

# Using Constraint Solvers as an oracle, with CPMpy

Prof. Tias Guns [<tias.guns@kuleuven.be>](mailto:tias.guns@kuleuven.be)  @TiasGuns

Emilio Gamba [<emilio.gamba@vub.be>](mailto:emilio.gamba@vub.be)

Ignace Bleukx [<ignace.bleukx@kuleuven.be>](mailto:ignace.bleukx@kuleuven.be)

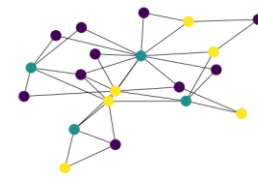
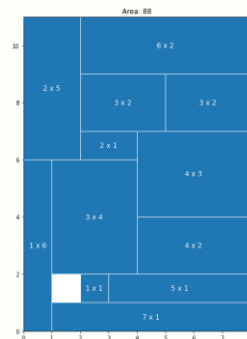
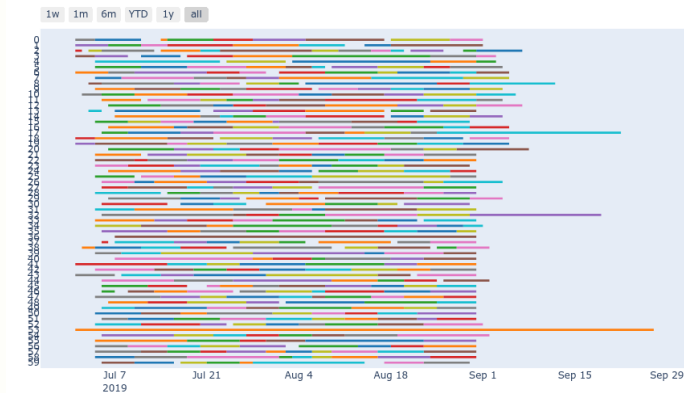
# Constraint solving

## “Solving combinatorial optimisation problems”

- Vehicle Routing
- Scheduling
- Packing
- Other combinatorial problems



P-Large-02 (59 ROOMS), ExitStatus.OPTIMAL (1558.940814725 seconds)



# Solving paradigm

Model



+

Solve

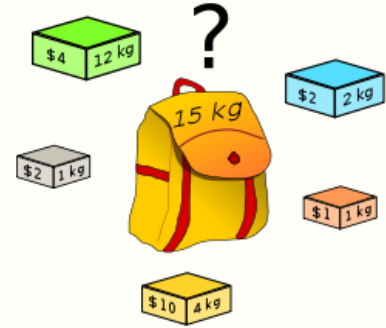


P-Large10 (10 nodes), knapsack-CP2000, (1000 nodes/10 seconds)



# Modeling

## Knapsack:



Model =

- Variables, with a domain
- Constraints over variables
- Optionally: an objective

-  $gr, bl, og, ye, gy :: \{0,1\}$

-  $12*gr + 2*bl + 1*og + 4*ye + 1*gy \leq 15$

-  $\text{maximize}(4*gr + 2*bl + 1*og + 10*ye + 2*gy)$

Model.solve()

#### GETTING STARTED:

Installation instructions

Getting started with Constraint Programming and CPMpy

Quickstart sudoku notebook

More examples

#### USER DOCUMENTATION:

Setting solver parameters and hyperparameter search

Obtaining multiple solutions

UnSAT core extraction with assumption variables

How to debug

Behind the scenes: CPMpy's pipeline

#### API DOCUMENTATION:

Expressions (`cpmpy.expressions`)

Model (`cpmpy.Model`)

Solver interfaces (`cpmpy.solvers`)

Expression transformations  
(`cpmpy.transformations`)

## CPMpy: Constraint Programming and Modeling in Python

CPMpy is a Constraint Programming and Modeling library in Python, based on numpy, with direct solver access.

Constraint Programming is a methodology for solving combinatorial optimisation problems like assignment problems or covering, packing and scheduling problems. Problems that require searching over discrete decision variables.

