

# COMSM0045: Convolutional Neural Networks (Part 1)

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# Introduction

- ▶ Not every Deep Neural Network (DNN) is a Convolutional Neural Network (CNN)

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- ▶ By the end of this course you will be familiar with 3 types of DNNs
  - ▶ Fully-Connected DNN
  - ▶ Convolutional DNN
  - ▶ Recurrent DNN

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- ▶ By the end of this course you will be familiar with 3 types of DNNs
  - ▶ Fully-Connected DNN
  - ▶ Convolutional DNN
  - ▶ Recurrent DNN
- ▶ CNNs could be credited for the recent success of Neural Networks<sup>1</sup>
- ▶ The term was first used by LeCun in his technical report: “Generalization and network design strategies” (1989).

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  - ▶ Video: 3-D (sequence of 2-D grid of pixels)

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- ▶ Typical examples:
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- ▶ As the input is grid-like, operations might apply to individual or groups of grid cells.
- ▶ Accordingly, CNN is a neural network that uses *convolution* in place of general matrix multiplication *in at least one of its layers*.

# Kernels vs Tensors

- ▶ The *convolution* operation is typically denoted with \*

$$x * \omega \tag{1}$$

where  $x$  is the **input** and  $\omega$  is the **kernel**, also known as the **feature map**

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- ▶ In CNNs, kernels are trained/learnt from data, for one or multiple tasks
- ▶ Moreover, multiple *dependent* kernels are trained/learnt in one go
- ▶ In CNN,  $x$  is a multidimensional array of data, and  $\omega$  is a multidimensional array of kernels - referred to as **a tensor**

# Convolutional Neural Networks

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- ▶ Three primary properties distinguish fully-connected networks from convolutional neural networks:
  1. Sparse Interactions
  2. Parameter Sharing
  3. Equi-variant Representations

# CNN Properties: 1- Sparse Interactions<sup>2</sup>

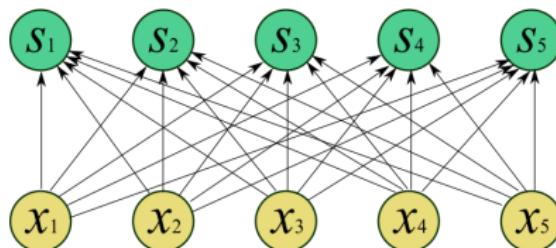
- ▶ A major difference between fully connected neural networks and CNNs are the contributions of input units to output units.

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<sup>2</sup>Also referred to as multi-scale interactions

# CNN Properties: 1- Sparse Interactions<sup>2</sup>

- ▶ A major difference between fully connected neural networks and CNNs are the contributions of input units to output units.
- ▶ Consider this two-layer fully-connected network, with 5 input units,

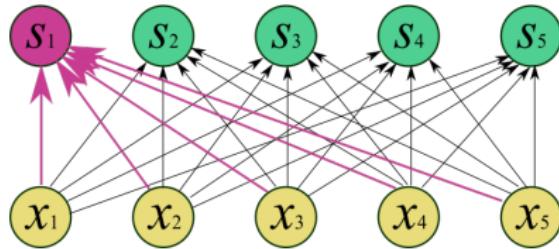


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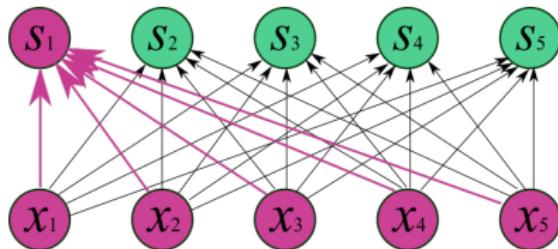
- ▶ A major difference between fully connected neural networks and CNNs are the contributions of input units to output units.
- ▶ For one output unit  $s_1$ ,



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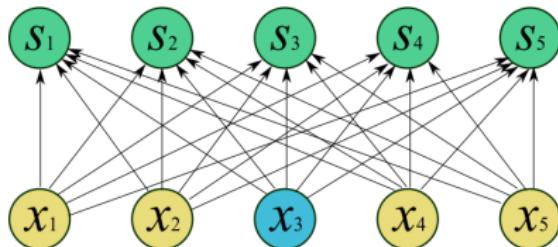
- ▶ A major difference between fully connected neural networks and CNNs are the contributions of input units to output units.
- ▶ its value is decided from all 5 input units

$$s_1 = f(x_1, x_2, x_3, x_4, x_5; \omega_1, \omega_2, \omega_3, \omega_4, \omega_5).$$



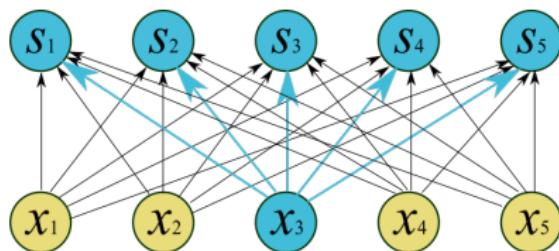
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- ▶ similarly, each input unit, e.g.  $x_3$ , contributes to all output units

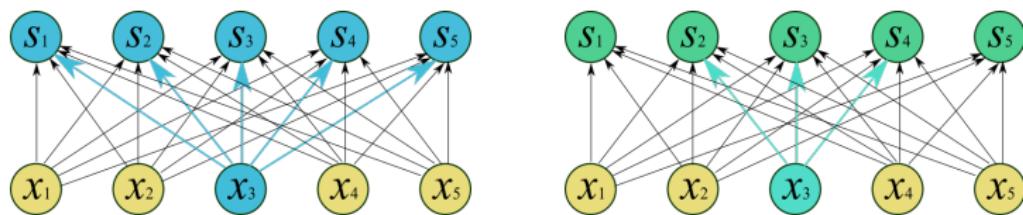


# CNN Properties: 1- Sparse Interactions

- ▶ In **CNNs**, due to the grid structure, it is sufficient to limit the number of connections from each input unit to  $k$ ,

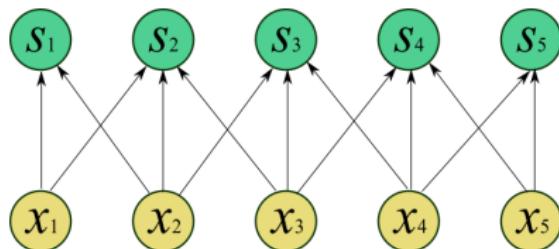
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- ▶ See the connections from  $x_3$



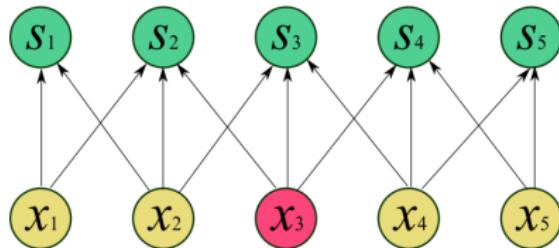
# CNN Properties: 1- Sparse Interactions

- ▶ In **CNNs**, due to the grid structure, it is sufficient to limit the number of connections from each input unit to  $k$ ,
- ▶ resulting in sparse weights - and sparse interactions between input and output



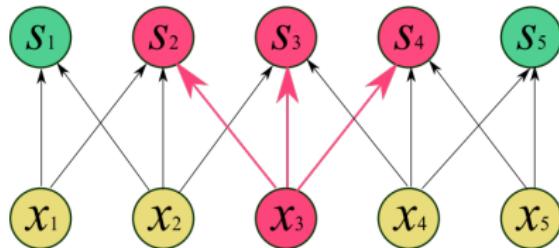
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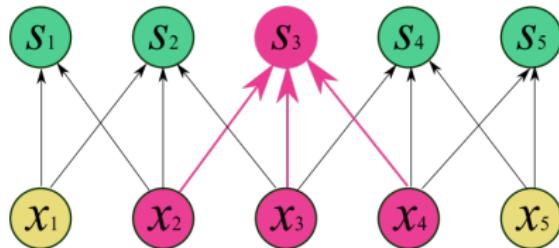
# CNN Properties: 1- Sparse Interactions

- ▶ In **CNNs**, one input unit  $x_3$ , affects a limited number of output units



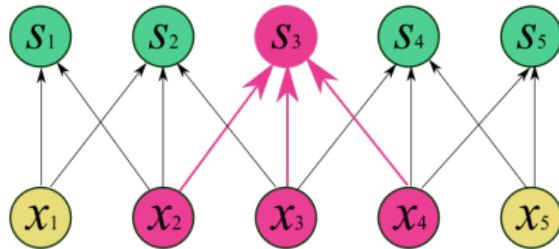
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- ▶ Similarly, the input units affecting a certain output unit (e.g.  $s_3$ ),



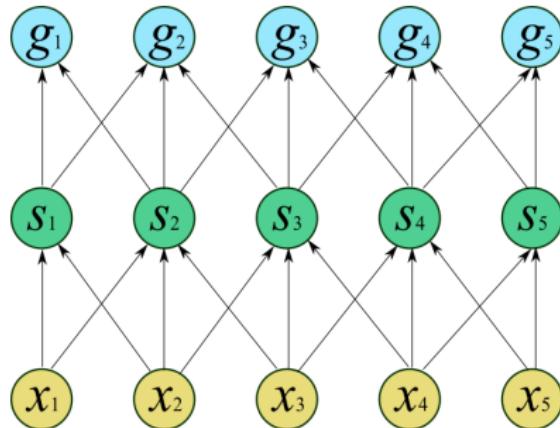
# CNN Properties: 1- Sparse Interactions

- ▶ The input units affecting a certain output unit (e.g.  $s_3$ ), are known as the unit's **receptive field**.



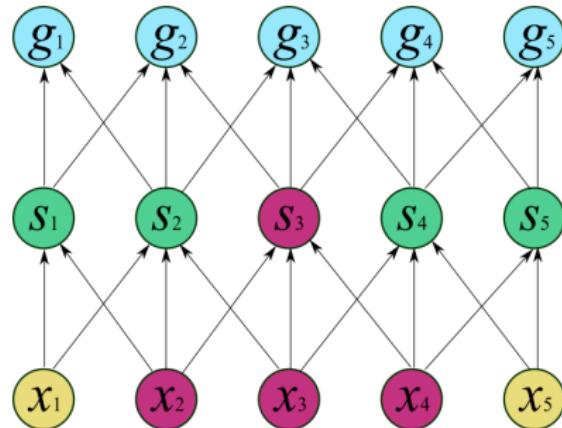
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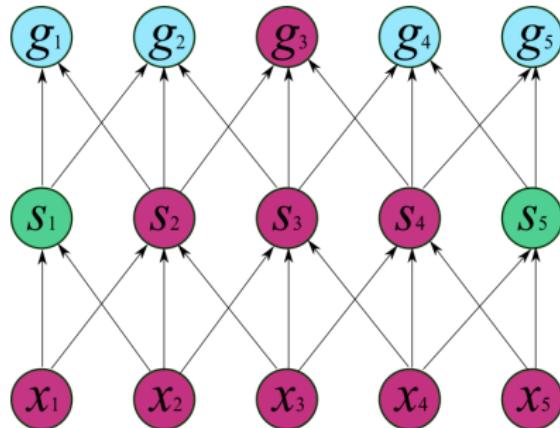
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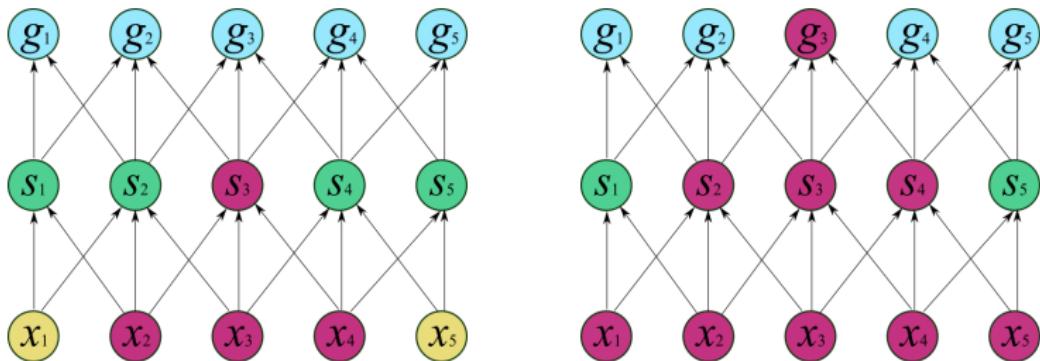
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# CNN Properties: 1- Sparse Interactions

- The receptive field of the units in the deeper layers of a CNN is larger than the receptive field of the units in the shallow layers



# CNN Properties: 2- Parameter Sharing

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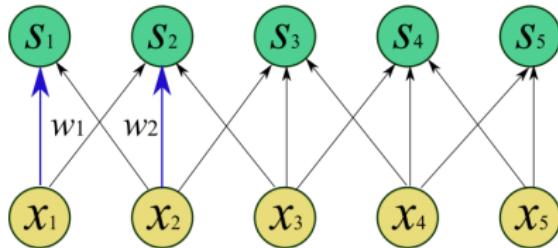
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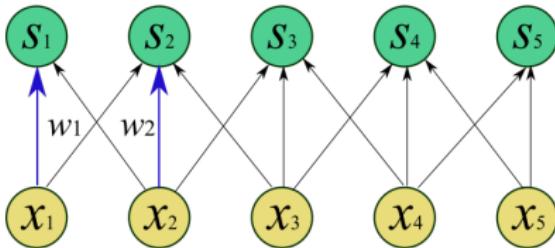
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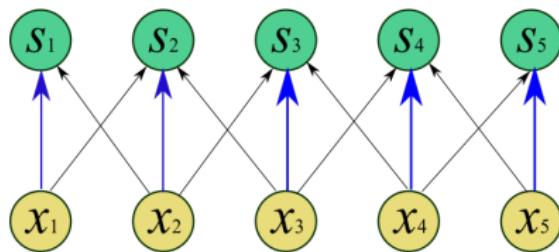
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- ▶ You have dropped the number of parameters you need to train by 1 (!)



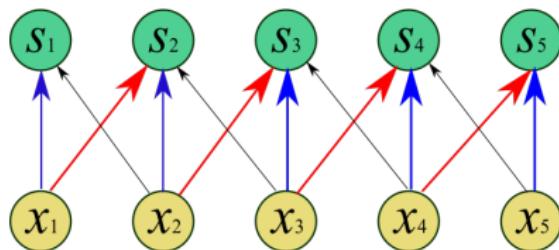
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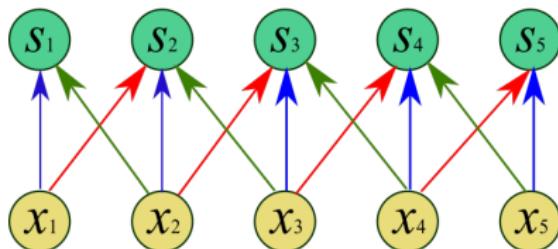
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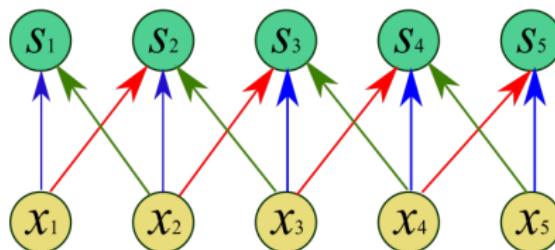
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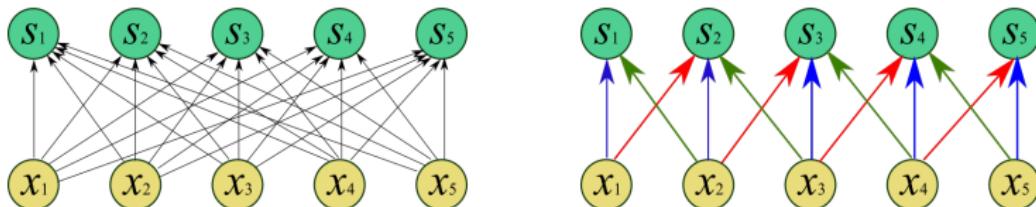
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- ▶ Though parameter sharing on this network - with sparse interactions - the number of parameters to train is... 3 !!!



# CNN Properties: 2- Parameter Sharing

- ▶ Compare the number of parameters in the fully-connected network to this CNN with sparse interactions and parameter sharing!
- ▶ Only 12% !!! :-)



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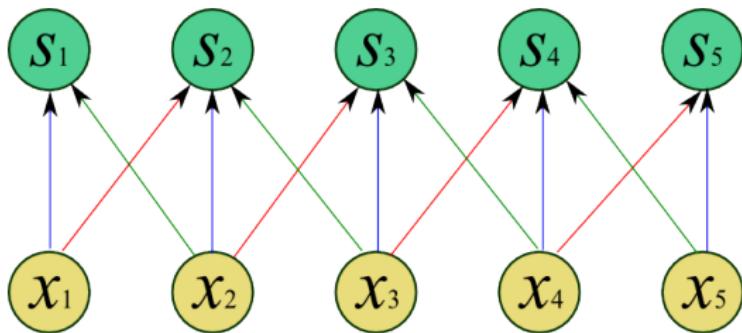
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- ▶ Does not affect the runtime of the forward pass
- ▶ Does significantly reduce the memory requirements for the model
- ▶ You have significantly less parameters to train, and thus you need less data
- ▶ But only works on the assumption that the data is grid-like and thus sharing the weights is a sensible idea!

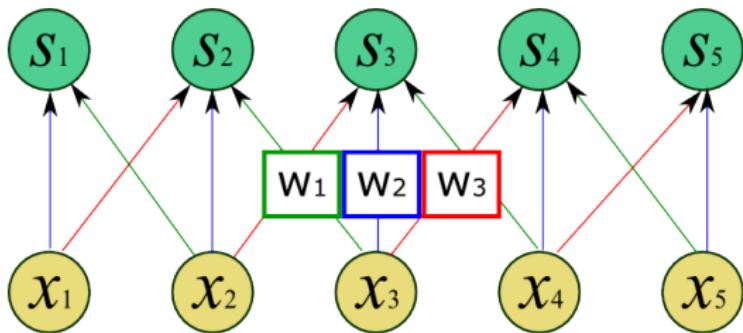
# CNN Properties: 2- Parameter Sharing

- ▶ Is this new??



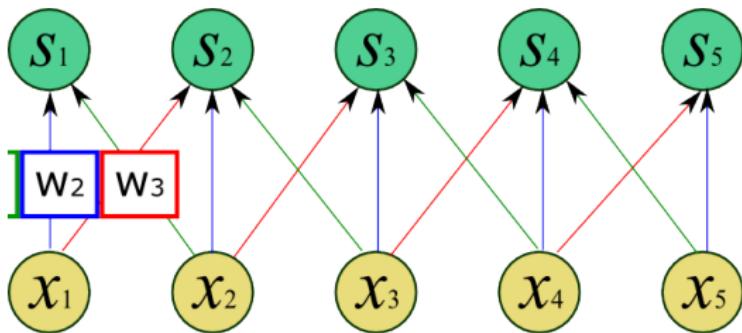
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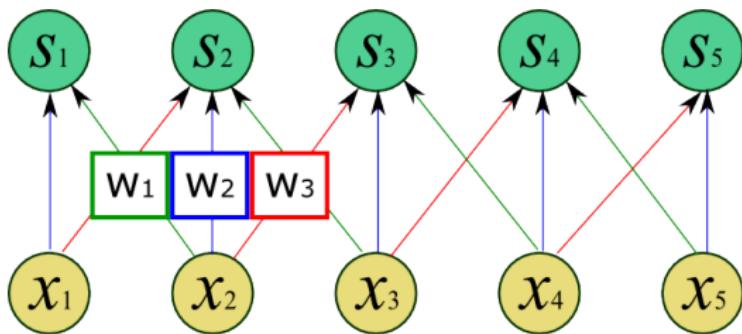
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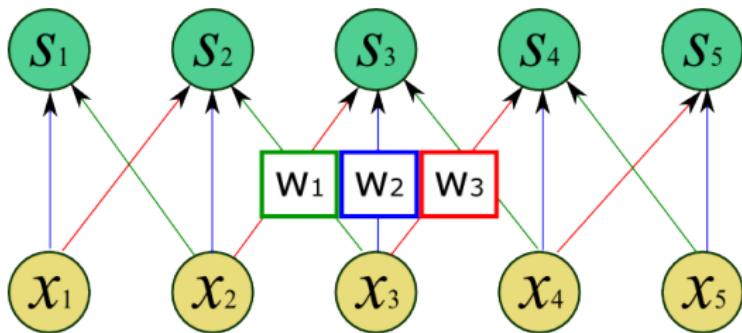
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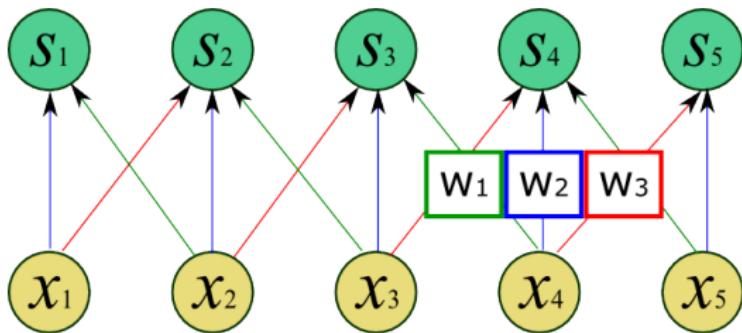
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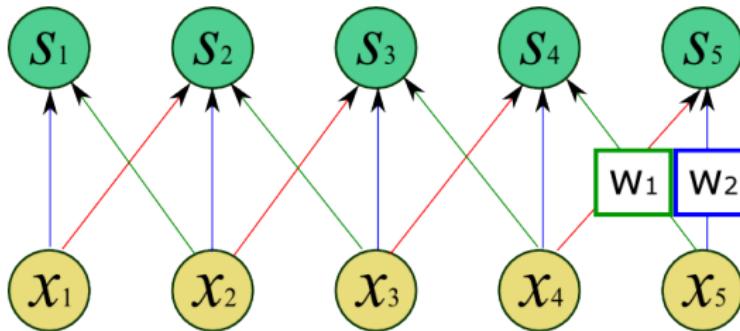
# CNN Properties: 2- Parameter Sharing

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# CNN Properties: 2- Parameter Sharing

- Is this new?? **CONVOLUTION!!!** - or cross-correlation :-)



# Convolution vs Correlation

- ▶ Using the convolution operator, for  $x$  and  $\omega$ , the result  $S$  would be

$$S(i,j) = (x * \omega)(i,j) = \sum_m \sum_n x(m,n)\omega(i-m,j-n) \quad (2)$$

- ▶ A main property of convolution is that it is commutative

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- ▶ *The only reason to flip the kernel is to obtain the commutative property - helpful in writing proofs*

# Convolution vs Correlation

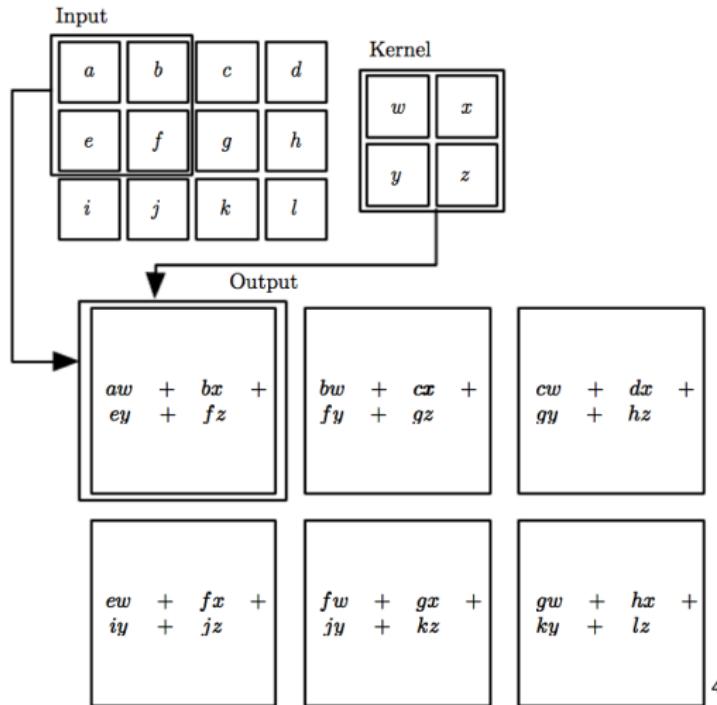
- ▶ However, *most* DNN libraries implement the convolution as a **cross-correlation** operation, without flipping the kernel<sup>3</sup>

$$S(i,j) = (\mathbf{x} * \omega)(i,j) = \sum_m \sum_n \mathbf{x}(i+m, j+n) \omega(m, n) \quad (4)$$

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<sup>3</sup>We do not have a good reason to call them CNNs really!

# Convolution vs Correlation

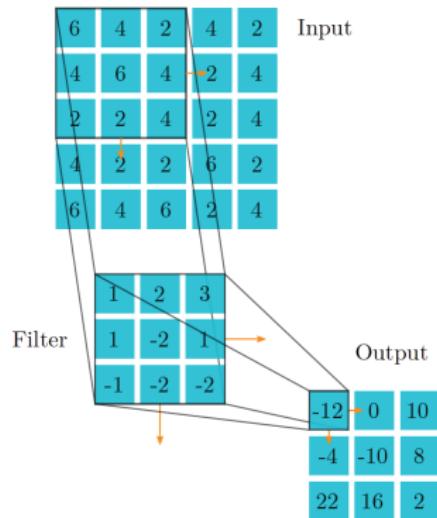


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<sup>4</sup>Reference: Goodfellow et al (2016) p325

# CNN Properties: 2- Parameter Sharing

- And in 2-D



Source: BSc Thesis, Will Price, Univ of Bristol, May 2017

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# Your first CNN Layer

- ▶ Multiple convolutional layers → You can learn multiple features, e.g.

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Source: Rob Fergus, NN, MLSS2015 Summer School Presentation

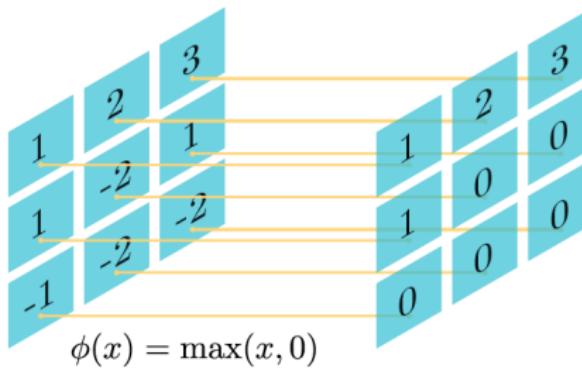
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# Your first CNN Layer

- ▶ The convolutions are directly followed by activation functions, in the same fashion as fully-connected CNNs
- ▶ RELU activation function is shown in the example below

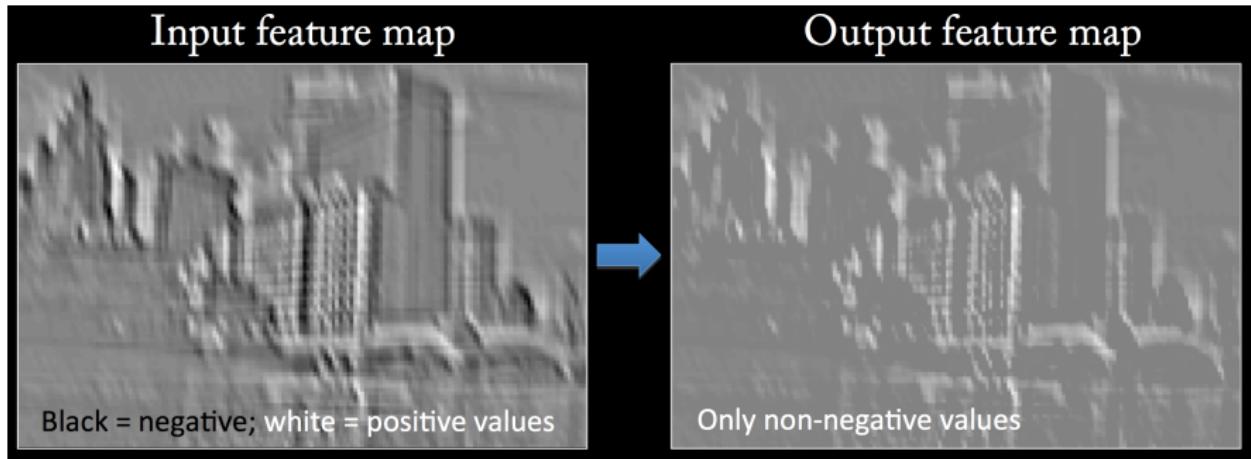


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<sup>5</sup>Source: BSc Thesis, Will Price, Univ of Bristol, May 2017

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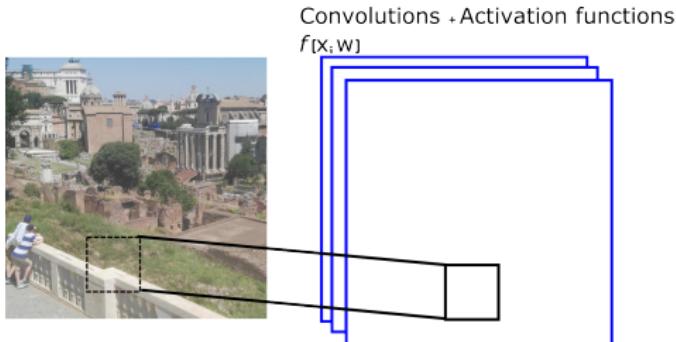
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<sup>6</sup>Source: Rob Fergus, NN, MLSS2015 Summer School Presentation

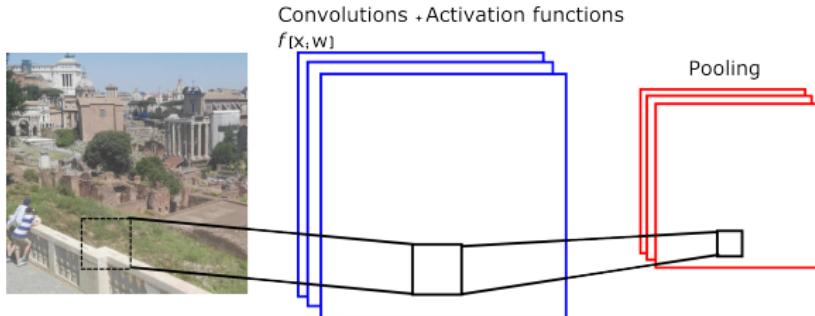
# Your first CNN Layer

- ▶ Multiple convolutions can be piled
- ▶ Convolving a single kernel can extract one kind of feature
- ▶ We want to extract many kinds of features at many locations



# Your first CNN Layer

- ▶ **Pooling functions** are added to modify the output layer further, typically its size.
- ▶ A pooling function **replaces** the output of the net at a certain location, with a **summary** of the outputs in nearby outputs.



# Your first CNN Layer

- ▶ **Max pooling**<sup>7</sup>, for example, takes the maximum output within a rectangular neighbourhood.
- ▶ Pooling is almost always associated with downsampling,

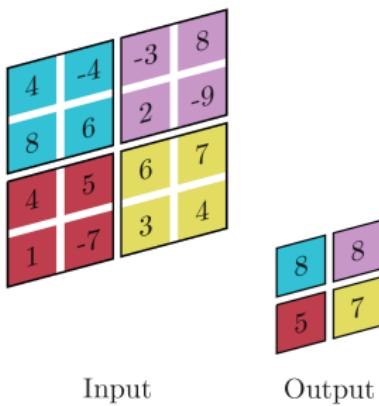
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  - ▶ weighted average pooling
  - ▶  $L^2$  norm

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- ▶ Other pooling functions are:
  - ▶ average pooling
  - ▶ weighted average pooling
  - ▶  $L^2$  norm
- ▶ Pooling allows invariance to small translations in input

# Further Reading

## ► Deep Learning

Ian Goodfellow, Yoshua Bengio, and Aaron Courville  
MIT Press, ISBN: 9780262035613.

## ► Chapter 9 – Convolutional Networks