The OneAPI ecosystem: Intel Advisor, SYCLomatic and you".

Stephen Blair-Chappell

Certified Intel oneAPI Instructor



# About Me

#### **Stephen Blair-Chappell**

- Freelance software consultant
- Intel Certified oneAPI instructor.
- Formerly the Technical Director at Bayncore
- For 18 years he was a Technical Consulting Engineer at Intel
- Author of the book "Parallel Programming with Intel Parallel Studio XE".
- Sponsored by Lenovo to do some work at their Centre's of Excellence.

#### When I'm not working

- Trustee of two charities involved with mental health & young people.
- Adventurous DIY
- Play the Pipe Organ



#### oneAPI Spec Elements

The Spec is made of 7 core elements.



oneDPL

oneAPI Data Parallel C++ Library

A companion to the DPC++
Compiler for programming
oneAPI devices with APIs from
C++ standard library, Parallel STL,
and extensions.



oneDNN

oneAPI Deep Neural Network Library

High performance implementations of primitives for deep learning frameworks.



oneCCL

oneAPI Collective
Communications Library

Communication primitives for scaling deep learning frameworks across multiple devices.



**Level Zero** 

oneAPI Level Zero

System interface for oneAPI languages and libraries.



oneDAL

oneAPI Data Analytics Library

Algorithms for accelerated data science.



oneTBB

oneAPI Threading Building Blocks

Library for adding thread-based parallelism to complex applications on multiprocessors.



oneMKL

oneAPI Math Kernel Library

High performance math routines for science, engineering, and financial applications.

https://uxlfoundation.org/

#### Intel<sup>®</sup> oneAPI Toolkits



Intel® oneAPI Base Toolkit



A core set of high-performance libraries and tools for building C++, SYCL, C/OpenMP, and Python applications

Add-on **Domain-specific**Toolkits



For HPC developers



For visual creators, scientists & engineers



For edge & IoT developers

Intel® oneAPI Tools for HPC

Deliver fast Fortran, OpenMP & MPI applications that scale

#### Intel® oneAPI Rendering Toolkit

Accelerate visual compute, deliver high-performance, high-fidelity visualization applications.

Intel® oneAPI Tools for IoT
Build efficient, reliable solutions
that run at network's edge

Toolkits
powered by
oneAPI



For AI developers & data scientists

#### Intel® Al Analytics Toolkit

Accelerate machine learning & data science pipelines end-to-end with optimized DL & ML frameworks & high-performing Python libraries



For deep learning inference developers

#### Intel® OpenVINO™ toolkit

Deploy high performance inference & applications from edge to cloud

Download at <a href="intel.com/oneAPI">intel.com/oneAPI</a>
Or visit Intel® DevCloud for oneAPI

## Intel<sup>®</sup> oneAPI Base Toolkit

#### Accelerate Data-centric Workloads

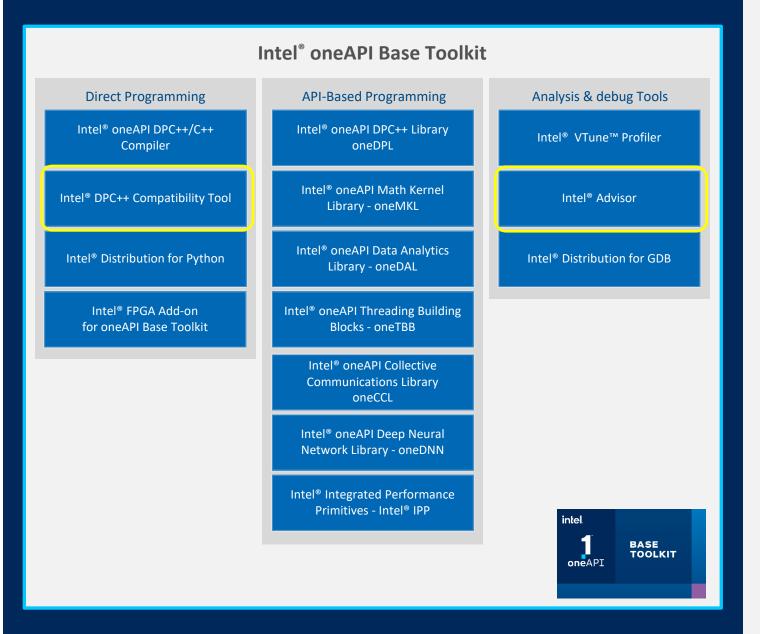
A core set of core tools and libraries for developing high-performance applications on Intel® CPUs, GPUs, and FPGAs.

#### Who Uses It?

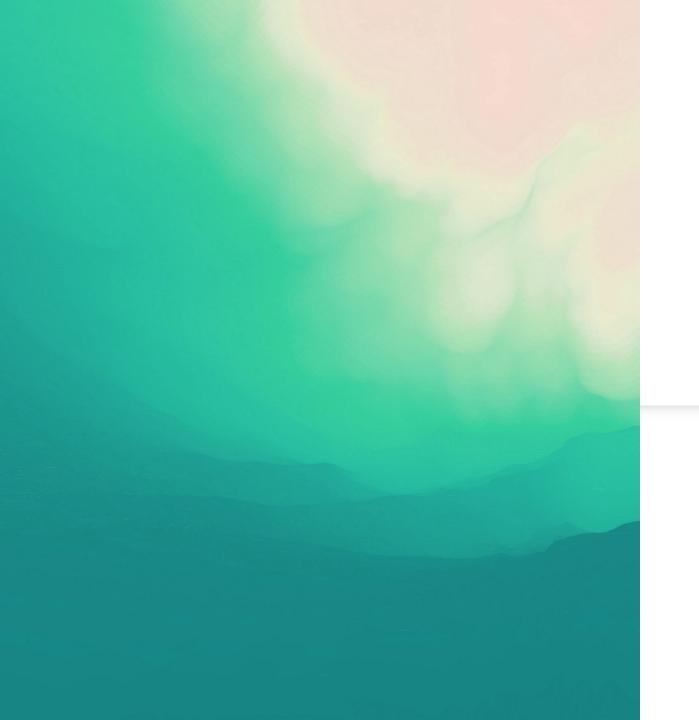
- A broad range of developers across industries
- Add-on toolkit users since this is the base for all toolkits

#### Top Features/Benefits

- Data Parallel C++ compiler, library and analysis tools
- SYCLomatic / DPC++ Compatibility tool helps migrate CUDA code to C++ with SYCL
- Python distribution includes accelerated scikit-learn, NumPy, SciPy libraries
- Optimized performance libraries for threading, math, data analytics, deep learning, and video/image/signal processing