CPMpy allows to model search problems in a high-level manner, by defining decision variables and constraints and an objective over them (similar to MiniZinc and Essence<sup>1</sup>). You can freely use numpy functions and indexing while doing so. This model is then automatically translated to state-of-the-art solver like or-tools, which then compute the optimal answer.

Source code and bug reports at <https://github.com/CPMpy/cpmPy>

### Getting started:

- [Installation instructions](#)
- [Getting started with Constraint Programming and CPMpy](#)
- [Quickstart sudoku notebook](#)
- [More examples](#)

### User Documentation:

- [Setting solver parameters and hyperparameter search](#)
- [Obtaining multiple solutions](#)
- [UnSAT core extraction with assumption variables](#)
- [How to debug](#)
- [Behind the scenes: CPMpy's pipeline](#)

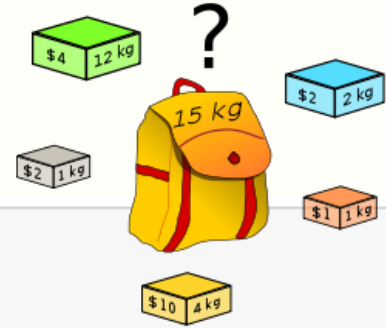
### API documentation:

- [Expressions](#) ( `cpmpy.expressions` )
- [Model](#) ( `cpmpy.Model` )
- [Solver interfaces](#) ( `cpmpy.solvers` )
- [Expression transformations](#) ( `cpmpy.transformations` )

<https://cpmpy.readthedocs.io/>

# Modeling

## Knapsack:



Model =

- Variables, with a domain
- Constraints over variables
- Optionally: an objective

```
model = Model()

gr,bl,og,ye,gy = boolvar(shape=5)

model += (12*gr + 2*bl + 1*og + 4*ye + 1*gy <= 15)

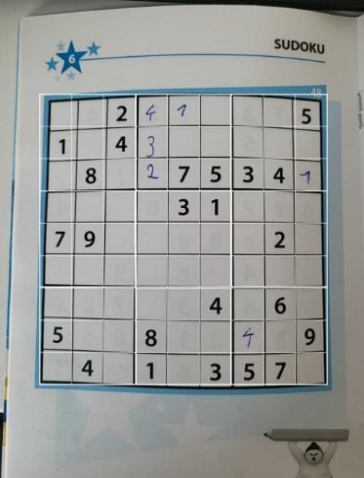
model.maximize(4*gr + 2*bl + 1*og + 10*ye + 2*gy)

model.solve()
```

Model.solve()

```
print(gr.value(), bl.value(), og.value(), ye.value(), gy.value())
```

```
0 1 1 1 1
```



# Modeling

Also satisfaction problems, e.g. *sudoku*

```
e = 0 # value for empty cells
given = np.array([
    [e, e, 2, 4, 1, e, e, e, 5],
    [1, e, 4, 3, e, e, e, e, e],
    [e, 8, e, 2, 7, 5, 3, 4, 1],

    [e, e, e, e, 3, 1, e, e, e],
    [7, 9, e, e, e, e, e, 2, e],
    [e, e, e, e, e, e, e, e, e],

    [e, e, e, e, e, 4, e, 6, e],
    [5, e, e, 8, e, e, 4, e, 9],
    [e, 4, e, 1, e, 3, 5, 7, e]])
```

```
model = Model()

# Variables
puzzle = intvar(1, 9, shape=given.shape, name="puzzle")

# Constraints on rows and columns
model += [AllDifferent(row) for row in puzzle]
model += [AllDifferent(col) for col in puzzle.T]

# Constraints on blocks
for i in range(0, 9, 3):
    for j in range(0, 9, 3):
        model += AllDifferent(puzzle[i:i+3, j:j+3])

# Constraints on values (cells that are not empty)
model += (puzzle[given!=e] == given[given!=e])

model.solve()
```

