

Unit-I :-

1- Complex Number System

2- Functions of complex Variables ($w = f(z)$)

3. Limit, Continuity, Differentiability (L, C, D)
of $w = f(z)$.

4. Analyticity and its properties

5. Singularities

Unit-II :-

Complex Integration :-

1- Fundamental of complex integration
(Curve & Defn of complex integration)

2- Theorems on complex integration

3- C.I.F., C.I.F.D., C.I.F.H.D.

(Cauchy Integral Formula), (Cauchy Integral formula
for Derivative), (Cauchy Integral Formula for Higher Derivative)

4- ~~Liouville~~ Liouville's Theorem and its applications *

Unit-III :-

1 Series and Expansions:-

1- Power series *

2- Taylor series

3- Laurent's expansion or, Laurent's series

- 4 - Application of Laurent's and Taylor's expansion
- (a) Zeros of analytic functⁿ
 - (b) Extension of Liouville's theorem
 - (c) Singularities re-visited
 - (d) Residue at $z=a$: $\text{Res}(f(z), a)$

Unit - IV

Special Types of Funct^{ns}

1. Meromorphic functⁿ / Rational functⁿ
- 2.
2. Argument Theorem / Argument functⁿ
3. Rouché's Theorem *

Unit - V

Conformal mapping

1. Fundamental of Conformality
2. Bilinear / Möbius Transformation
 & Linear Fractional Transformation
3. Maximum / Minimum Modulus Principle
4. Schwarz's lemma and its application.

#

$$x+1=0$$

$$-1$$

$$2x-1=0$$

$$\frac{1}{2}$$

$$x^2-2=0$$

$$\sqrt{2}$$

$$x^2+1$$

$$i = \sqrt{-1}$$

then, we have

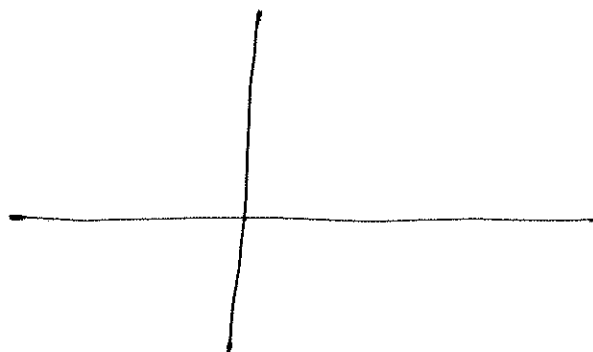
$$\mathbb{C} = \{x+iy : x, y \in \mathbb{R}\}$$

called the complex number system

For every complex no. $z = x+iy$

there is unique $(x, y) \in \mathbb{R}^2$, denoting the position of z .

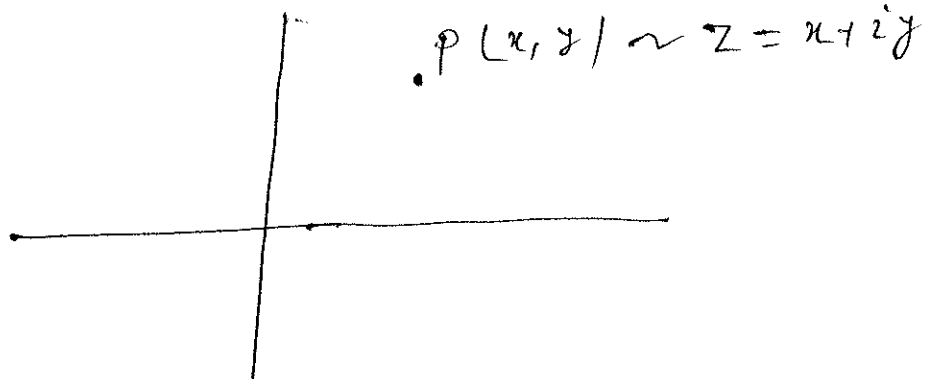
i.e., at every pt. of the cartesian plane, there is a complex number and conversely



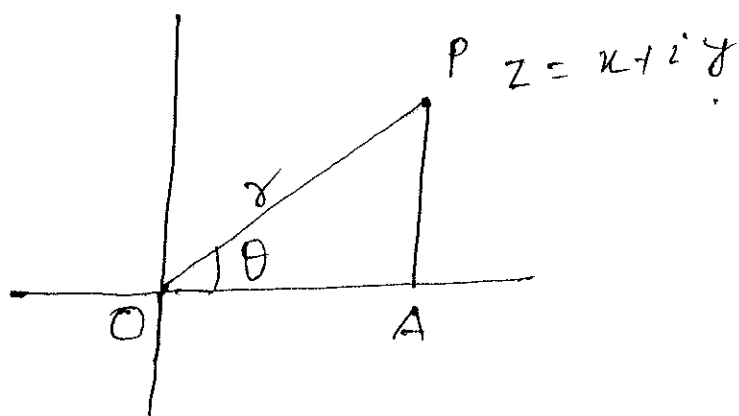
~~# When in the Cartesian plane~~

When at any point in the Cartesian plane we obtain a complex number, the plane is called Complex-plane or Argand-plane or,

or, z -plane.



#



$$x = r \cos \theta, \quad y = r \sin \theta$$

then $z = x + iy$ has equivalent form (r, θ) called polar form of $z = x + iy$.

$$(r, \theta) \in \mathbb{R}^2$$

Note:- $z = 0 + i0$ has no polar form. ($\because r = 0$)

\swarrow
#

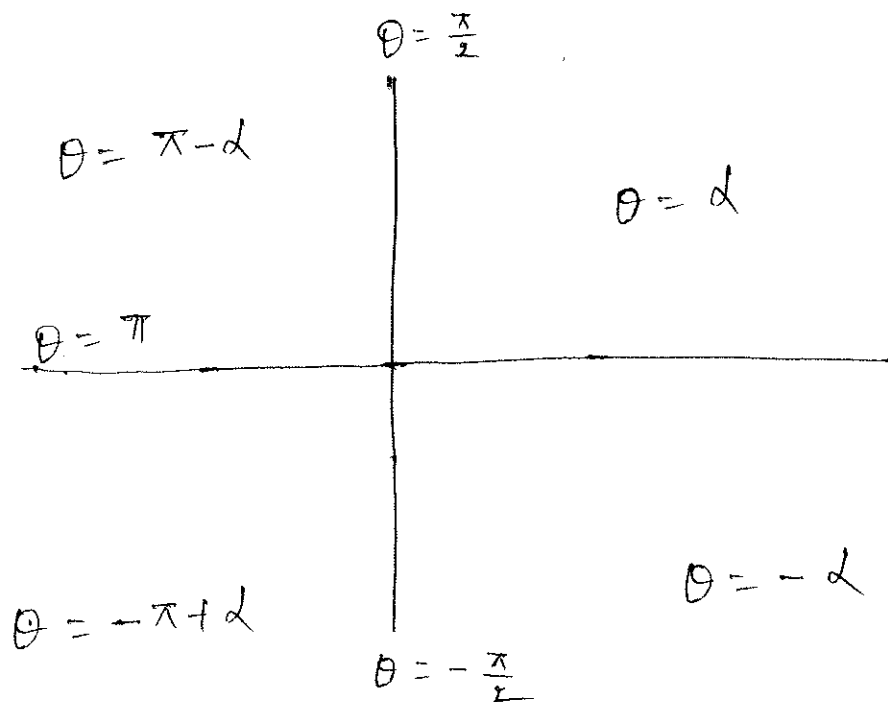
Principal Argument of z ($\text{Arg } z$) :-

$$\begin{aligned} \text{Arg } z &\equiv \text{Principal Argument} \\ &= \theta \in (-\pi, \pi] \end{aligned}$$

$$\text{Let } z = x + iy \neq 0 ; x \neq 0$$

$$\phi = \tan^{-1} \left| \frac{y}{x} \right|$$

$$\Rightarrow 0 \leq \phi < \frac{\pi}{2}$$



e.g. $z = -1 + 4i$

$\rightarrow \tan \alpha = \left| \frac{4}{-1} \right| \Rightarrow \alpha = \tan^{-1}(4)$

$$\begin{aligned} \therefore \arg z &= \pi - \tan^{-1}(4) \\ &= 180^\circ - 76^\circ \\ &= 104^\circ \end{aligned}$$

$\arg z = \{ \text{Arg } z + 2n\pi : n \in \mathbb{Z} \}$

$|z| = \text{Absolute value of } z$
 $= \sqrt{x^2 + y^2} = r.$

$$\theta = \begin{cases} 0 & x > 0, y = 0 \\ \tan^{-1} \left| \frac{y}{x} \right| & x > 0, y > 0 \\ \frac{\pi}{2} & x = 0, y > 0 \\ \pi - \tan^{-1} \left| \frac{y}{x} \right| & x < 0, y > 0 \end{cases}$$

$$\left\{ \begin{array}{ll} \pi & x < 0, y = 0 \\ -\pi + \tan^{-1} \left| \frac{y}{x} \right| & x < 0, y < 0 \\ -\frac{\pi}{2} & x = 0, y < 0 \\ -\tan^{-1} \left| \frac{y}{x} \right| & x > 0, y < 0 \end{array} \right.$$

if $\text{Arg } z = \theta, |z| = r$

$$\begin{aligned} \text{then } z &= r e^{i\theta} \\ &= r \cos \theta + i r \sin \theta \\ &= x + iy \end{aligned}$$

$$\left(\begin{aligned} \therefore e^{i\theta} &= 1 + \frac{i\theta}{1!} + \frac{(i\theta)^2}{2!} + \dots \\ &= \cos \theta + i \sin \theta \end{aligned} \right)$$

