



Visible Light Communication

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- **Visible Light Communication**

- ▶ Communication with visible light (380nm – 780nm)

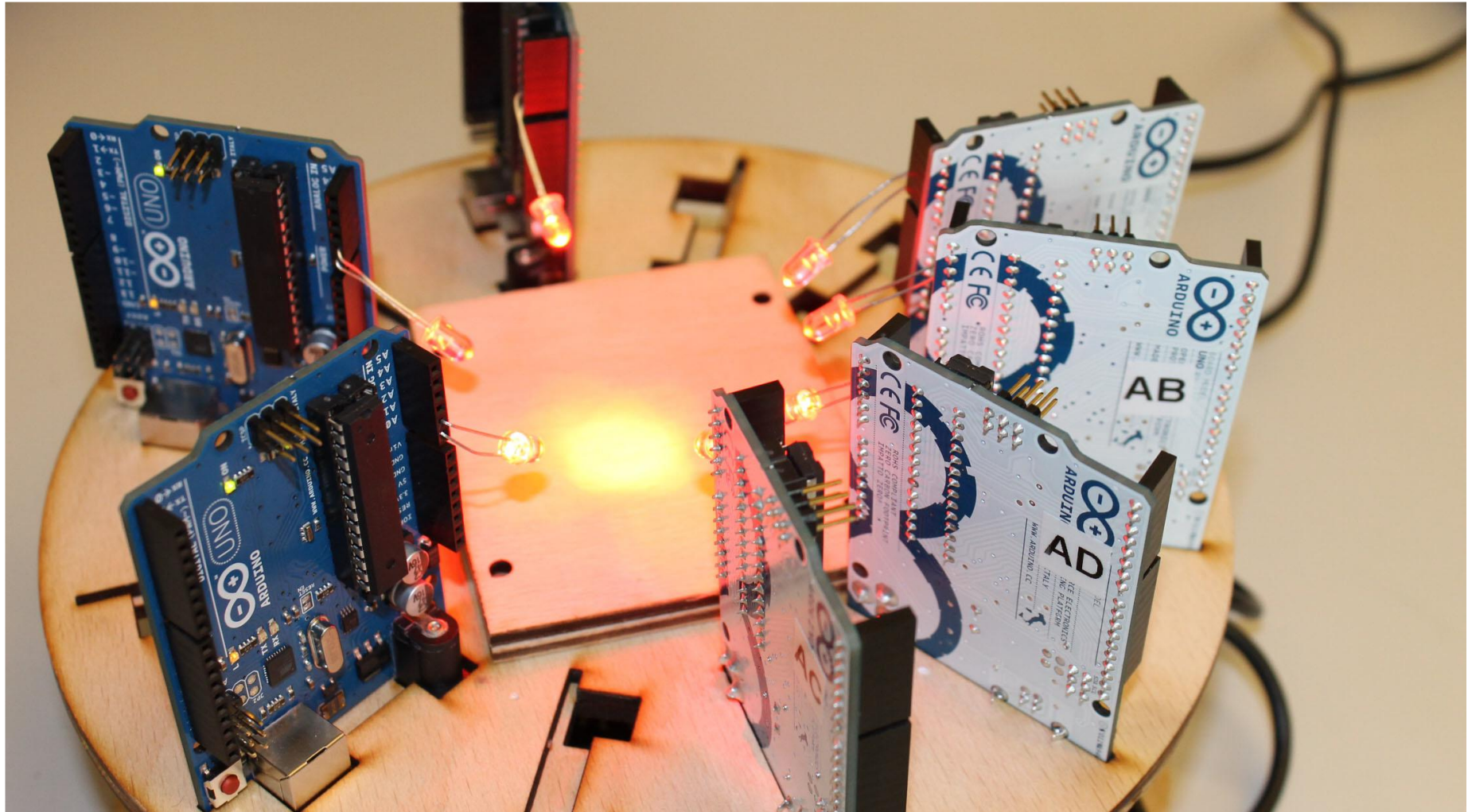
- **Advantages**

- ▶ No restrictions to radio bands
- ▶ Cheap hardware
- ▶ No known health issues

- **Disadvantages**

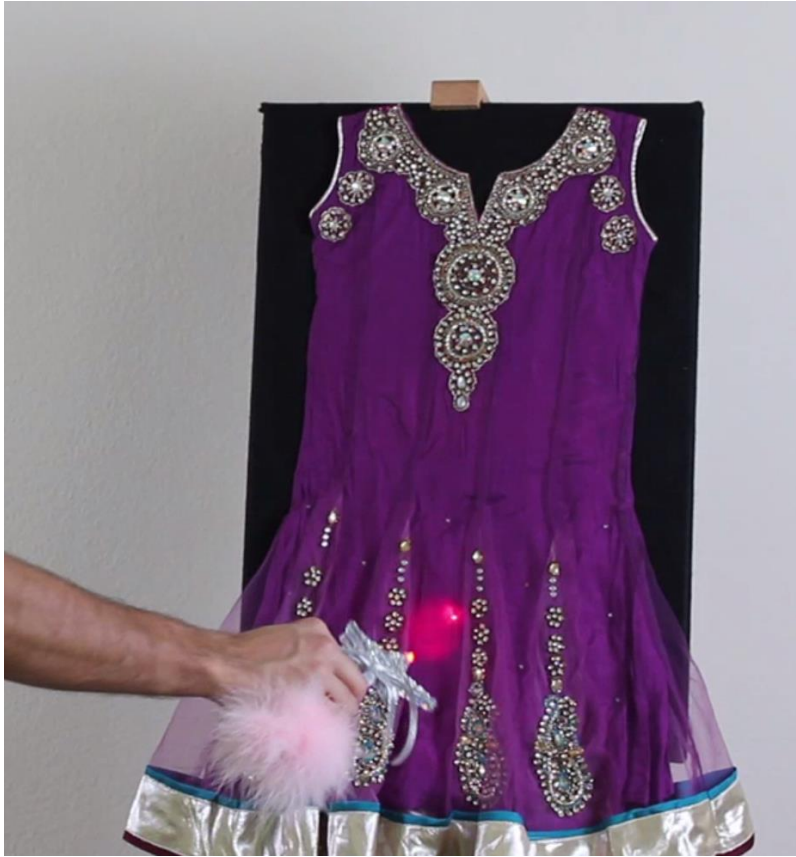
- ▶ Heavy environmental noise
- ▶ High absorption rates

Motivation – Related Work



[3]

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[3]

- **Basic Communication**

- ▶ End-to-end
- ▶ From Arduino to Arduino
- ▶ From Smartphone to Arduino

- **Practical Use Case**

- ▶ Possibly anything
- ▶ Decided for moving toy train
 - Controlled by Smartphone via Bluetooth and VLC

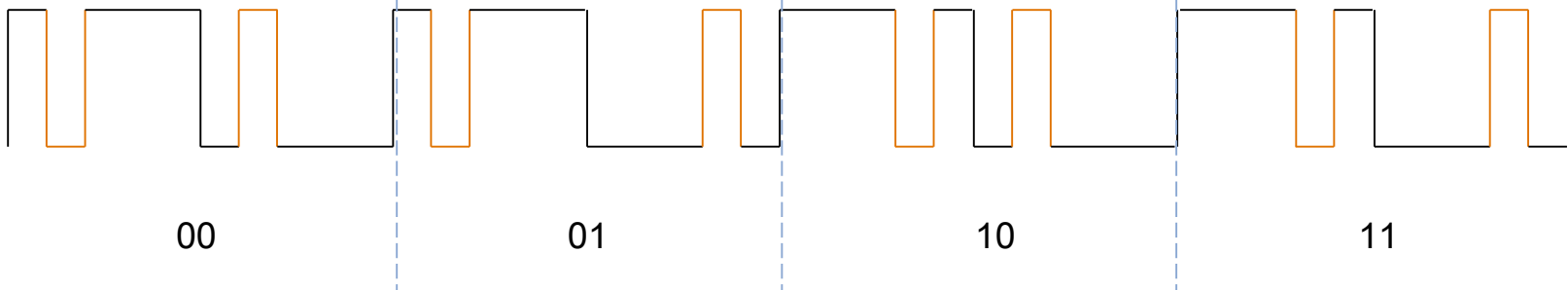
- **Orientated on OSI model**
- **Bit layer**
 - ▶ Hardware control to transceive signals
 - ▶ Responsible for sending single bits
 - ▶ Synchronization
- **MAC layer**
 - ▶ Error detection
 - ▶ Frame separation
 - ▶ Delivery control

