Methods of Mathematical Physics

—Lecture 2 Functions of a Complex Variable—

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Introduction

The concepts in ordinary calculus in the setting of \mathbb{R} , like convergence of sequences, or continuity and differentiability of functions, all rely on the notion of closeness of points in \mathbb{R} .

In order to do calculus with complex numbers, we need a notion of distance $d(z_1, z_2)$ between for pairs of complex numbers (z_1, z_2) , and the first order of business is to explain what this notion is.

Metric on $\mathbb C$

A metric space is a pair (X, d), where X is a set and $d: X \times X \to \mathbb{R}$ is a function called a distance function or metric that satisfies the following conditions: for $x, y, z \in X$,

- 2 d(x, y) = d(y, x) (symmetry);

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- 2 d(x, y) = d(y, x) (symmetry);
- $d(x, z) \le d(x, y) + d(y, z)$ (triangle inequality).

Example

Let
$$X=\mathbb{C}, z_1=(x_1,y_1), z_2=(x_2,y_2)\in X$$
 and define $d(z_1,z_2)=|z_1-z_2|=\sqrt{(x_1-x_2)^2+(y_1-y_2)^2},$ or $d(z_1,z_2)=|x_1-x_2|+|y_1-y_2|,$ or $d(z_1,z_2)=\max\{|x_1-x_2|,|y_1-y_2|\}.$ Then (\mathbb{C},d) is a metric space.



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Open discs, open sets, closed sets, compact sets, connected sets

- An open ball/disc $D(z_0, r)$ with center z_0 and radius r > 0 is defined by $D(z_0, r) := \{z \in \mathbb{C} : |z z_0| < r\}$.
- A subset U of $\mathbb C$ is called open if for every $z \in U$, there exists an $r_z > 0$ such that $D(z, r_z) \subset U$. (z is an interior point)
- A set S is said to be closed when every limit point of S belongs to S. (A set $F \subset X$ is said to be closed if its complement, X F, is open.)
- A subset S of $\mathbb C$ is called bounded if there exists a M>0 such that for all $z\in S, |z|\leq M$. Thus S is contained in a big enough disc in the complex plane.
- A subset $K \subset \mathbb{C}$ is called compact if it is both closed and bounded.
- An open set is said to be connected if it cannot be represented as the union of two nonempty disjoint open sets. A nonempty open set in the complex plane is connected if and only if any two of its points can be joined by a polygonal arc¹ lying entirely in the set.

¹By a polygonal arc we mean a continuous chain of a finite number of line segments.

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Open and Closed Domain (or Region), Curves

- A nonempty open connected subset of the complex plane is called an open domain or an open region or, simply, a region.
- A curve or a continuous arc Γ in the complex plane is the set of points z in the complex plane determined by the equation

$$z = z(t) = x(t) + iy(t)$$

where x(t) and y(t) are real continuous functions of a real variable t defined on a real interval $\alpha \leq t \leq \beta$ where $\alpha \leq \beta$. We call $z(\alpha)$ and $z(\beta)$ the end points of Γ , $z(\alpha)$ being the initial point and $z(\beta)$ the terminal point of Γ . If $z(\alpha) = z(\beta)$, Γ is called a closed curve. If the equation $z_0 = x(t) + iy(t)$ is satisfied by more than one value of t in the given range $I: \alpha \leq t \leq \beta$, then z_0 is said to be a multiple point. In particular, the multiple point is called a double point when the above equation is satisfied by two values of t in the given range I.

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Jordan Arc and Simple Closed Jordan Curve

• A curve Γ is called a Jordan arc or a simple curve if it has no multiple points, i.e., if there exists some parametric representation

$$z = z(t) = x(t) + iy(t), \quad \alpha \le t \le \beta,$$

such that, if $t_1 \neq t_2$, then $z(t_1) \neq z(t_2)$, i.e., z(t) is one-to-one. The simplest example of a Jordan arc is a straight line segment.

• If, in a Jordan arc, the initial and terminal points coincide, that is, if there is a double point corresponding to the end points (α and β) of the interval $I: \alpha \leq t \leq \beta$ and there is no other multiple point on it, then it is called a simple closed Jordan curve or simply a closed Jordan curve.