Log z :-

$$\begin{aligned} \log z &= \log(r e^{i\theta}) \\ &= \log r + \log e^{i\theta} \\ &= \log r + i\theta \\ &= \log r + i(\theta + 2n\pi) \end{aligned}$$

$\Rightarrow \log z$ has infinite values

$$\log z = \boxed{\log r + i \text{Arg } z}$$

↓
Principal value of $\log z$

Note:- $\log(z_1 z_2)$ may not be $\log z_1 + \log z_2$.

if $a, b \in \mathbb{C}$

a^b may have more than one values.

$$\boxed{\text{Principal value of } a^b = e^{b \log a}}$$
$$= e^{b \cdot \text{P.V. of } \log a}$$

e.g. Find principal value of $(1+i)^i$

$$\rightarrow \text{P.V. of } (1+i)^i = e^{i \log(1+i)}$$
$$= e^{i (\log \sqrt{2} + i \frac{\pi}{4})}$$

$$= e^{-\frac{\pi}{4} + i \log \sqrt{2}}$$

$$= e^{-\frac{\pi}{4}} \cdot e^{i \log \sqrt{2}}$$

$$= e^{-\frac{\pi}{4}} \cos(\log \sqrt{2}) + i e^{-\frac{\pi}{4}} \sin \log \sqrt{2}$$

$$\therefore \text{Re}(\text{P.V. of } (1+i)^i) = e^{-\frac{\pi}{4}} \cos \log \sqrt{2}.$$

e.i.

$$\text{P.V. of } i^i = e^{i \log i}$$

$$= e^{i (i \frac{\pi}{2})}$$

$$= e^{-\frac{\pi}{2}}$$

$$= \frac{1}{e^{\frac{\pi}{2}}}$$

$$\left(\because \log i = \log 1 + i \frac{\pi}{2} \right)$$

Note:-

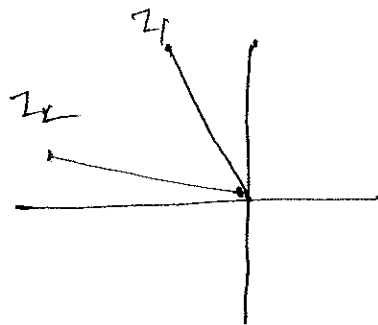
$$\textcircled{i} \quad e^{ix} = \cos x + i \sin x ; x \in \mathbb{R}$$

$$\text{but } e^{iz} \neq \cos z + i \sin z ; z \in \mathbb{C}.$$

$$\textcircled{ii} \quad |e^{ix}| = 1 ; x \in \mathbb{R}$$

$$\text{but } |e^{iz}| \neq 1 ; z \in \mathbb{C} \text{ (in general)}.$$

e.g.:



$$\text{Let } \text{Arg } z_1 = \pi - \frac{\pi}{3}$$

$$\text{Arg } z_2 = \pi - \frac{\pi}{6}$$

$$\log z_1 + \log z_2 = \log r_1 r_2 + i \left(\pi - \frac{\pi}{3} - \frac{\pi}{6} \right)$$

$\theta'' > \pi$

$$\text{but } \log z_1 z_2 = \log r + i \underbrace{\theta}_{\hat{< \pi}}$$

Note:-

$$e^z = e^{x+iy}$$

$$= e^x \cdot e^{iy}$$

$$= e^x \cos y + i e^x \sin y$$

$$\text{Re } e^z = e^x \cos y$$

$$\text{Im } e^z = e^x \sin y$$

Index:-

1. Vector Spaces and Sub-Spaces (Fundamental)
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7. Matrix of Linear Transformation
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Vector Spaces and Sub-Spaces:

External Composition:

Let $f: A \times B \longrightarrow C$
adopt $'*'$ for $f(a, b) = a * b \quad \forall (a, b) \in A \times B$

i.e., if $f(a, b) = c$

We write
 $a * b = c$

$'*'$ is called an external composition. (w/ $A \neq B$ in this order)
if $A = B = C \Rightarrow *$ is Binary Operation
or, internal composition.

e.g. $B = \mathbb{R}[x] - \{0\}$

$$A = \mathcal{P}$$

$$C = \mathbb{N} \cup \{0\}$$

define $f: A \times B \longrightarrow C$

$$f(d, p(x)) = \deg(d \cdot p(x))$$

e.g. $f: \mathbb{Z} \times \mathcal{P}^* \longrightarrow \mathcal{P}^*$

$$f(d, a) = a^d$$

$$d * a = a^d$$

Vector Space:

Let $(V, +)$ be an abelian group $+ is a notation for the binary operation on $V$$

e.g. $V = \{ I, (12), (34), (12)(34) \}$

$$(V, +)$$

$$(12) + (12) = I$$

Let $(F, +, \cdot)$ be a field.

define $F \times V \longrightarrow V$
an external composition,

$$d \in F, X \in V$$

$$d \cdot X = f(d, X) \in V$$

then V forms vector space over F .

if (i) $\forall d, \beta \in F, X \in V$

$$(d + \beta) \cdot X = d \cdot X + \beta \cdot X$$

(ii) $\forall d \in F, X, Y \in V$

$$d \cdot (X + Y) = d \cdot X + d \cdot Y$$

(iii) $\forall d, \beta \in F, X \in V$

$$(d \cdot \beta) \cdot X = d \cdot (\beta \cdot X)$$

(iv) $1 \in F, X \in V, 1$ is unity of F

$$1 \cdot X = X$$

The elements of V are called vectors and that of F are scalars, we may also think in this way, the elements of V are objects and that of F are multiples.

The identity of $(V, +)$ will be referred as zero vector and denoted by $\bar{0}$.

And $0 \in F$ is called '0' scalar.

Scalars are always ~~just~~ kept on the left of vectors.

~~# (i) $\bar{0} \cdot X = \bar{0} \quad \forall X \in V$~~

(i) $0 \cdot X = \bar{0} \quad \forall X \in V, 0 \in F$

(ii) $c \cdot \bar{0} = \bar{0} \quad \forall c \in F$

(iii) $(-1) \cdot X = -X, -1 \in F; -1$ is the additive inverse of unity.

Ex:-

$$(V, +) = (\mathbb{R}^+, \cdot)$$

$$(F, +, \cdot) = (\mathbb{R}, +, \cdot)$$

$$a \in F, X \in V = \mathbb{R}^+$$

$$a \cdot X = X^a$$

V is a vector space over \mathbb{R} .

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Let $(V, +)$ be an abelian. ($+$ is the notation for the B.O. on V) $\& (F, +, \cdot)$ be a field.

if $f: F \times V \longrightarrow V$ s.t.

$$f(d, X) = d \cdot X$$

then V forms V.S. over F .

$$(i) (d + \beta) \cdot X = d \cdot X + \beta \cdot X$$

$$(ii) d \cdot (X + Y) = d \cdot X + d \cdot Y$$

$$(iii) (d \cdot \beta) \cdot X = d \cdot (\beta \cdot X)$$

$$(iv) 1 \cdot X = X$$

$\forall d, \beta \in F$
 $\forall X, Y \in V$

e.g. $(V, +) = (\mathbb{R}^+, \cdot)$

$$F = \mathbb{R}$$

$$f: F \times V \longrightarrow V$$

$$f(d, X) = X^d$$

\rightarrow here, (\mathbb{R}^+, \cdot) is an abelian gp ✓
 \mathbb{R} is a field ✓

$$(i) (d + \beta) \cdot X = X^{d+\beta}$$

$$d \cdot X + \beta \cdot X = X^d \cdot X^\beta = X^{d+\beta}$$

$$\therefore (d + \beta) \cdot X = d \cdot X + \beta \cdot X$$

$$(ii) d \cdot (X + Y) = (X + Y)^d$$

$$= (X \cdot Y)^d = X^d \cdot Y^d$$

$$= d \cdot (X \cdot Y)$$

$$(iii) (d \cdot \beta) X = X^{d \cdot \beta}$$

$$\begin{aligned} i \quad d \cdot (\beta \cdot X) &= d \cdot X^\beta \\ &= (X^\beta)^d \\ &= X^{\beta d} = X^{d \cdot \beta} \end{aligned}$$

$$(iv) 1 \cdot X = X^1 = X$$

Ex 2:-

Let $(R, +, \cdot)$ be a ring

then if $V = R \Rightarrow (V, +)$ is an abelian group.

Let $F \leq R$ s.t. F is a field.

define $f: F \times V \longrightarrow V$

$$as \quad f(d, X) = d \cdot X$$

where \cdot is that of $(R, +, \cdot)$

f is well defined as $d, X \in R$.

Now,

as $\forall d, \beta \in F, X, Y \in V \Rightarrow d, \beta, X, Y \in R$

and $(R, +, \cdot)$ is ring \Rightarrow

- (i) $\checkmark \quad (d + \beta) \cdot X = d \cdot X + \beta \cdot X$
- (ii) $\checkmark \quad d \cdot (X + Y) = d \cdot X + d \cdot Y$
- (iii) $\checkmark \quad (d \cdot \beta) \cdot X = d \cdot (\beta \cdot X)$

if the unity of F & R are same, then

same $1 \cdot X = X \quad \forall X \in R$.

