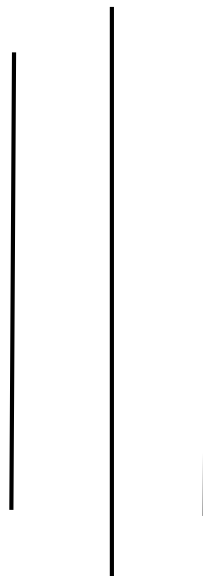


SAGARMATHA ENGINEERING COLLEGE

(TU Affiliated)

Sanepa, Lalitpur



LAB NO: 4

A LAB REPORT ON

MID POINT ELLIPSE ALGORITHM

Submitted By:

Name:.....

Faculty/Year:.....

Roll No:.....

Date:.....

Submitted To:

Department of electronics and Computer Engineering

Signature:.....

Date:.....



COMPUTER GRAPHICS LAB-04

TITLE

MID POINT ELLIPSE ALGORITHM

OBJECTIVES

- ✓ To be familiar with fundamental knowledge of Mid-point ellipse drawing algorithm and its implementation.

HARDWARE/SOFTWARE REQUIRED

- ✓ C Compiler

RELATED THEROY

Mid-point Ellipse Algorithm

An ellipse is defined as the set of points such that the sum of the distances from two fixed point/ positions (foci) is same for all points.

Elongated circle

Equation of ellipse:

$$d_1 + d_2 = \text{constant}$$

$F1 \rightarrow (x_1, y_1), F2 \rightarrow (x_2, y_2)$

$$\sqrt{(x-x_1)^2 + (y-y_1)^2} + \sqrt{(x-x_2)^2 + (y-y_2)^2} = \text{constant}$$

General Equation

$$Ax^2 + By^2 + Cxy + Dx + Ey + F = 0$$

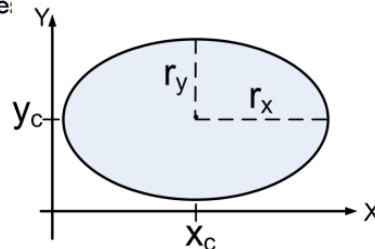
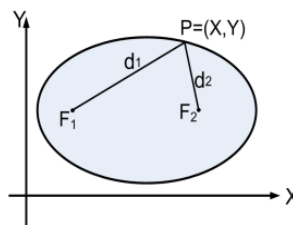
In terms of ellipse center coordinate:

$$\left(\frac{x-x_c}{r_x}\right)^2 + \left(\frac{y-y_c}{r_y}\right)^2 = 1$$

In polar co-ordinate

$$x = x_c + r_x \cos \theta$$

$$y = y_c + r_y \sin \theta$$



$$f_{\text{ellipse}}(x, y) = r_y^2 x^2 + r_x^2 y^2 - r_x^2 r_y^2$$

$$f_{\text{ellipse}}(x, y) \begin{cases} < 0, & \text{if } (x, y) \text{ is inside the ellipse boundary} \\ = 0, & \text{if } (x, y) \text{ is on the ellipse boundary} \\ > 0, & \text{if } (x, y) \text{ is outside the ellipse boundary} \end{cases}$$



COMPUTER GRAPHICS LAB-04

ALGORITHM

1. Input r_x, r_y , and the ellipse center (x_c, y_c) and obtain the first point on an ellipse centered on the origin as

$$(x_0, y_0) = (0, r_y)$$

2. Calculate the initial value of the decision parameter in region 1 as

$$p1_0 = r_y^2 - r_x^2 r_y + \frac{1}{4} r_x^2$$

3. At each x_k position in region 1, starting at $k = 0$, perform the following test:

If $p1_k < 0$ /* next point (x_{k+1}, y_k) */

$$x_{k+1} = x_k + 1, y_{k+1} = y_k$$

$$p1_{k+1} = p1_k + 2r_y^2 x_{k+1} + r_y^2$$

Else

/* next point $(x_k + 1, y_k - 1)$ */

$$x_{k+1} = x_k + 1, y_{k+1} = y_k - 1$$

$$p1_{k+1} = p1_k + 2r_y^2 x_{k+1} - 2r_x^2 y_{k+1} + r_y^2$$

With

$$2r_y^2 x_{k+1} = 2r_y^2 x_k + 2r_y^2, \quad 2r_x^2 y_{k+1} = 2r_x^2 y_k - 2r_x^2$$

and continue until $2r_y^2 x \geq 2r_x^2 y$

4. Calculate the initial value of decision parameter in region 2 using the last point (x_0, y_0) calculated in region 1 as

$$p2_0 = r_y^2 \left(x_0 + \frac{1}{2} \right)^2 + r_x^2 (y_0 - 1)^2 - r_x^2 r_y^2$$