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Convergence and continuity

A sequence $(z_n)_{n\in\mathbb{N}}$ is said to be convergent with limit L if for every $\epsilon>0$, there exists an index $N\subset\mathbb{N}$ such that for every n>N, there holds that $|z_n-L|<\epsilon$. It follows from the triangle inequality that for a convergent sequence the limit is unique, and we write

$$\lim_{n\to\infty} z_n = L.$$

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$$\lim_{n\to\infty} z_n = L.$$

Let S be a subset of $\mathbb{C}, z_0 \in S$ and $f: S \to \mathbb{C}$. Then f is said to be continuous at z_0 if for every $\epsilon > 0$, there exists a $\delta > 0$ such that whenever $z \in S$ satisfies $|z - z_0| < \delta$, there holds that $|f(z) - f(z_0)| < \epsilon$.

f is said to be continuous if for every $z \in S$, f is continuous at z.

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Definitions

Let D be an arbitrary non-empty point set of the complex plane. If z is allowed to denote any point of D, z is called a complex variable and D is called the domain of definition of z or simply the domain.

A complex variable w is said to be a function of the complex variable z if, to every value of z in a certain domain D, there corresponds **one or more values** of w. Thus, if w is a function of z, it is written as w = f(z). We also say that f defines a mapping of D into the w-plane. The totality of values f(z) corresponding to all z in D constitutes another set R of complex numbers, known as the range of the function f.

Since z = x + iy, f(z) will be of the form u + iv, where u and v are functions of two real variables x and y. We may then write

$$w = f(z) = u(x, y) + iv(x, y).$$

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Single-valued and multiple-valued Functions

A function f(z) of the complex variable z with domain of definition D and range R is said to be single-valued or one-valued if w takes only one value in R for each value of z in D.

If there correspond two or more values of f(z) in R for some or all values of z in D, then f(z) is called a multiple-valued or many-valued function of z.

Limits of Functions

Let f(z) be a function of z defined in some neighborhood of a point z_0 . The function f(z) is said to have the limit ℓ as z tends to z_0 if, to each positive arbitrary number ϵ , there exists a positive number δ depending upon ϵ with the property that

$$|f(z) - \ell| < \epsilon$$

for all z such that $0<|z-z_0|<\delta$ and $z\neq z_0$. In other words, there exists a deleted neighborhood of the point $z=z_0$ in which $|f(z)-\ell|$ can be made as small as we please. Symbolically, we write $\lim_{z\to z_0}f(z)=\ell$.

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Continuity

Let G be an open set in $\mathbb C$ and let $f\colon G\to\mathbb C$. Then f is said to be continuous at a point z_0 in G if, given any positive number ϵ , we can find a member $\delta>0$ depending in general on ϵ and z_0 such that

$$|f(z)-f(z_0)|<\epsilon$$

for all $z \in G$ in the neighborhood $|z - z_0| < \delta$ of z_0 .

It follows from the above definition and the definition of limit that f is continuous at $z=z_0$ if

$$\lim_{z\to z_0}f(z)=f(z_0).$$

If a function is continuous at every point of G, it is said to be continuous in G.

Continuity in terms of Real & Imaginary Parts of f(z)

If f(z) = u(z, y) + iv(x, y), then it can be easily shown that f is a continuous function of z if and only if u(x, y) and v(x, y) are separately continuous functions of x and y.

Let f and g be continuous functions from X into $\mathbb C$ and let $a,b\in\mathbb C$. Then af+bg and fg are both continuous. Also, f/g is continuous provided $g(x)\neq 0$ for every x in X.

A continuous function of a continuous function is a continuous function; that is, if $f: X \to Y$ and $g: Y \to Z$ are continuous functions, then $g \circ f$ where $(g \circ f)(x) = g(f(x))$ is a continuous function from X into Z.

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Complex differentiability

In this section we will learn three main things:

- The definition of complex differentiability.
- The Cauchy-Riemann equations.
- **3** The geometric meaning of the complex derivative $f'(z_0)$.

The central result in this section is the necessity and (under mild conditions) sufficiency of the Cauchy-Riemann equations for the complex differentiability of a function in an open set.

If G is an open set in $\mathbb C$ and $f\colon G\to\mathbb C$ is a function, then f is said to be differentiable at a point z_0 in G if, for any positive number ϵ , we can find a positive number δ depending on ϵ and possibly on z_0 such that

$$\left|\frac{f(z)-f(z_0)}{z-z_0}-f'(z_0)\right|<\epsilon$$

for all $z \in G$ in the neighborhood of z_0 defined by $|z - z_0| < \delta$.

