

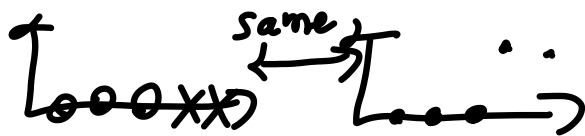


ML: machine learn with task, performance, experience

1. Supervised learning:  $(x, y) \in E, x \rightarrow y$

① regression:  $y \rightarrow \text{continuous}$   
logistic regression: separate good/bad

② classification:  $y \rightarrow \text{discrete}$



CV: digitize  $\rightarrow$  learn neural  
 $\rightarrow$  execute

ML decisions many: strategic important

never work first-time: debug important  
strategy

2. Deep learning:

3. unsupervised learning: label ~~outputs~~  
→ find interesting clustering  
eg. cocktail party problem

4. reinforcement learning: do stuff → reward  
←  
eg. dog training

# L2

Linear regression

Train set  $T$



feed algorithm



ed.

size

$h$

hypothesis

function

house price

How to represent  $h$ ?

$$h(x) = \sum_{j=0}^n \theta_j x_j, \quad x_0 = 1$$

$$\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}, \quad x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \end{bmatrix}$$



$\theta$  : parameter

$m$  : # training examples

$x$  : input / features

$y$  : output / target variable

$(x, y)$  : train examples

$(x^{(i)}, y^{(i)})$  =  $i$ th example

$n$  : # features

Goal : ? classify performance?

Linear regression:  $J(\theta) = \frac{\min}{2} \left( \sum_{i=1}^m (h(x^{(i)}) - y^{(i)})^2 \right)$

↓

Gradient descent : 1. start with  $\theta$   
2. change  $\theta$  to  $\theta'$

? no local minima!

$$\theta_j := \theta_j - \boxed{2} \frac{\partial}{\partial \theta_j} J(\theta)$$

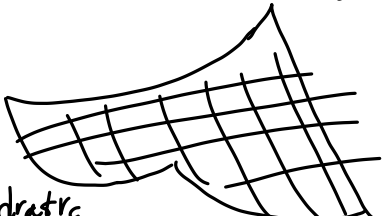
learning rate

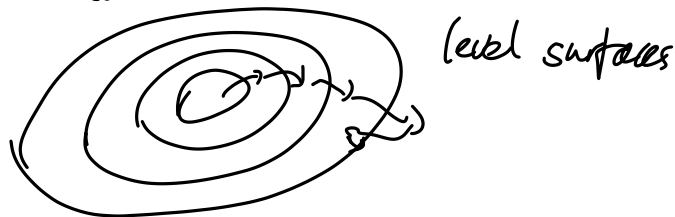


$$\frac{\partial}{\partial \theta_j} (J(\theta)) = (h(\theta) - y) x_j$$

Repeat until converge

$$\theta_j := \theta_j - \alpha \frac{\partial J(\theta)}{\partial \theta_j}$$

$J(\theta)$  :  a bowl  
 ↓  
 because quadratic  
 so no local minima



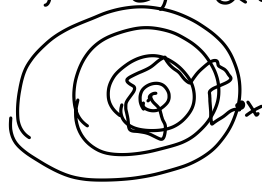
$\alpha$  value: ↓ → slow  
 ↑ → overshoot → slow

? make sure one → one? how?  
 no need I think

Batch gradient descent : disadvantage :  $m \uparrow \rightarrow$  slow

Alternative: Stochastic gradient descent

Repeat  
 For  $i$  to  $m$   
 $\theta_j := \theta_j - \alpha (h(x^{(i)}) - y^{(i)}) x_j^{(i)}$



Never converge!

Switch stochastic to batch?  
 no. instead ↓  $\alpha$

$$\nabla_{\theta} J(\theta) = \begin{bmatrix} \frac{\partial J}{\partial \theta_0} \\ \vdots \\ \frac{\partial J}{\partial \theta_2} \end{bmatrix}$$

$$\nabla_{\theta} f(\theta) = \begin{bmatrix} \frac{\partial f}{\partial \theta_{1,1}} & \frac{\partial f}{\partial \theta_{1,2}} \\ \vdots & \vdots \end{bmatrix} \text{ if } f: \mathbb{R}^{m \times n} \rightarrow \mathbb{R}$$

$$\nabla_{\theta} J(\theta) = \vec{0} \rightarrow \text{global min}$$

$$f(A) = \text{tr} AB, \quad \nabla_{\theta} f(A) = B^T$$

$$\nabla_{\theta} \text{tr} A^T C = CA + C^T A$$

$$\vec{X} = \begin{bmatrix} \text{---} x^{(1)T} \text{---} \\ \text{---} x^{(2)T} \text{---} \\ \vdots \end{bmatrix}$$

similar to  $y$

$$J(\theta) = \frac{1}{2} (X\theta - y)^T (X\theta - y)$$

$$\nabla_{\theta} J(\theta) = X^T X \theta - X^T y \stackrel{\text{set}}{=} \vec{0}$$

$$\theta = \underbrace{(X^T X)^{-1}}_{\text{must exist}} X^T y$$

# L3

locally weighted regression  $\Rightarrow$  fit non-linear

parametric / non-parametric learning algorithm



fixedset of  $\theta_i$



Size of Cset of  $\theta_i$   
increases

Locally weighted - regression

$$J(\omega) = \sum_{i=1}^m w^i (y^{(i)} - \theta_x^{T(i)})^2$$

$$w^i = \frac{e^{-(x^i - x)^2 / 2\sigma^2}}{\sum_{j=1}^m e^{-(x^j - x)^2 / 2\sigma^2}}$$

bandwidth  
decide width

if  $|x^{(i)} - x| \rightarrow 0$ ,  $w^i \rightarrow 1$

if  $|x^{(i)} - x| \rightarrow \infty$ ,  $w^{(i)} \rightarrow 0$





## Probabilistic Interpretation

Why LS? <sup>Assume</sup>  $y^{(i)} = \theta^T x^{(i)} + \epsilon^{(i)}$

$$\epsilon^{(i)} \sim N(0, \sigma^2)$$

↑  
error

Assume  $\epsilon \sim \text{IID} \rightarrow$  independent & identically distributed

$$\Rightarrow p(y^{(i)} | x^{(i)}; \theta) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y^{(i)} - \theta^T x^{(i)})^2}{2\sigma^2}}$$

