

Christopher Paucar: Predicting Penalty Kicks with ML models

Class: IW Seminar 02
Advisor: Professor Li





1) Motivation & Goal

- Penalty kicks
 - Straightforward way to score
 - Drama & Suspense
 - Decisive
- What if one were able to predict whether a penalty shot would go in?



1) Motivation & Goal

GOAL : Using different ML models, offer the ability to predict whether a penalty kick will go in or not based on certain features.



2) Previous Works

ROBOKEEPER: THE ROBOTIC GOALKEEPER

- Uses image processing to predict where the ball will impact the goal
- Using dynamics and planning to have robot dive

<https://www.robokeeper.com/en/facts.html>

PREDICTING FOOTBALL PENALTY DIRECTIONS USING IN-MATCH PERFORMANCE INDICATORS

By Lotte Bransen & Jesse Davis

- Used IN-GAME metrics to predict penalty kicks
 - Missed shots
 - Pass Accuracy

https://analytics.scisports.com/research/penalty_predictor

3) Steps



1. Datasets

- World Cup (1984-2018)
- Champions League (2019-20)
- **World Cup Misses (2022)**
- Pandas Python Library
- English Premier League(2016-17)
- **Serie A Misses (2019-20)**
- **Copa America Misses (2019, 2021)**

2. Feature Engineering, EDA

- Feature Extraction
- Random Oversampling
- Pandas Python Library
- One Hot Encoding
- Correlation

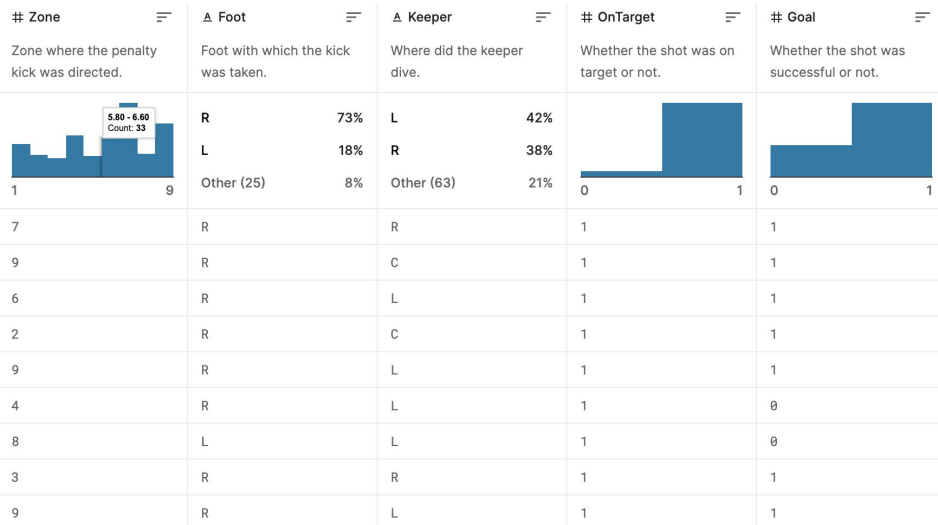
3. Prediction: Binary Classification

- Sklearn Python Library
- Imblearn Python Library

4. Iterative Evaluation of Model Performance

- Accuracy, precision, etc
- Sklearn, Seaborn, Matplotlib Python Libraries

Scored		Foot		Kick_Direction		Keeper_Direction	
Scored Missed	76% 24%	R L Other (3)	80% 17% 3%	L R Other (20)	44% 37% 19%	R L Other (9)	49% 42% 8%
Scored		L		C		R	
Scored		R		L		L	
Missed		R		L		L	
Scored		R		C		L	
Scored		R		L		R	
Scored		R		L		R	
Scored		R		C		L	
Scored		R		R		L	
Scored		R		C		R	
Missed		R		R		R	
Missed		L		R		R	
Missed		L		L		L	
Scored		R		L		L	
Scored		R		C		R	



1. GATHER MY DATA POINTS
 - a. Kaggle, YouTube

[illegible]

4.2) Implementation: Feature Engineering and EDA

DATASETS

```
# ONE HOT ENCODING
```

```
dominant_foot_missed = ohe.fit_transform(missed_pens[['Dominant Foot']])  
kick_direction_missed = ohe.fit_transform(missed_pens[['Kick Direction']])  
keeper_direction_missed = ohe.fit_transform(missed_pens[['Keeper Direction']])
```

