Rename your zoom name to your index number and surname, e.g., **18001234\_Perera** 

During the lecture we will ask you to put a message in the **chat** indicating your index number. You should respond within **5 minutes**.

Dr. Hiran Ekanayake

### **ANALOG OUTPUT**



## Generating a Sine Wave

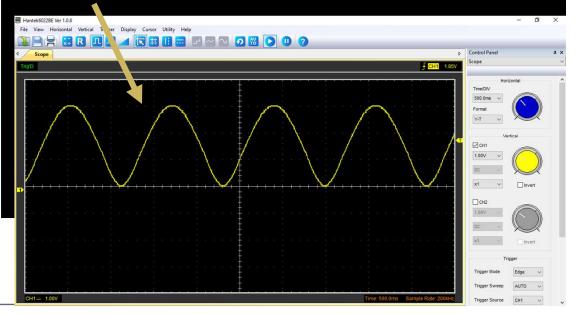
```
int SineValues[256];

void setup() {
    Serial.begin(9600);
    float ConversionFactor=(2*PI)/256;
    float RadAngle;
    for(int MyAngle=0;MyAngle<256;MyAngle++) {
        RadAngle=MyAngle*ConversionFactor;
        SineValues[MyAngle]=(sin(RadAngle)*127)+128;
    }
}

void loop() {
    for(int i=0;i<256;i++) {
        Serial.println(SineValues[i]);
        dacWrite(25,SineValues[i]);
    }
}</pre>
```

What is this device?

What is this oscilloscope?





## ESP32

These are cheap Wi-Fi modules to develop DIY IoT projects







# Why ESP32?

	Arduino Uno	Arduino Mega	ESP8266 (12E)	ESP32
MCU	ATmega328p 8-bit	ATmega2560 8-bit	Xtensa Single-core 32-bit L106	Xtensa Dual-Core 32-bit LX6 with 600 DMIPS
Operating Voltage / Current / Per Pin	5V	5V	3.3V (3.0-3.6V) / 80mA / 15mA	3.3V
Speed	16 MHz	16 MHz	80 MHz	Up to 240 MHz
Memory: Flash / SRAM / EEPROM	32kB / 2kB / 1kB	256kB / 8kB / 1kB	16MB / 160kB	16MB / 512kB / 448kB
IO: GPIO/PWM/ADC/DAC	14/6/6/0	54/14/16/0	17 / 8 / 1(10 bit) / 0	36 / 16 / 1 (12 bits) / 2
Wireless: Type / Wi-Fi / Bluetooth	No	No	STA / AP / STA + AP 802.11 b/g/n (HT20)	STA / AP / STA + AP 802.11 b/g/n (HT40) BT 4.2 / BLE
Wired: SPI / I2C / I2S / UART / CAN / Ethernet	0/1/0/1/0/0	0/1/0/4/0/0	2/1/2/2/0	4/2/2/2/1 Ethernet MAC
Networking: Protocols / Serial / Clients	1200 - 115200 bps	1200 - 115200 bps	IPv4/TCP/UDP/HTTP/FTP 110 - 921600 bps TCP Client 5	IPv4/TCP/UDP/HTTP/FTP 110 - 921600 bps TCP Client 5
Sensors	No	No	No	Touch, Temperature, Hall Effect
Security	No	No	WEP / WPA-PSK / WPA2- PSK	WEP / WPA-PSK / WPA2- PSK



