

Wellcome Trust Centre for Neuroimaging





DCM is a <u>generative model</u>
= a quantitative / mechanistic description of how observed data are generated.



Key features:
1- Dynamic
2- Causal
3- Neuro-physiologically motivated
4- Operate at hidden neuronal interactions
5- Bayesian in all aspects.

DCM [default] implementation:

Deterministic Stochastic [Daunizeau et al. 2009]

Bilinear Nonlinear [Stephan et al. 2008]

The one-state neuronal The two-state [Marreiros et al. 2008]

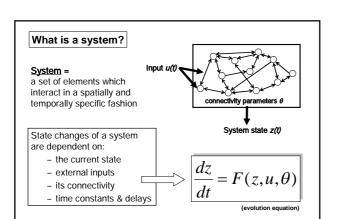


"The central idea behind dynamic causal modelling (DCM) is to treat the brain as a deterministic nonlinear dynamic system that is subject to inputs and produces outputs."

"DCM assumes the responses are driven by designed changes in inputs."

"DCM is used to test the specific hypothesis that motivated the experimental design. It is not an exploratory technique [...]; the results are specific to the tasks and stimuli employed during the experiment."

[Friston et al. 2003 Neuroimage]

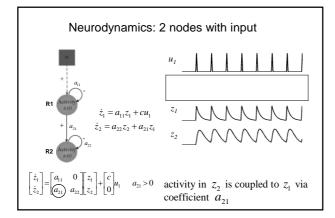


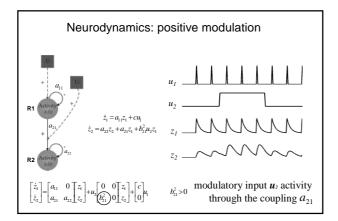
Basic idea of DCM for fMRI

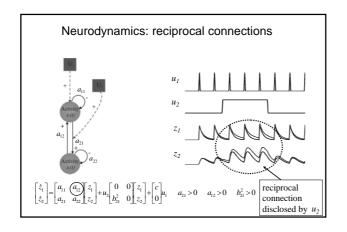
- Effective connectivity is parameterised in terms of coupling among unobserved brain states (e.g., neuronal activity in different regions).
 The objective is to estimate these parameters by perturbing the system and measuring the response.
- $\mbox{\Large \ \ }$ A cognitive system is modelled as a bilinear model of neural population dynamics (z).
- \bullet The modelled neuronal dynamics (z) is transformed into area-specific BOLD signals (y) by a hemodynamic forward model (\(\lambda\)).

Aim: to estimate the parameters of a reasonably realistic neural model such that the predicted regional blood oxygen level dependent (BOLD) signals, correspond as closely as possible to the observed BOLD signals.

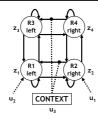








bilinear dynamic system



Bilinear state equation in DCM for fMRI

The neural state equation



$$\dot{z} = (A + \sum_{j=1}^{m} u_j B^j) z + Cu$$

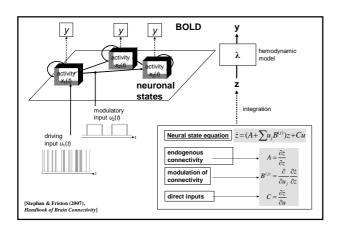
"C", the direct or driving effects:

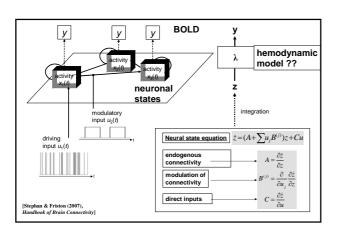
- extrinsic influences of inputs on neuronal activity.
- "A", the intrinsic coupling or the latent connectivity:
- fixed or endogenous effective connectivity;
 first order connectivity among the regions in the absence of input.
- "B", the bilinear term, modulatory effects, or the induced connectivity:
- context-dependent change in connectivity;
 eq. a second-order interaction between the input and activity in a source region when causing a response in a target region.

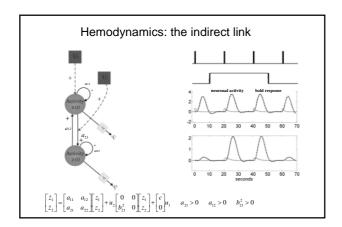
[Units]: rates, [Hz]; Strong connection = an effect that is influenced quickly or with a small time constant.