Using One
Hot Encoding
On Features

Features

1. Dominant Foot
 - a. Left or Right
2. Kicker Direction
 - a. Left, Center, Right
3. Keeper Direction
 - a. Left, Center, Right

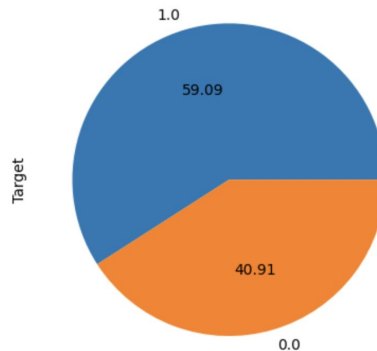
Label

- 0: Penalty Miss
- 1: Penalty Goal

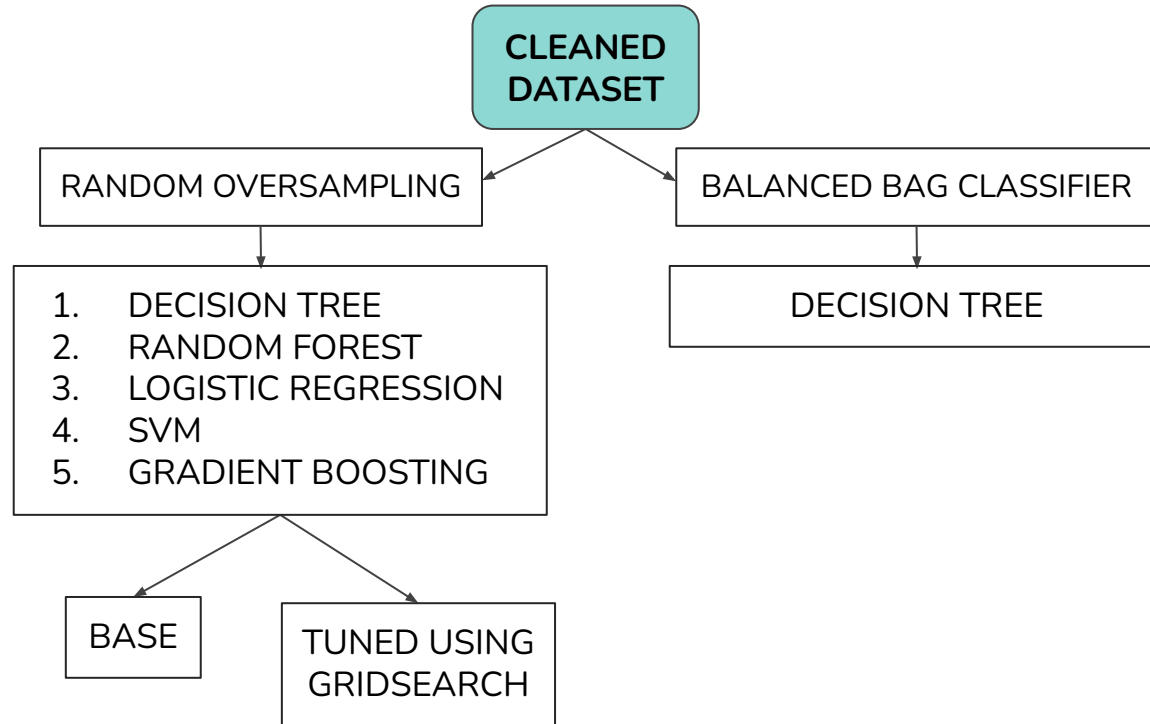
528 x 9
Dataset

Left Footed	Right Footed	Kicked Left	Kicked Center	Kicked Right	Keeper Left	Keeper Center	Keeper Right	Target
0.0	1.0	0.0	1.0	0.0	1.0	0.0	0.0	1.0
0.0	1.0	1.0	0.0	0.0	0.0	1.0	0.0	0.0
0.0	1.0	0.0	1.0	0.0	0.0	0.0	1.0	1.0
1.0	0.0	0.0	0.0	1.0	0.0	1.0	0.0	0.0
0.0	1.0	0.0	0.0	1.0	0.0	0.0	1.0	0.0

Imbalanced!!



