

# Group Inference, Non-sphericity & Covariance Components in SPM

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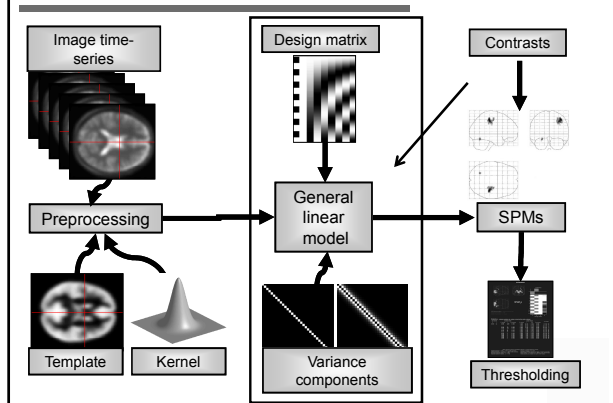
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## Overview of SPM




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## Overview

- Making the group inferences we want
  - Two stage GLM revisited
- Non-sphericity
- Beyond Ordinary Least Squares
  - Non-sphericity at the first level
  - Multiple Covariance Components
- Model estimation
- A word on power




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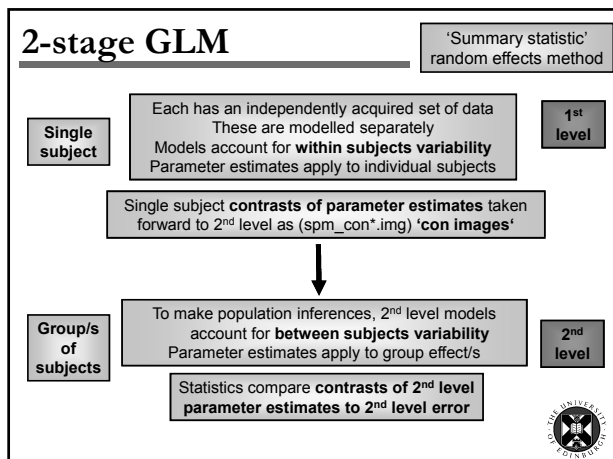
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## Models for fMRI

1. Non-sphericity & why it matters
2. Hierarchical models
  - Why they are needed
  - Issues and SPM solutions
3. We need to estimate
  - Effect magnitude
  - Effect variability
  - p values

$$t = \frac{\text{contrast of estimated parameters}}{\sqrt{\text{variance estimate}}}$$

Null Distribution of T

$p(T > t | H_0)$

The diagram shows the formula for the t-statistic and a graph of the Null Distribution of T. The graph is a bell curve with a vertical line at t, and the area to the right is shaded green and labeled p-value. The University of Edinburgh logo is in the bottom right corner.

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## Covariance and non-sphericity

- Classical inference is about what is surprising
- Compare observed (estimated) parameters with their expected behaviour under the null hypothesis
- A statistic is formed from estimates of effects and their variability, but how surprising is this?
- Degrees of freedom must reflect how related (correlated) different observations are
- If observations are not independent (i.e. covary), then there are fewer observations than we think, and the significance of statistics is overrated

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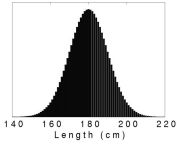
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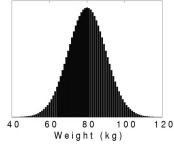
## Variance

Length of men



$$\mu=180\text{cm}, \sigma=14\text{cm} (\sigma^2=200)$$

Weight of men



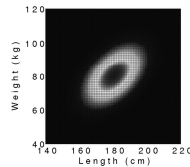
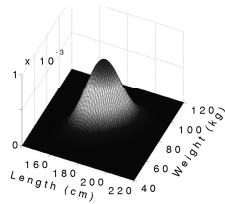
$$\mu=80\text{kg}, \sigma=14\text{kg} (\sigma^2=200)$$

Each 1-dimensional variable is completely characterised by  $\mu$  (mean) and  $\sigma^2$  (variance)

i.e. can calculate  $p(l|\mu, \sigma^2)$  for any  $l$  and  $p(w|\mu, \sigma^2)$  for any  $w$

## Variance-covariance matrix

- Can also view length and weight as a 2-dimensional stochastic variable ( $p(l, w)$ ).