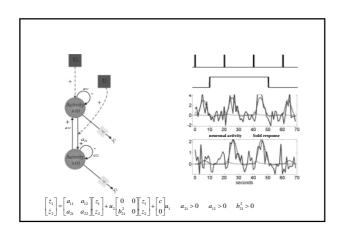
Integration of a first-order linear differential equation gives an exponential function: $\frac{dx}{dt} = ax \qquad \qquad x(t) = x_0 \exp(at)$ Coupling parameter a is inversely proportional to the half life τ of x(t): $x(\tau) = 0.5x_0$ $= x_0 \exp(a\tau)$ $a = \ln 2/\tau$ The coupling parameter a thus describes the speed of the exponential change in x(t) $\tau = \ln 2/a$

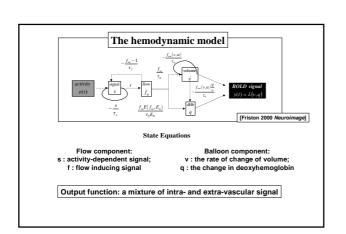
If A \rightarrow B is 0.10 s⁻¹ this means that, per unit time, the increase in activity in B corresponds to 10% of the activity in A

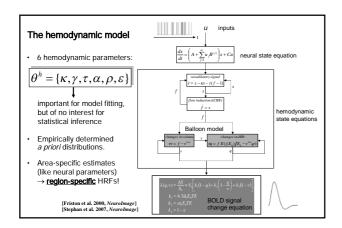


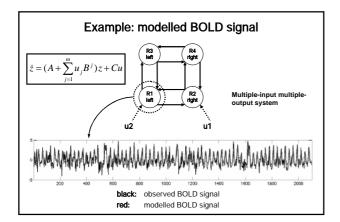












Priors & parameter estimation

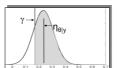
Bayesian statistics (inversion) Bayes theorem allows us to express our **prior knowledge** or "belief" about parameters of the model. $p(y|\overline{\theta})$ $p(\overline{\theta})$ 0.5 0.4 0.3 $p(\theta \mid y) \propto \vec{p}(y \mid \theta) p(\theta)$ posterior ∞ likelihood • prior The **posterior** probability of the parameters given the data is an optimal combination of prior knowledge and new data, weighted by Priors in DCM their relative precision. hemodynamic parameters: empirical priors coupling parameters of self-connections: principled priors coupling parameters other connections: shrinkage priors

Inference about DCM parameters: **Bayesian inversion**

- Gaussian assumptions about the posterior distributions of the parameters
- Use of the cumulative normal distribution to test the probability that a certain parameter (or contrast of parameters $c^T\eta_{\theta|y}$ is above a chosen threshold γ

$$p = \phi_N \left(\frac{c^T \eta_{\theta|y} - \gamma}{\sqrt{c^T C_{\theta|y} c}} \right)$$

mean $\eta_{\theta|y}$ and covariance $C_{\theta|y}$



• By default, γ is chosen as zero ("does the effect exist?").

Bayesian parameter estimation by means of expectation-maximisation (EM)

[Friston 2002 Neuroimage]

DCM: practical steps Select areas you want to model · Extract timeseries of these areas (x(t)) · Specify at neuronal level - what drives areas (c) neuronal - how areas interact (a) states - what modulates interactions (b) State-space model with 2 levels: - Hidden neural dynamics BOLD - Predicted BOLD response · Estimate model parameters: Gaussian a posteriori parameter distributions, characterised by

Attention to motion in the visual system

Stimuli 250 radially moving dots at 4.7 degrees/s

Pre-Scanning

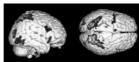
5 x 30s trials with 5 speed changes (reducing to 1%) Task - detect change in radial velocity

Scanning (no speed changes) 6 normal subjects, 4 x 100 scan sessions; each session comprising 10 scans of 4 different conditions

FAFNFAFNS....

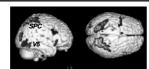
- F fixation point only
 A motion stimuli with attention (detect changes)
- N motion stimuli without attention
- S no motion





[Büchel & Friston 1997, Cereb. Cortex] [Büchel et al. 1998, Brain]

How we can interpret, mechanistically, the increase in activity of area V5 by attention when motion is physically unchanged.



Choice of areas and time series extraction. → Three ROIs: V1, V5, and SPC.

Definition of driving inputs.

