

# COSC 4010 Practical Machine Learning Fall 2023

## Pipeline Optimization Report

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### 1 Introduction

This exercise involves creating a machine-learning pipeline, intending to create a somewhat automated process to preprocess data, tune learner/pipeline hyperparameters, and train a learner to make predictions on a data set. This report will detail the effect of a Yeo-Johnson transformation on data within the white wine dataset. In addition to tuning hyperparameters utilizing Bayesian optimization and nested cross-validation. The effects of preprocessing the data and tuning the hyperparameters will be examined on multiple learners used for regression.

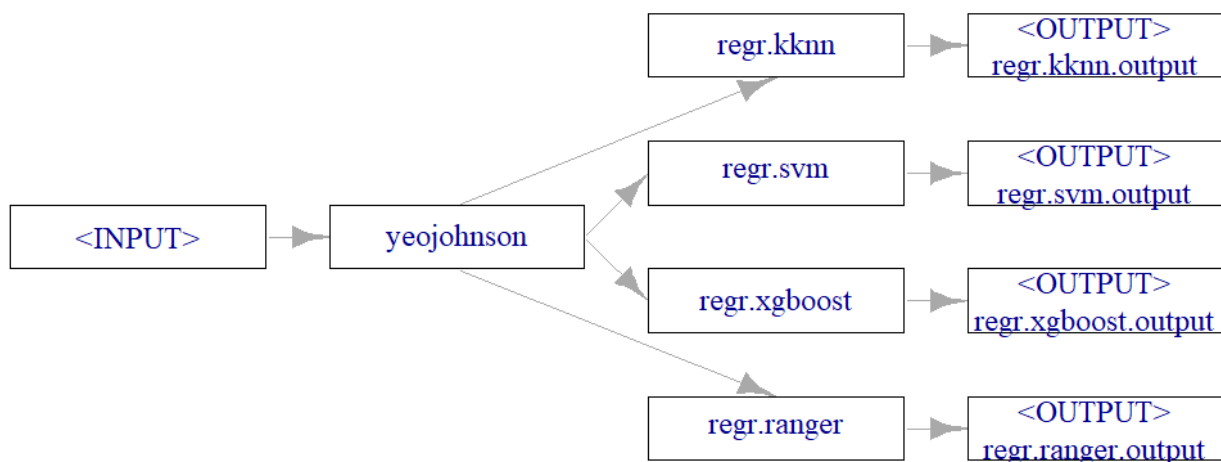
### 2 Data Description

The wine quality dataset consists of tabular data. There are two datasets included one for white wine and the other for red, both datasets consist of wine samples from northern Portugal. The datasets consist of 11 features, these features are continuous values for various wine characteristics. The target data are discrete values used to describe the quality of the wine. This repository makes use of the white wine dataset which consists of 4898 observations. The data was divided into a training and test split, 67% of the data was used for training and the remaining 33% for testing.

#### 3.1 Experiment Setup

This exercise was completed using the R programming language and a number of packages including `mlr3`, `mlr3benchmark`, `mlr3learners`, `mlr3mbo`, `mlr3tuning`, `mlr3tuningspaces`, and `mlr3viz` (dependencies for these packages have been omitted for the sake of brevity). This exercise utilizes a random forest regressor, XGBoost regressor, K-Nearest Neighbor (KNN) regressor, and Support Vector Machine (SVM) regressor from the `mlr3learners` package. The hyperparameter search space within the pipeline is similar to the default search space with some alterations that are discussed in the next section. The hyperparameter optimization algorithm that was used for the pipeline in this exercise utilizes a Bayesian optimization algorithm in combination with nested cross-validation on the dataset. In addition, run time is the limiting factor within this implementation to make program runtimes reasonable. The nested cross-validation consists of 3 outer folds that are implemented using the `benchmark_grid` function from `mlr3`, and 5 inner folds that were implemented using the `auto_tuner` function from `mlr3`. The run-time limitation was enforced on the inner folds if for example each inner fold is allowed 3 minutes to optimize the learner's hyperparameters the overall runtime of the program would be about 9 minutes per learner. The choice for the number of outer and inner folds was mostly arbitrary, 5 inner folds were selected as this seems to be a common value used within machine learning pipelines, and 3 outer folds were selected