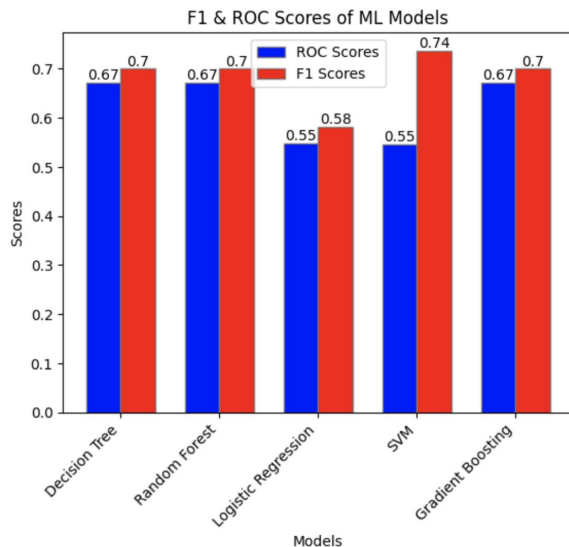
4.3) Implementation: Models



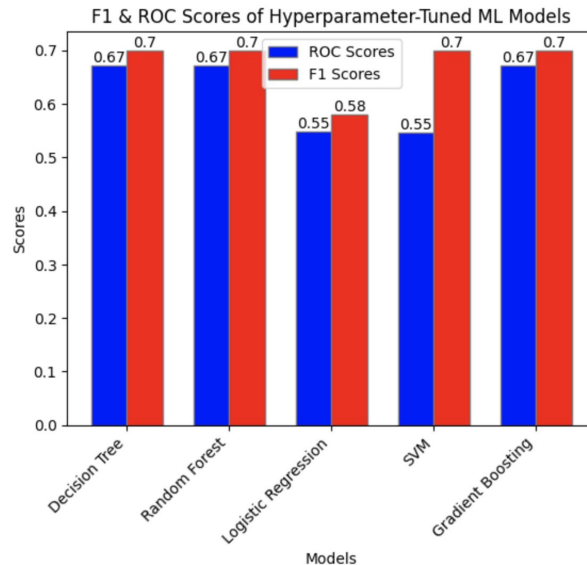
5) Evaluation & Results

RANDOM OVERSAMPLING

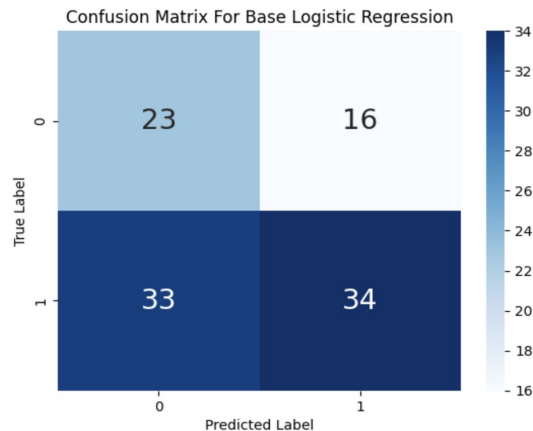
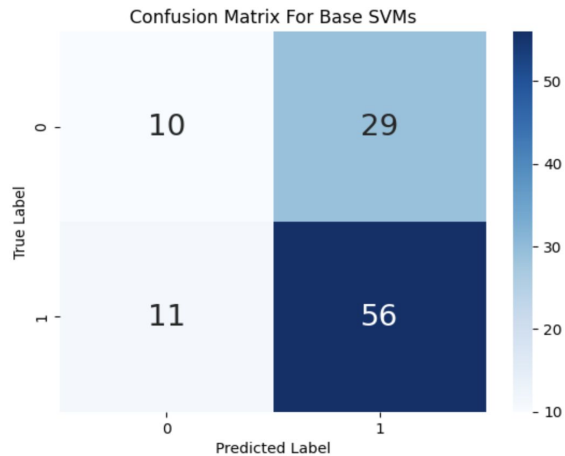
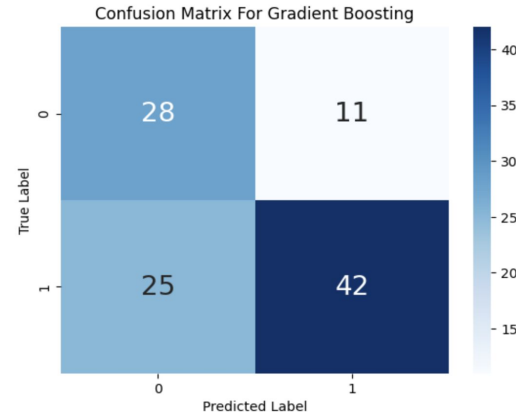
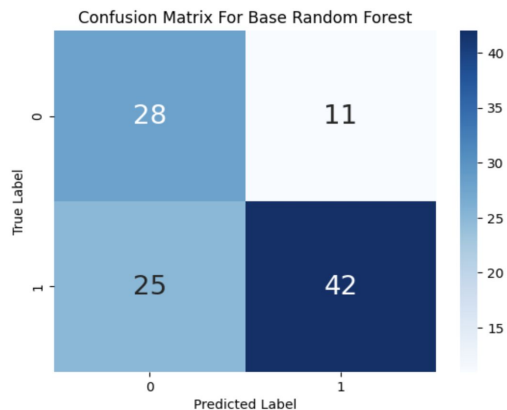
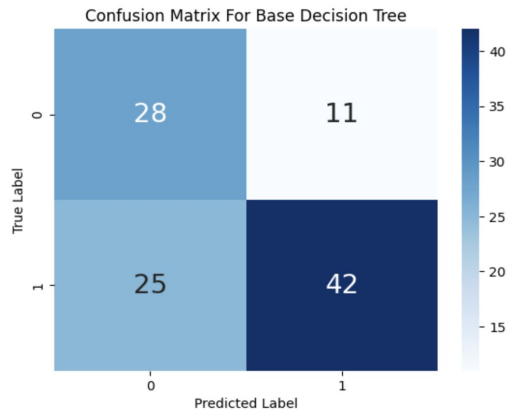
BASE



