

Simulation Engines for Maintenance Events in Heterogeneous Machines

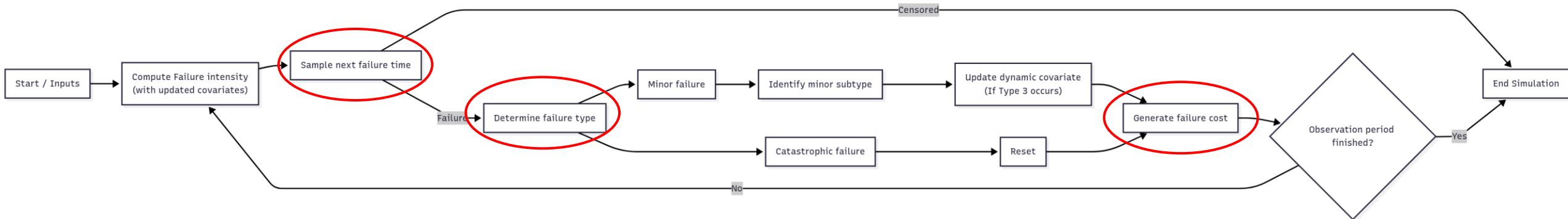
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A virtual laboratory for reliability research and practice

We have two versions of the simulation engine: maintenance can be time-based or condition-based

	Time-based maintenance (TBM)	Condition-based maintenance (CBM)
Focus	Failure & maintenance events	Degradation process
Model basis	Failure intensity models (e.g., NHPP)	Stochastic degradation models
Feature dependency	Hazard intensity adjusted by covariates	Degradation increments affected by covariates
PM requirement	Time based PM interval	PM policy (threshold based/time based)
Outputs	Failure/maintenance time, type, cost	Degradation paths, event log

Architecture of the Simulation Framework: The TBM simulation engine generates historical maintenance logs given periodic maintenance policy



Setup

Number of machines
Observation time & discretization

Failure process models

Failure intensity

Maintenance policy

PM interval & effectiveness

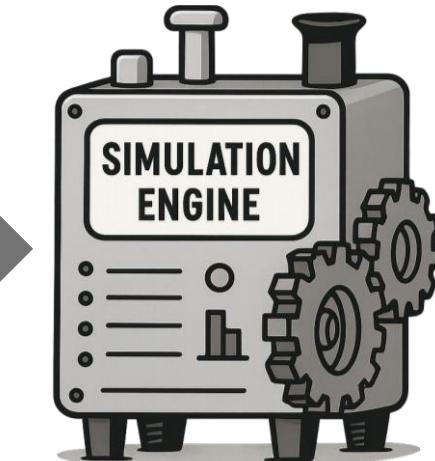
Machine heterogeneity

$$X(t) = (x_1, x_2, \dots, x_n, x_{n+1}(t), x_{n+2}(t), \dots)$$

Fixed covariates Dynamic covariates

Cost structure

Failure cost + PM cost
(Parameters for gamma)



Event identification

Machine id
censor status

Event time

Failure time
PM time

Event type

PM; Catastrophic failure;
Minor failure 1, 2, 3

\$ Event cost

Configurable inputs of the TBM simulation engine

Setup

```
results_df, all_machines_dynamic_covs = simulate_all_machines(n_machines, t_obs, m, n_dynamic_features, delta_t,
    #Preventive maintenance interval for each machine and PM effectiveness parameter ("push")
    T_machines, push, )
```

Maintenance policy

```
#Failure process
```

```
include_minor, model_type_minor, shape_minor, scale_minor, intercept_minor, with_covariates_minor,
```

```
include_catas, model_type_catas, shape_catas, scale_catas, intercept_catas, with_covariates_catas,
```

```
# Machine heterogeneity
```

```
fixed_covs, machines_dynamic_covs, beta_fixed, beta_dynamic, beta_multinom_fixed, beta_multinom_dynamic,
```

```
n_minor_types, cov_update_fn,
```

```
# cost-related (lists for minor types)
```

```
gamma_coeffs_cat_fixed, gamma_coeffs_cat_dynamic,
```

```
gamma_coeffs_minor_fixed_list, gamma_coeffs_minor_dynamic_list,
```

```
theta_copula,
```

```
shape_cat, scale_cat, loc_fixed_cat,
```

```
shape_minor_list, scale_minor_list, loc_fixed_minor_list,
```

```
use_covariates, minor_combo_map,
```

```
# PM cost
```

```
gamma_coeffs_pm_fixed, gamma_coeffs_pm_dynamic, shape_pm, scale_pm, loc_fixed_pm)
```

Failure process
models

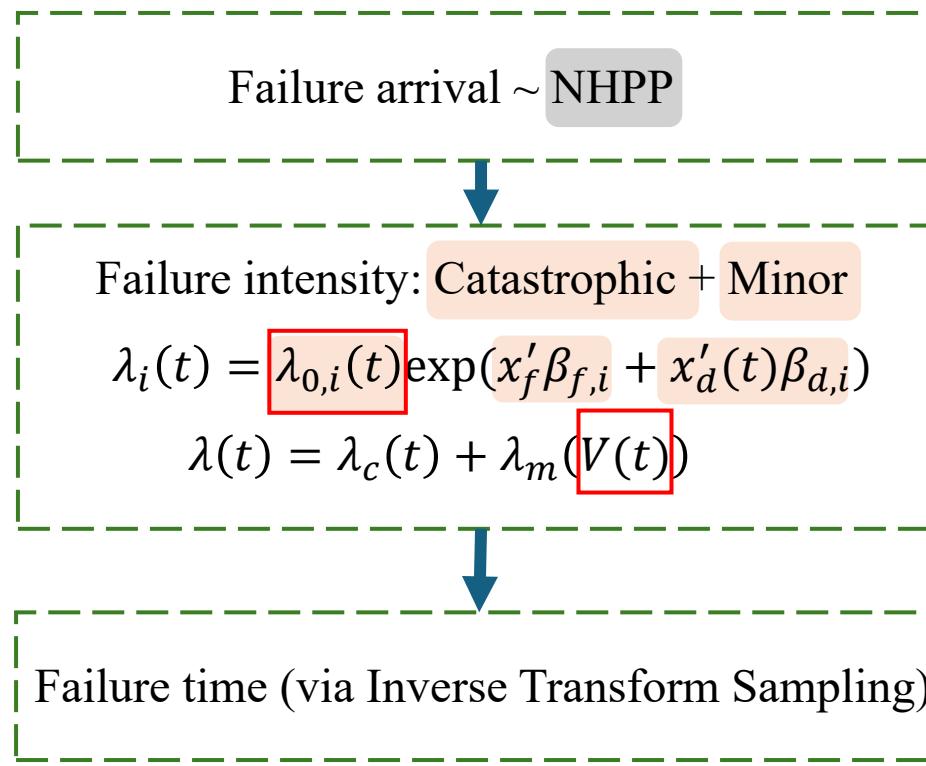
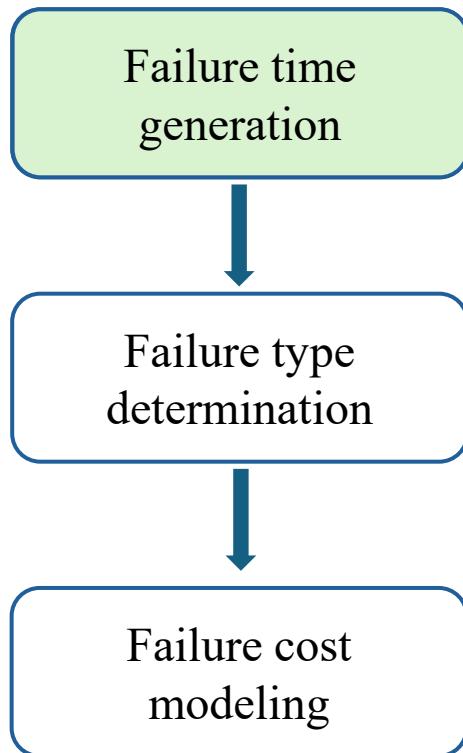
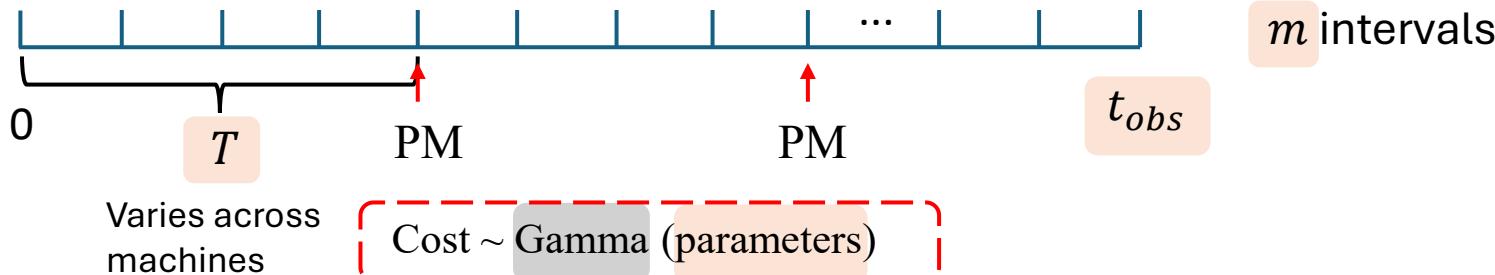
Machine heterogeneity

Cost structure

Refer to

`run_tbm_example.py`

III The TBM engine generates failure times for machines with individual PM intervals