# Other examples: room scheduling

Demo

[https://github.com/CPMpy/cpm.py/blob/master/examples/  
room\\_assignment.ipynb](https://github.com/CPMpy/cpm.py/blob/master/examples/room_assignment.ipynb)



# Example: room scheduling (backup slide)

```
def model_rooms(df, max_rooms, verbose=True):
    n_requests = len(df)

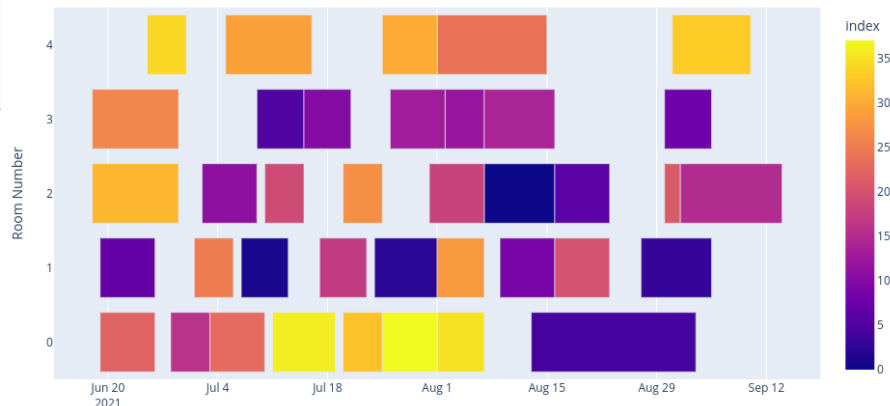
    # All requests must be assigned to one out of the rooms (same room during entire period).
    requestvars = intvar(0, max_rooms-1, shape=(n_requests,))

    m = Model()

    # Some requests already have a room pre-assigned
    for idx, row in df.iterrows():
        if not pd.isna(row['room']):
            m += (requestvars[idx] == int(row['room']))

    # A room can only serve one request at a time.
    # <=> requests on the same day must be in different rooms
    for day in pd.date_range(min(df['start']), max(df['end'])):
        overlapping = df[(df['start'] <= day) & (day < df['end'])]
        if len(overlapping) > 1:
            m += AllDifferent(requestvars[overlapping.index])

    return (m, requestvars)
```



# Solving



`model.solve()`

Depends on solver family...

- SAT: *Boolean* decision variables; *clauses* as constraints
- MIP: *Integer* decision variables; *linear* constraints
- CP: *Integer* decision variables; *logical, mathematical, global* constraints

# The changing role of solvers

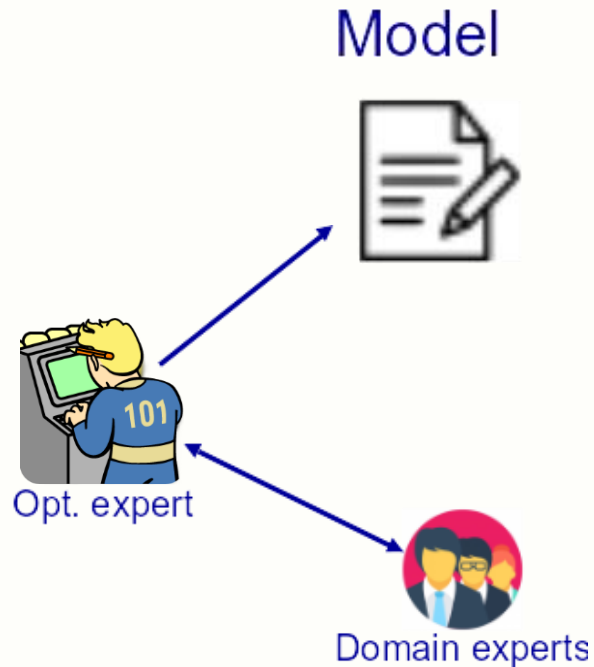
Holy Grail: user specifies, solver solves [Freuder,1997]

I think we reached it... MiniZinc, Essence'

“Beyond NP” → Constraint Solver as an **oracle**

- Use CP solver to solve subproblem of larger algorithm
- Iteratively build-up and solve a problem until failure
- Integrate neural network predictions (structured output prediction)
- Generate proofs, explanations, or counterfactual examples, ...