\Rightarrow "the additive gp of any ring R forms V.S. over its subring (which is field) if unity of R & the subring are same and the external composition is the multiplication of $(R, +, \cdot)$ ".

eg. 3

$$\text{Let } (R, +, \cdot) = (\mathbb{Z}_{10}, +_{10}, \cdot_{10})$$

$$(V, +) = (\mathbb{Z}_{10}, +_{10})$$

$\Rightarrow V$ is abelian gp.

$$F = \{0, 2, 4, 6, 8\}$$

$\Rightarrow (F, +_{10}, \cdot_{10})$ is field

but V doesn't form V.S. over F as unity of R is 1 and that of F is 6.

Ex 4:

$$R = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : a, b, c, d \in \mathbb{R} \right\}$$

$(R, +, \cdot)$ is a ring

$\Rightarrow V = R$, then $(V, +)$ is an abelian gp.

$$F = \left\{ \begin{bmatrix} a & a \\ a & a \end{bmatrix} : a \in \mathbb{R} \right\}$$

$(F, +, \cdot)$ is a field and $F \subset R$

if u.t. of $(R, +, \cdot)$ is taken the external compo. V doesn't form V.S. over F .

$$\text{as } I = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \in F \text{ and } X = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \in V$$

$$I \cdot X = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} \neq X.$$

Jai Maa Saraswati

Set: — A collection of well defined distinct objects is defined as a set.

By well defined we mean, there is no confusion or ambiguity regarding the inclusion or the exclusion of the object.

* If cardinality of A is n i.e., $|A| = n$ then $|P(A)| = 2^n$.

Proof: — Let $|A| = n$, then

No. of subsets of A having no element = nC_0
" " " " " " = nC_1
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No. of subsets of A having n element = nC_n

We have,

$${}^nC_0 + {}^nC_1 + \dots + {}^nC_n = |P(A)| \quad \text{--- (I)}$$

By Binomial theorem,

$$(1+x)^n = {}^nC_0 + {}^nC_1 x + \dots + {}^nC_n x^n \quad \text{--- (II)}$$

On comparing (I) & (II),

we get $x = 1$

$$\therefore |P(A)| = (1+1)^n = 2^n.$$

Ind method:-

$$\text{Let } A = \{x_1, x_2, \dots, x_n\}$$

inclusion exclusion
2 ways

$$\therefore |P(A)| = \underbrace{2 \times 2 \times \dots \times 2}_n$$
$$= 2^n.$$

Q. Let A be the set ~~having~~ containing $(2n+1)$ elements, then the number of subsets of A having more than n elements is

(a) 2^{n-1}

(b) 2^n

(c) 2^{n+1}

~~(d) 2^{2n}~~

Soln:-

$${}^{2n+1}C_0 + {}^{2n+1}C_1 + \dots + {}^{2n+1}C_n + \overbrace{{}^{2n+1}C_{n+1} + \dots + {}^{2n+1}C_{2n+1}}^{\alpha}$$
$$= 2^{2n+1}$$

$$\Rightarrow \alpha + \alpha = 2^{2n+1}$$

$$\therefore {}^{2n+1}C_n = {}^{2n+1}C_{n+1}$$
$$\dots$$
$${}^{2n+1}C_0 = {}^{2n+1}C_{2n+1}$$

$$\Rightarrow 2\alpha = 2^{2n+1}$$

$$\alpha = 2^{2n}$$

Ans - (d)

Cartesian Product:-

Let A & B be any two non-empty sets

define $A \times B = \{(a, b) : a \in A, b \in B\}$

Then, $A \times B$ is defined as Cartesian product of A & B .

If either A or B is empty, then

$$A \times B = \phi.$$

Properties:

i) If $|A| = m$, $|B| = n$

then $|A \times B| = m \times n = mn$

$$\text{ii) } (A \cup B) \times C = (A \times C) \cup (B \times C)$$

$$\text{iii) } (A \cap B) \times C = (A \times C) \cap (B \times C).$$

$$\text{iv) } (A \times B) \cap (C \times D) = (A \cap C) \times (B \cap D).$$

Q. If A and B have 99 elements in common then the no. of elements common to $A \times B$ and $B \times A$ is.

(i) 100 (ii) 2^{99} (iii) 99^2 (iv) 101.

Soln:-

$$\begin{aligned}(A \times B) \cap (B \times A) &= (A \cap B) \times (B \cap A) \\ &= 99 \times 99 \\ &= 99^2\end{aligned}$$

Relation: -

Let A and B be any two sets any subset of $A \times B$ is defined as relation from A to B .

Two relations are said to be ~~different~~ distinct if and only if they correspond to different subsets.

if $|A| = m$ and $|B| = n$

Then, No. of relations from A to $B = 2^{mn}$
 $= 2^{|A| \times |B|}$

i.e., ~~Relation~~ .

Types of relⁿs on the set A :

1) Identity relation:

Let A be any set and $S \subseteq A \times A$ is defined as identity relation if every element of A is related to itself only.

i.e., $I = \{(a, a) : a \in A\}$

e.g. $I_1 = \{(1, 1), (1, 1), (2, 2), (2, 3)\} \times$

$I_2 = \{(1, 1), (2, 2)\} \times$

$I_3 = \{(1, 1), (2, 2), (3, 3)\} \checkmark$

Note: - Identity relation is always unique.

2) Reflexive relⁿ:

Let A be any set and $S \subseteq A \times A$
then S is said to be reflexive relⁿ if
 $I \in S$.

e.g. $S = \{(1,1), (2,2), (1,2)\} \times$

$S = \{(1,1), (2,2), (3,3), (1,2)\} \checkmark$

$S = \{(1,1), (2,2), (3,3)\} \checkmark$

If $|A| = n$, then

Total no. of reflexive relⁿ on $A = 2^{n^2-n}$

Proof:-

No. of choices for elements of the type

$(a_i, a_i) = 1$

"

"

"

"

$(a_i, a_j) = 2$

where $i \neq j$

\therefore No. of reflexive relⁿ = $\underbrace{1 \times 1 \times \dots \times 1}_{n \text{ times}} \times \underbrace{2 \times 2 \times \dots \times 2}_{n^2-n \text{ times}}$

$= 2^{n^2-n}$

3) Irreflexive relⁿ:

Let A be any set and $S \subseteq A \times A$

then S is said to be irreflexive relⁿ if

$I \cap S = \emptyset$.

e.g. $A = \{1, 2, 3\}$

$S = \{(1,1), (1,2), (2,3)\} \times$

$S = \{(1,2), (3,2)\} \checkmark$

If $|A| = n$, then

Total no. of reflexive rel^{ns} = 2^{n^2-n}

Proof: —

No. of choices for the elements of the type $(a_i, a_i) = 1$

"

" $(a_i, a_j) = 2$

\therefore No. of reflexive rel^{ns}

$$= \underbrace{1 \times 1 \times \dots \times 1}_{n \text{ times}} \times \underbrace{2 \times 2 \times \dots \times 2}_{n^2-n \text{ times}}$$

$$= 2^{n^2-n}$$

4) Symmetric relⁿ:-

Let A be a relⁿ and $S \subseteq A \times A$

then S is said to be symmetric relⁿ if

$$(a, b) \in S \Rightarrow (b, a) \in S$$

i.e., if $a \sim b$ then $b \sim a$.

Eg:- $A = \{1, 2, 3\}$

$S = \{(1,1), (2,2), (3,3)\} \times$

$$S = \{ (1,1), (2,3), (3,2) \}$$

if $|A| = n$, then

$$\text{Total no. of symmetric solns} = 2^{\frac{n(n+1)}{2}}$$

Proof: -

no. of choices for the elements of type

$$(a_i, a_i) = 2$$

"

"

of the pairs

$$(a_i, a_j) \text{ and } (a_j, a_i) = 2$$

where $i \neq j$

\therefore no. of symmetric solns

$$= \underbrace{2 \times 2 \times \dots \times 2}_{n \text{ times}} \times \underbrace{2 \times 2 \times \dots \times 2}_{\frac{n^2-n}{2} \text{ times}}$$

$$= 2^n \times 2^{\frac{n^2-n}{2}}$$

$$= 2^{n + \frac{n^2-n}{2}}$$

$$= 2^{\frac{n^2+n}{2}}$$

$$= 2^{\frac{n(n+1)}{2}}$$

$$= 2^{\frac{n(n+1)}{2}}$$

$$(a_i, a_j) \notin (a_j, a_i) \in S$$

Or, Neither

$$(a_i, a_j) \notin (a_j, a_i) \in S$$

5) Asymmetric relations:-

16/07/2019

Let A be any set and $S \subseteq A \times A$,

then S is said to be asymmetric relation if
 $(a, b) \in S \Rightarrow (b, a) \notin S$

Note:- If rel^n is asymmetric then it is ~~not~~ reflexive.

i.e., Asymmetric \Rightarrow Irreflexive Rel^n

Eg:- $A = \{1, 2, 3\}$

$$S = \{(1, 1), (2, 3)\} \quad \times$$

$$S = \{(2, 3), (3, 2)\} \quad \times$$

$$S = \{(2, 3)\} \quad \checkmark$$

Syllabus

5-6
18-23

1. Introduction

2. Order & Degree of the D.E.

3. Formation of D.D.E.

4. First Order and First degree D.E.

Q. (i) Separation of Variable

(ii) Reducible to separation of variable

(iii) Homogeneous D.E.

(iv) Reducible to Homⁿ. D.E.

(v) Exact + I.F.

