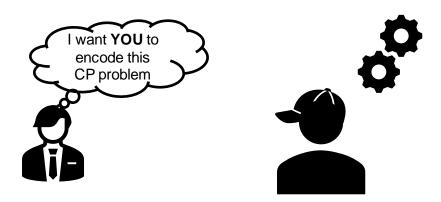
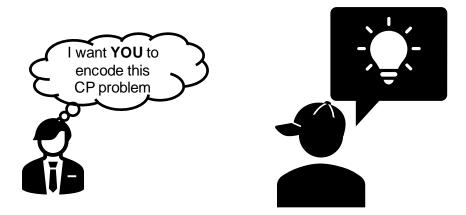


> problem > model



model



model

```
I want YOU to encode this CP problem
```



```
x = intvar(-9, 9, name="x")
y = intvar(-9, 9, name="y")
m = Model(
    x < 0,
    x < 1,
    x > 2,
    (x + y > 0) | (y < 0),
    (y >= 0) | (x >= 0),
    (y < 0) | (x < 0),
    AllDifferent(x,y)
)</pre>
```

model

solve

```
I want YOU to encode this CP problem
```

```
x = intvar(-9, 9, name="x")
y = intvar(-9, 9, name="y")
m = Model(
    x < 0,
    x < 1,
    x > 2,
    (x + y > 0) | (y < 0),
    (y >= 0) | (x >= 0),
    (y < 0) | (x < 0),
    AllDifferent(x,y)
</pre>
```

model

solve

UNSAT

```
I want YOU to encode this CP problem
```



```
x = intvar(-9, 9, name="x")
y = intvar(-9, 9, name="y")
m = Model(
    x < 0,
    x < 1,
    x > 2,
    (x + y > 0) | (y < 0),
    (y >= 0) | (x >= 0),
    (y < 0) | (x < 0),
    AllDifferent(x,y)</pre>
```

Solver says UNSAT, what now?

- (Human) modeling error ?
- Problem is <u>over-constrained</u> or <u>unsatisfiable</u>?

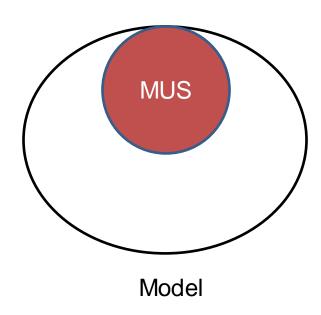
Part 2: Explaining Unsatisfiability with examples of Master ←→ Sub-problem solving

Debugging a model

- Need for an explanation of UNSAT
 - 1. Identify <u>conflicting constraints</u> as explanation for UNSAT
 - → Extract Minimum Unsatisfiable Subset (MUS) a.k.a UNSAT Core, Irreducible Inconsistent Subsystem (IIS)
 - 2. Identify Maximal Satisfiable Subset (MSS)
 - 3. "Correct" the infeasibility in the model

 → Extract Minimum Correction Subsets (MCS)

 Complement of some MSS, removal/correction leads to a satisfiable subset

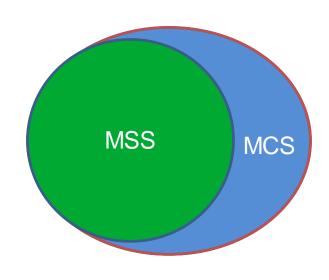


Debugging a model

- = Need for an explanation of UNSAT
 - 1. Identify <u>conflicting constraints</u> as explanation for UNSAT
 - → Extract Minimum Unsatisfiable Subset (MUS) a.k.a UNSAT Core, Irreducible Inconsistent Subsystem (IIS)
 - 2. Identify Maximal Satisfiable Subset (MSS)
 - 3. <u>"Correct" the infeasibility</u> in the model

 → Extract Minimum Correction Subsets (MCS)

Complement of some MSS, removal/correction leads to a satisfiable subset

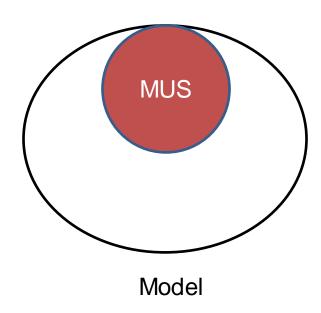


Debugging a model

- Need for an explanation of UNSAT
 - 1. Identify <u>conflicting constraints</u> as explanation for UNSAT
 - → Extract Minimum Unsatisfiable Subset (MUS) a.k.a UNSAT Core, Irreducible Inconsistent Subsystem (IIS)
 - 2. Identify Maximal Satisfiable Subset (MSS)
 - 3. "Correct" the infeasibility in the model