If f is differentiable at each point of G, then we say that f is differentiable on G.

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An example

Example

If $f(z) = \frac{x^3y(y-ix)}{x^6+y^2}$ $(z \neq 0)$, f(0) = 0, prove that $\frac{f(z)-f(0)}{z-0} \to 0$ as $z \to 0$ along any radius vector but not as $z \to 0$ in any manner.

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Proof.

Let $z \to 0$ along y = mx (radius vector). Then we have

$$\lim_{z \to 0} \frac{f(z) - f(0)}{z - 0} = \lim_{z \to 0} \frac{x^3 y(y - ix)}{(x^6 + y^2)(x + iy)} = \lim_{x \to 0} \frac{x^3 mx(mx - ix)}{(x^6 + m^2 x^2)(x + imx)}$$
$$= \lim_{x \to 0} \frac{m(m - i) \cdot x^2}{(m^2 + x^4)(1 + im)} = 0.$$

Now, let $z \to 0$ along the path $y = x^3$. Then, for $x \neq 0$

$$\lim_{z \to 0} \frac{f(z) - f(0)}{z} = \lim_{x \to 0} \frac{x^6 (x^3 - ix)}{(x^6 + x^6)(x + ix^3)} = \lim_{x \to 0} \frac{(x^2 - i)}{2(1 + ix^2)} = -\frac{i}{2}.$$

Theorem

If $f: G \to C$ is differentiable at a point z_0 in G, then f is continuous at z_0 .

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Proof.

Consider the following identity:

$$\lim_{z \to z_0} |f(z) - f(z_0)| = \left[\lim_{z \to z_0} \frac{|f(z) - f(z_0)|}{|z - z_0|} \right] \cdot \left[\lim_{z \to z_0} |z - z_0| \right]$$

$$= f'(z_0) \cdot 0$$

$$= 0$$

that is, $\lim_{z\to z_0} f(z) = f(z_0)$. Thus it follows that f(z) is continuous at z_0 . This completes the proof.

The converse of the above theorem is not necessarily true. For example, take the function $|z|^2$ which is continuous in all finite regions of the z-plane. It has, however, a derivative only at the origin, since, when $z \neq z_0$ and $z_0 \neq 0$, we have, for $f(z) = |z|^2$,

$$\begin{split} \frac{f(z) - f(z_0)}{z - z_0} &= \frac{|z|^2 - |z_0|^2}{z - z_0} = \frac{z\bar{z} - z_0\bar{z}_0}{z - z_0} \\ &= \frac{z\bar{z} - z_0\bar{z} + z_0\bar{z} - z_0\bar{z}_0}{z - z_0} = \bar{z} + z_0\frac{\bar{z} - \bar{z}_0}{z - z_0} \\ &= \bar{z} + z_0\frac{\rho(\cos\theta - i\sin\theta)}{\rho(\cos\theta + i\sin\theta)} = \bar{z} + z_0(\cos2\theta - i\sin2\theta), \end{split}$$

where $\rho=|z-z_0|$ and $\theta=\arg\left(z-z_0\right)$. Clearly, $\lim_{z\to z_0}\frac{f(z)-f(z_0)}{z-z_0}$ does not exist since the limit depends upon $\arg\left(z-z_0\right)$. However, when $z_0=0$, the expression reduces to \bar{z} which tends to 0 with z tends to 0.

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Definition

Definition

- The function f is analytic at z_0 if f(z) is differentiable in some neighborhood of z_0 (open region including z_0);
- The function f is analytic in a region if it is analytic at all points in that region;
- The function f is holomorphic if it is analytic. The terms are synonyms.
- An analytic function is entire if its region of analyticity includes all points in C, the finite complex plane, excluding infinity.

If we describe a function as analytic, without specifying any point or region, that means there is some region within which it is analytic.

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Rules of Differentiation

Theorem

If f and g are analytic on G, where $g(z) \neq 0$, then

- $(f \pm g)'(z) = f'(z) \pm g'(z).$
- ② (cf)'(z) = cf'(z), where c is a complex constant.
- $(f \cdot g)'(z) = f(z) \cdot g'(z) + g(z) \cdot f'(z).$

Rules of Differentiation

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Theorem (Chain Rule)

If f and g are analytic on G and Ω , respectively, and suppose f(G) $\subset \Omega$, then $g \circ f$ is analytic on G and for all z in G,

$$(g \circ f)'(z) = g'(f(z))f'(z).$$

The chain rule shows that an analytic function of an analytic function is analytic.