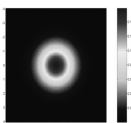
$$p(l, w | \mu, \Sigma)$$

$$\mu = \begin{bmatrix} 180 \\ 80 \end{bmatrix} \quad \Sigma = \begin{bmatrix} 200 & 100 \\ 100 & 200 \end{bmatrix}$$

Length and weight are related – i.e., covary

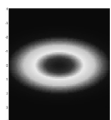
## What is (and isn't) sphericity?

sphericity  $\Rightarrow$  i.i.d.  
error covariance is a  
multiple of the  
identity matrix:  
 $\text{Cov}(e) = \sigma^2 I$



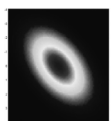
$$\text{Cov}(e) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Examples of non-sphericity:



$$\text{Cov}(e) = \begin{bmatrix} 4 & 0 \\ 0 & 1 \end{bmatrix}$$

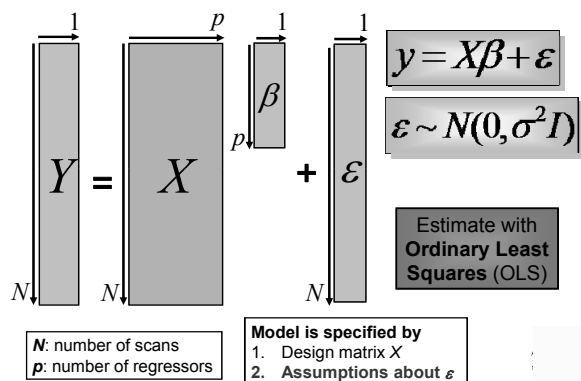
non-identity



$$\text{Cov}(e) = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

non-independence

### The voxel-wise GLM revisited



### Ordinary Least Squares estimation revisited

Find  $\hat{\beta}$  that minimises  $\|y - X\beta\|^2 = \varepsilon^T \varepsilon$

The Ordinary Least Squares parameter estimates are:

$$\hat{\beta} = (X^T X)^{-1} X^T y$$

Under i.i.d. assumptions i.e. sphericity, these estimates are unbiased, and have maximum precision (minimum variance)

$$\varepsilon \sim N(0, \sigma^2 I) \rightarrow Y \sim N(X\beta, \sigma^2 I)$$

$$\hat{\beta} \sim N(\beta, \sigma^2 (X^T X)^{-1})$$

$\hat{\sigma}^2 = \frac{\hat{\varepsilon}^T \hat{\varepsilon}}{N - p}$  Estimate of error variance

Covariance of parameter estimates

### Ordinary Least Squares conditions

- Estimated covariance of parameter estimates  
 $C_{\hat{\beta}} = (X^T C_{\varepsilon}^{-1} X)^{-1}$   
 $\hat{C}_{\varepsilon} = \sigma^2 I$  i.i.d.
- Estimation is direct – find the (pseudo) inverse of the design matrix  $X$  & multiply data by it
- This works because there is a single covariance component, the variance  $\sigma^2$
- But only valid if errors are i.i.d. because covariance affects the statistics...



## Covariance and statistics

$$T = \frac{c^T \hat{\beta}}{\sqrt{\text{var}(c^T \hat{\beta})}} = \frac{c^T \hat{\beta}}{\sqrt{\hat{\sigma}^2 c^T (X^T X)^{-1} c}} \sim t_{N-p}$$

$$T = \frac{\text{contrast of estimated parameters}}{\sqrt{\text{variance estimate}}}$$

- How good an estimator (precise) is  $\beta$ ?
- How much do we think betas covary? – a minimum  $C_\beta$  maximises T
- df are also a function of  $C_\varepsilon$  & design matrix X...

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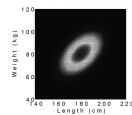
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## The traditional solution (e.g. SPSS)

- A measure of departure from sphericity:  $\varepsilon$
- Using  $\varepsilon$ , distribution of SS ratios is approximated by F with Greenhouse-Geisser df – i.e. fewer

Heights & weights



$$\Sigma = \begin{pmatrix} 200 & 100 \\ 100 & 200 \end{pmatrix} \quad \varepsilon = 0.8$$

= Satterthwaite correction

(in theory sl. liberal – but see Mumford & Nichols, 2009)

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## Sphericity, df and surprise

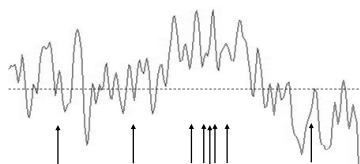
How much do the following observations tell us?

Rain on 4 consecutive days in June

Rain on the same day in May, June, July and August

...which is more likely to indicate a wet summer?

Can we determine the patterns of correlation?




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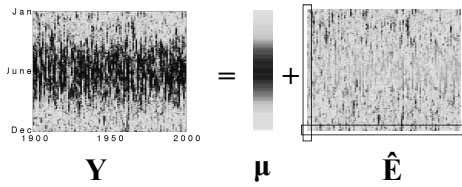
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## The rain in Bergen

12 months for 100 years



A simple GLM: model monthly rainfall using mean  
Data from whole 20th century




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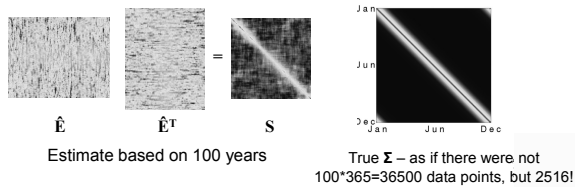
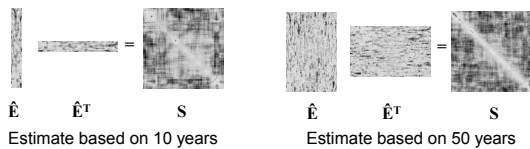
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## Estimating nonsphericity




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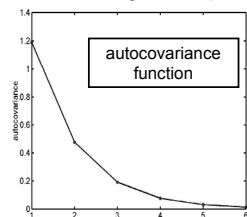
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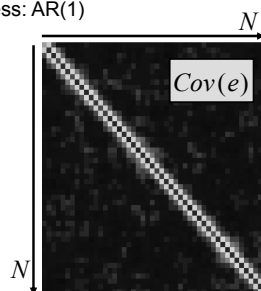
## Serial correlations in fMRI

$$e_t = ae_{t-1} + \varepsilon_t \text{ with } \varepsilon_t \sim N(0, \sigma^2)$$

1<sup>st</sup> order autoregressive process: AR(1)



Also: high-pass filtering




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## Dealing with serial correlations

### Pre-whitening

- Use an enhanced noise model with multiple error covariance components  
i.e.  $e \sim N(0, \sigma^2 V)$  instead of  $e \sim N(0, \sigma^2 I)$   
V is modelled using AR (1) + white noise model estimated across all active voxels
- Use the estimated V to specify a filter matrix W for whitening the data – 'undoing' the serial correlations

$$We \sim N(0, \sigma^2 W^2 V)$$

$$\Rightarrow W^2 V = I$$

$$\Rightarrow W = V^{-1/2}$$

$$Wy = WX\beta + We$$




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## Dealing with serial correlations

- Once data are 'pre-whitened', estimation can proceed using Ordinary Least Squares
- The parameter estimates are again optimal – unbiased and minimum variance
- This is Generalised Least Squares (GLS)
- However
  - How do we estimate V?
  - How robust is this method?




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## Prewhitening in SPM

- Model using  $e_t = ae_{t-1} + \varepsilon_t$  with  $\varepsilon_t \sim N(0, \sigma^2)$
- 1<sup>st</sup> order autoregressive process: AR(1)
  - Cannot be estimated precisely at each voxel
  - But precision is key, or estimates are worse than OLS – biased and imprecise
  - Use spatial regularisation
  - Pool estimation over active voxels, defined using 1st pass OLS estimate ( $P < .001$ )
- PLUS White noise – voxel-specific variance  $\sigma^2$
- AND – this introduces another issue...