 → Extract Minimum Correction Subsets (MCS)

 Complement of some MSS, removal/correction leads to a satisfiable subset



Explaining UNSAT with MUSes

Methods

- 1. Some solvers provide an implementation for extracting unsatisfiable cores as explanations of UNSAT.
- 2. Deletion-based Minimal unsatisfiable subsets
 - Iterate over constraints
 - Delete constraints if removing them leaves the model UNSAT

```
def mus(constraints):
    m = Model(constraints)
    assert ~m.solve(), "MUS: model must be UNSAT"

    core = m.get_core() # or all constraints
    i = 0
    while i < len(core):
        subcore = core[:i] + core[i+1:] # check if all but i makes core SAT

    if Model(subcore).solve():
        i += 1 # removing it makes it SAT, must keep
    else:
        core = subcore # overwrite core, so core[i] is next one

    return core</pre>
```

Joao Marques-Silva. Minimal Unsatisfiability: Models, Algorithms and Applications. ISMVL 2010. pp. 9-14

Example of MUS extraction

cpmpy/examples/tutorial ijcai22/2 musx ocus.ipynb

```
x = intvar(0,3, shape=4, name="x")
# circular 'bigger then', UNSAT
mus_cons = [
    x[0] > x[1],
    x[1] > x[2],
    x[2] > x[0],
    (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x[2]))
]
core = m.get_core() # or all constraints
```

```
# circular 'bigger then', UNSAT
mus cons = [
   x[0] > x[1],
   x[1] > x[2],
   x[2] > x[0],
   x[3] > x[0],
    (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x[2]))
core = m.get core() # or all constraints
i = 0 # we will dynamically shrink mus vars
while i < len(core):</pre>
    # add all other remaining constraints
    subcore = core[:i] + core[i+1:]
    if Model(subcore).solve():
        # with all but 'i' it is SAT, so 'i' belongs to the MUS
        print("\tSAT so in MUS", core[i])
        i += 1
    else:
        # still UNSAT, 'i' does not belong to the MUS
        print("\tUNSAT so not in MUS", core[i])
        # overwrite current 'i' and continue
        core = subcore
```

x = intvar(0,3, shape=4, name="x")

```
x = intvar(0,3, shape=4, name="x")
# circular 'bigger then', UNSAT
mus cons = [
 \rightarrow x[0] > x[1],
   x[1] > x[2],
   x[2] > x[0],
   x[3] > x[0],
    (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x[2]))
core = m.get core() # or all constraints
i = 0 # we will dynamically shrink mus vars
while i < len(core):</pre>
    # add all other remaining constraints
    subcore = core[:i] + core[i+1:]
    if Model(subcore).solve():
        # with all but 'i' it is SAT, so 'i' belongs to the MUS
```

print("\tSAT so in MUS", core[i])

still UNSAT, 'i' does not belong to the MUS

print("\tUNSAT so not in MUS", core[i])
overwrite current 'i' and continue

i += 1

core = subcore

SAT so in MUS: (x[0]) > (x[1])

else:

```
x = intvar(0,3, shape=4, name="x")
# circular 'bigger then', UNSAT
mus cons = [
   x[0] > x[1],
\rightarrow x[1] > x[2],
   x[2] > x[0],
   x[3] > x[0],
    (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x[2]))
core = m.get core() # or all constraints
i = 0 # we will dynamically shrink mus vars
while i < len(core):</pre>
    # add all other remaining constraints
    subcore = core[:i] + core[i+1:]
    if Model(subcore).solve():
        # with all but 'i' it is SAT, so 'i' belongs to the MUS
```

print("\tSAT so in MUS", core[i])

```
# still UNSAT, 'i' does not belong to the MUS
print("\tUNSAT so not in MUS", core[i])
# overwrite current 'i' and continue
core = subcore
SAT so in MUS: (x[0]) > (x[1])
```