# ESP32 Development Boards

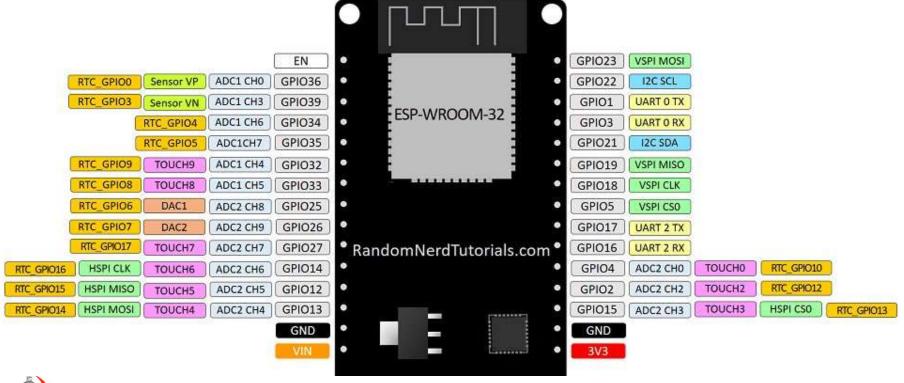




## Pin Description

#### **ESP32 DEVKIT V1 - DOIT**

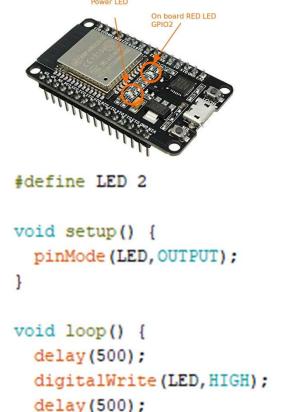
version with 30 GPIOs





#### "Hello World" with ESP32

- Under File> Preferences add https://dl.espressif.com/dl/package\_es p32\_index.json into the "Additional Board Manager URLs" (use comma to add to existing)
- Go to Tools > Board > Boards
   Manager... search ESP32 ... and install
- Select DOIT ESP32 DEVKIT V1 as the board and correct port
- Press upload in Arduino while holding down the BOOT button on ESP until "Connecting..." succeeds
- Press ENABLE button to reset & test



digitalWrite (LED, LOW);



# Hantek 6022BL PC Based USB Digital Portable Oscilloscope + 16 CHs Logic Analyzer, 48MS/s Real-time Sampling, 20MHz Bandwidth





## DSO138 DIY Oscilloscope

#### Vertical

Number of Channel: 1

Analog Bandwidth: 0 - 200KHz

Sensitivity: 10mV/Div - 5V/Div

Sensitivity error: < 5%</li>

· Resolution: 12-bit

Input Impedance: 1M ohm

Maximum Input voltage: 50Vpk

Coupling: DC, AC, GND

#### Horizontal

Max Real-time Sampling Rate: 1Msps

Timebase: 10us/Div - 500s/Div

Record Length: 1024

#### Trigger

Trigger Modes: Auto, Normal, Single

• Trigger Types: Rising/falling edge

Trigger Position: 1/2 of buffer size fixed

#### Display

• 2.4-inch color TFT LCD with 320 x 240 rd

#### **Power Supply**

• 9V DC (8 - 12V acceptable)

Supply Current: 120mA

#### Physical

Dimension: 117mm X 76mm X 15mm

Weight: 70 gram (not including cables)

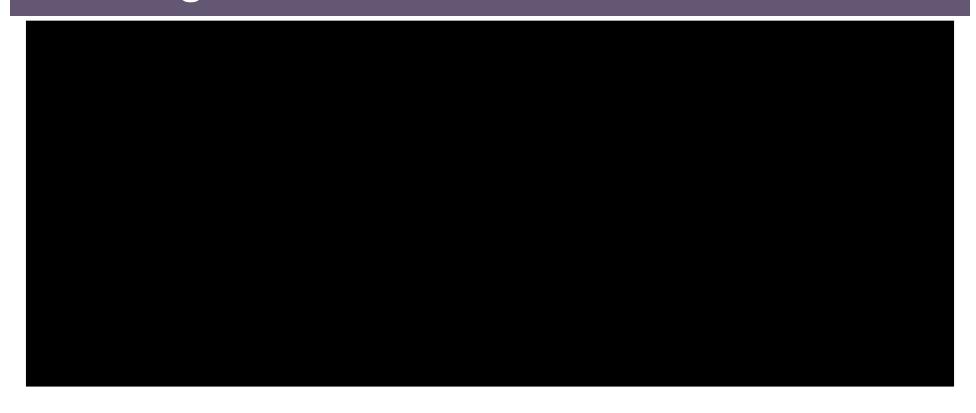
By JYE Tech based on Cortex-M3 ARM processor (STM32F103C8) https://jyetech.com/dso-138-oscilloscope-diy-kit/