Learn More & Download



# Intel Advisor

#### Intel<sup>®</sup> Advisor

#### Configure Your Accelerated Computing Solution

#### Offload Advisor

Estimate performance of offloading to an accelerator

#### **Roofline Analysis**

Optimize CPU/GPU code for memory and compute

#### **Vectorization Advisor**

Add and optimize vectorization

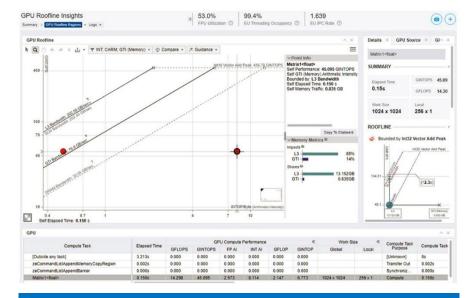
#### Threading Advisor

Add effective threading to unthreaded applications

#### Flow Graph Analyzer

Create and analyze efficient flow graphs

# Top Metrics 3.3x Speed Up for Accelerated Code Program Metrics Original Accelerated 7.00s Program Time on Host... Speed Up for Accelerated Time Non Accelerated Time Speed Up for Accelerated Code Time in MPI calls Speed Up for Accelerated Code Time on Target Time on Target Tools Amdahi's Law Speed Up Time on Target Tools Amdahi's Law Speed Up Time on Target Tools Amdahi's Law Speed Up Time on Target Tools Target Platform Speed Up Time on Target Tools Target Platform Target Tools Target Platform Target Tools Target Platform Tools Target Platform Tools Target Platform Tools Target Tools Tools Target Tools Tool



**Know Before You Offload** 

#### Learn More & Download

# Advisor Offload Modelling

intel

## Offload Modelling – doing it by hand

and see if there is a speed up

CPU Run code on CPU and find hotspots Examine results – decide which hotspots are suitable for offloading Implement offload using SYCL or OpenMP **CPU** Run code on CPU and GPU

# Offload Modelling – with Advisor

1 Run code on CPU using Advisor (multiple stage profiling collection)



- 2 Examine results decide which hotspots are suitable for offloading
- $oxed{3}$  Implement offload using SYCL or OpenMP
- Run code on CPU and GPU and see if there is a speed up



Advisor
Simulates
all these
stages

Report



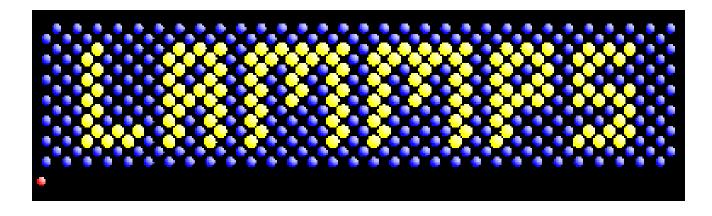
## Demo – An example you could experiment with

git clone https://github.com/oneapi-src/oneAPI-samples.git

make CXX=icpx EXTRA\_CFLAGS=-g advisor --collect=offload -- ./release/Mandelbrot

#### **OUR EXAMPLE**

#### LAMMPS Molecular Dynamics Simulator



https://www.lammps.org/

■ DO THE DEMO NOW!

### Using accuracy presets to control modelling

#### Default (Medium Accuracy)

```
advisor --collect=offload --config=gen12_tgl
--project-dir=./cpu2gpu_offload_modeling --
./release/Mandelbrot 1
```

#### Low Accuracy

```
advisor --collect=offload -accuracy=low --config=gen12_tgl --project-dir=./cpu2gpu_offload_modeling --./release/Mandelbrot 1
```

#### Getting list of steps

```
advisor --collect=offload --dry-run --config=gen12_tgl --project-dir=./cpu2gpu_offload_modeling --./release/Mandelbrot 1
```

Low	Medium	High	
5-10x overhead	15-50x overhead	50-80x overhead	
Survey Trip Count Offload Modelling	Survey Trip Count Offload Modelling	Survey Trip Count Dependenc y analysis Offload Modelling	
L1 Cache	L1 Cache + Host- Device data	L1 Cache + Host- Device data	

## Steps to Offload Projection with Advisor

1. Run a **Survey**: get a list of hotspots

advisor -collect survey

- Sampling
- Binary Static Analysis
- Compiler & debug info

Run a **Trip Count**: count loop iteration

advisor -collect=tripcounts -target-device=gen9 gt2

- Trip count
- Cache simulation

Perform a dependency analysis [optional for quick modelling]

advisor -collect dependencies . .

- Check memory accesses
- Loop selection heuristic

**Model** the Performance

advisor -collect projection (-no-assume-dependencies). . .

Generate HTML report



# GPU-GPU modelling

Add the –gpu flag

Runs code on ACTUAL GPU and models against new GPU.

Use when upgrading from one GPU to another one.

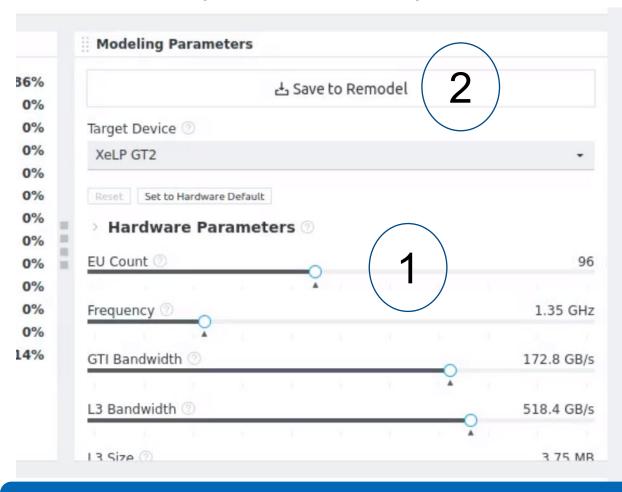
■ NB: use –accuracy=low

# Comparison of CPU-GPU and GPU-GPU modelling

CPU-GPU	GPU-GPU	
Survey	Survey (on GPU)	
Trip Count	Trip Count	
	(Characterization	
	- num Floats and	
	Integer operations)	
Dependency Check	X	
Model Offloading	Model Offloading	

