## SuperScalar Processors

CS 1541 Wonsun Ahn



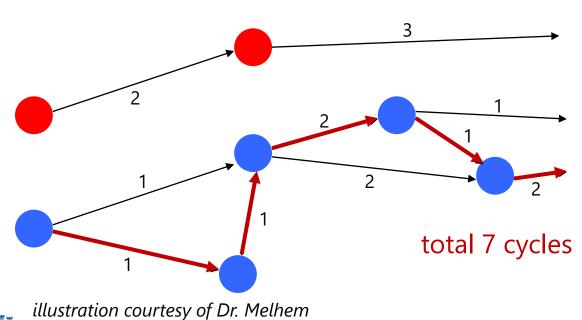
### In-order vs. Out-of-order superscalars

- Superscalar: a wide-issue processor that does dynamic scheduling
  - Extracts instruction level parallelism (ILP) within the processor
- In-order superscalar: does not reorder instructions
  - Only detects hazards between instructions to insert bubbles
  - Only extracts ILP that arises from given ordering of instructions
  - The processor simulated in Project 1
- Out-of-order superscalar: does reorder instructions
  - o Reorders instructions to remove hazards and increase utilization
  - Typically results in higher performance compared to in-order
  - But dynamic reordering consumes lots of power
- Out-of-order sounds more exciting so let's talk about that



### Name of the game is still ILP

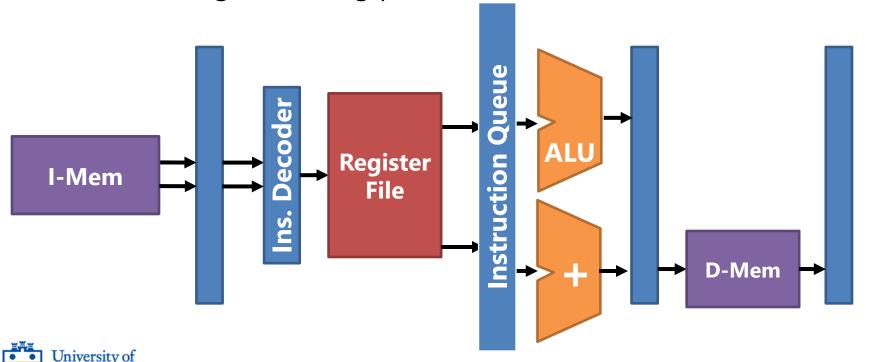
- The processor internally constructs the data dependency graph
- The processor tries to take advantage of ILP as much as possible
  - o By executing the red nodes in parallel with the blue nodes



### Instruction Queue

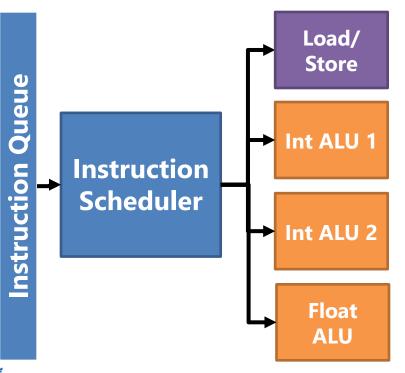
- In order to expose ILP, superscalars need a big instruction window
  Just like the compiler did for VLIWs
  - HW structure for storing instructions is called instruction queue

Now EX stage has a big pool of instructions to choose from



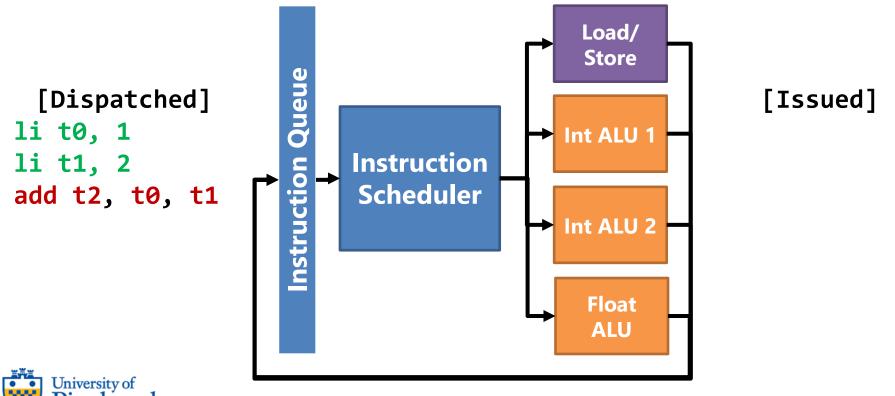
### Instruction Queue

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  - Just like the compiler did for VLIWs
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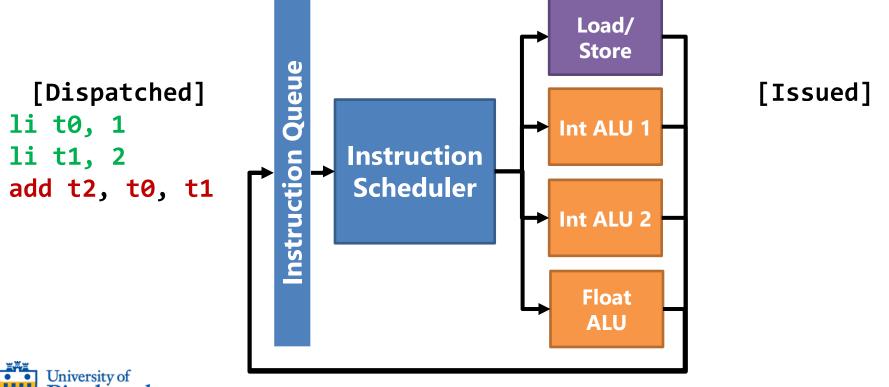