# Solving paradigm, taking the human in the loop



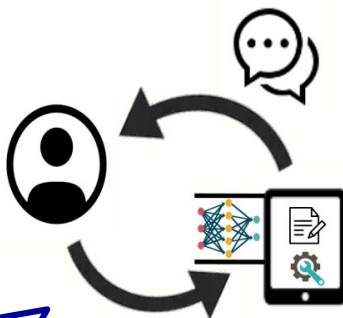
+

Solve





# CHAT-Opt: Conversational **H**uman-**A**ware **T**echnology for **O**ptimisation



Towards **co-creation** of constrained optimisation solutions

- Solver that learns from user and environment
- Towards conversational: explanations and stateful interaction

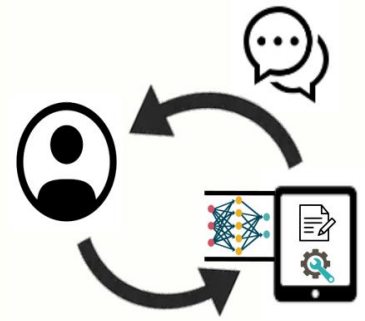
<https://people.cs.kuleuven.be/~tias.gun>



@TiasGuns

Hiring post-docs!

# Towards conversational solving

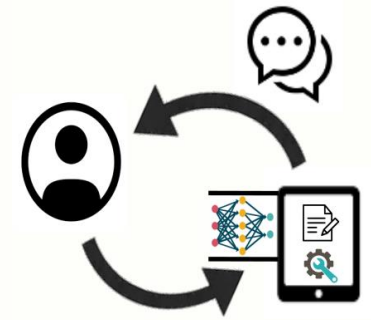


## Asking for explanations

- Why is there no solution?
- How is this solution obtained?
- Why is X part of the solution?
- What are possible alternatives?
- What if Y should be part of the solution?

=> requires “Constraint Solving as oracle”

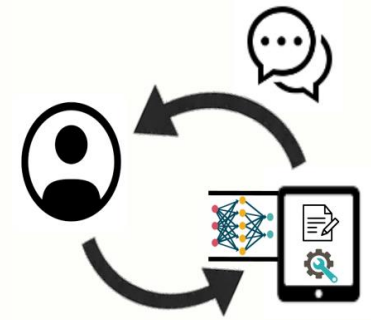
# Conversational **H**uman-**A**ware **T**echnology for **O**ptimisation



What would the ideal Constraint Solving system be?

- Efficient repeated solving  
=> Incremental
- Use CP/SAT/MIP or any combination  
=> solver independent and multi-solver
- Easy integration with Machine Learning libraries  
=> Python and numpy arrays

# Conversational **H**uman-**A**ware **T**echnology for **O**ptimisation



What would the ideal Constraint Solving system be?

- **Efficient repeated solving**  
=> Incremental
- Use CP/SAT/MIP or any combination  
=> solver independent and multi-solver
- Easy integration with Machine Learning libraries  
=> Python and numpy arrays



# Incrementality

Solving:

- MIP: can add constraints, change objective  
(mechanisms not documented, e.g. start from previous basis)
- SAT: *assumption* variables: can be toggled on/off when calling solve, adding constraints  
(reuses learned clauses, variable activity)
- CP: if CP-SAT, assumption variables like SAT, adding constraints and changing objective
- SMT: all of the above and push/pop of constraints (Z3)

Modeling?

- Only if using solver API directly...
- With CPMpy: part of the high-level modeling language!