# Re-modelling for a different GPU

- once you already have a set of results



- 1. Adjust Values
- 2. Save parameters
- 3. Re-run modelling

e.g.: advisor -c=projection
--customconfig=config.toml
--config=gen12 tgl

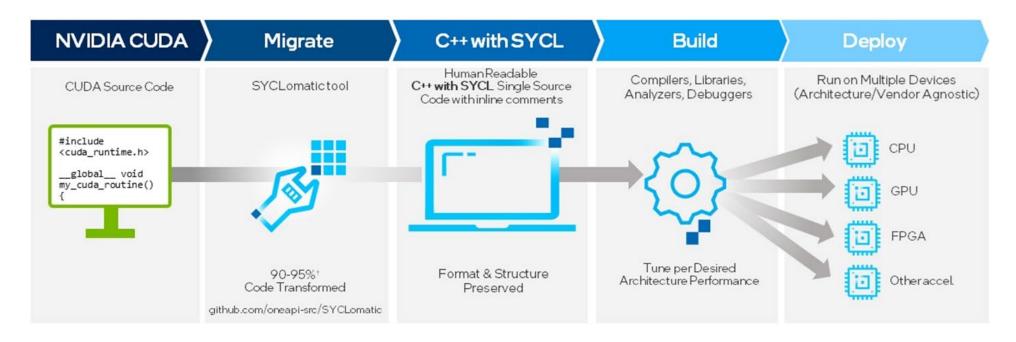
Advantage: quicker than doing a completely new modelling



# SYCLomatic

#### CUDA to SYCL Migration Made Easy

Open Source SYCLomatic Tool Reduces Code Migration Time



Assists developers migrating code written in CUDA to C++ with SYCL, generating **human readable** code wherever possible

~90-95% of code typically migrates automatically<sup>1</sup>

Inline comments are provided to help developers finish porting the application

Intel® DPC++ Compatibility Tool is Intel's implementation, available in the Base Toolkit

# Intel® DPC++ Compatibility Tool

Migration of Large Code Bases

Prepare Intercept-Build

1. <u>Create</u> a compilation database file

intercept-build make

Migrate dpct

- 2. <u>Migrate</u> your source to DPC++ dpct -p compile\_commands.json -in-root=\$PROJ\_DIR
  - -out-root=dpcpp out \*.cu

Review Verify & Manually Edit

3. <u>Verify the source</u> for correctness and <u>fix</u> not migrated parts

# BlackScholes Demo

# SYCLOMATIC on BlackScholes NVIDIA CUDA example

- git clone <a href="https://github.com/NVIDIA/cuda-samples.git">https://github.com/NVIDIA/cuda-samples.git</a>
- cd Samples/5 Domain Specific/BlackScholes
- make clean
- intercept-build make
- mkdir ../migration
- dpct --cuda-include-path /usr/local/cuda-12/include \
   -p compile commands.json --in-root=. --out-root=../migration
- cp Makefile ../migration

## Changes to make command line

make: \*\*\* No rule to make target 'BlackScholes.cu', needed by 'BlackScholes.o'. Stop. BlackScholes.o:BlackScholes.cu => BlackScholes.o:BlackScholes.dp.cpp BlackScholes.dp.qpp:34:10: fatal error: sycl/sycl.hpp: No such file or directory make "NVCC=icpx -fsycl" icpx: error: unsupported option '--threads'; did you mean '-mthreads'? icpx: error: unknown argument: '-maxrregcount=16' icpx: error: unknown argument: '-gencode' make "NVCC=icpx -fsycl" ALL CCFLAGS="" GENCODE FLAGS="-q -03"

## Changes to BlackScholes.dp.cpp

```
    BlackScholes.dp.cpp:106:3: error: use of undeclared identifier 'findCudaDevice' checkCudaErrors(DPCT_CHECK_ERROR(findCudaDevice(argc, (const char **)argv); getLastCudaError("BlackScholesGPU() execution failed\n");
    add to BlackScholes.dp.cpp
```

```
void checkCudaErrors(int err){}
void findCudaDevice(int argc,const char** argv){}
void getLastCudaError(char * strErr){}
```

#### Different Performance

#### **CUDA**

- Executing Black-Scholes GPU kernel (512 iterations)...
- Options count : 8000000
- BlackScholesGPU() time : 0.158816 msec
- Effective memory bandwidth: 503.726277GB/s
- Gigaoptions per second : 50.372628
- BlackScholes, Throughput = 50.3726
   GOptions/s, Time = 0.00016 s, Size = 8000000 options, NumDevsUsed = 1, Workgroup = 128

#### **SYCL**

- Executing Black-Scholes GPU kernel (512 iterations)...
- Options count : 8000000
- BlackScholesGPU() time : 1.463035 msec
- Effective memory bandwidth: 54.680848GB/s
- Gigaoptions per second : 5.468085
- BlackScholes, Throughput = 5.4681
   GOptions/s, Time = 0.00146 s, Size = 8000000 options, NumDevsUsed = 1, Workgroup = 128

## Checking app is running on correct GPU

#### Check what accelerators are available

[opencl:acc:0] Intel(R) FPGA Emulation Platform for OpenCL(TM), Intel(R) FPGA Emulation Device 1.2 [2023.16.6.0.22\_223734] [opencl:cpu:1] Intel(R) OpenCL, 13th Gen Intel(R) Core(TM) i9-13900HX 3.0 [2023.16.6.0.22\_223734] [opencl:gpu:2] Intel(R) OpenCL HD Graphics, Intel(R) Graphics [0xa788] 3.0 [22.24.23453] [ext\_oneapi\_level\_zero:gpu:0] Intel(R) Level-Zero, Intel(R) Graphics [0xa788] 1.3 [1.3.23453] [ext\_oneapi\_cuda:gpu:0] NVIDIA CUDA BACKEND, NVIDIA GeForce RTX 4090 Laptop GPU 8.8 [CUDA 12.0]

#### Run app with SYCL\_PI\_TRACE

SYCL\_PI\_TRACE=1 ./Blackscholes SYCL\_PI\_TRACE[all]: Selected device: -> final score = SYCL\_PI\_TRACE[all]: platform: Intel(R) Level-Zero SYCL\_PI\_TRACE[all]: device: Intel(R) Graphics [0xa788] [./BlackScholes] - Starting...