- **Signal**

- ▶ Idle Pattern



- ▶ Data Pattern



- **Equal up- and downtime**

- ▶ Constant level of perceived brightness

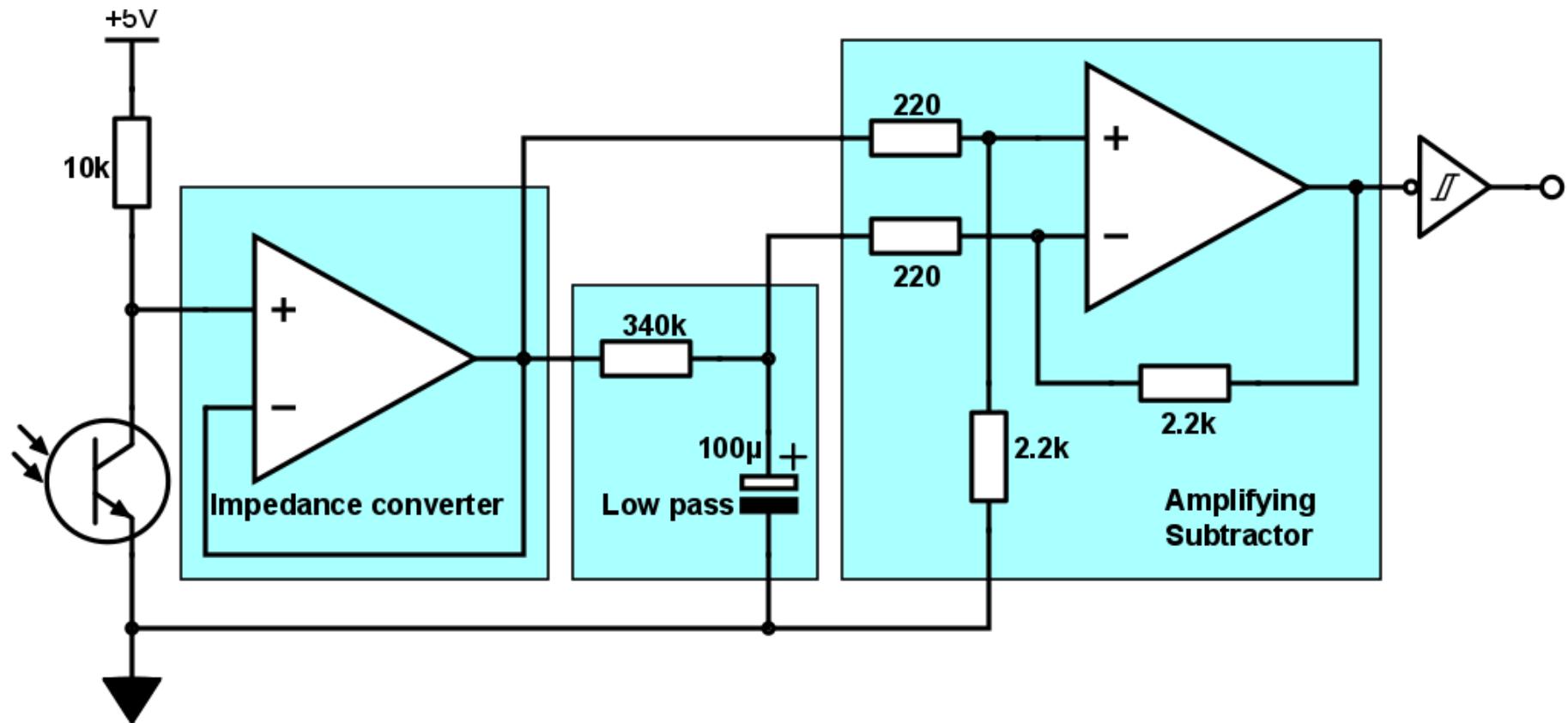
- **Slower than e.g. Manchester coding**

- **Biggest problem in our project!**
- **First variant**
 - ▶ Continuous AD conversions of the sensor input
 - ▶ Moving average to remove background noise and to detect edges
 - ▶ Analyzation of each edge on detection
 - ▶ Problems:
 - conversions caused delays
 - High number of interrupts blocked program flow
- **Final variant**
 - ▶ With hardware edge detection
 - ▶ Edge triggered interrupt
 - ▶ All edges of a period are stored and analysed afterwards

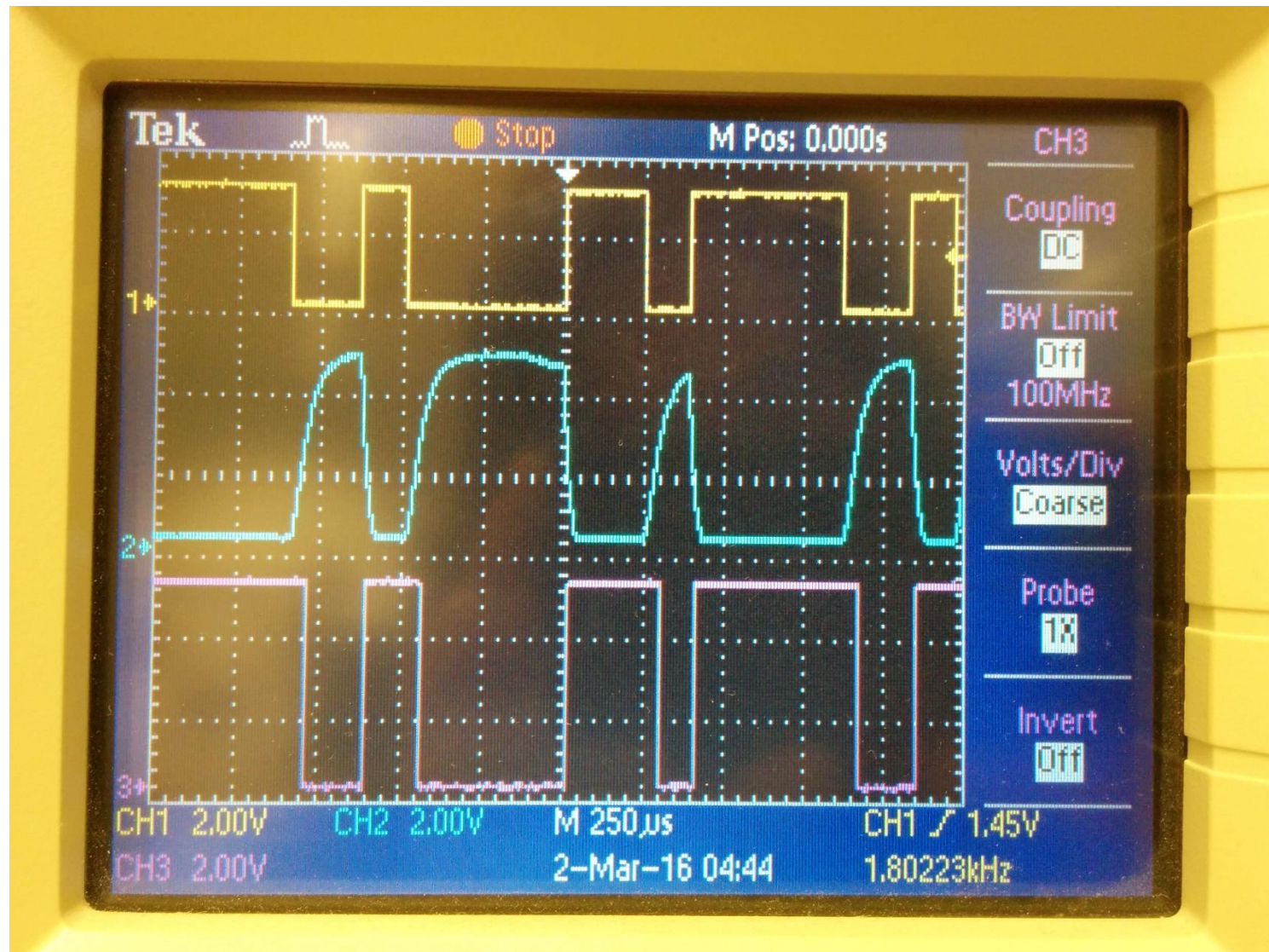
16	8	8	0-248	8
0xBEEF	Flags + Length	Header CRC	Payload	Payload CRC

- Synchronization sequence to delimit frames
- Up to 31 byte per frame
- Header CRC to validate length
- Continuous repetition until the message is acknowledged
- Message buffer