SAT so in MUS: (x[1]) > (x[2])

i += 1

else:

```
(x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x[2]))
core = m.get core() # or all constraints
i = 0 # we will dynamically shrink mus vars
while i < len(core):</pre>
    # add all other remaining constraints
    subcore = core[:i] + core[i+1:]
    if Model(subcore).solve():
        # with all but 'i' it is SAT, so 'i' belongs to the MUS
        print("\tSAT so in MUS", core[i])
        i += 1
    else:
        # still UNSAT, 'i' does not belong to the MUS
        print("\tUNSAT so not in MUS", core[i])
        # overwrite current 'i' and continue
        core = subcore
SAT so in MUS: (x[0]) > (x[1])
SAT so in MUS: (x[1]) > (x[2])
SAT so in MUS: (x[2]) > (x[0])
```

x = intvar(0,3, shape=4, name="x")
circular 'bigger then', UNSAT

mus cons = [

x[0] > x[1], x[1] > x[2], x[2] > x[0],

x[3] > x[0],

```
x = intvar(0,3, shape=4, name="x")
# circular 'bigger then', UNSAT
mus cons = [
   x[0] > x[1],
   x[1] > x[2],
   x[2] > x[0],
 x[3] > x[0],
    (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x[2]))
core = m.get core() # or all constraints
i = 0 # we will dynamically shrink mus vars
while i < len(core):</pre>
    # add all other remaining constraints
    subcore = core[:i] + core[i+1:]
    if Model(subcore).solve():
        # with all but 'i' it is SAT, so 'i' belongs to the MUS
        print("\tSAT so in MUS", core[i])
        i += 1
    else:
        # still UNSAT, 'i' does not belong to the MUS
        print("\tUNSAT so not in MUS", core[i])
        # overwrite current 'i' and continue
        core = subcore
SAT so in MUS: (x[0]) > (x[1])
SAT so in MUS: (x[1]) > (x[2])
SAT so in MUS: (x[2]) > (x[0])
UNSAT so not in MUS: (x[3]) > (x[0])
```

```
x = intvar(0,3, shape=4, name="x")
# circular 'bigger then', UNSAT
mus cons = [
   x[0] > x[1],
   x[1] > x[2],
   x[2] > x[0],
   x[3] > x[0],
 (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x[2]))
core = m.get core() # or all constraints
i = 0 # we will dynamically shrink mus vars
while i < len(core):</pre>
    # add all other remaining constraints
    subcore = core[:i] + core[i+1:]
    if Model(subcore).solve():
        # with all but 'i' it is SAT, so 'i' belongs to the MUS
        print("\tSAT so in MUS", core[i])
        i += 1
    else:
        # still UNSAT, 'i' does not belong to the MUS
        print("\tUNSAT so not in MUS", core[i])
        # overwrite current 'i' and continue
        core = subcore
SAT so in MUS: (x[0]) > (x[1])
SAT so in MUS: (x[1]) > (x[2])
SAT so in MUS: (x[2]) > (x[0])
UNSAT so not in MUS: (x[3]) > (x[0])
```

UNSAT so not in MUS: $((x[3]) > (x[1])) \rightarrow ((x[3]) > (x[2]))$ and ((x[3] == 3) or ((x[1]) == (x[2])))

Explaining UNSAT with MUSes

Methods & Insights

- Some solvers provide unsatisfiable cores as a starting point for debugging.
- Deletion-based Minimal unsatisfiable subsets
 - Iterate over constraints
 - Delete constraints if removing them leaves the model UNSAT

KEY Insights

- ✓ Depends on the ordering of the clauses
- ✓ <u>Faster</u> if the solver <u>supports</u> unsat core extraction and <u>assumptions</u> especially for larger problems
 - ☐ Most solvers provide an assumption interface
 - □ Does not require many modifications

```
# make assumption indicators, add reified constraints
                                                        ind = BoolVar(shape=len(mus_cons), name="ind")
                                                        for i,bv in enumerate(ind):
                                                             assum model += [bv.implies(mus cons[i])]
x = intvar(0,3, shape=4, name="x")
                                                        # to map indicator variable back to soft constraints
# circular 'bigger then', UNSAT
                                                        indmap = dict((v,i) for (i,v) in enumerate(ind))
mus cons = [
   x[0] > x[1],
   x[1] > x[2],
                                                        assum solver = CPM ortools(assum model)
   x[2] > x[0],
                                                        assert (not assum solver.solve(assumptions=ind)), "Model must be UNSAT"
   x[3] > x[0],
   (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x)
```

assum model = Model()

```
# make assumption indicators, add reified constraints
                                                         ind = BoolVar(shape=len(mus cons), name="ind")
                                                         for i,bv in enumerate(ind):
                                                              assum model += [bv.implies(mus cons[i])]
x = intvar(0,3, shape=4, name="x")
                                                         # to map indicator variable back to soft constraints
# circular 'bigger then', UNSAT
                                                         indmap = dict((v,i) for (i,v) in enumerate(ind))
mus cons = [
   x[0] > x[1],
   x[1] > x[2],
                                                         assum solver = CPM ortools(assum model)
   x[2] > x[0],
                                                         assert (not assum solver.solve(assumptions=ind)), "Model must be UNSAT"
   x[3] > x[0],
   (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) \mid (x[1] == x \mid \# unsat \underline{core is an unsatisfiable subset})
                                                         mus vars = assum solver.get core()
                                                         print("UNSAT core of size", len(mus vars))
```