to keep run time to a minimum while allowing the pipeline 3 opportunities to produce an accurate learner. The runtimes used in this exercise for the inner folds included 5, 10, and 30 minutes the results of these are discussed in a later section. The seed was arbitrarily set to '349' to ensure comparability between the 3 different run times used. Learner prediction accuracy was evaluated using Mean Squared Error `regr.mse` "Measure to compare true observed response with predicted response in regression tasks". [Bischl, 2023] There is a single preprocessing step within the pipeline this being a Yeo-Johnson transformation "a statistical method used to stabilize variance and make data more closely follow a normal or Gaussian distribution.". [OpenAI, 2023] To determine if this preprocessing step would be beneficial the data for each feature was checked using the skewness function to determine how far it was skewed from normal distribution. All features appeared to be fairly skewed thus, the ranges for the Yeo-Johnson transformation were determined by setting the lower bounds at 5% below the minimum values for each feature and the upper bounds at 5% above the maximum values for each respective feature. Thus the lower bound was 0 - 8.55, and the upper bound was 0.3633-303.45. That was the idea at least, however, this range resulted in missing value errors, so instead the lower bound was set to 0-10 and the upper bound to 10-30. Two untuned learners were used for a comparison of learner performance a random forest regressor (selected as it was the best-performing model in previous exercises) and a featureless regressor.



The figure above provides a visualization of the pipeline used in this exercise.

## 3.2 Hyperparameter Ranges

This section will discuss the hyperparameters that were tuned for each learner used in this exercise in addition to the ranges used for tuning.

Learner	Hyperparameter	Range Used
Random Forest	sample.fraction	<ul style="list-style-type: none"> <li>Specifies the fraction of observations to be used in each tree. Smaller fractions lead to greater diversity, and thus less correlated trees which often is desirable. [Lovelace, 2020]</li> <li>For this exercise, the search space utilized a range from 0.1-1.</li> </ul>

Learner	Hyperparameter	Range Used
	num.trees	<ul style="list-style-type: none"> <li>The number of trees in the forest.</li> <li>For this exercise, the search space utilized a range from 1-2000.</li> </ul>
	mtry.ratio	<ul style="list-style-type: none"> <li>The parameter determines the ratio of variables to be sampled as candidates at each split when constructing each tree in the random forest model. [OpenAI, 2023]</li> <li>For this exercise, the search space utilized a range from 0-1.</li> </ul>
	min.node.size	<ul style="list-style-type: none"> <li>The minimum number of samples (observations) required to create a terminal node (leaf) in each tree of the random forest. [OpenAI, 2023]</li> <li>For this exercise, the search space utilized a range from 1-20.</li> </ul>
KNN	k	<ul style="list-style-type: none"> <li>Number of nearest neighbors used for prediction in the k-nearest neighbors (k-NN) algorithm. [OpenAI, 2023]</li> <li>For this exercise, the search space utilized a range from 1-20.</li> </ul>
	distance	<ul style="list-style-type: none"> <li>Distance between data points in the k-nearest neighbors (k-NN) algorithm. [OpenAI, 2023]</li> <li>For this exercise, the search space utilized a range from 1-20.</li> </ul>
SVM	type	<ul style="list-style-type: none"> <li>For this exercise, the search space utilized eps-regression.</li> </ul>
	kernel	<ul style="list-style-type: none"> <li>For this exercise, the search space utilized radial.</li> </ul>
	cost	<ul style="list-style-type: none"> <li>For this exercise, the search space utilized a range from 0.1-10.</li> </ul>
	epsilon	<ul style="list-style-type: none"> <li>For this exercise, the search space utilized a range from 0.01-2.</li> </ul>
	gamma	<ul style="list-style-type: none"> <li>For this exercise, the search space utilized a range from 0.01-2.</li> </ul>
XGBoost	nrounds	<ul style="list-style-type: none"> <li>For this exercise, the search space utilized a range from 10-300.</li> </ul>
	max_depth	<ul style="list-style-type: none"> <li>For this exercise, the search space utilized a range from 1-20.</li> </ul>

## 4 Results

The figures below provide learner prediction accuracy for pipelines that were provided 3 different run\_time allowances. Figure 1 is a pipeline given 5 minutes to run per inner cross-validation fold, Figure 2 is a pipeline given 10 minutes per inner cross-validation fold, and Figure 3 is a pipeline given 30 minutes per inner cross-validation fold. It can be seen that as tuning time is increased the prediction accuracy of the pipeline increases. It is likely the case that if the pipeline was given more time to train it could produce even better predictions, however, for this exercise, this will not be done. From the figures, it can be seen that the random forest regressor within the pipeline performed the best, with the default random forest having a slightly worse performance, in all 3 cases.