# Running on Intel GPU not NVIDIA GPU!

# Force app to use NVIDIA GPU using SYCL\_DEVICE\_FILTER

SYCL\_DEVICE\_FILTER=cuda SYCL\_PI\_TRACE=1 ./BlackScholes

```
SYCL_PI_TRACE[basic]: Plugin found and successfully loaded: libpi_cuda.so [ PluginVersion: 12.27.1 ]
SYCL_PI_TRACE[all]: Requested device_type: info::device_type::automatic
SYCL_PI_TRACE[all]: Selected device: -> final score = 500
                                                                        Invalid Binary: looks
                    platform: NVIDIA CUDA BACKEND
SYCL_PI_TRACE[all]:
SYCL_PI_TRACE[all]: device: NVIDIA GeForce RTX 4090 Laptop GPU
                                                                          like wrong options
[./BlackScholes] - Starting...
Initializing data...
...allocating CPU memory for options.
                                                                          were used in initial
...allocating GPU memory for options.
...generating input data in CPU mem.
                                                                                     build!
...copying input data to GPU mem.
Data init done.
Executing Black-Scholes GPU kernel (512 iterations)...
terminate called after throwing an instance of 'sycl::_V1::runtime_error'
 what(): Native API failed. Native API returns: -42 (PI_ERROR_INVALID_BINARY) -42 (PI_ERROR_INVALID_BINARY)
Aborted
```

## Rebuilding and Running fixes the problem

## NVIDIA GPU

- App should have been built with 'option' -fsycltargets=nvptx64-nvidiacuda
- make NVCC="icpx fsycl" ALL\_CCFLAGS=""
  GENCODE\_FLAGS="-g O3 -fsycltargets=nvptx64-nvidiacuda "

```
SYCL_PI_TRACE[all]: Selected device: -> final sco
SYCL_PI_TRACE[all]: platform: NVIDIA CUDA BACKEN
SYCL_PI_TRACE[all]: device: NVIDIA GeForce RTX 4090 Laptop
[./BlackScholes] - Starting...
Initializing data...
                               SYCL same Perf
..allocating CPU memory for opti
..allocating GPU memory for opti
                                            as CUDA
 ..generating input data in CPU m
..copying input data to GPU mem.
Data init done.
Executing Black-Scholes GPU kernel (512 iterations)...
Options count
                  : 8000000
BlackScholesGPU() time : 0.162633 msec
Effective memory bandwidth: 491.905667 GB/s
Gigaoptions per second : 49.190567
BlackScholes, Throughput = 49.1906 GOptions/s, Time = 0.00016
Devslised = 1 Workgroup = 128
```

```
SYCL_PI_TRACE[basic]: Plugin found and successfully loaded: libpi_cuda.so [ PluginVersion: 12.27.1 ]
SYCL_PI_TRACE[all]: Requested device_type: info::device_type::automatic
SYCL_PI_TRACE[all]: Selected device: -> final score = 1500
SYCL_PI_TRACE[all]: platform: NVIDIA CUDA BACKEND
SYCL_PI_TRACE[all]: device: NVIDIA GeForce RTX 4090 Laptop GPU
[./BlackScholes] - Starting...
Initializing data...
...allocating CPU memory for options.
...allocating GPU memory for options.
...generating input data in CPU mem.
...copying input data to GPU mem.
Data init done.
Executing Black-Scholes GPU kernel (512 iterations)...
Options count
                          : 8000000
BlackScholesGPU() time : 0.160705 msec
Effective memory bandwidth: 497.806309 GB/s
Gigaoptions per second
                         : 49.780631
BlackScholes, Throughput = 49.7806 GOptions/s, Time = 0.00016 s, Size = 8000000 options, NumDevsUsed = 1, Workgroup = 12
```

# 

# and

YOU

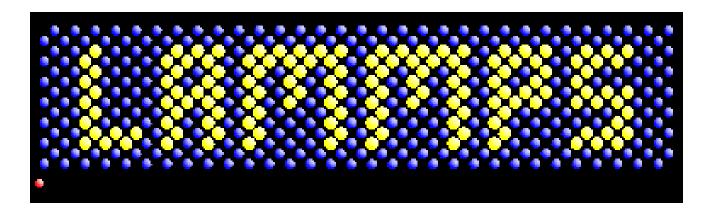
# Backup

# Lammps offloading

Stephen Blair-Chappell

# Test Application

#### LAMMPS Molecular Dynamics Simulator



https://www.lammps.org/

# Machine 1 Spec - Workstation

```
load-OneAPI/LAB3/1-Model-Offload$ lscpu
rchitecture:
                                x86 64
                                32-bit, 64-bit
PU op-mode(s):
Byte Order:
                                Little Endian
ddress sizes:
                                46 bits physical, 48 bits virtual
n-line CPU(s) list:
                                0-23
hread(s) per core:
ore(s) per socket:
ocket(s):
NUMA node(s):
endor ID:
                                GenuineIntel
PU family:
lode1:
odel name:
                                Intel(R) Core(TM) i9-10920X CPU @ 3.50GHz
Stepping:
                                1200.315
PU MHz:
CPU max MHz:
                                4800.0000
PU min MHz:
                                1200.0000
ogoMIPS:
                                6999.82
/irtualization:
1d cache:
                                 384 KiB
1i cache:
                                 384 KiB
L2 cache:
                                12 MiB
                                19.3 MiB
3 cache:
NUMA node0 CPU(s):
                                0-23
/ulnerability Itlb multihit:
                                KVM: Mitigation: Split huge pages
/ulnerability L1tf:
                                Not affected
/ulnerability Mds:
                                Not affected
/ulnerability Meltdown:
                                Not affected
ulnerability Spec store bypass: Mitigation; Speculative Store Bypass disabled via prctl and seccomp'
ulnerability Spectre v1:
                                Mitigation; usercopy/swapgs barriers and __user pointer sanitization
/ulnerability Spectre v2:
                                Mitigation; Enhanced IBRS, IBPB conditional, RSB filling
/ulnerability Srbds:
                                Not affected
/ulnerability Tsx async abort: Mitigation; TSX disabled
                                 fpu vme de pse tsc msr pae mce cx8 apic sep mtrr pge mca cmov pat pse36 clflush dts acp
                                i mmx fxsr sse sse2 ss ht tm pbe syscall nx pdpe1gb rdtscp lm constant_tsc art arch_pe
                                fmon pebs bts rep_good nopl xtopology nonstop_tsc cpuid aperfmperf pni pclmulqdq dtes6
                                 monitor ds_cpl vmx est tm2 ssse3 sdbg fma cx16 xtpr pdcm pcid dca sse4_1 sse4_2 x2api
                                 movbe popcnt tsc_deadline_timer aes xsave avx f16c rdrand lahf_lm abm 3dnowprefetch c
                                uid fault epb cat 13 cdp 13 invpcid single ssbd mba ibrs ibpb stibp ibrs enhanced tpr
                                hadow vnmi flexpriority ept vpid ept_ad fsgsbase tsc_adjust bmi1 avx2 smep bmi2 erms
                                vpcid cqm mpx rdt a avx512f avx512dq rdseed adx smap clflushopt clwb intel pt avx512cd
                                avx512bw avx512vl xsaveopt xsavec xgetbv1 xsaves cqm_llc cqm_occup_llc cqm_mbm_total c
                                m_mbm_local dtherm_ida_arat_pln_pts_hwp_hwp_act_window_hwp_epp_hwp_pkg_req_avx512_vnn
                                md clear flush 11d arch capabilities
```

```
Intel(R) Core(TM) i9-10920X CPU @ 3.50GHz

CPU(s): 24

On-line CPU(s) list: 0-23

Thread(s) per core: 2
```

```
/x2 smep bmi2 erms in
/b intel_pt avx512cd
_llc cqm_mbm_total cq
_pkg_req avx512_vnni
```

