The Golden Age of Computer Architecture

Hung-Wei Tseng

Recap: 4Cs of cache misses

- 3Cs:
  - Compulsory, Conflict, Capacity
- Coherency miss:
  - A “block” invalidated because of the sharing among processors.
- True sharing
  - Processor A modifies X, processor B also want to access X.
- False sharing
  - Processor A modifies X, processor B also want to access Y. However, Y is invalidated because X and Y are in the same block!

Performance comparison

- Comparing implementations of thread_vadd — L and R, please identify which one will be performing better and why

Version L

```
void *threaded_vadd(void *thread_id)
{
  int tid = *(int *)thread_id;
  int i;
  for(i=tid;i<ARRAY_SIZE;i+=NUM_OF_THREADS)
  {
        c[i] = a[i] + b[i];
  }
  return NULL;
}
```

Version R

```
void *threaded_vadd(void *thread_id)
{
  int tid = *(int *)thread_id;
  int i;
  for(i=tid*(ARRAY_SIZE/NUM_OF_THREADS);i<(tid+1)*(ARRAY_SIZE/NUM_OF_THREADS);i++)
  {
      c[i] = a[i] + b[i];
  }
  return NULL;
}
```

A. L is better, because the cache miss rate is lower
B. R is better, because the cache miss rate is lower
C. L is better, because the instruction count is lower
D. R is better, because the instruction count is lower
E. Both are about the same

Main thread

```
for(i = 0 ; i < NUM_OF_THREADS ; i++)
{
  tids[i] = i;
  pthread_create(&thread[i], NULL, threaded_vadd, &tids
}
for(i = 0 ; i < NUM_OF_THREADS ; i++)
  pthread_join(thread[i], NULL);
```

Again — how many values are possible?

- Consider the given program. You can safely assume the caches are coherent. How many of the following outputs will you see?

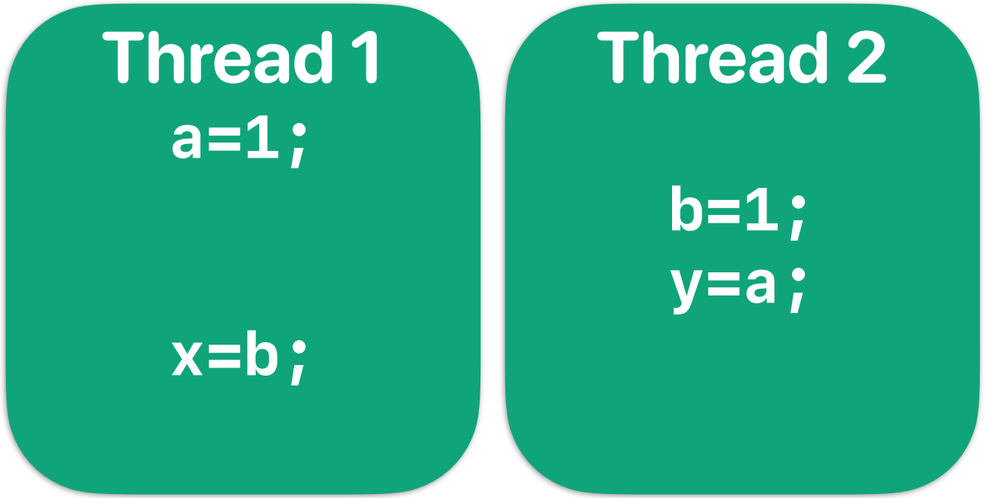
① (0, 0)
② (0, 1)
③ (1, 0)
④ (1, 1)

A. 0
B. 1
C. 2
D. 3
E. 4

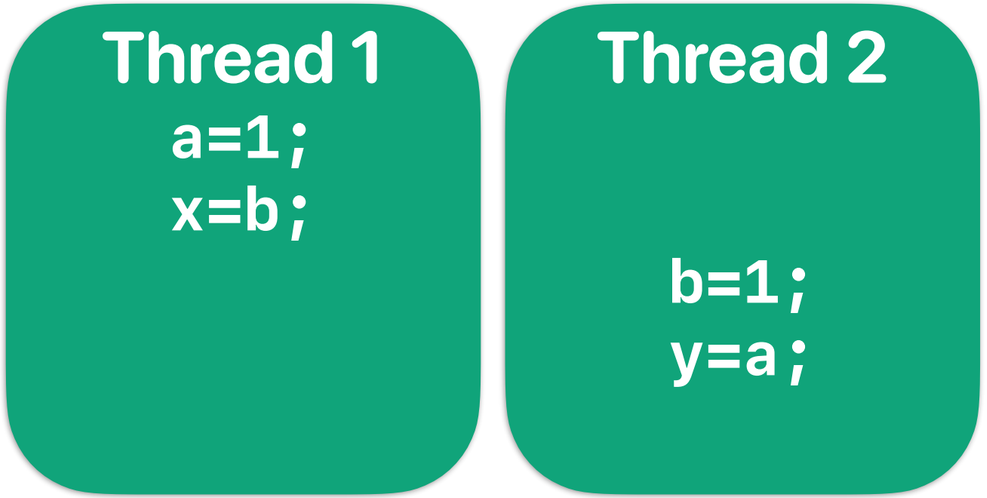
```c
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>
#include <unistd.h>

volatile int a,b;
volatile int x,y;
volatile int f;
void* modifya(void *z) {
  a=1;
  x=b;
  return NULL;
}
void* modifyb(void *z) {
  b=1;
  y=a;
  return NULL;
}
```

```c
int main() {
  int i;
  pthread_t thread[2];
  pthread_create(&thread[0], NULL, modifya, NULL);
  pthread_create(&thread[1], NULL, modifyb, NULL);
  pthread_join(thread[0], NULL);
  pthread_join(thread[1], NULL);
  fprintf(stderr,"(%d, %d)\n",x,y);
  return 0;
}
```

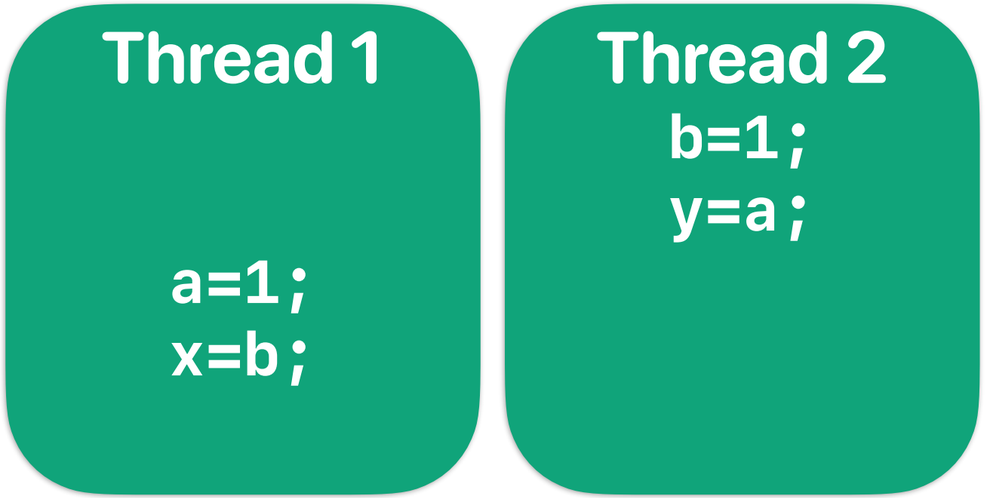
Possible scenarios



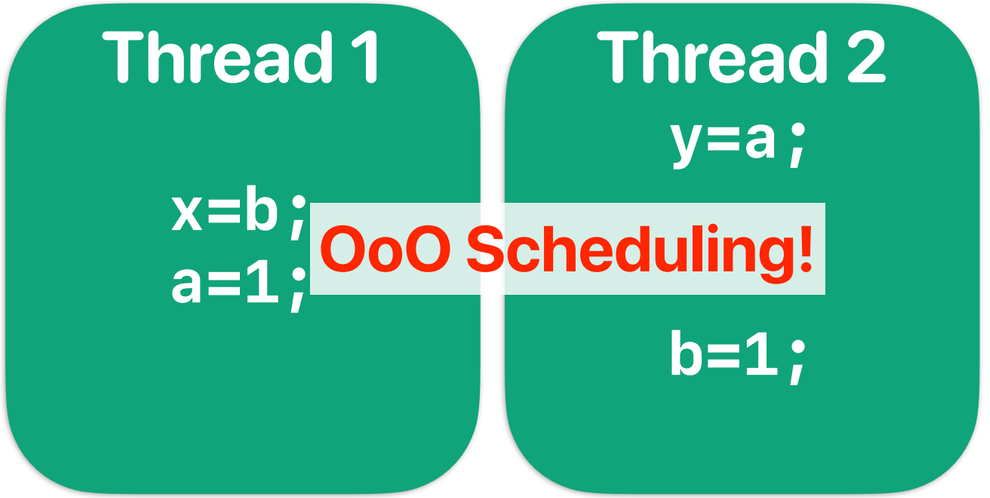
(1,1)



(0,1)



(1,0)



(0,0)

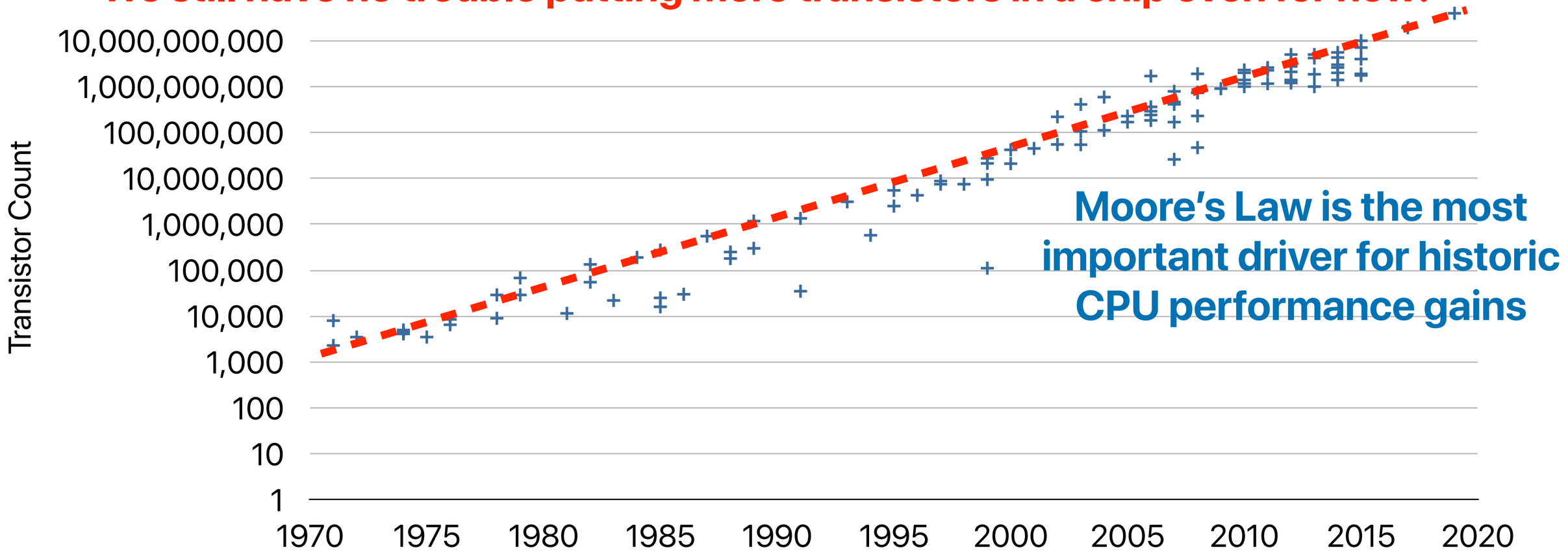
Take-aways of parallel programming

- Processor behaviors are non-deterministic
  - You cannot predict which processor is going faster
  - You cannot predict when OS is going to schedule your thread
- Cache coherency only guarantees that everyone would eventually have a coherent view of data, but not when
- Cache consistency is hard to support

Moore's Law[(1)] is still alive

- The number of transistors we can build in a fixed area of silicon doubles every 12 ~ 24 months.

We still have no trouble putting more transistors in a chip even for now!



(1) Moore, G. E. (1965), 'Cramming more components onto integrated circuits', Electronics 38 (8) .

Plot based on https://en.wikipedia.org/wiki/Transistor_count by Hung-Wei Tseng

Recap: Power consumption to light on all transistors

Chip

1	1	1	1	1	1	1
1	1	1	1	1	1	1
1	1	1	1	1	1	1
1	1	1	1	1	1	1
1	1	1	1	1	1	1
1	1	1	1	1	1	1
1	1	1	1	1	1	1

=49W

Dennardian Scaling

Chip

0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5
0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5	0.5

=50W

Dennardian Broken

Chip

1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1

On ~ 50W

Off ~ 0W

Dark!

=100W!

Outline

- Dark silicon and the Golden Age of Computer Architecture

Solutions/trends in dark silicon era

Trends in the Dark Silicon Era

- Aggressive dynamic voltage/frequency scaling
- Throughout oriented — slower, but more
- Just let it dark — activate part of circuits, but not all
- From general-purpose to domain-specific — ASIC

Aggressive dynamic frequency scaling

Modern processor's frequency

```
NUMA node(s):                    1
Vendor ID:                       GenuineIntel
CPU family:                      6
Model:                           151
Model name:                      12th Gen Intel(R) Core(TM) i7-12700KF
Stepping:                        2
CPU MHz:                         1226.409
CPU max MHz:                     5000.0000
CPU min MHz:                     800.0000
BogoMIPS:                        7219.20
```

	i7-12700K
	Intel 7
	$450.00 - $460.00
	PC/Client/Tablet, Workstation

CPU Specifications

Total Cores	12
# of Performance-cores	8
# of Efficient-cores	4
Total Threads	20
Max Turbo Frequency	5.00 GHz
Intel® Turbo Boost Max Technology 3.0 Frequency ‡	5.00 GHz
Performance-core Max Turbo Frequency	4.90 GHz
Efficient-core Max Turbo Frequency	3.80 GHz
Performance-core Base Frequency	3.60 GHz
Efficient-core Base Frequency	2.70 GHz
Cache	25 MB Intel® Smart Cache

https://www.intel.com/content/www/us/en/products/sku/134594/intel-core-i712700k-processor-25m-cache-up-to-5-00-ghz/specifications.html

Modern processor's frequency

```
Architecture:                    x86_64
CPU op-mode(s):                  32-bit, 64-bit
Byte Order:                      Little Endian
Address sizes:                   48 bits physical, 48 bits virtual
CPU(s):                          12
On-line CPU(s) list:             0-11
Thread(s) per core:              2
Core(s) per socket:              6
Socket(s):                       1
NUMA node(s):                    1
Vendor ID:                       AuthenticAMD
CPU family:                      25
Model:                           80
Model name:                      AMD Ryzen 5 5500
Stepping:                        0
Frequency boost:                 enabled
CPU MHz:                         3600.000
CPU max MHz:                     3600.0000
CPU min MHz:                     1400.0000
```

Dynamic/Active Power

- The power consumption due to the switching of transistor states
- Dynamic power per transistor

  $P_{dynamic} \sim \alpha \times C \times V^2 \times f \times N$

  - α: average switches per cycle
  - C: capacitance
  - V: voltage
  - f: frequency, usually linear with V
  - N: the number of transistors

Recap: Demo — changing the max frequency and performance

- Change the maximum frequency of the intel processor — you learned how to do this when we discuss programmer's impact on performance
- LIKWID a profiling tool providing power/energy information
  - likwid-perfctr -g ENERGY [command_line]
  - Let's try blockmm and popcount and see what's happening!

Slower, but more

Single-ISA Heterogeneous Multi-Core Architectures: The Potential for Processor Power Reduction

Rakesh Kumar, Keith I. Farkas*, Norman P. Jouppi*, Parthasarathy Ranganathan*, Dean M. Tullsen

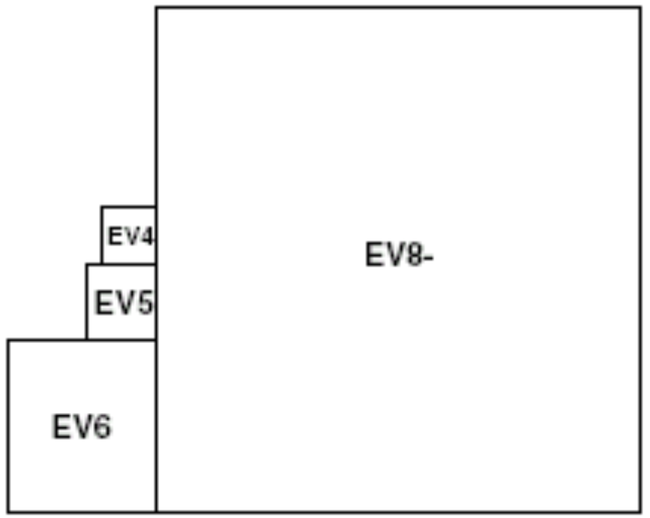
UCSD and HP Labs*

In the 36th Annual IEEE/ACM International Symposium on Microarchitecture, 2003. MICRO-36., 2003
MICRO Test-of-time award, 2021

Areas of different processor generations

- You fit about 5 EV5 cores within the same area of an EV6
- If you build a quad-core EV6, you can use the same area to
  - build 20-core EV5
  - 3EV6+5EV5

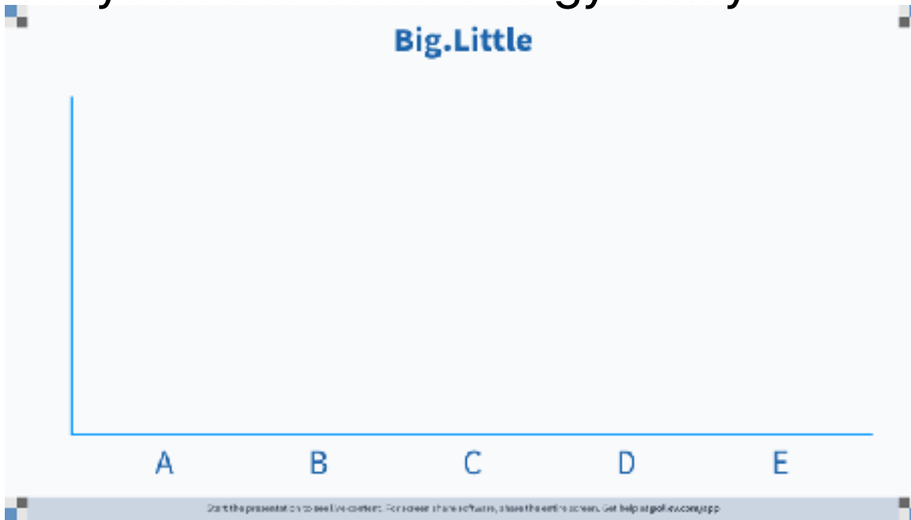
Processor	EV5	EV6	EV6+
Issue-width	4	6 (OOO)	6 (OOO)
I-Cache	8KB, DM	64KB, 2-way	64KB, 2-way
D-Cache	8KB, DM	64KB, 2-way	64KB, 2-way
Branch Pred.	2K-gshare	hybrid 2-level	hybrid 2-level
Number of MSHRs	4	8	16
Number of threads	1	1	4
Area (in mm^2)	5.06	24.5	29.9



Single ISA heterogeneous CMP

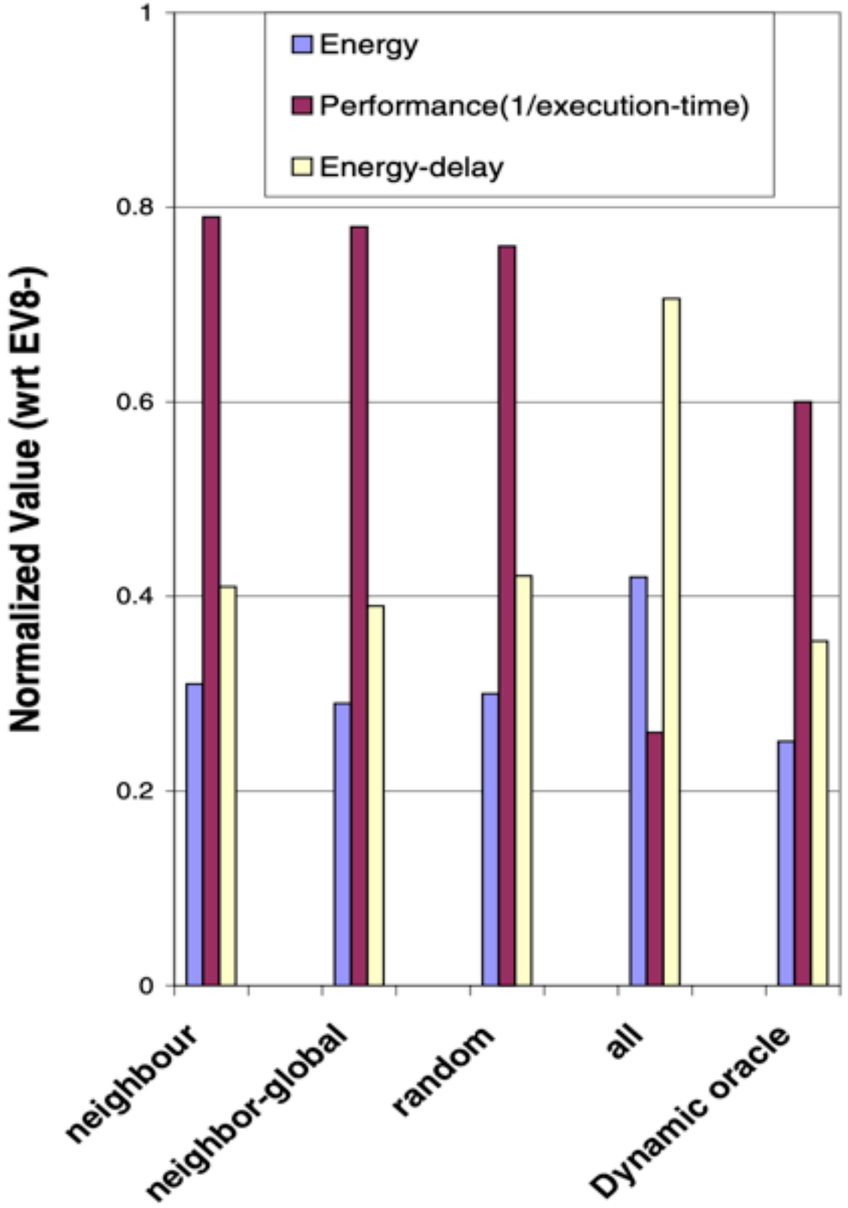
- Regarding "Single-ISA Heterogeneous Multi-Core Architectures", how many of the following statements is/are correct?
  - ① You need to recompile and optimize the binary for each core architecture to exploit the thread-level parallelism in this architecture
  - ② For a program with limited thread-level parallelism, single ISA heterogeneous CMP would deliver better or at least the same level of performance than homogeneous CMP
  - ③ For a program with rich thread-level parallelism, single ISA heterogeneous CMP would deliver better or at least the same level of performance than homogeneous CMP built with older-generation cores
  - ④ Spending more instructions on older-generation cores would always lead to better energy-delay

  A. 0
  B. 1
  C. 2
  D. 3
  E. 4



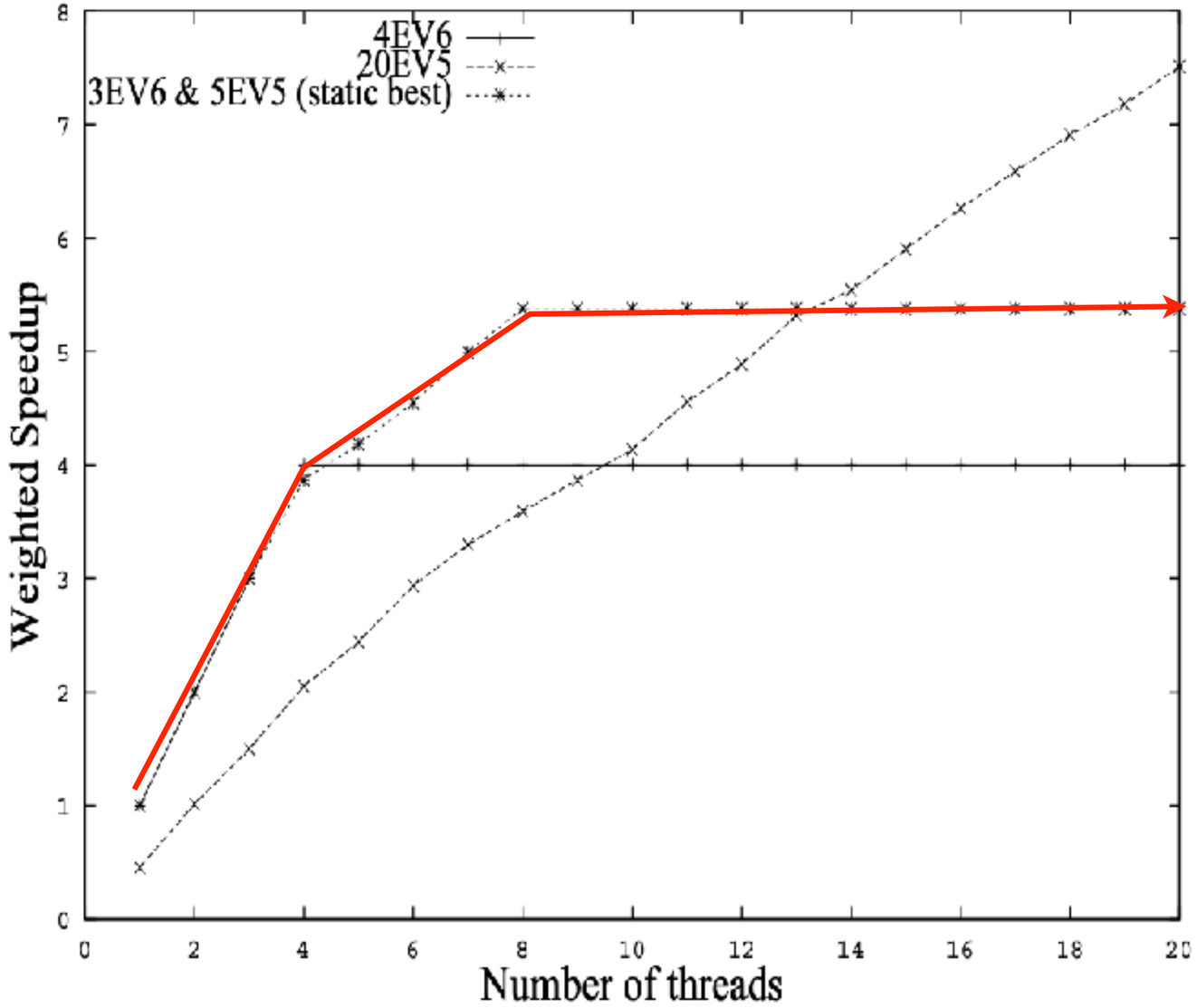
Energy-delay

- Energy * delay = Power * ET * ET = Power * ET^2

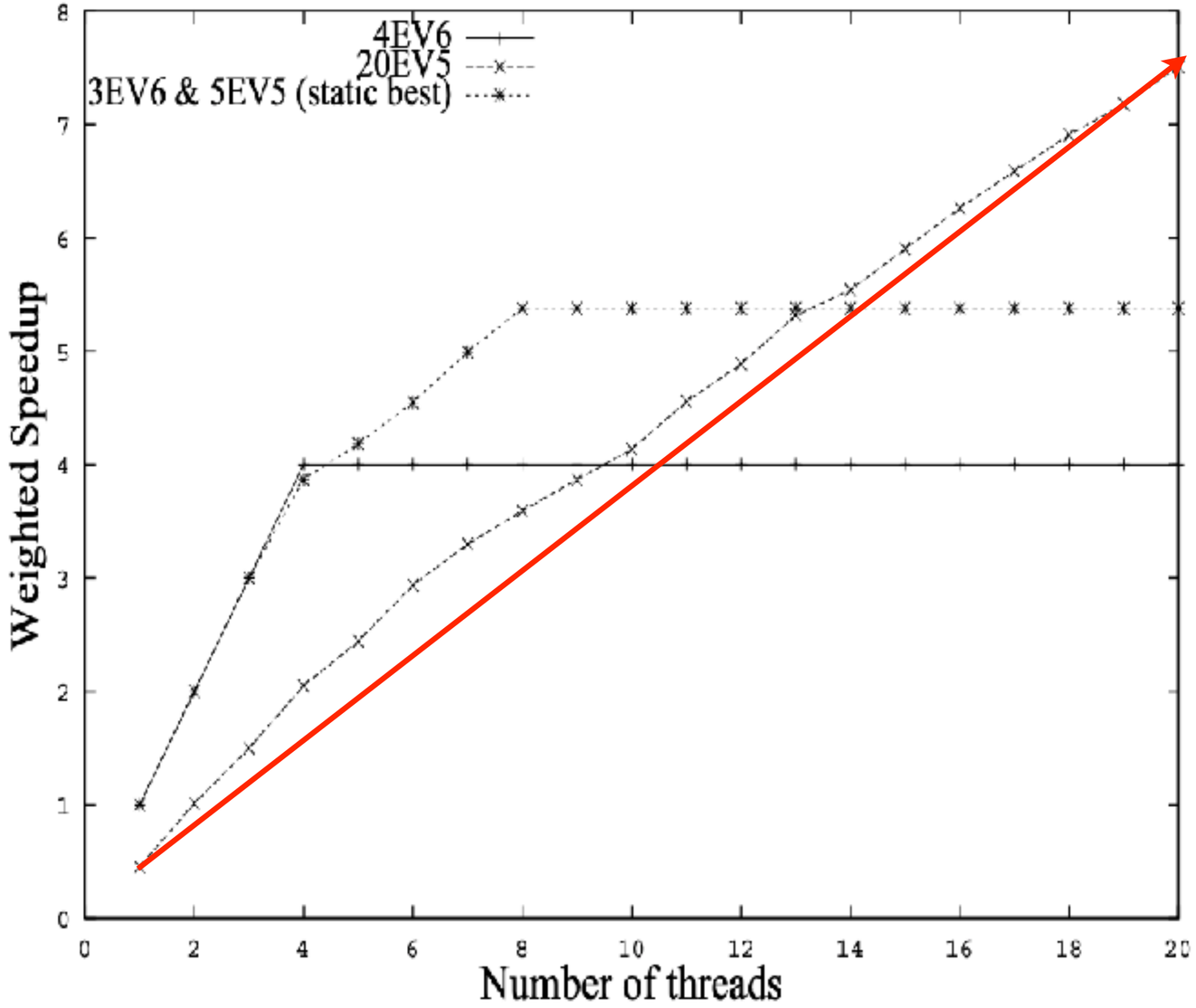


Benchmark	Total switches	% of instructions per core				Energy Savings(%)	ED Savings(%)	ED^2 Savings(%)	Perf. Loss (%)
		EV4	EV5	EV6	EV8-				
ammp	0	0	0	0	100	0	0	0	0
applu	27	2.2	0.1	54.5	43.2	42.7	38.6	33.6	7.1
apsi	2	0	0	62.2	37.8	27.6	25.3	22.9	3.1
art	0	0	0	100	0	74.4	73.5	72.6	3.3
equake	20	0	0	97.9	2.1	72.4	71.3	70.1	3.9
fma3d	0	0	0	0	100	0	0	0	0
wupwise	16	0	0	99	1	72.6	69.9	66.2	10.0
bzip	13	0	0.1	84.0	15.9	40.1	38.7	37.2	2.3
crafty	0	0	0	0	100	0	0	0	0
eon	0	0	0	100	0	77.3	76.3	75.3	4.2
gzip	82	0	0	95.9	4.1	74.0	73.0	71.8	3.9
mcf	0	0	0	0	100	0	0	0	0
twolf	0	0	0	0	100	0	0	0	0
vortex	364	0	0	73.8	26.2	56.2	51.9	46.2	9.8
Average	1(median)	0.2%	0%	54.8%	45.0%	38.5%	37.0%	35.4%	3.4%

4EV6 v.s. 20 EV5 v.s. 3EV6+5EV5



4EV6 v.s. 20 EV5 v.s. 3EV6+5EV5



Demo

- We can use taskset command in linux to control the task allocation.
- Core i7 12700K is a processor with big.Little architecture

Processor Number	i7-12700K
Status	Launched
Launch Date	Q4'21
Lithography	Intel 7
Recommended Customer Price	$450.00 - $460.00
Use Conditions	PC/Client/Tablet, Workstation

CPU Specifications

Total Cores	12
# of Performance-cores	8
# of Efficient-cores	4

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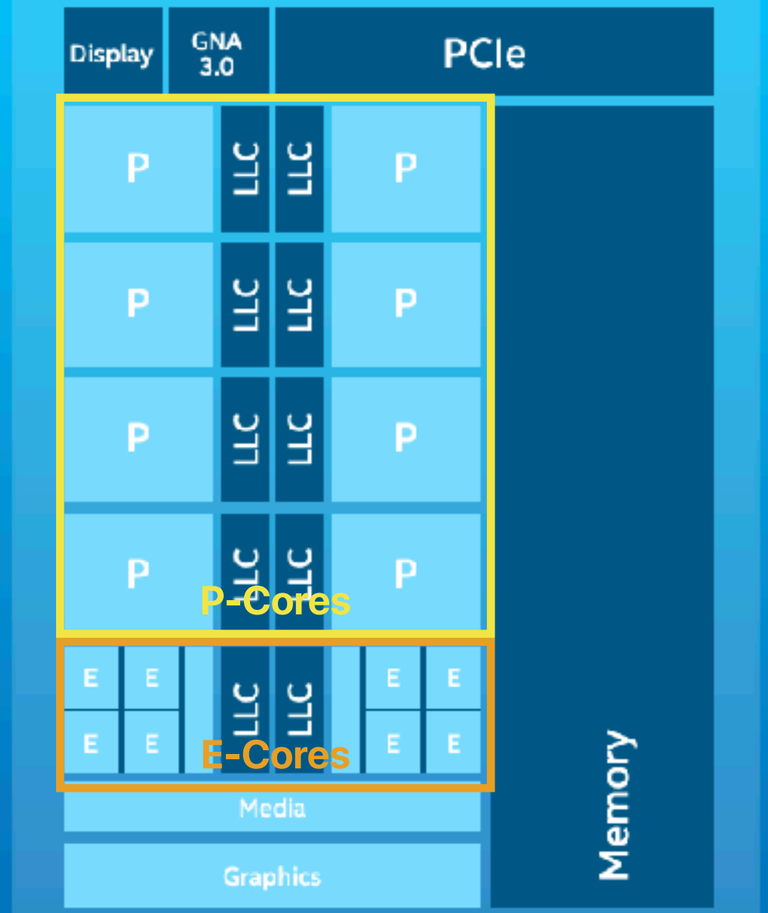
  - ③ For a program with rich thread-level parallelism, single ISA heterogeneous CMP would deliver better or at least the same level of performance than homogeneous CMP built with older-generation cores
  - ④ Spending more instructions on older-generation cores would always lead to better energy-delay

  A. 0
  B. 1
  C. 2
  D. 3
  E. 4

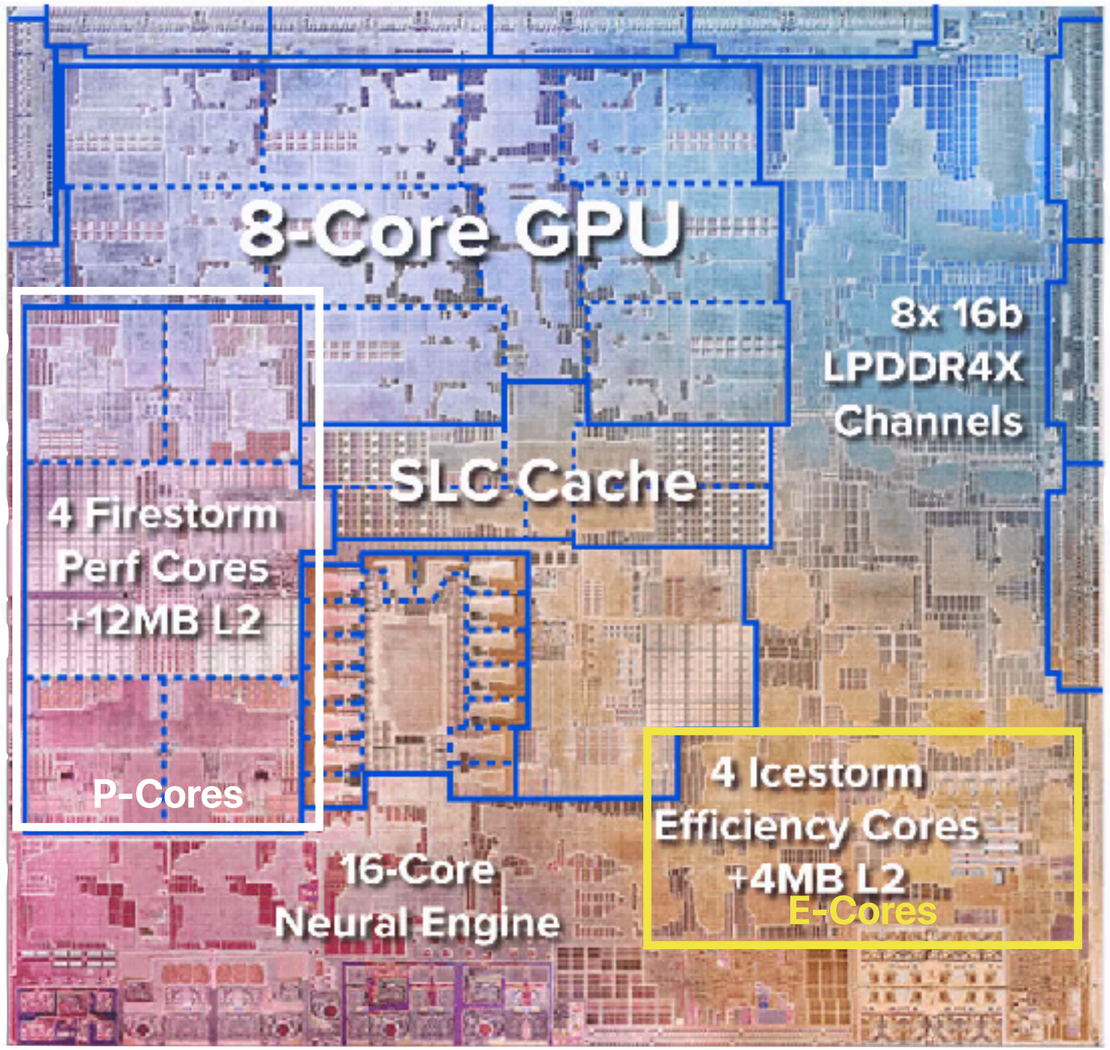
Single ISA heterogeneous CMP in Intel Processors



In a game-changing advance for core performance, 12th Gen Intel® Core™ desktop processors power a revolutionary approach to the x86 architecture. Its Performance-cores—or "P-cores"—are optimized for single & lightly-threaded performance, while its Efficient-cores—or "E-cores"—are optimized for scaling highly-threaded workloads. Intel® Thread Director helps to monitor and analyze performance data in real-time to seamlessly place the right application thread on the right core and optimize performance per watt.[1] That means gamers, creators, and professionals can harness both intelligence and power to enhance the experiences that matter most.

https://download.intel.com/newsroom/2021/client-computing/12th-gen-processor-product-brief.pdf

Single ISA heterogeneous CMP in Apple's M1



https://www.toptal.com/apple/apple-m1-processor-compatibility-overview

More cores per chip, slower per core

Export comparison	Intel® Xeon® Platinum 849...	Intel® Xeon® Platinum 846...	Intel® Xeon® Gold 6448H ...	Intel® Xeon® Platinum 844...	Intel® Xeon® Gold 6434H ...
Total Cores	60	48	32	16	8
Total Threads	120	96	64	32	16
Max Turbo Frequency	3.50 GHz	3.80 GHz	4.10 GHz	4.00 GHz	4.10 GHz
Processor Base Frequency	1.90 GHz	2.10 GHz	2.40 GHz	2.90 GHz	3.70 GHz
Cache	112.5 MB	105 MB	60 MB	45 MB	22.5 MB
Intel® UPI Speed	16 GT/s	16 GT/s	16 GT/s	16 GT/s	16 GT/s
Max # of UPI Links	4	4	3	4	3
TDP	350 W	330 W	250 W	270 W	195 W

https://ark.intel.com/content/www/us/en/ark/products/series/228622/4th-generation-intel-xeon-scalable-processors.html

Xeon Phi

Essentials

Product Collection	Intel® Xeon Phi™ 72x5 Processor Family
Code Name	Products formerly Knights Mill
Vertical Segment	Server
Processor Number	7295
Off Roadmap	No
Status	Launched
Launch Date	Q4'17
Lithography	14 nm

Performance

# of Cores	72
# of Threads	72
Processor Base Frequency	1.50 GHz
Max Turbo Frequency	1.50 GHz
Cache	36 MB L2 Cache
TDP	320 W

Static/Leakage Power

- The power consumption due to leakage — transistors do not turn all the way off during no operation
- Becomes the **dominant** factor in the most advanced process technologies.

$P_{leakage} \sim N \times V \times e^{-V_t}$

How about static power?

- N: number of transistors
- V: voltage
- V_t: threshold voltage where transistor conducts (begins to switch)

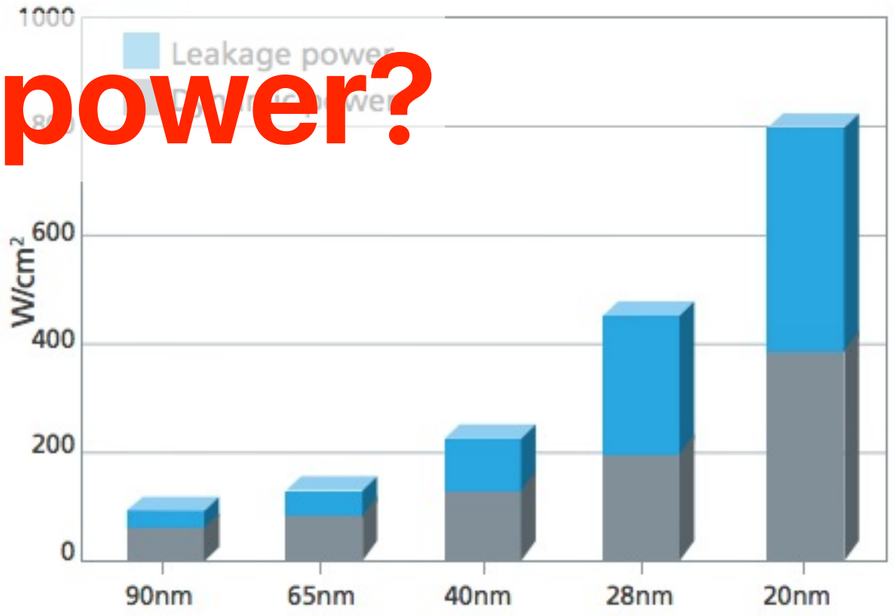
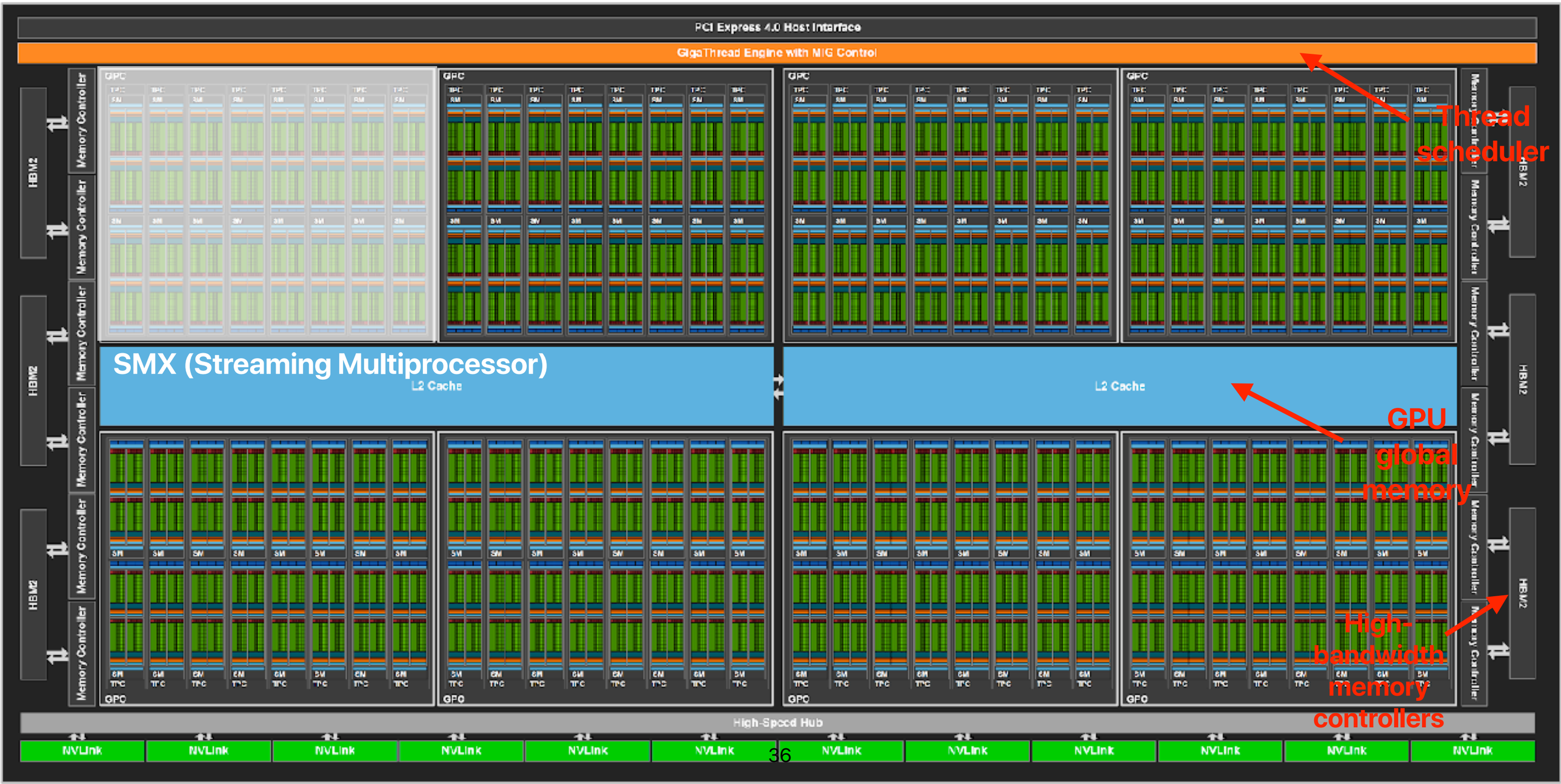


Figure 1: Leakage power becomes a growing problem as demands for more performance and functionality drive chipmakers to nanometer-scale process nodes (Source: IBS).

Just let it dark

https://developer.nvidia.com/blog/nvidia-ampere-architecture-in-depth/

The rise of GPU



Inside an SM

A total of 16*4 = 64 FP32 cores
A total of 16*4 = 64 INT32 cores
A total of 16*4 = 16 FP64 cores

- All of these can only perform the same operation at the same time, but each of these is named as a "thread" in CUDA
- You can only use either FP32, FP64, INT32 and "Tensor Cores" at the same time

Programming in Turing Architecture

Use tensor cores

```
cublasErrCheck(cublasSetMathMode(cublasHandle, CUBLAS_TENSOR_OP_MATH));
```

Make them 16-bit

```
convertFp32ToFp16 <<< (MATRIX_M * MATRIX_K + 255) / 256, 256 >>> (a_fp16, a_fp32,
MATRIX_M * MATRIX_K);
   convertFp32ToFp16 <<< (MATRIX_K * MATRIX_N + 255) / 256, 256 >>> (b_fp16, b_fp32,
MATRIX_K * MATRIX_N);
```

```
cublasErrCheck(cublasGemmEx(cublasHandle, CUBLAS_OP_N, CUBLAS_OP_N,
                 MATRIX_M, MATRIX_N, MATRIX_K,
                 &alpha,
                 a_fp16, CUDA_R_16F, MATRIX_M,
                 b_fp16, CUDA_R_16F, MATRIX_K,
                 &beta,
                 c_cublas, CUDA_R_32F, MATRIX_M,
                 CUDA_R_32F, CUBLAS_GEMM_DFALT_TENSOR_OP));
```

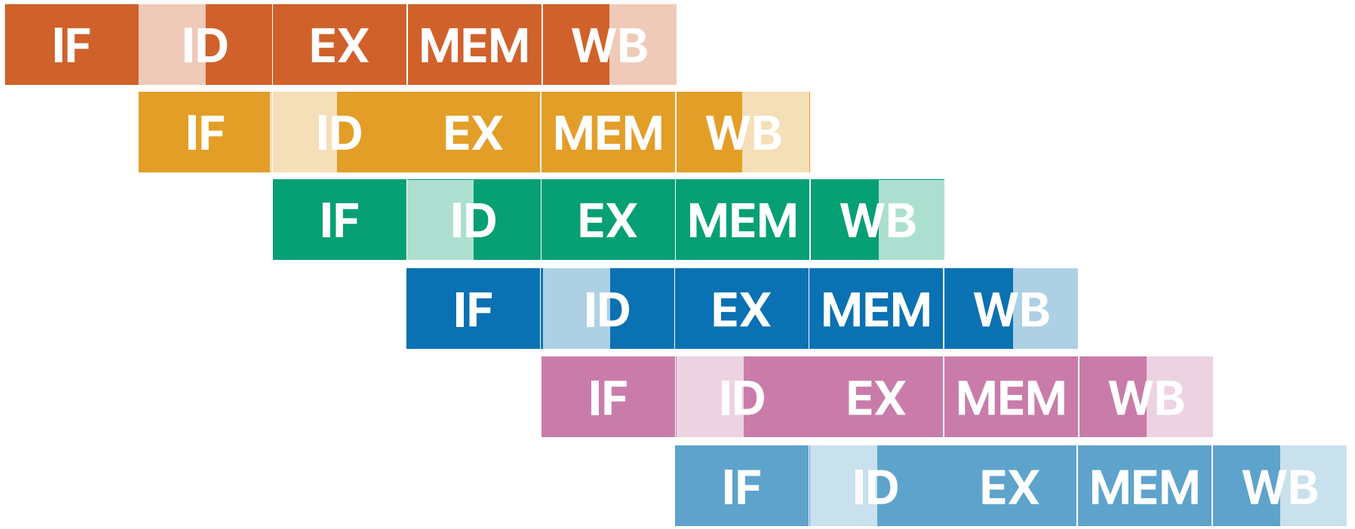
call Gemm

The Rise of ASICs/Accelerators

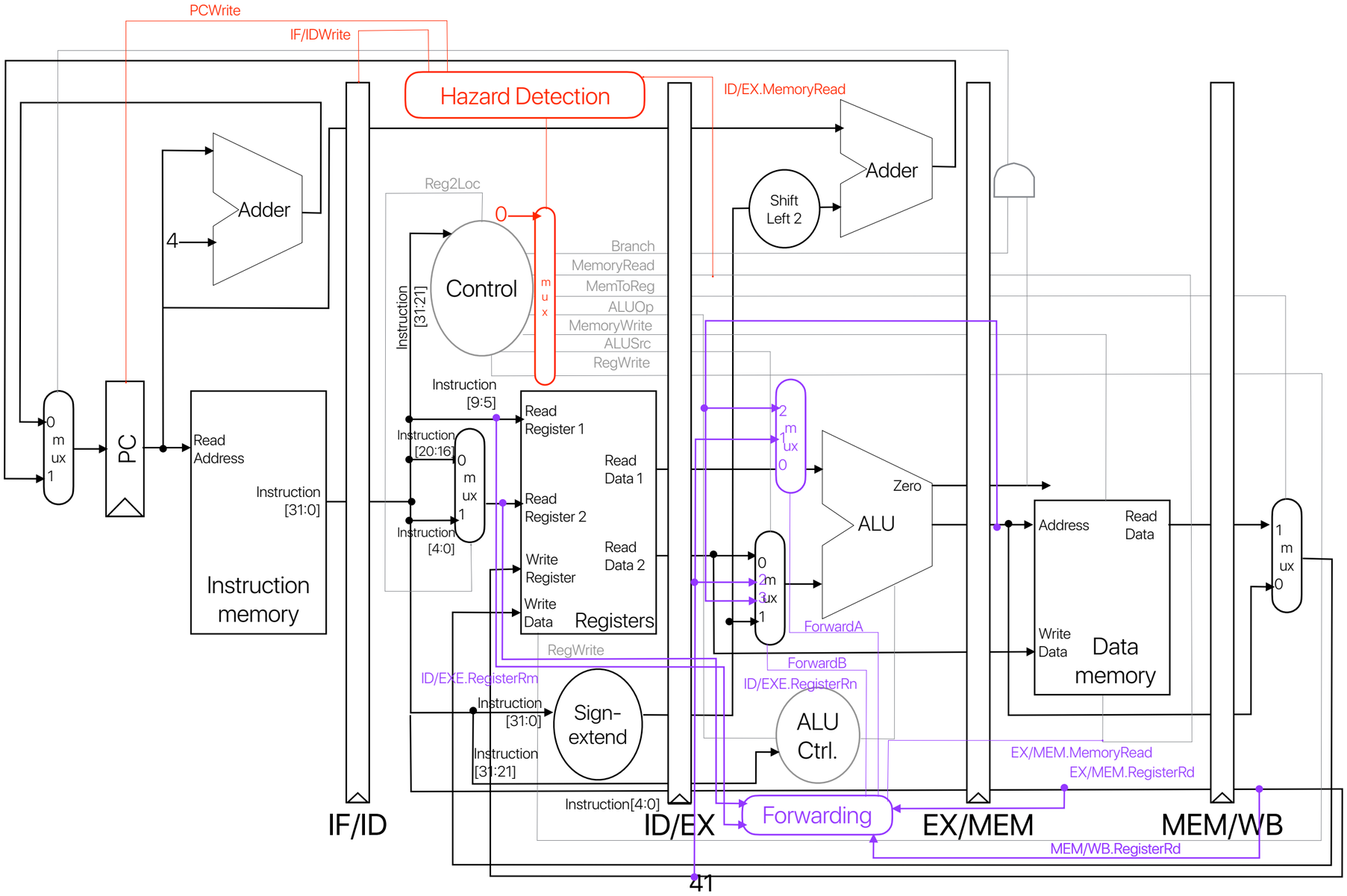
Say, we want to implement a[i] += a[i+1]*20

- This is what we need in RISC-V in each iteration

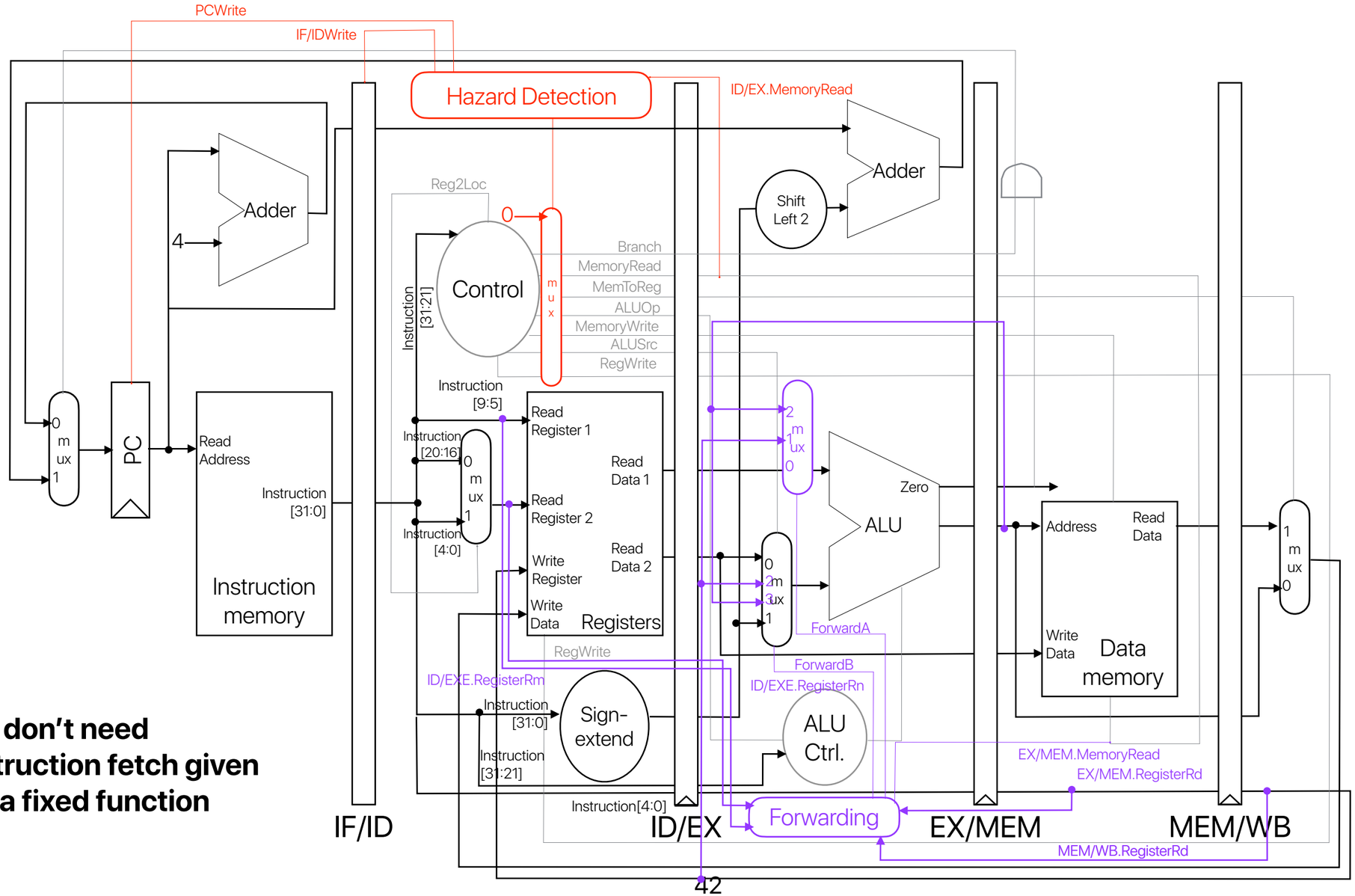
```
ld    X1, 0(X0)
ld    X2, 8(X0)
add   X3, X31, #20
mul   X2, X2, X3
add   X1, X1, X2
sd    X1, 0(X0)
```



This is what you need for these instructions



Specialize the circuit

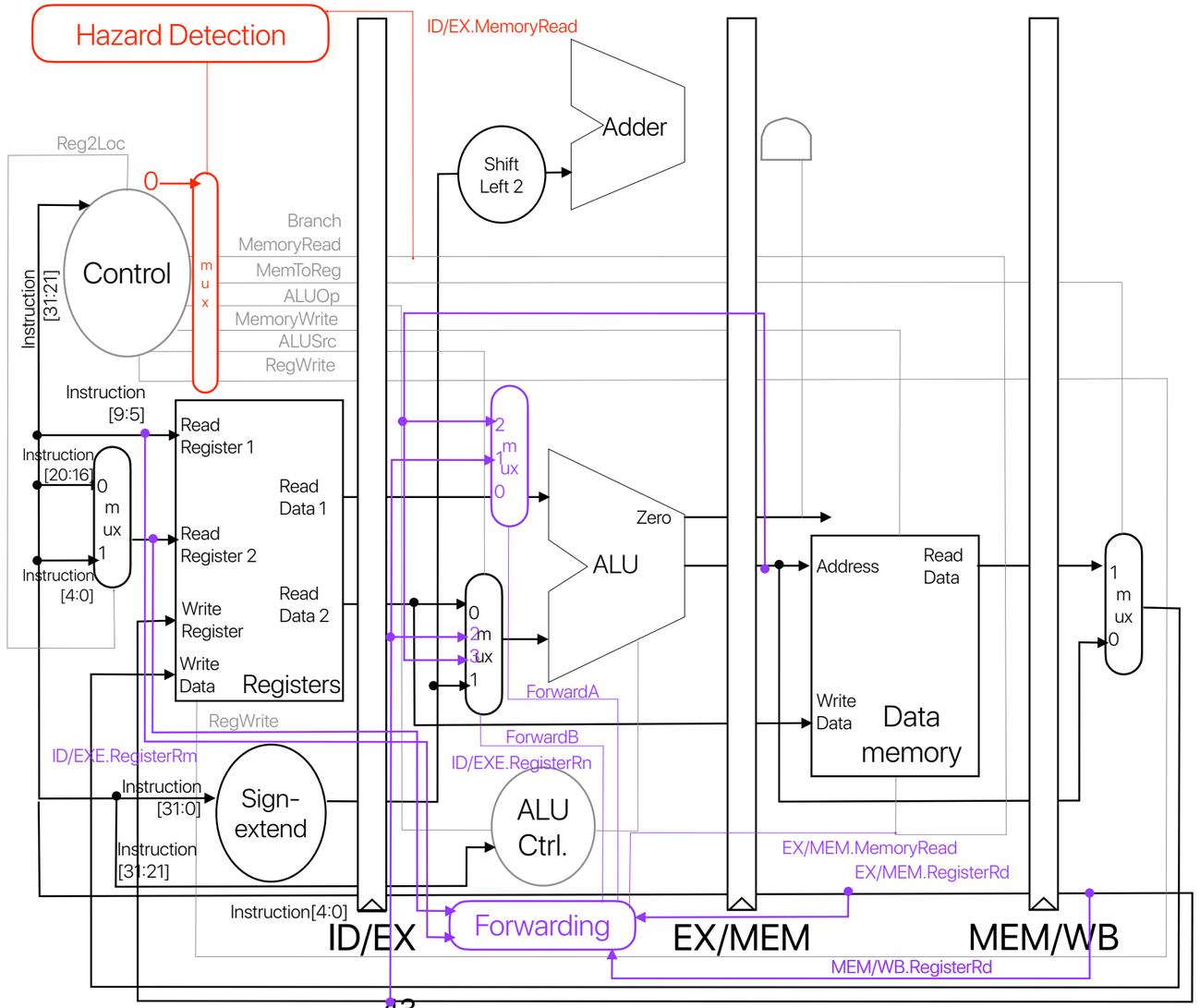


We don't need instruction fetch given it's a fixed function

Specialize the circuit

We don’t need these many registers, complex control, decode

We don’t need instruction fetch given it’s a fixed function

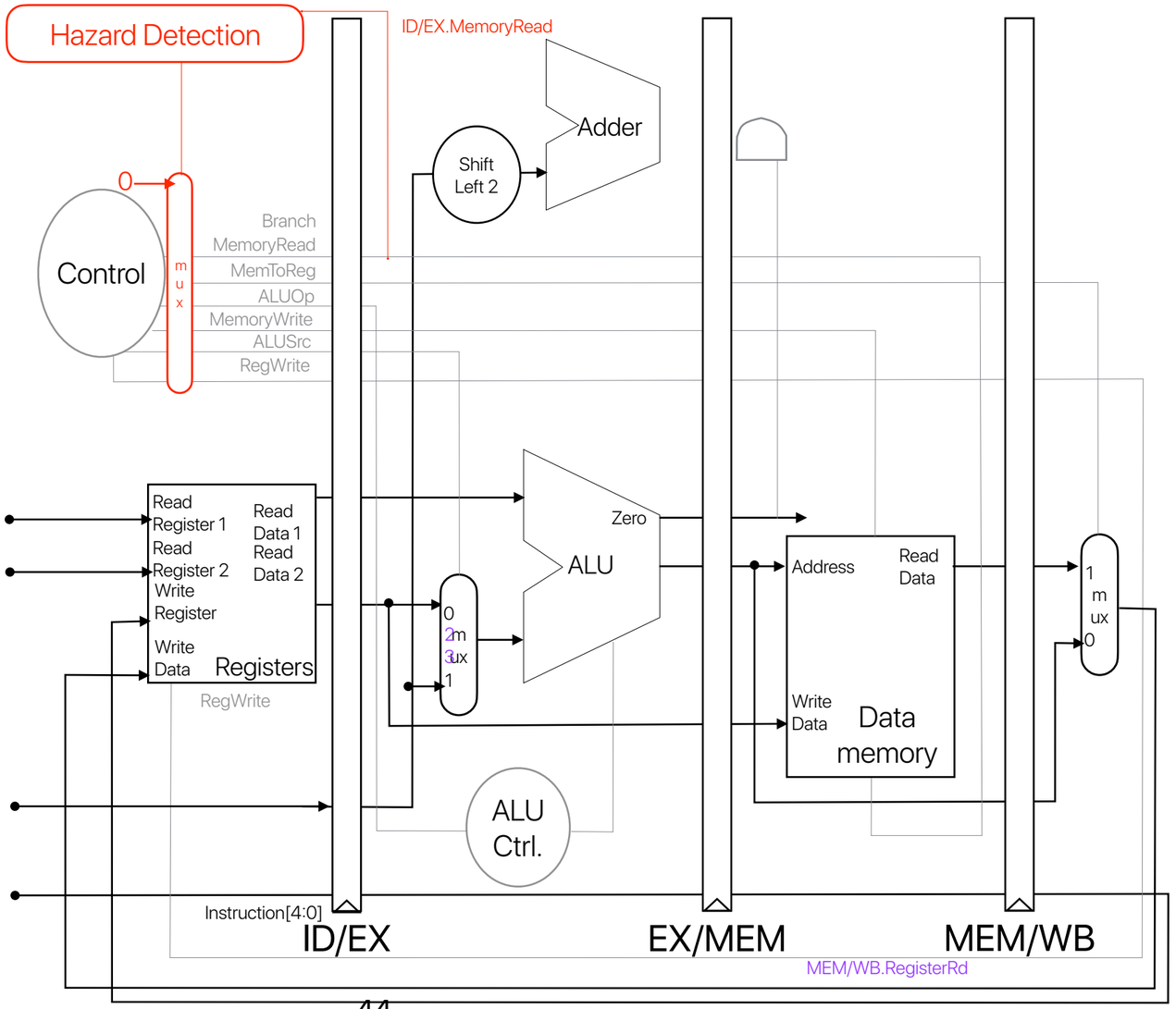


Specialize the circuit

We don't need ALUs, branches, hazard detections…

We don't need these many registers, complex control, decode

We don't need instruction fetch given it's a fixed function

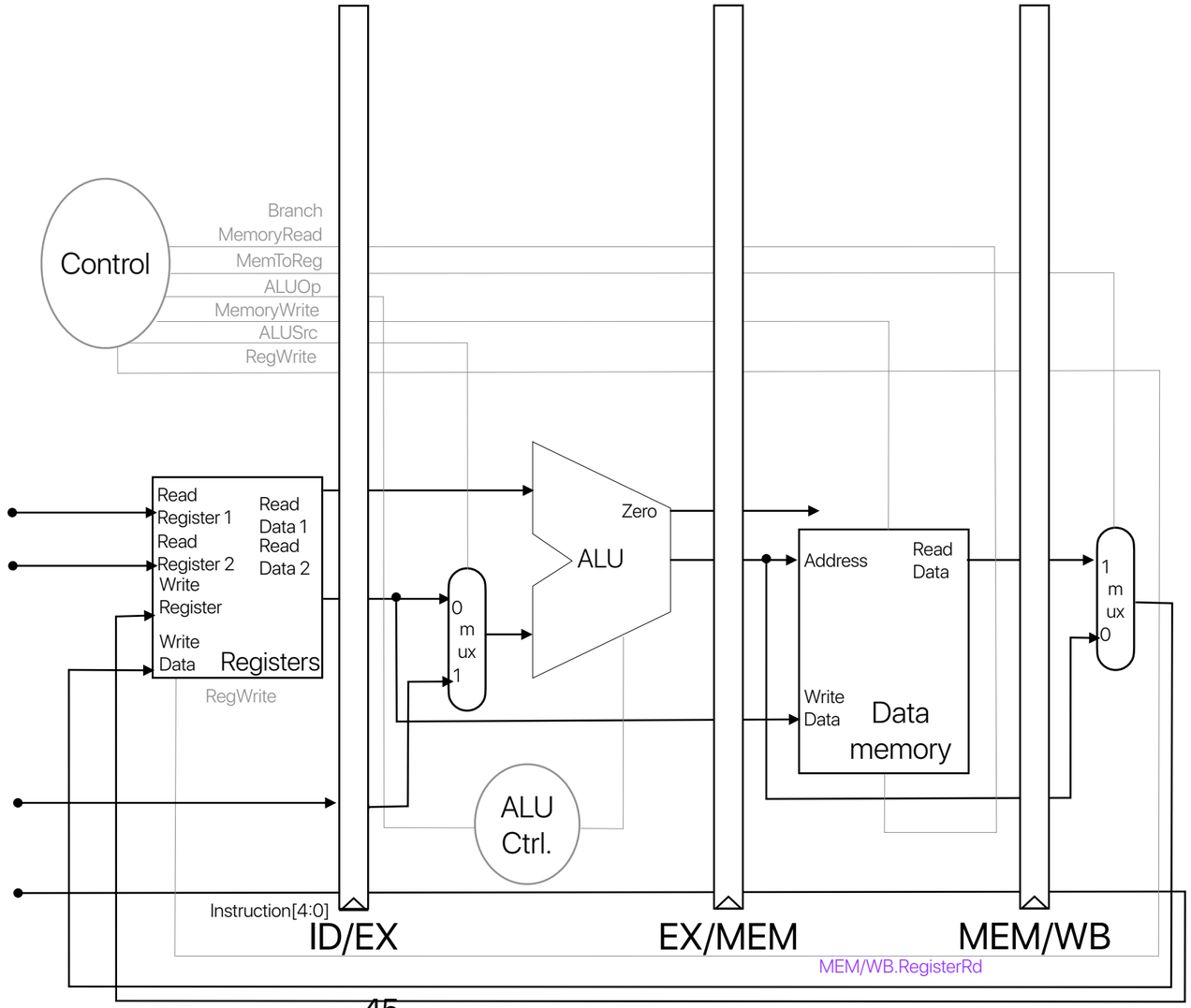


Specialize the circuit

We don’t need big ALUs, branches, hazard detections…

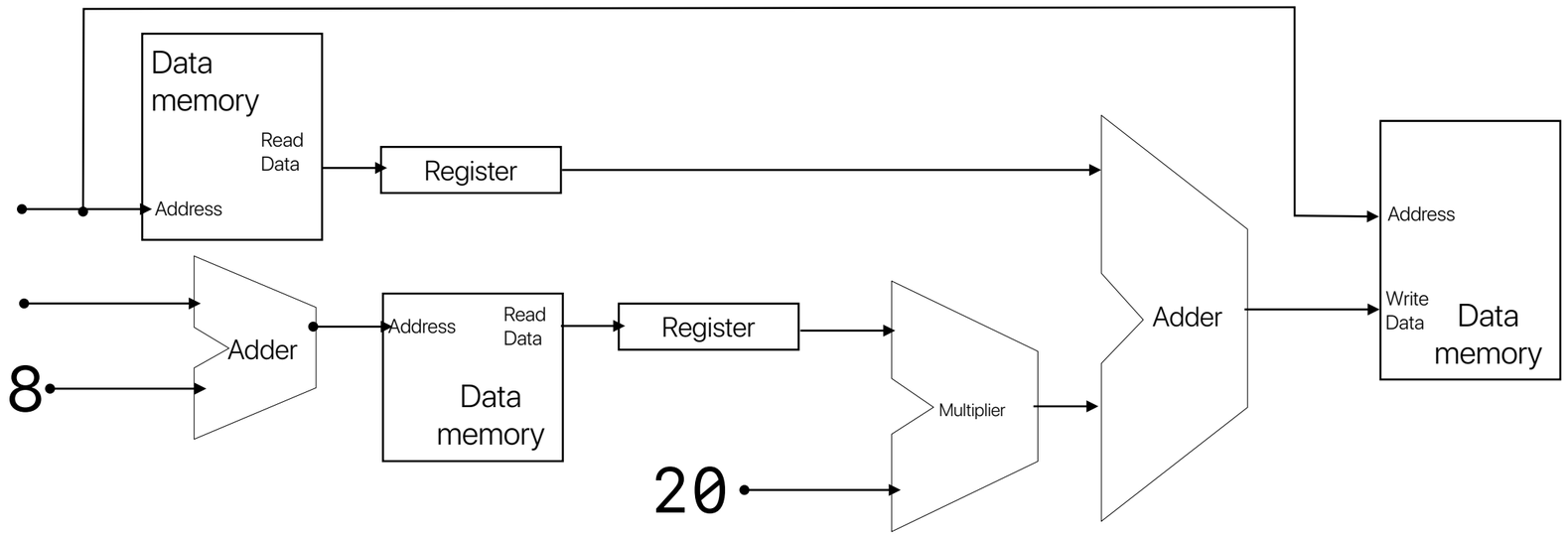
We don’t need these many registers, complex control, decode

We don’t need instruction fetch given it’s a fixed function



Rearranging the datapath

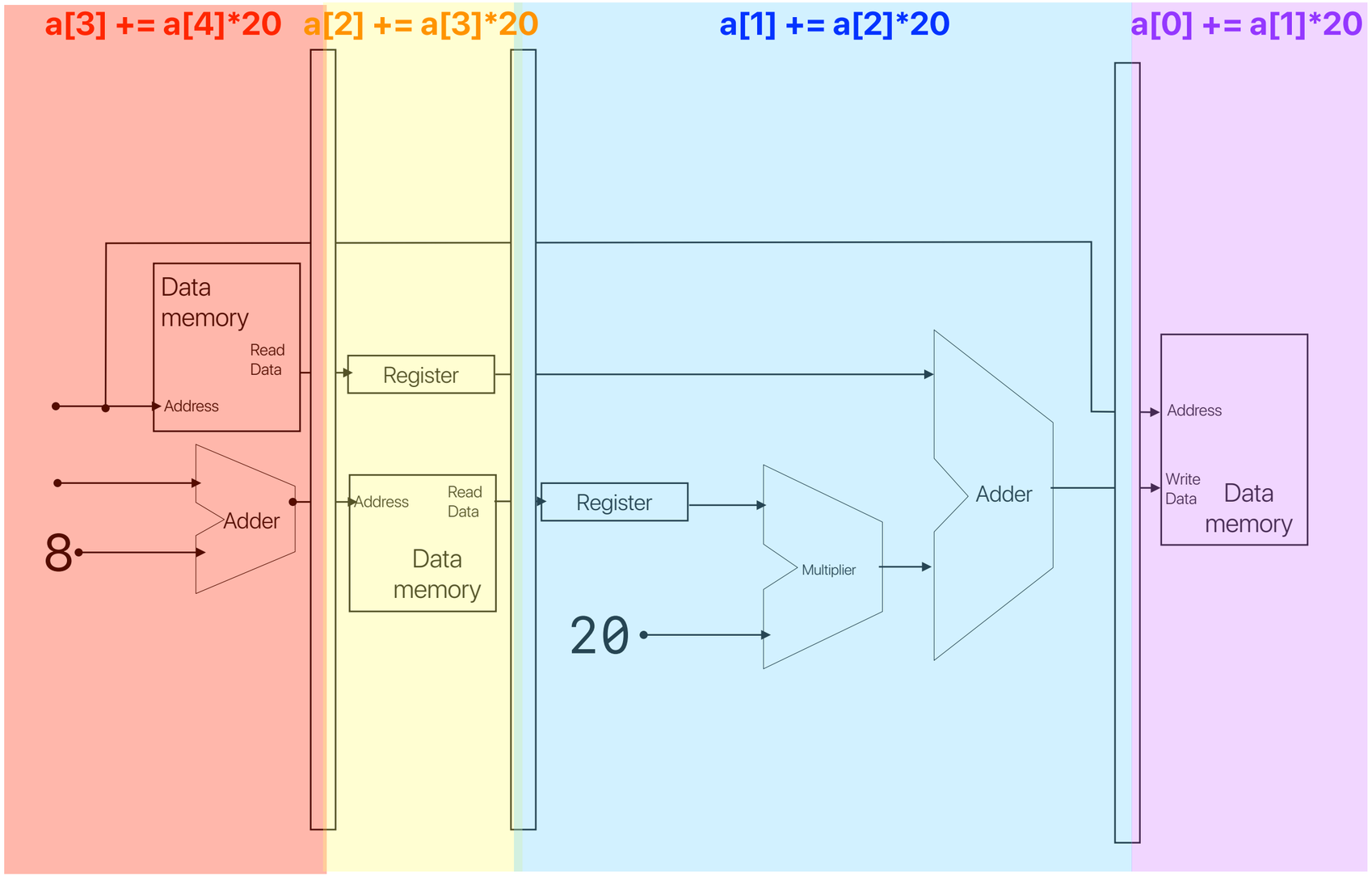
```
ld    X1, 0(X0)
ld    X2, 8(X0)
add   X3, X31, #20
mul   X2, X2, X3
add   X1, X1, X2
sd    X1, 0(X0)
```



The pipeline for a[i] += a[i+1]*20

Each stage can still be as fast as the pipelined processor

But each stage is now working on what the original 6 instructions would do

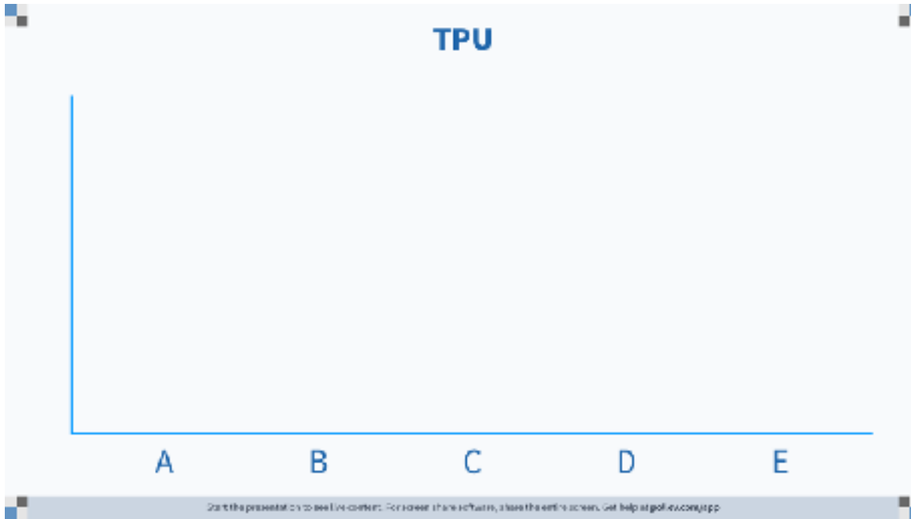


In-Datacenter Performance Analysis of a Tensor Processing Unit

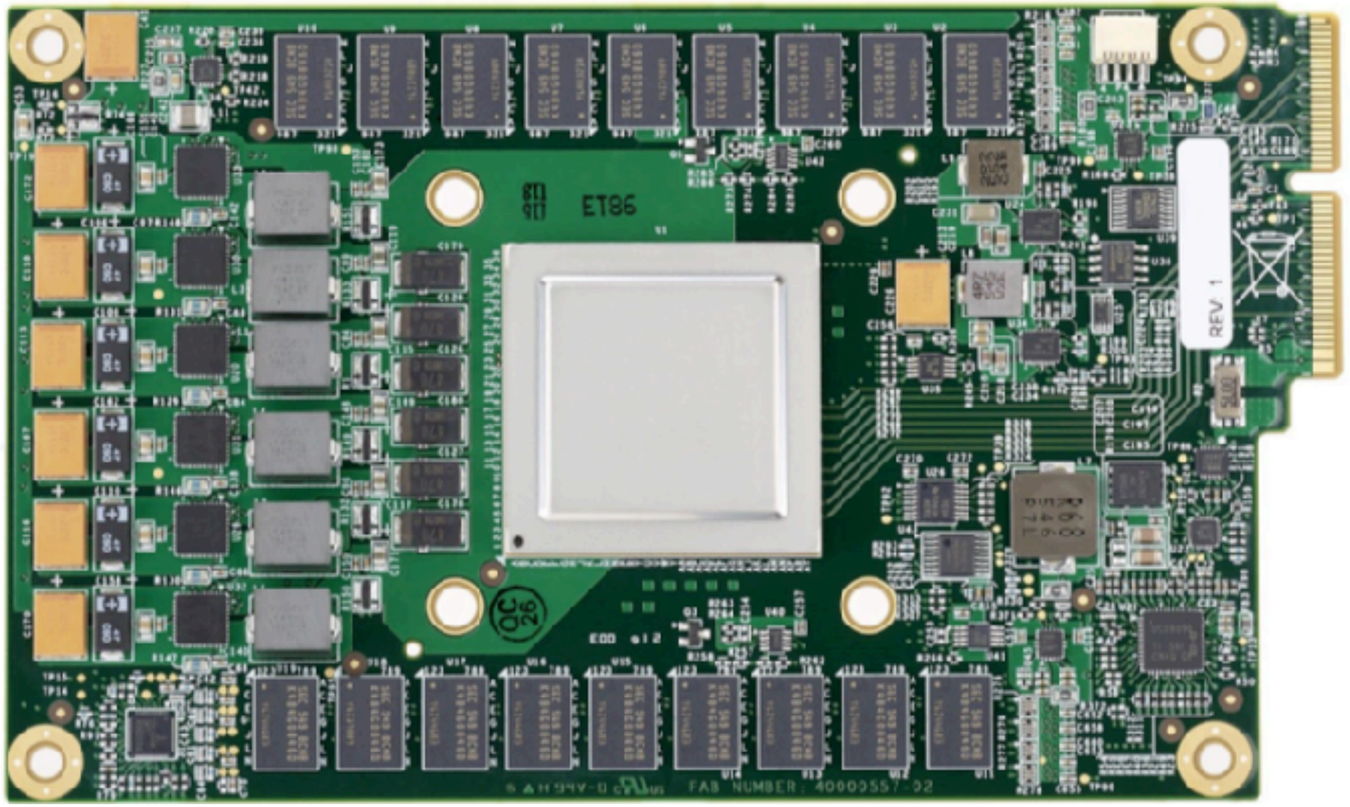
N. P. Jouppi, C. Young, N. Patil, D. Patterson, G. Agrawal, R. Bajwa, S. Bates, S. Bhatia, N. Boden, A. Borchers, R. Boyle, P.-l. Cantin, C. Chao, C. Clark, J. Coriell, M. Daley, M. Dau, J. Dean, B. Gelb, T. V. Ghaemmaghami, R. Gottipati, W. Gulland, R. Hagmann, C. R. Ho, D. Hogberg, J. Hu, R. Hundt, D. Hurt, J. Ibarz, A. Jaffey, A. Jaworski, A. Kaplan, H. Khaitan, D. Killebrew, A. Koch, N. Kumar, S. Lacy, J. Laudon, J. Law, D. Le, C. Leary, Z. Liu, K. Lucke, A. Lundin, G. MacKean, A. Maggiore, M. Mahony, K. Miller, R. Na- garajan, R. Narayanaswami, R. Ni, K. Nix, T. Norrie, M. Omernick, N. Penukonda, A. Phelps, J. Ross, M. Ross, A. Salek, E. Samadiani, C. Severn, G. Sizikov, M. Snelham, J. Souter, D. Steinberg, A. Swing, M. Tan, G. Thorson, B. Tian, H. Toma, E. Tuttle, V. Vasudevan, R. Wal- ter, W. Wang, E. Wilcox, and D. H. Yoon
Google Inc.