Examples

Example

Show that the function $f(z) = z^n$ where n is a positive integer is an analytic function. Furthermore, polynomials and rational Functions are analytic functions.

Cauchy-Riemann Equations

Theorem

A necessary condition for a function f(z) = u(x,y) + iv(x,y) to be analytic at any point z = x + iy of the domain D of f is that the four partial derivatives u_x , u_y , u_y and v_x should exist and satisfy the equation

$$u_{\mathsf{X}} = \mathsf{v}_{\mathsf{y}}, \quad u_{\mathsf{y}} = -\mathsf{v}_{\mathsf{X}}. \tag{1}$$

The equations given in (1) are known as the Cauchy–Riemann equations.

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$$u_{x}=v_{y}, \quad u_{y}=-v_{x}. \tag{1}$$

The equations given in (1) are known as the Cauchy–Riemann equations.

Example

Show that the function f(z) = u + iv, where

$$f(z) = \frac{x^3(1+i)-y^3(1-i)}{x^2+v^2} (z \neq 0), \quad f(0) = 0,$$

is continuous and the Cauchy-Riemann equations are satisfied at the origin, but f'(0) does not exist.

Sufficient conditions

Theorem

The one-valued function f(z) = u(x, y) + iv(x, y) is analytic in a domain D if the four partial derivatives u_x , v_x , u_y and v_y exist, are continuous and satisfy the Cauchy-Riemann equations at each point D.

$$f'(z) = u_x + iv_x = v_v - iu_v.$$

Conjugate Functions

Definition

If a function f(z) = f(x + iy) = u(x, y) + iv(x, y) is analytic in a domain D, then the functions u and v of two variables x and y are called conjugate functions.

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Harmonic Functions

Definition

A real-valued function u(x, y) is said to be harmonic in a domain D if, for all $x, y \in D$, all second-order partial derivatives exist and are continuous and satisfies Laplace's equation, that is,

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0.$$

Theorem

If the harmonic functions u and v satisfy the Cauchy-Riemann equations, then u+iv is an analytic function.

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Examples

Example

Show that the functions $u(x, y) = e^x \cos y$ is harmonic. Determine its harmonic conjugate v(x, y) and the analytic function f(z) = u + iv.

Example

If $u=x^2-y^2$ and $v=-\frac{y}{x^2+y^2}$, then show that both u and v satisfy Laplace's equation, but u+iv is not an analytic function of z.

Example

Let f be analytic on an open set U and let |f| = constant. Show that f = constant.

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Polar Form of the Cauchy-Riemann Equations

Theorem

If f(z) = u + iv is an analytic function and $z = re^{i\theta}$, where u, v, r and θ are all real, show that the Cauchy-Riemann equations are as follows:

$$\frac{\partial u}{\partial r} = \frac{1}{r} \frac{\partial v}{\partial \theta}, \quad \frac{\partial v}{\partial r} = -\frac{1}{r} \frac{\partial u}{\partial \theta}.$$

Method of Constructing Analytic Functions

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Power Series

Definition

A power series is an infinite series of the type

$$\sum_{n=0}^{\infty} a_n z^n \text{ or } \sum_{n=0}^{\infty} a_n (z - z_0)^n$$

where variable z and the constants a_0, z_0 are, in general, complex numbers and a_n in independent of z.

Power series

Theorem

The power series $\sum a_n z^n$ either

- 1 converges for all values of z;
- 2 converges only for z = 0;
- for z in some region in the complex plane.

Theorem (Abel's Theorem)

If the power series $\sum_{n=0}^{\infty} a_n z^n$ converges for a particular value z_0 of z, then it converges absolutely for all values of z for which $|z| < |z_0|$.

Theorem (Cauchy-Hadamard's Theorem)

For all power series $\sum_{n=0}^{\infty} a_n z^n$, there exists a number $R, 0 \le R \le \infty$, called the radius of convergence with the following properties:

- 1 The series converges absolutely for all |z| < R.
- 2 If $0 \le \rho < R$, then the series converges uniformly for $|z| \le \rho$.
- 3 The series diverges if |z| > R.