# Machine 2 Spec - Laptop

```
stephen@stephen-Swift-SF314-510G:~/dv/OneAPI-Package-1/LAMMPS$ lscpu
Architecture:
                                 x86 64
                                 32-bit. 64-bit
CPU op-mode(s):
                                 Little Endian
Byte Order:
Address sizes:
                                 39 bits physical, 48 bits virtual
CPU(s):
On-line CPU(s) list:
                                 0-7
Thread(s) per core:
Core(s) per socket:
Socket(s):
NUMA node(s):
Vendor ID:
                                 GenuineIntel
CPU family:
Model:
                                 11th Gen Intel(R) Core(TM) i5-1135G7 @ 2.40GHz
Model name:
```

```
u58345@s011-n001:~/ILDevCON/lammps-offload-OneAPI/LAB3/1-Model-Offload$ lspci | grep VGA 1c:00.0 VGA compatible controller: Intel Corporation Device 4905 (rev 01) 6a:00.0 VGA compatible controller: Intel Corporation Device 4905 (rev 01)
```

Graphics processor table				
PCI IDs	Name	Architecture	Codename	
4905	Intel® Iris® Xe MAX Graphics	Xe	DG1	





Analyze



# Goal of Analysis





1. Find the 'hot spots'

2. if possible, predict benefit of offloading

# APS – (Application Performance Snapshot)

# Three Tools

Advisor - model offloading

VTune - Profiler

APS – (Application

Run a GPU Offload (Preview) or a GPU Compute/Media Hotspots (Preview) analysis with VTune Profiler to discover how to better utilize the GPU.

Performance Snapshot)

Tuning Potential

Ħ

#### **Application Performance Snapshot**

Report creation date: 2021-09-23 06:58:02 Number of ranks: 16 Ranks per node: 16

HW Platform: Intel(R) microarchitecture code named Tigerlake

Frequency: 2.42 GHz

Logical Core Count per node: 8

Collector type: Event-based sampling driver, Event-based counting driver

1.43 2.88 GHz

0.06 s GPU

Virtual Per Node

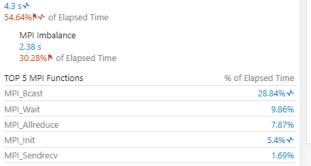
42338 MB

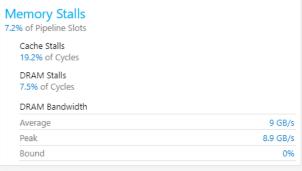
SP GFLOPS DP GFLOPS Average CPU Frequency

MPI Time

GPU Utilization when Busy 3.6%	
EU State	% of EUs
Active	3.6%
Idle	83%№
Stalled	13.4%
GPU Occupancy 9.1% of Peak Value	

#### **Memory Footprint** Resident 113.19 MB Resident per Node 1811 MB Virtual 2646.12 MB





54.64% № <10%

<20%

0% ▶ >70%

3.6% > >80%

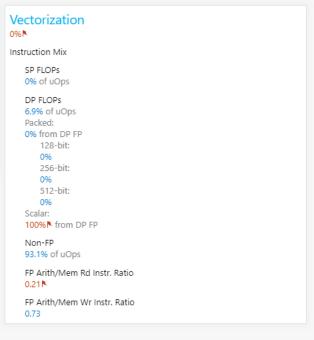
7.2%

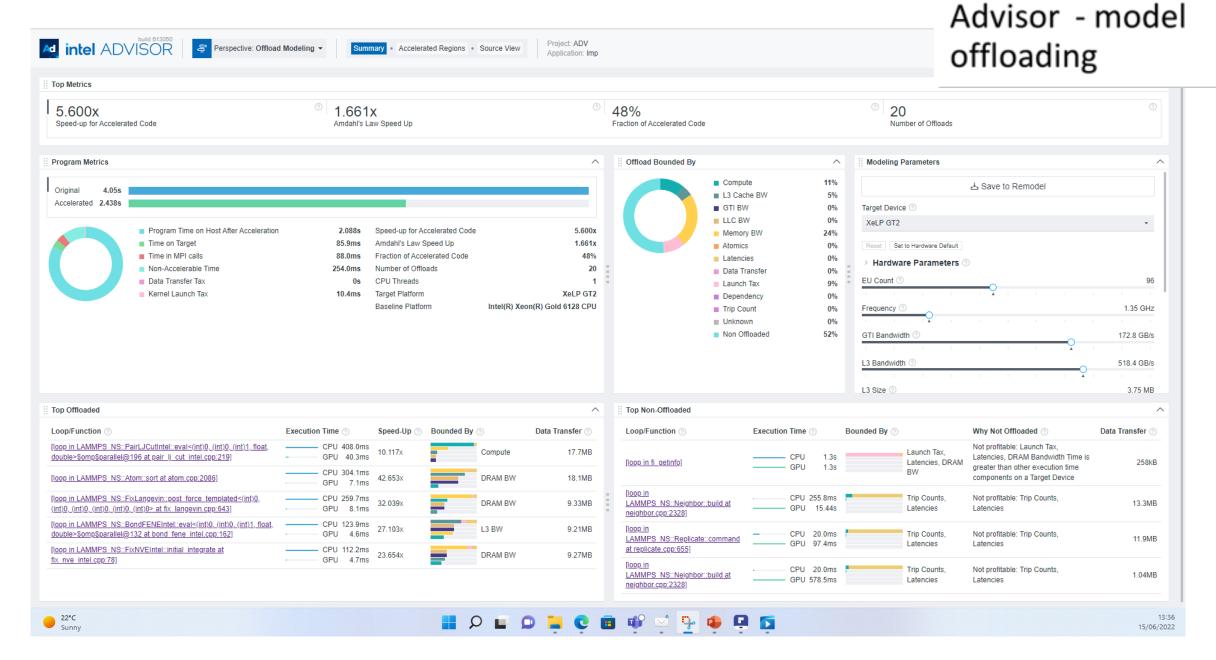
Your application may underutilize the GPU.