- At **ID**, instructions are decoded
  - And dispatched to the i-queue
- At **EX**, ready instructions are chosen from the instruction queue
  - Ready as in operands are available
  - And issued to an EX unit
- Typically queue is always full
  - Insts start queueing up when insts fail to issue due to hazards

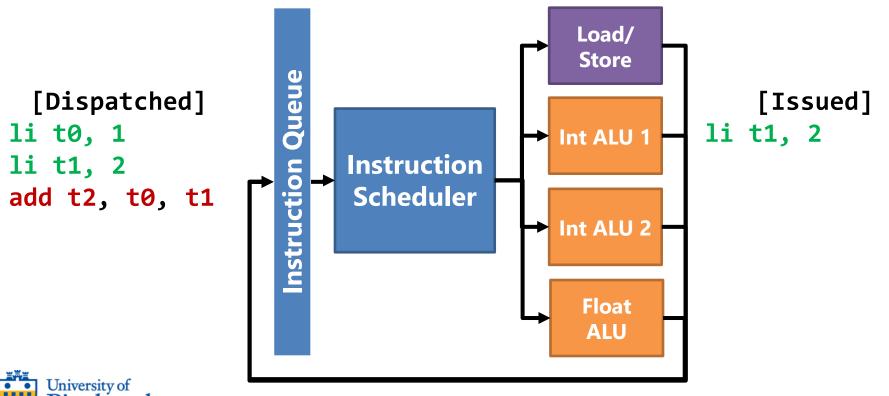
- Now we have pool of instructions. When do they become ready?
  - Ready operands and instructions are in green
  - Not ready operands and instructions are in red



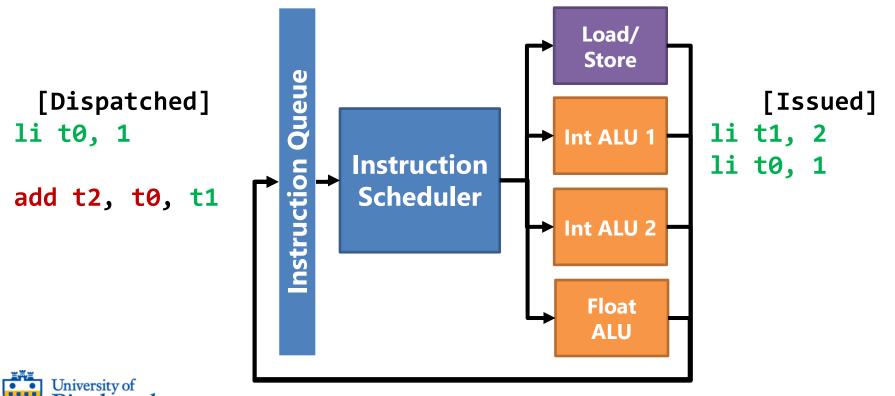
- Initially both li t0, 1 and li t1, 2 are ready
  - The li instruction does not have any register operands
  - Instruction scheduler has a choice of what to issue



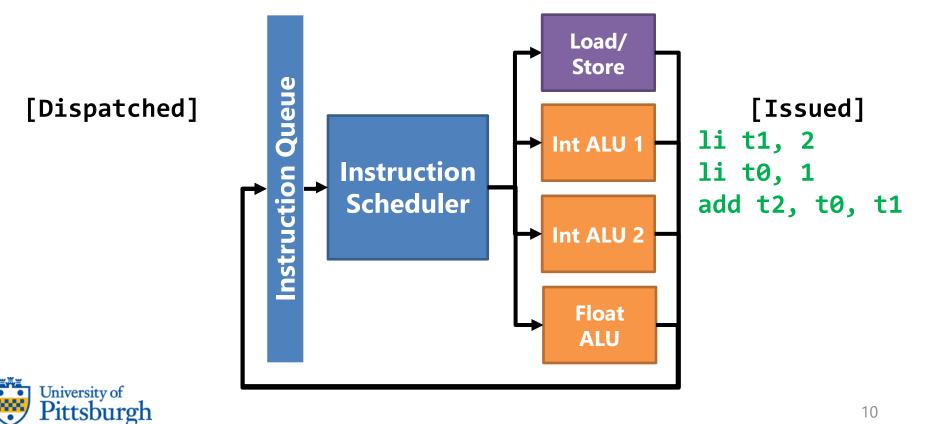
- Let's say the scheduler issues li t1, 2 first
- Then the t1 operand becomes ready after it completes



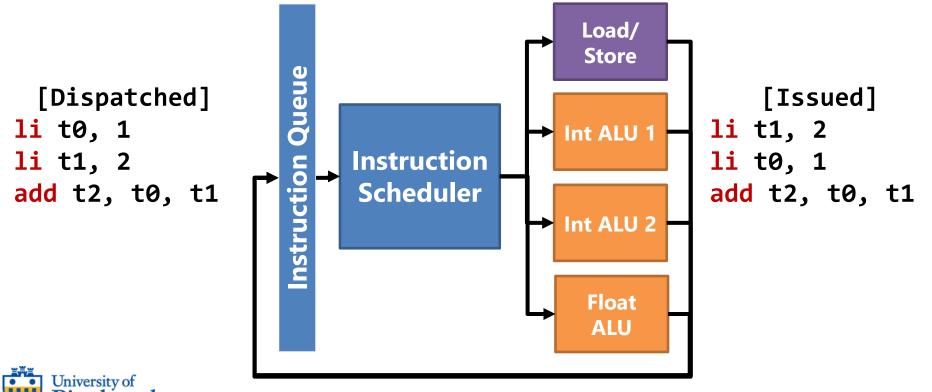
- Now the only ready instruction li to, 1 issues
- Then the to operand becomes ready after it completes
- Now add t2, t0, t1 is finally ready to issue



And we are done!