Hardware Edge Detector



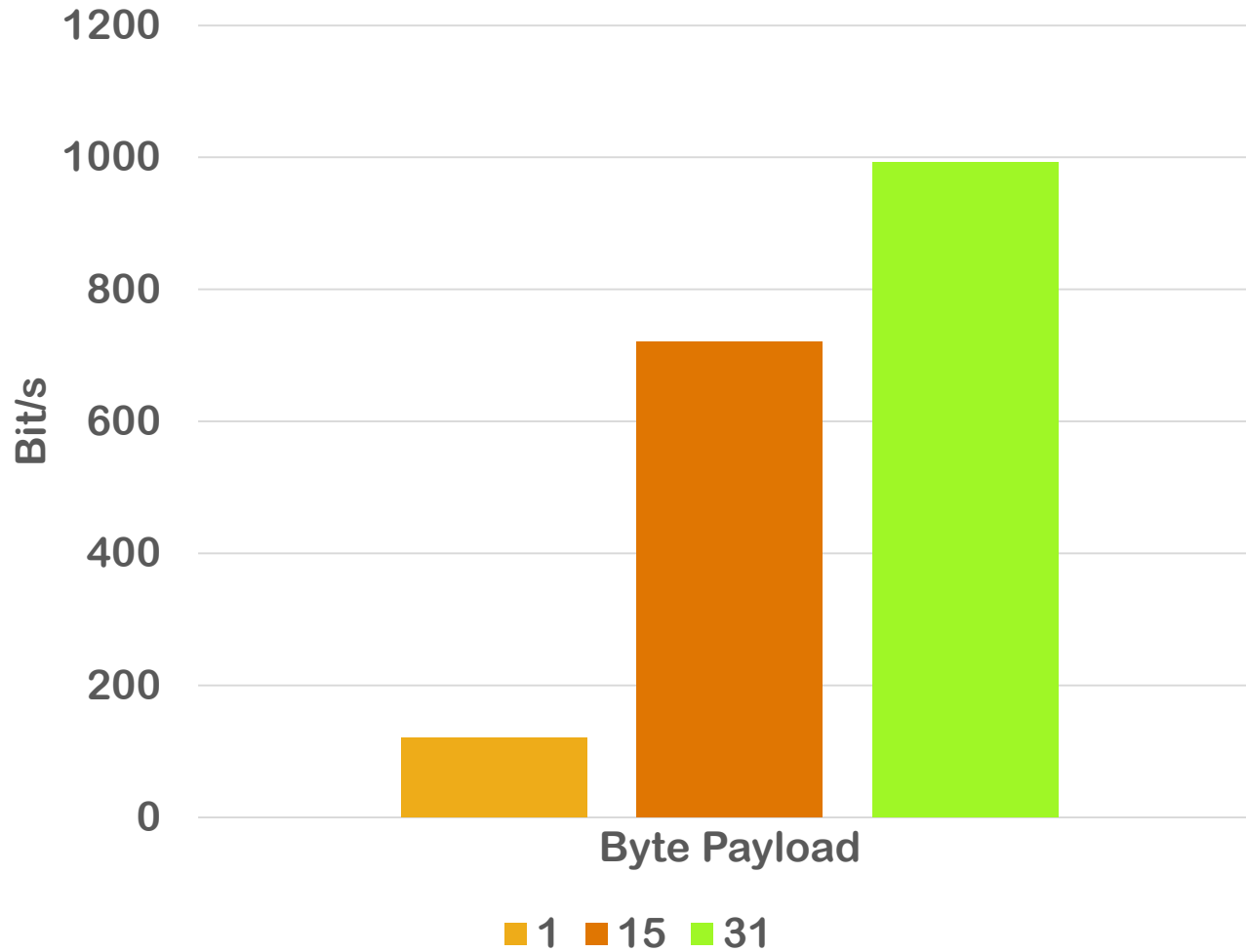
Hardware Edge Detector



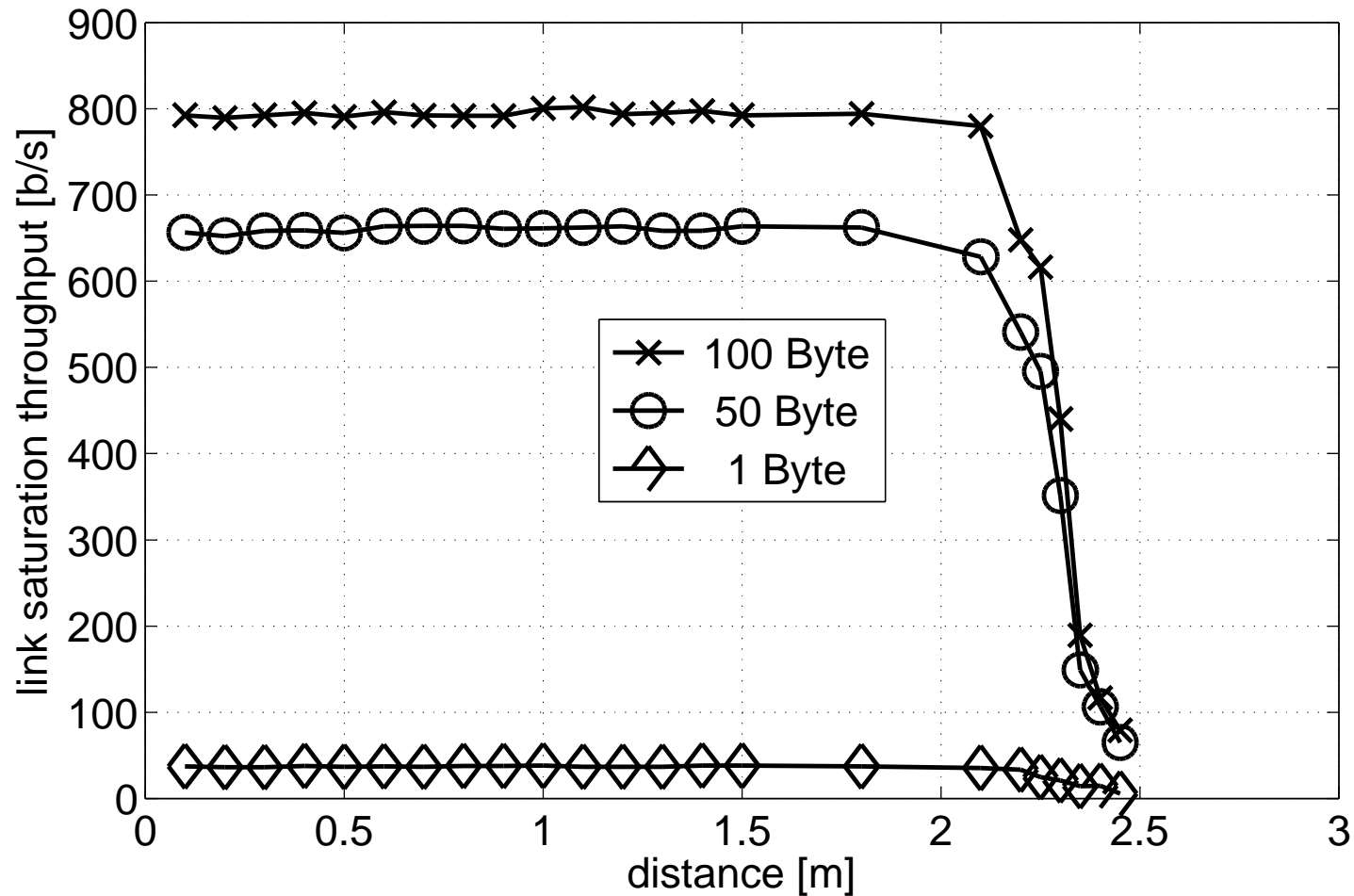
Hardware Edge Detector



- Distance: 12 cm



Comparison: DisneyResearch vs. Our VLC



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Comparison: DisneyResearch vs. Our VLC