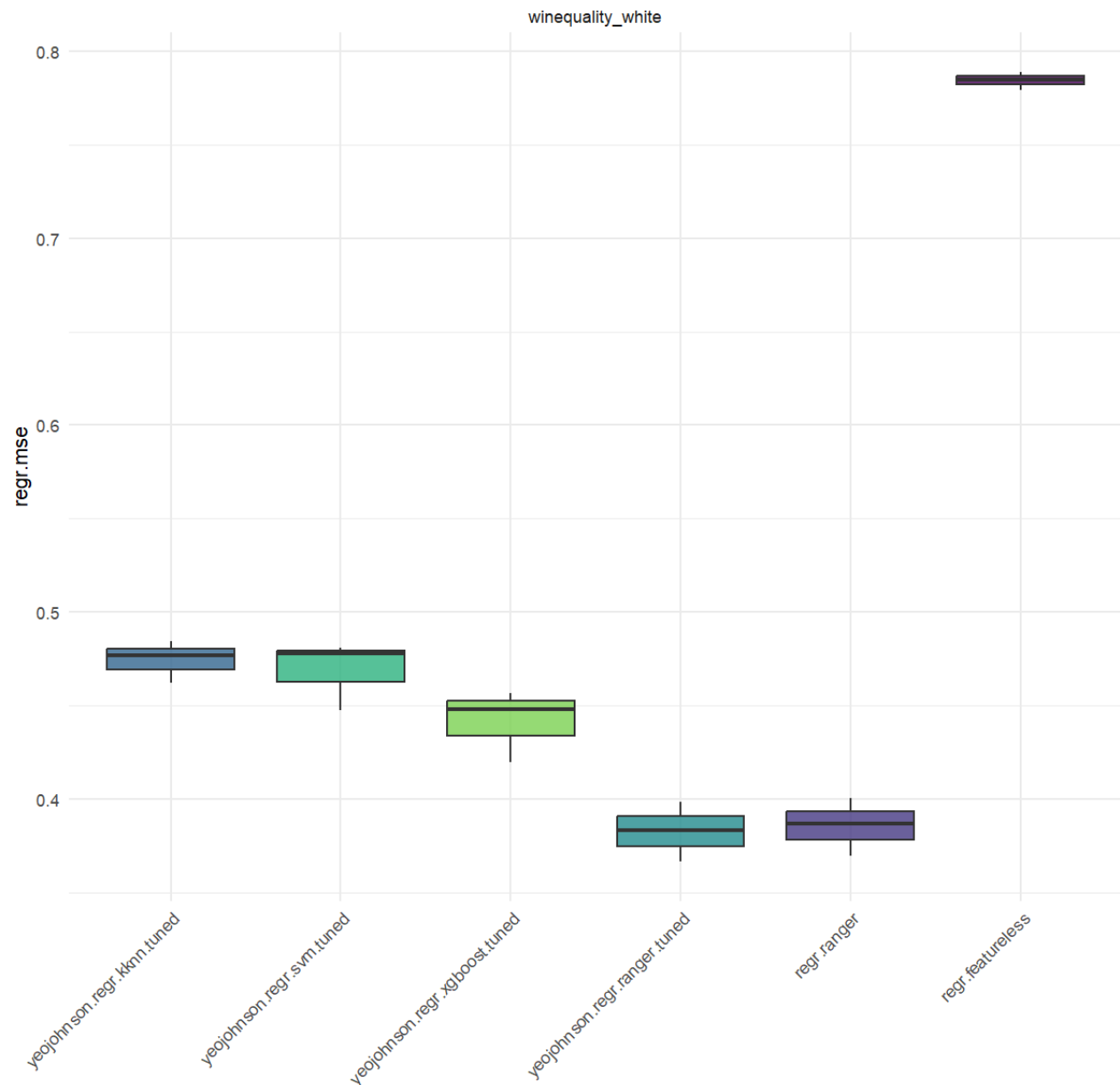


Figure 1: yeojohnson.regr.kknn.tuned 0.473, yeojohnson.regr.svm.tuned 0.469, yeojohnson.regr.xgboost.tuned 0.441, yeojohnson.regr.ranger.tuned 0.383, regr.ranger 0.386, regr.featureless 0.784.