assum model = Model()

```
assum model += [bv.implies(mus cons[i])]
x = intvar(0,3, shape=4, name="x")
                                                      # to map indicator variable back to soft constraints
# circular 'bigger then', UNSAT
                                                      indmap = dict((v,i) for (i,v) in enumerate(ind))
mus cons = [
   x[0] > x[1],
   x[1] > x[2],
                                                      assum solver = CPM ortools(assum model)
   x[2] > x[0],
                                                      assert (not assum solver.solve(assumptions=ind)), "Model must be UNSAT"
   x[3] > x[0],
   (x[3] > x[1]).implies(x[3] > x[2]) & ((x[3] == 3) | (x[1] == x)
                                                      # unsat core is an unsatisfiable subset
                                                      mus vars = assum solver.get core()
                                                      print("UNSAT core of size", len(mus vars))
                                                      # now we shrink the unsatisfiable subset further
                                                      i = 0 # we wil dynamically shrink mus vars
                                                      while i < len(mus vars):</pre>
                                                          # add all other remaining constraints
                                                          assum vars = mus vars[:i] + mus vars[i+1:]
                                                          if assum solver.solve(assumptions=assum vars):
                                                              # with all but 'i' it is SAT, so 'i' belongs to the MUS
                                                               print("\tSAT so in MUS:", mus cons[i])
                                                               i += 1
                                                          else:
                                                              # still UNSAT, 'i' does not belong to the MUS
                                                              print("\tUNSAT so not in MUS:", mus cons[i])
                                                              # overwrite current 'i' and continue
                                                              mus cons = testcons
                                                      UNSAT core of size 3
                                                              SAT so in MUS: (x[0]) > (x[1])
                                                                                                Also use new core here
                                                              SAT so in MUS: (x[1]) > (x[2])
                                                               SAT so in MUS: (x[2]) > (x[0])
```

assum model = Model()

for i,bv in enumerate(ind):

make assumption indicators, add reified constraints

ind = BoolVar(shape=len(mus cons), name="ind")

Explaining UNSAT with MUSes

Methods & Insights

- Some solvers provide unsatisfiable cores as a starting point for debugging.
- Deletion-based Minimal unsatisfiable subsets
 - Iterate over constraints
 - Delete constraints if removing them leaves the model UNSAT

KEY Insights

- ✓ Faster if the solver supports unsat core extraction and assumptions
 - Most solvers provide an assumption interface
 - Does not require many modifications
- ✓ Depends on the ordering of the clauses

Enumerate all Minimal Unsatisfiable Subsets and Minimum Correction Subets

MUS extraction

cpmpy/examples/tutorial ijcai22/2 musx ocus.ipynb

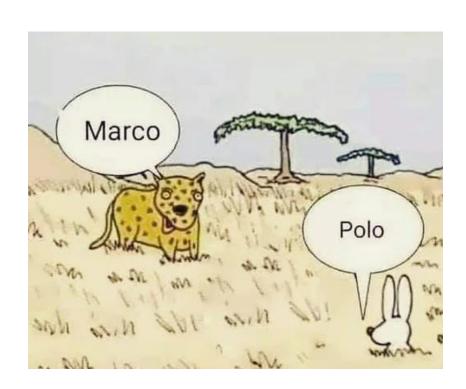
Master ←→ sub-problem



Marco Polo (1254 –1324)

Marco-Polo

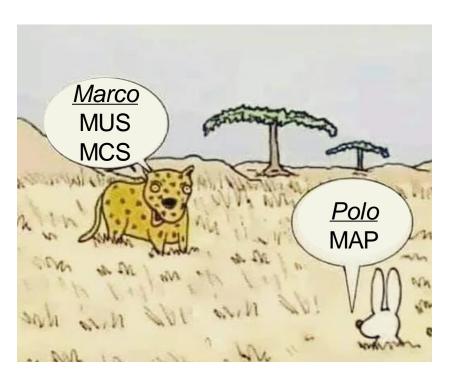
An example of Master ←→ Sub-problem approach