DisneyResearch

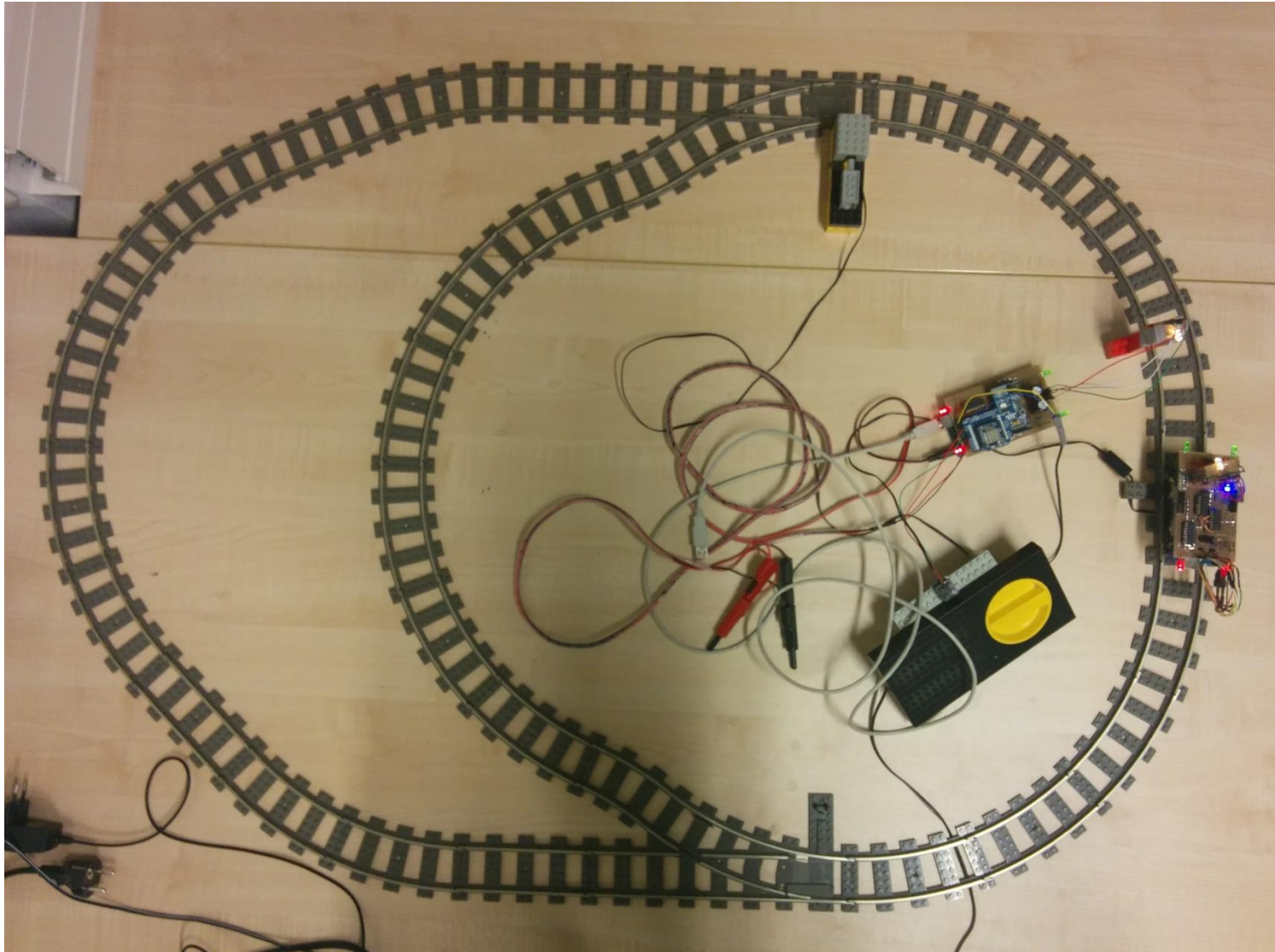
- Communication between several devices (CSMA)
- LED for sending/receiving
- Continuous AD conversion