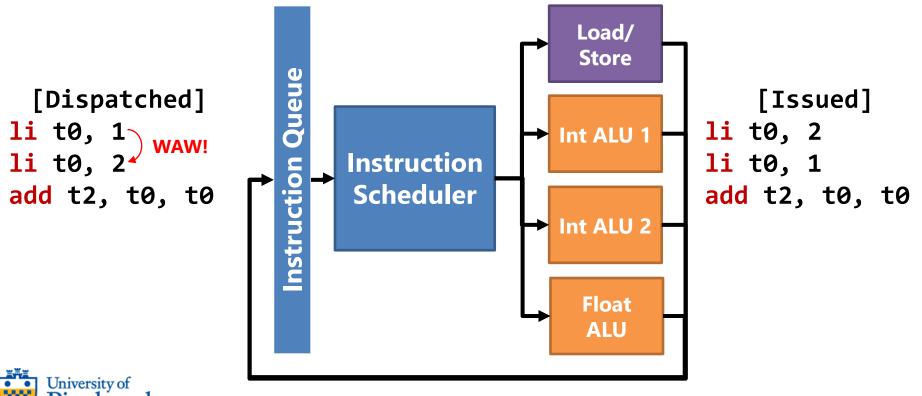


- Note how we reordered li t0, 1 and li t1, 2
  - There are no dependencies between the two, so no issues
  - Also, RAW dependency with add t2, t0, t1 was enforced



### What if we had a WAW dependency?

- Reordering li to, 1 and li to, 2 still allowed (both are ready)
  - O Now t2 = 4 in original code, but t2 = 2 during execution!
  - O How do we disallow this from happening?

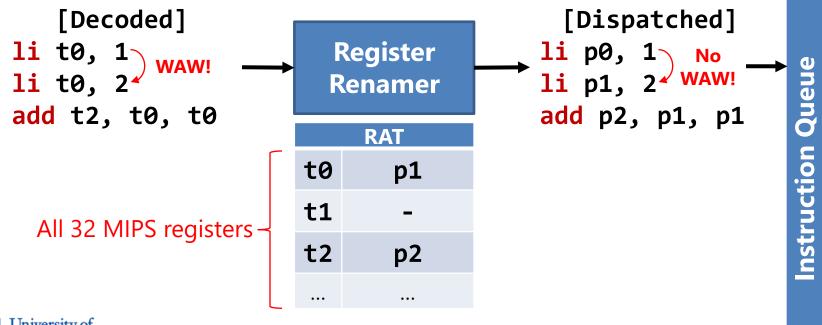


### WAW and WAR dependencies are tricky

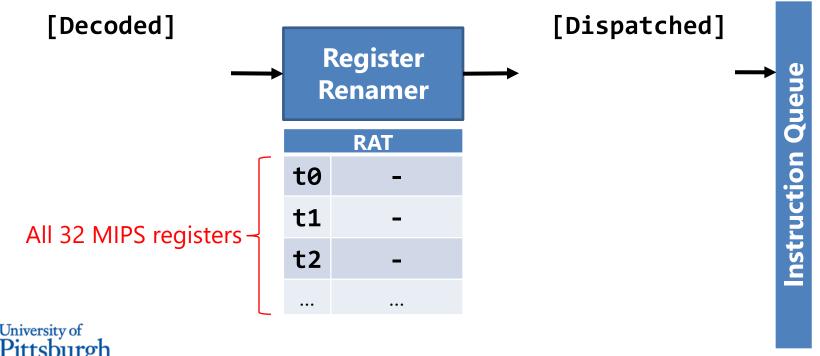
- RAW (true) dependencies are automatically enforced
  - Instructions cannot issue until all operands are ready (written)
- WAW and WAR dependencies are not enforced
  - There is no data passing between the two instructions
  - The two instructions can become ready in any order
- We could somehow enforce WAW and WAR dependencies
  - O But there is a better solution: register renaming!
  - o Remember? That's what the compiler did to remove WAW/WAR.



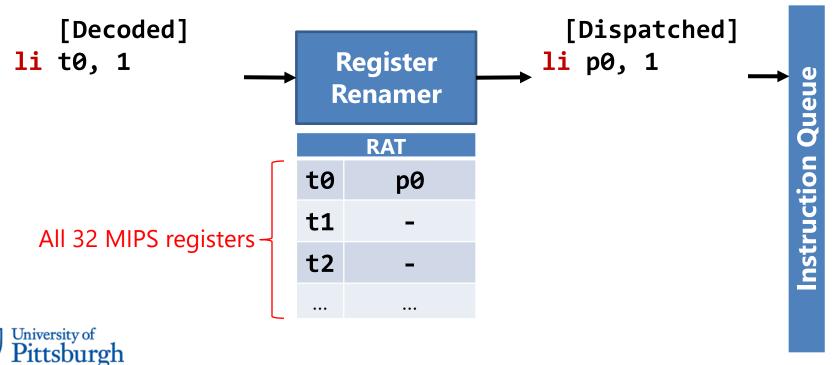
- As soon as decode, Register Renamer renames all registers
  - Done with the help of the Register Alias Table (RAT)
  - o **RAT** is current mapping between **architectural** and **physical** registers
    - Architectural registers: Registers in ISA used in programs (t0, t1, t2, ...)
    - Physical registers: Renamed registers used in processor (p0, p1, p2, ...)



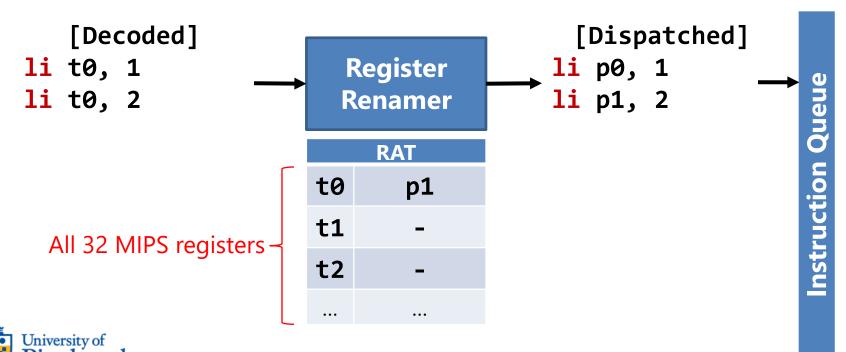
- So how does the RAT work?
- Initially, no assignments have been done, so mapping is empty.



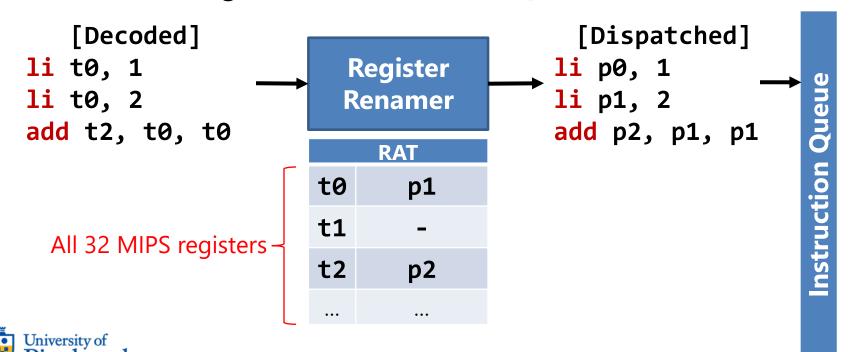
1. li t0, 1 is decoded, destination t0 is renamed to p0



- 1. li t0, 1 is decoded, destination t0 is renamed to p0
- 2. li t0, 2 is decoded, destination t0 is renamed to p1
  - o Remember the single assignment rule?
  - A new value always gets a new register

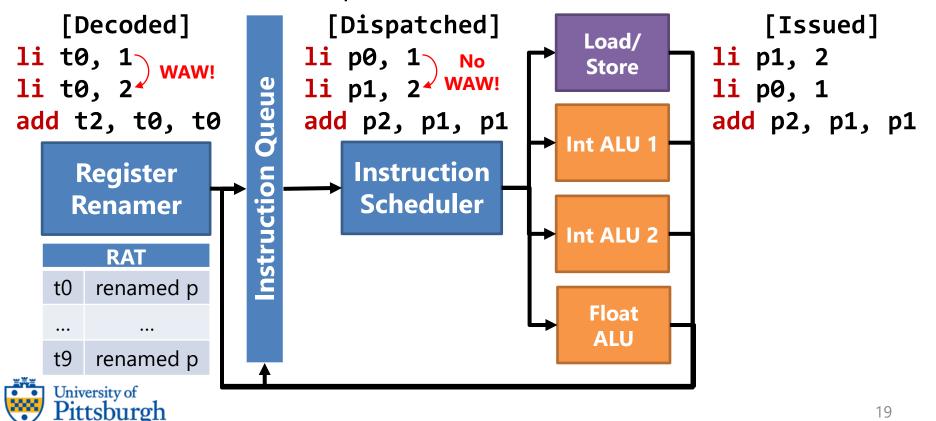


- 1. li t0, 1 is decoded, destination t0 is renamed to p0
- 2. li t0, 2 is decoded, destination t0 is renamed to p1
- 3. add t2, t0, t0 is decoded:
  - Two to input registers use current mapping p1
  - Destination register t2 is renamed to p2



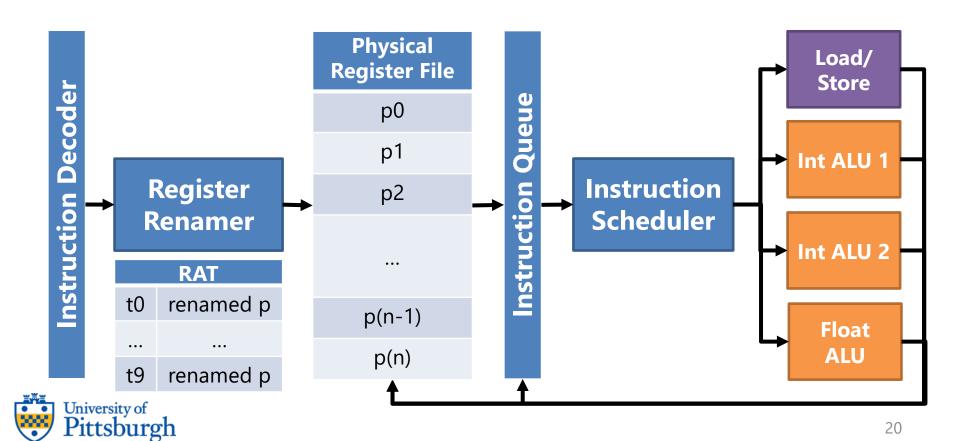
### Register Rename Removes all WAW/WAR Deps

- By the time instructions are dispatched to i-queue
  - All architectural registers have been renamed to physical registers
  - All WAR and WAR dependencies have been removed



## All Computation Done using Physical Registers

- Now ID stage (dispatch) reads registers from physical register file
- All data forwarding also done based on physical registers



### ILP limits performance improvements of wide-issue

- We already discussed limits on pipelining.
- Time to discuss limits on IPC improvements through wide-issue!
- There is a **fundamental limit** to achievable IPC
  - Amount of ILP (Instruction Level Parallelism) in code
  - o Remember the data dependence graph?
  - ILP is constrained only by true RAW dependencies
  - O How about control dependencies?
    - Not a fundamental limit → can elide using branch prediction
- ILP is a **property of the program**, not the processor
  - This limit applies to both VLIW and superscalar processors



### ILP present in different programs

After renaming, theoretical limit of IPC is 35 ~ 4003!

Benchmark	IPC	IPC	IPC	$\mathbf{IPC}$	IPC
	No	Register	Memory	<b>r29</b>	10K
	Renaming	Renaming	Renaming	Removed	Window
compress95	3.12	26.25	73.88	226.33	18.89
cc1	3.61	39.79	41.63	239.96	86.45
go	2.50	49.15	53.77	141.46	70.71
ijpeg	2.41	55.47	93.60	94.11	52.94
li	3.56	19.60	19.61	81.45	27.70
m88ksim	2.76	19.93	62.06	363.26	20.50
perl	3.47	82.01	127.57	153.05	128.84
vortex	4.57	26.26	26.27	271.97	92.04
applu	2.82	106.65	2037.61	2076.06	78.67
apsi	3.6	54.89	183.44	1224.86	79.56
fpppp	3.33	103.62	774.13	1837.96	134.62
hydro2d	3.09	144.80	147.67	242.08	52.14
mgrid	3.34	1876.11	3933.03	4003.44	286.48
su2cor	3.22	38.21	34.81	55.56	47.60
swim	3.10	112.08	112.08	275.21	89.15
tomcatv	3.61	32.85	61.47	119.67	58.91
turb3d	3.42	370.98	482.24	3652.46	0
wave5	3.25	29.28	35.71	35.71	0

Matthew Postiff et al. "The Limits of Instruction Level Parallelism in SPEC95 Applications". ACM SIGARCH Computer Architecture News, 1999



### Practical limits on performance of Superscalar

- Achieving the theoretical limit would be awesome
  - o In reality, superscalars are typically no more than 10-wide
- Practical limits on superscalar processors
  - o Number of execution units (e.g. ALU, Load/Store) **not** really a limit
  - o Practical limits on the **IPC** you can achieve
    - Instruction queue size (impacts scheduling window)
    - Physical register file size (also impacts scheduling window)
  - Upsizing above structures negatively impacts cycle time
    - Time to search and schedule instruction queue
    - Time to access register file (increased size and number of ports)
  - Upsizing above structures negatively impacts energy efficiency



# Exceptions



### **Exceptions Review**

- **Exception**: an event which causes the CPU to stop the normal flow of execution and go somewhere else (the exception handler)
- There are mainly two causes of exceptions:
  - Software exceptions (or traps): Triggered by a program instruction
    - Trap instruction: typically used to call OS routines (system calls)
    - Page fault: instruction accessed a page not mapped to memory
    - Divide-by-0: instruction performed a divide-by-0 arithmetic
    - Arithmetic overflow: instruction overflowed MAX\_INT of register
  - Hardware exceptions (or interrupts): Triggered by hardware event
    - User has typed on the keyboard
    - A network packet has arrived
    - A file block read has completed
- In all cases, the OS exception handler is invoked



### Handling exceptions

- What happens when an exception is triggered:
  - 1. Processor stops execution of user program.
  - 2. Processor stores information about exception (cause, PC).
  - 3. Processor jumps to the OS exception handler.
  - 4. Handler creates backup of program register values in memory.
  - 5. Handler inspects exception info and handles it accordingly.
    - While overwriting some of the registers that were backed up.
  - 6. Handler **restores** program **register values** from memory.
  - 7. Processor resumes execution of user program.
- Processor must provide precise register values at point of exception
  - Otherwise, when processor resumes, program will malfunction
  - Guaranteeing this is called a precise exception



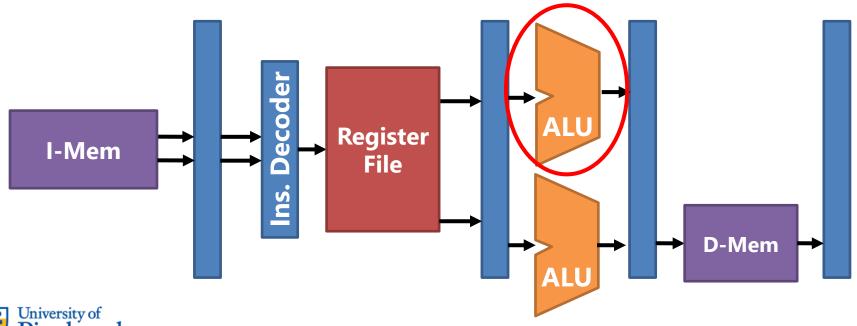
### Rules for Precise Exceptions

- 1. All instructions before the exception must have executed
- 2. No instructions after the exception must execute
- Architectural state: the state visible to the ISA (i.e. software)
  - State in architectural registers (For MIPS: t0, t1, t2, ...)
  - State in data memory
- Architectural state at point of exception must reflect above rules



## Precise Exceptions in In-order Processors is Easy

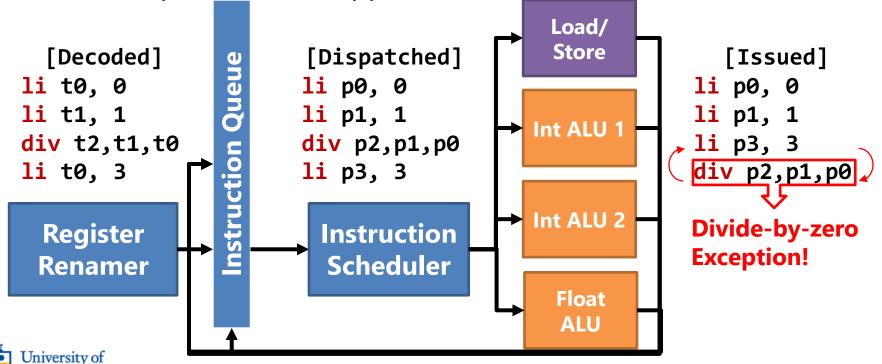
- Exceptions are typically detected at the EX stage
  - Stage where all arithmetic happens as well as address calculations
- On exception, flush EX and all previous stages (ID and IF)
  - Since in-order, guarantees instructions following EX do not writeback
  - o Only state leading up to instruction at EX will be written to reg / mem



### Precise Exceptions in Out-of-order Processors is Hard

- Suppose div t2,t1,t0 and li t0, 3 issue out-of-order as below
  - o div p2,p1,p0 triggers a divide-by-zero exception (p0 = 0)
  - But at point of exception, t0 appears to be 3 due to li p3, 3!