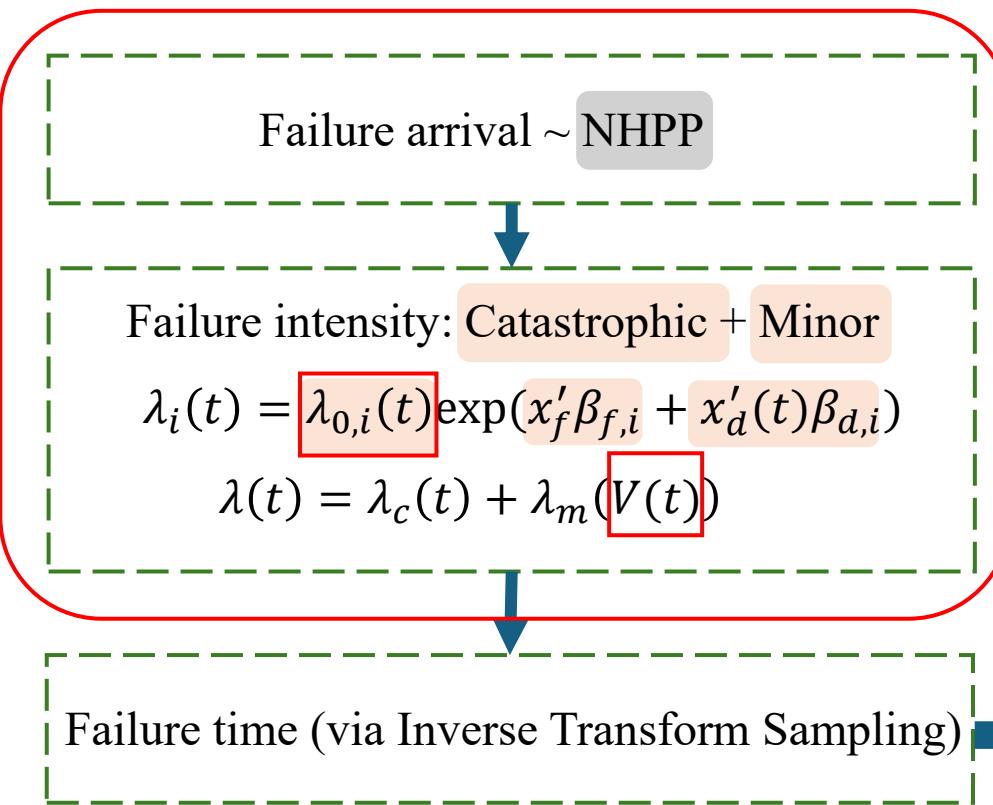
Linear, log-linear, Weibull

PM resets virtual age

$$V(t) = (t \bmod T) + (1 - k_{\lambda_0}) \cdot T \cdot \lfloor t/T \rfloor$$

The graph shows a sawtooth wave starting at 0 and ending at 1, with vertical asymptotes at $t = k_{\lambda_0}T$ and $t = (k_{\lambda_0}+1)T$.

Code for failure time generation under machine-specific PM policies



```
1     """
2     Hazard function implementations for failure intensity modeling.
3
4     This module contains:
5     - lambda_f: Unified hazard function for both minor and catastrophic failures
6     - integrated_lambda_closed: Closed-form cumulative hazard
7     - integrated_lambda_numeric: Numerical integration of hazard
8     - compute_cumulative_integrals: Update cumulative integrals
9     """
10
11    import numpy as np
12    from scipy.integrate import quad
13
14
15    def lambda_f(
16        machine_id, t, pm_affects=True, T=None, push=0.0, scale=None, intercept=None, shape=None,
17        fixed_covs=None, dynamic_cov_t=None, beta_fixed=None, beta_dynamic=None,
18        model_type="weibull", with_covariates=True
19    ):
20        """
21        Failure time generation module.
22
23        This module contains the getFailureTime function that determines when
24        failures occur based on cumulative hazard functions.
25        """
26
27
28    import numpy as np
29    from .hazard import compute_cumulative_integrals
30
31
32    def getFailureTime(
33        s, cumulative_integrals_minor, cumulative_integrals_catas, cumulative_integrals,
34        dynamic_covs_changed, machine_id, valid_indices, m, delta_t,
35        # Minor failure parameters
36        include_minor=True,
37        model_type_minor="linear", shape_minor=None, scale_minor=None, intercept_minor=None,
38        fixed_covs=None, dynamic_covs=None, beta_fixed=None, beta_dynamic=None,
39        with_covariates_minor=True, T=None, push=0.0,
40        # Catastrophic failure parameters
41        include_catas=True,
42        model_type_catas="linear", shape_catas=None, scale_catas=None, intercept_catas=None,
43        with_covariates_catas=False
44    ):
```