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## Discovering the 'colour'

- In order to prewhiten we want to know the error covariance
  - Estimate it using  $C_\varepsilon$  - BUT now not multiple of I
  - $C_\varepsilon = \hat{\varepsilon}\hat{\varepsilon}^T + X C_\beta X^T$
  - $C_\beta$  is a function of  $C_\varepsilon$ !
- So to prewhiten we need to know
  - Covariance of residuals
  - Covariance of parameter estimates that produced the residuals
- ...Use EM/ ReML

$$C\hat{\beta} = (X^T C_\varepsilon^{-1} X)^{-1}$$

$$\hat{C}_\varepsilon \neq \sigma^2 I$$

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## Why bother with 2 stages?

- We want to make an inference to the population, not a single subject, so why do we care?
- Why can't we just do group stats on data for each voxel, as in SPSS?

$$Y = X\beta + \varepsilon$$

Use if data Y are simple values per voxel  
– precisely known

Estimate with Ordinary Least Squares (OLS)

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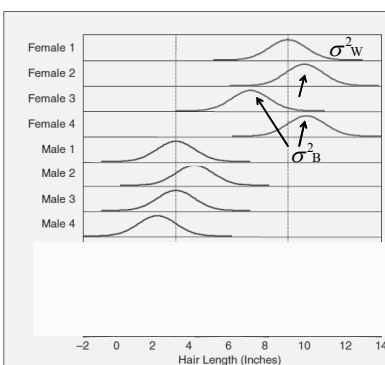
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## Hierarchical models



Mumford & Nichols (2006)

### Does hair length differ by gender?

2 sources of variability

Within-subject:  $\sigma^2_W$

Between-subjects:  $\sigma^2_B$

To generalise across this sample, combine data from hairs measured in all subjects, get  $\sigma^2_{FFX}$

To generalise to population, use estimates of hair length for each subject, get  $\sigma^2_{MFX}$

**MIX of between/within variability**

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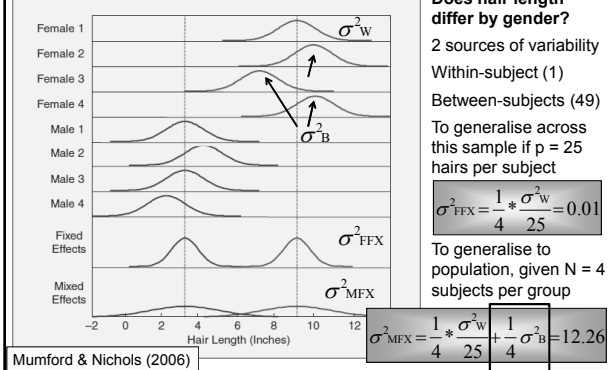
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## Hierarchical models

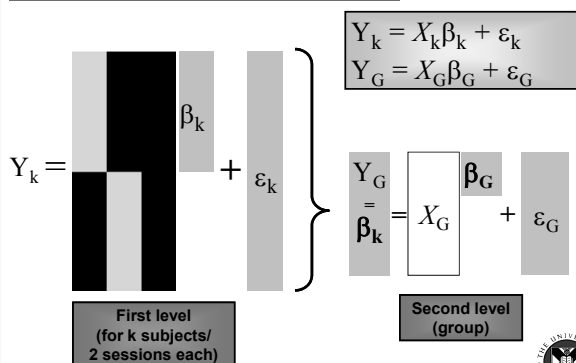


## Why bother with 2 stages?

- We want to make an inference to the population, not a single subject, so why do we care?
- Why can't we just do group stats on data for each voxel, as in SPSS?
- ...that could be valid but would not be optimal
- Hierarchical models deal with mixed sources of variance, not just between-subject variance
- Model both scan-to-scan and subject-to-subject variability



## A hierarchical model for fMRI



## Hierarchical modelling in SPM

- Two approaches
  1. Simple summary statistic – Holmes & Friston
  2. Non-sphericity modelling at group level
- Pros and cons – assumptions vs. flexibility
  - Subject variances equivalent
  - Subject design matrices equivalent
  - (2) enables a wide range of 2<sup>nd</sup> level models