At that point, to is mapped to p3 in the RAT (not p0)



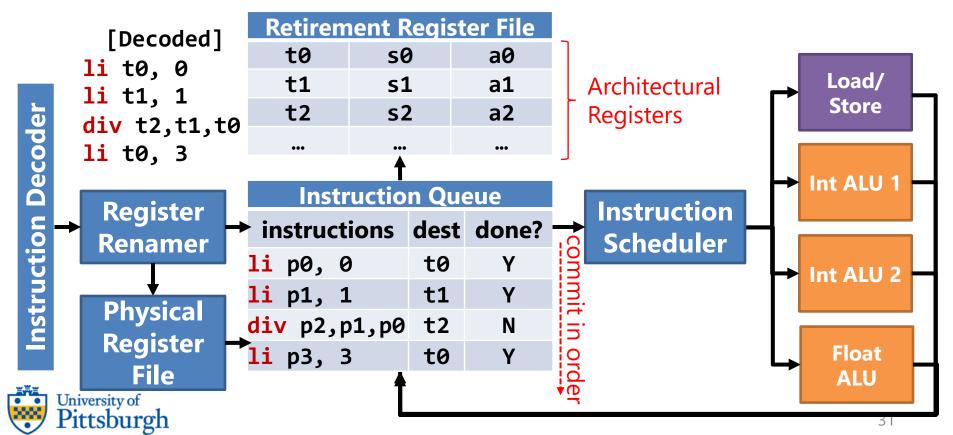
### Precise Exceptions in Out-of-order Processors is Hard

- This is the challenge with out-of-order processors
  - Instructions execute and complete out-of-order
  - o For precise exceptions, instructions must appear to complete in-order
- Solution: update architectural state in-order
  - When instructions execute, have them only update "internal" state
    - Physical registers
    - Store queue (MEM queues up stores instead of performing them)
  - Internal state is transferred to visible state during in-order commit
    - Physical registers are copied to architectural registers
    - Store queue entries are written to memory



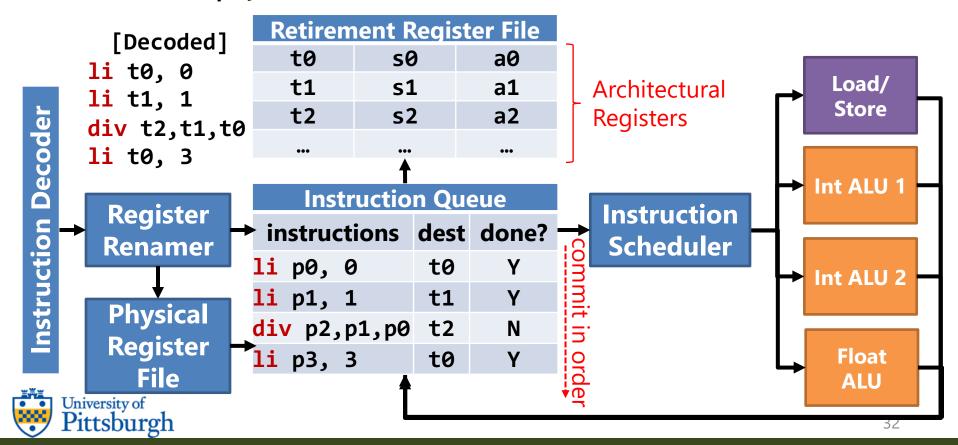
### In-order Commit

- Decoded instructions are stored to i-queue in-order
- Instructions execute out-of-order (updating done? field)
- Done instructions commit in-order to Retirement Register File (RRF)



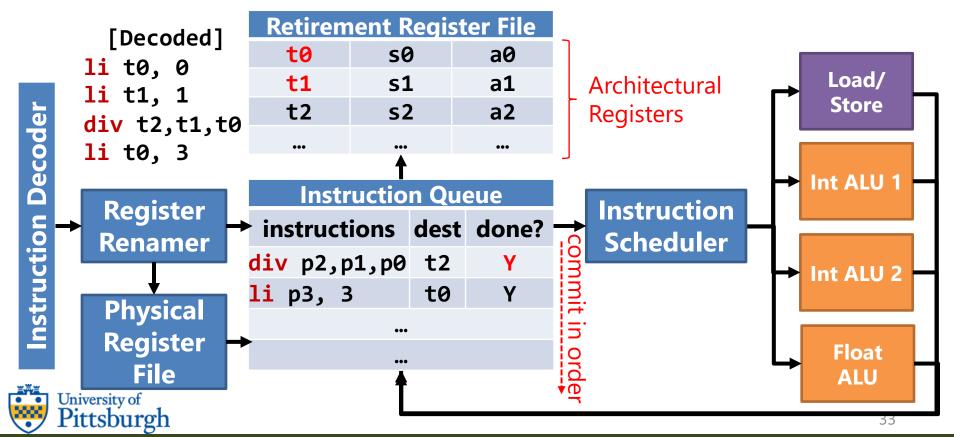
### In-order Commit Example: Cycle 1

- At this point, all li instructions have completed but not the div
- li p0, 0 and li p1, 1 can commit on the next cycle
  - o But not **li p3**, **3** since we have in-order commit!