(vi) Reducible to Exact D.E.

(vii) Linear D.E.

(viii) Reducible L.D.E.

(ix) Bernoulli Eqⁿ

5. First order ~~and~~ but not first degree (Singular solⁿ)

6. Linear D.E. with constant coefficient

7. Linear D.E. with variable coefficient

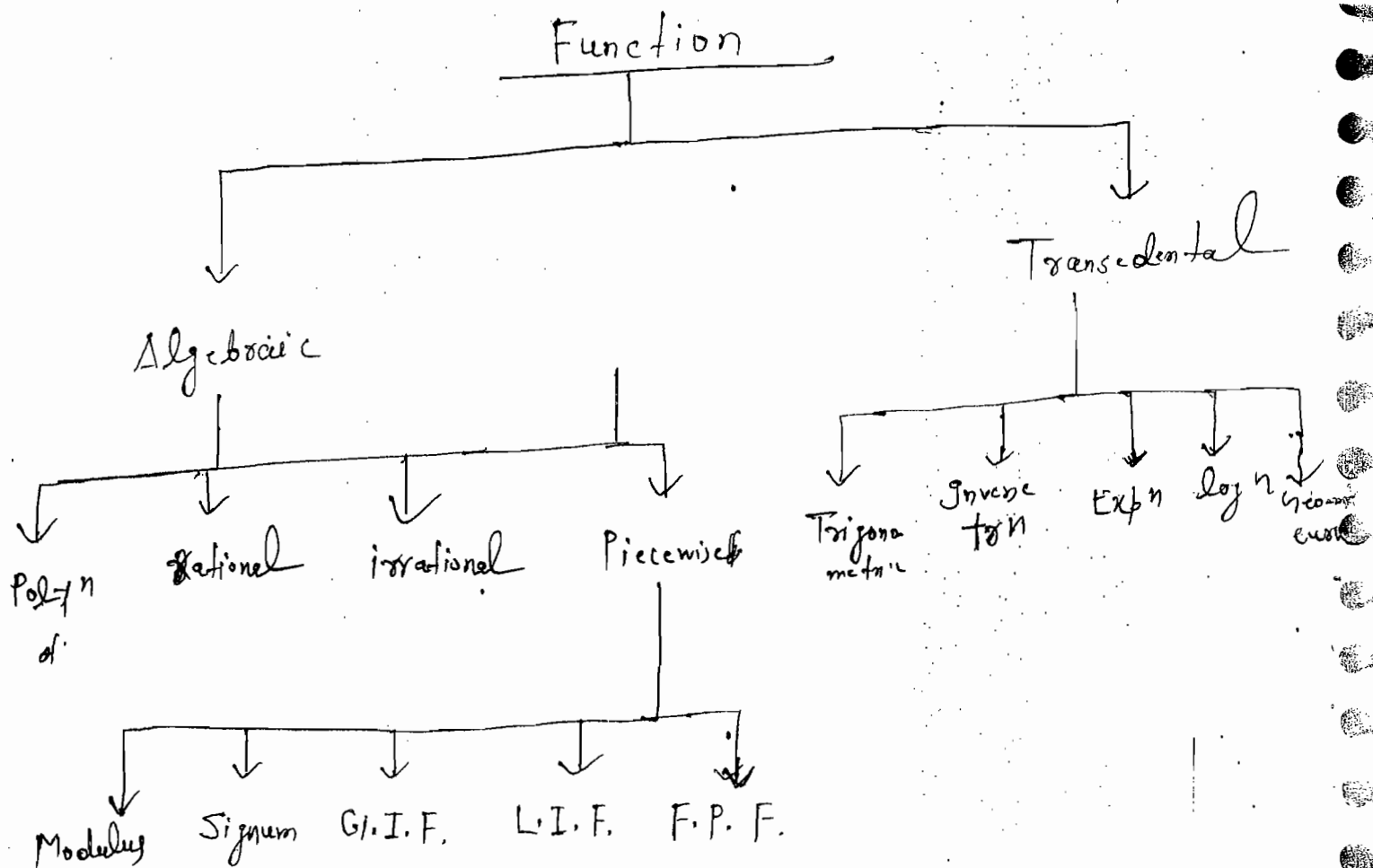
8. Wronskian + Zeros — (1)

9. Uniqueness & Existence — (1)

10. Boundary Value Problem — (1)

11. System of D.D.E. — (1)

12. Green function.



Dependent Variable & Independent Variable:

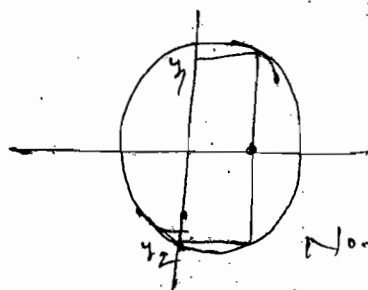
The variable whose value is assigned is called independent variable and the variable whose value is obtained corresponding to assigned value is called dependent variable.

Function:

① Every element in domain having a unique image in codomain.

② $f: A \rightarrow B$

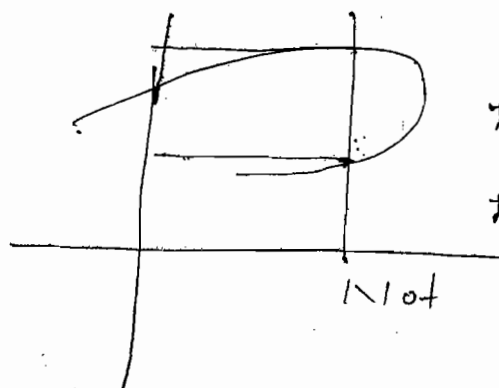
$\forall x \in A: \exists \text{ unique } y \in B \text{ such that } y = f(x).$



$$y = f(x)$$

$$x = f(y)$$

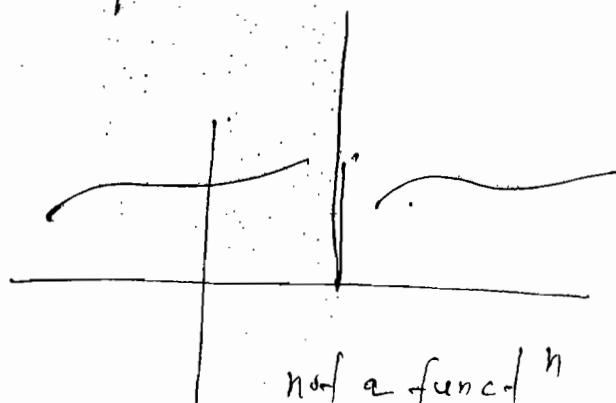
Not unique



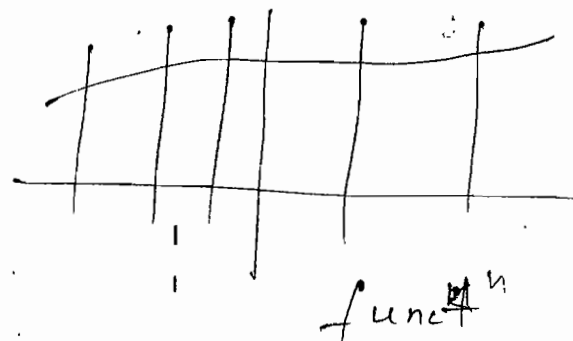
$$y = f(x)$$

$$x = f(y)$$

Not



not a function



function

(iii) Graphical defⁿ:

A mapping $f: A \rightarrow B$ is called a function if any line passing through domain and \parallel to y-axis should intersect the curve $y = f(x)$ exactly once.

1-1 function:

$$f: A \rightarrow B : \rightarrow 1-1$$

$$\Rightarrow \text{if } f(x_1) = f(x_2) \Rightarrow x_1 = x_2$$

$$\text{or } x_1 \neq x_2 \Rightarrow f(x_1) \neq f(x_2)$$



Not 1-1

Since $f(x_1) = f(x_2) = f(x_3) \Rightarrow x_1 = x_2 = x_3$

'A functⁿ' $f: A \rightarrow B$ is called 1-1, if f any line passing through co-domain and \parallel to x -axis should intersect the curve $y = f(x)$ at most once.