↑  
parametrization,  $\theta$  not random variable

↑  
likelihood

$$\begin{aligned} \ell(\theta) &= p(\vec{y} | \vec{X}; \theta) \\ &= \prod_{i=1}^m p(y^{(i)} | x^{(i)}; \theta) \end{aligned}$$

likelihood  $\rightarrow$  fixed  $\vec{X}$ , vary  $\theta \rightarrow$  likelihood of  $\theta$

prob  $\rightarrow$  fixed  $\theta$ , vary  $\vec{X} \rightarrow$  prob of data

log likelihood

$$\begin{aligned} \ell(\theta) &= \log \mathcal{L}(\theta) \\ &= m \log \frac{1}{\sqrt{2\pi}\sigma} + \sum_{i=1}^m -\frac{(y^{(i)} - \theta^T x^{(i)})^2}{2\sigma^2} \end{aligned}$$

maximize  $\ell(\theta) \rightarrow$  minimize  $\Rightarrow$  maximal likelihood to

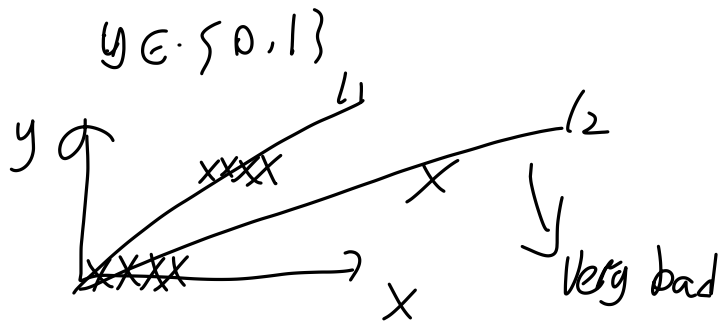




Non IID  $\rightarrow$  not bother to have better computation

Maximal likelihood estimation

classification problem

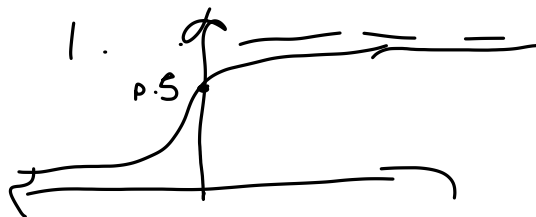


so linear regression bad

Logistic regression

$$h_{\theta}(x) = g(\theta^T x) = \frac{1}{1 + e^{-\theta^T x}} \quad (\text{generalized linear models})$$

"sigmoid" or "logistic function"



$$P(y|x; \theta) = h^y (1-h)^{1-y}$$

for  $y \in \{0, 1\}$

$$l = \log \mathcal{L}(\theta) = \sum_{i=1}^m y^{(i)} \log h_{\theta}(x^{(i)}) + (1 - y^{(i)}) \log (1 - h_{\theta}(x^{(i)}))$$

To maximize likelihood: use ~~Batch~~

all for GIM

$$\theta_0 = \theta_0 + \alpha \frac{\partial}{\partial \theta_j} l(\theta) \cdot \alpha$$

$$\theta_j := \theta_j + \alpha \sum_{i=1}^m (y^{(i)} - h_{\theta}(x^{(i)})) x_j^{(i)}$$

There is no local minima/maxima  
for the log function, so for logistic function

Sadly no normal equation

Newton's method

$$l'(\theta) = 0 \Rightarrow \text{maxima}$$

$$\theta^{(i)} := \theta^{(co)} - \Delta$$

$$\Delta = \frac{f(\theta^{(co)})}{f'(\theta^{(co)})}$$

$$\theta^{(t+1)} := \theta^{(t)} - \frac{l(\theta^{(t)})}{l'(\theta^{(t)})}$$

"Quadratic error"



# sigmoid ~~digits~~ digits doubles on  
one iteration

When  $\theta$  is a vector

$$\theta^{(t+1)} := \theta^{(t)} + H^{-1} \nabla_{\theta} l$$

$H$ : Hessian matrix

$$H_{ij} := \frac{\partial^2 l}{\partial \theta_i \partial \theta_j}$$

Newton pro: fast con: matrix large  
then bad.

✓ actually

$$\rightarrow \nabla_{\theta}^2$$

$H^{-1}$  equivalent to  
 $\frac{1}{A}$



# L4

Perceptron algorithm

$$g(z) = \begin{cases} 1 & z \geq 0 \\ 0 & z < 0 \end{cases}$$

$$h_{\theta}(x) = g(\theta^T x) \quad \theta_j := \theta_j + \alpha (y^{(i)} - h_{\theta}(x^{(i)})) x_j^{(i)}$$

0 : right  $y^{(i)} = 1$   
 $\pm 1$  : if wrong  $y^{(i)} = 0$