# Multiple solutions

```
x = intvar(0,3, shape=2)
m = Model(x[0] > x[1])

while m.solve():
    print(x.value())
    m += ~all(x == x.value()) # block solution
```

```
[3 0]
[3 1]
[3 2]
[2 0]
[1 0]
[2 1]
```

Returns True (sol. found) or False (no solution)

Adds constraint to model (even if already solved before)

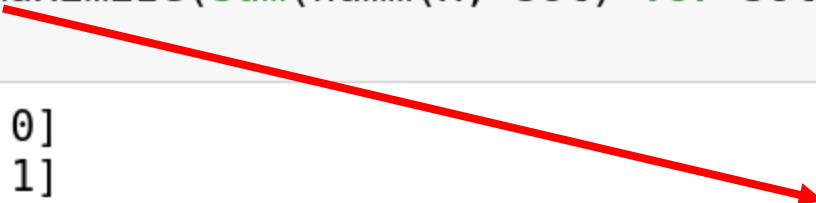
# Alternative (diverse) solutions

```
# a diversity measure, hamming distance
def hamm(x, y):
    return sum(x != y)

x = intvar(0,3, shape=2)
m = Model(x[0] > x[1])

store = []
while m.solve():
    print(len(store), ":", x.value())
    m += ~all(x == x.value()) # block solution
    store.append(x.value())
    # maximize number of elements that are different
    m.maximize(sum(hamm(x, sol) for sol in store))
```

```
0 : [3 0]
1 : [2 1]
2 : [1 0]
3 : [3 2]
4 : [2 0]
5 : [3 1]
```



Can change  
obj. function  
(even if already  
solved before)

# Incremental room assignment problem

```
def model_rooms(df, max_rooms, verbose=True):
    n_requests = len(df)

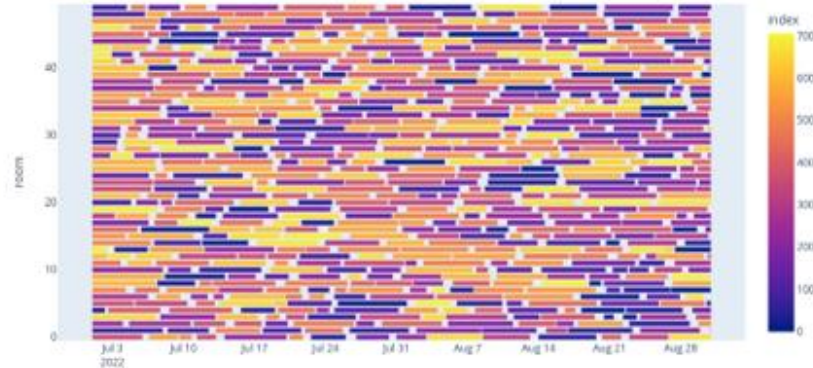
    # All requests must be assigned to one out of the rooms (same room during entire period).
    requestvars = intvar(0, max_rooms-1, shape=(n_requests,))

    m = Model()

    # Some requests already have a room pre-assigned
    for idx, row in df.iterrows():
        if not pd.isna(row['room']):
            m += (requestvars[idx] == int(row['room']))

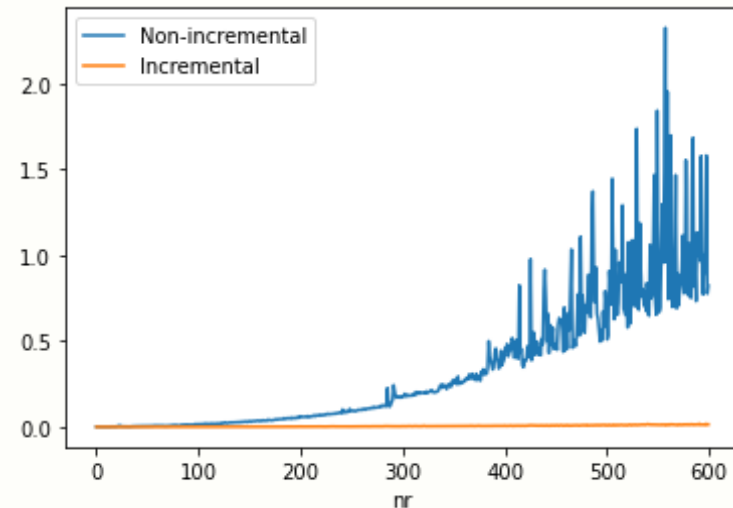
    # A room can only serve one request at a time.
    # <=> requests on the same day must be in different rooms
    for day in pd.date_range(min(df['start']), max(df['end'])):
        overlapping = df[(df['start'] <= day) & (day < df['end'])]
        if len(overlapping) > 1:
            m += Alldifferent(requestvars[overlapping.index])

    return (m, requestvars)
```