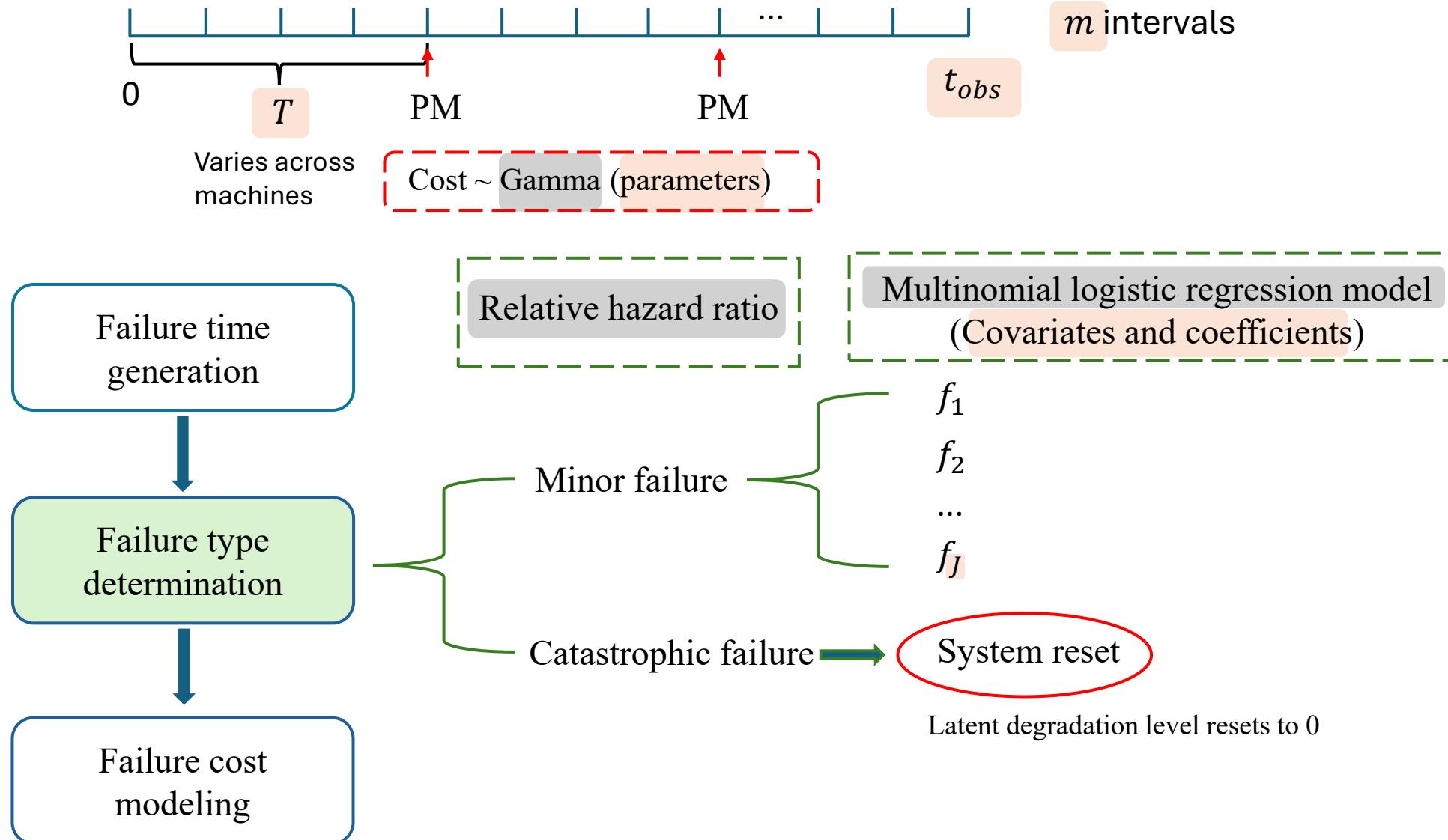
Refer to

time_based/hazard.py

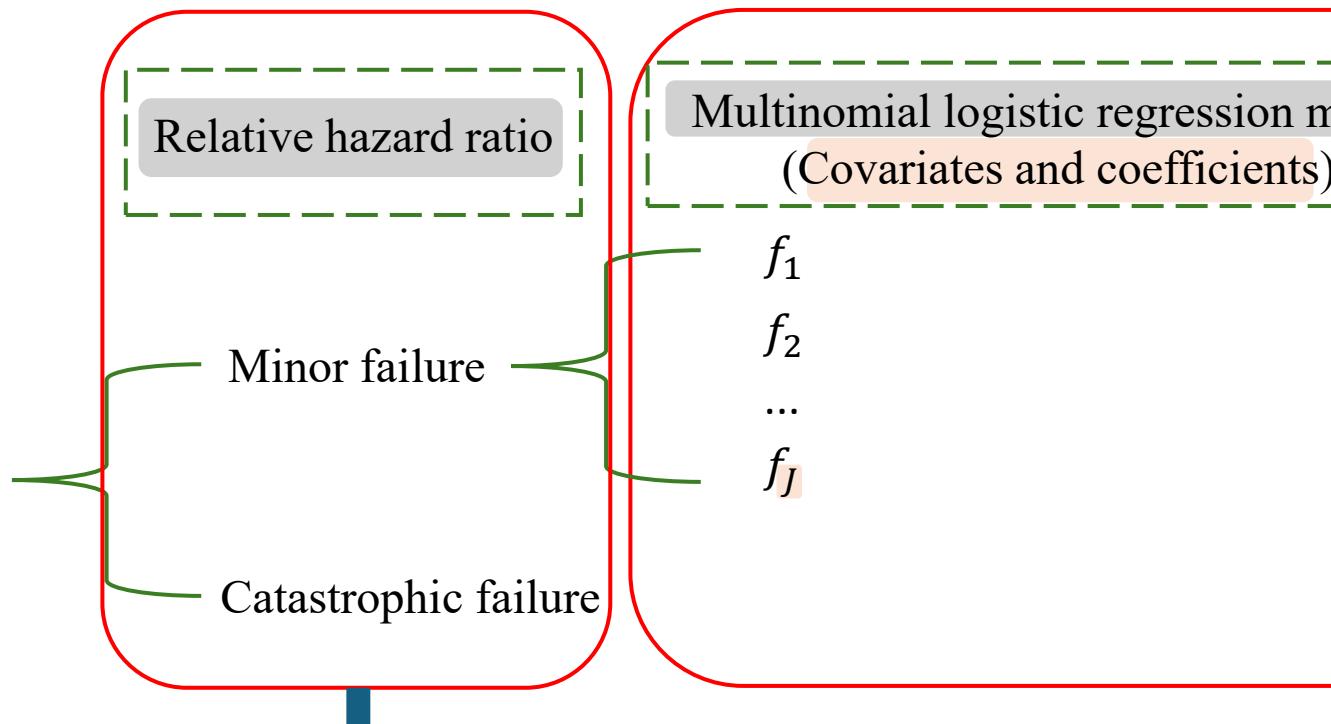
Refer to

time_based/failure_time.py

The TBM engine determines the failure type using covariate-driven competing risks and multinomial logistic models



Code for failure type determination

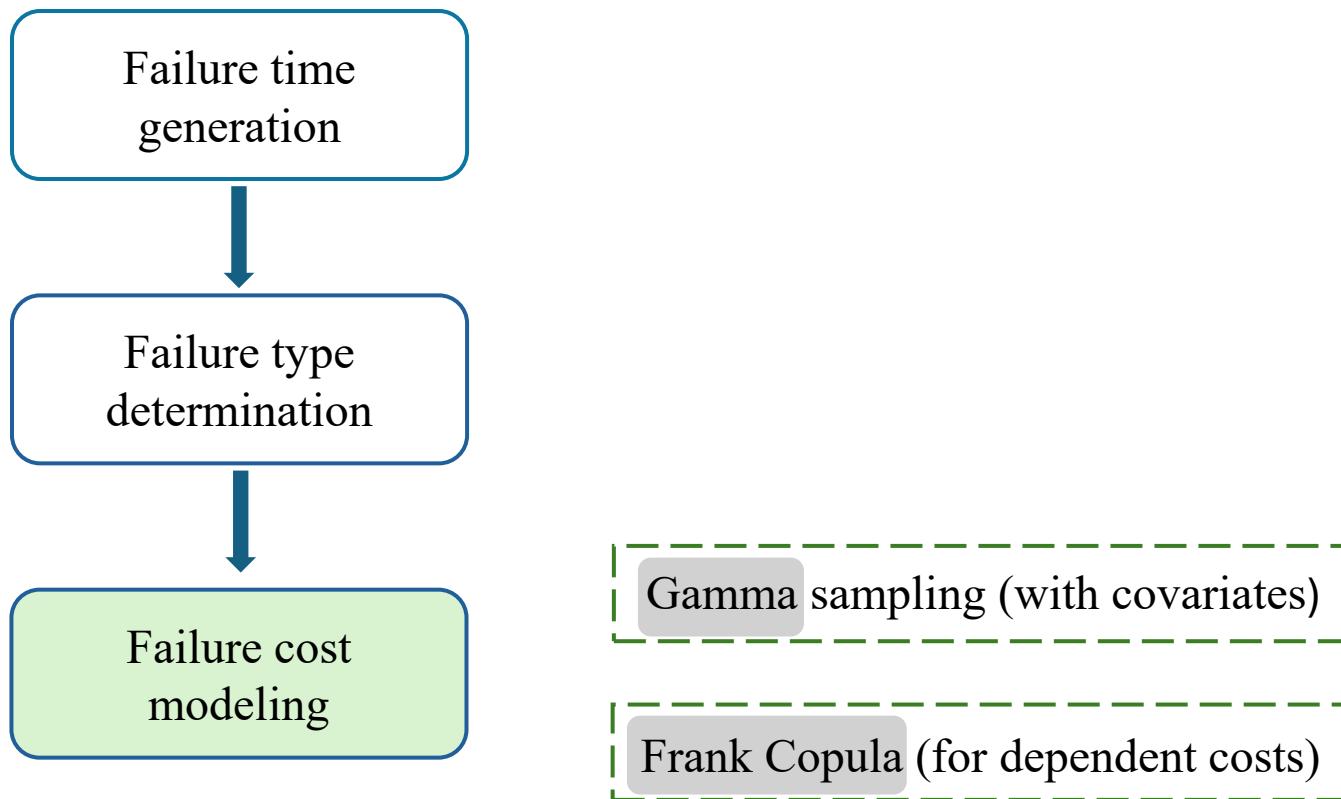
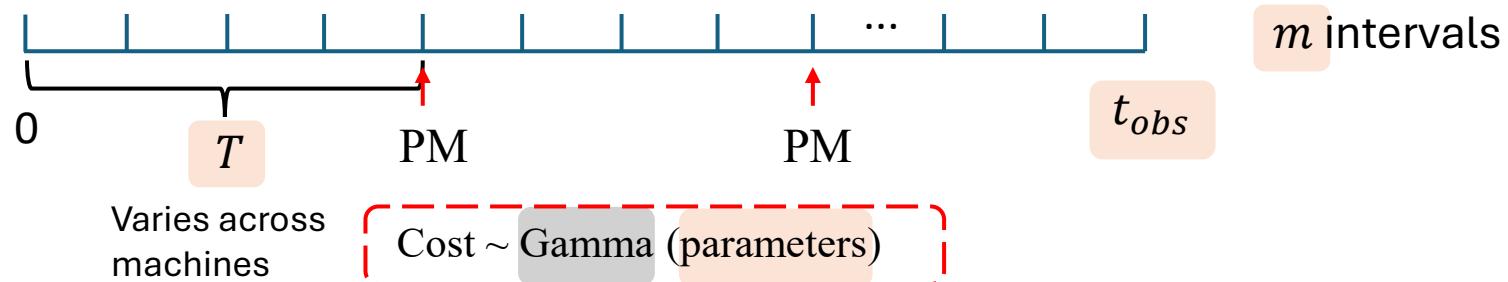


```
def get_failure_type(  
    machine_id, ft, T, push, scale, intercept, shape, with_covariates_minor, model_type_minor,  
    fixed_covs, dynamic_cov_t, beta_fixed, beta_dynamic,  
    scale_c, shape_c, intercept_c, model_type_catas, with_covariates_catas  
):  
    """  
    Determine whether failure at time ft is minor or catastrophic  
    """
```

Refer to [time_based/failure_type.py](#)