Local: Rs. 4000-8000/=



# Analog Out in ESP32: LED





## Analog Out in Arduino: LED

```
void setup() {
  Serial.begin(9600);
  pinMode (3, OUTPUT);
void loop() {
  for (int i=0; i<255; i+=10) {
    analogWrite(3, i);
    Serial.println(i);
    delay(30);
                                                                                   Pulse Width Modulation
                                                                                 0% Duty Cycle - analogWrite(0)
  for (int i=255; i>0; i-=10) {
                                                                       5v
    analogWrite(3, i);
    Serial.println(i);
                                                                                25% Duty Cycle - analogWrite(64)
    delay(30);
                                                                                50% Duty Cycle - analogWrite(127)
           PWM for creating a pseudo analog voltage
                                                                                75% Duty Cycle - analogWrite(191)
           Duty Cycle -20\% =>  duty cycle within 1 sec.
           period = ON for 200 m.sec.
                                                                               100% Duty Cycle - analogWrite(255)
                                                                       0v
             Electronics & Physical Computing by HBE
                                                                                                                   11
     uese
```

## Which Pins in Arduino Uno Provides PWM?



## Which Pins in Arduino Uno Provides PWM?





#### Attention

- Put a chat message indicating your index number and 111, e.g.,
  - 18001234\_111



## How to Use an Oscilloscope?

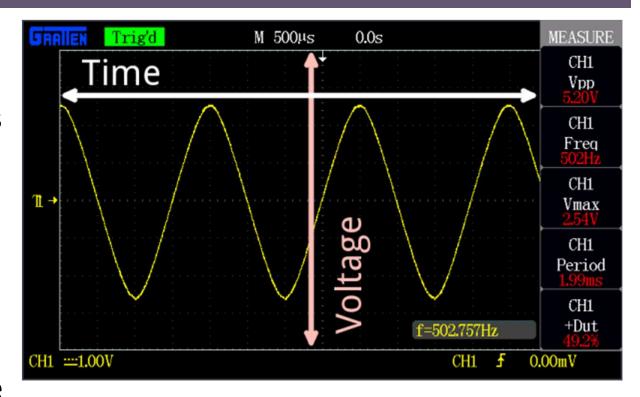
https://learn.sparkfun.com/tutorials/how-to-use-an-oscilloscope/all

#### Purpose:

 To graph an electrical signal as it varies over time

#### Controls:

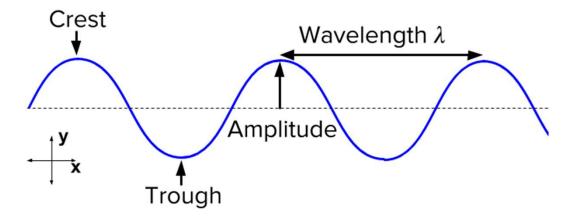
- To zoom in and zoom out the horizontal and vertical axes
- Trigger to stabilize the display





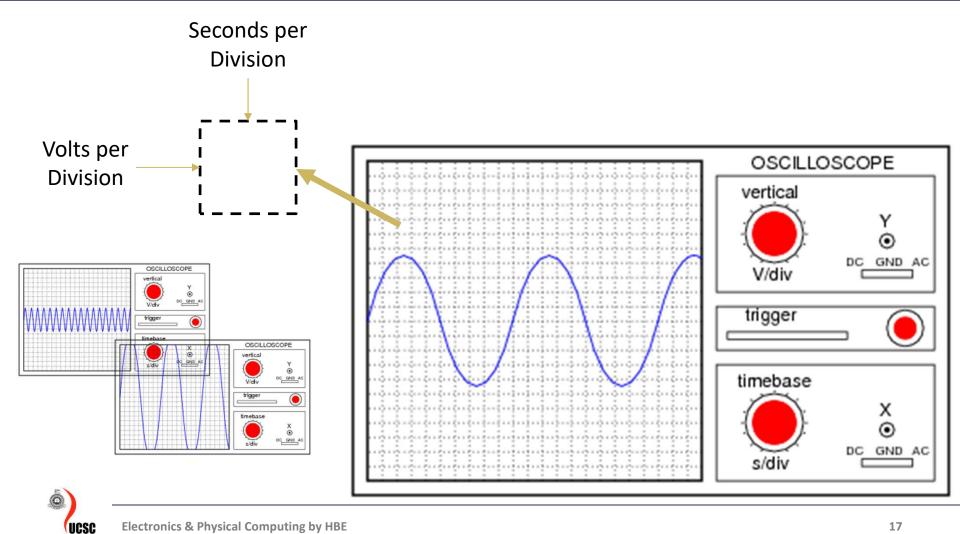
## What Can O-Scopes Measures?