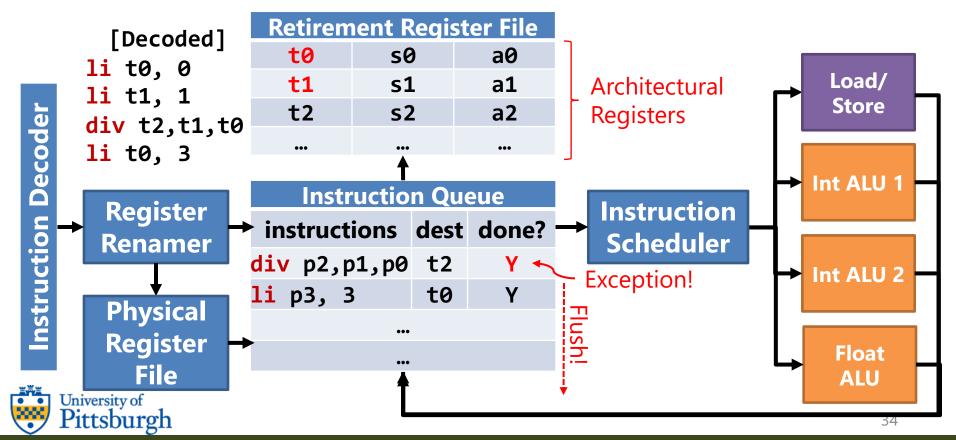
### In-order Commit Example : Cycle 2

- li p0, 0 and li p1, 1 have committed updating t0 and t1
- div p2,p1,p0 has completed execution and is finally ready to commit
  - On completion, div has set an "exception bit" in i-queue (not shown here)



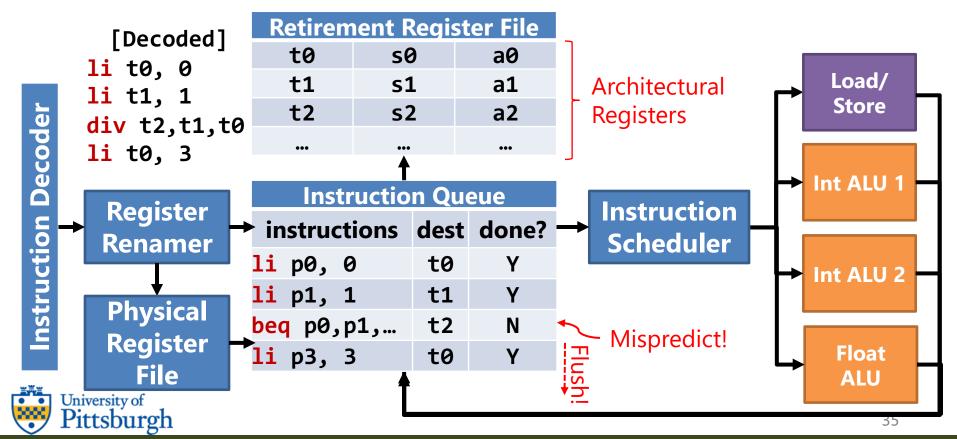
### In-order Commit Example: Cycle 3

- An exception is raised for **div p2,p1,p0** when it tries to commit
  - Instructions following div are flushed, without modifying RRF
- Retirement Register File contains a precise architectural state



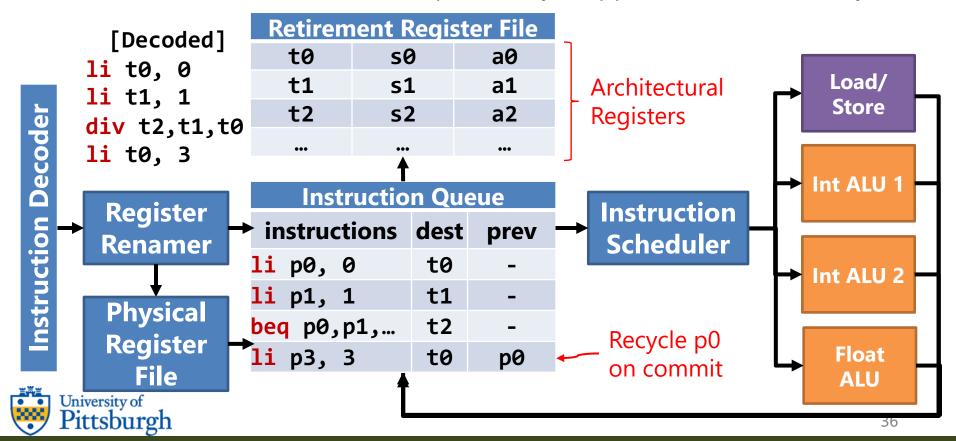
### In-order Commit also solves branch misprediction

- What if processor finds out it mispredicted a branch?
  - o Just flush instructions below it after the branch executes!
  - Also restore an RAT snapshot that was taken at point of branch.