MPI Time

Memory Stalls Vectorization

GPU Utilization when Busy





## Steps to Offload Projection with Advisor

1. Run a **Survey**: get a list of hotspots

advisor -collect survey

- Sampling
- Binary Static Analysis
- Compiler & debug info

Run a **Trip Count**: count loop iteration

advisor -collect=tripcounts -target-device=gen9 gt2

- Trip count
- Cache simulation
- Perform a dependency analysis [optional for quick modelling]

advisor -collect dependencies . . .

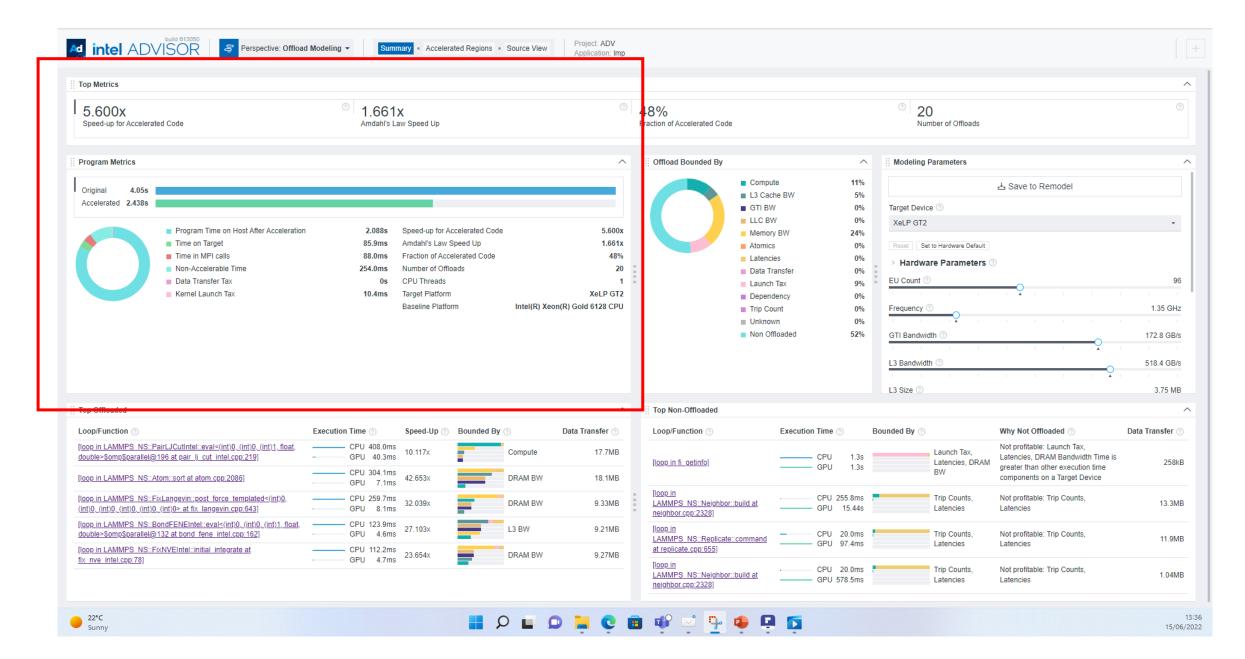
- Check memory accesses
- Loop selection heuristic

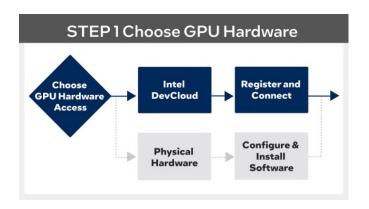
**4. Model** the Performance

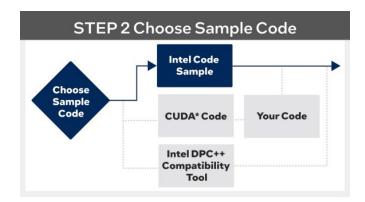
advisor -collect projection (-no-assume-dependencies). . .

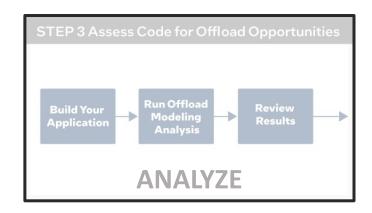
Generate HTML report

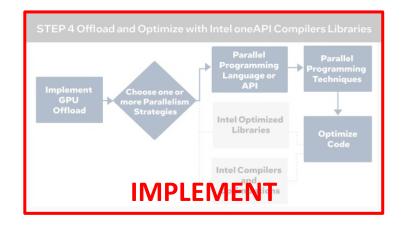
Expensive Steps

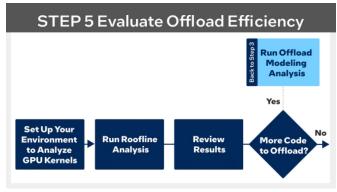


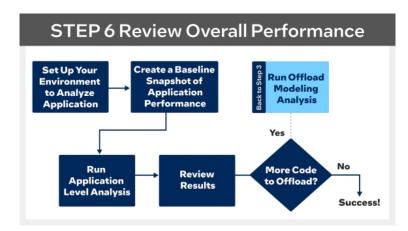












https://www.intel.com/content/www/us/en/developer/tools/oneapi/gpu-optimization-workflow.html

## TWO TYPES OF COMPILER

CLASSIC [Same as was in Parallel Studio]

Deprecated and will be removed from product release in the second half of 2023 icc