Source: https://9gag.com/gag/a07MMXZ

Marco-Polo

An example of Master ←→ Sub-problem approach



MARCO: Mapping Regions of

Constraints sets

MUS enumeration algorithm

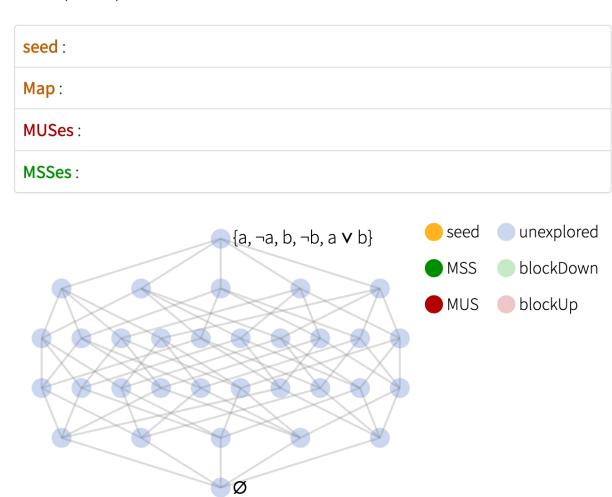
POLO: **Power Logic**

"Map" of the powerset as a propositional logic Formula

```
MARCO Algorithm
Input: Constraint system C
 Map \leftarrow T
 while Map is satisfiable:
    seed \leftarrow getUnexplored(Map)
    if seed is satisfiable:
       MSS \leftarrow grow(seed, C)
       output MSS
       Map \leftarrow Map \land blockDown(MSS)
    else:
       MUS \leftarrow shrink(seed, C)
       output MUS
       Map \leftarrow Map \land blockUp(MUS)
```



Example input: $C = \{a, \neg a, b, \neg b, a \lor b\}$



Demo MarcoPolo MUS/MCS enumeration

cpmpy/examples/tutorial_ijcai22/marco-mus-mcs-enumeration.ipynb

Explaining UNSAT with MUSes

Methods & Insights

- Deletion-based MUS extracts only 1MUS
- Efficiently enumerate all Minimal Unsatisfiable Subsets and Minimum Correction Subets
- No guarantee of subset-minimality (only heuristically)
 - → Smallest Minimal Unsatisfiable Subset (SMUS)

or optimality with weighted constraints

→ Optimal (Constrained) Unsatisfiable Subset (OCUS)

Master ←→ Sub-problem

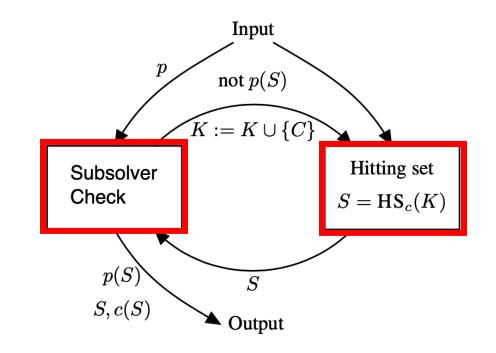
Implicit hitting set algorithms

Master ← → Sub-problem approach

Implicit hitting set algorithms

General Structure:

- 1. Find minimum hitting set
- 2. Call subsolver for checking (SAT, UNSAT)



Saikko, Paul, Johannes P. Wallner, and Matti Järvisalo. "Implicit hitting set algorithms for reasoning beyond NP." Fifteenth International Conference on the Principles of Knowledge Representation and Reasoning. 2016.

Master ← → Sub-problem approach

Implicit hitting set algorithms

Smallest MUS [1] and Optimal (C)US [2]:

- Deciding whether a MUS of size \leq k is $\sum_{p}^{2} -complete$
- Extracting a smallest MUS (OCUS/SMUS) is in $FP^{\sum_{p}^{2}}$

Based on the implicit hitting set duality between MCSs and MUSs:

• Also used for MaxSAT, the dual of the OCUS-problem, i.e. MaxHS [3]

A set $S \subseteq F$ is a MCS of F if and only if it is a *minimum hitting set* of MUSs(F).

A set $S \subseteq F$ is a MUS of F if and only if it is a *minimum hitting set* of MUSs(F).

^[2] A. Ignatiev, et al. "Smallest MUS extraction with minimal hitting set dualization." CP 2015.

^[3] J. Davies, and B.Fahiem. "Exploiting the power of MIP solvers in MAXSAT." SAT 2013.