Power Series

Theorem

The power series $\sum_{n=0}^{\infty} na_n z^{n-1}$, obtained by differentiating the power series

 $\sum_{n=0}^{\infty} a_n z^n$, has the same radius of convergence as the original series.

Definition

If $f(z) = \sum_{n=0}^{\infty} a_n z^n$, then f(z) is called the sum function of the power series

$$\sum_{n=0}^{\infty} a_n z^n.$$

Theorem

The function f(z) of the series $\sum_{n=0}^{\infty} a_n z^n$ represents an analytic function inside its circle of convergence.

Exponential Functions

Definition

The exponential function f(z) of a complex variable z is defined as the solution of the differential equation: f'(z) = f(z), with initial value f(0) = 1.

Let us solve by setting

$$f(z) = a_0 + a_1 z + \cdots + a_n z^n + \cdots.$$

Then we have

$$f'(z) = a_1 + 2a_2z + \cdots + na_nz^{n-1} + \cdots$$

Hence, if f'(z) = f(z) satisfied, then we must have

$$a_0=a_1,\quad a_1=2a_2,\quad \cdots.$$

In general, $a_{n-1}=na_n$. Since f(0)=1, we have $a_0=1$. If follows from the above relation that

$$a_1 = 1$$
, $a_2 = \frac{1}{2}$, $a_3 = \frac{a_2}{3} = \frac{1}{2 \cdot 3} = \frac{1}{3!}$, $a_n = \frac{1}{n!}$.

We denote the solution by $\exp z$ or e^z . Thus we have

$$\exp z = 1 + \sum_{n=1}^{\infty} \frac{z^n}{n!}.$$

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Addition Theorems for Exponential Functions

Theorem

For all z_1 and z_2 ,

$$\exp(z_1+z_2)=\exp z_1\exp z_2.$$

Proof.

We have

$$\exp z_1 = 1 + \sum_{n=1}^{\infty} \frac{z_1^n}{n!}, \quad \exp z_2 = 1 + \sum_{n=1}^{\infty} \frac{z_2^n}{n!}$$

Since the above two series are absolutely convergent, it follows from Cauchy's Theorem on multiplication of absolutely convergent series that

$$\begin{aligned} \exp z_1 \cdot \exp z_2 &= \left(1 + \sum_{n=1}^{\infty} \frac{z_1^n}{n!}\right) \cdot \left(1 + \sum_{n=1}^{\infty} \frac{z_2^n}{n!}\right) \\ &= 1 + \frac{z_1 + z_2}{1!} + \frac{z_1^2 + 2z_1z_2 + z_2^2}{2!} + \cdots \\ &= 1 + \frac{(z_1 + z_2)}{1!} + \frac{(z_1 + z_2)^2}{2!} + \cdots \\ &= \exp(z_1 + z_2). \end{aligned}$$

Addition Theorems for Exponential Functions

By induction, we have

$$\exp z_1 \cdot \exp z_2 \cdots \exp z_n = \exp (z_1 + z_2 + \cdots + z_n).$$

In particular, we have

$$\exp z \cdot \exp(-z) = \exp(0) = 1$$

An interesting consequence of this theorem is that $\exp z$ never vanishes. For, if $\exp z_1 = 0$, the identity

$$\exp z_1 \cdot \exp \left(-z_1\right) = 1$$

would yield the conclusion that $\exp(-z_1)$ is not finite. But this is impossible on account of the fact that $\exp z$ is an analytic function in every bounded domain of the z-plane.

Trigonometrical Functions

The functions $\sin z$ and $\cos z$ for complex z are defined as in the case of a real variable by means of the formulae

$$\sin z = \frac{\exp(iz) - \exp(-iz)}{2i},$$

$$\cos z = \frac{\exp(iz) + \exp(-iz)}{2}.$$
(2)

Using the power series for exponential functions on the right-hand side of (2), we can easily see that

$$\sin z = z - \frac{z^3}{3!} + \frac{z^5}{5!} - \dots + \frac{(-1)^n \cdot z^{(2n+1)}}{(2n+1)!} + \dots,$$

$$\cos z = 1 - \frac{z^2}{2!} + \frac{z^4}{4!} - \dots + \frac{(-1)^n \cdot z^{2n}}{(2n)!} + \dots.$$
(3)

Since each of these power series has an infinite radius of convergence, it follows that $\sin z$ and $\cos z$ are analytic in every bounded domain of the z-plane.