### In-order Commit also solves physical register recycling

- When can the processor recycle physical registers?
  - The prev column records previous physical register mapped to dest.
  - When li p3, 3 commits, p0 previously mapped to t0 can be recycled



## Real Life Superscalars



#### The ARM Cortex-A8 architecture

The ARM Cortex-A8 is an in-order superscalar processor
 Notice the use of the architectural register file

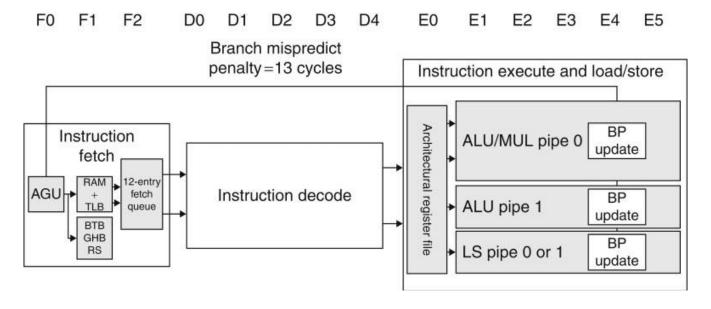
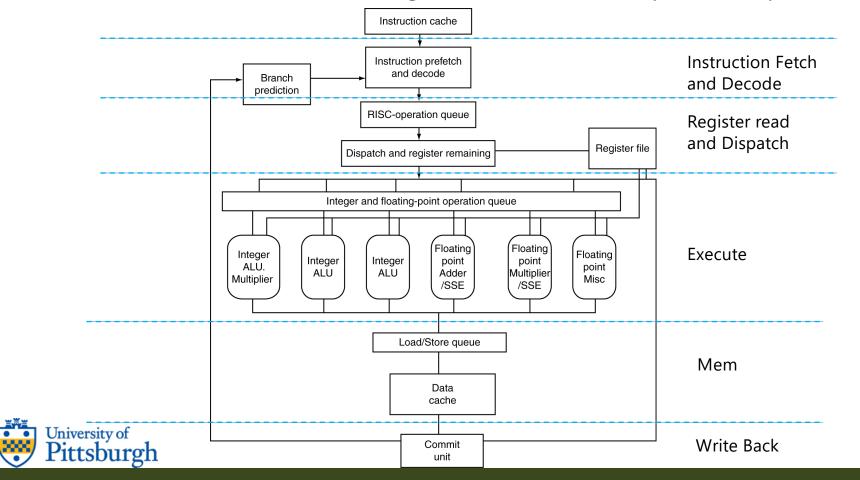


FIGURE 4.75 The A8 pipeline. The first three stages fetch instructions into a 12-entry instruction fetch buffer. The *Address Generation Unit* (AGU) uses a *Branch Target Buffer* (BTB), *Global History Buffer* (GHB), and a *Return Stack* (RS) to predict branches to try to keep the fetch queue full. Instruction decode is five stages and instruction execution is six stages.



### The AMD Opteron X4 Microarchitecture

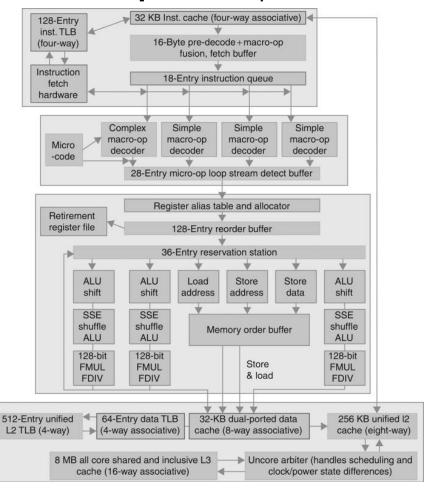
- The AMD Opteron is an out-of-order superscalar processor
  - o Commit unit oversees retiring instructions from operation queue



#### The Intel Core i7 architecture

The Intel Core i7 is another out-of-order superscalar processor

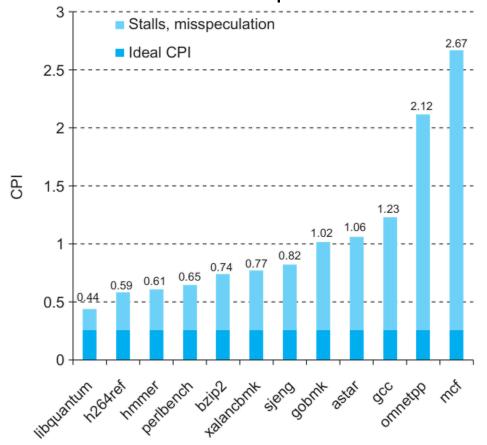
FIGURE 4.77 The Core i7 pipeline with memory components. The total pipeline depth is 14 stages, with **branch mispredictions costing 17 clock cycles**. This design can buffer 48 loads and 32 stores. It is a 4-wide processor but has 6 execution units of different types to reduce structural hazards.





### Intel Core i7 Performance

• Ideal CPI = 0.25 since this is a 4-wide processor





## Intel Core i7 Impact of Branch Misprediction

• Due to deep pipeline, tiny misprediction can have outsized impact

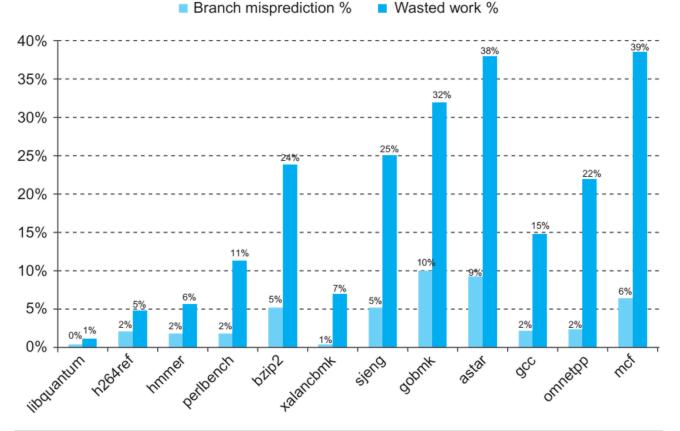




FIGURE 4.79 Percentage of branch mispredictions and wasted work due to unfruitful speculation of Intel Core i7 920 running SPEC2006 integer benchmarks.