Optimal Constrained Unsatisfiable Subsets

Let

```
\mathcal{F} be an unsatisfiable formula,

f: 2^{\mathcal{F}} \to \mathbb{N} a cost function

p: 2^{\mathcal{F}} \to \{t, f\} a predicate (constraint)
```

We call $S \subseteq \mathcal{F}$ an OCUS of \mathcal{F} (with respect to f and p) if

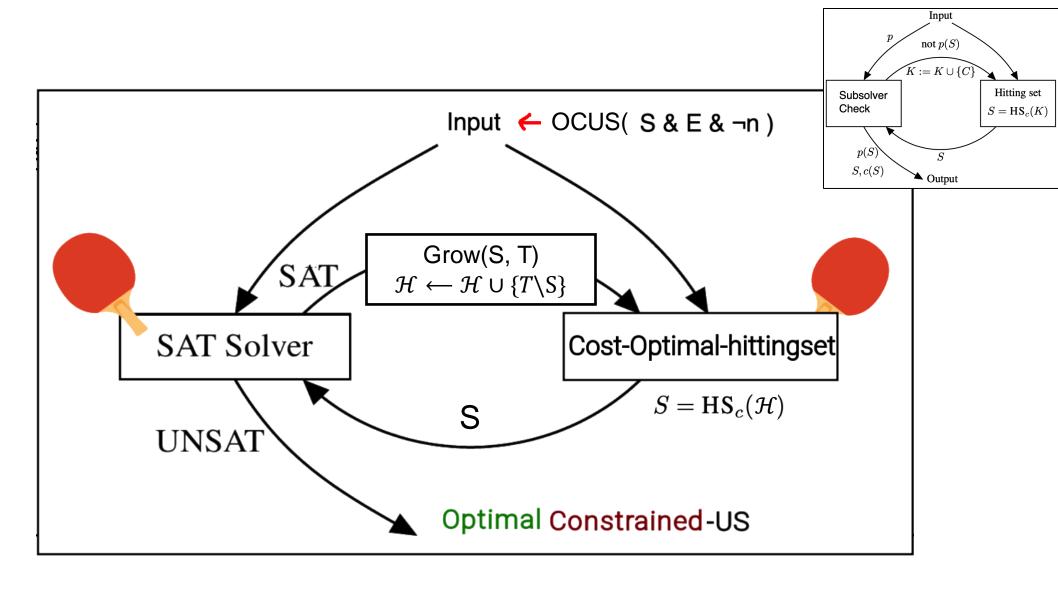
- S is unsatisfiable,
- p(S) is true
- all other unsatisfiable $S' \subseteq \mathcal{F}$ with p(S) = t satisfy $f(S') \ge f(S)$.

Optimal Constrained Unsatisfiable Subsets

Implicit hitting set-based algorithm

→ uses an implicit hitting set algorithm (like SMUS and MaxHS)

```
Algorithm 4: OCUS(T, f, p)
1 \mathcal{H} \leftarrow \emptyset
2 while true do
         S \leftarrow \text{COST-OPTIMAL-HITTINGSET}(\mathcal{H}, f, p)
                                                                                            MIP solver
         if \neg SAT(S) then
4
                                                                                             SAT/CP solver
               return S
5
                                                                                             as an oracle
         end
6
         \mathcal{S} \leftarrow \mathsf{GROW}(\mathcal{S}, T)
         \mathcal{H} \leftarrow \mathcal{H} \cup \{T \setminus \mathcal{S}\}
```



OCUS with assumptions

```
def OCUS_assum(soft, soft_weights, hard=[], solver='ortools', verbose=1):
   # init with hard constraints
    assum model = Model(hard)
   # make assumption indicators, add reified constraints
   ind = BoolVar(shape=len(soft), name="ind")
    for i.bv in enumerate(ind):
       assum_model += [bv.implies(soft[i])]
   # to map indicator variable back to soft_constraints
    indmap = dict((v,i) for (i,v) in enumerate(ind))
    assum solver = SolverLookup.lookup(solver)(assum model)
    if assum solver.solve(assumptions=ind):
       return []
                                         Hitting set Solver
    hs model = Model(
       # Objective: min sum(x_l * w_l)
       minimize=sum(x_l * w_l for x_l, w_l in zip(ind, soft_weights))
    # instantiate hitting set solver
    hittingset_solver = SolverLookup.lookup(solver)(hs_model)
                                                                                              repeatedly
    while(True):
                                                                                               compute
       hittingset_solver.solve()
                                                                                              hitting sets
       # Get hitting set
       hs = ind[ind.value() == 1]
                                                                                               CP/SAT
       if not assum_solver.solve(assumptions=hs):
                                                                                            as an oracle
           return soft[ind.value() == 1]
                                                                                                  Extract
       # compute complement of model in formula F
       C = ind[ind.value() != 1]
                                                                                          Correction Subset
       # Add complement as a new set to hit: sum x[j] * hij >= 1
       hittingset solver += (sum(C) >= 1)
```

