

```
graph BT; A["/home/cptsai/catkin_ws/src/ENPM808X/ROS/Turtlebot_RRT_SLAM/src/rrt_global_planner_plugin.cpp"] --> C["/home/cptsai/catkin_ws/src/ENPM808X/ROS/Turtlebot_RRT_SLAM/include/rrt_global_planner_plugin.h"]; B["/home/cptsai/catkin_ws/src/ENPM808X/ROS/Turtlebot_RRT_SLAM/test/test.cpp"] --> C;
```

/home/cptsai/catkin
_ws/src/ENPM808X/ROS
/Turtlebot_RRT_SLAM/include
/rrt_global_planner_plugin.h

/home/cptsai/catkin
_ws/src/ENPM808X/ROS
/Turtlebot_RRT_SLAM/src
/rrt_global_planner_plugin.cpp

/home/cptsai/catkin
_ws/src/ENPM808X/ROS
/Turtlebot_RRT_SLAM/test
/test.cpp