- Both voltage-based and time-based characteristics
- Voltage-based
  - Amplitude, peak-to-peak, min, max, average, etc.
- Time-based
  - Frequency, period/wavelength, duty cycle, rise/fall time, etc.
- Other
  - Shape of wave, phase, compare waves, noise, etc.

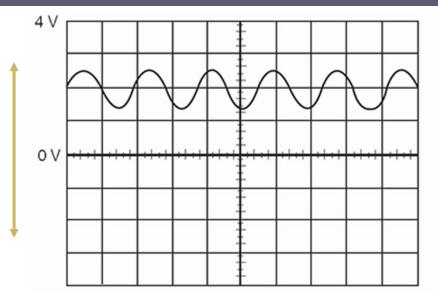


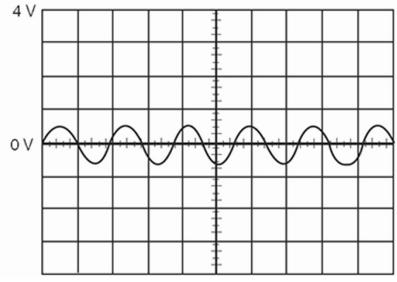


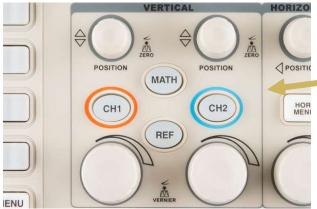
# O-Scope Display



# Vertical Position







Controls the Vertical (Voltage) Scale



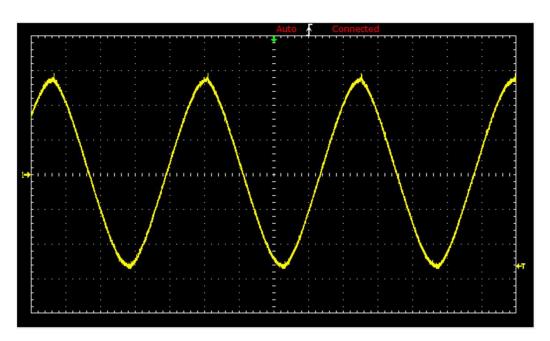
## **Horizontal Scale**





# Trigger

#### **No/Improper Trigger**







#### Exercise

 Calculate the frequencies of the two waveforms (A&B).

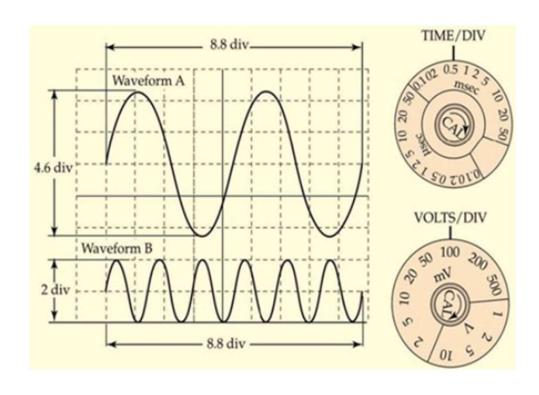
#### Waveform A:

$$V_{p-p} = 0.1*4.6 = 0.46V$$
  
T= 0.5\*(8.8/2) = 2.2 ms  
f = 1/T = 454.5 Hz

#### Waveform B:

$$V_{p-p} = 0.1*2 = 0.2V$$
  
T= 0.5\*(8.8/6) = 0.733 ms  
f = 1/T = 1.36 kHz.

TIME/DIV = 0.5ms/DIV VOLTS/DIV = 100mV/DIV = 0.1V/DIV





#### Attention

- Put a chat message indicating your index number and 125, e.g.,
  - 18001234\_125



#### int led = 3; void setup() { Exercise pinMode (led, OUTPUT); Hantek6022BE Ver 1.0.6 X void loop() { File View Horizontal Vertical Trigger Display Cursor Utility Help analogWrite(led, 64); ΦX Scope Scope F CH1 2.07V Trig'D Horizontal Time/DIV 1.000ms Format Vertical ☑ CH1 2.00V x1 Invert What is the frequency of the PWM signal? CH2 1.00V CH1 == 2.00V Time: 1.000ms Sample Rate: 1MHz Invert 15-12-2020 21:10 Running...

**UCSC**