MUS extraction

cpmpy/examples/tutorial ijcai22/2 musx ocus.ipynb

Optimal Constrained Unsatisfiable Subsets Implicit hitting set-based algorithm

- Example of multi-solver incremental solving
- Made easier and efficient with assumptions

1. Need to repeatedly compute hitting sets.

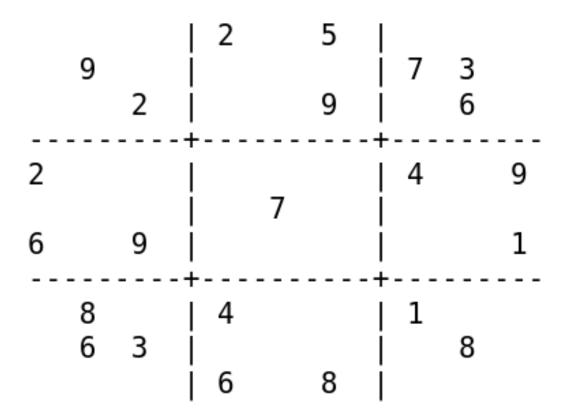
- > Problem becomes hard as collection of sets-to-hits expands.
- Big efficiency gains if incremental (and not restart)!

2. CP/SAT is used as an oracle

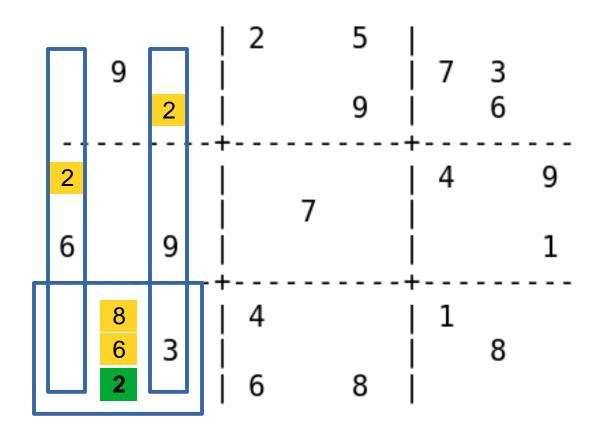
- > CP/SAT checking satisfiability of a subset
- Grow solves a MaxSAT problem, s.t. complement is a (small) MCS

Part 3: Advanced examples of Master ←→ Sub-problem solving Implicit Hitting set and Cutting plan algorithms

What if a model is SAT?

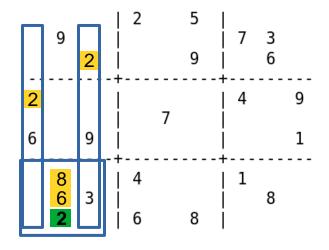


What if a model is SAT?



What if a model is SAT?

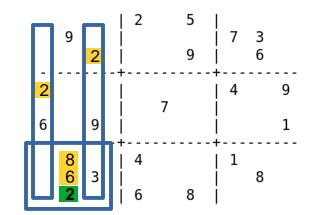
- User may not understand all derivations
- · Or wants to learn about it



"Explain in a human-understandable way how to solve constraint satisfaction problems"

Explanation step

Let E' & S' => n be one explanation step.



E' = a subset of previously derived facts E (Sudoku) Given and derived digits in the grid

S' = a minimal subset of constraints S such that E' & S' => n (Sudoku) Alldifferent column, row, box constraints

n = a newly derived fact

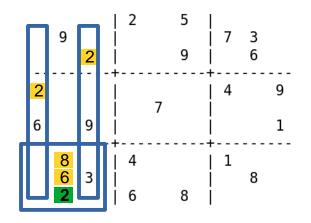
How? MUS(¬n & E & S) is a valid explanation step

The best/easiest explanation step...

Let f(S) be a cost function that quantifies how good (e.g. easy to understand) an explanation step is.