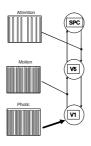
→ All visual stimuli/conditions (photic: A N S)

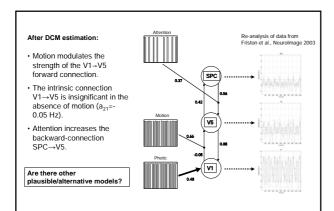
Definition of modulatory inputs.
→ The effects of motion and attention (A N)

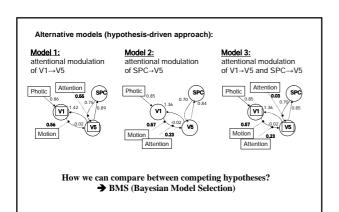
Building the model:

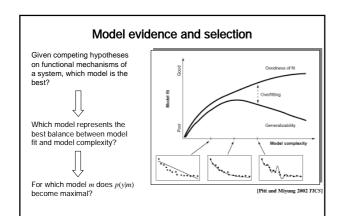
- 1- how to connect regions (intrinsic connections "A");
- 2- how the driving inputs enter the system (extrinsic effects "C");
 3- define the context-dependent connections (modulatory effects "B").

- Visual inputs drive V1.
- · Activity then spreads to hierarchically arranged visual
- Motion modulates the strength of the V1→V5 forward connection.
- Attention modualtes the strength of the SPC→V5 backward connection.









Bayesian model selection (BMS)

 $p(\theta \mid y, m) = \frac{p(y \mid \theta, m)p(\theta \mid m)}{p(\theta \mid y, m)}$ Bayes' rule: p(y|m)

Model evidence: $p(y|m) = \int p(y|\theta,m) \cdot p(\theta|m) d\theta$

Model evidence: probability of generating data y from parameters θ that are randomly sampled from the prior p(m).

Maximum likelihood: probability of the data y for the specific parameter vector θ that maximises $p(y|\theta,m)$

- > accounts for both accuracy and complexity of the model
- integral usually not analytically solvable, approximations necessary

Approximations to the model evidence in DCM

monotonic function

$$\qquad \qquad \Longrightarrow$$

Maximizing log model evidence

= Maximizing model evidence

Log model evidence = balance between fit and complexity

$$\log p(y | m) = accuracy(m) - complexity(m)$$
$$= \log p(y | \theta, m) - complexity(m)$$

The negative variotional free energy (F) approximation [Penny et al. 2014, NeuroImage] [Penny et al. 2010, PLoS Comp Biol]

Under Gaussian assumptions about the posterior (Laplace approximation), the negative free energy F is a lower bound on the log model evidence:

$$\Rightarrow F = \log p(y \mid m) - KL[q(\theta), p(\theta \mid y, m)]$$

The complexity term in F

• The negative free energy *F* accounts for parameter interdependencies.

$$\mathit{KL}[q(\theta), p(\theta \mid m)]$$

$$= \frac{1}{2} |C_{\theta}| - \frac{1}{2} |C_{\theta|y}| + \frac{1}{2} (\mu_{\theta|y} - \mu_{\theta})^{\mathsf{T}} C_{\theta}^{-1} (\mu_{\theta|y} - \mu_{\theta})$$

- The complexity term of F is higher
 - the more independent the prior parameters (\uparrow effective DFs)
 - the more dependent the posterior parameters
 - the more the posterior mean deviates from the prior mean
- NB: SPM8 only uses F for model selection !

Bayes factors

To compare two models, we can just compare their log evidences.

But: the log evidence is just some number – not very intuitive!

A more intuitive interpretation of model comparisons is made possible by Bayes factors:

positive value, [0; ∞[

$$BF_{12} = \frac{p(y | m_1)}{p(y | m_2)}$$

Kass & Raftery classification: [Kass & Raftery 1995, J. Am. Stat. Assoc.]

| BF ₁₂ | $p(m_1 y)$ | Evidence |
|------------------|------------|-------------|
| 1 to 3 | 50-75% | weak |
| 3 to 20 | 75-95% | positive |
| 20 to 150 | 95-99% | strong |
| ≥ 150 | ≥ 99% | Very strong |

Bayesian Model Selection in group studies.

Fixed effects BMS at group level

Group Bayes factor (GBF) for 1...K subjects:

$$GBF_{ij} = \prod_{k} BF_{ij}^{(k)} \qquad BF_{ij} = \frac{p(y \mid m_i)}{p(y \mid m_j)}$$

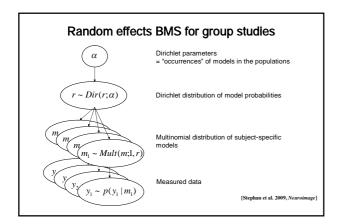
Average Bayes factor (ABF):

