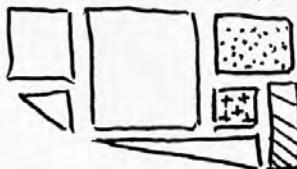


Movement 03

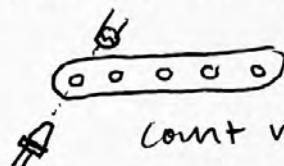
Warm-up: rectangles, + stripes
triangles

Tile an area +
use stripes to differentiate.



Attendance
practice

Last time: distance encoders.



Count notches \leftrightarrow distance.



★ short de.

$$p(s) = ? \quad \text{Analytical} = \frac{s \times 5}{\text{---}}$$

$$p(\emptyset) = ? \quad \text{Analytical} = \frac{1}{1024}$$

\uparrow
of vals.

Experimental?

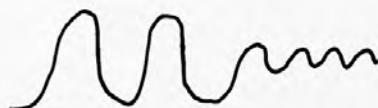
Agent $\xrightarrow{\text{act}}$ world Action $\stackrel{\text{Dom}}{=}$ \equiv ②
 $\xleftarrow{\text{sense.}}$ w/ motors (DOF)

Agent must sense itself... part
of the world!

output can be $lo \leftrightarrow hi$
if there's analogRead, then analogWrite
LEP brightness same concept.

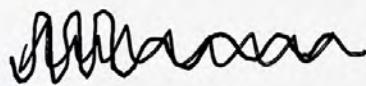
AM : amplitude modulation.

High V = More output



Hi: lo.

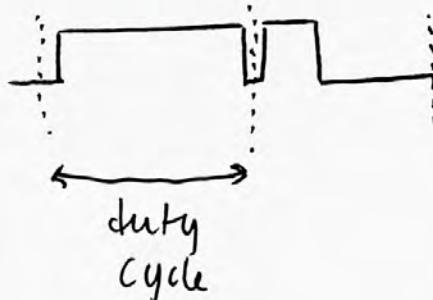
FM : frequency modulation



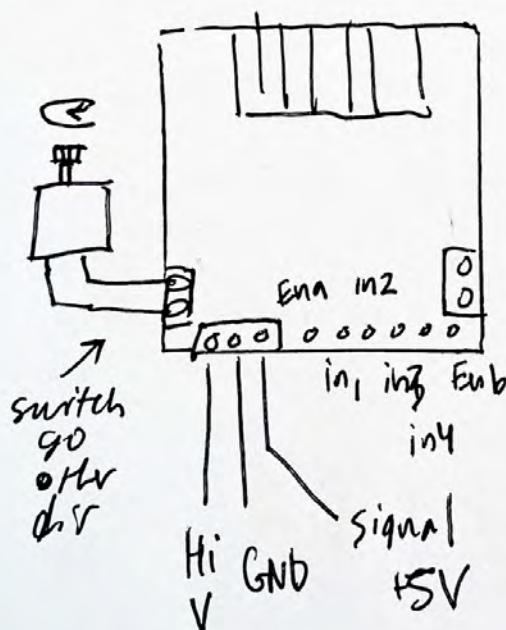
AM / FM :
yes, like
radio!

3

pulse-width modulation



\uparrow
more on
= more energy
in system



$i_{n_1} : H_i$ } dir
 $i_{n_2} : I_o$ }
 $E_{n_3} : \text{on/off}$

analog write
(ana, 0-255)

Higher =
more on

(4)

Notice: no sensor & no feedback.

★ How do you measure how much the wheel has rotated?

★ Bad encoder demo.

You can now drive your robots. Lab 3 is your first group lab w/ robot.

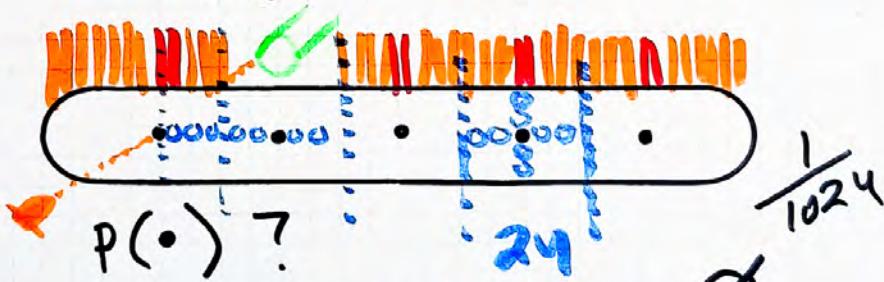
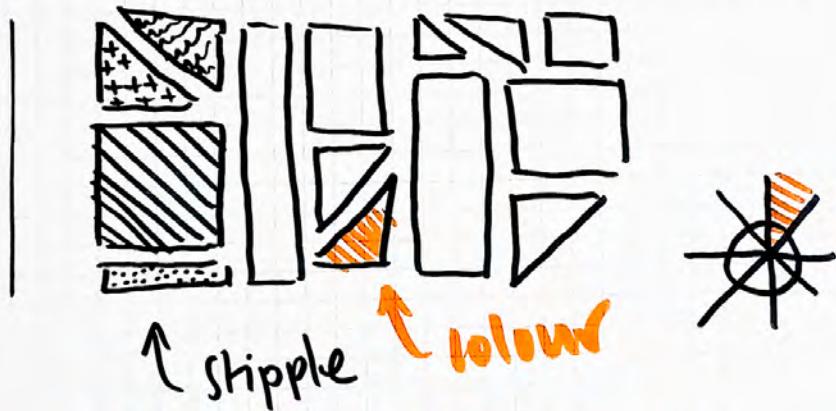
→ Group work review.
→ Survey

project intro

★ Brainstorm

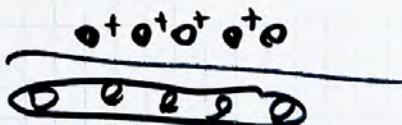
COGS 300 Movement 03 Sun 20/26

WARM UP: tile your page with rectangles + triangles.