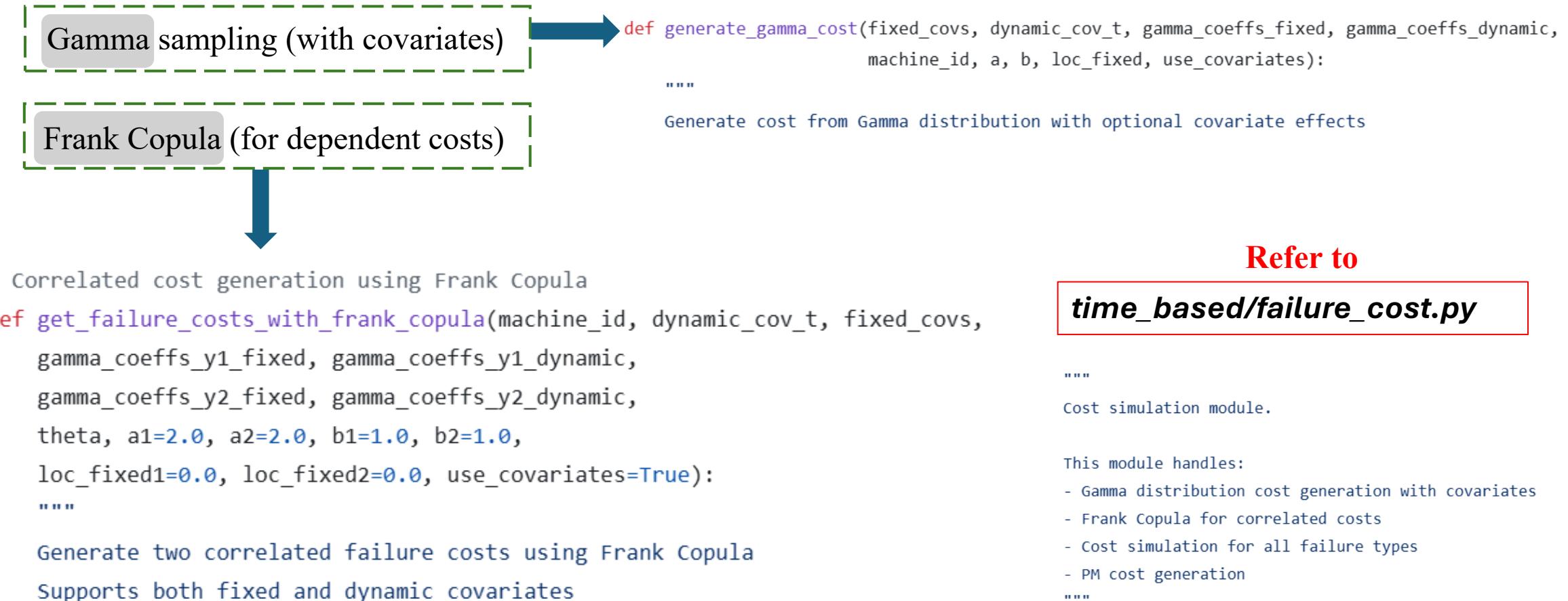
```
def get_minor_failure_type(  
    machine_id, beta_multinom_fixed, beta_multinom_dynamic,  
    fixed_covs, dynamic_cov_t, n_minor_types  
):  
    """  
    Sample minor failure subtype using multinomial logistic regression with covariates  
  
    Parameters:  
    -----  
    machine_id : int  
        Machine identifier  
    beta_multinom_fixed : array-like  
        Fixed covariate coefficients, shape (n_fixed_features, n_minor_types-1)  
    beta_multinom_dynamic : array-like  
        Dynamic covariate coefficients, shape (n_dynamic_features, n_minor_types-1)  
    fixed_covs : array-like  
        Fixed covariates for all machines, shape (n_machines, n_fixed_features)  
    dynamic_cov_t : array-like  
        Dynamic covariates at current time, shape (n_dynamic_features,)  
    n_minor_types : int  
        Number of minor failure types  
  
    Returns:  
    -----  
    int : Minor failure subtype (1 to n_minor_types)  
    """
```

The TBM Engine models failure costs using covariate-dependent gamma



Parameters

Code for failure costs modelling



Refer to

time_based/failure_cost.py

"""
Cost simulation module.

This module handles:
- Gamma distribution cost generation with covariates
- Frank Copula for correlated costs
- Cost simulation for all failure types
- PM cost generation
"""

Flow of multi-machine simulation in the TBM engine

"""
Main simulation orchestration module.

This module contains the high-level simulation functions:

- simulate_single_cycle: Simulate from AGAN state to failure or observation end
 - simulation_complete_observed_period: Handle catastrophic resets
 - simulate_machine_full_observed_period: Complete machine simulation with costs
 - simulate_all_machines: Multi-machine simulation
- """

```
def simulate_all_machines(n_machines, t_obs, m, n_dynamic_features, delta_t, T_machines, push,
                           include_minor, model_type_minor, shape_minor, scale_minor, intercept_minor, with_covariates_minor,
                           include_catas, model_type_catas, shape_catas, scale_catas, intercept_catas, with_covariates_catas,
                           fixed_covs, machines_dynamic_covs, beta_fixed, beta_dynamic, beta_multinom_fixed, beta_multinom_dynamic,
                           n_minor_types, cov_update_fn,
                           # cost-related (lists for minor types)
                           gamma_coeffs_cat_fixed, gamma_coeffs_cat_dynamic,
```

for machine_id in range(1, n_machines + 1): Loop over machines

```
    T = T_machines[machine_id]
```

```
    # Get the per-machine initial dynamic covariates
```

```
    dynamic_covs = machines_dynamic_covs.get(machine_id) if machines_dynamic_covs else None #initial dynamic covs
```

Run single-machine simulation **Simulate one machine**

```
    df_failures, machine_dynamic_covs, pm_index, pm_times, pm_costs = simulate_machine_full_observed_period(
        t_obs, machine_id, m, n_dynamic_features, delta_t, T, push,
```

Aggregate all machines

Aggregate results

```
    final_df = pd.concat(all_results, ignore_index=True)
```

Refer to

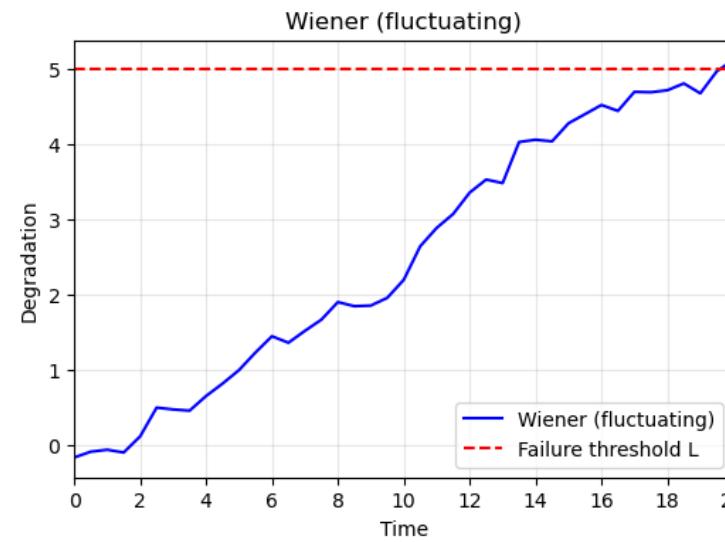
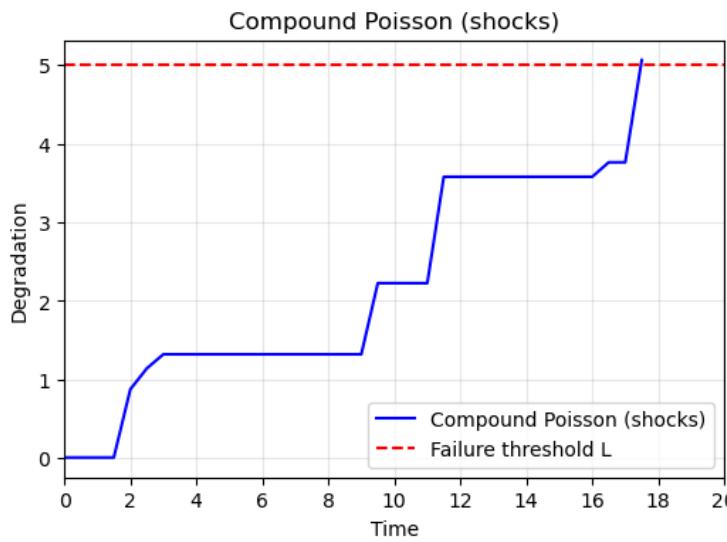
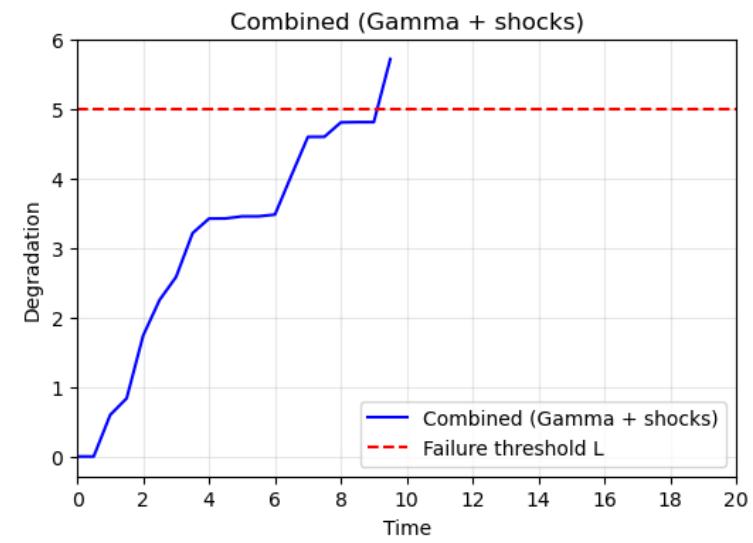
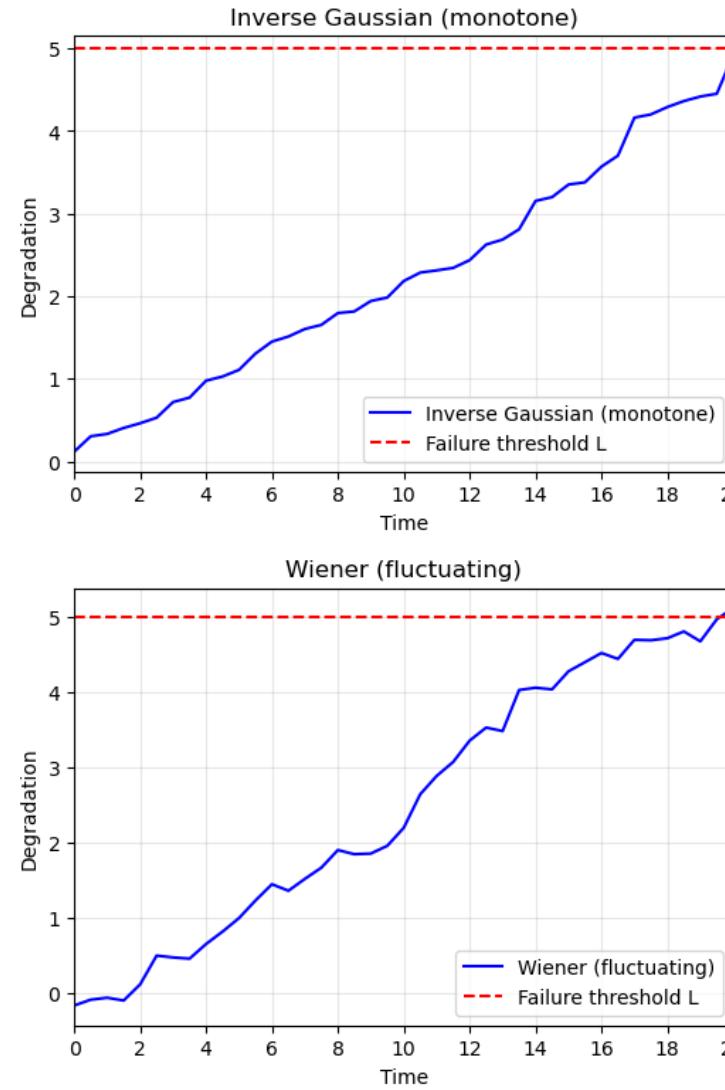
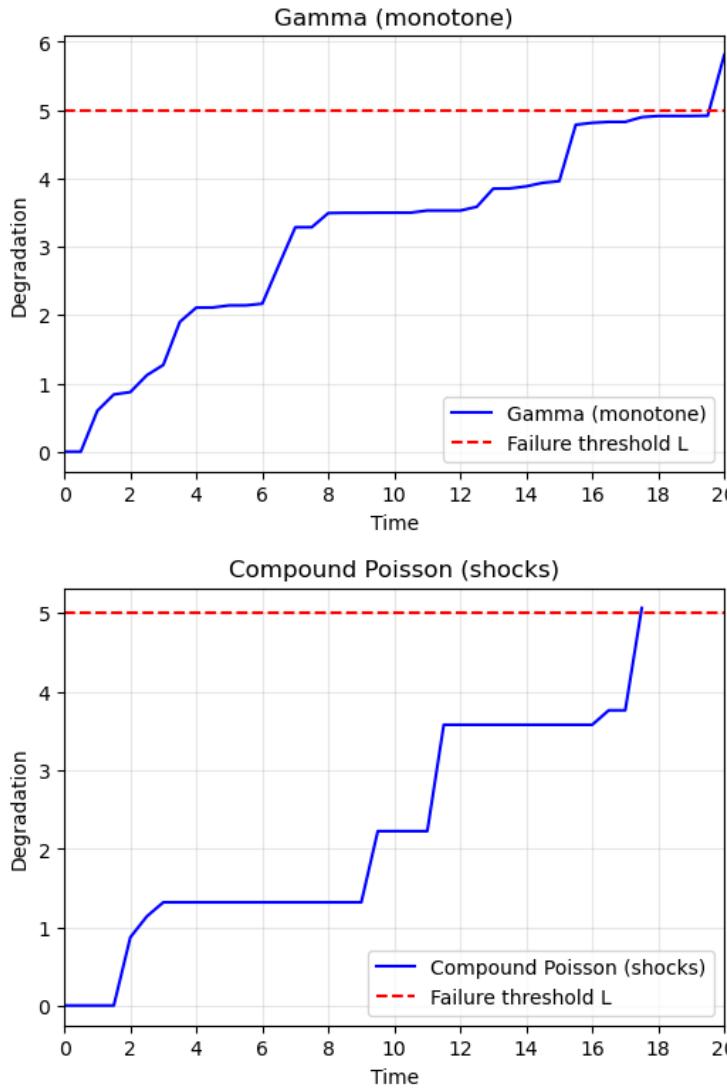
time_based/simulation.py

