

test_jupyter

January 31, 2023

0.0.1 NOTEBOOK EXAMPLE IN SPYDER - INVERSE MAPPING OF SHOWER PROBLEM

```
[1]: import numpy as np
import time
import nbconvert

import sys
sys.path.append('../')
from src.pyprop import nlp_based_approach

[2]: def shower2x2(u):

    d = np.zeros(2)
    y = np.zeros(2)
    y[0]=u[0]+u[1]
    if y[0]!=0:
        y[1]=(u[0]*(60+d[0])+u[1]*(120+d[1]))/(u[0]+u[1])
    else:
        y[1]=(60+120)/2

    return y

[3]: u0 = np.array([0, 10])
lb = np.array([0, 0])
ub = np.array([100,100])

DOS_bound = np.array([[17.5, 21.0],
                      [80.0, 100.0]])

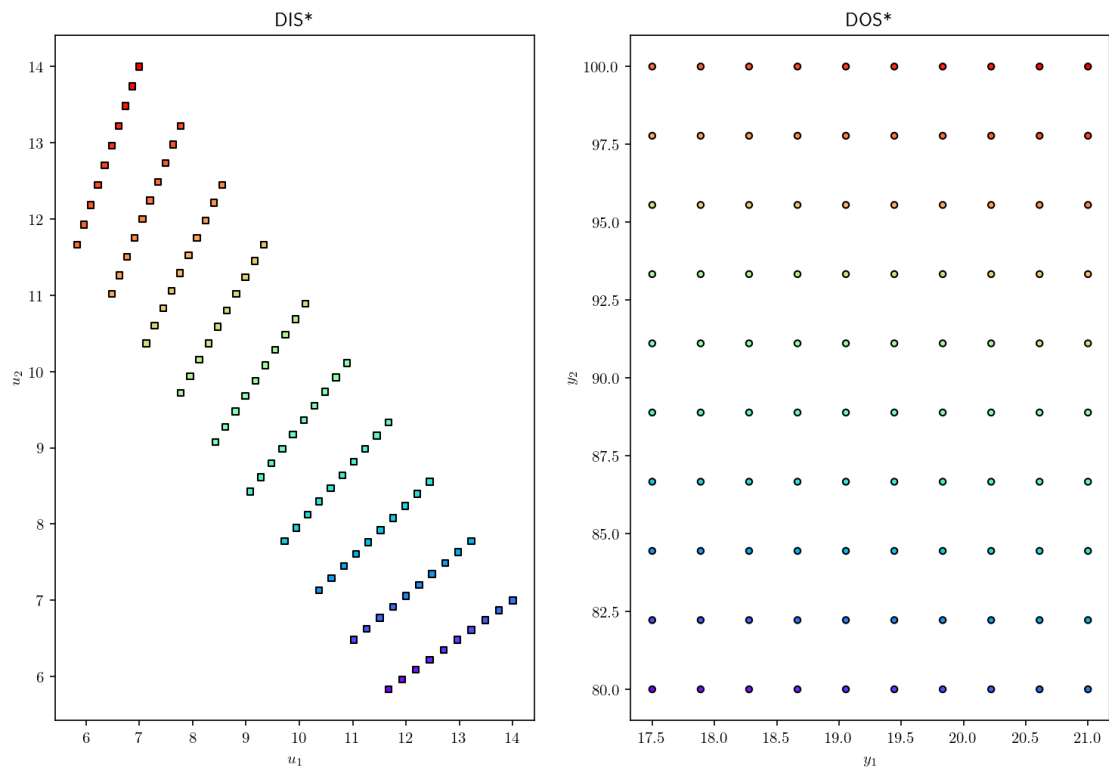
DOSresolution = [10, 10]

t = time.time()
fDIS, fDOS, message = nlp_based_approach(DOS_bound,
                                         DOSresolution,
                                         shower2x2,
                                         u0,
```

```
lb,
ub,
method='ipopt',
plot=True,
ad=False)
```

```
elapsed = time.time() - t
```

100% | 100/100 [00:08<00:00, 12.26it/s]



[]: