Cache Design 2

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Cache Design Parameter 6: Write-Through vs. Write-Back



Writes and Cache Consistency

- Assume &x is 111010_2 , and x = 24 initially Tag Data t0, &x 000 0 addi t0, t0, 1 001 0 # X++ 111 25 010 t0, &x SW 011 0 • How will the w change the cache? How will the sw change the cache? 100 0 Uh oh, now the cache is inconsistent. 101 0 (Memory still has the old value 24.) 110 0 111 0
- How can we solve this? Two policies:
 - Write-through: Propagate write all the way through memory
 - o Write-back: Write back cache block when it is evicted from cache

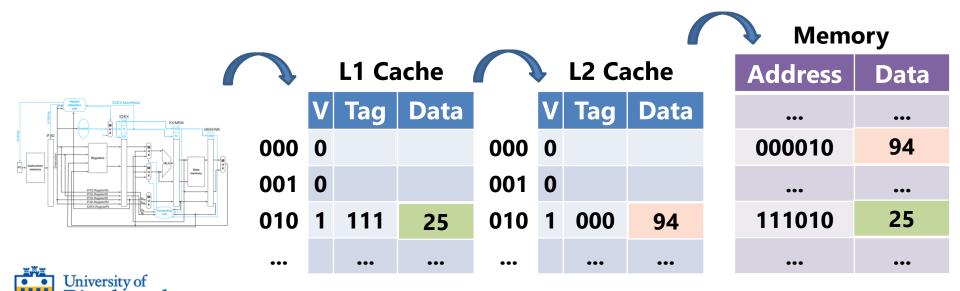


Write-Through Policy



Policy 1: Write-through

- Write-through:
 - On hit, write to cache block and propagate write to lower memory
 - On miss, keep on propagating the write to lower memory
- What happens if we write **25** to address **111010**₂?
- What happens if we write **94** to address **000010**₂?
- → Caches are kept consistent at all points in time!



Write-through: Reads

- What happens if we read from address 000010₂?
 - We can just discard the conflicting cache block 111010₂
 - o It's just an extra copy of the same data
- Note how we allocate blocks only on read misses
 - Write misses don't allocate blocks because it doesn't help anyway
 - --- writes are propagated to lower memory even on write hits
 - This policy is called **no write allocate**

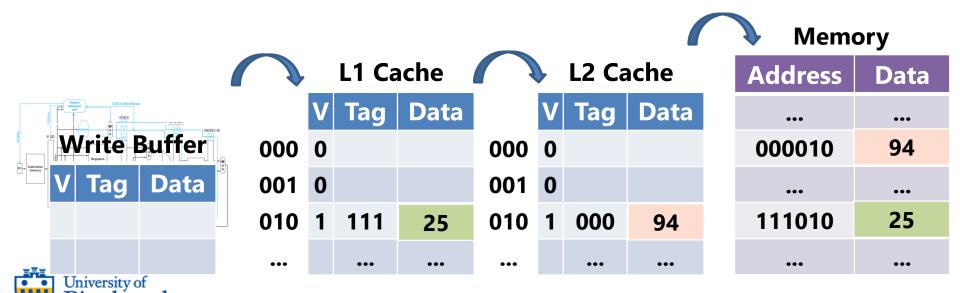
Memory

Address	Data
•••	•••
000010	94
•••	•••
111010	25
•••	•••



Write-through: Drawbacks

- Drawback: Long write delays regardless of hit or miss
 - Must always propagate writes all the way to DRAM
- Solution: Write buffer maintaining pending writes
 - o CPU gets on with work after moving pending write to write buffer
 - o But does the write buffer solve all problems?



Write-through: Drawbacks

- The write buffer does not solve all problems.
- 1. Write buffer must be **very big** to store all pending writes
 - May take more than 100 cycles for write to propagate to memory
 - \circ Write buffer is always checked before L1\$ \rightarrow adds to **hit time**
- 2. Write buffer does not solve **bandwidth** problems
 - If memory bandwidth < rate of writes in program, write buffer will fill up quickly, no matter how big it is
- Impractical to write-through all the way to memory
 - Typically only L1 caches are write-through, if any
- We need another strategy that is not so bandwidth-intensive



Write-Back Policy



- **Dirty** block: a block that is temporarily inconsistent with memory
 - On a hit, write to cache block, marking it dirty. No propagation.
 - Write back dirty block to lower memory only when it is evicted
 - → Saves bandwidth since write hits no longer access memory
- A dirty bit is added to the cache block metadata (marked "D")
 - Block 000001₂ is clean → can be discarded on eviction
 - Block 111010₂ is dirty → needs to be written back on eviction

 Memory

					ivienioi y		
Cache				e		Address	Data
	V	D	Tag	Data		•••	•••
000	0	0			consistent	000001	93
001	0	0	000	93	COL		
010	1	1	111	25	inconsistent		2.4
	-	-				111010	24
•••			•••	•••		•••	•••

Write-back: Write allocate

- What happens on a write miss?
 - If no write allocate like write-through, will miss again on next write
 - And on the next write, and on the next write, ...
 - No bandwidth savings from hitting in cache
- Unlike write-through, write-back has a write allocate policy
 - On write miss, block is allocated in cache to stop further misses
 - On allocation, the block is read in from lower memory
- Q: Why the wasted effort?
 - o Aren't we going to overwrite the block anyway with new data?
 - Owhy read in data that is going be overwritten?



Write-back: Write allocate

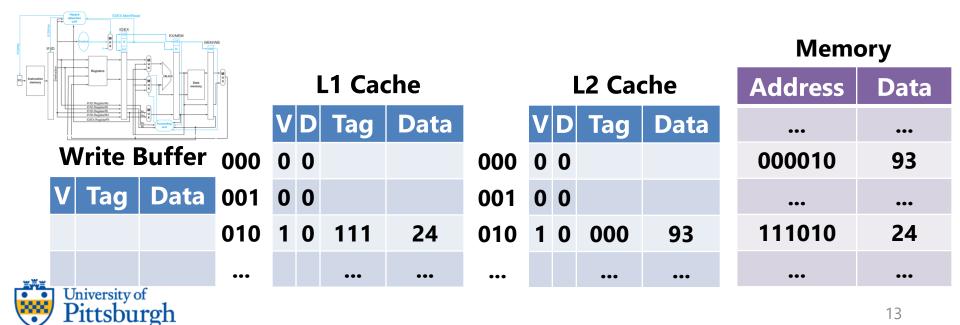
- Because a block is multiple bytes, and you are updating just a few
 - Suppose a cache block is 8 bytes (2 words)
 - Suppose you are writing to only the first word

V	D	Tag	Data			
1	1		first word (written)	second word (not written)		

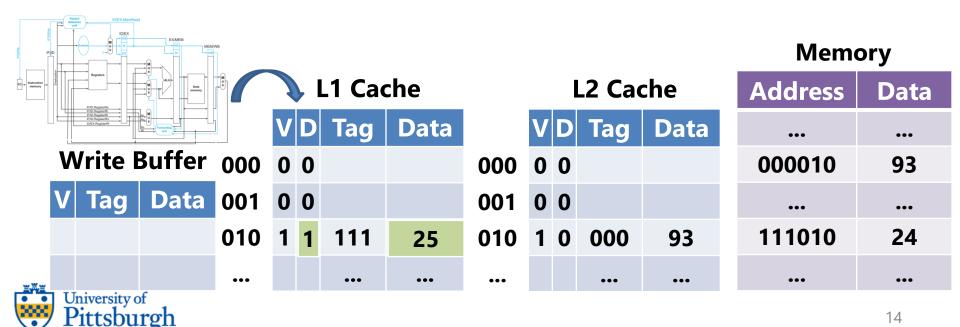
- After allocate, the entire cache block is marked valid
 - That means second word as well as first word must be valid
 - That means second word must be fetched from lower memory
 - Otherwise if later second word is read, it will contain junk data
 - Unavoidable, unless you have a valid bit for each byte
 - That means spending 1 bit for every 8 bits of data
 - That's just too much metadata overhead



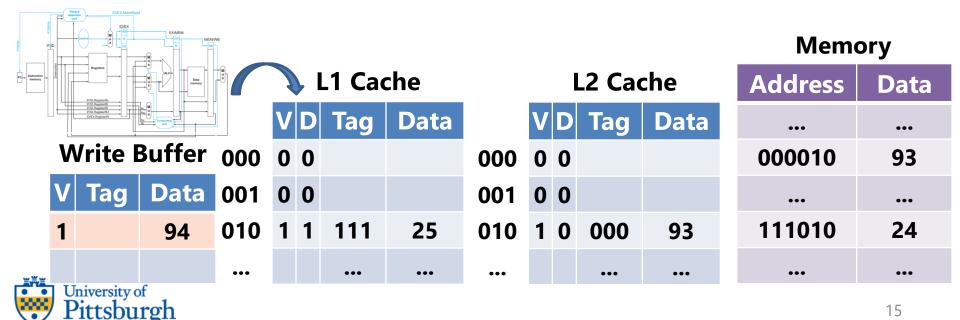
• What happens if we write **25** to address **111010**₂?



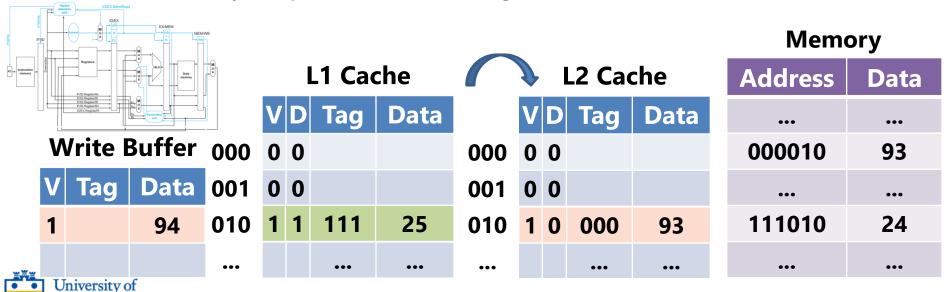
- What happens if we write **25** to address **111010**₂?
 - L1 Cache hit! Update cache block and mark it dirty.
 - o That's it! How quick is that compared to write-through?



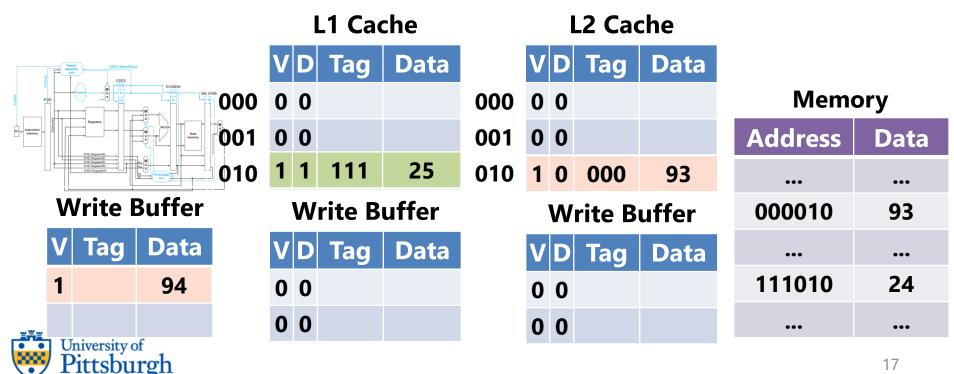
- What happens if we write 94 to address 000010₂?
 - L1 Cache miss! First thing we will do is add store to Write Buffer. (So that the CPU can continue executing past the store)



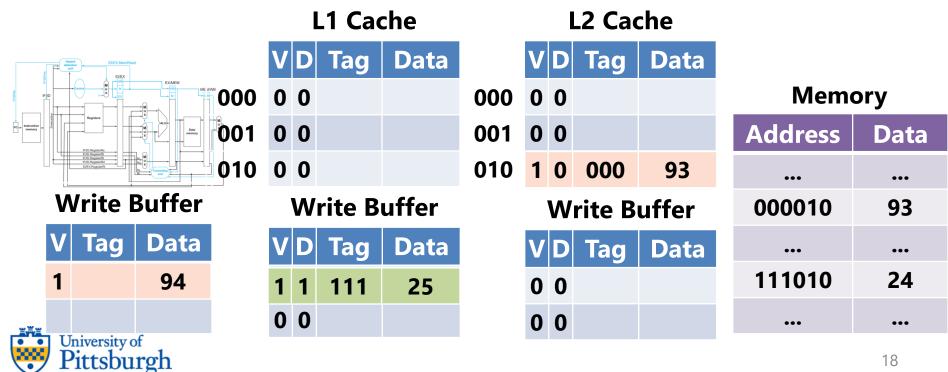
- What happens if we write **94** to address **000010**₂? (cont'd)
 - Next the L2 Cache is searched and it's a hit!
 - To bring in block to L1 Cache, we first need to evict block 25.
 - o It's a dirty block, so we can't just discard it. Need to write it back!
 - Since block 25 misses in L2, it will take the long trip to Memory
 - o Is there a way to put it aside and get to it later?



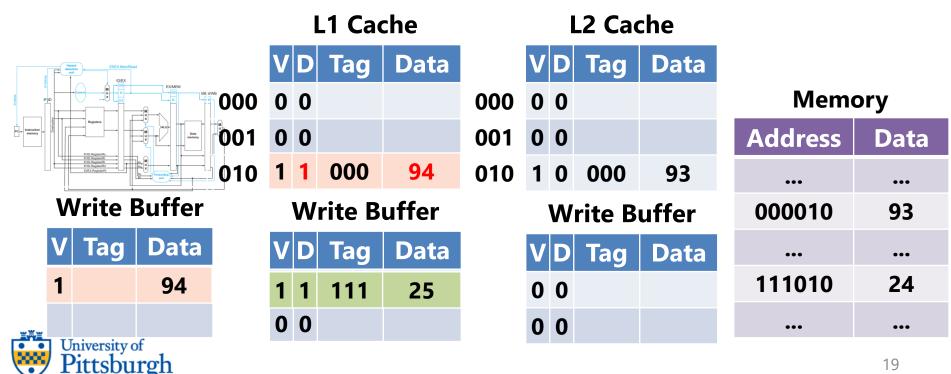
- What happens if we write **94** to address **000010**₂? (cont'd)
 - Yes! Add Write Buffers to caches, just like we did for the pipeline!
 - Move block to L1 Write Buffer so L1 Cache can continue working
 - Pending block will get written back to Memory eventually



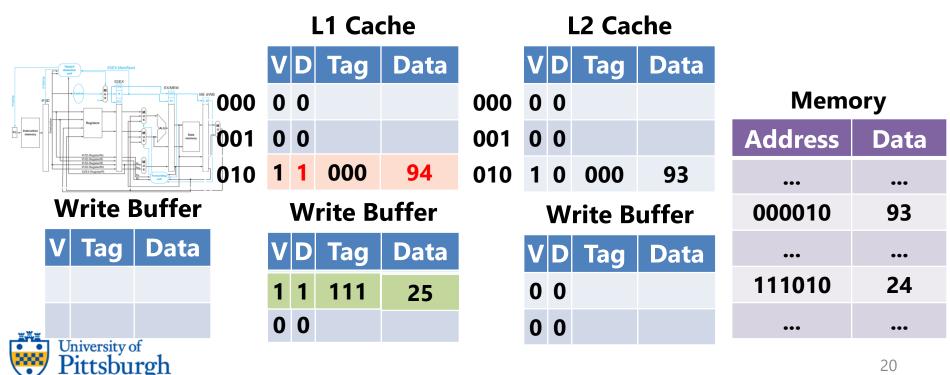
- What happens if we write **94** to address **000010**₂? (cont'd)
 - Now we can finally read in block 93 to the L1 Cache



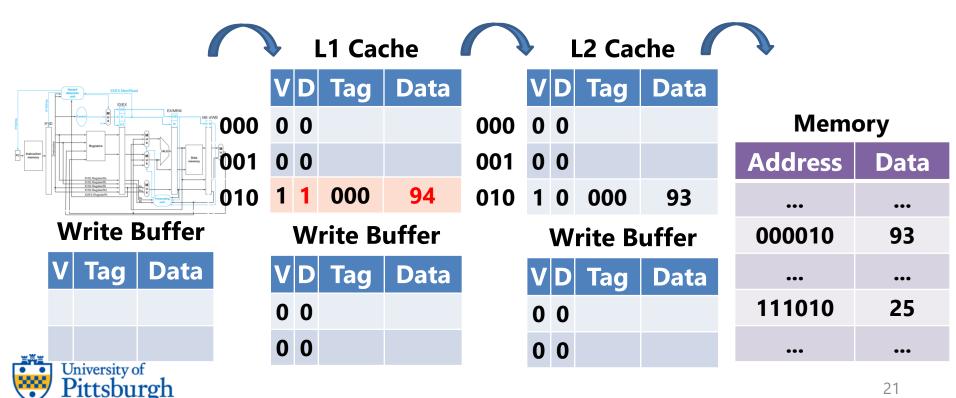
- What happens if we write **94** to address **000010**₂? (cont'd)
 - Now we can finally read in block 93 to the L1 Cache
 - o And write 94 into the cache block, also marking it dirty
 - Store is finished, so now remove it from pipeline Write Buffer!



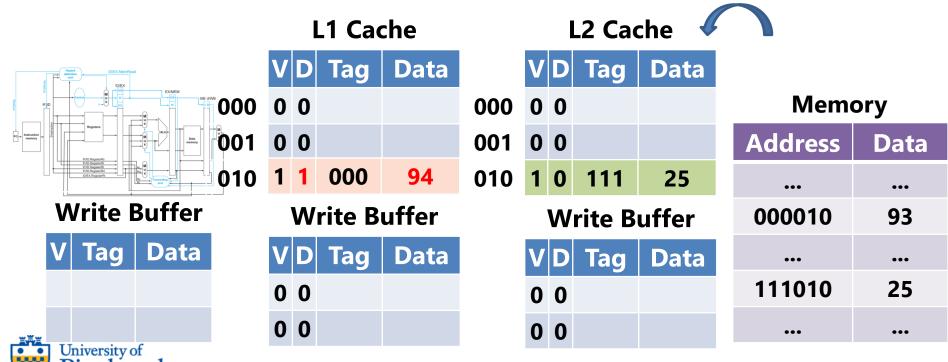
- What happens if we write **94** to address **000010**₂? (cont'd)
 - Eventually, the pending block in L1 Write Buffer will write back
 - But this didn't affect the original store latency



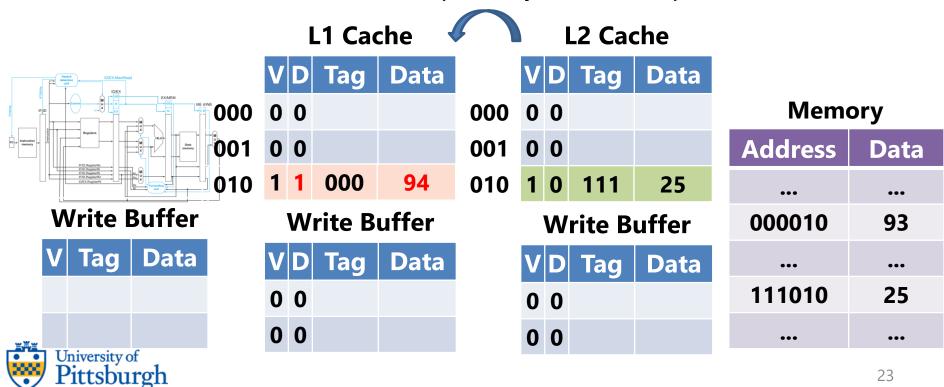
- What happens if we read 25 from address 111010₂?
 - Misses in L1 and L2 caches and must go all the way to Memory



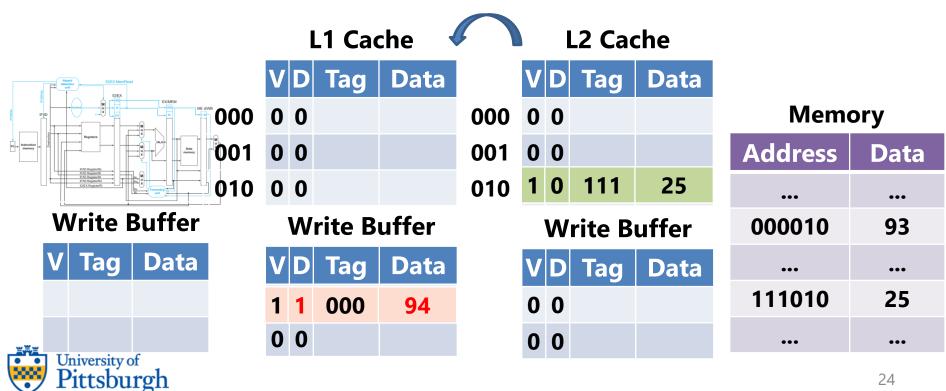
- What happens if we read **25** from address **111010**₂?
 - Misses in L1 and L2 caches and must go all the way to Memory
 - Fills the L2 Cache with 25 on the way back after evicting block 93 (Note that block 93 can simply be discarded since it's clean)



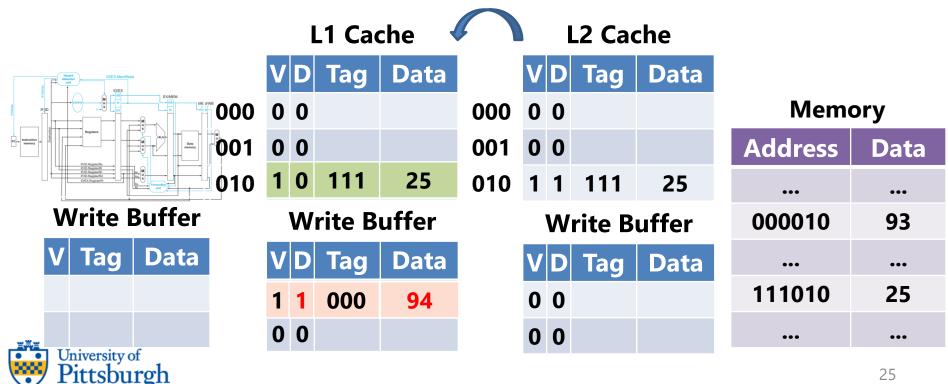
- What happens if we read **25** from address **111010**₂? (cont'd)
 - Now it needs to evict block 94 in L1 Cache before filling with 25
 - But block 94 needs to be written back since it's dirty!
 - So move to Write Buffer temporarily to make space.



- What happens if we read 25 from address 111010₂? (cont'd)
 - o Now L1 Cache can be filled with block 25



- What happens if we read **25** from address **111010**₂? (cont'd)
 - Now I 1 Cache can be filled with block 25
 - Block 94 will eventually be written back to Memory
 - Write buffers in this context are also called victim caches



Impact of Write Policy on AMAT

- AMAT = hit time + (miss rate × miss penalty)
- Write-through caches can have a larger write hit time
 - With write-back, a read hit and write hit take the same amount of time
 - With write-through, a write hit takes the same time as a write miss
- Write-back caches can have a larger miss penalty
 - Due to write allocate policy on write misses

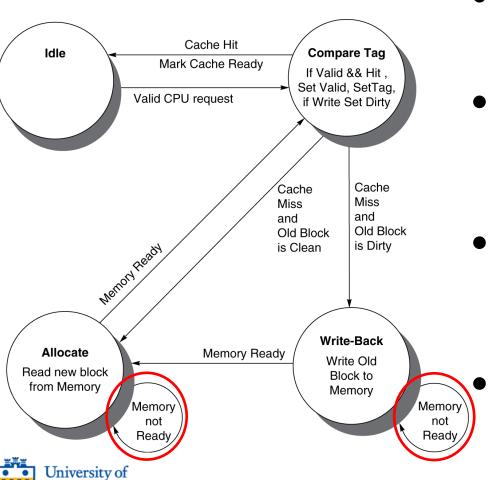
University of

- Due to write-backs of dirty blocks when making space for new block
- Both issues can be mitigated using write buffers to varying degrees
- All in all, write-back caches usually outperform write-through caches
 - Because write hits are much more frequent compared to misses
- But write-through sometimes used in L1 cache due to simplicity
 - \circ Plenty of L1 \rightarrow L2 (intra-chip) bandwidth to handle write propagation
 - \circ For L3, L3 \rightarrow DRAM bandwidth cannot support write propagation

Cache Design Parameter 7: Blocking vs. Non-blocking

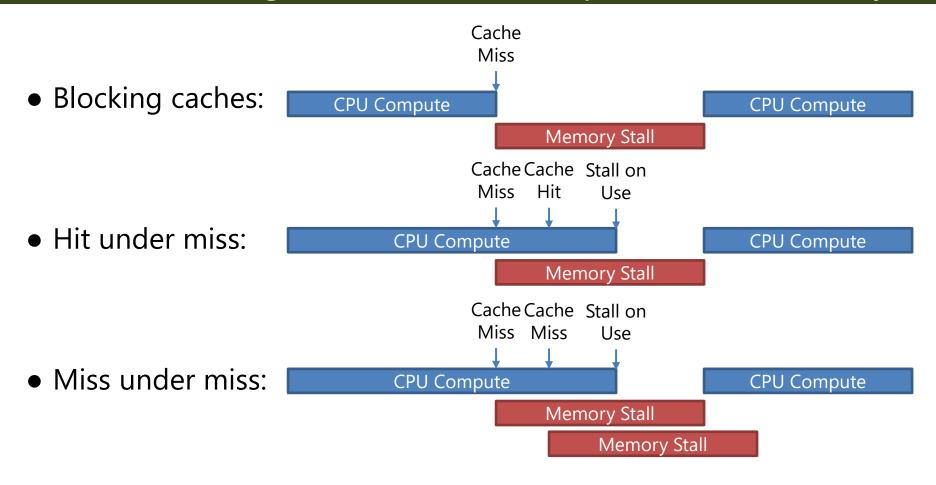


Blocking Cache FSM for Write Back Caches



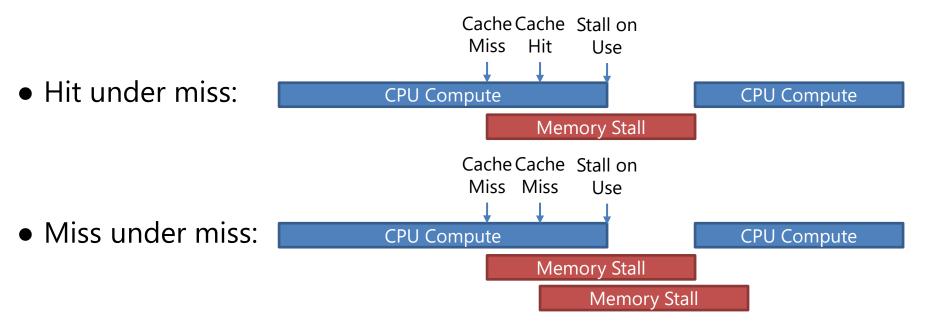
- FSM must be in **Idle** state for cache to receive new requests
- While "Memory not Ready",
 blocks subsequent requests
 → Called Blocking Cache
- Write buffer allows cache to defer write-back until later
 Allows quickly return to Idle
- But how about "Memory not Ready" on Allocate?

Non-blocking caches service requests concurrently





Non-blocking caches service requests concurrently



- Non-blocking cache allows both to happen
 - Allows Memory Level Parallelism (MLP)
 - As important to performance as Instruction Level Parallelism (ILP)
- Miss Status Handling Register (MSHR) table tracks pending requests



Impact of non-blocking caches

- Non-blocking caches do not impact our three cache metrics
 - o Hit time, miss rate, and miss penalty remain mostly the same
- Impact is that miss penalty can be overlapped with:
 - Computation of instructions not dependent on the miss
 - Miss penalties of other memory requests
- Out-of-order processors are always coupled with a non-blocking cache
 - Otherwise, the ability to do out-of-order execution is severely stymied



Cache Design Parameter 8: Unified vs. Split



Problem with Split Caches

- If cache is split into two (i-cache and d-cache)
 - Space cannot be flexibly allocated between data and code

If our working set looks like Code this – say, in a **I-Cache** small loop Code that's accessing a large array – then we run out of data **Data** space. **D-Cache Data**

If our working set looks like this – say, in a large function that's only using stack variables – then we run out of code space.



Impact of Unifying Cache

- The answer to the problem is to simply unify the cache into one
- AMAT = hit time + (miss rate × miss penalty)
- Impact of unifying cache on miss rate:
 - Smaller miss rate due to more flexible use of space
- Impact of unifying cache on hit time:
 - Potentially longer hit time due to structural hazard
 - With split caches, i-cache and d-cache can be accessed simultaneously
 - With unified cache, access request must wait until port is available
- L1 cache is almost always split
 - o Frequent accesses directly from pipeline trigger structural hazard often
- Lower level caches are almost always unified
 - Accesses are infrequent (filtered by L1), so structural hazards are rare

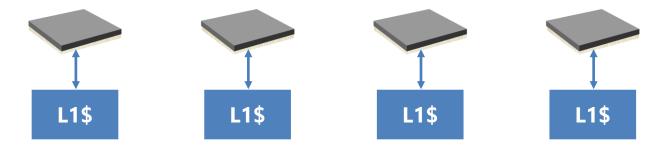


Cache Design Parameter 9: Private vs. Shared



Private vs. Shared Cache

- On a multi-core system, there are two ways to organize the cache
- **Private** caches: each core (processor) uses its own cache



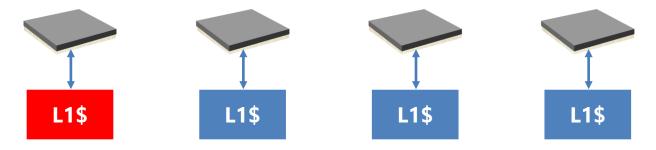
• **Shared** cache: all the cores share one big cache





Shared Cache can Use Space More Flexibly

- Suppose only 1st core is active and other cores are idle
 How much cache space is available to 1st core? (Shown in red)
- **Private** caches: 1st core can only use its own private cache



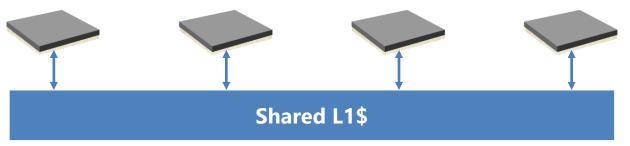
• **Shared** cache: 1st core can use entire shared cache!



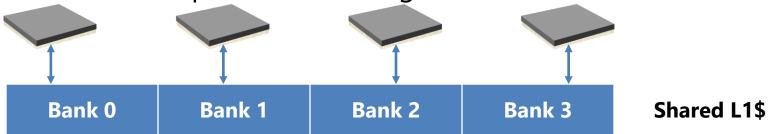


Banking: Solution to Structural Hazards

- Now what if all the cores are active at the same time?
 - Own't that cause structural hazards due to simultaneous access?



Could add more ports, but adding banks is more cost effective

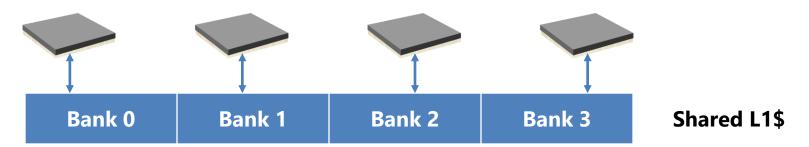


- Each bank has its own read / write port
- As long as two cores do not access same bank, no hazard!



Banking: Solution to Structural Hazards

• Cache blocks are **interleaved** between banks

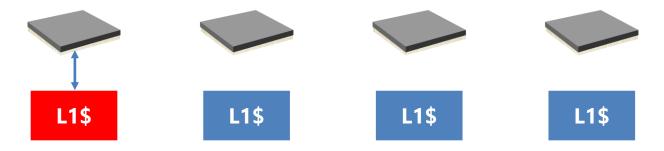


- \circ Blocks 0, 4, 8 ... \rightarrow Bank 0
- \circ Blocks 1, 5, 9 ... \rightarrow Bank 1
- o Blocks 2, 6, 10 ... → Bank 2
- Blocks 3, 7, 11 ... → Bank 3
- That way, blocks are evenly distributed across banks
 - Causes cache accesses to also be distributed → less hazards

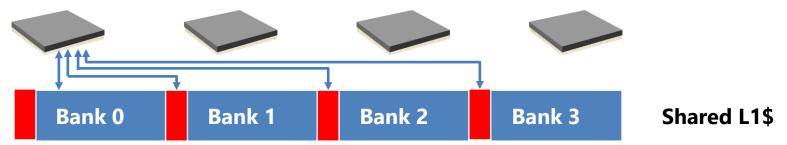


Shared Cache have Longer Access Times

- Again, suppose only 1st core is active and other cores are idle
 The working set data is shown in red
- Private caches: entire working set data in nearby private cache



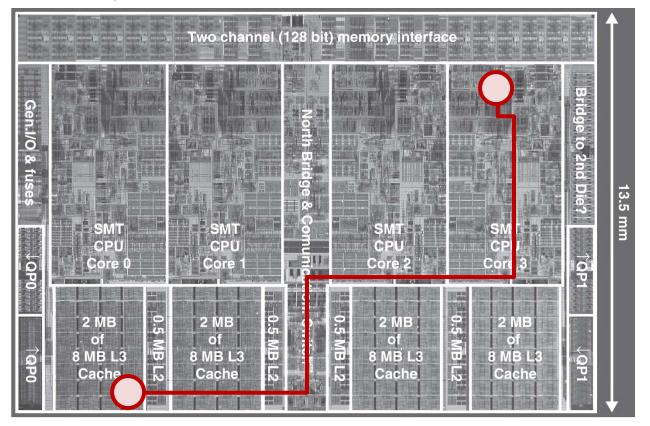
• Shared cache: data sometimes distributed to remote banks





Shared Cache have Longer Access Times

• Remember this picture?





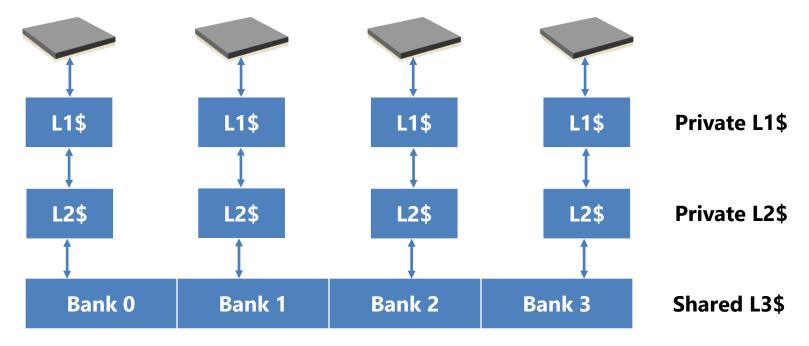
Impact of Shared Cache

- AMAT = hit time + (miss rate × miss penalty)
- Impact of shared cache on miss rate:
 - Smaller miss rate due to more flexible use of space
- Impact of shared cache on hit time:
 - Longer hit time due to sometimes having to access remote banks
- L1 caches are almost always private
 - Hit time is important for L1. Cannot afford access to remote banks.
- L3 (last level) caches are almost always shared
 - Reducing miss rate is top priority to avoid DRAM access.