Trigonometrical Functions

The remaining trigonometrical functions are defined, in strict analogy with the case of a real variable, by

$$\tan z = \frac{\sin z}{\cos z}, \quad \cot z = \frac{\cos z}{\sin z},$$
$$\sec z = \frac{1}{\cos z}, \quad \csc z = \frac{1}{\sin z}.$$

The term-by-term differentiation of the series (3) show that

$$\frac{d}{dz}\sin z = \cos z, \quad \frac{d}{dz}\cos z = -\sin z,$$

$$\sin(-z) = -\sin z, \quad \cos(-z) = \cos z,$$

$$\sin 0 = 0, \quad \cos 0 = 1.$$

These results are in strict parallelism with what we had in the calculus of functions of real variable.

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Euler's Equation

From (2), we have

$$\exp(iz) = \cos z + i\sin z$$
,

which is known as Euler's equation. Also, we have

$$\exp(z) = \exp(x + iy)$$

$$= \exp x \cdot \exp(iy)$$

$$= \exp x \cdot (\cos y + i\sin y).$$
(4)

Thus $\exp x$ is the modulus and y the argument of $\exp(x+iy)$.

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Addition Theorems for sin z and cos z

Theorem

For all z_1 and z_2 ,

$$\cos(z_1+z_2)=\cos z_1\cos z_2-\sin z_1\sin z_2,$$

and

$$\sin(z_1+z_2)=\sin z_1\cos z_2+\cos z_1\sin z_2.$$

Proof.

We have

$$\exp\{i(z_1+z_2)\} = \exp(iz_1)\exp(iz_2).$$
 (5)

Using Euler's theorem, it follows from (5) that

$$\cos(z_1 + z_2) + i\sin(z_1 + z_2) = (\cos z_1 + i\sin z_1)(\cos z_2 + i\sin z_2)$$

$$= (\cos z_1 \cos z_2 - \sin z_1 \sin z_2) + i(\sin z_1 \cos z_2 + \cos z_1 \sin z_2).$$
(6)

Replacing z_1 and z_2 with $-z_1$ and $-z_2$, respectively, it follows from (6) that

$$\cos(z_1 + z_2) - i\sin(z_1 + z_2) = (\cos z_1 - i\sin z_1)(\cos z_2 - i\sin z_2)$$

$$= (\cos z_1 \cos z_2 - \sin z_1 \sin z_2) - i(\sin z_1 \cos z_2 + \cos z_1 \sin z_2).$$
(7)

Addition Theorems for sin z and cos z

Adding (6) and (7), we have

$$\cos(z_1 + z_2) = \cos z_1 \cos z_2 - \sin z_1 \sin z_2$$

and, subtracting (7) from (6), we have

$$\sin(z_1+z_2)=\sin z_1\cos z_2+\cos z_1\sin z_2.$$

By virtue of formulae (5) and (6) and Euler's equation, we obtain the identity

$$\sin^2 z + \cos^2 z = 1.$$

We can also show that all the elementary identities of trigonometry still hold for the trigonometrical functions a complex variable.

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Hyperbolic Functions sinh z and cosh z

The hyperbolic functions of a complex variable are defined in the same way as for real variables. The fundamental formulae are

$$\sinh z = \frac{1}{2} \left(e^z - e^{-z} \right), \tag{8}$$

$$cosh z = \frac{1}{2} \left(e^z + e^{-z} \right) \tag{9}$$

Using power series for e^x and e^{-x} on the R.H.S. of (8) and (9), we can easily see that

$$\sinh z = \sum_{n=0}^{\infty} \frac{z^{2n+1}}{(2n+1)!},$$

$$\cosh z = \sum_{n=0}^{\infty} \frac{z^{2n}}{(2n)!}.$$

Evidently, $\sinh z$ and $\cosh z$ are regular in every bounded domain of the z plane. Relation between Hyperbolic and Trigonometric Functions It can be easily verified that

$$\sin iz = i \sinh z$$
, $\cos iz = \cosh z$,
 $\sinh iz = i \sin z$, $\cosh iz = \cos z$.