The result is a log table with maintenance event data and its feature values

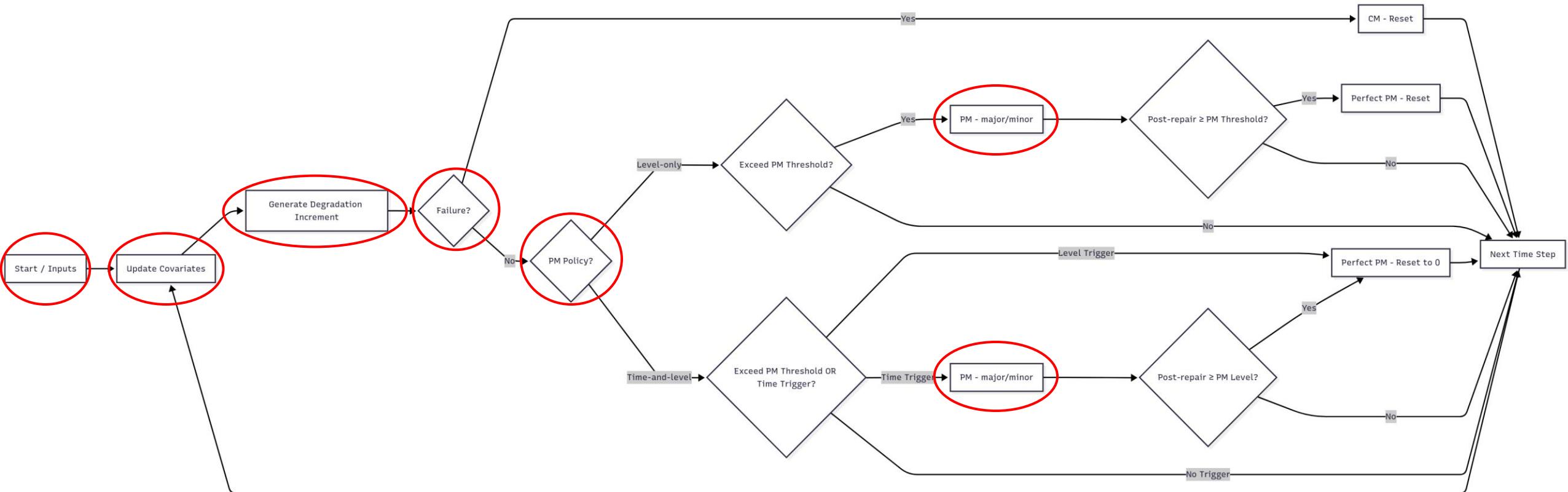
machine_id	event_time	event_type	censor_status	event_cost	fixed_cov_1	fixed_cov_2	fixed_cov_3	fixed_cov_4	dynamic_cov_1_at_event	
0	1	0.910	f_2	1	68.763955	1.0	1.0	0.0	1.0	0.0
1	1	1.000	pm	1	60.465617	1.0	1.0	0.0	1.0	0.0
2	1	1.105	f_2	1	124.086685	1.0	1.0	0.0	1.0	0.0
3	1	2.000	pm	1	59.990668	1.0	1.0	0.0	1.0	0.0
4	1	3.000	pm	1	45.915114	1.0	1.0	0.0	1.0	0.0
5	1	4.000	pm	1	54.933842	1.0	1.0	0.0	1.0	0.0
6	1	4.300	c	1	410.878490	1.0	1.0	0.0	1.0	0.0
7	1	5.000	pm	0	165.807104	1.0	1.0	0.0	1.0	0.0
8	2	0.525	f_1	1	150.726853	0.0	0.0	1.0	0.0	0.0
9	2	1.000	pm	1	45.336625	0.0	0.0	1.0	0.0	0.0
10	2	2.000	pm	1	33.130589	0.0	0.0	1.0	0.0	0.0
11	2	2.865	f_2	1	88.565947	0.0	0.0	1.0	0.0	0.0
12	2	3.000	pm	1	48.741522	0.0	0.0	1.0	0.0	0.0
13	2	3.665	f_3	1	91.236713	0.0	0.0	1.0	0.0	1.0
14	2	3.750	f_1	1	314.555790	0.0	0.0	1.0	0.0	1.0
15	2	4.000	pm	1	80.021697	0.0	0.0	1.0	0.0	1.0
16	2	4.360	f_1	1	204.948800	0.0	0.0	1.0	0.0	1.0
17	2	4.385	f_1	1	346.866142	0.0	0.0	1.0	0.0	1.0
18	2	4.440	f_2	1	90.656132	0.0	0.0	1.0	0.0	1.0
19	2	4.585	f_2	1	80.993307	0.0	0.0	1.0	0.0	1.0
20	2	4.935	f_1	1	133.096948	0.0	0.0	1.0	0.0	1.0
21	2	5.000	pm	0	56.546781	0.0	0.0	1.0	0.0	1.0



The CBM engine makes use of degradation paths



Architecture of the Simulation Framework: Condition-based maintenance events are generated based on the degradation paths



The simulation engine generates historical degradation paths and maintenance logs based on user-specified inputs

Setup

Number of machines
Observation time & discretization

Degradation process

Parameter adjustment

- Compound Poisson
 $\lambda(t) = \lambda_0 \exp(x_f' \beta_f + x_d'(t) \beta_d)$
 - Gamma
 - IG
 - Wiener
- $$\theta(t) = \theta_0 \exp(x_f' \beta_f + x_d'(t) \beta_d)$$

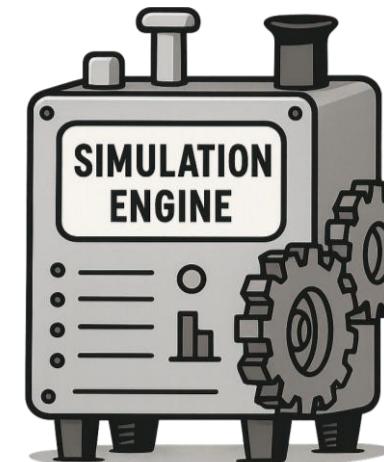
Maintenance policy

PM threshold (and PM time)
(level or time-and-level)
Repair strategy (major: p / minor: $(1 - p)$)