5. At each y_k position in region 2, starting at $k = 0$, perform the following test:

If $p2_k \leq 0$ /* next point $(x_k + 1, y_k - 1)$ */

$$x_{k+1} = x_k + 1$$

$$y_{k+1} = y_k - 1$$

$$p2_{k+1} = p2_k + 2r_y^2 x_{k+1} - 2r_x^2 y_{k+1} + r_x^2$$

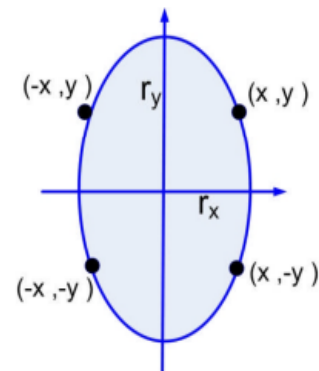
Else

/* next point $(x_k, y_k - 1)$ */

$$x_{k+1} = x_k$$

$$y_{k+1} = y_k - 1$$

$$p2_{k+1} = p2_k - 2r_x^2 y_{k+1} + r_x^2$$



4. Using the same incremental calculations for x and y as in region 1. continue until $y=0$.
6. Determine the symmetry points in the other three quadrants.
7. Move each calculated pixel position (x, y) onto the elliptical path centered on (x_c, y_c) and plot the co-ordinate values:

$$x = x + x_c, y = y + y_c$$



COMPUTER GRAPHICS LAB-04

IMPLEMENTATION OF MID-POINT ELLIPSE ALGORITHM

```
#include<graphics.h>
#include<stdio.h>
#include<math.h>

//Function to plot the ellipse
void pixel (int xc, int yc, int x,int y)
{
    putpixel(320+(xc+x),240-(yc+y),14);
    putpixel(320+(xc+x),240-(yc-y),14);
    putpixel(320+(xc-x),240-(yc-y),14);
    putpixel(320+(xc-x),240-(yc+y),14);
}

int main()
{
    int xc, yc, x, y, p, rx, ry;

    int gdriver=DETECT, gmode; //Detects the graphics drivers automatically
    initgraph(&gdriver, &gmode,(char*)""); //Initialize to graphics mode

    printf("Enter the co-ordinates of the center of the ellipse : ");
    scanf("%d %d",&xc,&yc);
    printf("Enter the value of rx and ry of the ellipse : ");
    scanf("%d %d",&rx,&ry);

    //Take start position as(0,ry)
    x=0;
    y=ry;

    p=(ry*ry)-(rx*rx*ry)+((rx*rx)/4); //Finding decision parameter p in region 1

    pixel (xc, yc, x, y);

    while((2*x*ry*ry)<(2*y*rx*rx)) //At each x position in region 1
    {
        if(p<0) //If decision parameter is less than 0
        {
            x++; //Increment x
            p=p+(2*ry*ry*x)+(ry*ry); //Calculate the new decision parameter
        }
        else //If decision parameter is greater than 0
        {
            x++; //Increment x
            y--; //Decrement y
            p=p+(2*ry*ry*x)+(ry*ry)-(2*rx*rx*y); //Calculate the new decision parameter
        }
        pixel (xc, yc, x, y);
    }
}
```



COMPUTER GRAPHICS LAB-04

```
p=ry*ry*pow((float)x+0.5,2) + rx*rx*pow(y-1,2)-rx*rx*ry*ry; //Finding decision parameter
pixel (xc, yc, x, y);

while(y>=0) //At each y position in region 2
{
    if(p>0) //If decision parameter is greater than 0
    {
        y--; //Decrement y
        p=p-(2*y*rx*rx)+(rx*rx); //Calculate the new decision parameter
    }
    else //If decision parameter is less than 0
    {
        y--; //Decrement y
        x++; //Increment x
        p=p+(2*ry*ry*x)-(2*y*rx*rx)+(rx*rx); //Calculate the new decision parameter
    }
    pixel (xc, yc, x, y);
}

getch(); //Pauses the Output Console until a key is pressed
closegraph(); //Closes the graphics mode
return 0;
}
```

OUTPUT

RESULT:

Program is compiled, Mid-point Ellipse algorithm implementation was done.