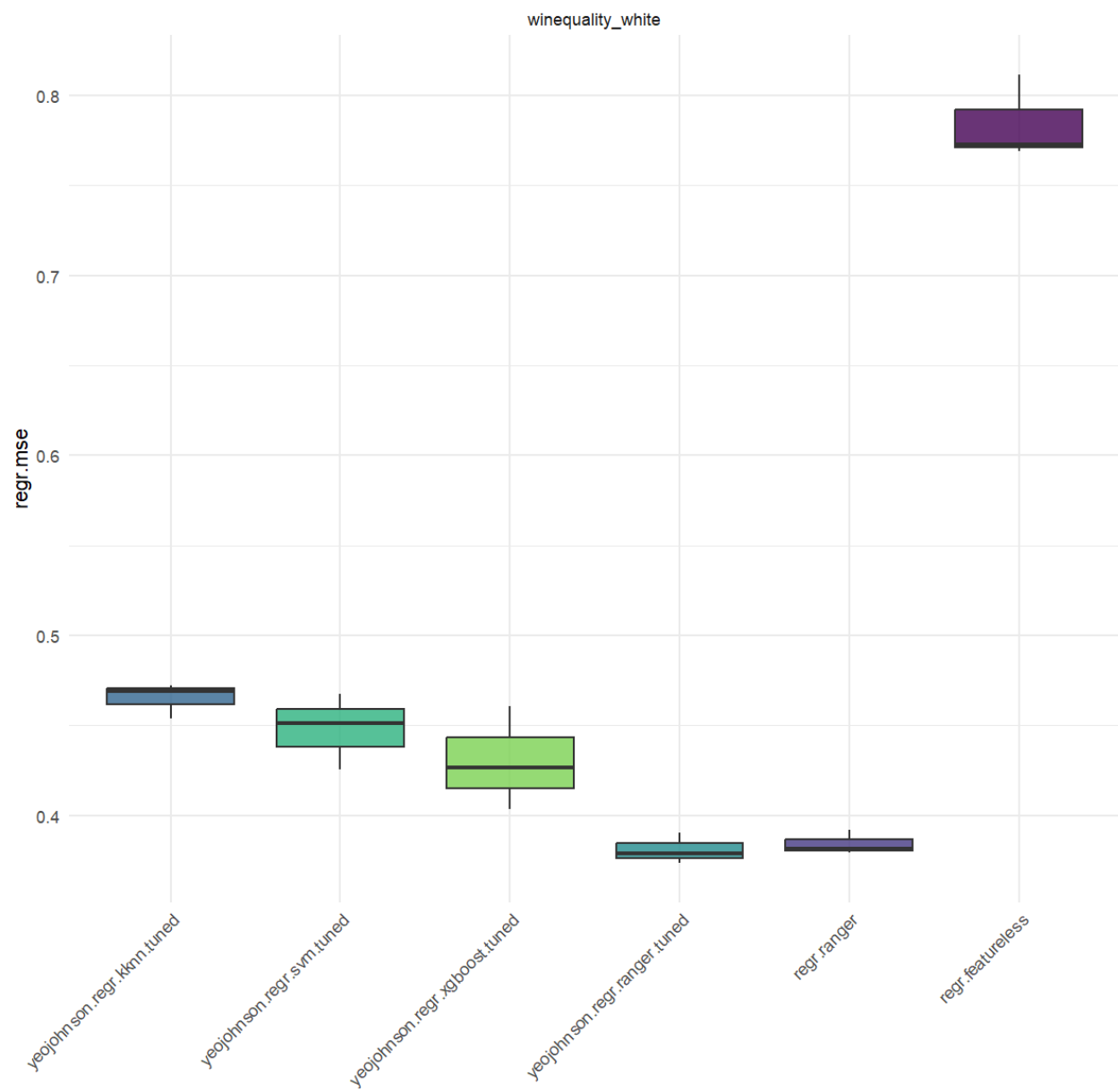


Figure 2: yeojohnson.regr.kknn.tuned 0.465, yeojohnson.regr.svm.tuned 0.448, yeojohnson.regr.xgboost.tuned 0.430, yeojohnson.regr.ranger.tuned 0.381, regr.ranger 0.384, regr.featureless 0.784.