TUNED USING
GRIDSEARCH

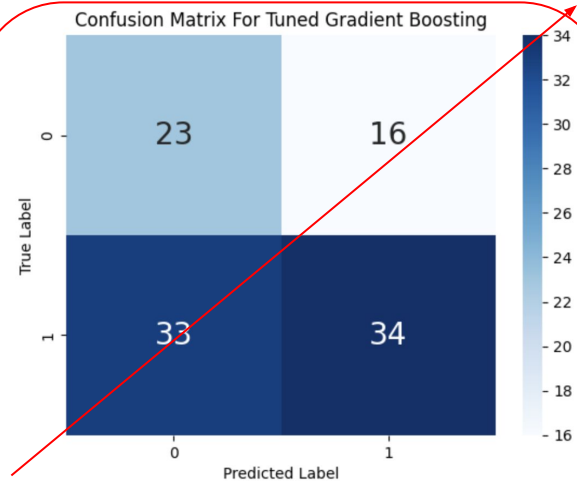
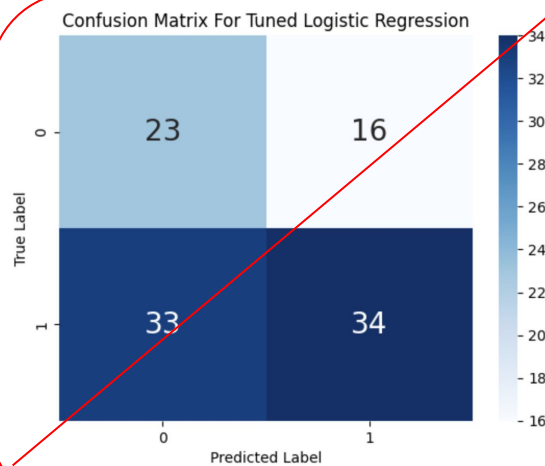
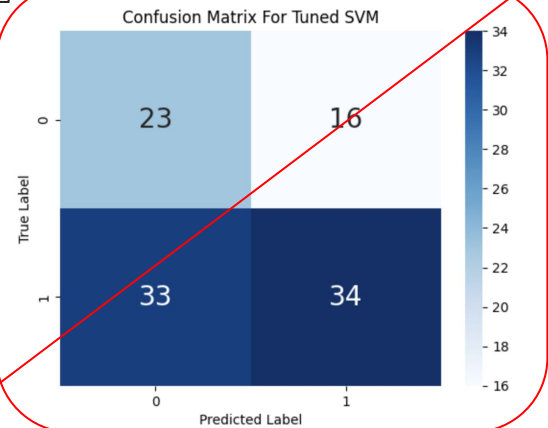
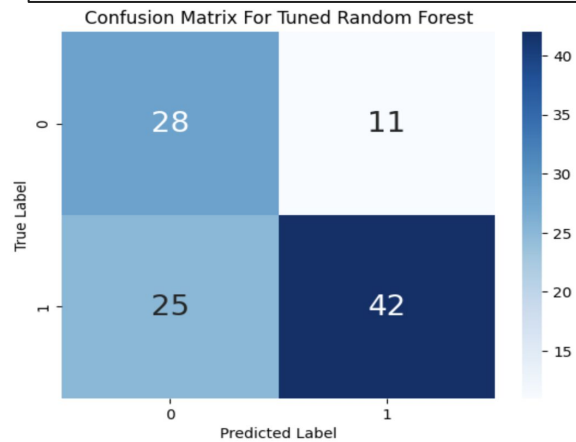
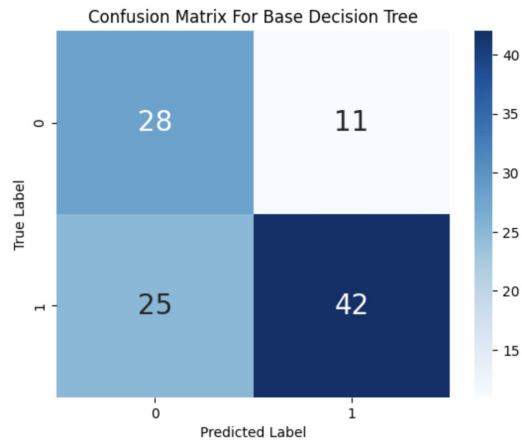