Machine heterogeneity

$$X(t) = (x_1, x_2, \dots, x_n, x_{n+1}(t), x_{n+2}(t), \dots)$$

Fixed covariates Dynamic covariates



Degradation path

Event identification

Machine id
censor status

Event time

Failure time
PM time

Event type

PM; CM

Configurable inputs of the CBM simulation engine

```
fleet_results['Scenario2_Gamma'] = simulate_multiple_machines(  
    n_machines=N_MACHINES,  
    degradation_type=scenario2_degradation_type,  
    degradation_params=scenario2_degradation_params,  
    covariate_specs=scenario2_covariates,  
    covariate_effects=scenario2_covariate_effects,  
    dt=DT,  
    PM_level=scenario2_pm_level,  
    PM_interval=scenario2_pm_interval,  
    L=L,  
    x0=x0,  
    repair_func=sample_post_repair_mixed,  
    repair_params=repair_params_shared,  
    obs_time=OBS_TIME,  
    random_seed_base=RANDOM_SEED_BASE + 1000,  
    noise=noise_params_shared,  
    cost_params=cost_params_shared,  
    cost_covariate_specs=cost_covariates_shared,  
    cost_covariate_effects=scenario2_cost_covariate_effects  
)
```

Setup

Degradation process

Machine heterogeneity

Maintenance policy

Cost structure

Refer to

`run_cbm_example.py`

Modeling degradation with PHM intensity and covariate-dependent increments

Refer to

condition_based/degradation.py

↳ Degradation process

Parameter adjustment

- Compound Poisson

$$\lambda(t) = \lambda_0 \exp(x_f' \beta_f + x_d'(t) \beta_d)$$

- Gamma
- IG
- Wiener

$$\theta(t) = \theta_0 \exp(x_f' \beta_f + x_d'(t) \beta_d)$$

```
✓ def compute_phm_intensity(
    base_intensity: float,
    covariates: np.ndarray,
    beta_coeffs: np.ndarray,
    t: float = None
) -> float:
    """

```

Compute Proportional Hazards Model (PHM) intensity function.

Formula: $\lambda(t|z(t)) = \lambda_0(t) \times \exp(\beta' z(t))$

🚜 Machine heterogeneity

$$X(t) = (x_1, x_2, \dots, x_n, x_{n+1}(t), x_{n+2}(t), \dots)$$

Fixed covariates Dynamic covariates

```
' def generate_degradation_increment_with_covariates(
    degradation_type: str,
    dt: float,
    params: Dict[str, Any],
    covariates: np.ndarray = None,
    covariate_effects: Dict[str, np.ndarray] = None
) -> float:
    """
    Generate degradation increment with covariate effects.

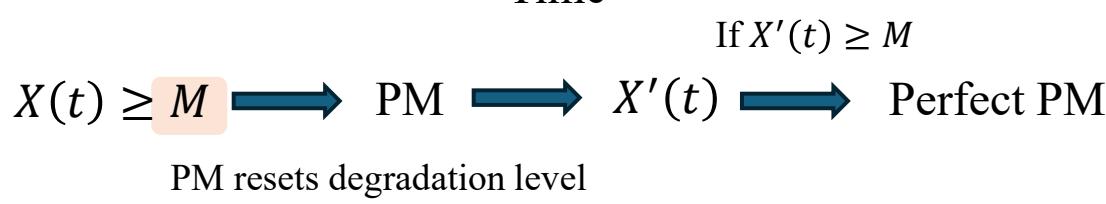
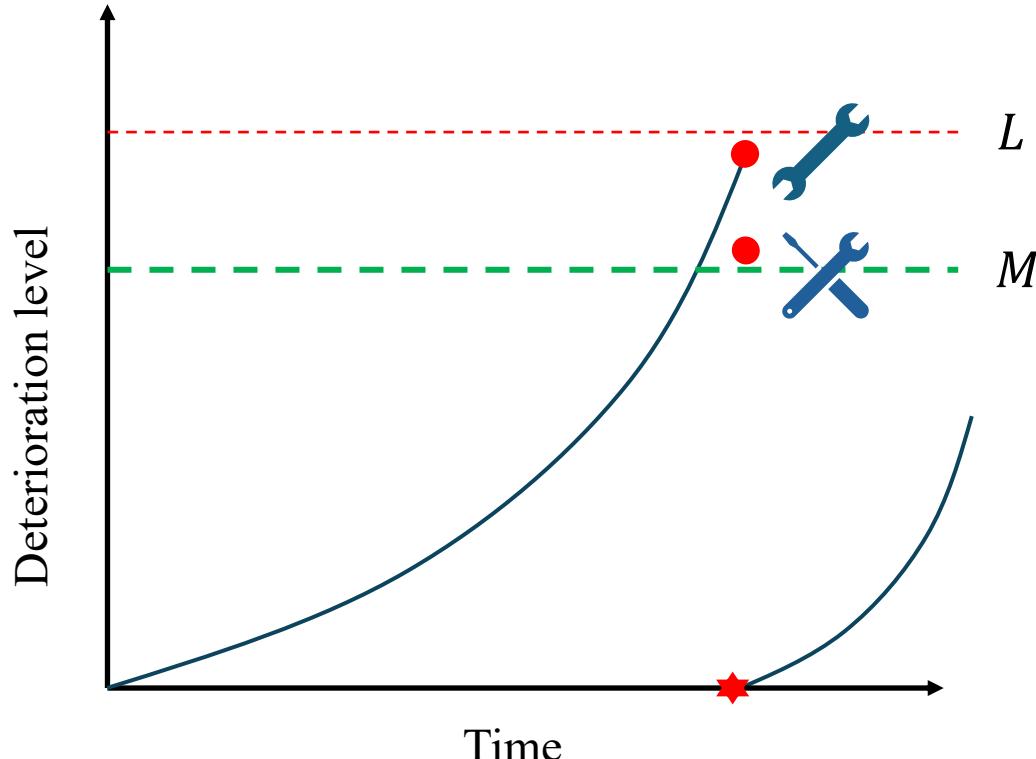
    Supports multiple stochastic processes:
    - gamma: Gamma process
    - inverse_gaussian: Inverse Gaussian process
    - wiener: Wiener process (Brownian motion with drift)
    - compound_poisson: Compound Poisson process with PHM for shock arrival
    - combined: Combination of base process and compound Poisson shocks

    def add_observation_noise(
        x: float,
        dt: float,
        noise: Optional[Dict[str, Any]]
    ) -> float:
        """
        Add observation noise to a scalar degradation level.

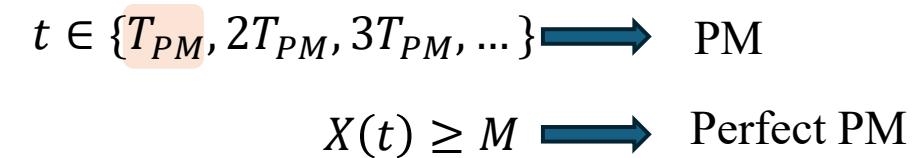
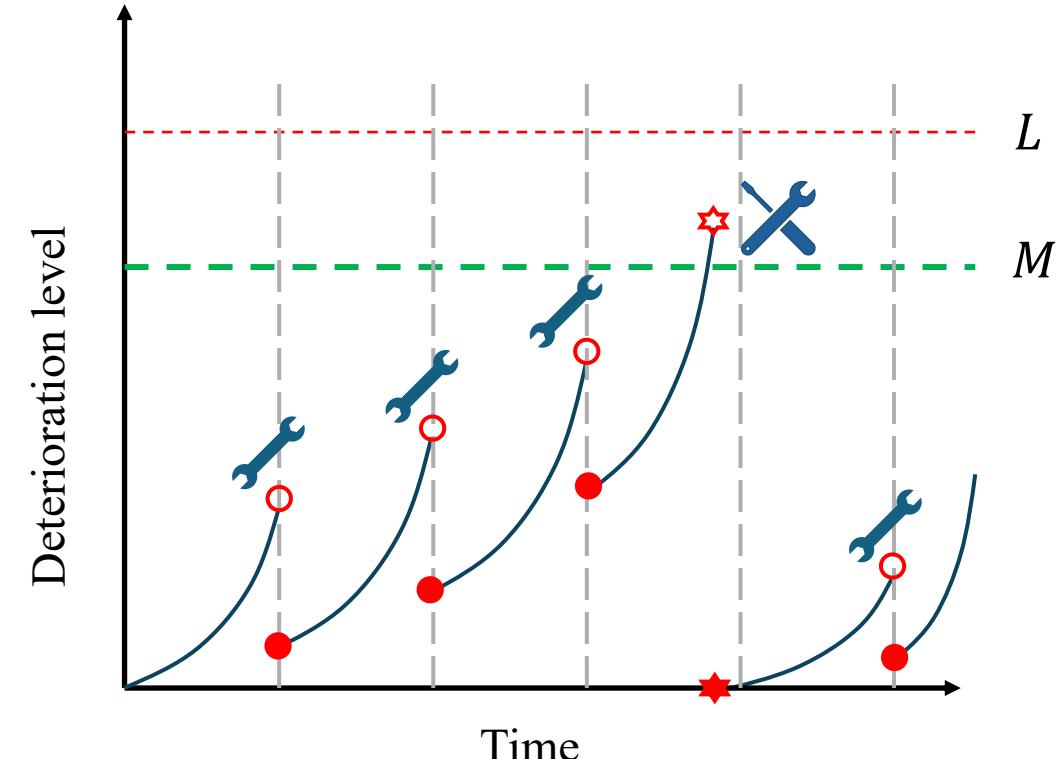
        Supports two types of noise:
        - additive_normal: x_obs = x + N(0, σ²)
        - brownian_increment: x_obs = x + N(0, σ² * dt)
```