Cache Organization of Broadwell CPU

• This is the cache organization of Broadwell used in our Linux server



Intel rebrands the shared cache as the "Smart Cache"



Cache Design Parameter 10: Prefetching



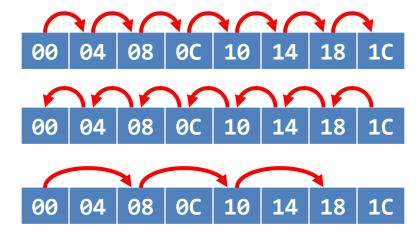
Prefetching

- Prefetching: fetching data that is expected to be needed soon
 - Allows you to hide the latency of fetching that data
 - o E.g. Web browsers prefetch resources from not-yet-clicked links
 - → when user later clicks on link, response is almost instantaneous
 - o Caches also prefetch data that is expected to be used soon
 - Can be used to avoid even cold misses
- Two ways prefetching can happen:
 - o Compiler-driven: compiler emits prefetch instructions
 - Can manually insert one in C program: __builtin_prefetch(addr)
 - Or rely on compiler to insert them using heuristics
 - Hardware-driven: CPU prefetcher emits prefetches dynamically
 - Relies on prefetcher to detect a pattern in memory accesses



Hardware Prefetching

- What do you notice about both these snippets of code?
- They both access memory **sequentially.** for(i = 0 .. 100000)
 - The first one data, the next instructions.
 A[i]++;
- These kinds of access patterns are very common.



Sequential

Reverse sequential

Strided sequential (think "accessing one field from each item in an array of structs")

00 **l**w

04 lw

08 **l**w

0C addi 10 sub

14 mul

18 SW

1C SW

20 sw



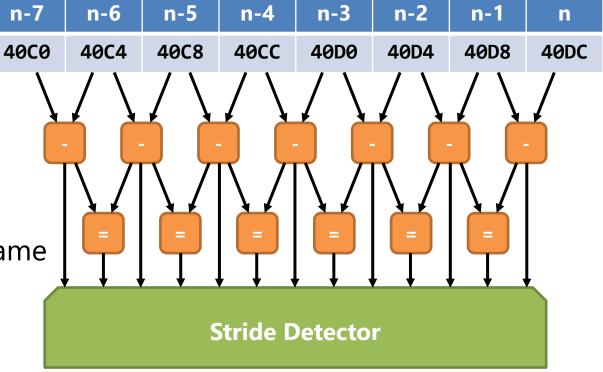
Hardware Prefetching Stride Detection

- What kinds of things would you need?
- A table of the last *n* memory accesses would be a good start.

 Some subtractors to calculate the stride

 Some comparators to see if strides are the same

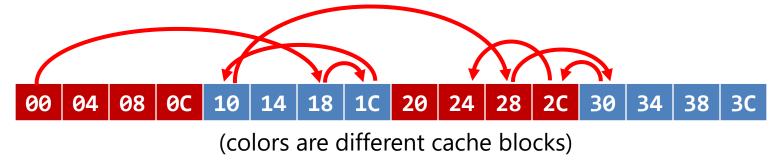
Some detection logic





Where Hardware Prefetching Doesn't Work

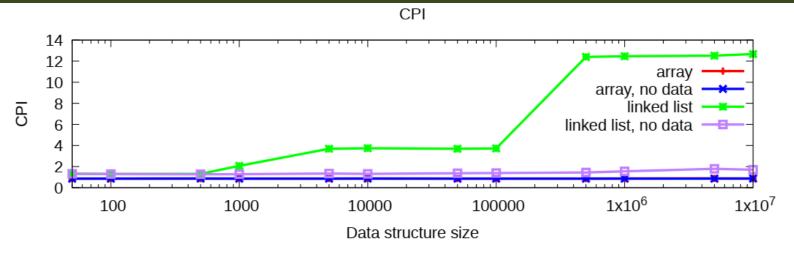
- Sequential accesses are where prefetcher works best
 - o E.g. Iterating over elements of an array
- Some accesses don't have a pattern or is too **complex** to detect
 - o At below is how a typical linked-list traversal looks like



- Other pointer-chasing data structures (graphs, trees) look similar
- Can only rely on naturally occurring locality to avoid misses
- o Or, have compiler insert prefetch instructions in middle of traversal



Mystery Solved



- How come Array performed well for even an array 1.28 GB large?
 - No spatial locality since each node takes up two 64-byte cache blocks
 - No temporal locality since working set of 1.28 GB exceeds any cache
- The answer is: Array had the benefit of a strided prefetcher!
 - Access pattern of Linked List was too complex for prefetcher to detect



Impact of Prefetching

- Prefetcher runs in parallel with the rest of the cache hardware
 - Does not slow down any on-demand reads or writes
- What if prefetcher is wrong? It can be wrong in two ways:
 - It fetched a block that was never going to be used
 - o It fetched a useful block but fetched it too soon or too late
 - Too soon: the block gets evicted before it can be used
 - Too late: the prefetch doesn't happen in time for the access
- A bad prefetch results in cache pollution
 - Unused data is fetched, potentially pushing out other useful data
- On the other hand, good prefetches can reduce misses drastically!