Simple MUS-based algo:

```
sol-to-explain = propagate( E & S ) \ E
X_best = None
for n in sol-to-explain:
    X = MUS(~ n & E & S )
    if f(X) < f(X_best):
        X_best = X
return X best</pre>
```

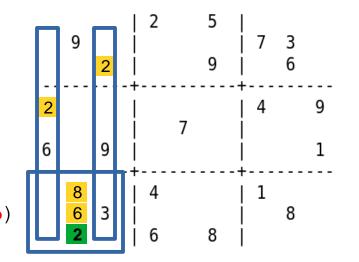


MUS gives no guarantees on quality, only subset minimal (SMUS)

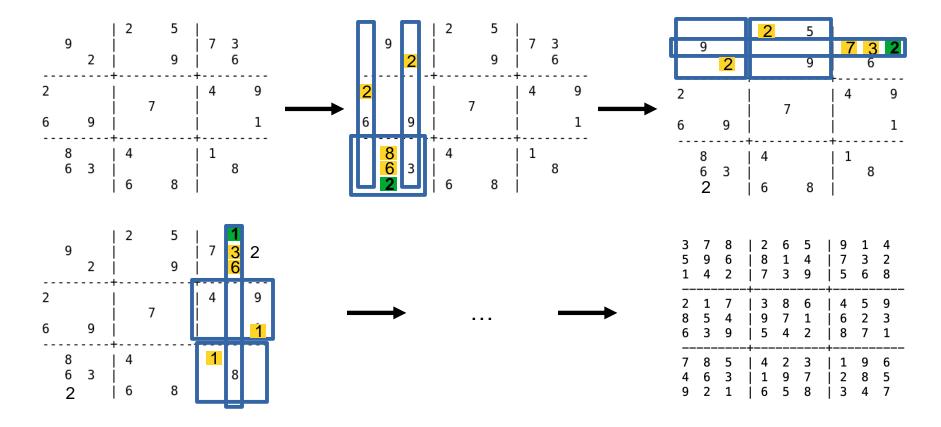
The best/easiest explanation step...

Let f(S) be a cost function that quantifies how good (e.g. easy to understand) an explanation step is.

Explain 1 step with OCUS



A sequence of explanations to explain SAT



Demo OCUS for explaining SUDOKU

cpmpy/examples/tutorial_ijcai22/4_explain_sudoku.ipynb

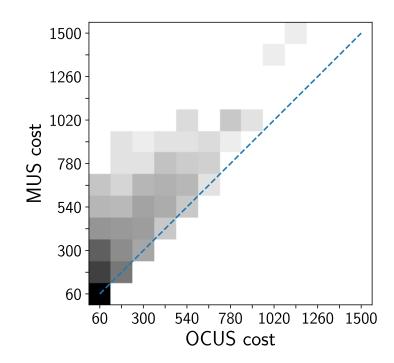
The best/easiest explanation step...

```
sol-to-explain = propagate( E & S ) \ E
```

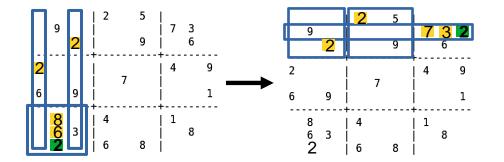
```
X_best = None
for n in sol-to-explain:
    X = MUS(~n & E & S )
    if f(X) < f(X_best):
        X_best = X
return X_best</pre>
```

```
p = exactly-one(\{ \sim n \mid n \in sol-to-explain \}),

OCUS(\{ \sim n \mid n \in sol-to-explain \} \& E \& S, f, p)
```



Incrementality at the Sequence-level



- S Model constraints
 - Do not change from an explanation step to another
- E Derived facts of E
 - Precision-increasing!

Incrementality at the Sequence-level

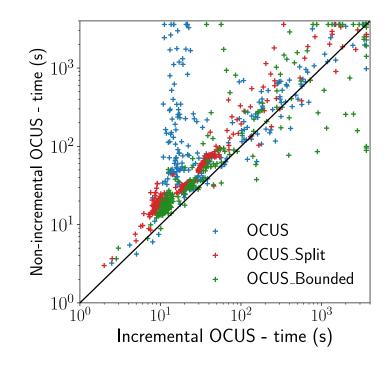
In practice

Incremental OCUS works with the full unsatisfiable formula of step 0

$$S \& \frac{E_{end}}{} \& \{ \neg n \mid n \in \text{sol-to-explain} \}$$

Initialize hitting set solver **once** and modify objective at every explanation step *i* such that

- Underived facts cannot be taken
- Negated facts (¬n) already explained should not be selected
- Assumptions are used to deactivate unused clauses



Summary observations

(OCUS) Multi-solver Incremental solving

Multi-solver

- MIP highly effective solving hittingset problem
- CP/SAT is used as an oracle for checking satisfiability of a subset

Incremental

- Need to repeatedly compute hitting sets.
- Problem becomes <u>hard</u> as collection of sets-to-hits <u>expands</u>.
- Big efficiency gains if incremental (and not restart)!
- (Sequence) Sets-to-hit re-used between explanation steps