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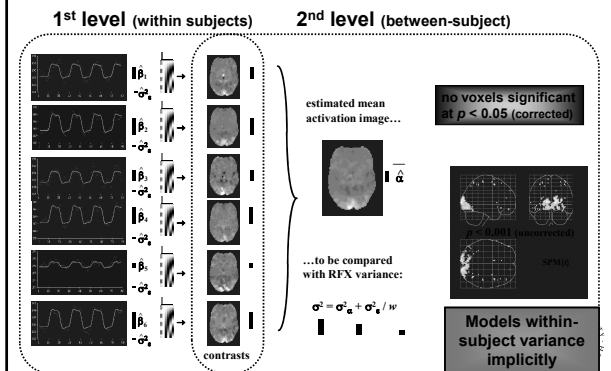
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## Summary statistic 'HF' approach




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## Simple HF approach - assumptions

- Distribution
  - Normality, independent subjects
- Homogeneous variance
  - Subjects' residual errors same
  - Subjects' design matrices same

- 2 covariance components
- Collapse into 1 if the elements of  $\text{Cov}(Y_G)$  are homogenous over subjects

$$Y_G = X_G \beta_G + \epsilon_G^m$$

$$\text{Cov}(\epsilon_G^m) = \text{Cov}(Y_G) + \sigma_G^2 \text{In}$$

$$\text{Cov}(Y_G) = \sum_i \sigma_i^2 c(X_i' V_i^{-1} X_i)^{-1} c'$$

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## Simple HF approach

- Only single image per subject
- Limits analysis to 1- or 2-sample t-tests at the 2<sup>nd</sup> level
- Balanced designs
- Limitation = strength
  - No 2<sup>nd</sup> level sphericity assumption
  - 'Partitioned' error term @ 2<sup>nd</sup> level




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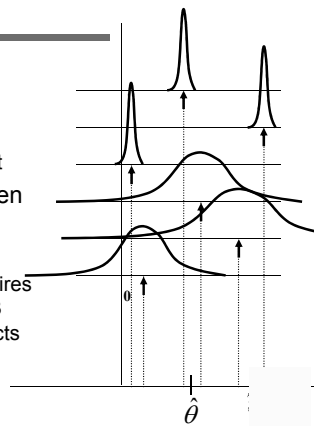
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## HF – efficiency

- If assumptions true
  - Optimal, fully efficient
- If  $\sigma^2_{\text{FFX}}$  differs between subjects
  - Reduced efficiency
  - Here, optimal  $\hat{\theta}$  requires down-weighting the 3 highly variable subjects




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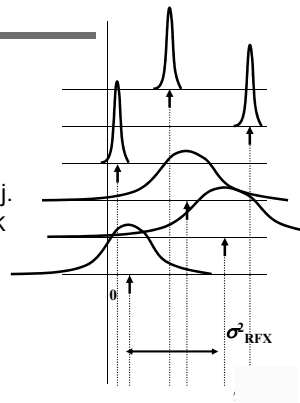
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## HF – validity

- If assumptions true
  - Exact P-values
- If  $\sigma^2_{\text{FFX}}$  differs btw subj.
  - Standard errors not OK
    - Est. of  $\sigma^2_{\text{RFX}}$  may be biased
  - df not OK
    - Here, 3 Ss dominate
    - $DF < 5 = 6-1$




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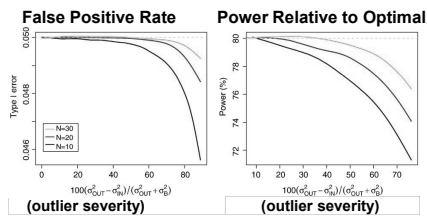
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## HF – robustness

- In practice, Validity & Efficiency are excellent
  - For one sample case, HF very robust



