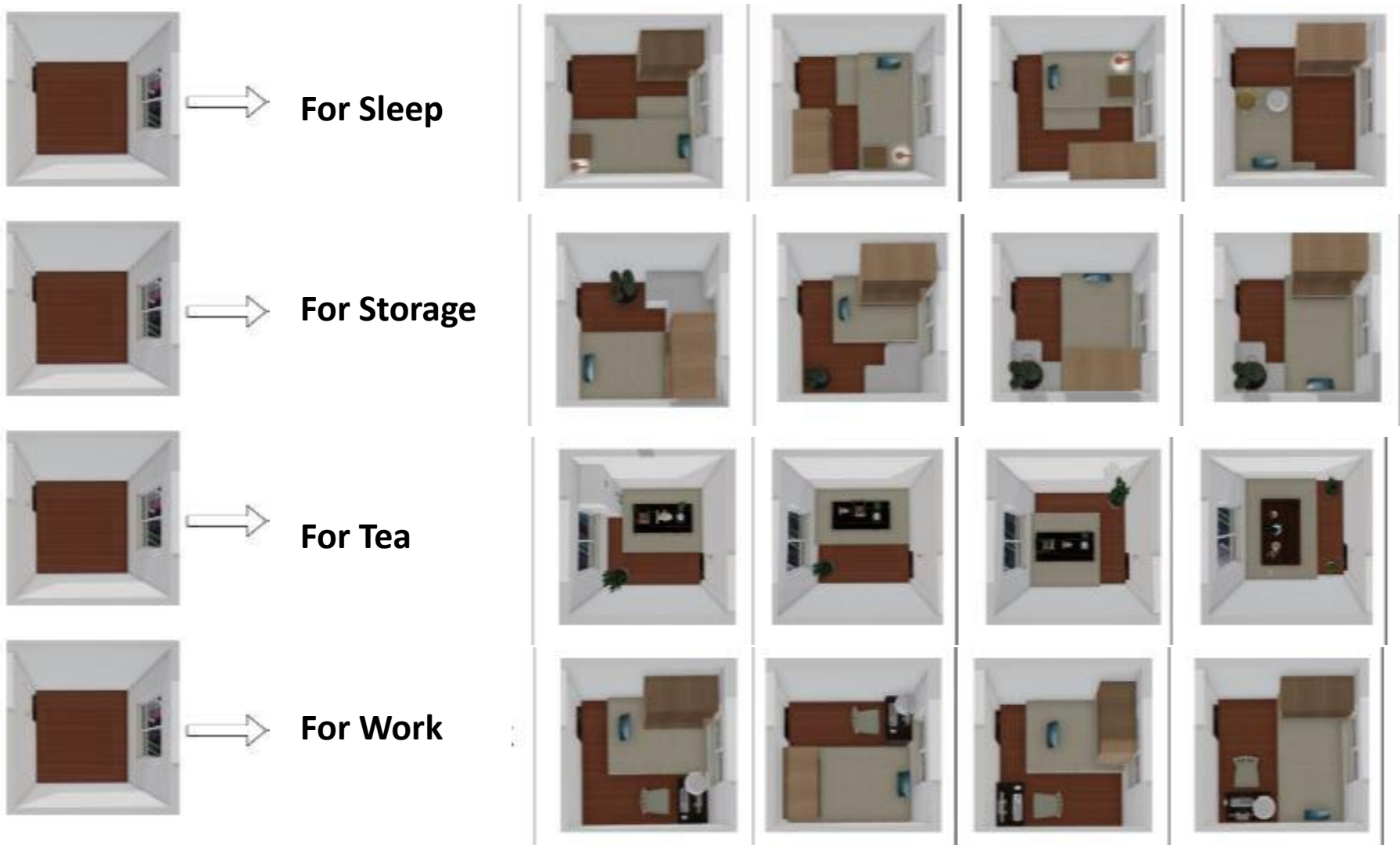
IBM **Research**



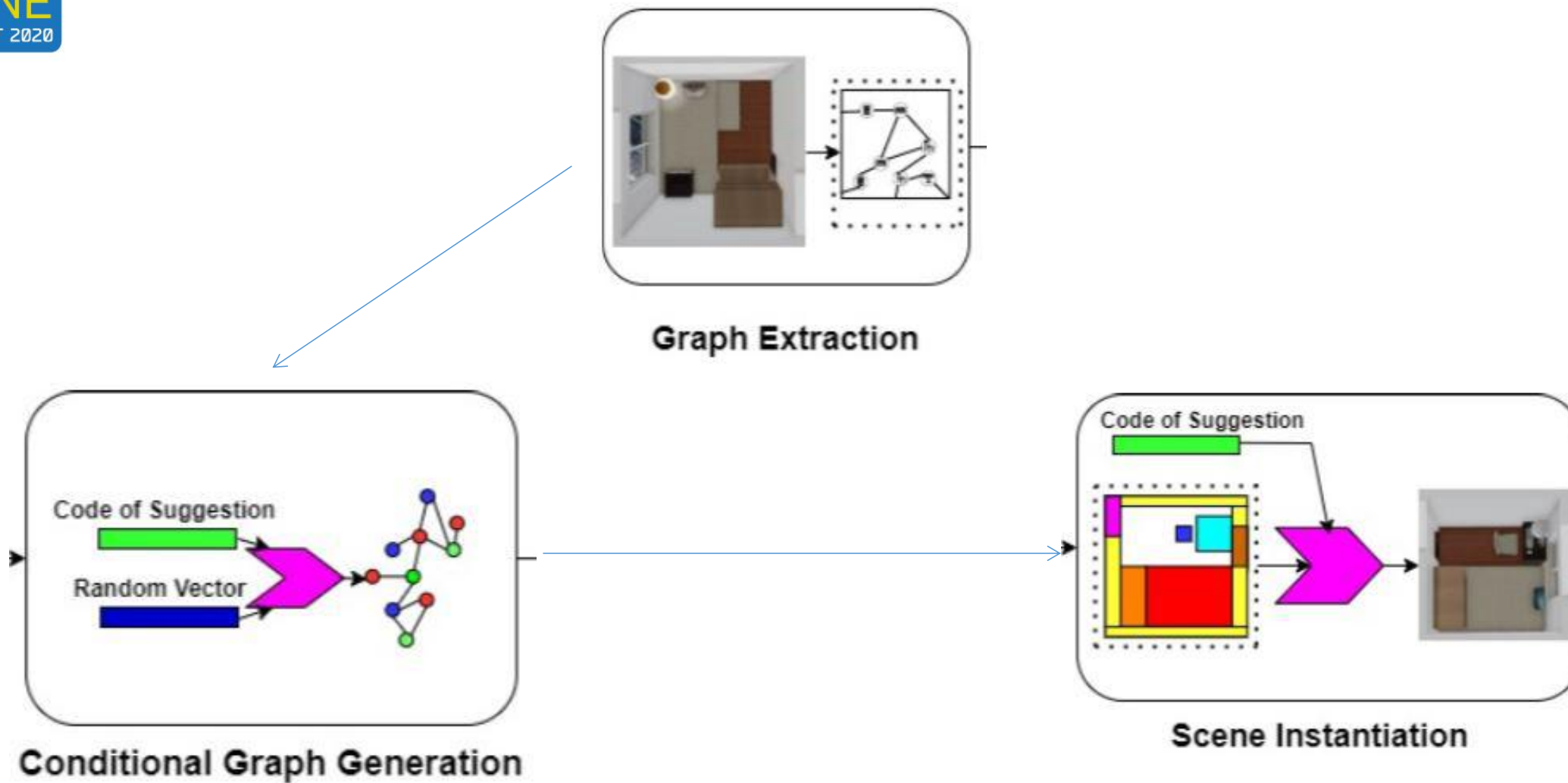
Structural Plan of Indoor Scenes with Personalized Preference

**Xinhan Di, Pengqian Yu, Hong Zhu, Lei Cai, Qiuyan Sheng, ChangyuSun,
and Lingqiang Ran**

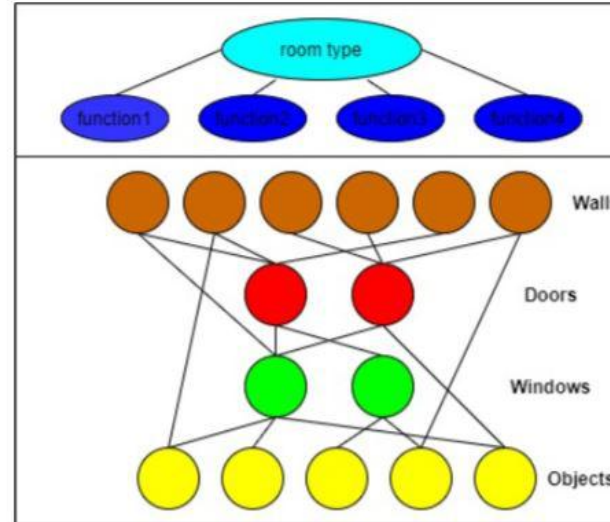
For each given empty room and corresponding functionality, the proposed model produces the layout plan of the furniture. The functionality is the customer's personalized preference.