icpc

ifort

Offloading not supported

**LLVM** based [Totally new compilers]

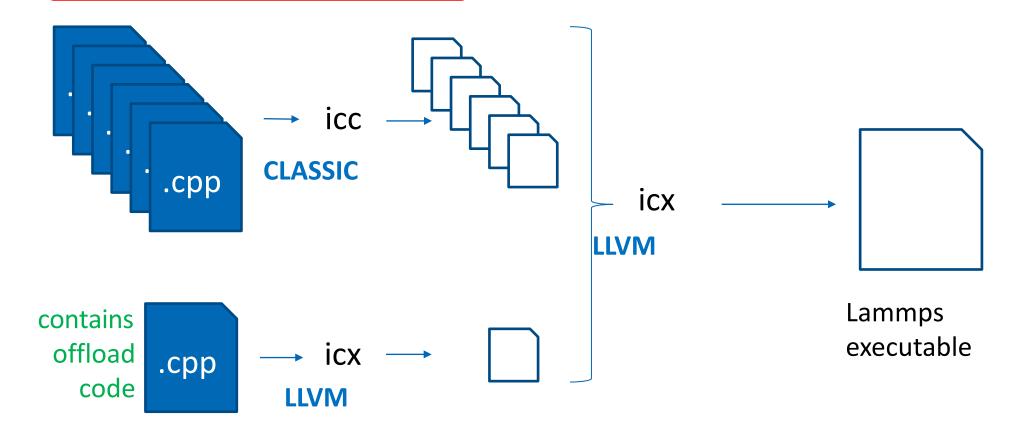
- icx
- dpcpp
- ifx

Offloading supported

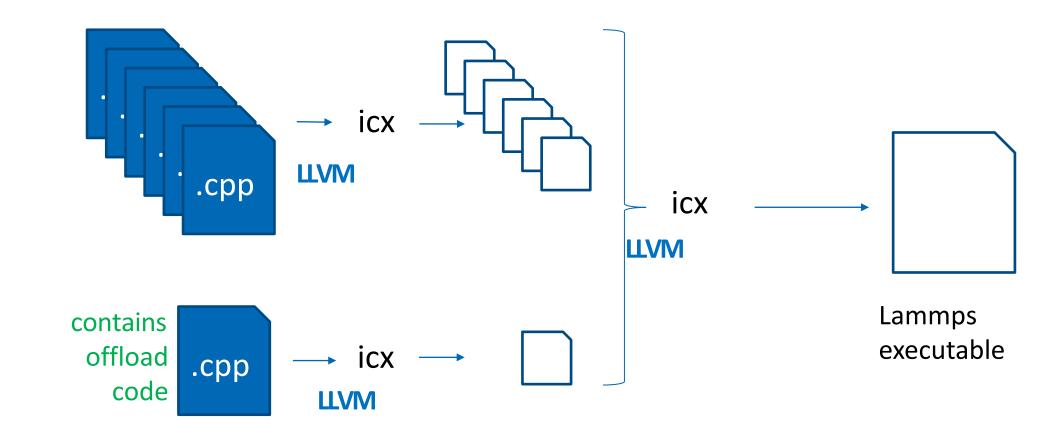
All objects are binary compatible

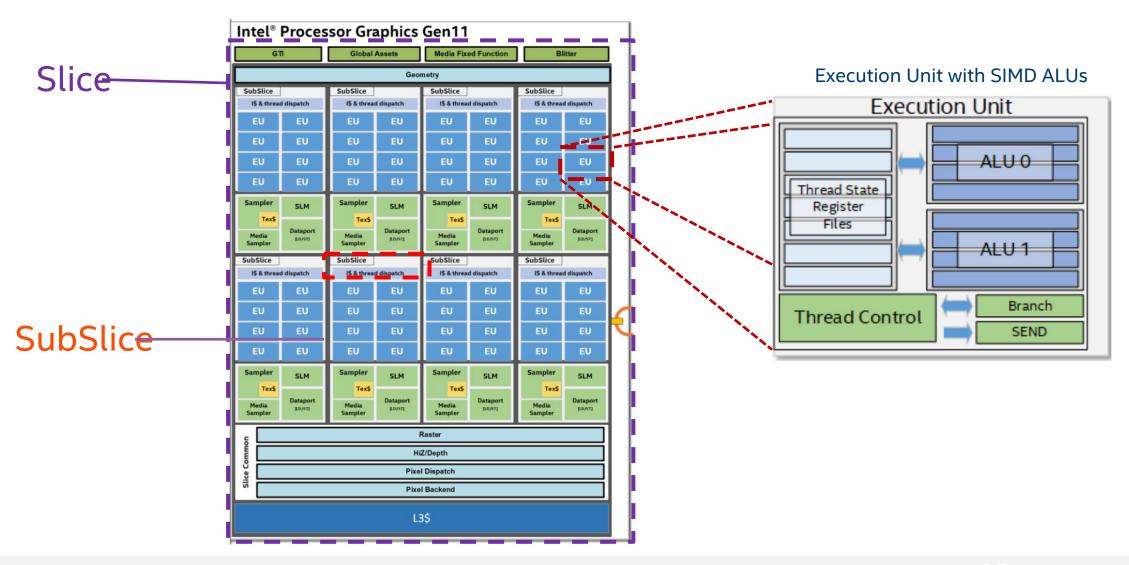
# One approach...

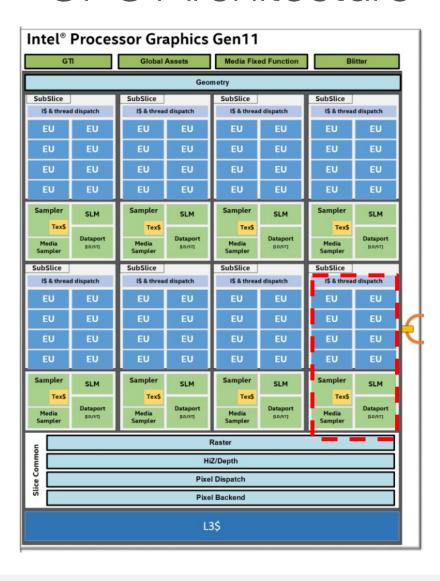
NB: icc deprecated mid 2023

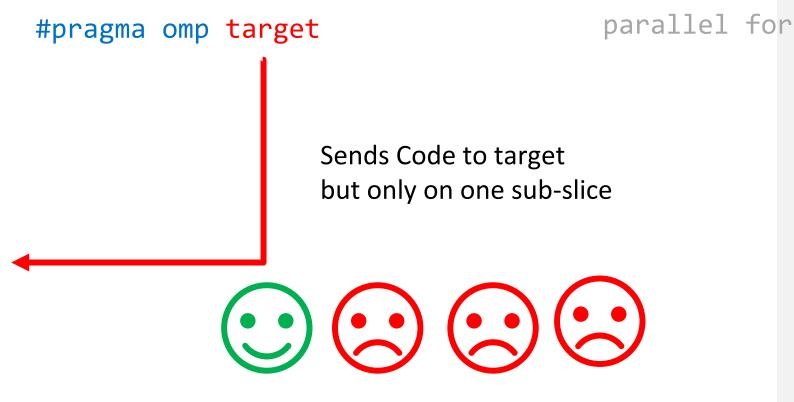


# ... or alternatively







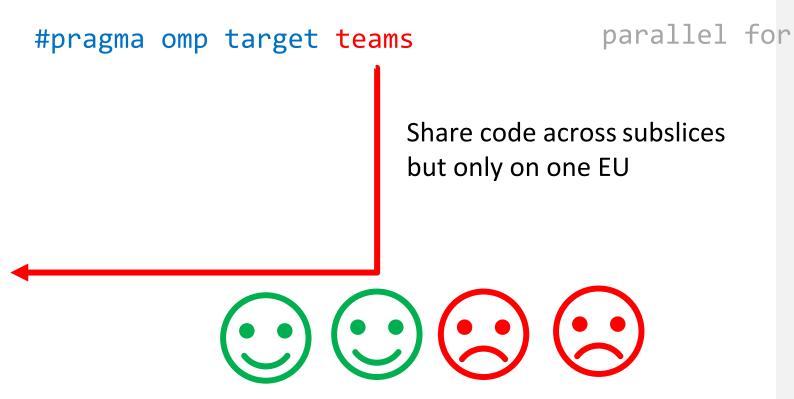


# OpenMP GPU Offload and OpenMP Constructs

- OpenMP GPU offload support all "normal" OpenMP constructs
  - E.g. parallel, for/do, barrier, sections, tasks, etc.
  - Not every construct will be useful