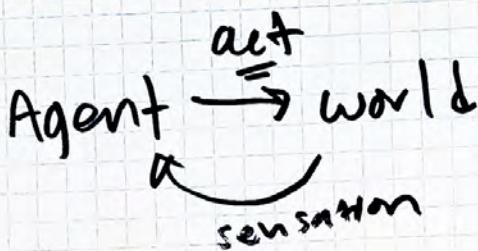
time

$$5 \times \frac{1}{24}$$

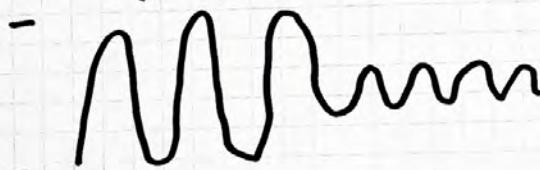


$p(\bullet) ?$

(2)

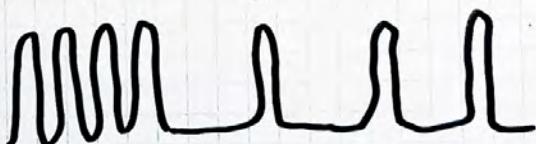


AM: amplitude modulation



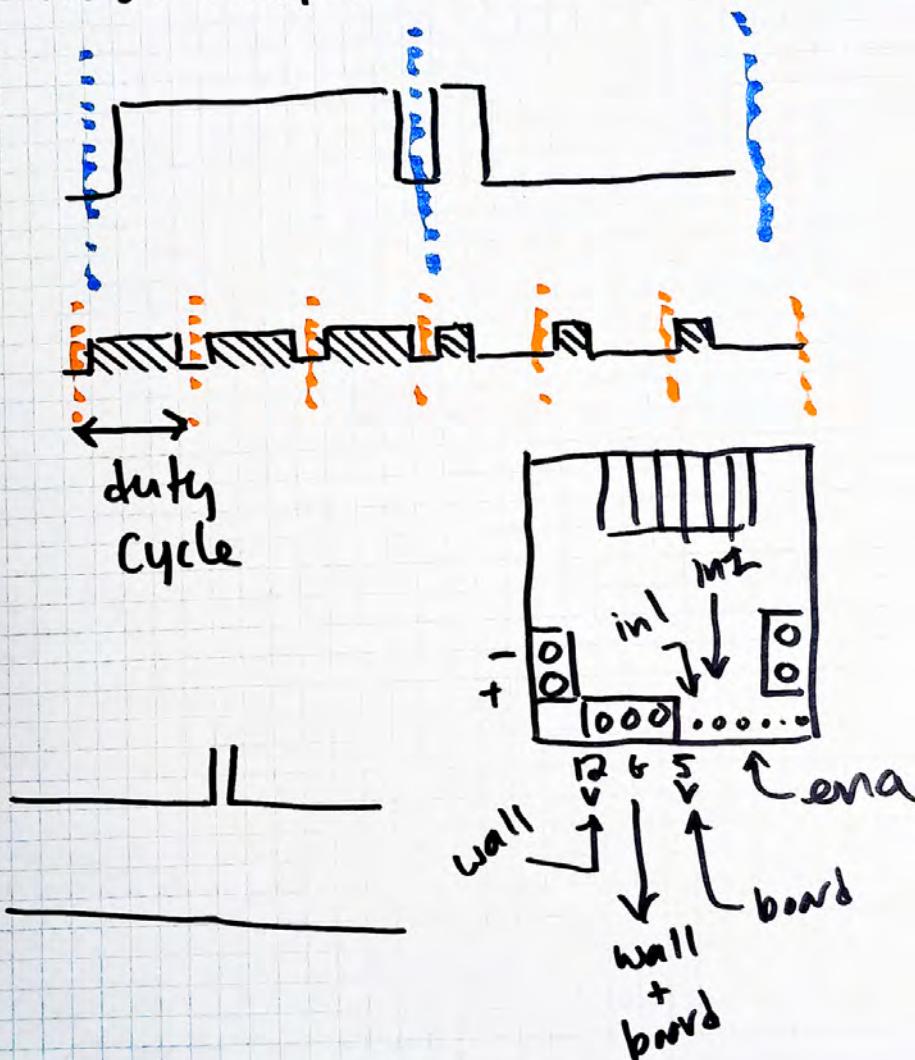
12V 5V

FM: Frequency modulation



Pulse-width modulation

(3)



(4)

Group work post-mortem
project pitch + sketch

Brainstorm
project
ideas.