III Preventive Maintenance Policies: Threshold-based and scheduled triggering

Level-only PM



Time-and-level PM



Code for implementation of level-only and time-and-level PM policies

```
def simulate_path_with_covariates(  
    degradation_type: str = "compound_poisson",  
    degradation_params: Dict[str, Any] = None,  
    covariate_specs: List[CovariateSpec] = None,  
    covariate_effects: Dict[str, np.ndarray] = None,  
    dt: float = 0.01,  
    PM_level: float = 2.0,  
    PM_interval: float = None,  
    L: float = 5.0,  
    x0: float = 0.0,  
    repair_func: Callable = None,  
    repair_params: Dict = None,  
    obs_time: float = 100.0,  
    random_seed: int = None,  
    noise: Optional[Dict[str, Any]] = None,  
    cost_params: CostParams = None,  
    cost_covariate_specs: List[CovariateSpec] = None,  
    cost_covariate_effects: Dict[str, np.ndarray] = None  
) -> Dict[str, Any]:  
    """  
  
    Simulate degradation path with covariates, distinguishing latent true wear (X_latent)  
    and noisy observations (X_obs), and compute maintenance costs.  
  
    Decision Logic:  
    - CM (Corrective Maintenance): Triggered when x_latent >= L (true failure)  
    - PM (Preventive Maintenance): Triggered when x_observed >= PM_level (decision based on observable info)
```

Maintenance Strategies:

- Level-only: PM triggered when observed degradation reaches PM_level
- Time-and-level: PM triggered by either time (PM_interval) or level (PM_level)

Level-only PM

```
# --- PM Logic (based on observed degradation level) ---  
if not has_scheduled_pm:  
    # Level-only strategy (based on observed level)  
    if x_obs >= PM_level:  
        z_lat = x_lat  
        y_lat = repair_func(last_repair_post_lat, z_lat, params=repair_params)
```

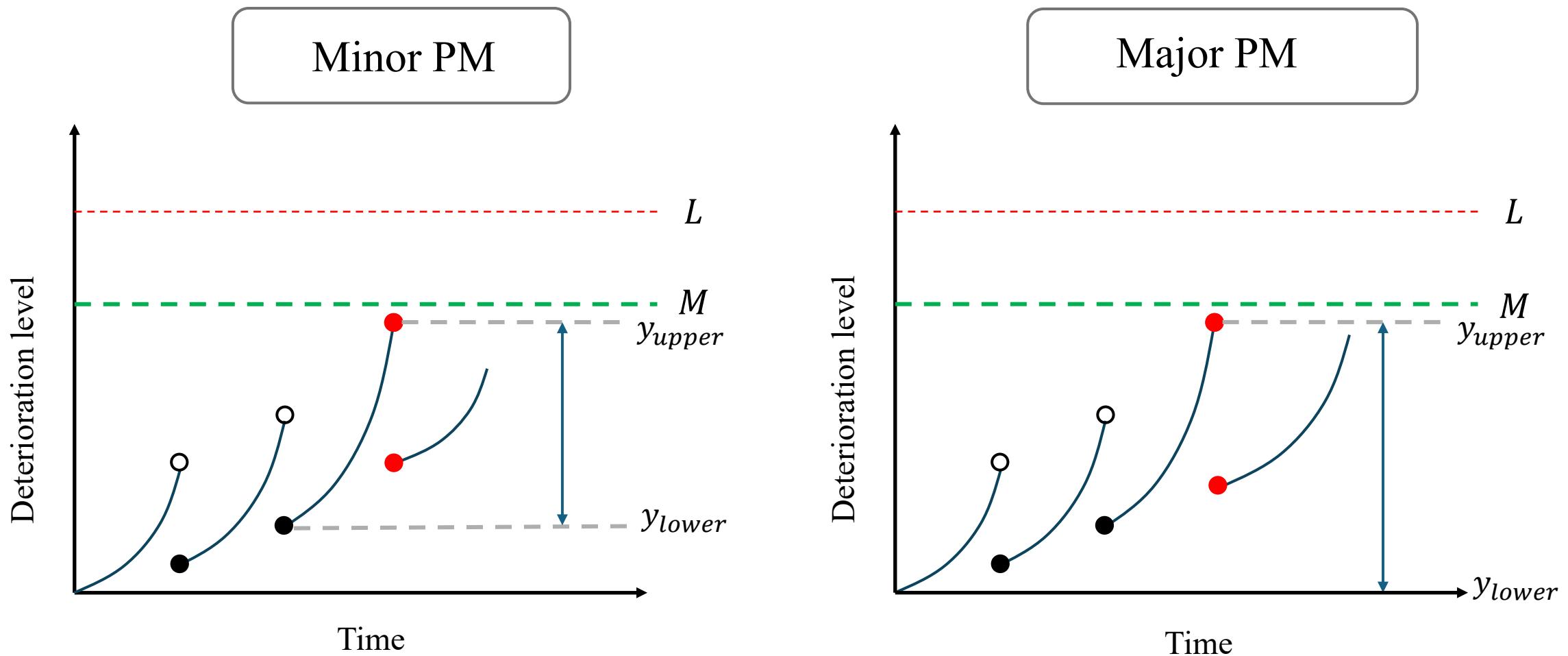
Time-and-level PM

```
else:  
    # Time-and-level strategy (based on observed level)  
    level_triggered = (x_obs >= PM_level)  
    time_triggered = (t - last_pm_time >= PM_interval)
```

Refer to

condition_based/single_machine_sim.py

Imperfect Repair Model: major and minor repairs



Post-repair degradation level $\sim U(y_{lower}, y_{upper})$
 $y_{lower} + (y_{upper} - y_{lower})B(a, b)$
 $y_{upper} - (1 - \rho)(y_{upper} - y_{lower})$

Code for major and minor repairs

```
def sample_post_repair_mixed(  
    y_lower: float,  
    y_upper: float,  
    params: Optional[Dict[str, Any]] = None  
) -> float:  
    """  
        Mixed/relaxed version of post-repair sampling for imperfect maintenance.  
    """
```

This function models the degradation level after an imperfect repair.

With probability p_major, performs major repair supporting [0, y_upper].

With probability 1-p_major, performs minor repair supporting [y_lower, y_upper].

Special Case Handling:

- If $y_{upper} \leq y_{lower}$: degradation level after last repair is still above PM threshold, execute perfect preventive maintenance (complete restoration to 0).
- If $y_{upper} \leq 0$: already at perfect condition, return 0.

Args:

y_lower: Lower bound (typically degradation level after last repair)
y_upper: Upper bound (typically current degradation level before repair)
params: Dictionary containing repair parameters:

- p_major: Probability of major repair (default: 0.2)
- dist_minor: Distribution for minor repair ('uniform'/'beta'/'proportional')
- dist_major: Distribution for major repair ('uniform'/'beta'/'proportional')
- a_minor, b_minor: Beta distribution parameters for minor repair
- a_major, b_major: Beta distribution parameters for major repair
- rho_minor: Proportional parameter for minor repair (reduction ratio)
- rho_major: Proportional parameter for major repair (reduction ratio)

Returns:

Post-repair degradation level

Refer to

condition_based/repair.py

Cost modeling in the CBM simulation engine

Perfect PM & CM Cost

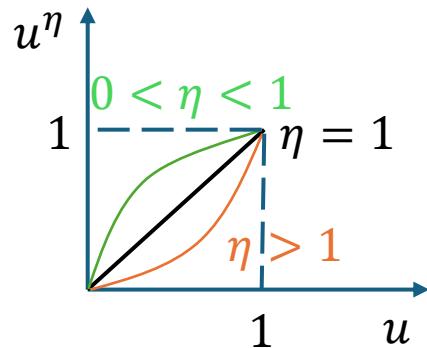
$$C_r(t)|W(t) \sim \text{Gamma}(k_r, \theta_r, l_r(t))$$

- $l_r(t)$: covariate-dependent location parameter
- $W(t)$: cost-related operational factors (operating environment + logistic factors)
- $r \in \{\text{PM, CM}\}$; k_r : shape parameter; θ_r : scale parameter

Imperfect PM Cost

$$u = \frac{X_{\text{before}} - X_{\text{after}}}{X_{\text{before}}} \in [0,1]$$

$$C_{IPM}(t) = c_{fix}(t) + c_0 u^\eta + \varepsilon$$



- $c_{fix}(t)$: fixed cost affected by operational covariates $W(t)$; fixed value if no covariates
- c_0 : largest possible variable cost (maintenance cost)
- η : controls the curvature of the cost–maintenance effect relationship
 - $\eta = 1$: Linear
 - $\eta > 1$: Increasing marginal cost
 - $0 < \eta < 1$: Diminishing returns
- ε : Noise
- Implemented with: $C_{IPM} = \max(0, C_{IPM})$