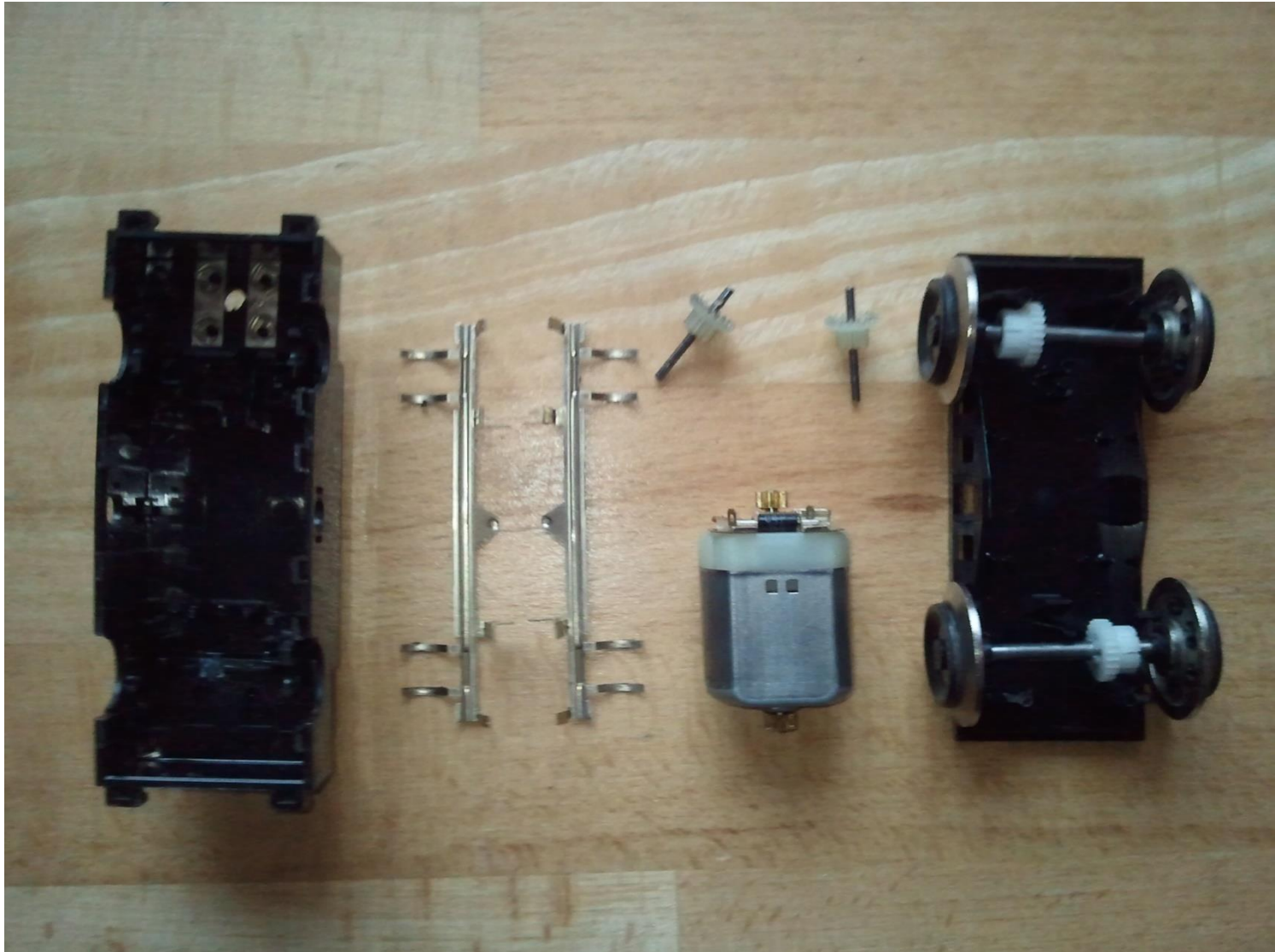
Our VLC

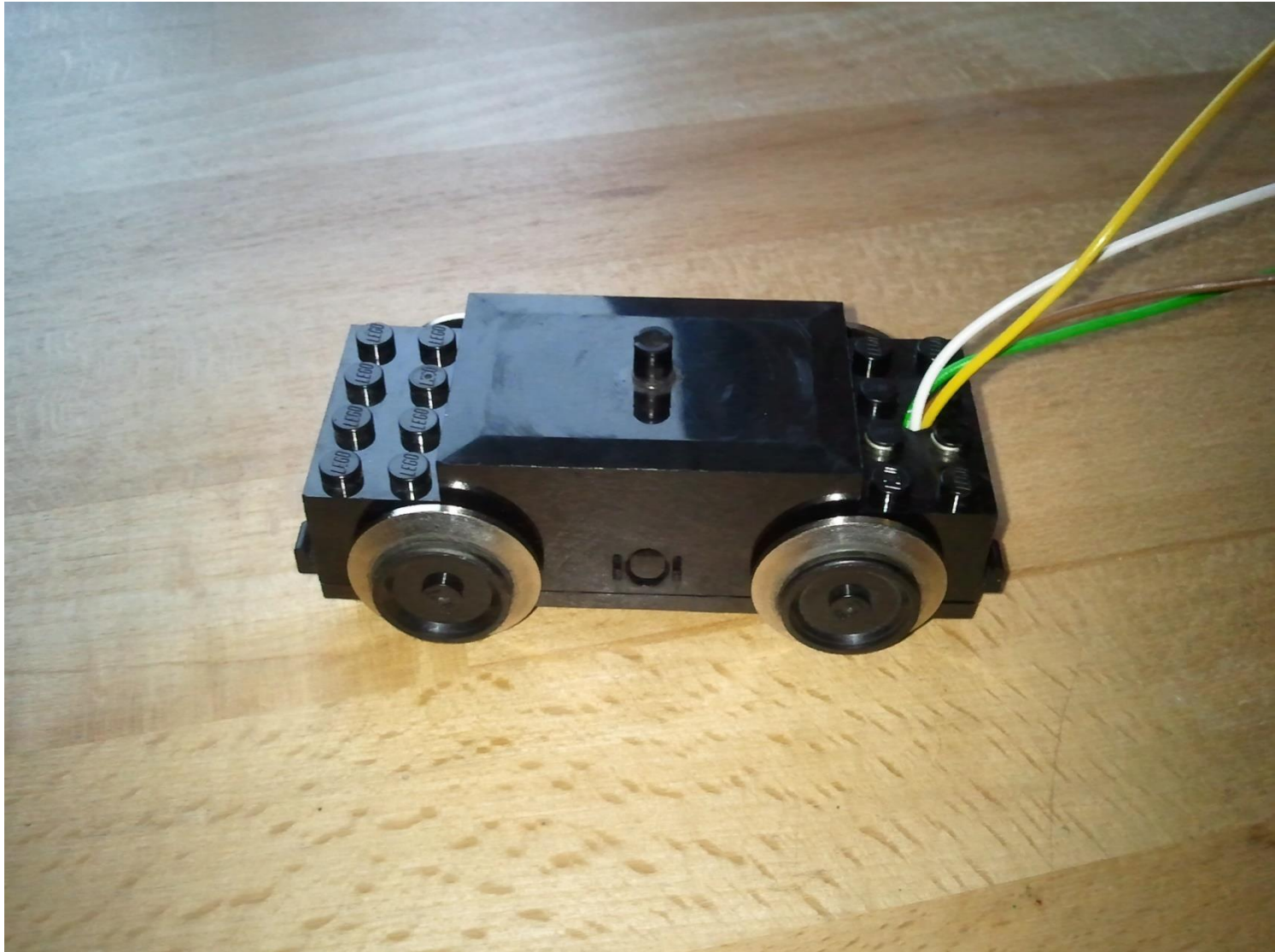
- Communication between 2 Arduinos
- LED for sending, phototransistors for receiving
- Hardware edge detector

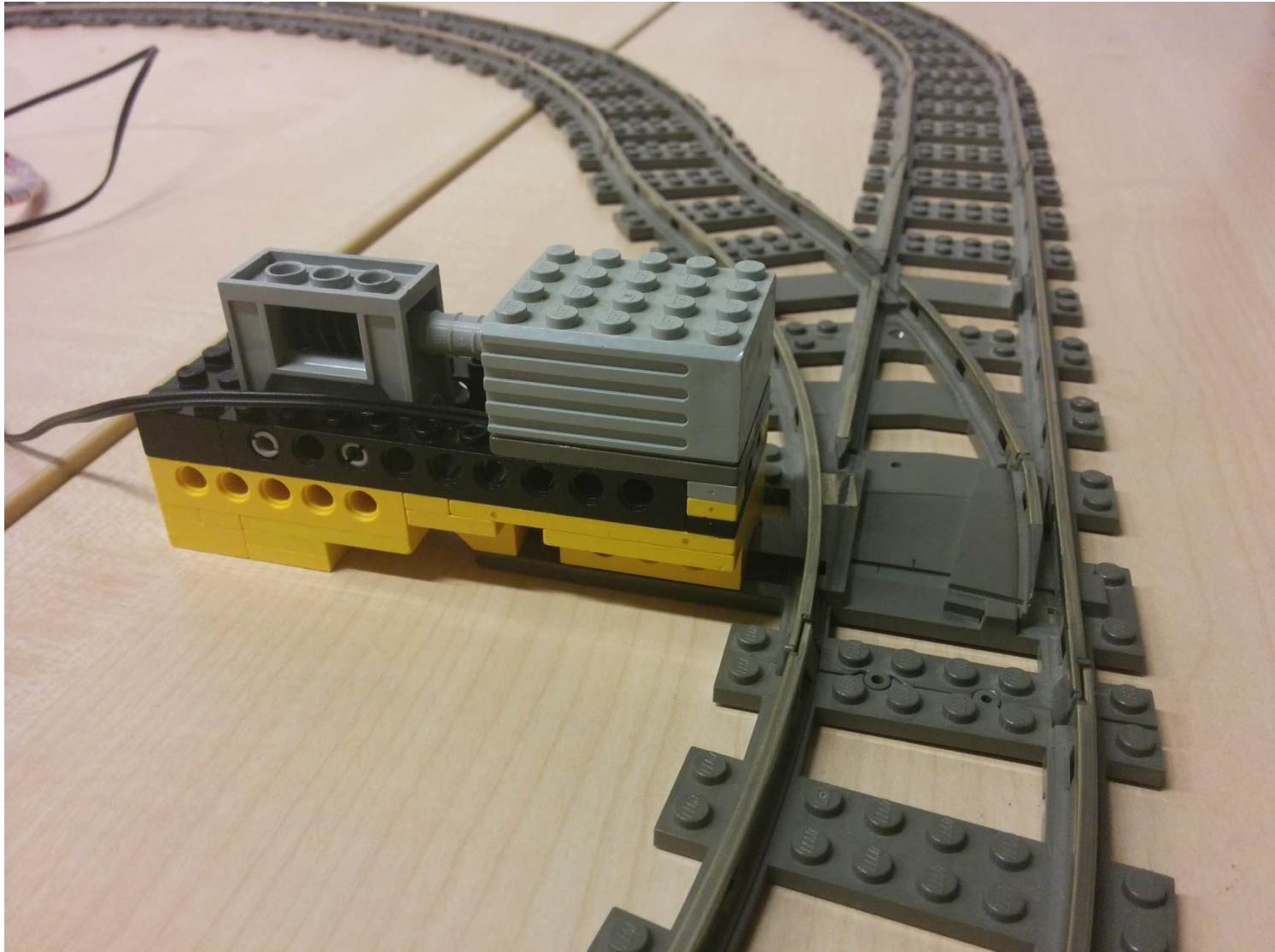
- **Control a LEGO train with VLC**
- **App communicates with a track controller via Bluetooth**
 - ▶ Control turnout, speed, direction, headlights and taillights
- **Track controller communicates with train via VLC**
 - ▶ Signal along the track transmits data