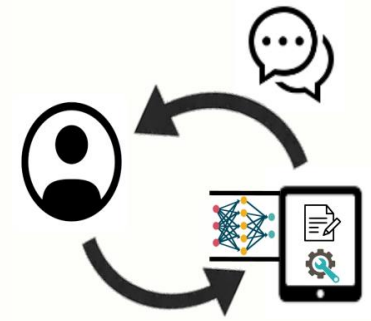


Assume requests come in sequentially.

Compute solution on every new request.



# Conversational **H**uman-**A**ware **T**echnology for **O**ptimisation



What would the ideal Constraint Solving system be?

- Efficient repeated solving  
=> Incremental
- **Use CP/SAT/MIP or any combination**  
=> solver independent and multi-solver
- Easy integration with Machine Learning libraries  
=> Python and numpy arrays

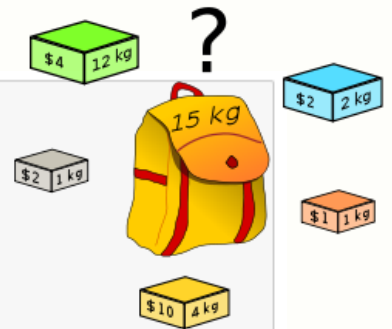
# Multi-solver

Same syntax, plus can reuse variables and their values

```
m_ort = SolverLookup.get("ortools", model_knapsack)
m_ort.solve()
print("\nOrtools:", m_ort.status(), ":", m_ort.objective_value(), items.value())

m_grb = SolverLookup.get("gurobi", model_knapsack)
m_grb.solve()
print("\nGurobi:", m_grb.status(), ":", m_grb.objective_value(), items.value())

# use ortools to verify the gurobi solution
m_ort += (items == items.value())
print("\tGurobi's is a valid solution according to ortools:", m_ort.solve())
```

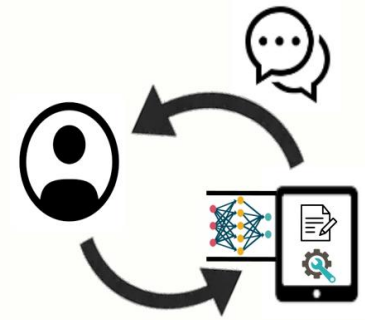


Ortools: ExitStatus.OPTIMAL (0.001146096 seconds) : 32.0 [ True False False True True True True True]

Gurobi: ExitStatus.OPTIMAL (0.0003108978271484375 seconds) : 32.0 [ True False True False True True True True]

Gurobi's is a valid solution according to ortools: True

# Conversational **H**uman-**A**ware Technology for **O**ptimisation



## What would the ideal CP system be?

- Efficient repeated solving  
=> Incremental
- Use CP/SAT/MIP or any combination  
=> solver independent and multi-solver
- **Easy integration with Machine Learning libraries**  
=> **Python and numpy arrays**  
Not covered, but see

[https://github.com/CPMpy/cpm.py/blob/master/examples/advanced/visual\\_sudoku.ipynb](https://github.com/CPMpy/cpm.py/blob/master/examples/advanced/visual_sudoku.ipynb)

# 3 short slides on CPMpy's design

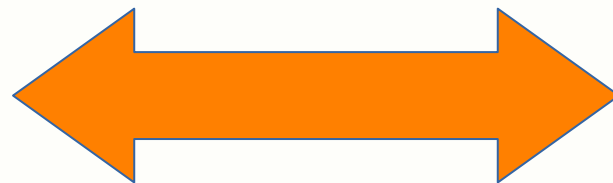
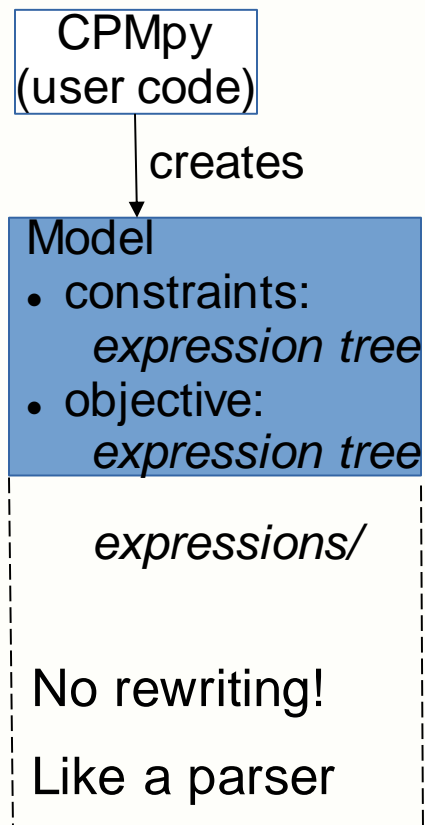
Design principle:

Aim to be a thin layer on top of solver API

Central concept: CPMpy expression

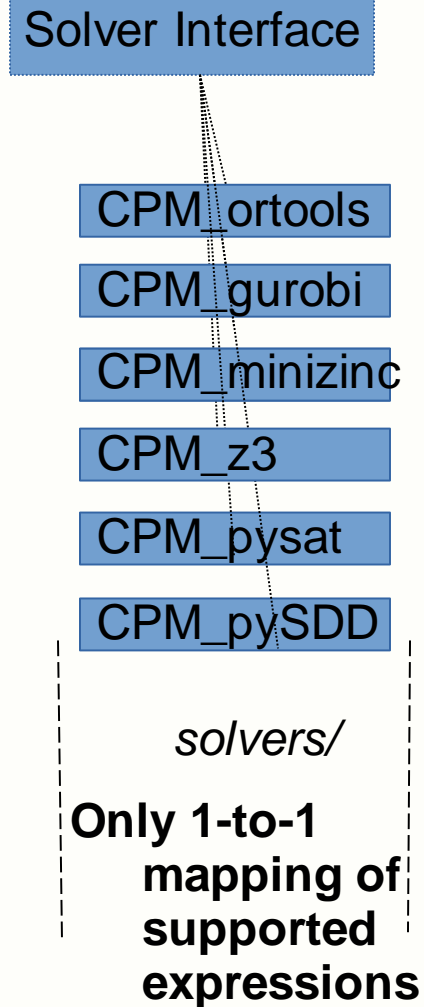


# Design

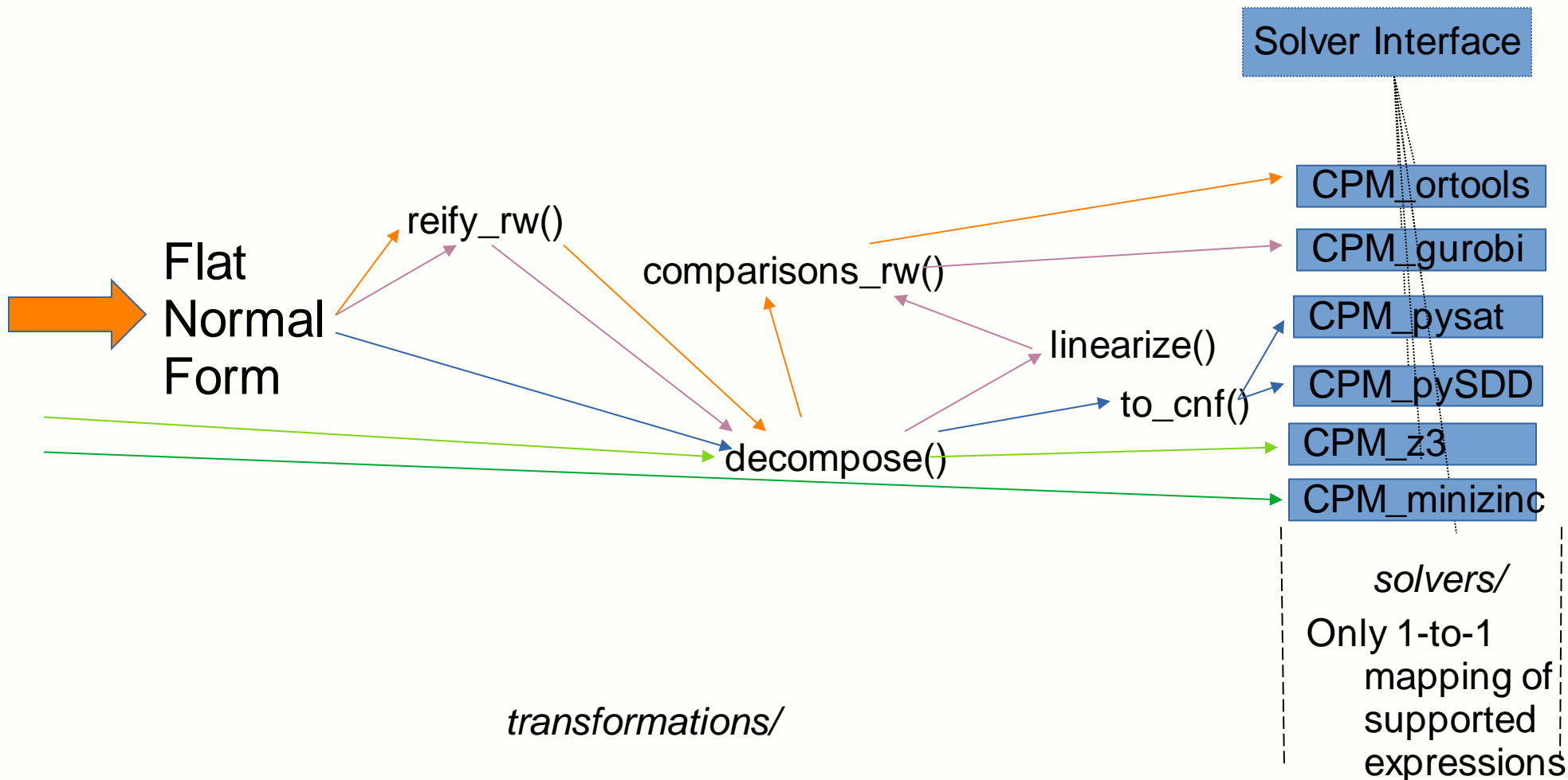


Hardest part

*transformations/*



# Transformations in a nutshell



# Solvers

CPMpy only interfaces to Python APIs

Key principle: solver can implement any subset of expressions!

Solvers can also choose to:

- Support assumptions or not
- Be incremental or not
- Expose own solver parameters

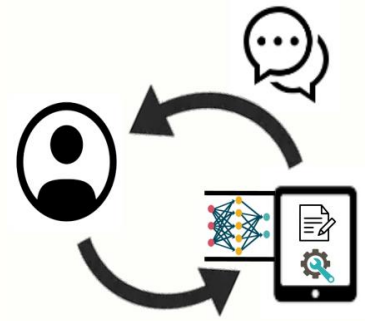
Currently:

- ortools
- pysat
- minizinc
- gurobi
- pySDD

Near future: ExactSolver, Z3

Wishlist: Mistral2, Geas, Gecode

# Towards conversational solving



## Asking for explanations

- Why is there no solution?
- How is this solution obtained?
- Why is X part of the solution?
- What are possible alternatives?
- What if Y should be part of the solution?

=> requires “Constraint Solving as oracle”