Onto functⁿ:

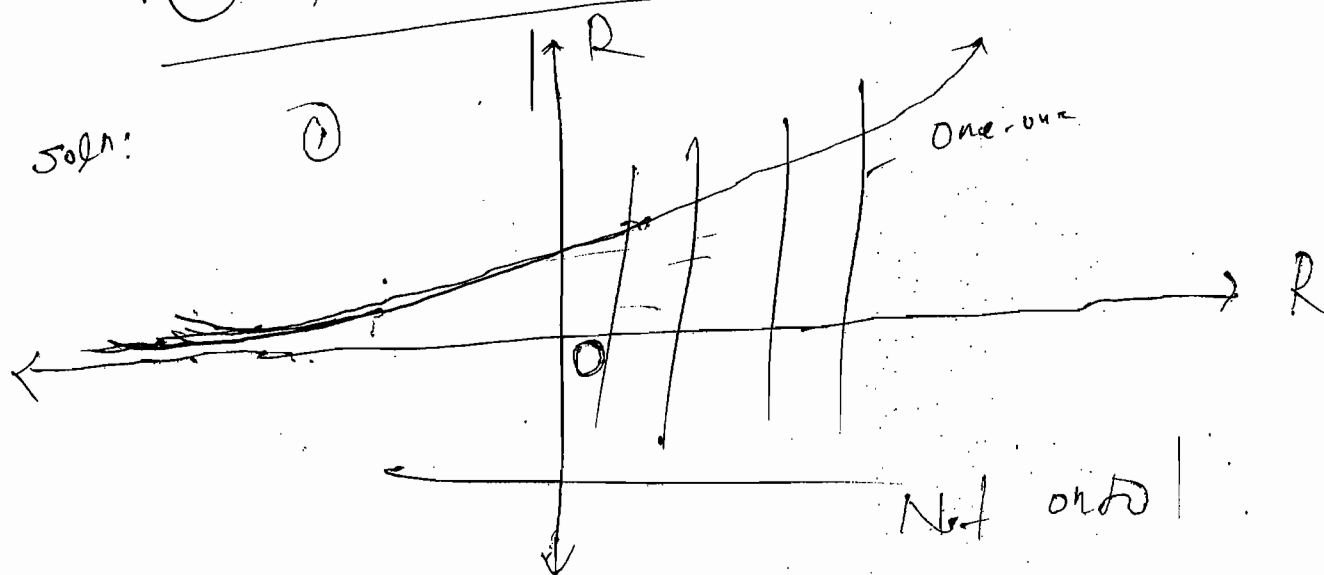
Range = Codomain

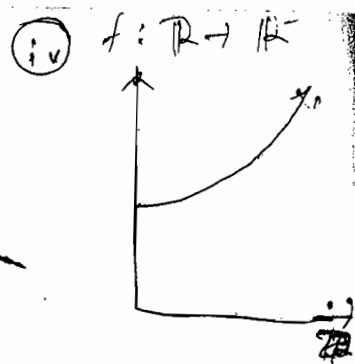
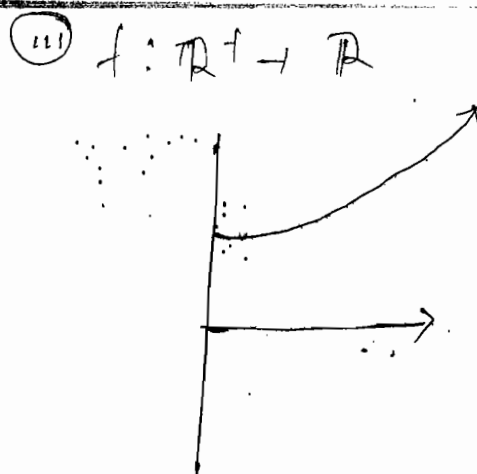
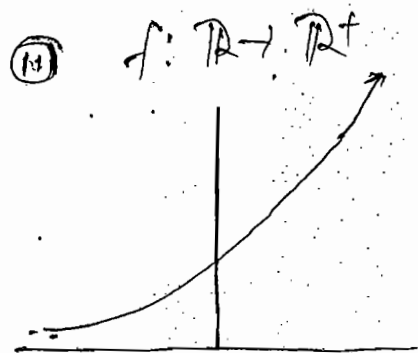
A functⁿ $f: A \rightarrow B$ is called onto iff any line passing through co-domain and \parallel to x -axis should intersect the curve $y = f(x)$ at least once.

Ex:- $f(x) = e^x$

	function	1-1	Onto
(i) $f: \mathbb{R} \rightarrow \mathbb{R}$	✓	✓	X
(ii) $f: \mathbb{R} \rightarrow \mathbb{R}^+$	✓	✓	✓
(iii) $f: \mathbb{R}^+ \rightarrow \mathbb{R}$	✓	✓	X
(v) $f: \mathbb{R}^+ \rightarrow \mathbb{R}^+$	✓	✓	X

Soln:

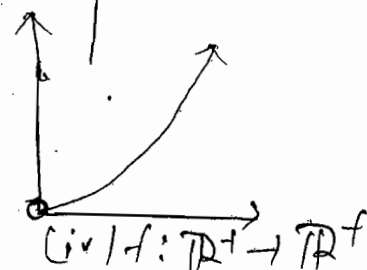
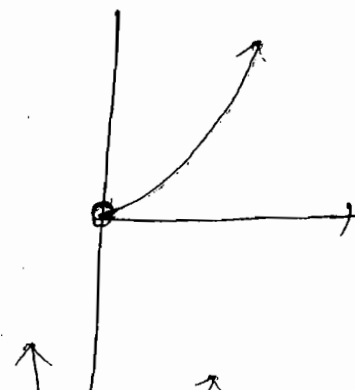
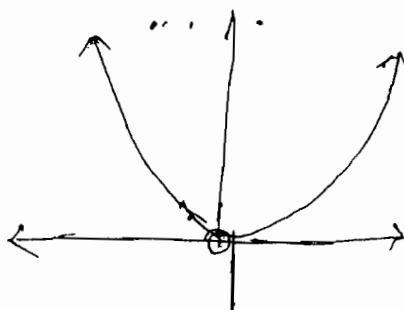
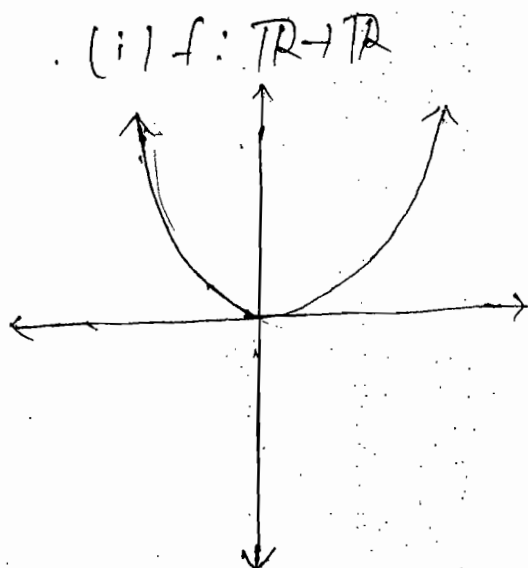




Ex 2:

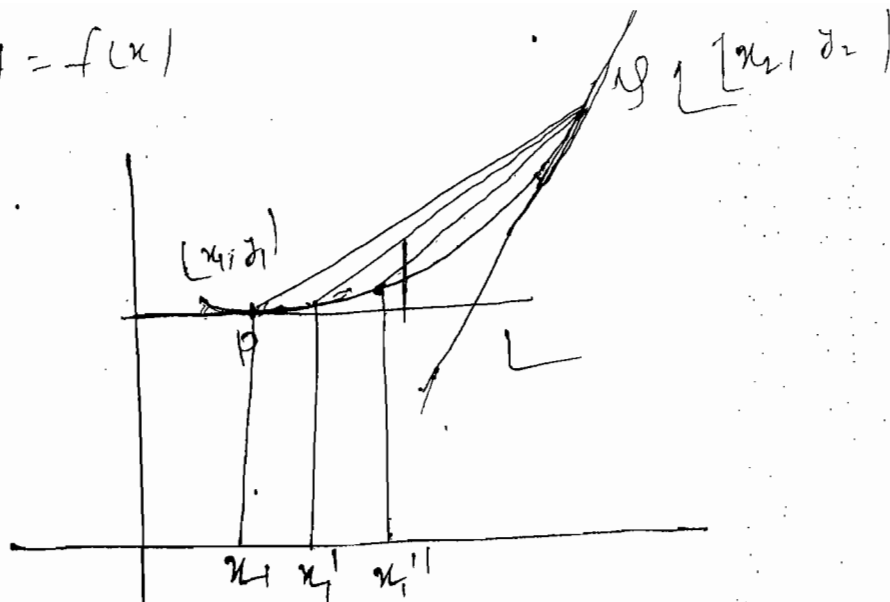
$$f(x) = x^2$$

(ii) $f: \mathbb{R} \rightarrow \mathbb{R}^+$ (iii) $f: \mathbb{R}^+ \rightarrow \mathbb{R}^+$



$f(x) = x^2$	Function	1-1	Onto
(i) $f: \mathbb{R} \rightarrow \mathbb{R}$	✓	✗	✗
(ii) $f: \mathbb{R} \rightarrow \mathbb{R}^+$	✗	✗	✗
(iii) $f: \mathbb{R}^+ \rightarrow \mathbb{R}$	✓	✓	✗
(iv) $f: \mathbb{R}^+ \rightarrow \mathbb{R}^+$	✓	✓	✓

$y = f(x)$



$$\Delta y = y_2 - y_1 = \text{distance b/w } y_1 \text{ \& } y_2$$

$$\Delta x = x_2 - x_1 = \text{distance b/w } x_1 \text{ \& } x_2$$

$$\frac{\Delta y}{\Delta x} = \frac{y_2 - y_1}{x_2 - x_1} = \text{slope of } L$$

$$\frac{dy}{dx} = \lim_{x_1 \rightarrow x_2} \frac{\Delta y}{\Delta x}$$

= slope of L when $P \rightarrow Q$

$$y \left(\frac{dy}{dx} \right) = \text{slope of tangent at point } Q$$

Algebraic form

Graphical form

rate of change $\rightarrow \frac{dy}{dx}$

Date
21/08/2019

Differential Equation:

Any eqⁿ between dependent variable independent variable and ~~constant~~ derivative of D.V. w.r.t. independent variable is called D.E.

Eg:-

(i) $y = f(x)$

$$\frac{dy}{dx} + y = \sin x$$

$$\frac{d^2y}{dx^2} + f(x)y = e^x$$

(ii) $y_1 = f(x)$

$$y_2 = g(x)$$

$$\frac{dy_1}{dx} + y_2 = \sin x$$

$$\frac{d^2y_1}{dx^2} + \frac{dy_2}{dx} = 0$$

(iii) $z = f(x, y)$

$$\frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial y^2} = 0$$

$$\frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial y^2} = \sin(x+y)$$

! Simple P.D.E.