Use Case

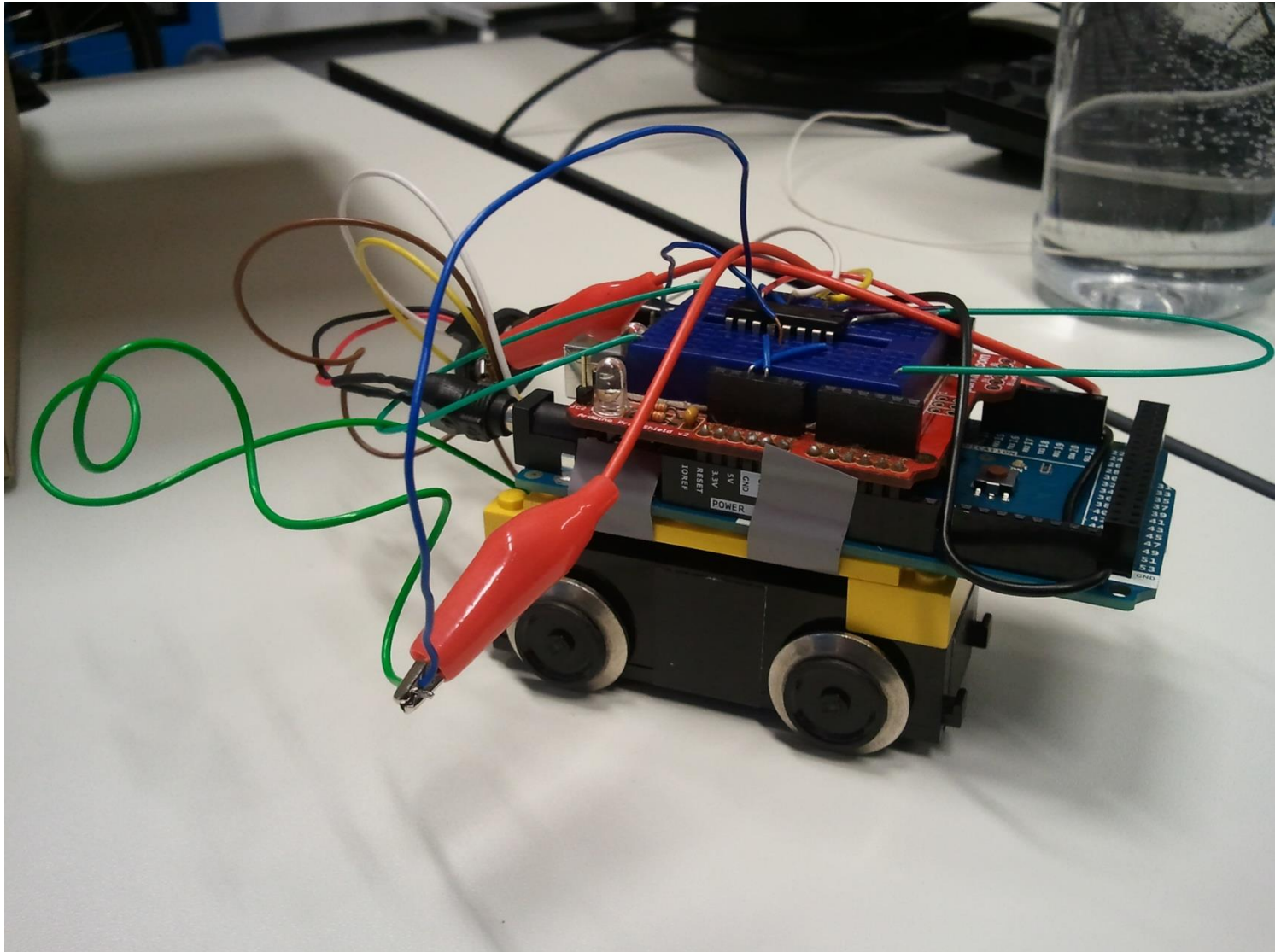




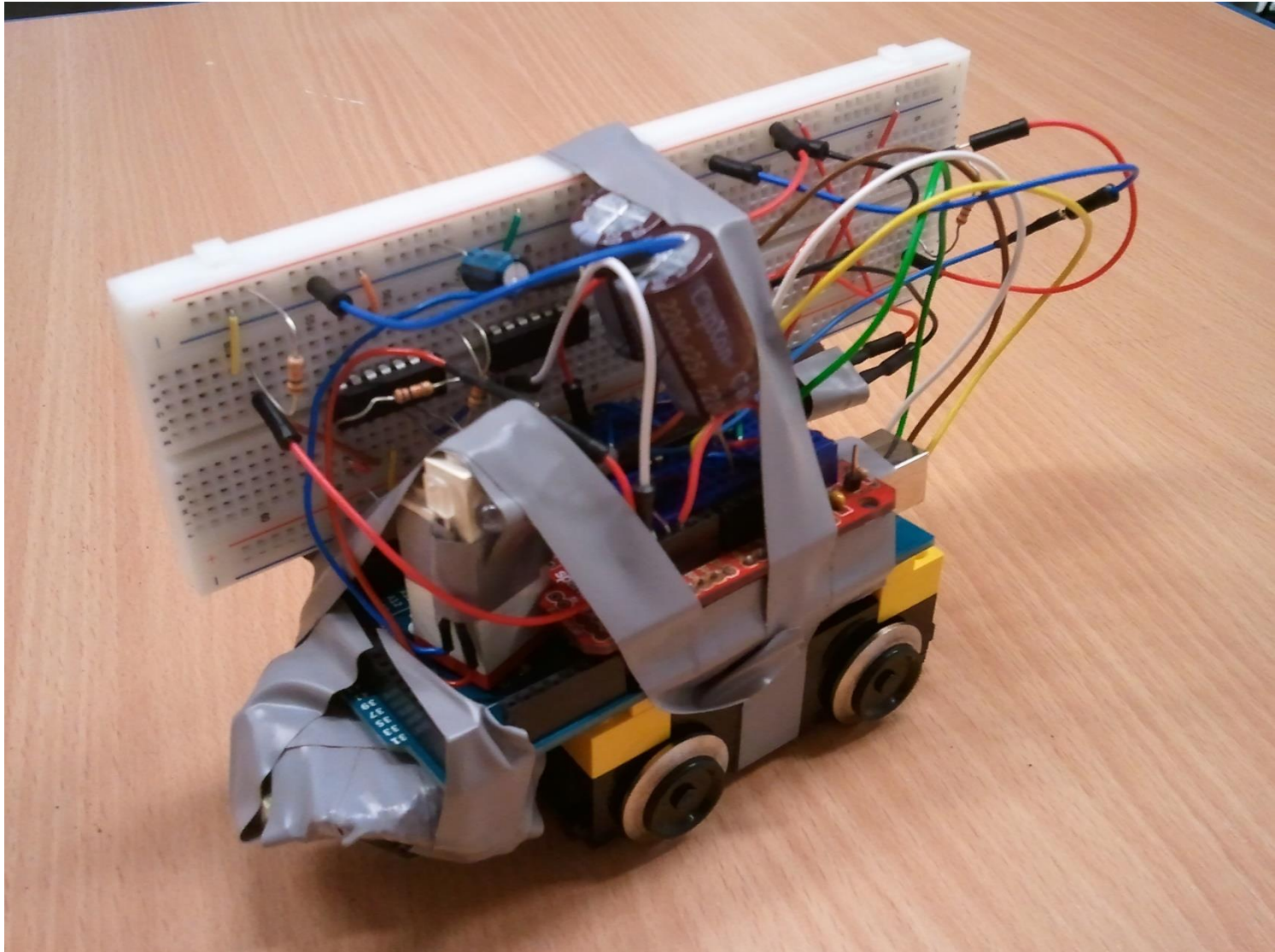




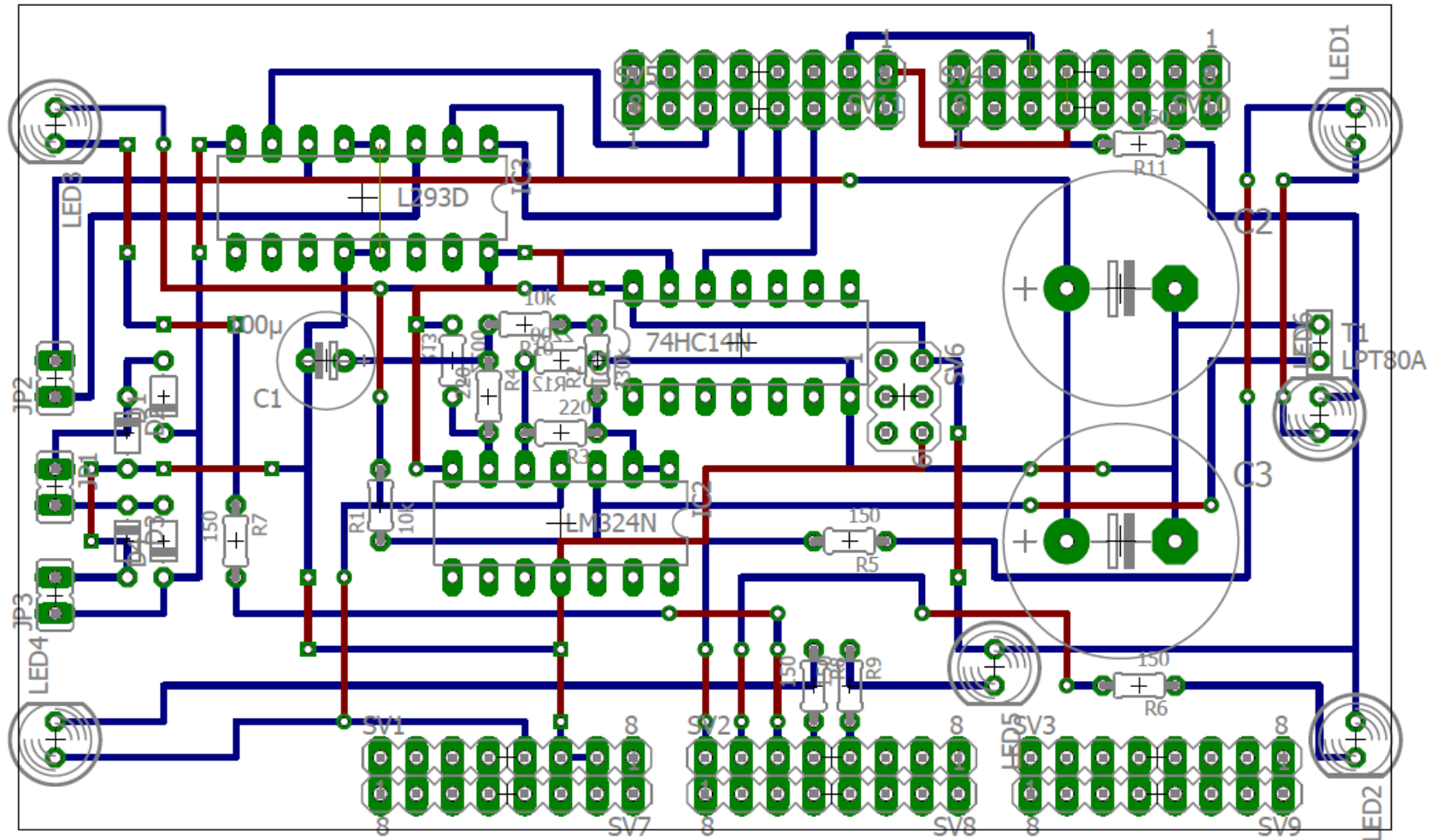