The pipeline is composed of three Stage



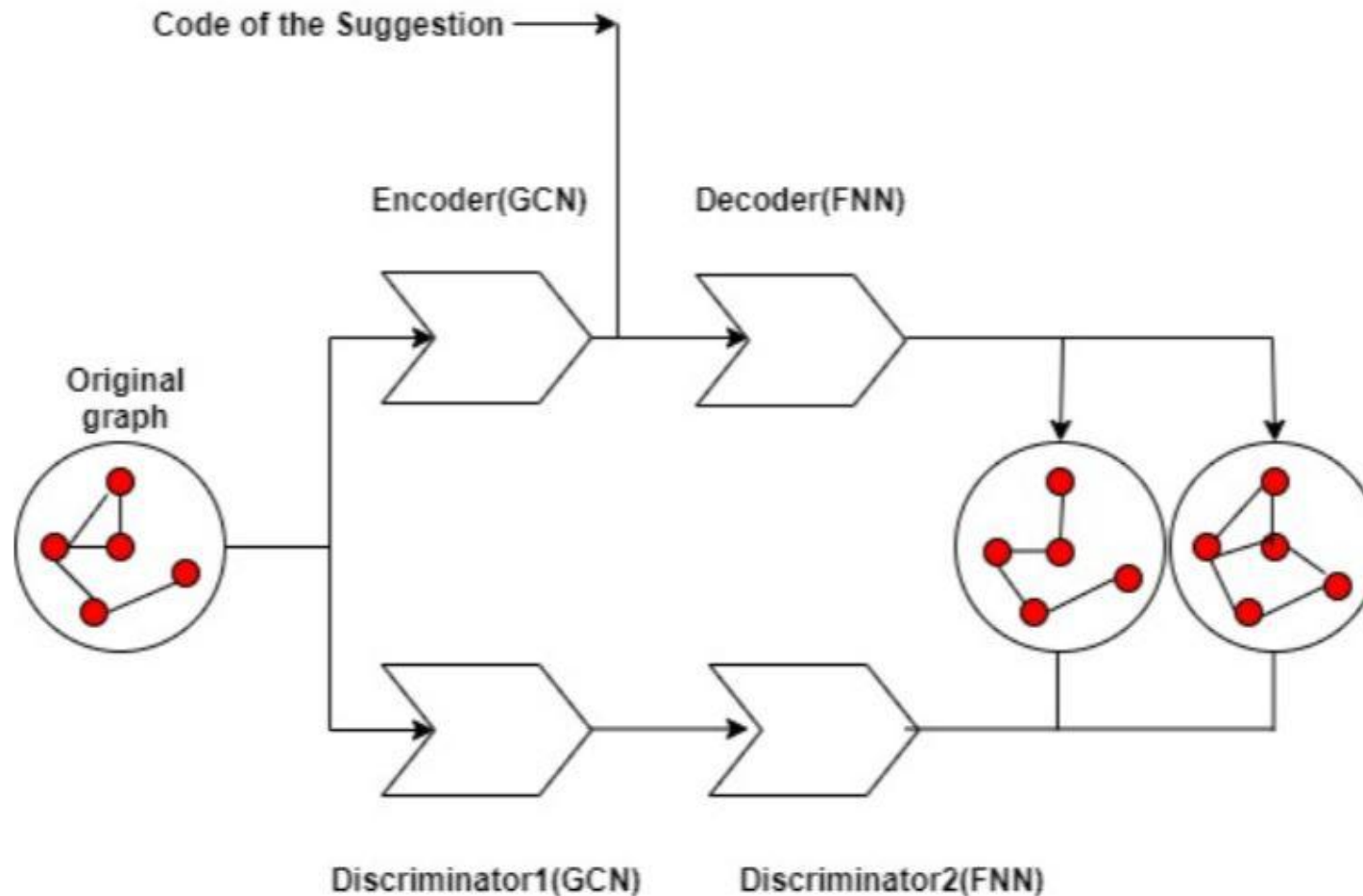
Graph Extraction



The Nodes of the Graph are Walls, Doors, Windows and Objects

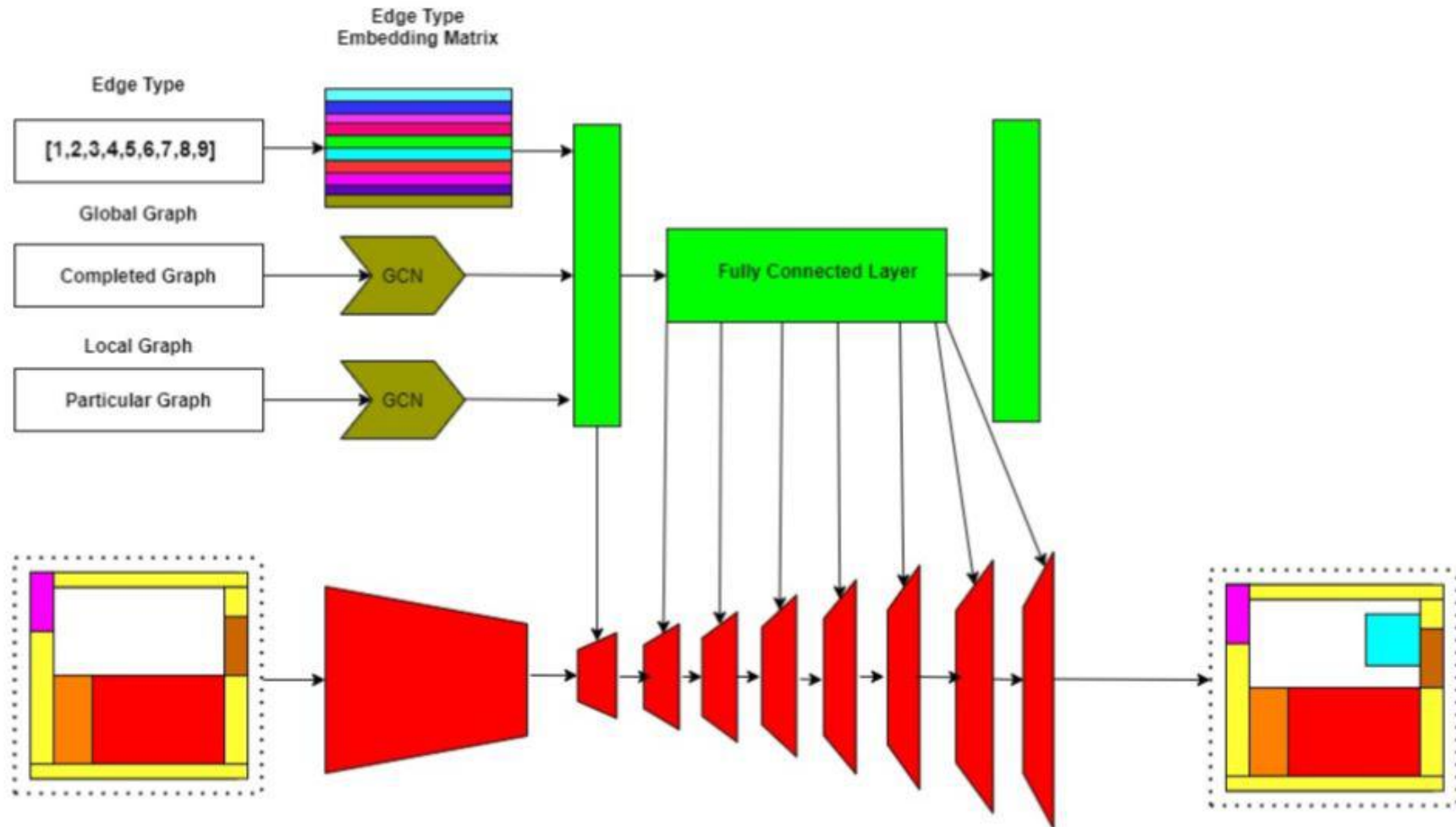
The Edges of the Graph Links These Nodes

Conditional Graph Generation



Using the Code of Suggestion, this Module Applies GCN Encoder, GCN Decoder, two Discriminators to Generate the Graph.

Scene Instantiation



This Module applies the Code of Edges, Global Layout Graph, and Local Layout Graph for the Scene Instantiation of the Generated Layout.