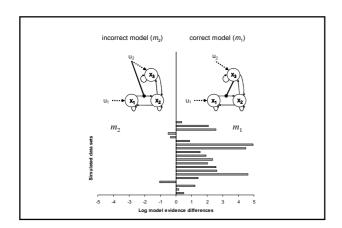
$$ABF_{ij} = \sqrt[K]{\prod_k BF_{ij}^{(k)}}$$

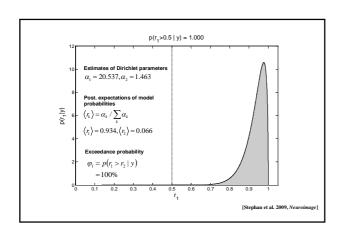
- Problems:

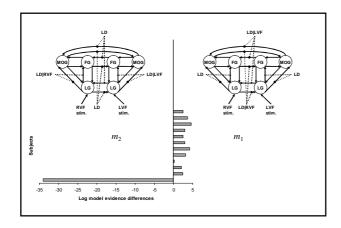
 ▶ blind with regard to group heterogeneity;

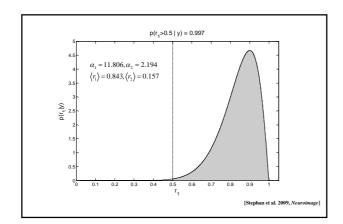
 ▶ sensitive to outliers.











Interface in SPM8

Post. expectations of model probabilities

$$\langle r_k \rangle = \alpha_k / \sum_k \alpha_k$$

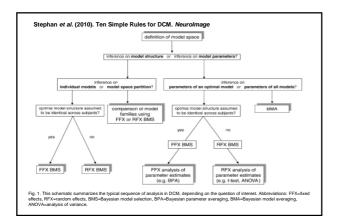
Exceedance probability

$$\forall j \in \{1...K\} \setminus k :$$

 $\varphi_k = p(r_k > r_j \mid y)$



Levels of inference: Group/population level -- Family level -- -- System/model level -- -- Parameter/connection level -- -- Parameter/connection level -- -- Parameter/connection level -- -- Parameter/connection level -- -- Variational Bayes: fast/accurate Nmod < N_sub_Gibbs sampling: optimal N_mod >> N_sub_Gibbs sampling: optimal N_mod sampling: optimal N_mod sampling: optimal N_mod sampling: optimal N_m





BMS has nothing to say about the "true" models.
find the most plausible (useful) model, given a set of alternatives.
Best model = best balance between accuracy and complexity.

BMS cannot be applied to models fitted to different data!
(Only models with the same ROIs can be compared using BMS).

It is helpful to constrain your DCM model space.

number of ROIs limited to 8 in SPM8 (GUI).

(e.g., 5 ROIs, fully connected, 1 Billion alternatives for modulations!).

Define sets of models that are plausible, in a systematic way, given prior knowledge about the system (e.g. anatomical, TMS, previous studies).

→ Bad models will affect your BMS results (BMS = a "relative" space)!

Extensions in DCM for fMRI (SPM8):

Bayesian Model Selection BMS

Slice specific sampling

Refined hemodynamic model

The two-state DCM

The non-linear DCM

Random-effects BMS (VB)

Random-effects BMS (Gibbs)

Stochastic DCM

Anatomical-based priors for DCM

· Family level inference BMS

Bayesian model averaging BMA

[Kiebel et al. 2007 Neuroimage]. [Stephan et al. 2007 Neuroimage]. [Marreiros et al. 2008 Neuroimage]. [Stephan et al. 2008 Neuroimage].

[Penny et al. 2004 Neuroimage].

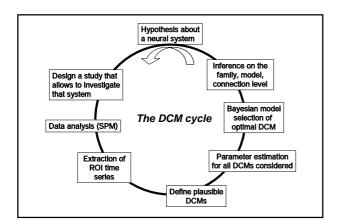
[Stephan et al. 2009 Neuroimage]. [Penny et al. 2010 PLoS Comp Biol].

[Daunizeau et al. 2009 Physica D].

Stephan et al. 2009 Neuroimage].

[Penny et al. 2010 PLoS Comp Biol].

[Penny et al. 2010 PLoS Comp Biol].



Theoritical reviews:

Stephan et al. (2010). Ten Simple Rules for DCM. Neurolmage

Daunizeau et al. (2010). DCM: a critical review of the biophysical and statistical foundations. Neurolmage

Friston (2009). Causal modelling and brain connectivity in fMRI. PLoS Biol

Applications: (recent examples of DCM-fMRI at the FIL)

- Word reading via the putamen: Seghier and Price (2010) Cerebral Cortex.

- Intelligible speech perception:

- Associative learning and prediction error: den Ouden et al. (2009) Cerebral Cortex.