Evolution of the Train



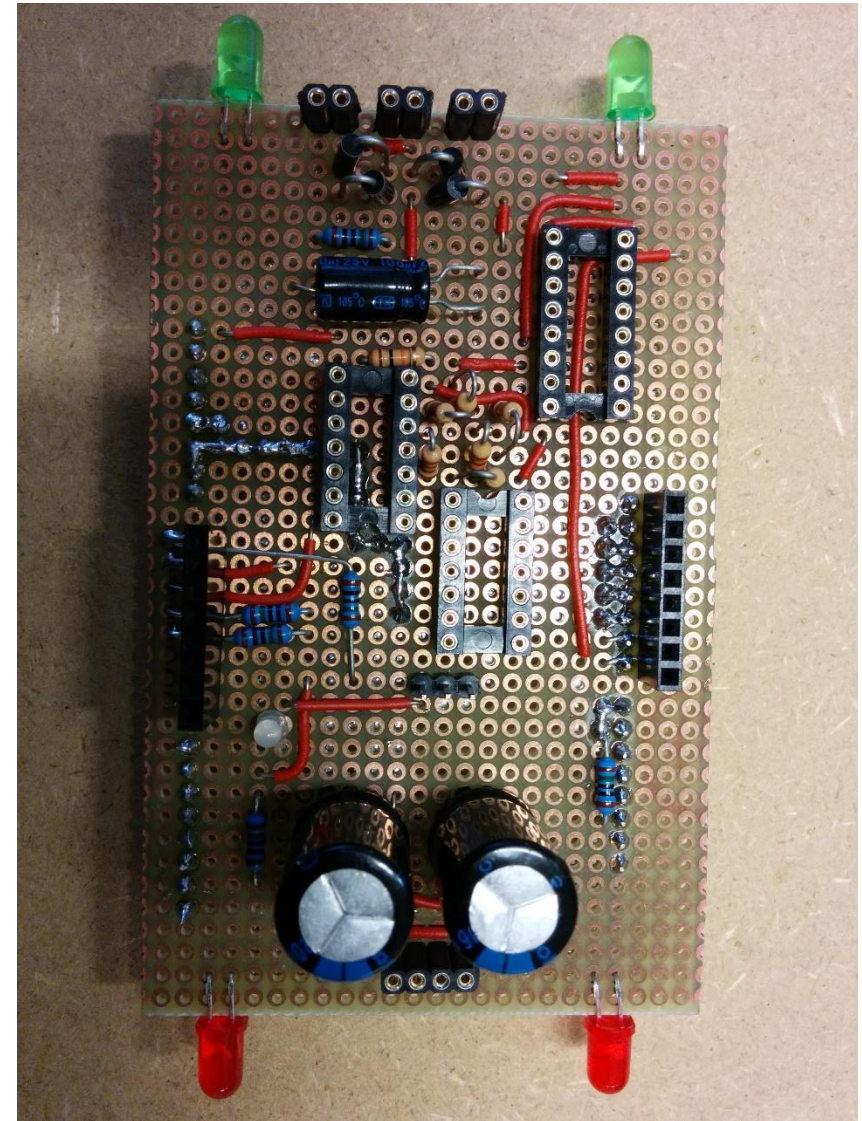
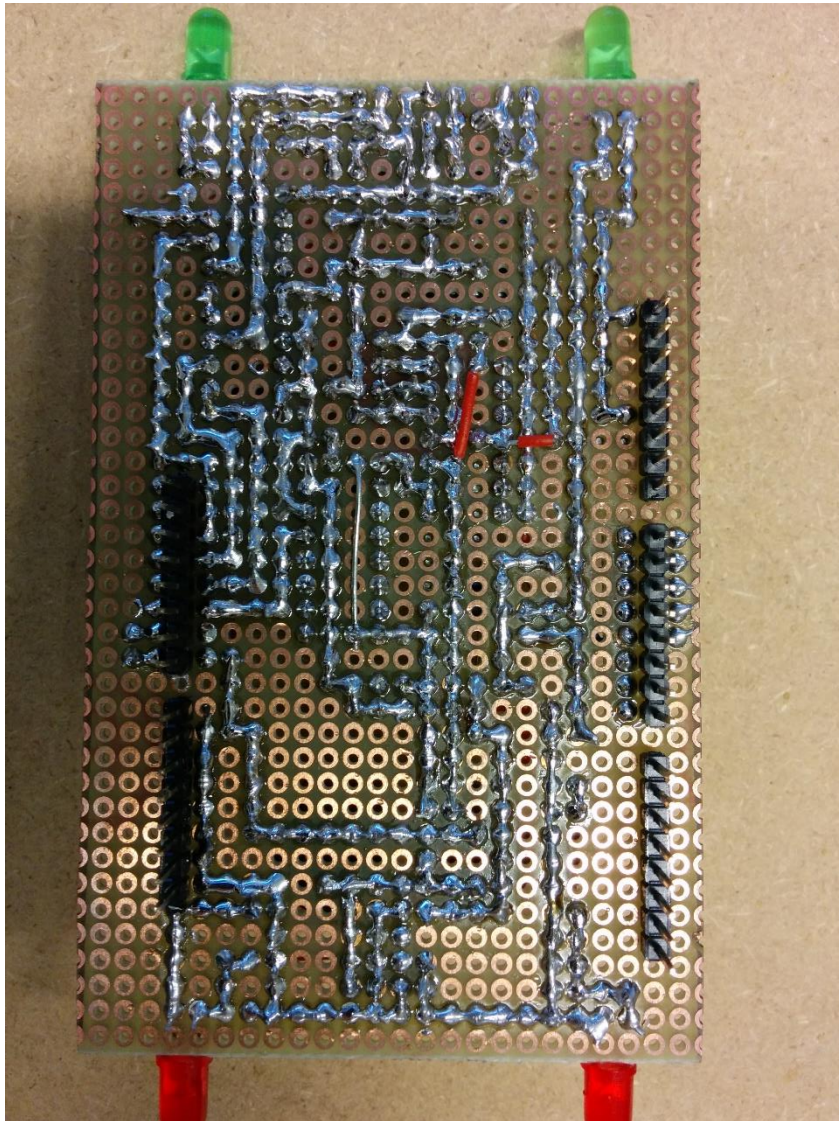
Evolution of the Train



