DTU Aqua: Department of Marine Fisheries http://www.dfu.dtu.dk/

State—space Stock Assessment as simple alternative to (semi) deterministic approaches and full parametric stochastic models

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#### Problems we wish to solve

- Deterministic approaches
  - Catch at age assumed known without error
  - Procedures not models
  - Convergence of a deterministic procedure
  - Ad-hoc adjustments
- Full parametric statistical models
  - Parametric F-structure (e.g. multiplicative)
  - Trade off between flexible with (too) many parameters and rigid with tractable number of parameters
  - Number of parameters increase with every new year of data added





















### State-space assessment models

- A very useful extension to full parametric statistical models is state-space models<sup>a</sup>
- Introduced for stock assessment by Gudmundsson (1987,1994) and Fryer (2001)
- The reason state-space models have not been more frequently used in stock assessment is that software to handle these models has not been available
- Can give very flexible models with low number of model parameters
- For instance we can include things like:

 $F_{3,y}$  is a random walk with yearly variance  $\sigma^2$ 

- Notice:
  - + Only one parameter  $(\sigma)$  to estimate for all  $F_{3,y}$  instead of one every year
  - +  $F_{3,y}$  are predicted once the parameters are estimated
  - + Each  $F_{3,y}$  is not estimated in isolation, but as part of the  $F_3$ -series
  - + This model includes the intuition behind 'F-shrinkage' and 'tapered time weights', but the amount is objectively estimated

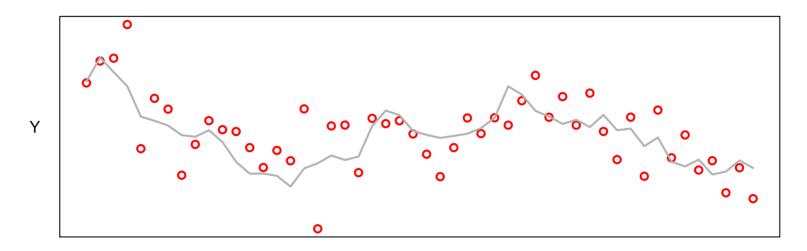
<sup>&</sup>lt;sup>a</sup>a.k.a. random effects models, mixed models, latent variable models, hierarchical models, ...







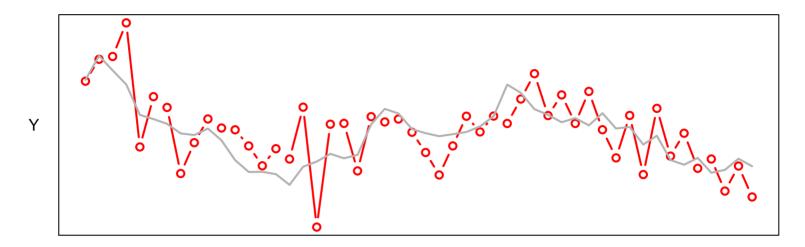
# Illustration of the three types of models



- Consider this example:
  - The true underlying F (here grey) follows a random walk with variance  $\sigma_F^2$
  - But we only observe Y (here red circles) which is F+'noise' with variance  $\sigma_Y^2$



# Deterministic model estimates



- If we assume no observation error the estimate of F is Y
- Too fluctuating
- No quantification of uncertainties











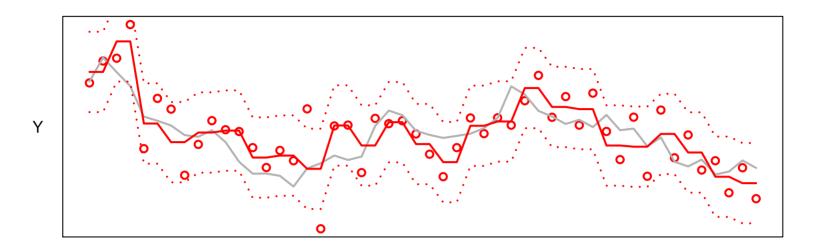








### Fully parametrized statistical model estimates



- To use a fully parametrized statistical model we first had to group the observations (here pairs, but choice is arbitrary)
- The reconstructed track appear OK
- The model contain 26 model parameters
- Uncertainties are estimated but the confidence interval seems too wide













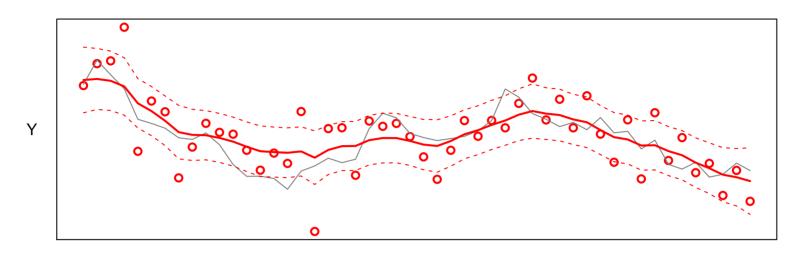








# State-space model estimates



- Consider  $\lambda$  as unobserved random variable
  - Estimate model parameters  $(\sigma_{\eta} \text{ and } \sigma_{\varepsilon})$  in marginal distribution  $\int p(\lambda, Y) d\lambda$
  - Predict  $\lambda$  via distribution of  $\lambda | Y$
- Closer reconstruction
- No artificial assumptions
- Two model parameters
- Correct coverage of the confidence interval
- Naturally this is just a simulated example, but ...









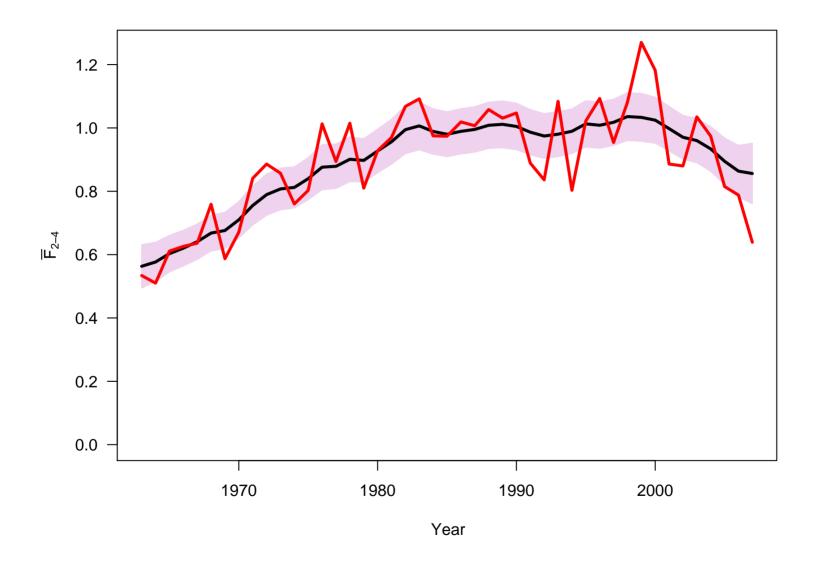








# Example: $\overline{F}_{2-4}$ for North Sea Cod























#### Model

**States** are the random variables that we don't observe  $(N_{a,y}, F_{a,y})$ 

$$\begin{pmatrix} N_y \\ F_y \end{pmatrix} = T \begin{pmatrix} N_{y-1} \\ F_{y-1} \end{pmatrix} + \eta_y$$

**Observations** are the random variables that we do observe  $(C_{a,y}, I_{a,y}^{(s)})$ 

$$\begin{pmatrix} C_y \\ I_y^{(s)} \end{pmatrix} = O \begin{pmatrix} N_y \\ F_y \end{pmatrix} + \varepsilon_y$$

**Model and parameters** are what describes the distribution of states and observations through T, O,  $\eta_y$ , and  $\varepsilon_y$ .

Parameters: Survey catchabilities, S-R parameters, process and observation variances.

All model equation are as expected:

- Standard stock equation
- Standard stock recruitment (B-H, Ricker, or RW)
- Standard equations for total landings and survey indices









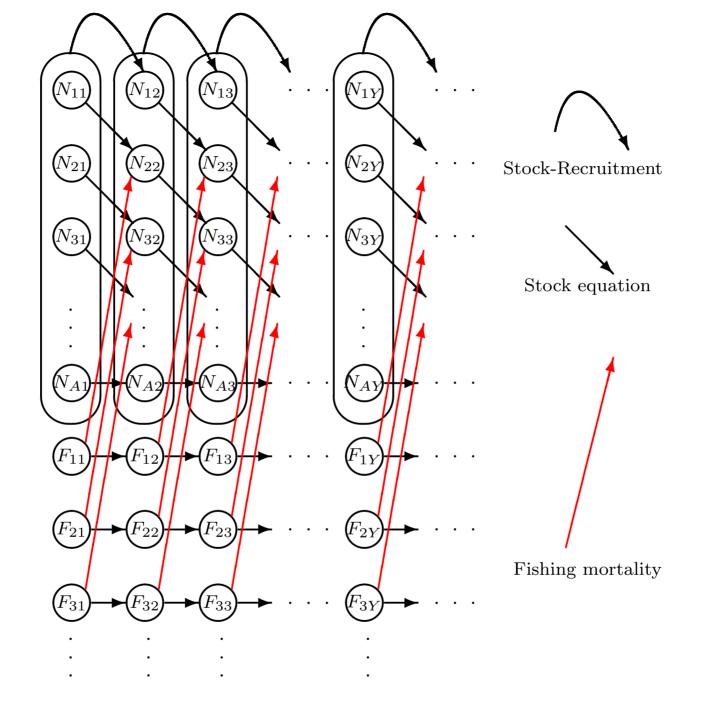






























### **Numerical Methods**

- Kalman Filter
- Extended Kalman Filter
- Unscented Kalman Filter
- Laplace approximation
- Sampling based methods

(Numerical methods are needed to calculate the marginal distribution)

Optimization is done using AD Model Builder





















#### Random effects in AD Model Builder

- In random effects models we have
  - Random variables we observe: x
  - Random variables we do not observe: z
  - Model parameters we want to estimate:  $\theta$
- If we had observed x and z we would have a joint likelihood  $L(x, z, \theta)$
- but z is unobserved so we have to estimate  $\theta$  in the marginal likelihood:

$$L(x,\theta) = \int L(x,z,\theta)dz$$

- This requires a high dimensional integral which is difficult
- This is (part of) the reason MCMC methods are so widely used
- MCMC can be slow, difficult to judge convergence, and in tools like winBugs a prior must be assigned to everything even when you have no prior information.
- AD Model Builder has a better solution



















# Laplace approximation

• Want to compute the marginal likelihood for a given  $\theta$  value:

$$L(x,\theta) = \int L(x,z,\theta)dz$$

- First the joint likelihood  $L(x, z, \theta)$  is optimized w.r.t. z.
- This optimization yields an estimate  $\hat{z}$ , and an estimated hessian  $\mathcal{H}(\hat{z})$ .
- Next a Gaussian approximation is assumed and the result (apart from a constant) is:

$$L(x,\theta) \approx |\det(\mathcal{H}(\hat{z}))|^{-0.5} L(x,\hat{z},\theta)$$

- Notice that when defined in this way  $\hat{z}$  and  $\mathcal{H}(\hat{z})$  and also depend on  $\theta$ , which makes AD of this pretty difficult, but all solved for us in AD Model Builder.
- Actually this is all very simple to use. All we have to do is:
  - Code up the joint negative log likelihood
  - declare as random\_effects\_vector z(1,n);











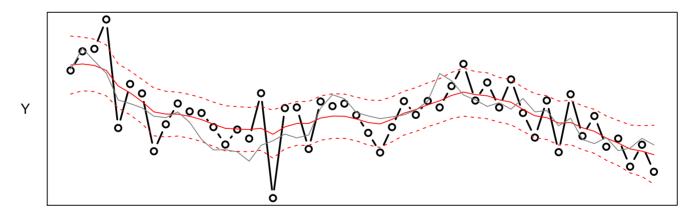






```
DATA_SECTION
  init_int N
  init_vector y(1,N)
PARAMETER_SECTION
  init_number logSdLam
  init_number logSdy
  random_effects_vector lam(1,N);
  objective_function_value jnll;
PROCEDURE SECTION
  jnll=0.0;
  dvariable var=exp(2.0*logSdLam);
  for(int i=2; i<=N; ++i){
    inl1+=0.5*(log(2.0*M_PI*var))
               +square(lam(i)-lam(i-1))/var);
  var=exp(2.0*logSdy);
  for(int i=1; i<=N; ++i){
    inll+=0.5*(log(2.0*M_PI*var)
               +square(lam(i)-y(i))/var);
TOP_OF_MAIN_SECTION
  gradient_structure::set_MAX_NVAR_OFFSET(3000);
```

```
index
         name
                      value
                                   std dev
         logSdLam -2.3131e-01 2.8824e-01
         logSdy
                      5.5298e-01 1.2554e-01
         lam
                     -1.1611e+00 1.0876e+00
                       .0768e+00
          lam
                    -1.1900e+00 9.8298e-01
-1.5622e+00 9.5522e-01
          lam
          lam
                     -2.7309e+00 8.2689e-01
         lam
                     -3.2436e+00 8.2301e-01
          lam
                     -3.8943e+00 8.3214e-01
          lam
                     -4.6716e+00 8.9801e-01
         lam
                    -5.1027e+00 8.2002e-01
-5.5115e+00 8.2467e-01
         lam
         lam
         lam
                     -5.4663e+00
                     -5.8623e+00
          lam
                     -6.1294e+00
          lam
                     -6.6359e+00 8.2991e-01
         lam
                     -7.0076e+00 8.4620e-01
         lam
                     -7.4495e+00 8.9770e-01
          lam
                    -7.6153e+00 9.5078e-01
-7.8819e+00 1.1064e+00
          lam
          lam
```





















#### **Status**

- Primary model for Western Baltic Cod, Kattegat Cod, and Sole in 3A
- Exploratory model for Eastern Baltic Cod, North Sea Cod, and North Sea Sole
- Quick unsystematic tests for a few other stocks (Western Baltic spring spawning herring, North Sea Haddock, 3PS Cod, and Georges Bank Yellowtail Flounder)

















# From Fryer's listed disadvantages

- Requires normally distributed errors. No, but they are still convenient.
- Requires linear approximation of non-linear equations. **Not anymore.**
- There is some arbitrariness in the starting values. Not anymore.
- The likelihood can be very flat. No change.
- Maximum likelihood estimation can take a long time. 1-2 minutes on my laptop.
- Initial coding is hard. ADMB makes it easier
- Favours status quo so struggles to pick up a collapsing stock.





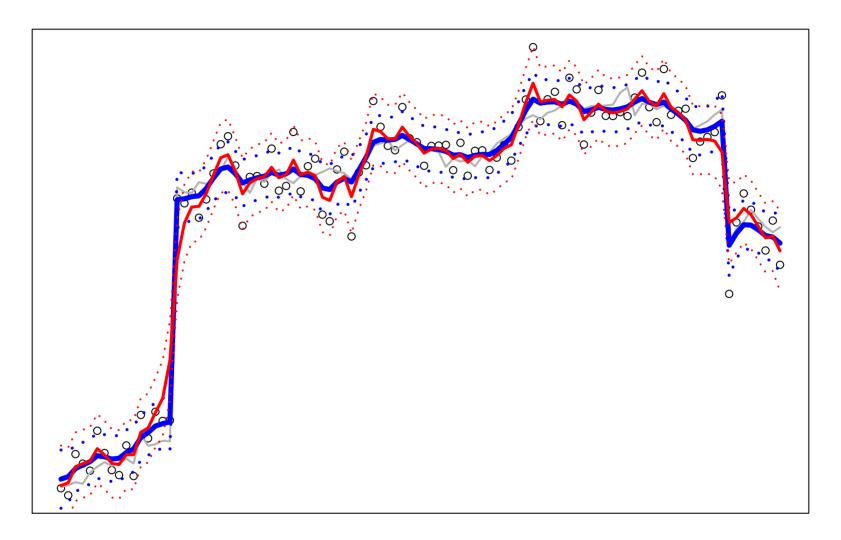








# Allow sharp jumps



- In the standard model  $\Delta \log F_y = \log F_y \log F_{y-1}$  is assumed Gaussian
- Instead use a mixture, such as:  $\Delta \log F_y \sim (1-p)\mathbf{N}(.,.) + p\mathbf{t}_1(.,.)$















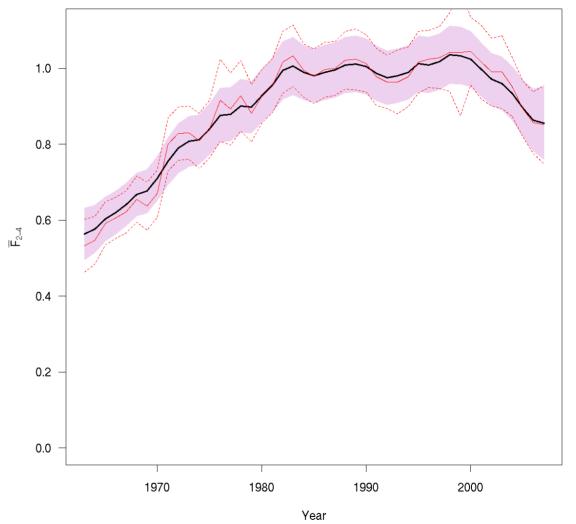


# Allow sharp jumps - results

Allowing the t-jump-fraction p to be estimated.
No change.

• Forcing p = 10%. No visible change.

Forcing p = 30%.
Visible change,
but nothing dramatic





















### **Correlated Random Walks**

ullet Instead of independent random walks for F at different ages, we can allow those random walks to be correlated

$$\Delta \log(F) \sim \mathcal{N}(0, \Sigma)$$

- The covariance matrix  $\Sigma$  is defined via the random walk variances, and the correlation coefficients  $\rho_{i,j} = \Sigma_{i,j} / \sqrt{\Sigma_{i,i} \Sigma_{j,j}}$
- We assume the very simple structure

$$\rho_{i,j} = \begin{cases} 1, & \text{for } i = j \\ \rho, & \text{otherwise} \end{cases}$$









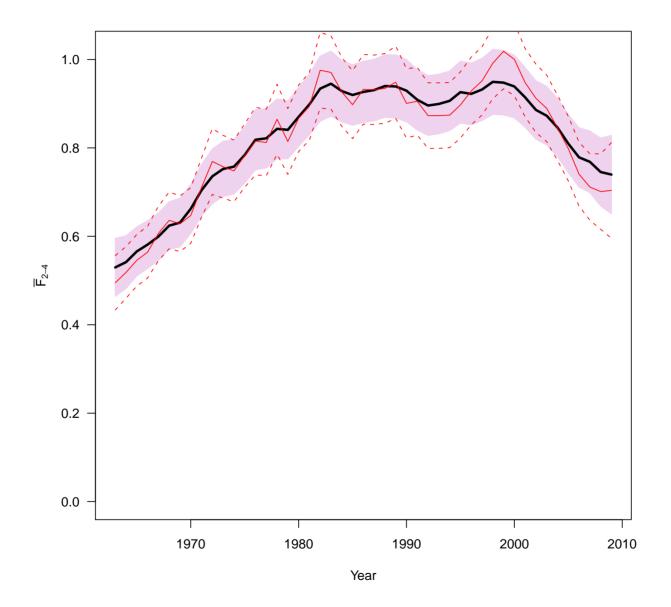








# Correlated Random Walks — results

















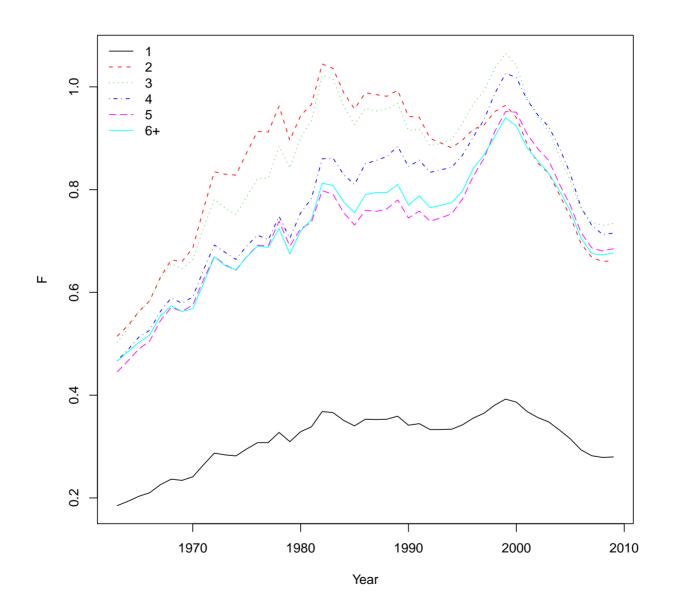








# Correlated Random Walks — results















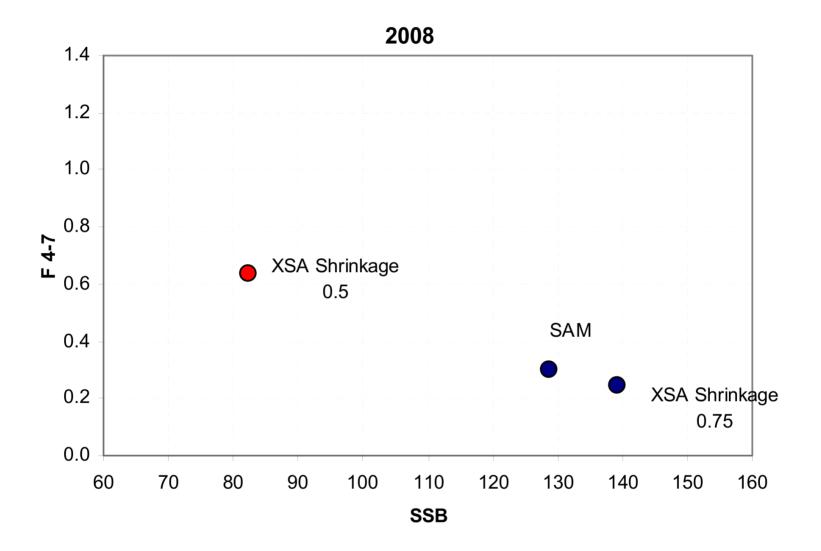








# Avoiding ad-hoc choices — Eastern Baltic Cod



• Using the State-space Assessment Model (SAM) gives us an objective criteria





















# Features of the State-space assessment model

- Statistical model
- Consistent treatment of all  $N_{a,y}$
- Random walk fishing mortality ( $\log F_{a,y} = \log F_{a,y-1} + e_{a,y}$ )
- Allows selectivity to evolve
- Maximum likelihood estimation of model parameters
- Estimation of uncertainties are an integrated part of the model
- Prediction is straight-forward
- Built-in 'F-shrinkage' and 'tapered time weights'
- Nicely handles missing observations
- Room for additional features



















# Web interface - Why?

- Scientific software is a way communicate ideas
- Peer review process is important
- Should be possible for all involved to:
  - see all details of the implementation<sup>a</sup>
  - run it themselves
  - experiment with data
  - experiment with model assumptions
  - run the same version
- The interface makes it all one step easier
- Will make update assessment very easy

aincluding all the "invisible" fixes they have had to include to get their models to work!





















### Web interface - How?

- Send an email<sup>a</sup> to request an account
- We will send a password back
- Go to the stock page:
   http://www.kcod.stockassessment.org
   http://www.sole3a.stockassessment.org
   http://www.nscod.stockassessment.org
   http://www.sole4.stockassessment.org

http://www.wbcod.stockassessment.org
http://www.ebcod.stockassessment.org
http://www.wbssher.stockassessment.org
http://www.plaice3a.stockassessment.org

• Log in to your new account



 $<sup>^{\</sup>rm a}$ an@aqua.dtu.dk or cbe@aqua.dtu.dk













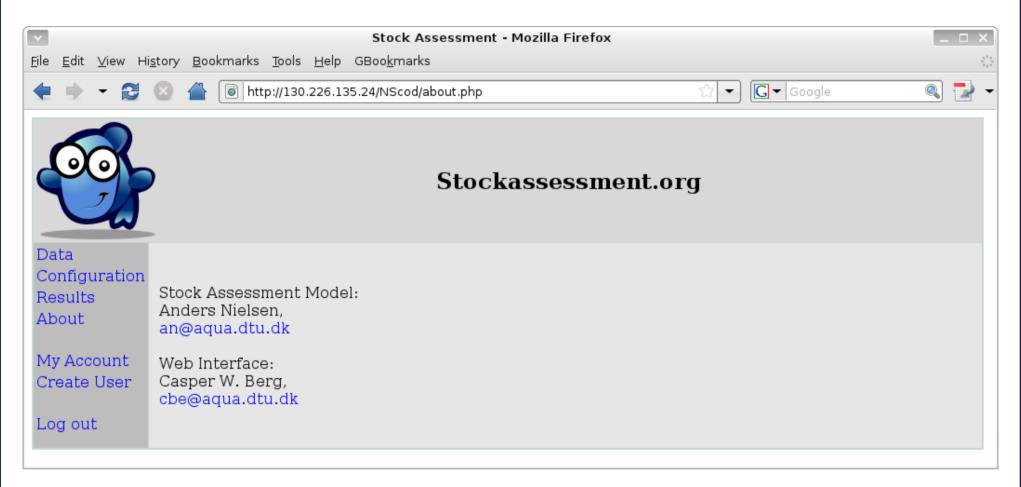








#### Web interface - How?



(small demo?)





















### Three scenarios for North Sea Cod

$$\log(C_{a,y}S_{a,y}) = \log\left(\frac{F_{a,y}}{Z_{a,y}}(1 - e^{-Z_{a,y}})N_{a,y}\right) + \varepsilon_{a,y}$$

• Use total landings as reported

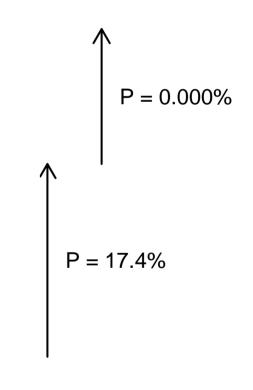
$$S_{a,y} = 1$$

• Separate scaling each year

$$S_{a,y} = \begin{cases} 1, & y < 1993 \\ \tau_y, & y \ge 1993 \end{cases}$$

• Separate scaling each year, and in three age classes

Year, and in three age classes
$$S_{a,y} = \begin{cases} 1, & y < 1993 \\ \tau_y^{(1)}, & y \ge 1993 \& a = 1 \\ \tau_y^{(2)}, & y \ge 1993 \& a = 2 \\ \tau_y^{(3+)}, & y \ge 1993 \& a \ge 3 \end{cases}$$













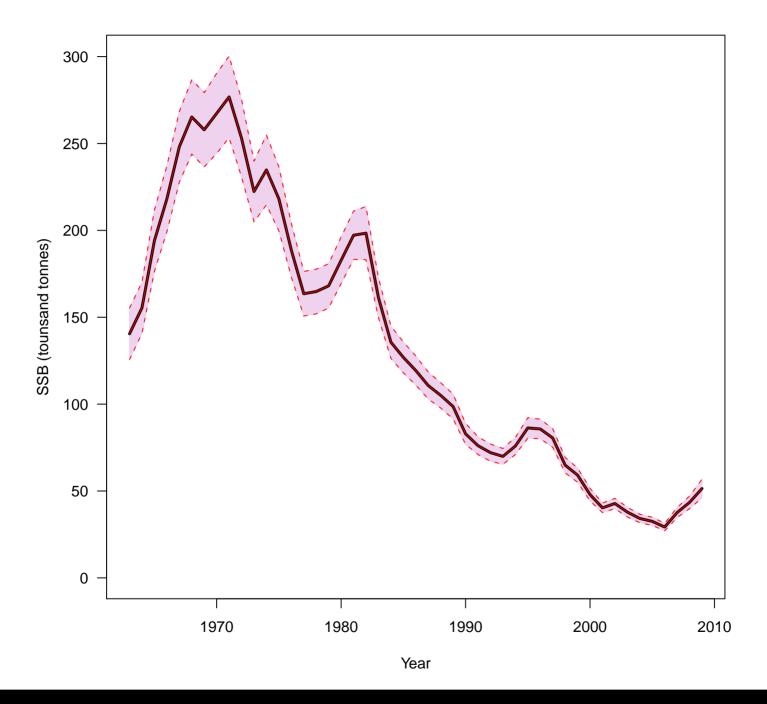






















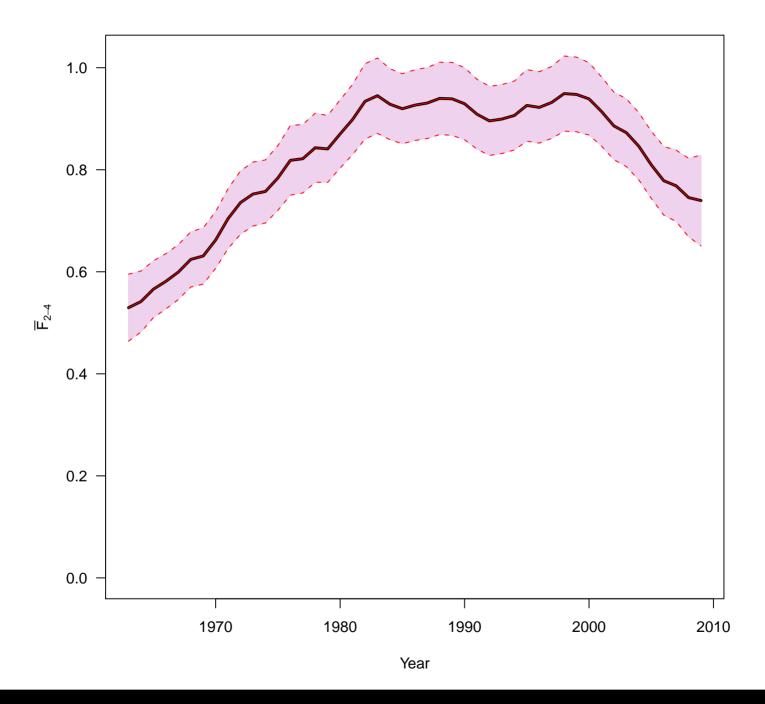




















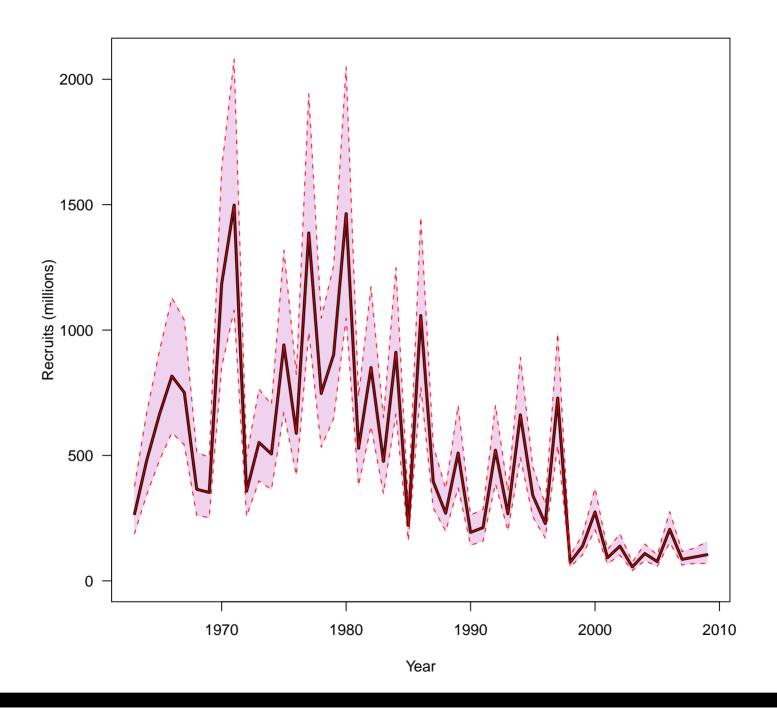






















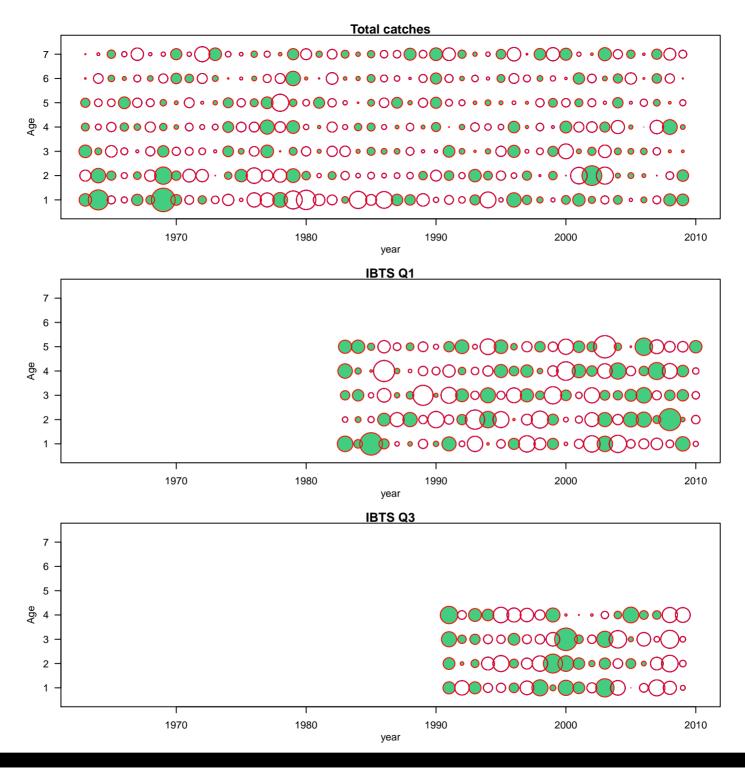




















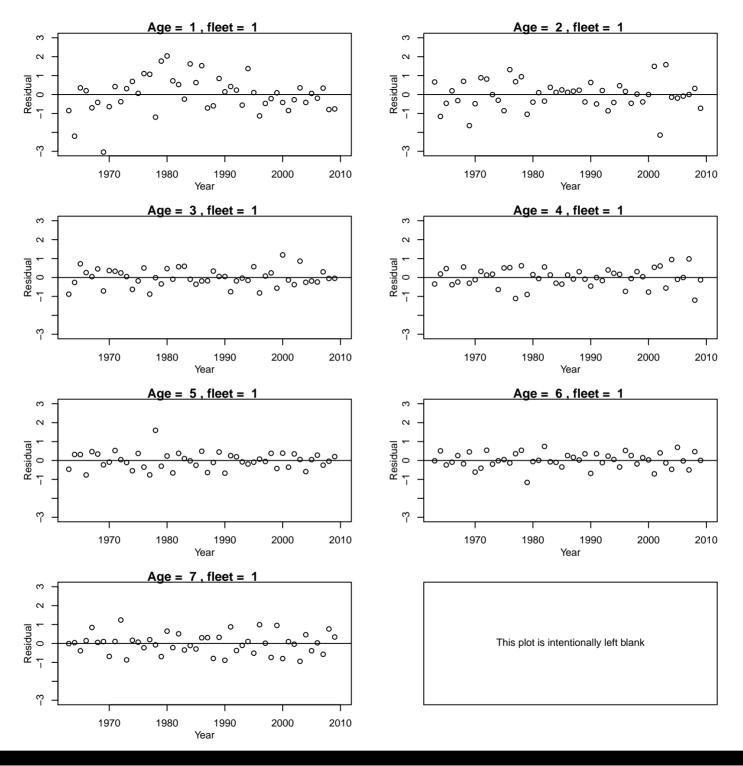




















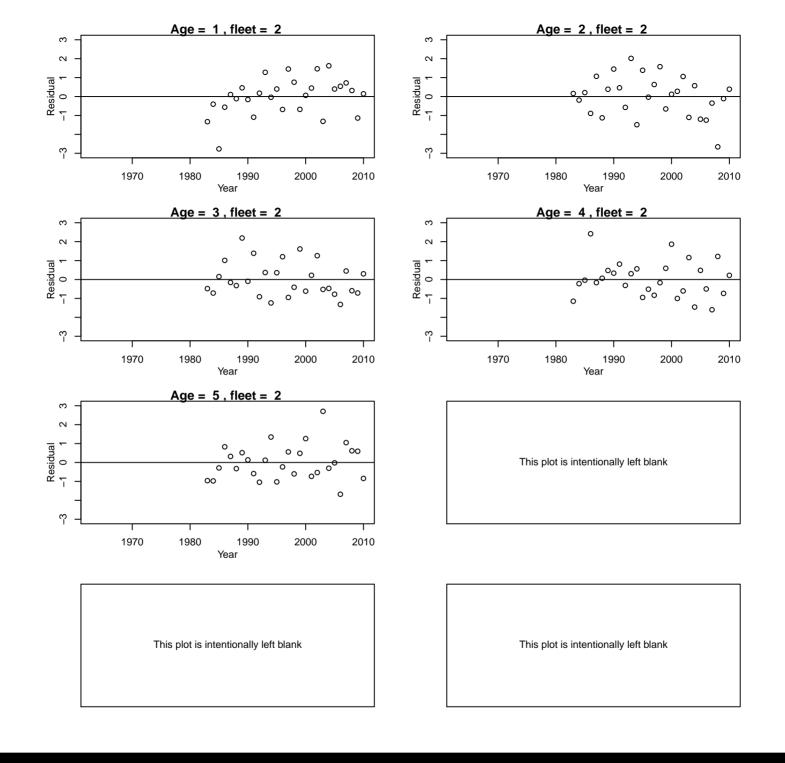
























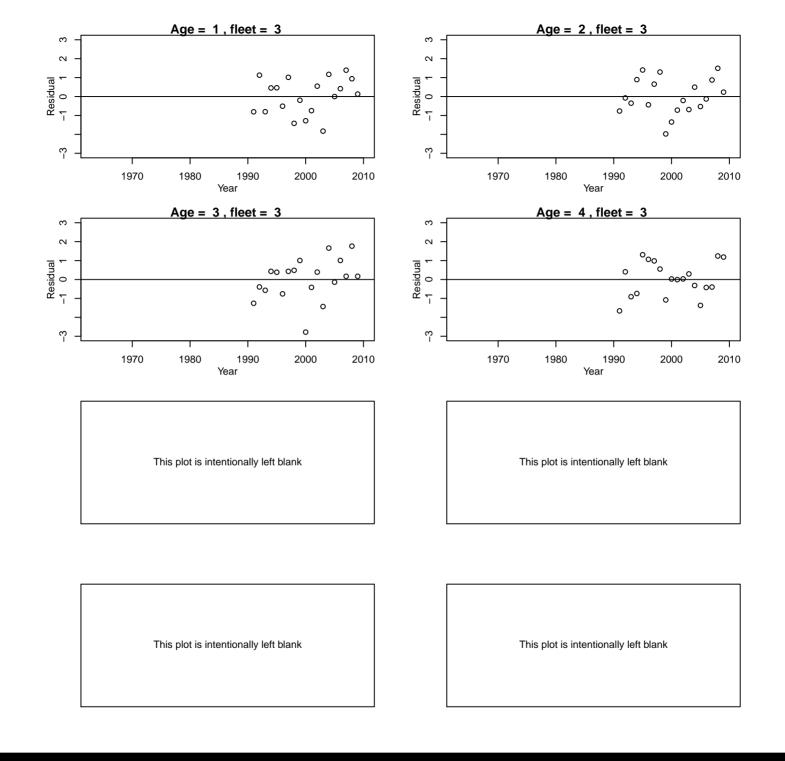






















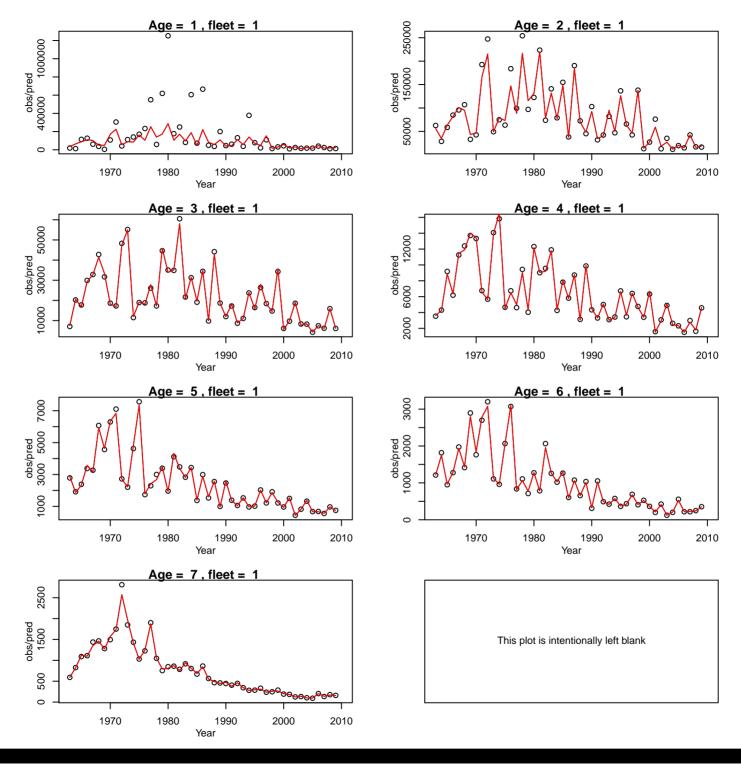






















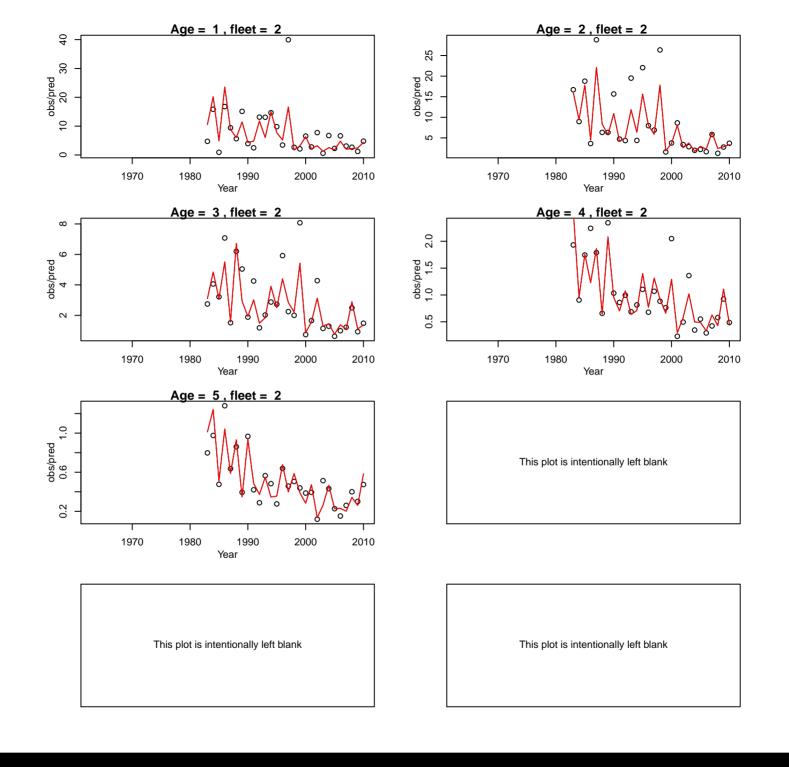
























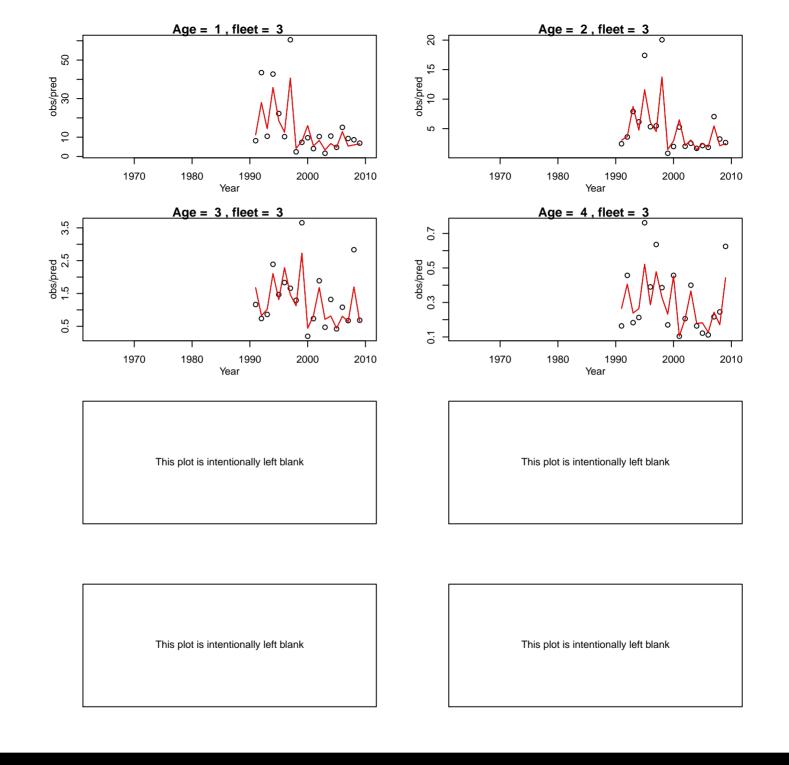








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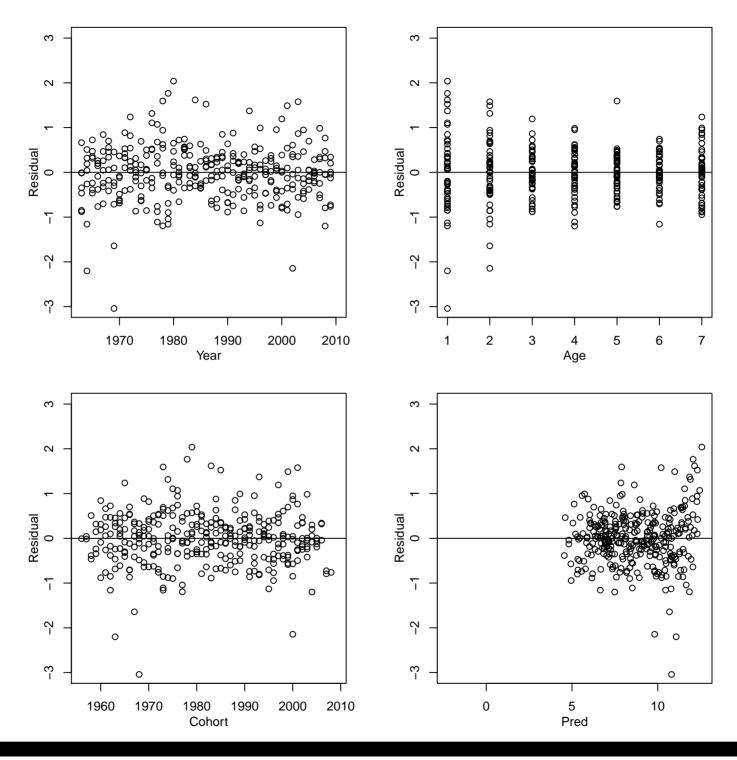




















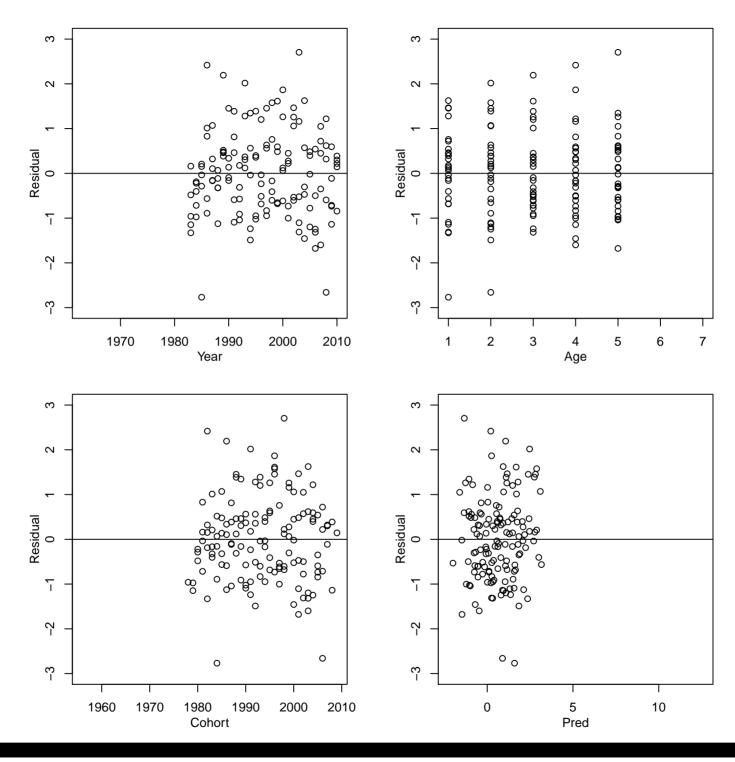




















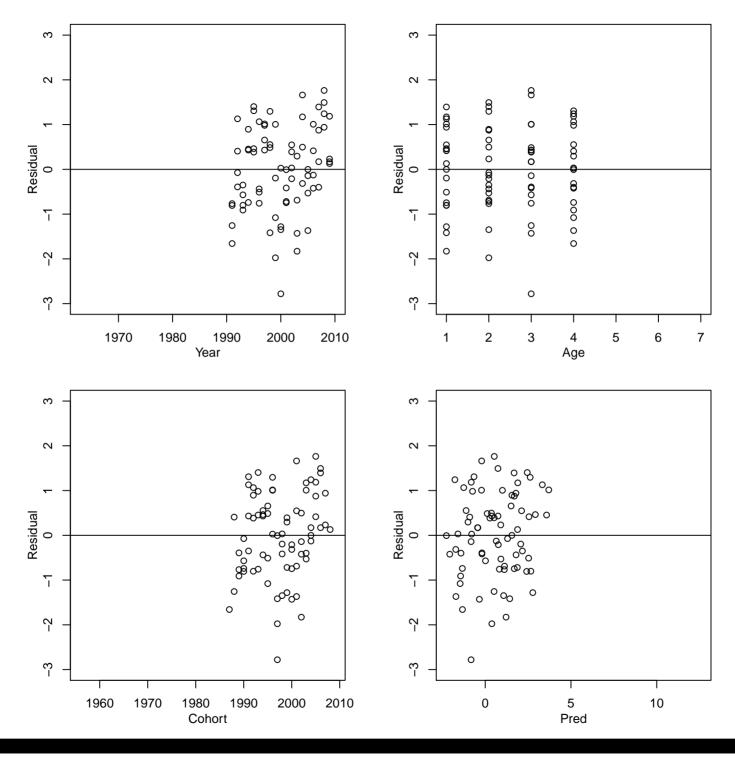




















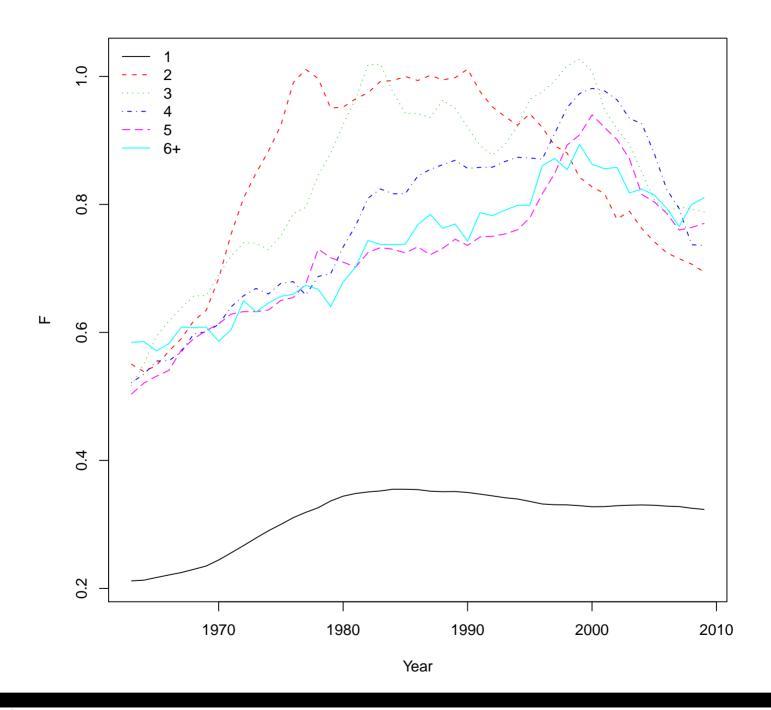






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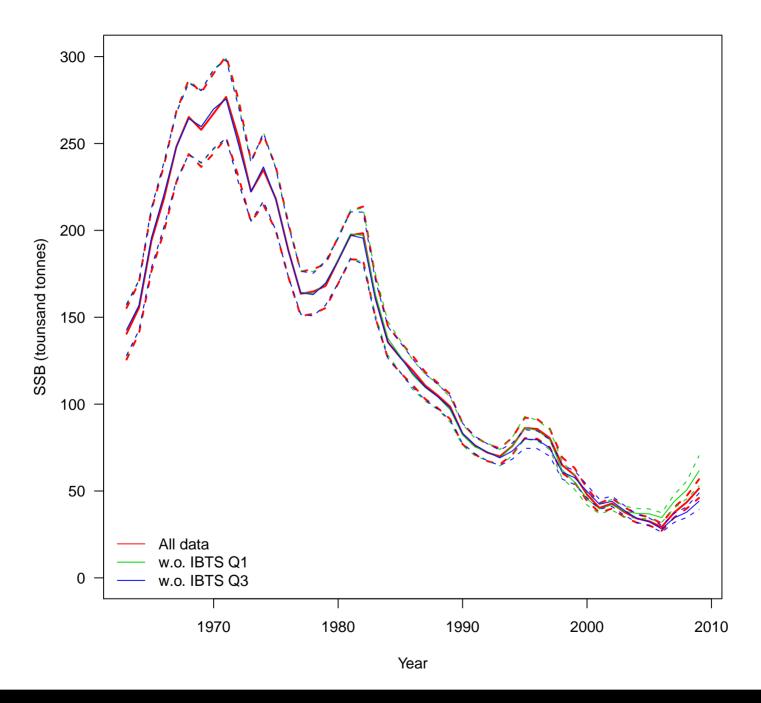






















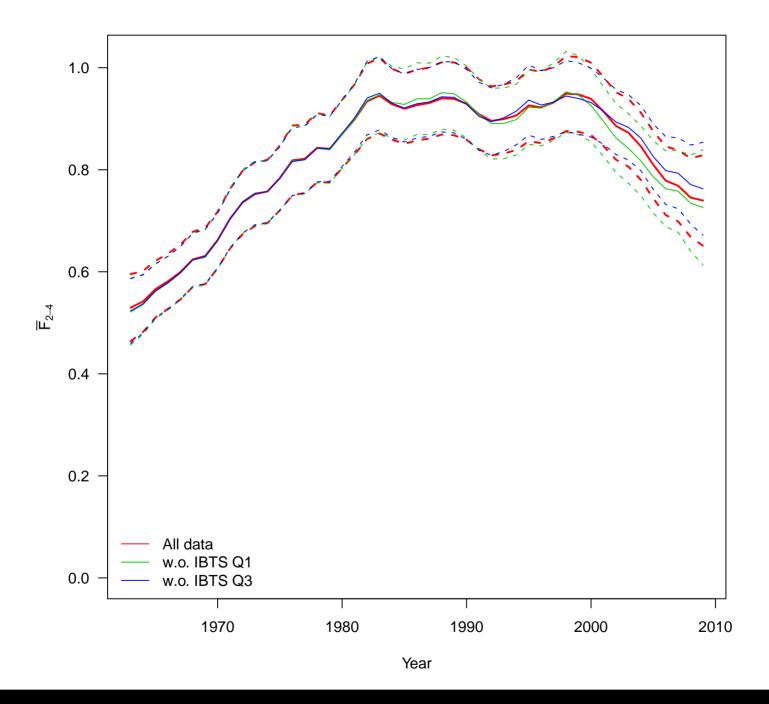






















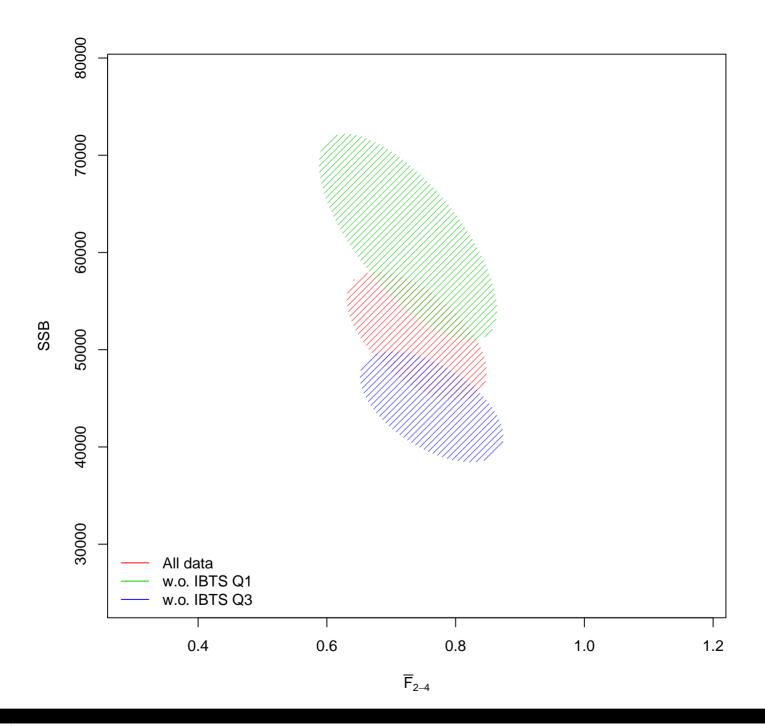
























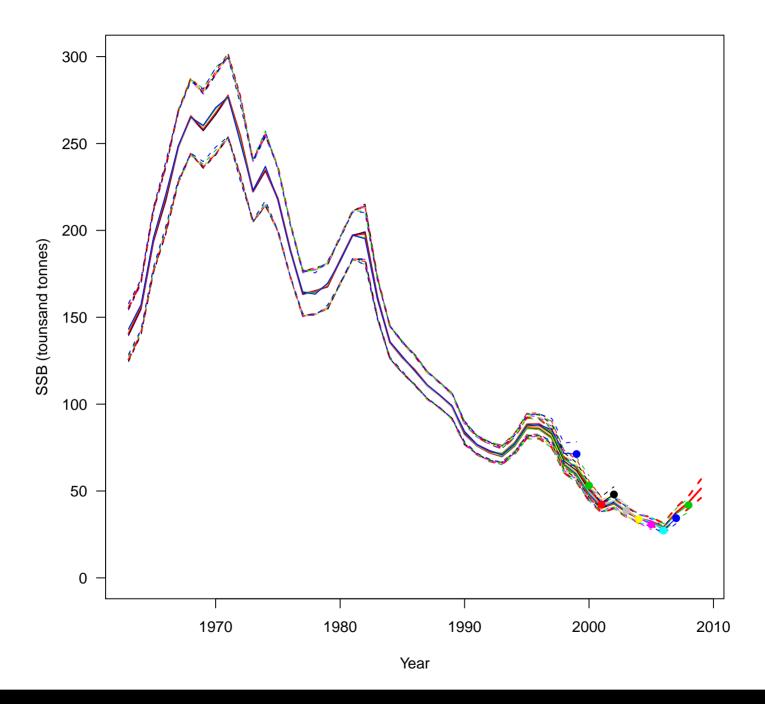








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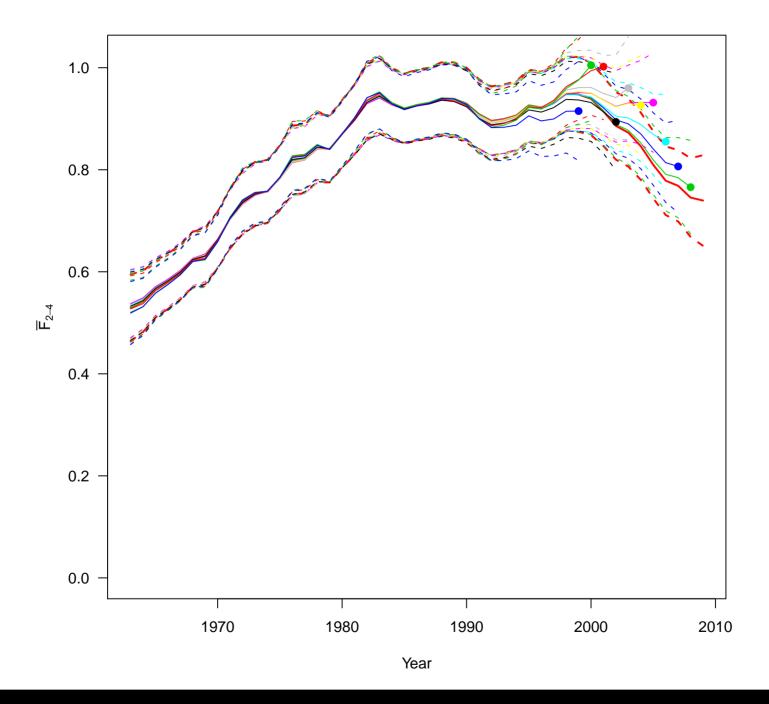






























## **Exercises**

**Exercise 1:** Unallocated mortality for North Sea Cod

- One of the more controversial issues for North Sea Cod is the estimation of the so-called unallocated mortality (could be black landings, wrong natural mortality, or something else)
- It enters the catch equation as:

$$\log(C_{a,y}S_{a,y}) = \log\left(\frac{F_{a,y}}{Z_{a,y}}(1 - e^{-Z_{a,y}})N_{a,y}\right) + \varepsilon_{a,y}$$

- A few different options can be imagined
  - Use total landings as reported

$$S_{a,y} = 1$$

- Separate scaling each year

$$S_{a,y} = \begin{cases} 1, & y < 2003 \\ \tau_y, & y \ge 2003 \end{cases}$$



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- Separate scaling each year, and in three age classes

$$S_{a,y} = \begin{cases} 1, & y < 2003 \\ \tau_y^{(1)}, & y \ge 2003 \& a = 1 \\ \tau_y^{(2)}, & y \ge 2003 \& a = 2 \\ \tau_y^{(3+)}, & y \ge 2003 \& a \ge 3 \end{cases}$$

- Discuss what these different options means in terms of the fishery
- Browse the on-line interface. Try to change something (some catches, some weights, or some options) and see what happens when you run.
- Try to run these different configurations via the on-line interface and carry out the statistical significant tests
- What option is the most appropriate?















