

2 Jetson TX2s, Raspberry Pi, UM7  
IMU and Support Electronics

GPS

Status Lights

Stereo Camera on  
Bow and Stern

Hardare E-stop  
on Port and  
Sarboard

Planar LiDAR  
on Bow and  
Stern

4 Blue Robotics T-200  
Thrusters in X Configuration

Finned Heat Sink

