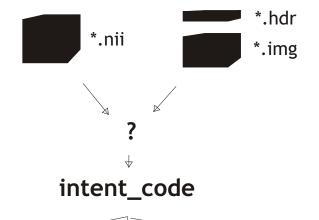
# THE NIFTI1 DATA FORMAT



NIFTI1 can store data with different meanings. Imaging data, statistical values and other data (any vector, matrix, label set or mesh). can be saved in a nifti1 \*.nii or \*.hdr/\*.img file. Once a data intent is chosen, the use of the nifti1 format is unambigious since the use of particular fields for a certain intent is predetermined.

#### DATASET

NIFTI\_INTENT\_VECTOR: 0

#### STATISTICS

NIFTI INTENT CORREL: 2 NIFTI INTENT TTEST:3 NIFTI INTENT FTEST: 4 NIFTI INTENT ZSCORE: 5 NIFTI INTENT CHISQ: 6 NIFTI INTENT BETA: 7 NIFTI INTENT BINOM: 8 NIFTI INTENT GAMMA: 9 NIFTI INTENT POISSON: 10 NIFTI INTENT NORMAL: 11 NIFTI INTENT FTEST NONC: 12 NIFTI INTENT CHISQ NONC: 13 NIFTI INTENT LOGISTIC: 14 NIFTI INTENT LAPLACE: 15 NIFTI INTENT UNIFORM: 16 NIFTI INTENT TIEST NONC: 17 NIFTI INTENT WEIBULL: 18 NIFTI INTENT CHI: 19 NIFTI INTENT INVGAUSS: 20 NIFTI INTENT EXTVAL: 21 NIFTI INTENT PVAL: 22

#### **OTHER**

NIFTI\_INTENT\_ESTIMATE: 1001
NIFTI\_INTENT\_LABEL: 1002
NIFTI\_INTENT\_NEURONAME: 1003
NIFTI\_INTENT\_GENMATRIX: 1004
NIFTI\_INTENT\_SYMMATRIX: 1005
NIFTI\_INTENT\_DISPVECT: 1006
NIFTI\_INTENT\_VECTOR: 1007
NIFTI\_INTENT\_POINTSET: 1008
NIFTI\_INTENT\_TRIANGLE: 1009
NIFTI\_INTENT\_QUATERNION: 1010

To determine the position of the voxel in the dataset, method 1 is used (translation). Methods 2 and 3 serve also for reconstructing rigid body and affine transformations so that the positions of the voxels withinthe dataset in a stereotactic space can be determined.

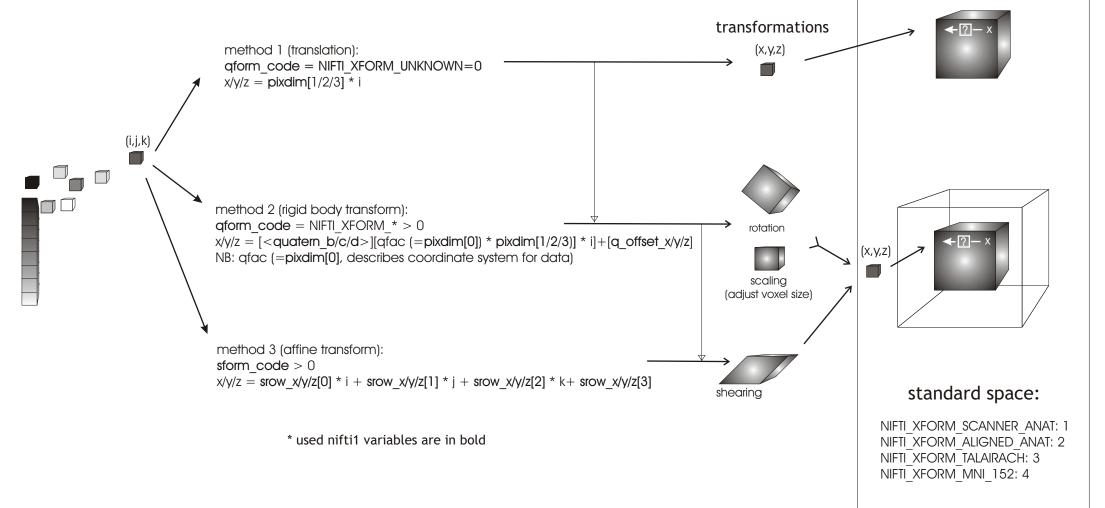
NIFTI\_INTENT: DATASETS

COORDINATE SYSTEM

# arbitrary space:

NIFTI XFORM UNKNOWN: 0

# Locating position of voxel in dataset: how to use the nifti1 variables for datasets



Nifti1 can also be used to store values drawn from a given distribution. For this purpose, many intent\_types are dedicated to describe statistical tests Univariate and multivariate tests can be stored, including the used parameters. In nifti1, it is possible to save more than one values per voxel (even a matrix per voxel).

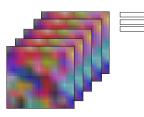
# NIFTI INTENT: STATISTICS

#### How to use the nifti1 variables for statistical values



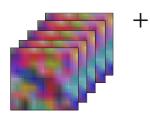
dim[3] = 1: single slice

dim[5] = 1: statistical parameters stored in intent\_p1/2/3 (parameters applied to whole dataset)



dim[3] > 1: several slices

dim[5] = 1: statistical parameters stored in Intent\_p1/2/3 (parameters applied to whole dataset)



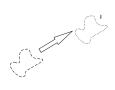
dim[5] > 1: voxel-wise statistical parameters stored in data planes after stat value plane, for example the degrees of freedom

## NIFTI INTENT: OTHER

#### How to use the nifti1 variables for other intents

~	NIFTI_INTENT_ESTIMATE: 1001 parameter for estimate in <b>intent_name</b>	
1 5 2 Property 1 4 Property	NIFTI_INTENT_LABEL: 1002 parameter at each voxel is index to label defined in aux_file	
152	NIFTI_INTENT_NEURONAMES: 1003 parameter at each voxel is index to label in NeuroNames label set	
[ M x N ]	NIFTI_INTENT_GENMATRIX: 100 parameter at each voxel is matrix dim[0] = 5 dim[5] > 1: M * N intent_p1: M (float) intent_p2: N (float)	04 row order: [m][n]0→ (n-1) 0 ↓ (m-1)
	NIFTI INTENT SYMMATRIX: 1005	

 $[N \times N]$ 



# NIFTI INTENT DISPVECT: 1006

parameter at each voxel is displacement vector dim[5] = dimensionality of displacement (e.g. 2 = in-plane, 3 = spatial)



# NIFTI INTENT VECTOR: 1007

parameter at each voxel is vector



## NIFTI INTENT POINTSET: 1008

value at each voxel is spatial coordinate (vertices/nodes of surface mesh) dim[0] = 5dim[1] = nr of points



#### NIFTI INTENT TRIANGLE: 1009

value at each voxel is triple of indices (forming triangle) from a pointset

dim[0] = 5

dim[1] = nr of triangles

dim[2/3/4] = 1

dim[2/3/4] = 1

dim[5] = dimentionality of space

intent\_name can describe the objects where points come from ("pial", "gray/white", "EEG" etc)



## NIFTI INTENT QUATERNION: 1010

vector value at each voxel isquaternion

dim[0] = 5dim[5] = 4

 $[4 \times 4]$ 

row order: dim[0] = 5[0][0]

parameter at each voxel is symmetrical matrix

dim[5] > 1: N \* (N+1)/2[1][0] [1][1] intent\_p1: N (float))

[2][0] [2][1] [2][2]