Logarithmic Functions (Inverse of Exponential Functions)

The logarithm of a complex variable w denoted by $\log w$ is defined as the solution of the equation

$$\exp z = w, \tag{10}$$

where

$$z = \log w. \tag{11}$$

Observe that the number 0 has no logarithm since $\exp z$ is never zero. If z = x + iy, then, for $w \neq 0$, (10) can be written

$$\exp(x+iy)=w$$

or

$$\exp x \cdot \exp(iy) = w$$
.

Since x and y are real, we have

$$\exp x = |w| \tag{12}$$

and

$$\exp iy = \frac{w}{|w|}. (13)$$

Evidently, the equation (12) has a unique solution $x = \log |w|$, the real logarithm of the positive number |w| and the R.H.S. of (13) is a complex number of the magnitude 1.

Logarithmic Functions (Inverse of Exponential Functions)

It follows that it has one and only one solution, say y_0 , such that $0 \le y_0 < 2\pi$. Now, we have

$$\exp(iy) = \cos y + i\sin y$$
$$= \cos(2n\pi + y) + i\sin(2n\pi + y)$$

where $n=0,1,2,\cdots$. Thus every non-zero complex number has infinitely many logarithms which differ from one another by an integral multiple of 2π .

The imaginary part of $\log w$ is called the argument of w. We denote it by $\arg w$ and it is geometrically interpreted as the angle between the positive real axis and the semi-line from 0 through the point w. This implies that $\arg w$ has infinitely many values which differ by an integral multiple of 2π . A value of $\arg w$ satisfying the inequality $0 \le \arg w < 2\pi$ is called its principal value. Thus we have

$$\log w = \log |w| + i \arg w.$$

Let |w| = r and arg $w = \theta$. Then we have

$$\log w = \log r + i\theta, \quad r > 0. \tag{14}$$

If θ_0 denotes the principle value of θ , we may write

$$\log w = \log r + i(\theta_0 + 2n\pi),$$

where $n=0,\pm 1,\pm 2,\cdots$. We notice from (10) and (11) that

$$\log(\exp z) = z. \tag{15}$$

Logarithmic Functions (Inverse of Exponential Functions)

When emphasis is sought to be placed on a many-valued character of the logarithm of any complex number w, it is denoted by Log w rather than by log w. The symbol log w is then reserved for the value of a logarithm corresponding to the principal value of w, namely, $\log |w| + i\theta_0$, where θ_0 is the principal to the principal value of arg w. Thus we have

$$Log w = \log w \pm 2n\pi i$$

for all $n = 0, 1, 2, \cdots$.

Each Log w, obtained by taking a special value of n, is called a branch of the logarithm. The most important branch is, of course, the branch corresponding to n=0, which is identical to $\log w$, the principal value of the logarithm of w.

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Branches of Log *w*

As we have discussed above, Log w is an infinitely many-valued function, but it can be easily decomposed into "branches" all of which are single valued. The only thing that we have to do is to restrict the value of θ in an interval of length 2π .

By imposing limitations on r and θ so that r>0 and $\theta_0<\theta<\theta_0+2\pi$, the function $\log w$ defined by (14) can be made single-valued and continuous, where θ_0 is any fixed angle in radians. Then we may write

$$\log w = \log r + i\theta,\tag{16}$$

where

$$r > 0$$
, $\theta_0 < \theta < \theta_0 + 2\pi$.

Note that, for each fixed θ_0 , the function defined by (16) is a branch of the multi-valued function Log w.

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Addition Theorem for log *w*

Theorem

If w_1 and w_2 are two complex numbers, then

$$\log (w_1 w_2) = \log w_1 + \log w_2,$$

$$\arg (w_1 w_2) = \arg w_1 + \arg w_2.$$

Proof.

Suppose that $\log w_1 = z_1$ and $\log w_2 = z_2$. Then, by the definition, we have

$$\exp z_1 = w_1, \quad \exp z_2 = w_2.$$

Hence, by the addition theorem for exponential functions and (15), we have

$$\log(w_1w_2) = \log(\exp z_1 \exp z_2) = \log[\exp(z_1 + z_2)] = z_1 + z_2 = \log w_1 + \log w_2.$$

Thus we have

$$\log(w_1 w_2) = \log w_1 + \log w_2. \tag{17}$$

The second result, i.e.,

$$\arg(w_1w_2) = \arg w_1 + \arg w_2 \tag{18}$$

follows in the usual sense.