Generated Samples

Tea



Tatami-Tea



Tatami-Work



Tatami-Storage



Tatami-Sleep



Balcony



Balcony-Leisure



Balcony-Storage



Balcony-Wash



Kitchen



Kitchen-Classical



Kitchen-Mixsure



Evaluation

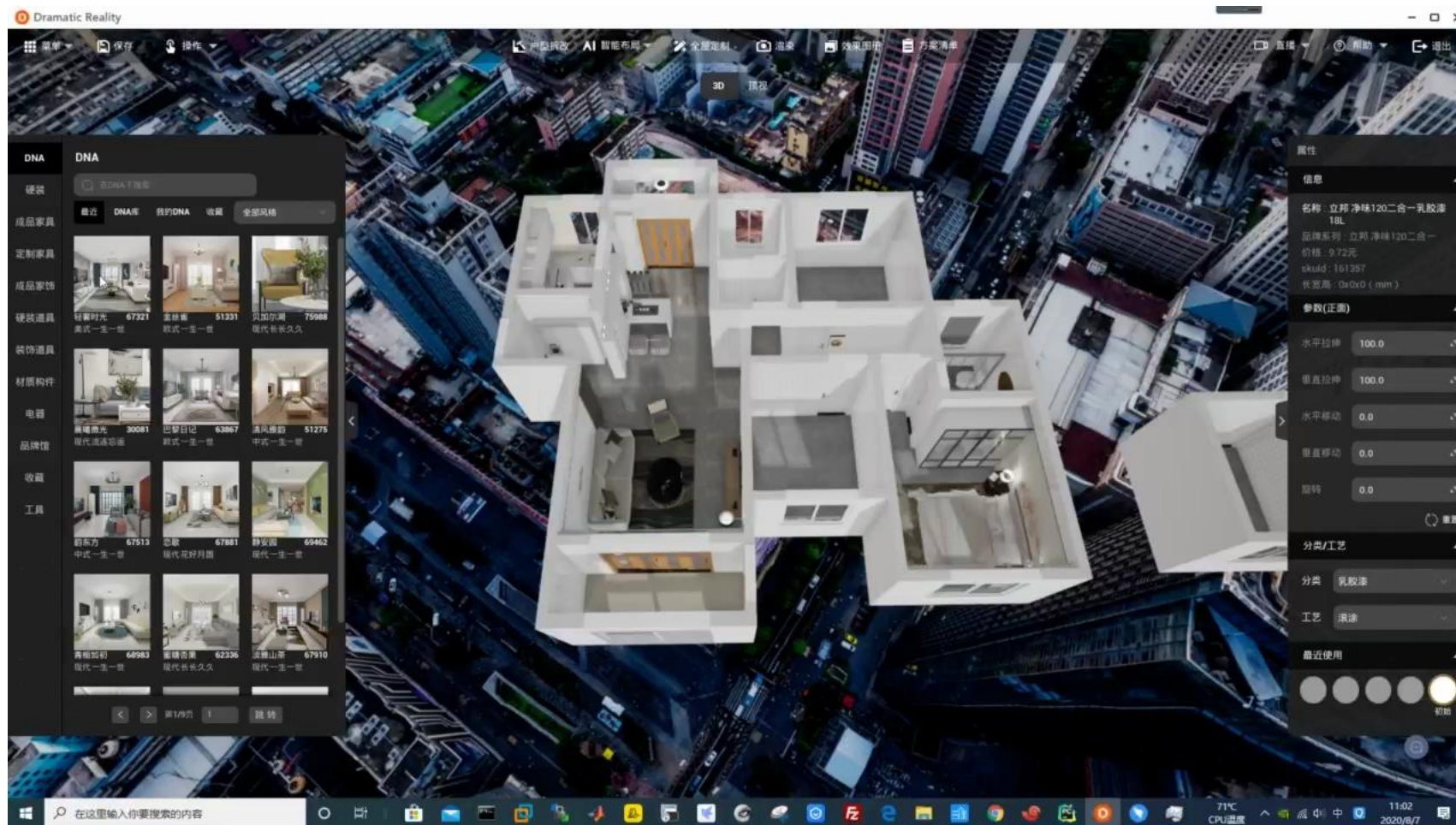
Room	Ours	PlanIT	Grains
Tatami	57.12 ± 3.48	71.93 ± 6.42	69.42 ± 5.87
Balcony	58.21 ± 2.95	75.23 ± 2.74	67.51 ± 1.53
Kitchen	54.21 ± 4.51	74.68 ± 4.62	77.94 ± 2.90

Percentage of 2AFC Perceptual Study Where the Real Sold Solutions are Justed as More Plausible than Generated Scenes

A New Layout Dataset

----a real-world 11000 designs from professional designers

An Example:



Application of the Model in the Industry