Code for cost modeling in the CBM simulation engine

```
def compute_maintenance_cost(
    maintenance_type: str,
    cost_params: CostParams,
    cost_covariates: np.ndarray = None,
    cost_covariate_effects: Dict[str, np.ndarray] = None,
    repair_effectiveness: float = None
) -> float:

    if maintenance_type == 'perfect_pm':
        # Perfect PM cost follows 3-parameter gamma distribution
        shape = cost_params.pm_shape
        scale = cost_params.pm_scale

        # Compute location parameter from covariates (linear effect)
        location = 0.0
        if cost_covariates is not None and cost_covariate_effects is not None:
            if 'pm_location' in cost_covariate_effects:
                beta = cost_covariate_effects['pm_location']
                location = np.dot(beta, cost_covariates)

        # Generate from 3-parameter gamma: shape, scale, location
        cost = gamma_dist.rvs(a=shape, scale=scale, loc=location)
        return cost

    elif maintenance_type == 'cm':
        # CM cost follows 3-parameter gamma distribution (higher than PM)
        shape = cost_params.cm_shape
        scale = cost_params.cm_scale

        # Compute location parameter from covariates (linear effect)
        location = 0.0
        if cost_covariates is not None and cost_covariate_effects is not None:
            if 'cm_location' in cost_covariate_effects:
                beta = cost_covariate_effects['cm_location']
                location = np.dot(beta, cost_covariates)

        # Generate from 3-parameter gamma: shape, scale, location
        cost = gamma_dist.rvs(a=shape, scale=scale, loc=location)
        return cost

    elif maintenance_type == 'imperfect_pm':
        # Imperfect PM: C_IPM = c_fix + c_0*u + ε
        if repair_effectiveness is None:
            raise ValueError("repair_effectiveness must be provided for imperfect_pm")
```

Refer to

condition_based/cost.py

Flow of multi-machine simulation in the CBM engine

Simulate multiple machines with the same or different maintenance policies.

This function simulates a fleet of machines operating under the same degradation parameters but potentially different maintenance policies, with independent random realizations.

IMPORTANT:

- Fixed covariates (type='fixed') are independently sampled for each machine
- PM_level and PM_interval can be specified per machine or shared across fleet

```
def simulate_multiple_machines(  
    n_machines: int,  
    degradation_type: str = "compound_poisson",  
    degradation_params: Dict[str, Any] = None,  
    covariate_specs: List[CovariateSpec] = None,  
    covariate_effects: Dict[str, np.ndarray] = None,  
    dt: float = 0.01,  
    PM_level: Union[float, List[float], Dict[int, float]] = 2.0,  
    PM_interval: Union[float, List[float], Dict[int, float], None] = None,  
    L: float = 5.0,  
    x0: float = 0.0,  
    repair_func: Any = None,  
    repair_params: Dict = None,  
    obs_time: float = 100.0,  
    random_seed_base: int = None,  
    noise: Optional[Dict[str, Any]] = None,  
    cost_params: CostParams = None,  
    cost_covariate_specs: List[CovariateSpec] = None,  
    cost_covariate_effects: Dict[str, np.ndarray] = None  
):
```

```
for i in range(n_machines):  
    # Set random seed for this machine  
    seed = random_seed_base + i if random_seed_base is not None else None
```

Loop over machines

```
# Get machine-specific maintenance policy  
machine_pm_level = pm_levels[i]  
machine_pm_interval = pm_intervals[i]
```

PM policy varies across machines

```
# Deep copy covariate specs so each machine can have independent fixed values  
machine_covariate_specs = copy.deepcopy(covariate_specs) if covariate_specs else None  
machine_cost_covariate_specs = copy.deepcopy(cost_covariate_specs) if cost_covariate_specs else None
```

```
# Run simulation for this machine  
result = simulate_path_with_covariates(  
    degradation_type=degradation_type,  
    degradation_params=degradation_params,  
    covariate_specs=machine_covariate_specs,  
    covariate_effects=covariate_effects,  
    dt=dt,  
    PM_level=machine_pm_level,  
    PM_interval=machine_pm_interval,  
    L=L,  
    x0=x0,  
    repair_func=repair_func,
```

Simulate one machine

```
# Compute fleet-level cost analysis  
fleet_costs = compute_fleet_costs(machine_results)
```

Aggregate results

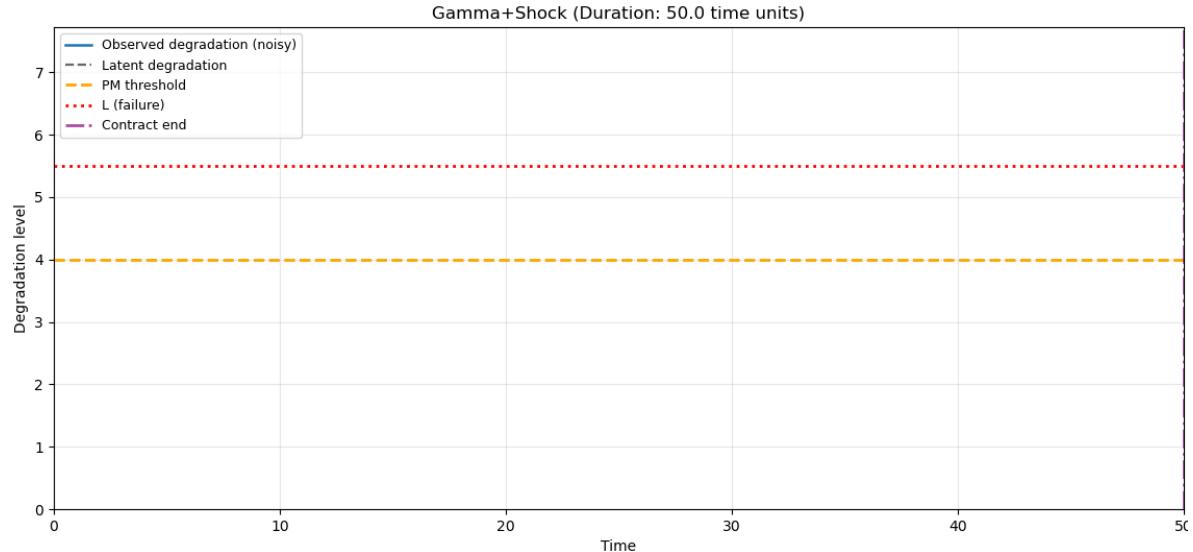
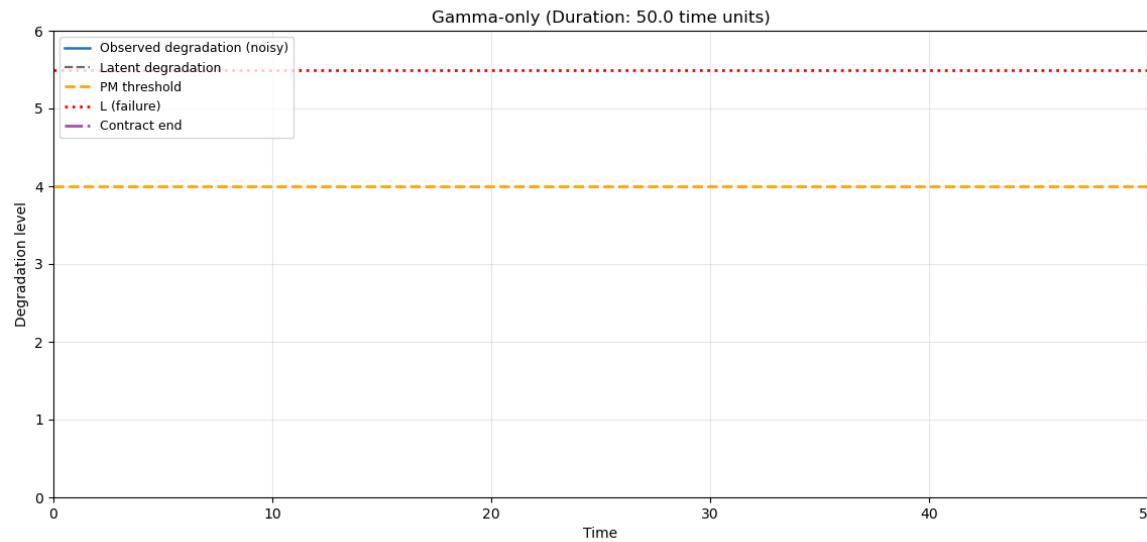
```
# Record events of multiple machines  
event_logs = export_event_level_df(machine_results)
```

```
# Record events of multiple machines  
machine_logs = export_machine_level_df(machine_results)
```

Refer to

condition_based/multi_machine_sim.py

CBM Outputs: Degradation paths and maintenance logs



machine_id	PM_level	PM_interval	time	type	trigger_reason	level_before_latent	level_before_observed	level_after_latent	level_af
0	0	4.0	15.0	10.4	perfect_preventive_maintenance	level_threshold_observed	4.751474	4.796827	0.000000
1	0	4.0	15.0	15.1	imperfect_repair	scheduled_time	1.176669	1.301039	0.995994
2	0	4.0	15.0	30.1	imperfect_repair	scheduled_time	2.613625	2.405190	1.804810
3	0	4.0	15.0	42.5	perfect_preventive_maintenance	level_threshold_observed	4.364901	4.432757	0.000000
4	0	4.0	15.0	45.1	imperfect_repair	scheduled_time	0.134978	0.163415	0.067489
5	1	3.5	12.0	10.5	perfect_preventive_maintenance	level_threshold_observed	3.541137	3.563063	0.000000
6	1	3.5	12.0	12.1	imperfect_repair	scheduled_time	0.000000	0.000000	0.000000
7	1	3.5	12.0	24.1	imperfect_repair	scheduled_time	1.779304	1.641513	0.889652
8	1	3.5	12.0	30.9	catastrophic_failure_replacement	N/A	5.509543	5.465794	0.000000

||| Access the simulation engine repository

Scan the QR code below to access the GitHub repository for the TBM and CBM simulation engines:

