

The von Neumann Model

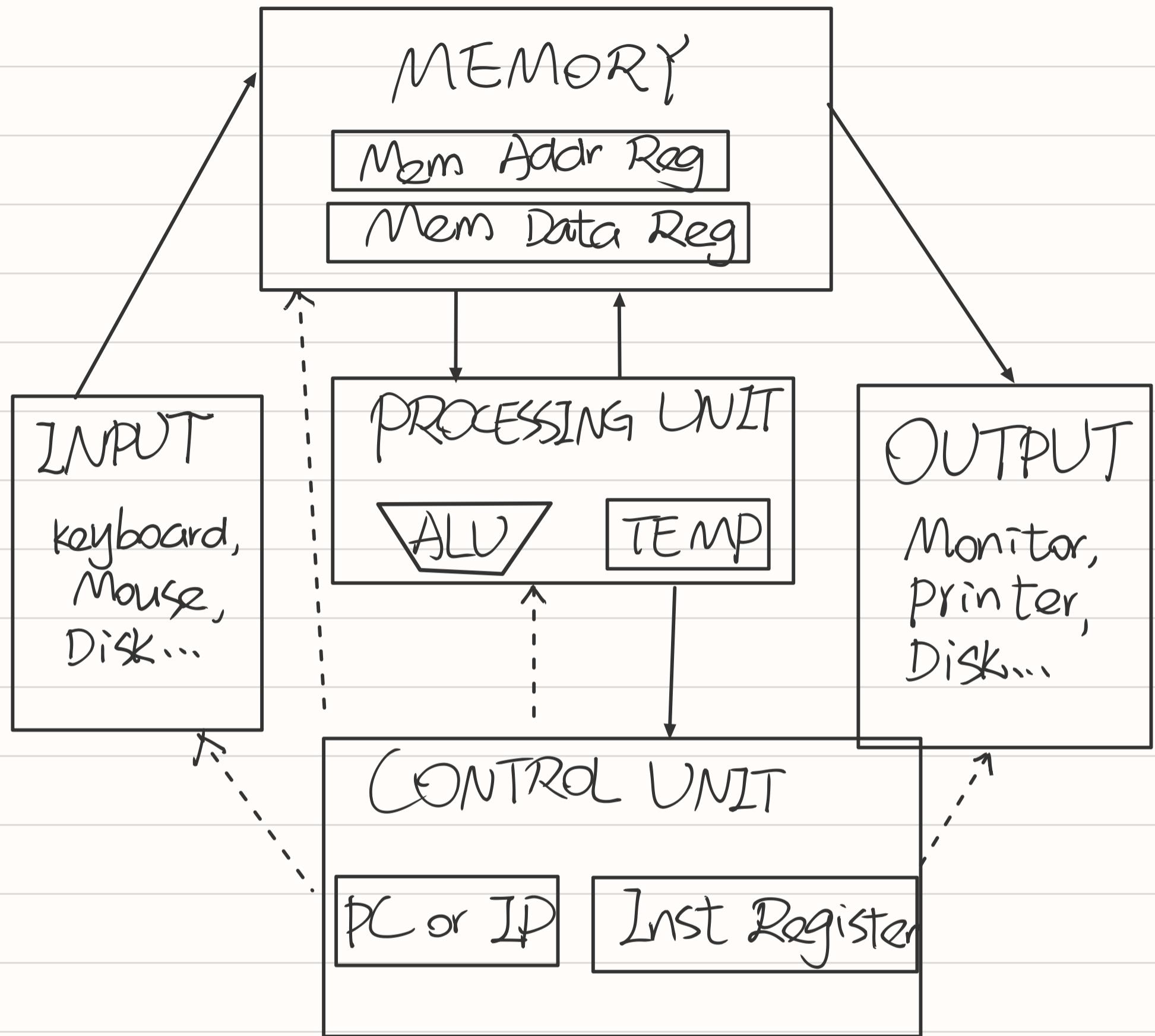
We need an execution model to process computer programs!

