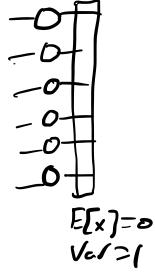
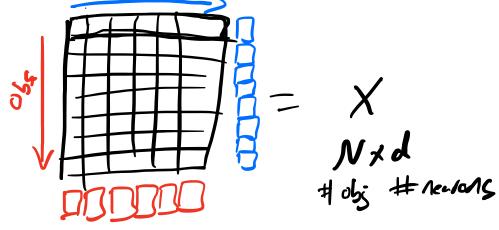
\_cottine Normalization à Keep data at consistent meen and Veriance BN(x) = X-E(x) Advontages 1 du, = |x| | o (xu) | T | da, )  $\beta N(\phi_{i-1}) = \frac{\phi_{i-1} - E[\phi_{i-1}]}{\sqrt{V_{i}/(\phi_{i-1}) - \varepsilon}}$ W/o NolMelization

Butch norm

Luyel NolM





Batch norm

## Residual Networks

Aproach: Residual function

$$\frac{\partial L}{\partial u} = \frac{\partial L}{\partial u} + \frac{\partial L}{\partial u} + \frac{\partial L}{\partial u}$$
Aproach: Residual function

$$\frac{\partial L}{\partial u} = \frac{\partial L}{\partial u} + \frac{\partial L}{\partial u} + \frac{\partial L}{\partial u}$$

Regident Leyer

Layer: 
$$\phi := \sigma - (\phi_i - W_i)$$
Computes next when

Reliand Layers 
$$\phi_i = \sigma(\phi_{i-1}^T w) + \phi_{i-1}$$

$$\phi_i = \sigma(\phi_{i-1} w) = \phi_i - \phi_{i-1}$$

residual

Backprop step  $\frac{dL}{d\phi_{i-1}} = \frac{dL}{d\phi_{i}} \cdot \frac{d\phi_{i}}{d\phi_{i-1}} = \frac{dL}{d\phi_{i}} \left[ \frac{1}{d\phi_{i}} \sigma(\phi_{i}, w_{i}) \right] + \frac{dL}{d\phi_{i}}$ 

$$=\frac{dL}{d\phi_{i}}\left[\frac{d}{d\phi_{i-1}}\left(\sigma(\phi_{i-1}V_{i})+\phi_{i-1}\right)\right]$$

No residual do [wio(sin)+]

We find  $\frac{dL}{dv} = xo(xv_i) \frac{1}{1!} \left(\frac{d\hat{\phi}_i}{d\hat{\phi}_i} + 1\right) \frac{dL}{d\hat{\phi}_L}$