BASE MODELS

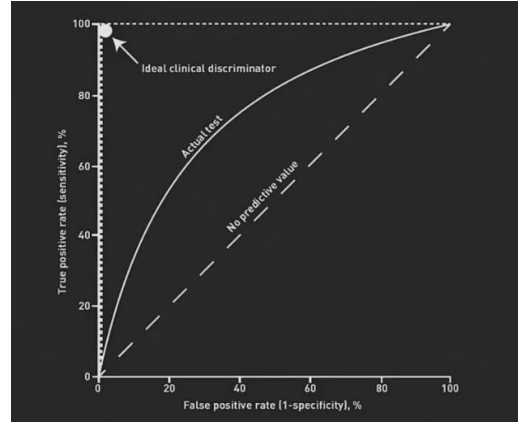


- Highest TN, TP values
 - Decision Tree, Random Forest, Gradient Boosting
- SVM
 - Low TP value, High TN value
- Logistic Regression
 - In the middle

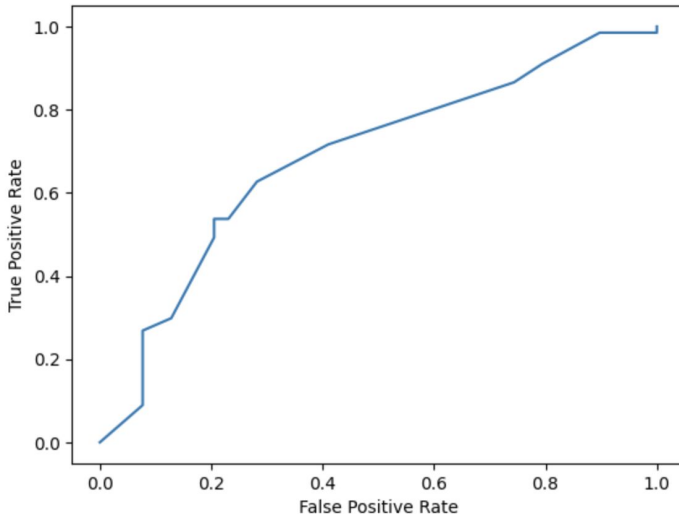
TUNED MODELS



ROC CURVES

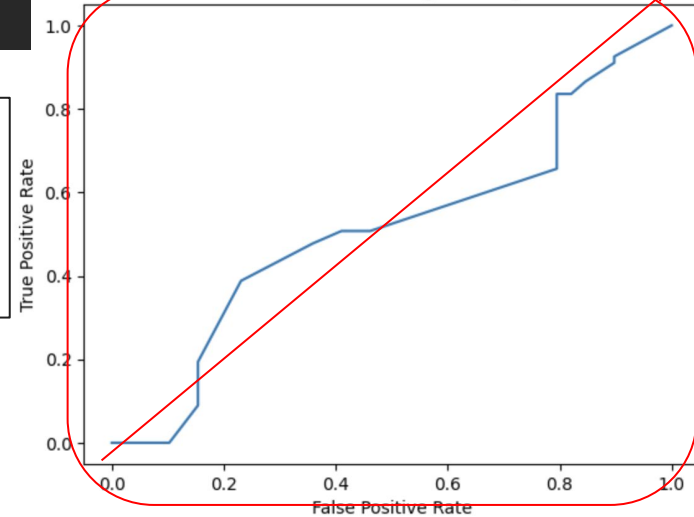


ROC curve for Base Decision Tree



- Logistic Regression ROC Curve much closer to the “No predictive value” line

ROC Curve for Base Logistic Regression

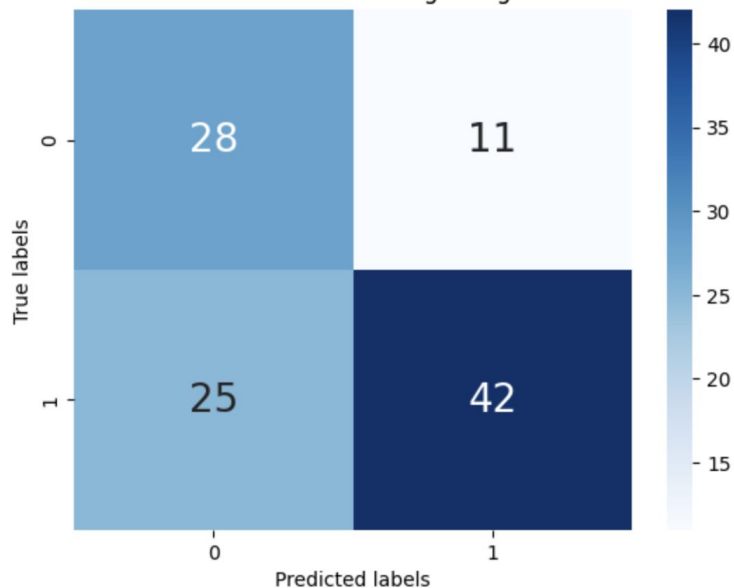




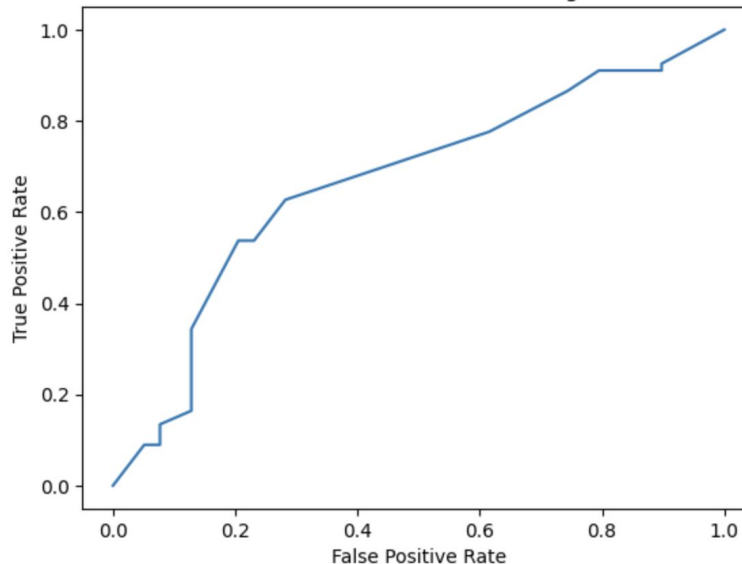
5) Evaluation & Results

BALANCED BAG CLASSIFIER

Confusion Matrix For Balanced Bag Using Decision Tree



ROC Curve for Balanced Bag



6) Conclusions & Future Work

- CONCLUSION

- At a standstill in terms of performance
 - F1: 0.7 ; ROC: 0.67
- More deciding factors in predicting penalty kicks
- Following advice from Professor Li, will extract more features in order to enhance performance

- FUTURE WORK

- Penalty Predictor Using Images & Clips of In-Moment Penalty Kicks





7) Acknowledgements

- Big Thanks To...
 - Professor Li
 - Meet Patel
 - Seminar Classmates
 - Camila & Natalie, for their advice and fun times throughout this seminar:)