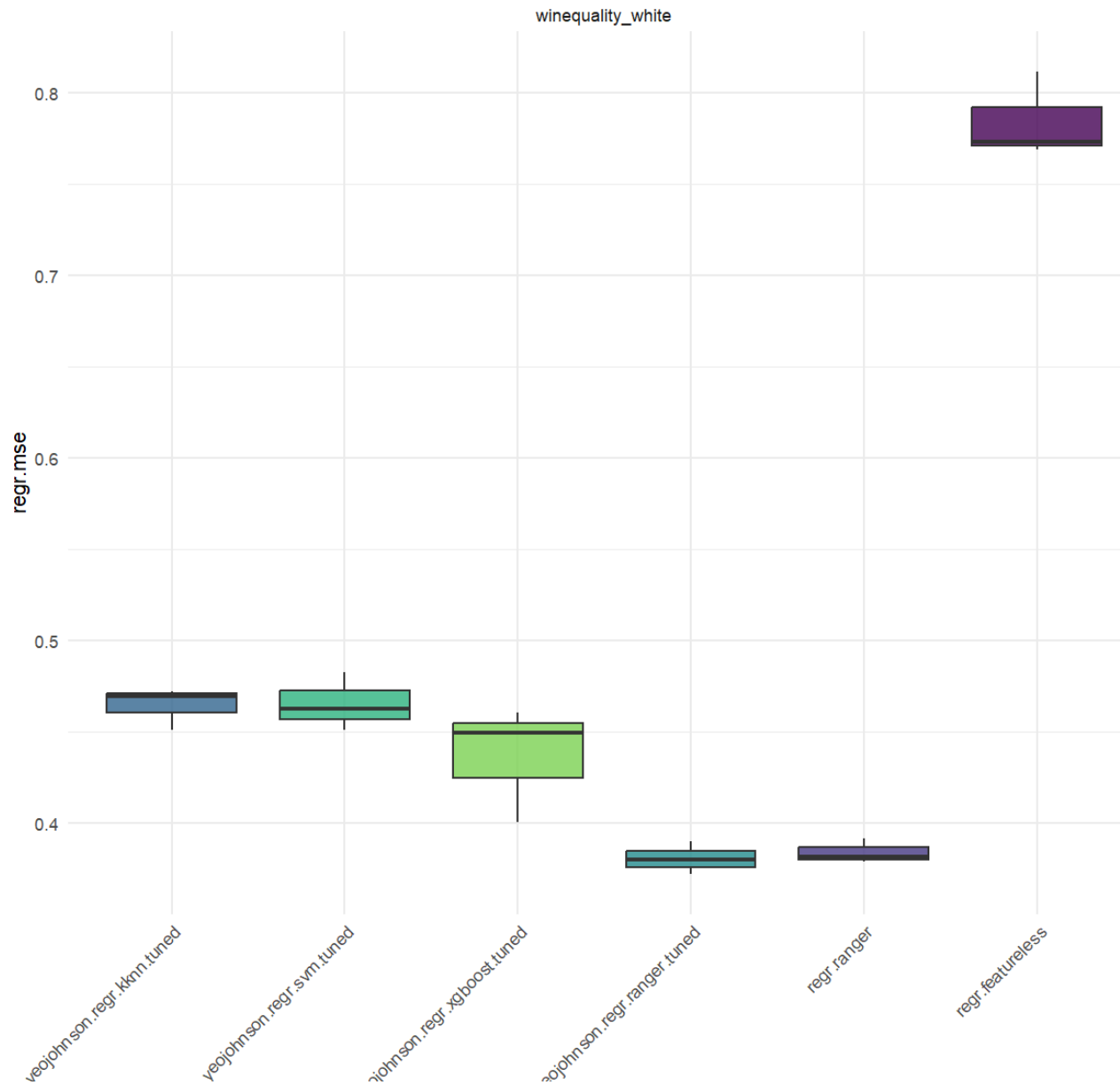


Figure 3: yeojohnson.regr.kknn.tuned 0.464, yeojohnson.regr.svm.tuned 0.466, yeojohnson.regr.xgboost.tuned 0.437, yeojohnson.regr.ranger.rsq • mlr3. 0.38, regr.ranger 0.384, regr.featureless 0.784.

## References

Bischl, B., Sonabend, R., Kotthoff, L., & Lang, M. (2023). R squared - MLR\_MEASURES\_REGR.RSQ. - mlr\_measures\_regr.rsq • mlr3. [https://mlr3.mlr-org.com/reference/mlr\\_measures\\_regr.rsq.html](https://mlr3.mlr-org.com/reference/mlr_measures_regr.rsq.html)

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Lovelace, R., Muenchow, J., & Nowosad, J. (2020). 15 Ecology. In *Geocomputation with R*. essay, CRC press.

ChatGPT (version 2), an AI language model developed by OpenAI