John von Neumann proposed a fundamental model in 1946

This model consists of 5 components:

- ① Memory (store the program and data)
- ② Processing Unit
- ③ Input
- ④ Output
- ⑤ Control Unit (control the order in which instructions are carried out)

Two examples: LC-3, MIPS



The von Neumann Model

Memory:

Memory contains bits (二进制数)

(8 bits)

- Bits are logically grouped into Bytes (字节) and words (8, 16, 32 bits)

Address space: Total number of uniquely identifiable locations in memory

In LC-3 $\rightarrow 2^{16}$, 16-bit address

In MIPS $\rightarrow 2^{32}$, 32-bit address

In x86-64 $\rightarrow 2^{48}$, 48-bit address

Word-Addressable Memory:

Each data word has a unique address

In MIPS \rightarrow 32-bit data word

In LC-3 \rightarrow 16-bit data word

Byte-Addressable Memory:

Each byte has a unique address ~~★~~

MIPS and LC-3 are actually Byte-Addressable

Big-Endian vs Little-Endian Convention

Accessing Memory: MAR vs MDR.

Two ways:

1. Reading or loading data from a memory location
2. Writing or storing data to a memory location

Two registers:

- 1 - MAR: Memory Address Register
2. MDR: Memory Data Register

To read:

Step1: Load the MAR with address we want to read
Step2: Data in corresponding location gets placed in MDR

To write:

Step1: Load the MAR with the address and the MDR with the data we want to write
Step2: Activate Write Enable signal → Value in MDR is written to address specified by MAR

Processing Unit:

- performs the actual computations.
- Consist of many functional units
- Start with a simple ALU: Arithmetic and Logic Unit

Fast temporary storage

A computer provides a small amount of storage very close to ALU to store temporary values and quickly access them later

A memory access is much slower than an addition multiplication or division.

This is usually a set of registers called **Register File**

[C-3 has 8 general purpose registers (GPRs)]

$R_0 - R_7$: 3-bit register number

Register size = Word length = 16 bits

MIPS has 32 general purpose registers

$R_0 - R_{31}$: 5-bit register number

Register size = Word Length = 32 bits

MIPS Register File Convention

Name	Register Number	Usage
\$0	0	the constant value 0
\$at	1	assembler temporary
\$v0-\$v1	2-3	function return value
\$a0-\$a3	4-7	function arguments
\$t0-\$t7	8-15	temporary variables
\$s0-\$s7	16-23	saved variables
\$t8-\$t9	24-25	temporary variables
\$k0-\$k1	26-27	OS temporaries
\$gp	28	global pointer
\$sp	29	stack pointer
\$fp	30	frame pointer
\$ra	31	function return address

Control Unit(the core)

Conduct a step-by-step process of executing
(every instruction in) a program (in sequence)

- △ It keeps track of which instruction being processed, via **Instruction Register (IR)**, which contains the instruction.
- △ It keeps track of which instruction to process next, via **Program counter (PC)** or **Instruction Pointer (IP)**, which contains the address of the (next) instruction to process.

Two Key Properties:

1. Stored Program

- Instructions stored in a linear memory array
- Memory is unified between instructions and data

The interpretation of a stored value depends on the control signals.

2. Sequential Instruction Processing

- One instruction processed (fetched, executed, completed)
- PC (or IP) identifies the current instruction ^{at a time}
- PC is advanced sequentially except for control transfer instructions.

For word-addressable memory, the processor increments the PC by 1 (C-3)

For Byte-addressable memory, the processor increments the PC by the instruction length in Bytes (4 In MIPS)

The Instruction:

An Instruction is the most basic unit of computer processing.

Instructions are words in the language of a computer.

Instruction set Architecture (ISA) is the vocabulary

The language of computer can be written as

Machine language: Computer-readable representation

Assembly language: Human-readable representation

IS made up of 2 parts:

Opcode: 操作码 specifies what the Instr does

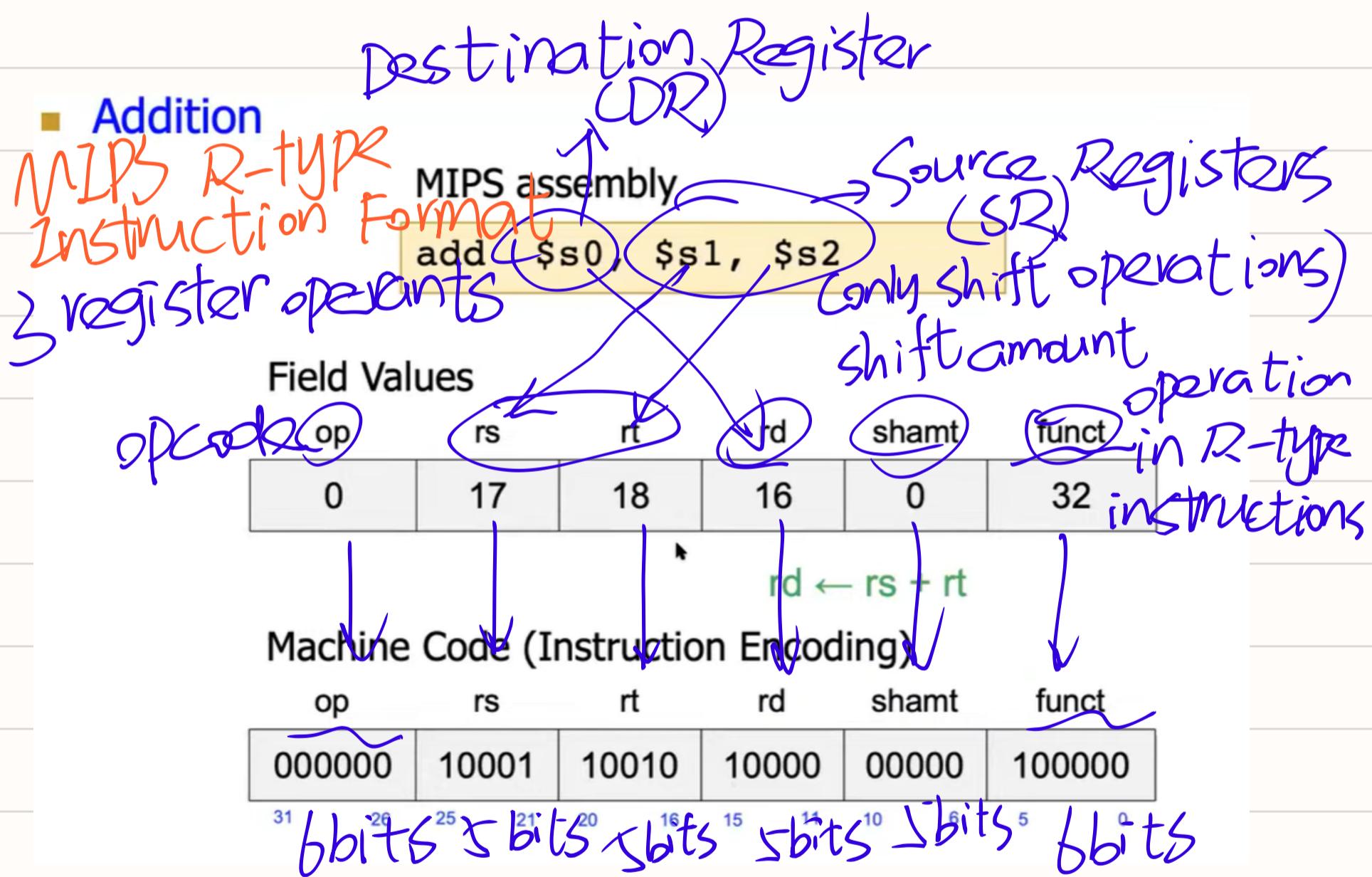
Operands: 操作数 specify who the Instr is to do it

Both are specified in instruction format
(or instr encoding)

Instruction TYPES:

1. Operate instructions: Execute operations in
2. Data movement instructions: read from or write to memory.
3. Control instructions: change the sequence of execution.

From Assembly to Machine Code in MIPS



High-level code: $a = A[2]$

MIPS Load Data

MIPS assembly

lw \$s3, 8(\$s0)

Field Values

op	rs	rt	imm
35	16	19	8

31 26 25 21 20 16 15 0

base + offset

\$s3 ← memory[\$s0+8]

I-Type