- Full threading model outside of a single GPU subslice not supported
  - No synchronization among subslices
  - No coherence and memory fence between among subslice L1 caches







#pragma omp target teams distribute parallel for

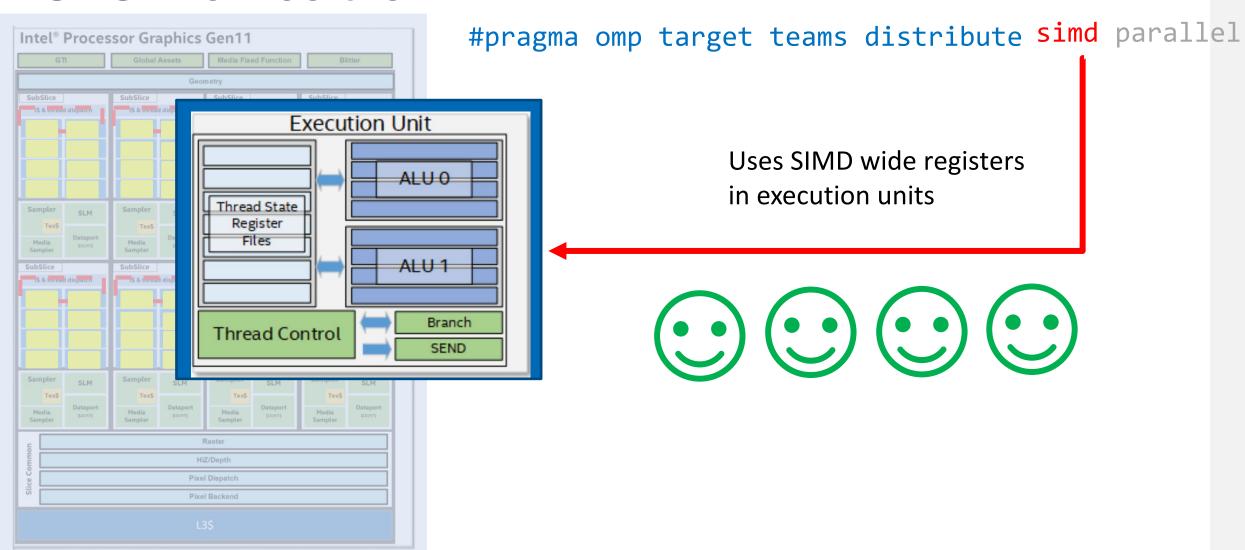
Distributes loop iterations across all EUs











# Experiment in Lammps - Target

```
#if 1
     #pragma omp target map(to:ilist[iifrom:iito]) \
                        map(to:x[x min:x max]) \
                        map(tofrom:f[f min:f max]) \
                        map(from:ev global[0:7]) \
                        map (tofrom:lj1,lj2,lj3,lj4,offset)
     #pragma omp teams distribute parallel for
 #endif
        ----- END SBC code ------
      for (int ii = iifrom; ii < iito; ii += iip) {</pre>
        const int i = ilist[ii];
        int itype, ptr off;
        const FC PACKED1 T * noalias ljc12oi;
        const FC PACKED2 T * noalias lj34i;
        if (!ONETYPE) {
         itype = x[i].w;
          ntr off = itvne * ntvnes:
```

54 intel

# Experiment in Lammps –Indirect Indexes

```
Start here | *pair lj cut intel.cpp | *
                      ----- SBC code ------
         223
         224
                       // find min an max of indirect indexes
         225
                       int i min=0:
         226
                       int i max=0;
        227
                       int jlist min=0;
        228
                       int jlist max=0;
        229
                       int j min =0;
        230
                       int j max=0;
        231
                       int x min=0;
        232
                       int x max=0;
         233
                       int f min=0:
         234
                       int f max=0;
         235
         236
                       for (int ii = iifrom; ii < iito; ii += iip) {</pre>
         237
                        int i=0, itype=0, sbindex=0;
         238
         239
                        // get i min and i max
         240
                         i = ilist[ii];
         241
                         i min=std::min(i,i min);
         242
                         i max=std::max(i,i max);
         243
         244
                          const int * noalias const jlist = firstneigh[i];
        245
        246
                         int jnum = numneigh[i];
        247
                         // we also need the j min and j max as this is used in x[j]
         248
                         for (int jj = 0; jj < jnum; jj++) {</pre>
         250
                          int j=0, jtype=0, sbindex=0;
         251
                           if (!ONETYPE) {
         252
                            sbindex = jlist[jj] >> SBBITS & 3;
                            j = jlist[jj] & NEIGHMASK;
         253
         254
         255
                             j = jlist[jj];
        256
         257
                            j min=std::min(j,j min);
         258
                            i max=std::max(j,j max);
         259
         260
         261
                       x min = f min = std::min(i min,j min);
         262
                       x max = f max = std::max(i max,j max);
         263
         264
        265
        266
                       #endif
        267
                   #endif
         268
         269
                       #pragma omp target map(to:ilist[iifrom:iito]) \
evCon/lammps-offload-OneAPI/LAB2/6-ICX-PATCHED/pair lj cut intel.cpp
                                                                                   C/C++
```

```
// we also need the j min and j max as this
 for (int jj = \theta; jj < jnum; jj++) {
   int j=0, jtype=0, sbindex=0;
   if (!ONETYPE)
     sbindex = jlist[jj] >> SBBITS & 3;
     j = jlist[jj] & NEIGHMASK;
    } else
      j = jlist[jj];
    j min=std::min(j,j min);
    i max=std::max(j,j max);
x min = f min = std::min(i min,j min);
x max = f max = std::max(i max,j max);
```