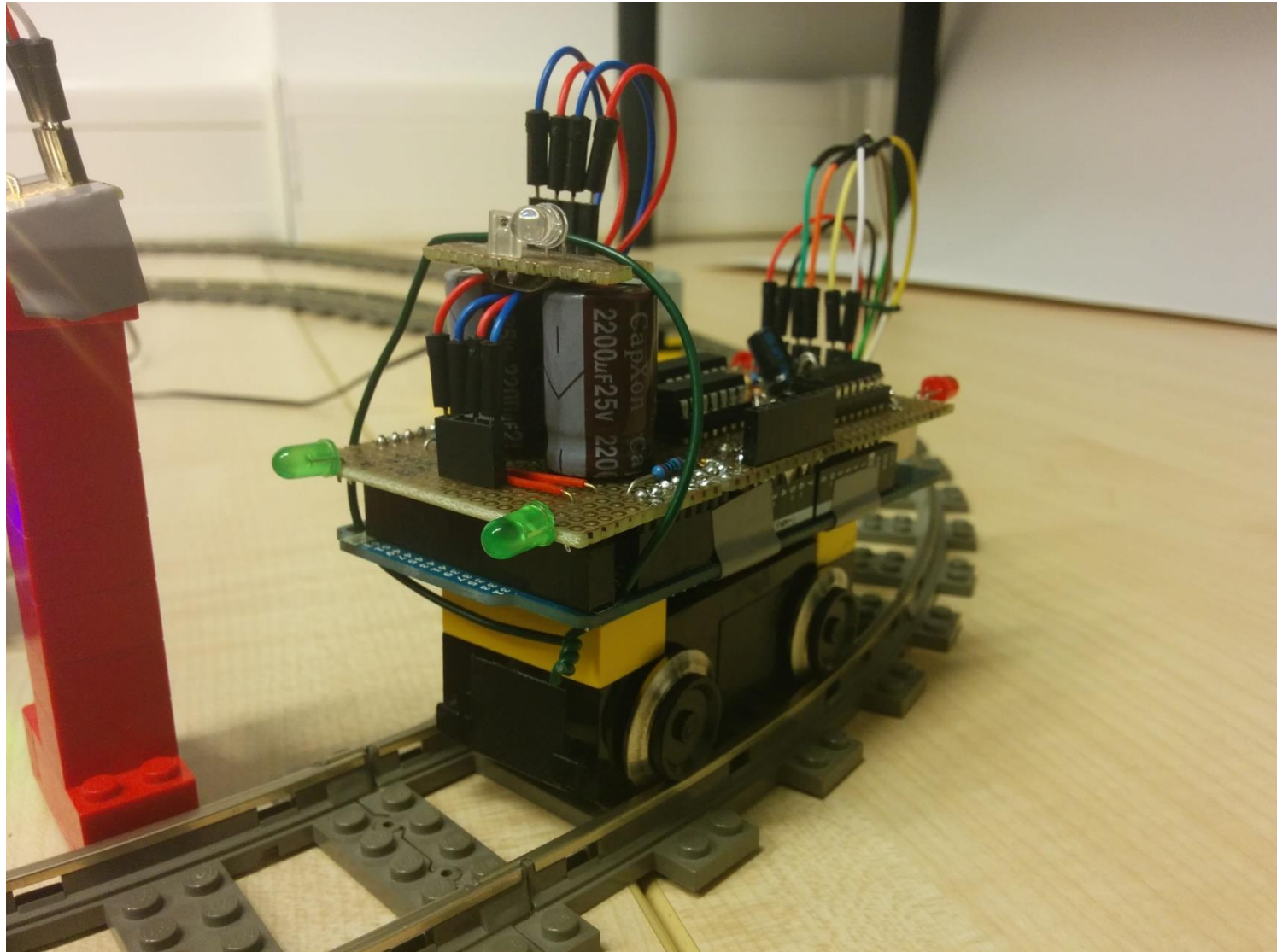
Evolution of the Train



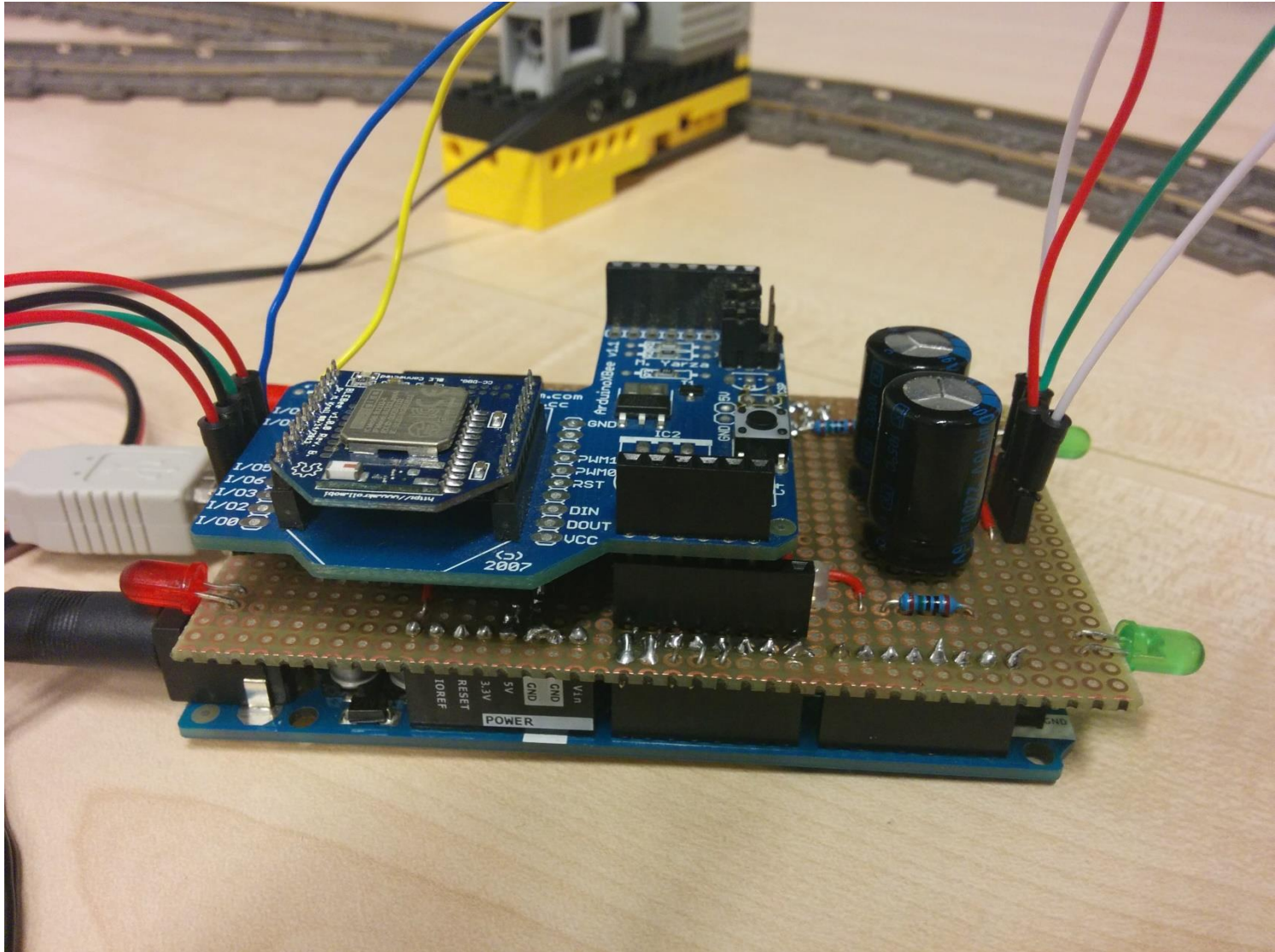
Evolution of the Train



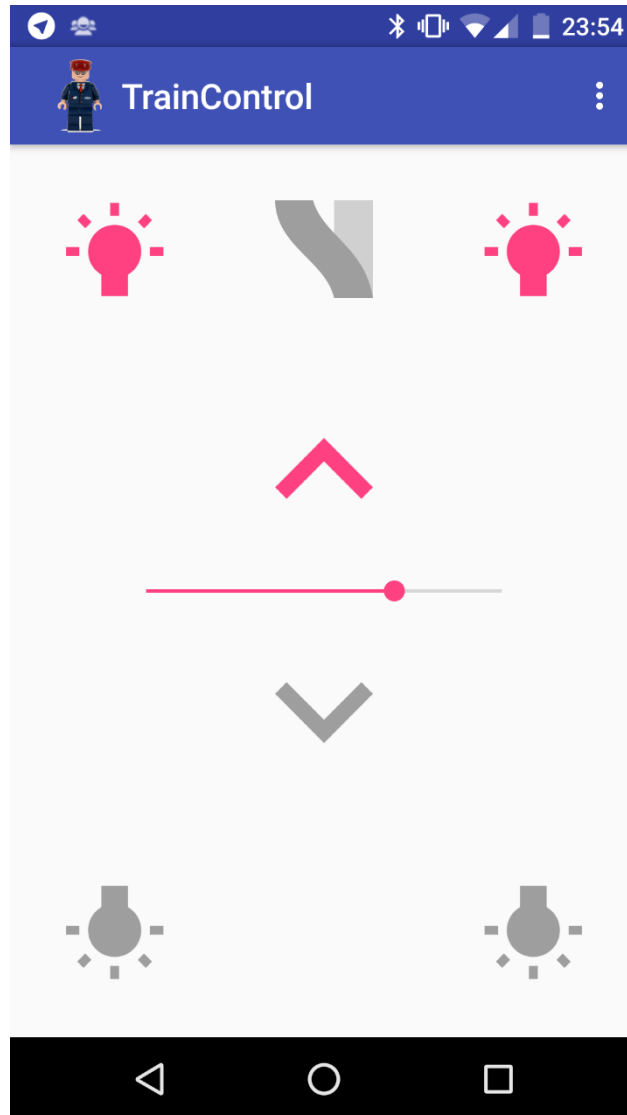
Evolution of the Train



Final Track Controller



App - TrainControl



Demonstration



1. Subway Train Conductor.
http://lego.wikia.com/wiki/Subway_Train_Conductor
2. Stefan Schmid, Giorgio Corbellini, Stefan Mangold, and Thomas R. Gross. 2013. LED-to-LED visible light communication networks. In *Proceedings of the fourteenth ACM international symposium on Mobile ad hoc networking and computing* (MobiHoc '13). ACM, New York, NY, USA, Pages 1-10.
3. Visible Light Communication.
<https://www.disneyresearch.com/project/visible-light-communication/>