- Potential concern with 2-sample or correlation if outliers/ large imbalance

## A more flexible approach

- Can model non-sphericity at the 2<sup>nd</sup> level
- Model within-level just as at 1<sup>st</sup> level
- Represent different sources of covariance using linear combination of basis functions
- Multiple covariance components
  - Need to estimate using ReML as at 1<sup>st</sup> level
  - Prewhitening approach, cross-voxel 'pooling'



## Modelling 2<sup>nd</sup> level covariance

- Errors are independent but not identical



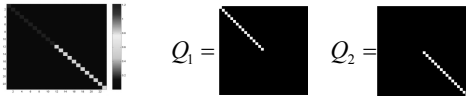
- Errors are not independent and not identical



## Non-identical data

Errors can be Independent but Non-Identical when...

- 1) One parameter but from different groups – 2-sample t-test  
e.g. patients and control groups




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## Non-independent data

Error can be Non-Independent and Non-Identical when...

Several contrasts per subject are taken to 2<sup>nd</sup> level  
e.g. Repeated Measures ANOVA

Omnibus test is needed across several basis functions characterising the hemodynamic response  
e.g. F-test combining HRF, temporal derivative and dispersion regressors




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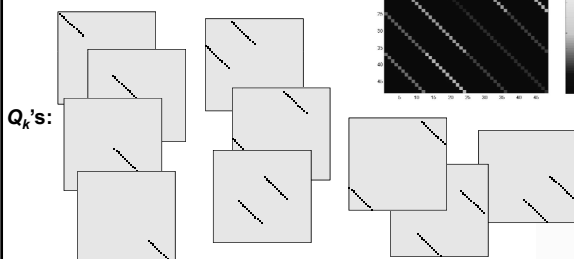
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## Non-independent data

Errors are not independent and not identical




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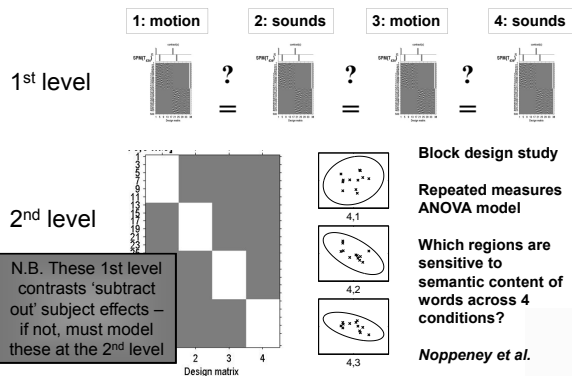
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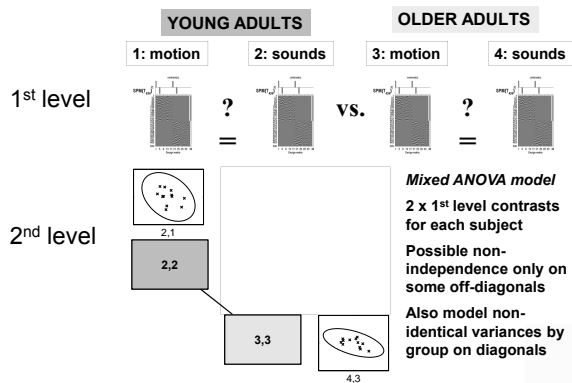
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## Example



## Example



## A more flexible approach

- Assumptions
  - Fewer than HF but may be more at risk of violations
  - of cross-voxel pooling, homogenous across 'active' voxels
  - Within subject covariance still homogenous
- Advantages
  - Fast relative to 'full' mixed-effects procedures
  - Flexibility of 2nd level models e.g. Multiple basis functions



## Summary

- fMRI models need to take account of
  - Multiple sources of variability at 1<sup>st</sup> level
  - Hierarchical nature of data
  - Multiple sources of variability at 2<sup>nd</sup> level
- If estimate correctly, get maximum precision, unbiased estimates of parameters & errors
  - Iterative methods are used (EM/ ReML)
  - Spatial regularisation by cross-voxel pooling
  - SPM8 enables very flexible 2<sup>nd</sup> level models



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Many thanks to J Andersson, J Daunizeau, R Henson, A Holmes, S Kiebel, T Nichols for slides



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