(iv) $z_1 = f(x, y)$

$$z_2 = g(x, y)$$

$$\frac{\partial^2 z_1}{\partial x^2} + \frac{\partial^2 z_2}{\partial x \partial y} = 0$$

$$\frac{\partial z_1}{\partial y} + \frac{\partial z_2}{\partial x} = e^{x+y}$$

System of P.D.E.

Ordinary differential eqⁿ:

Any differential eqⁿ in which unique independent variable and total derivative of D.V. w.r.t. I.V. is called O.D.E.

Eg: $y = f(x)$

$\frac{dy}{dx} - y = \sin x$

$\frac{d^2y}{dx^2} + f(x)y = e^x$

Simple O.D.E

$y_1 = f(x)$

$y_2 = g(x)$

$\frac{dy_1}{dx} + y_2 = \sin x$

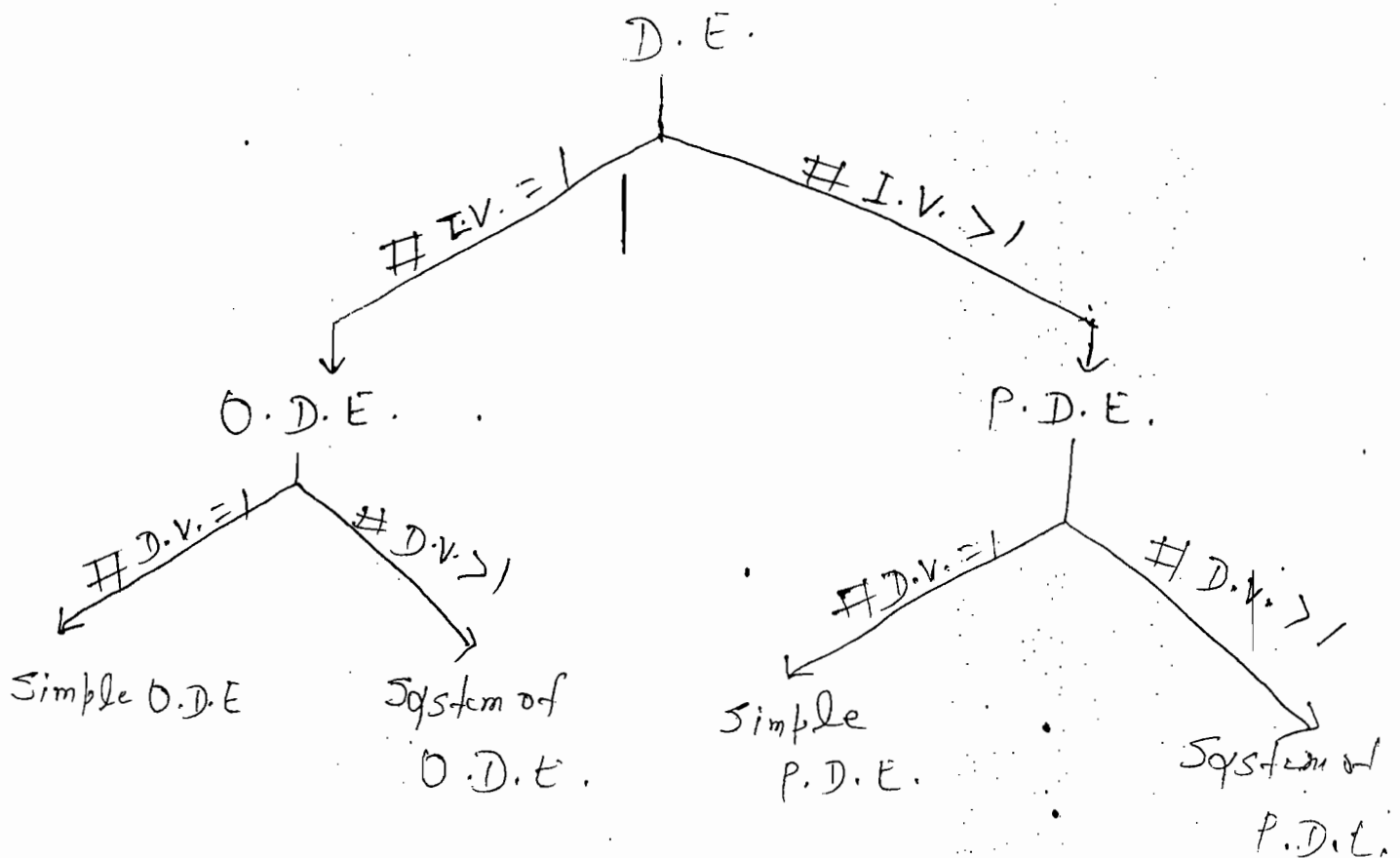
$\frac{d^2y_1}{dx^2} + \frac{dy_2}{dx} = 0$

System of O.D.E.

Partial Differential eqn:

Any D.E. contain partial derivative is called partial D.E.

Classification of D.E.:



1. Formation of 1st order P.D.E.
 → by eliminating of arbitrary constant
 → by eliminating of arb. functⁿ ①

2. First order P.D.E.

- (i) Linear
- (ii) Semi-linear
- (iii) Quasi-linear
- (iv) Non-linear

→ Lagrange's method
 → Charpit's Method
 → ①
 → ①
 → Quasi-linear
 → Non-linear

3. Integral surface passing through a given curve

4. Surface orthogonal to surface

5. Classification of 2nd order P.D.E.
 { Hyperbolic
 { parabolic
 { elliptic ①

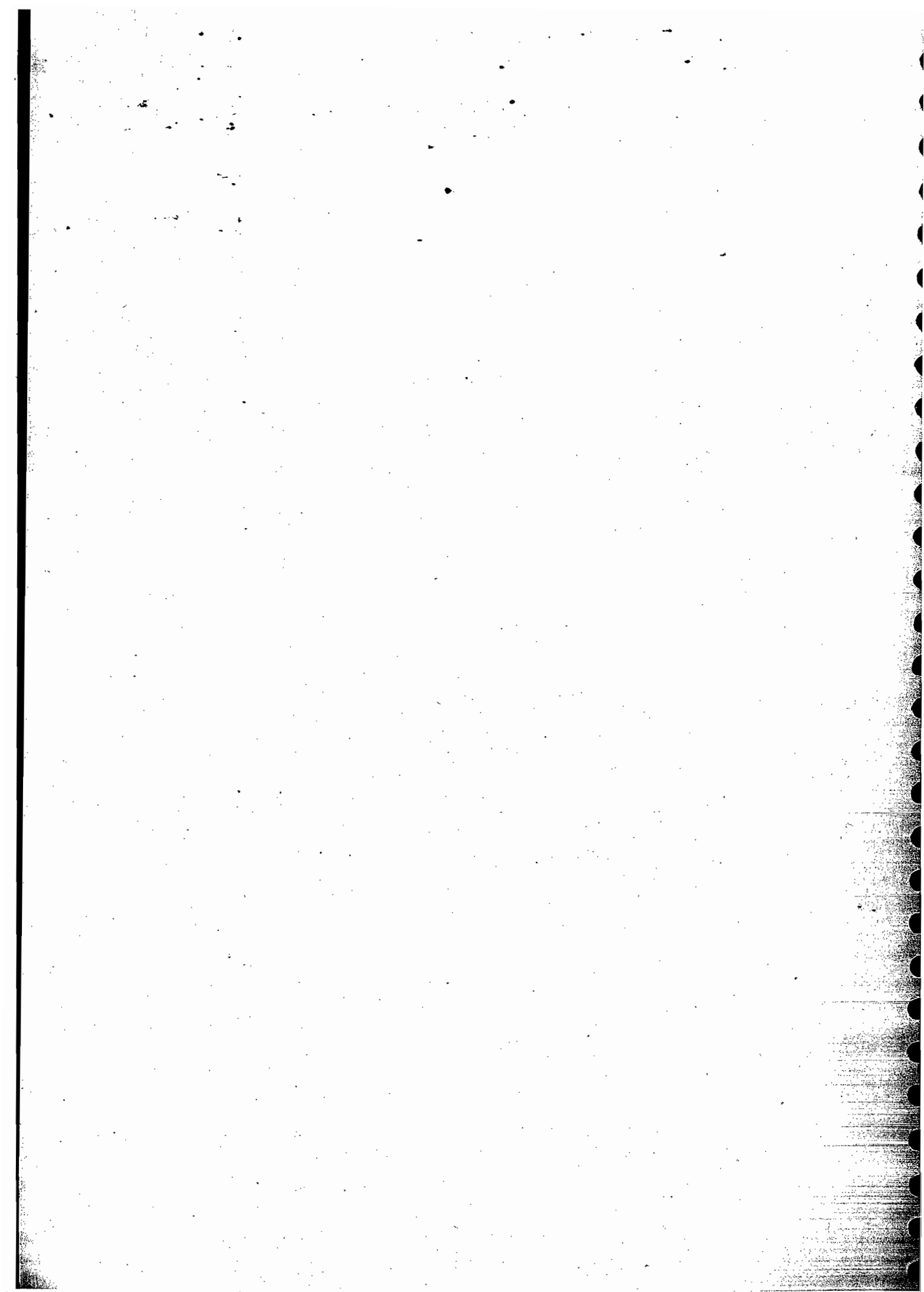
6. P.D.E. with constant coefficient L. ①

7. Separation of variable
 { Heat eqⁿ
 { Wave eqⁿ
 { Laplace Eqⁿ } — 200, 3

Note:-

$$\frac{\partial z}{\partial x} = p, \frac{\partial z}{\partial y} = q,$$

$$\frac{\partial^2 z}{\partial x^2} = r, \frac{\partial^2 z}{\partial x \partial y} = s, \frac{\partial^2 z}{\partial y^2} = t,$$



Def. Partial Differential Equation:

An eqⁿ which contains partial derivative of dependent variable w.r.t. two or more than two independent variable, is called P.D.E.

Note:-

$$\text{No. of D.V.} = 1$$

$$\text{No. of I.V.} \geq 2$$

E.g.:

$$\textcircled{i} \frac{\partial z}{\partial x} + \frac{\partial z}{\partial y} = x + y$$

$$\textcircled{ii} \frac{\partial^2 z}{\partial x^2} + \frac{\partial^2 z}{\partial x \partial y} + \frac{\partial^2 z}{\partial y^2} = 0$$

Classification of 1st order P.D.E.

1. Linear:-

A 1st order P.D.E. is said to be linear, if it is linear in p, q & z and of the form

$$P(x, y)p + Q(x, y)q = \underline{R(x, y)}z + S(x, y)$$

e.g.:

$$\textcircled{i} xp + yq = xyz + x^3 y^3$$

$$\textcircled{ii} p + q = xyz$$

$$\textcircled{iii} x^2 p + y^2 q = 1$$

Note:-

① If $S(x, y) = 0$, then it is called homogⁿ linear P.D.E.

② If $S(x, y) \neq 0$, then it is called non-homogⁿ linear

P.D.E.

2. Semi linear:-

A 1st order P.D.E. is said to be semi linear if it is linear in p & q but not necessarily in z and of the form

$$P(x, y)p + Q(x, y)q = \underline{R(x, y, z)}$$

e.g.

① $p + q = xyz$

② $x^2 p + y^2 q = x^2 y^2 z^2 \rightarrow$ Semi linear

3. Quasi linear:-

A 1st order P.D.E. is said to be Quasi linear, if it is linear in ~~p & q~~ p & q and of the form

$$\underline{P(x, y, z)p + Q(x, y, z)q = R(x, y, z)}$$

e.g.

① $p + q = xyz$

② $(y - z)p + (z - x)q = x - y$

③ $y^2 p + (x - z)q = z^2$

** 1. $P(x, y)p + Q(x, y)q = R(x, y)z + S(x, y)$ - linear

2. $P(x, y)p + Q(x, y)q = R(x, y, z)$ - semi-linear

3. $P(x, y, z)p + Q(x, y, z)q = R(x, y, z)$

Note:-

Linear \subset Semi-linear \subset Quasi linear.

4. Non-linear

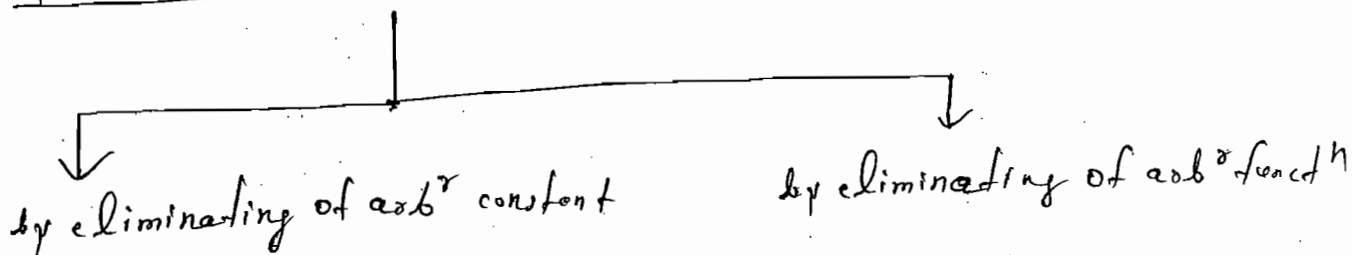
A 1st order P.D.E. is said to be non-linear if it doesn't come under any one of the above types.

e.g.

① $pz = z^2$

② $p^2 z^2 = 1$

Formation of 1st order P.D.E. :-



1. By eliminating of a & b constant :-

Let $F(x, y, z; a, b) = 0$ ——— ①

where a & b are a & b constant & z is dependent variable and x & y are independent variable.

Differentiate partially w.r.t. x & w.r.t. y

$F_x(x, y, z, \frac{\partial z}{\partial x}, a, b) = 0$ ——— ②

$F_y(x, y, z, \frac{\partial z}{\partial y}, a, b) = 0$ ——— ③

We eliminate a & b from eqn ①, ② & ③, then we get $\boxed{\Psi(x, y, z, p, q) = 0}$

e.g. — The P

Eg:- The P.D.E. representing the set of all sphere of unit radius with centre in the xy -plane is

(i) $x^2 + y^2 + z^2 = 0$

(ii) $y^2 - x - z = 0$

~~(iii) $z^2(1 + x^2 + y^2) = 1$~~

(iv) N.O.T.

→ $(x-a)^2 + (y-b)^2 + z^2 = 1$

~~$x(x-a) = 0$~~

$x(x-a) + 2yz = 0$

$\therefore x-a = -2z$

Now, $y-b = -2z$

$\therefore z^2 + z^2 + z^2 = 1$

$\therefore z^2(1 + 1 + 1) = 1$

GATE

Eg:- The P.D.E. for $z^2(1+a^3) = 8(x+ay+b)^3$ is

(i) $z = x^2 + y^2$

(ii) $27z = x^2 + y^2$

~~(iii) $27z = x^3 + y^3$~~

(iv) $z = x^3 + y^3$

→ $z^2(1+a^3) = 8(x+ay+b)^3$ — (i)

$x(1+a^3)z = 24(x+ay+b)^2$ — (ii)

$x(1+a^3)z^2 = 24(x+ay+b)$ — (iii)

~~$\therefore \frac{x(1+a^3)z^2}{x} = \frac{24(x+ay+b)}{1}$~~

$\therefore a^3 = \frac{b}{x}$ $\therefore a^3 = \frac{b}{x}$ $\therefore a^3 = \frac{b}{x}$

$\frac{b}{x} = \frac{1}{a} \therefore a = \frac{x}{b}$

$$\text{eqn ①} \div (1)$$

$$\frac{z}{x^2 p} = \frac{1}{3} (x + ay + b)$$

$$x + ay + b = \frac{3z}{p}$$

$$\therefore \left(z^2 + \frac{z^3}{p^3} \right) = \cancel{8x} \frac{27z^3}{\cancel{8p^3}}$$

$$\therefore \frac{p^3 + z^3}{p^2} = \frac{27z}{p^3}$$

$$\therefore 27z = p^3 + z^3$$

Ex:-

$$z = ax - y$$

Part Diffⁿ w.r.t. x ,
 $p = a$

$$\boxed{z = px - y}$$

Again partially diffⁿ w.r.t. y

$$z = -1$$

$$\boxed{z + 1 = 0}$$

Ex:-

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1 \quad \text{--- ①}$$

\rightarrow ~~$\frac{2x}{a^2}$~~ partially diffⁿ w.r.t. x ,
 (case-1)

$$\frac{2x}{a^2} + \frac{2z}{c^2} p = 0 \quad \text{--- ②}$$

$$\therefore \frac{x}{a^2} + \frac{zp}{c^2} = 0$$

Again diffⁿ w.r.t. x

$$\frac{1}{a^2} + \frac{1}{c^2} (z + p^2) = 0$$

$$\therefore \frac{1}{a^2} = -\frac{1}{c^2} (z + p^2)$$

$$\frac{-\kappa}{c^2} \{z\delta + b^2\} + \frac{zb}{c^2} = 0 \quad \{fn \textcircled{II}\}$$

$$\boxed{\kappa z\delta + \kappa b^2 = zb}$$

Case-II) Partially diffⁿ w.r.t. y ;

$$\frac{\partial y}{\partial z} + \frac{zzz}{c^2} = 0$$

$$\frac{\partial}{\partial z} + \frac{zz}{c^2} = 0$$

Again diffⁿ w.r.t. y

$$\frac{1}{\delta z} + \frac{1}{c^2} \{z\delta + z^2\} = 0$$

$$\frac{1}{\delta z} = -\frac{1}{c^2} \{z\delta + z^2\}$$

$$-\frac{y}{c^2} \{z\delta + z^2\} + \frac{zz}{c^2} = 0$$

$$\boxed{yz\delta + yz^2 = zz}$$

Case-III) Partially diffⁿ w.r.t. x

$$\frac{\kappa}{a^2} + \frac{zb}{c^2} = 0$$

Again diffⁿ w.r.t. y

$$0 + \frac{1}{c^2} \{z\delta + b^2\} = 0$$

$$\boxed{z\delta + b^2 = 0}$$

Note:-

(i) By eliminating arbit^r constant, we can get both non-linear as well as quasi linear.

(ii) No. of arbit^r constant = No. of independent variable
 Then, we will get unique partial D.E.

JMS

Unit-1 :

Chapter-1 - Sets & its Fundamentals

Chapter-2 Point set topology of \mathbb{R}

Unit-2

1 - Sequence of Real number

2 - Series of Real Number

Unit-3

1 - Fundamentals of functions

2 - Limits and Continuity

3 - Differentiability

4 - Application of Derivative

Unit-4

1 - Sequence of Function

2 - Series of Function

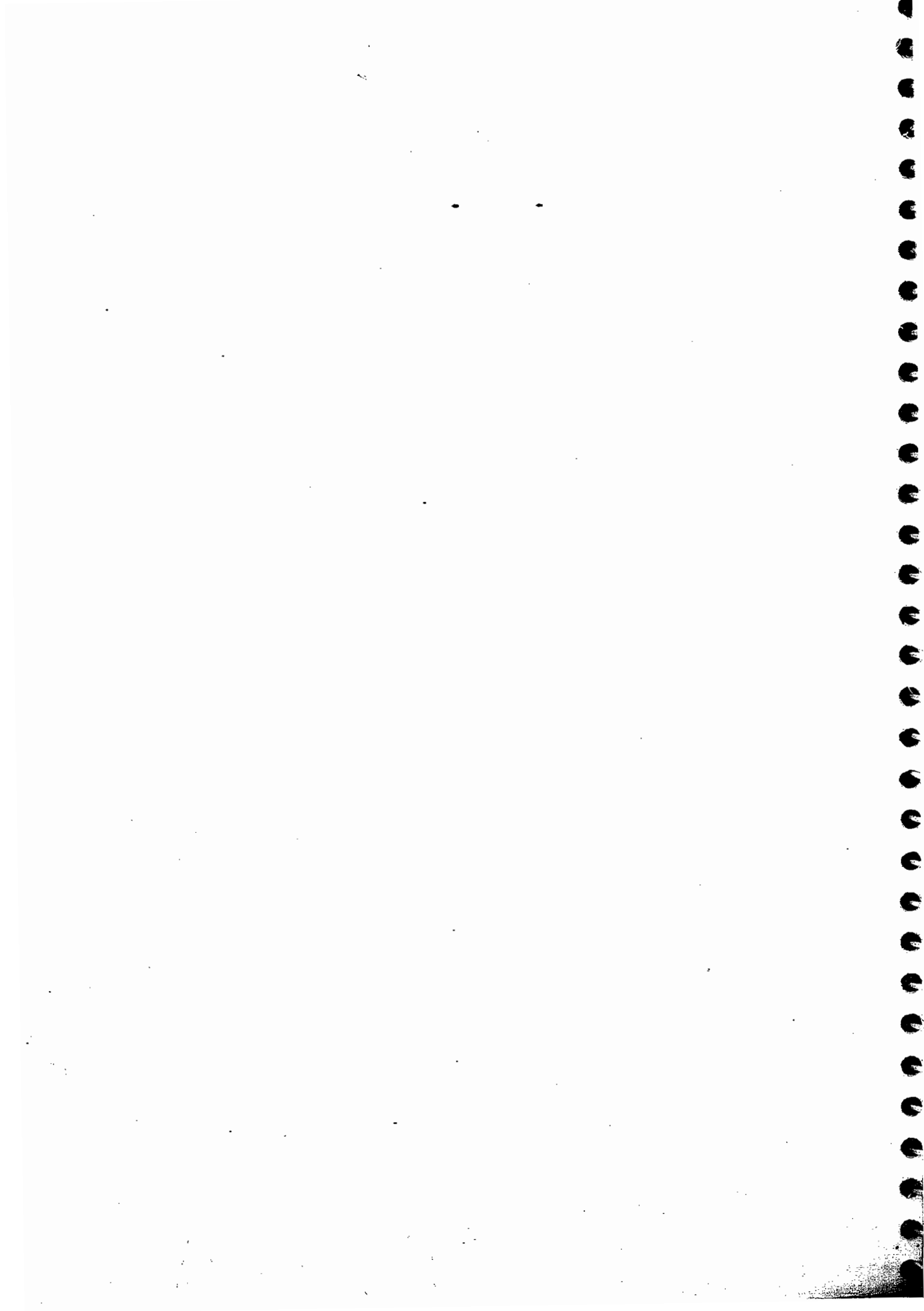
Unit-5

1 - Riemann Integrability

2 - Function of Bounded Variation

Unit-6

1 - Function of Several Variables



A well defined collection of distinct objects is called sets.

Note:- (i) By "well defined", we mean there is no ambiguity or confusion regarding inclusion or exclusion of object.

(ii) Empty collection is well defined so it is a set called void set or null set or empty set and denoted by $\{\}$ or ϕ .

(iii) Set itself considers as an object, hence eligible to collection for any set.

(iv) Generally, sets are denoted by capital letters and objects included in the set, elements are denoted by small letters a, b, c, x, y, z etc and if a is an object included in the set X , a belongs to X and write $a \in X$

* Axiom of Regularity (AOR):

No set can belong to itself i.e, if X is a set then $X \notin X$.

→ Ordinary and Extra Ordinary Sets:-

If X is a set s.t. $X \in X$, X is called extra ordinary set.

A set is called ordinary if it doesn't contain itself as an element.

$$X = \{d \text{ is an object} : d \text{ is not a tea cup}\}$$

X is a set $\Rightarrow X$ is not a tea cup.

\Rightarrow Russel's Paradox:

$$X = \{A : A \text{ is an ordinary set}\}$$

= collection of all the ordinary sets

if X is a set

$$\text{if } X \text{ is ordinary} \Rightarrow X \in X$$

$\Rightarrow X$ is extraordinary

$$X \text{ is extraordinary} \Rightarrow X \in X$$

$\Rightarrow X$ is ordinary

i.e., X is not a set

\therefore Therefore is no set of all the ordinary sets.

$$X = \{A \text{ is a set} : A \notin A\}$$

= The collection of all the sets

$$\text{if } X \text{ is a set} \Rightarrow X \notin X$$

$$\Rightarrow X \in X$$

Subset: -

Let A & B are sets, if

$x \in A \Rightarrow x \in B$, then we say A is a subset of B denoted by $A \subset B$.

OR,

$$\nexists x \in A \text{ s.t. } x \notin B$$

Note: (i) Empty set is a subset of every set.

(ii) Every set is a subset of itself.

$$\Rightarrow \textcircled{i} A \cup B = \{x : x \in A \vee x \in B\}$$

$$\textcircled{ii} A \cap B = \{x : x \in A \wedge x \in B\}$$

$$\textcircled{iii} A - B = \{x : x \in A, x \notin B\}$$

$$\textcircled{iv} A \Delta B = (A - B) \cup (B - A) \\ = (A \cup B) - (A \cap B)$$

$$\textcircled{v} A^c = U - A$$

$$\textcircled{vi} (A \cup B)^c = A^c \cap B^c$$

$$\textcircled{vii} (A \cap B)^c = A^c \cup B^c$$

$$\textcircled{viii} A = B \Leftrightarrow A \subset B \text{ \& } B \subset A$$

* Power set: -

Let A be a set

$$P(A) = \{X : X \subset A\}$$

= The set of all subsets of A .

e.g. Let $A = \{a, b, c\}$

$$P(A) = \{ \emptyset, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, \{a, b, c\} \}.$$

For any set A , $P(A) \neq \emptyset$.

Proof: - Define $P(A) = \{ X : X \subset A \}$

Cartesian product: -

Let A & B are sets.

Define $A \times B = \{ (a, b) : a \in A, b \in B \}$

where (a, b) is called ordered pair.

Note: - ① $A_1 \times A_2 \times \dots \times A_n = \prod_{i=1}^n A_i = \{ (a_1, a_2, \dots, a_n) \mid a_i \in A_i \}$
n-tuples

$$\textcircled{II} \prod_{i=1}^n A_i = \emptyset \Leftrightarrow A_i = \emptyset \text{ for some } i.$$

Functions: -

Let A & $B \neq \emptyset$. Then a rule by which every element is assigned to some unique element of B is defined as a function from A to B and defined by $f: A \rightarrow B$.

if $f: A \rightarrow B$ then,

(i) A is called domain

(ii) B is called co-domain

(iii) If $x \in A$ is assigned to $y \in B$, we write
 $y = f(x)$

And y is called the image of x
f x - pre-image of y .

(iv) $f(A) = \{ f(x) : x \in A \} \subset B$ called
the range of f .

(v) One-one function (Injection):

$$f(a) = f(b) \Leftrightarrow a = b$$

(vi) Surjection (onto)

$$f(A) = B.$$

(vii) Bijection - One-one and onto.

$$\text{Not:- } |N| = \{ 1, 2, 3, \dots, n, n+1, \dots \}$$

$$J(n) = \{ 1, 2, 3, \dots, n \}.$$

Similar sets:-

Two non-empty sets are said to be similar if \exists a bijection between them.

The words like equivalent, equinumerous, equipotential are also used in the place of similar.

Note: -

① If $A \not\subseteq B \neq \emptyset$, we say B has more potential than that of A if onto function from A to B can't be defined.

② If one-one function can't be defined then we say A has more potential than B.

Finite Set: -

A non-empty set is said to be finite if it is similar to S_n .

if $A \sim S(n)$, we say cardinality of A is n, denoted by $\text{card}(A) = |A| = n$.

Note: - ① By extension of defⁿ of finite set, empty set is also considered as finite set and its cardinality is 0.

$$\aleph_0 = \{0, 1, 2, 3, \dots\}$$

= The set of all the finite cardinals.

② The intersection of two power sets can't be disjoint.