TPU (Tensor Processing Unit)

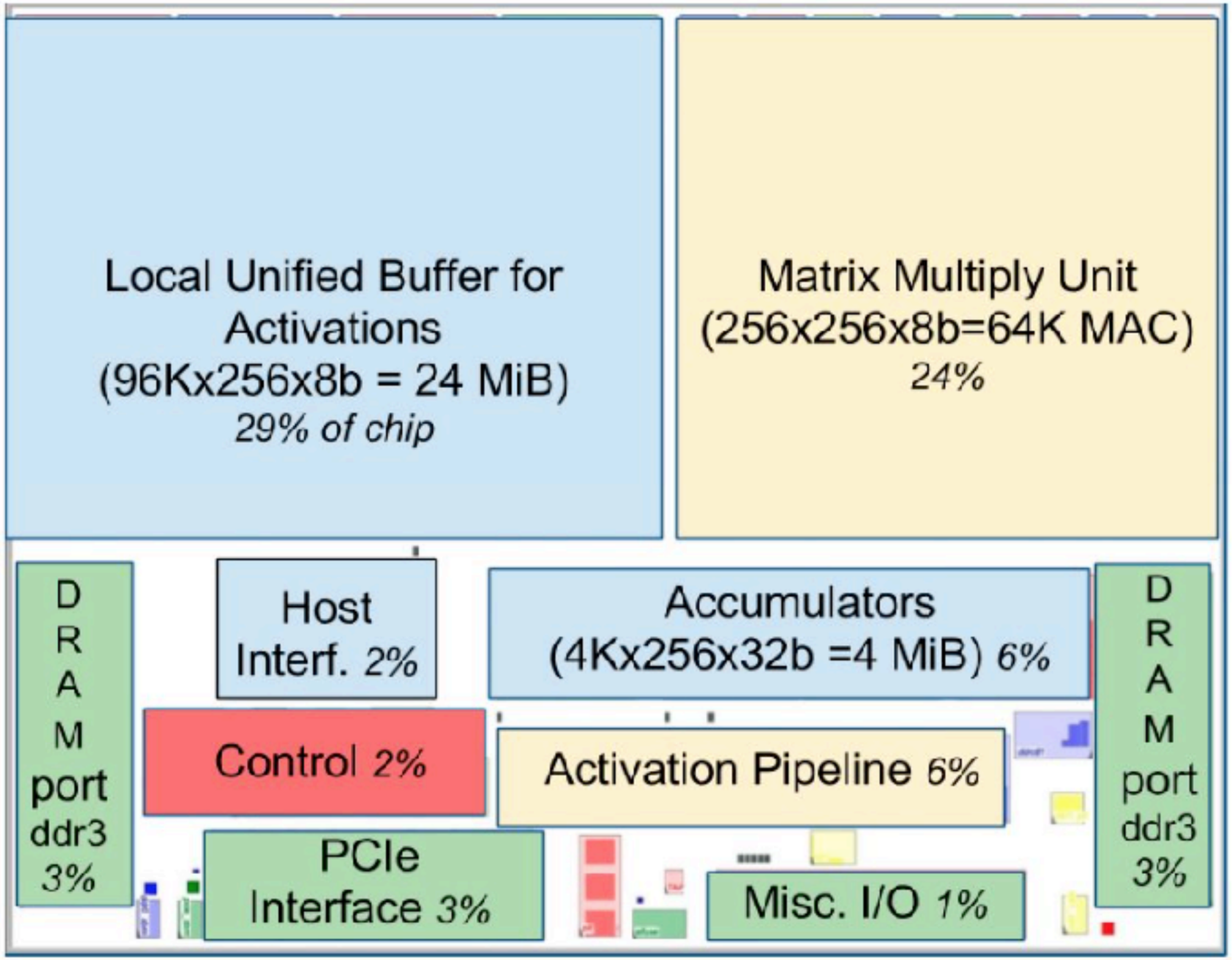
- Regarding TPUs, please identify how many of the following statements are correct.
  - ① TPU is optimized for highly accurate matrix multiplications
  - ② TPU is designed for dense matrices, not for sparse matrices
  - ③ TPU can reduce the "IC" in the performance equation
  - ④ All TPU instructions are equally long
  - A. 0
  - B. 1
  - C. 2
  - D. 3
  - E. 4



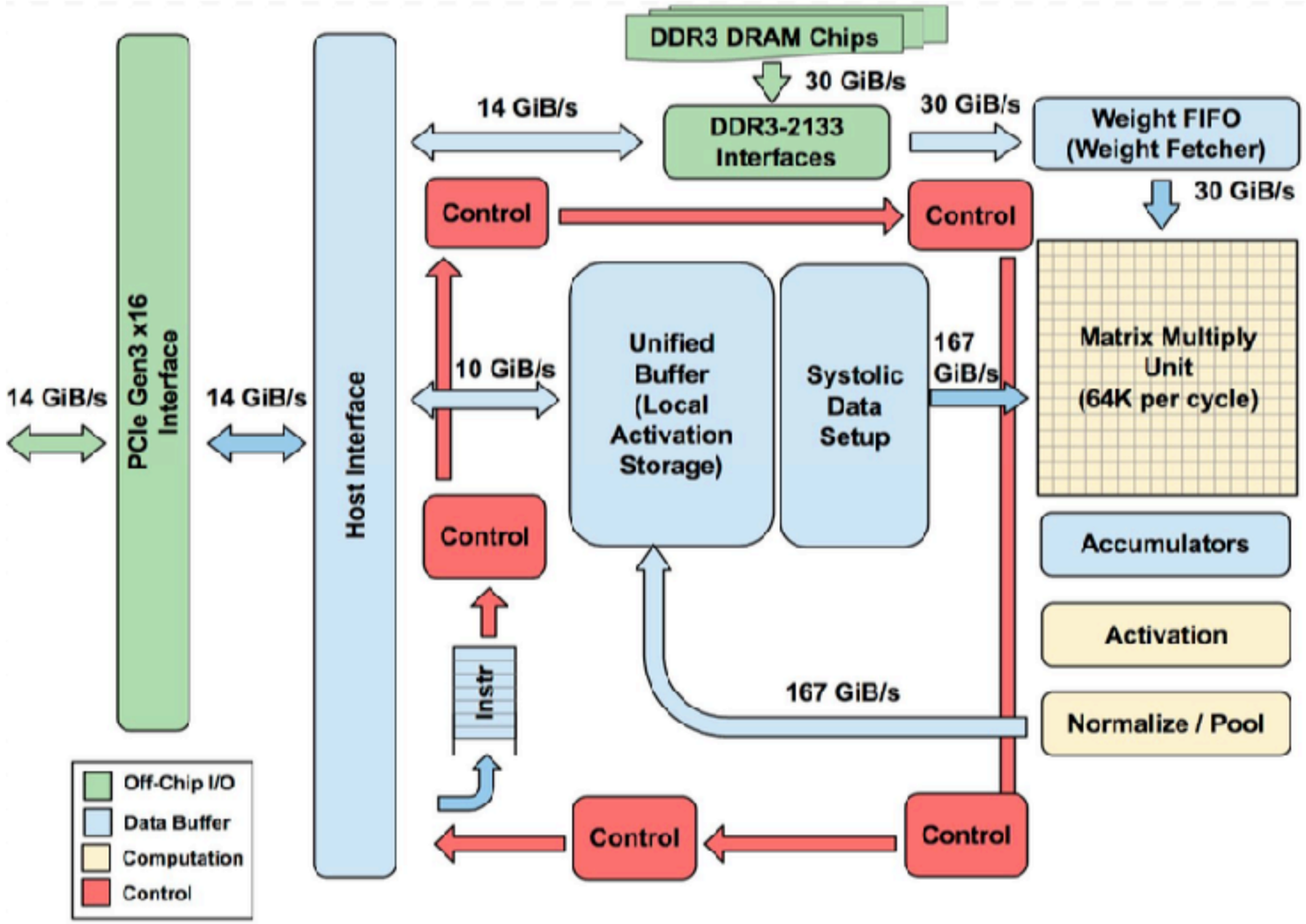
What TPU looks like



TPU Floorplan



TPU Block diagram



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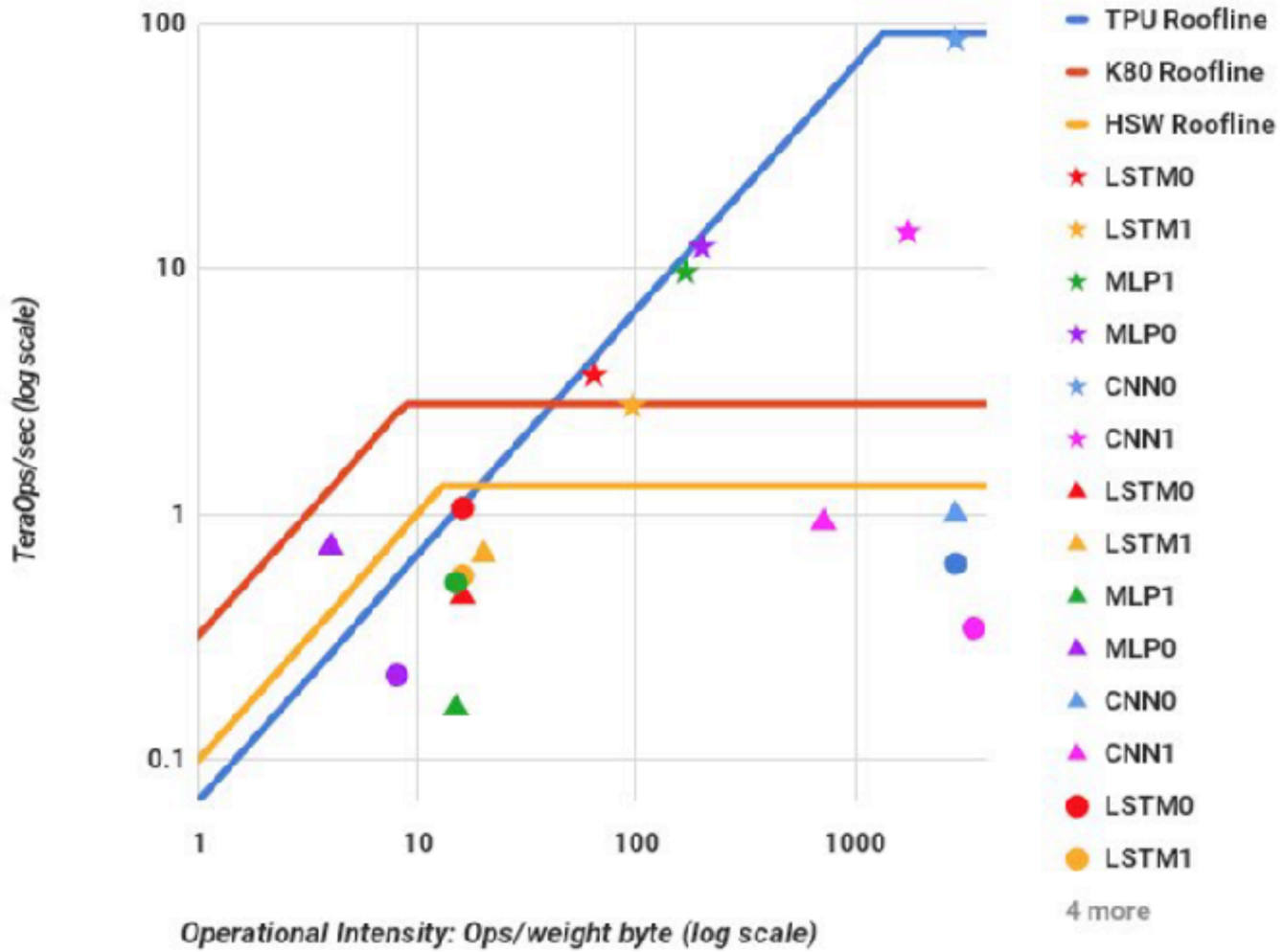
  - D. 3
  - E. 4

Experimental setup

Model	Die										Benchmarked Servers				
	mm^2	nm	MHz	TDP	Measured		TOPS/s		GB/s	On-Chip Memory	Dies	DRAM Size	TDP	Measured	
					Idle	Busy	8b	FP						Idle	Busy
Haswell E5-2699 v3	662	22	2300	145W	41W	145W	2.6	1.3	51	51 MiB	2	256 GiB	504W	159W	455W
NVIDIA K80 (2 dies/card)	561	28	560	150W	25W	98W	--	2.8	160	8 MiB	8	256 GiB (host) + 12 GiB x 8	1838W	357W	991W
TPU	NA*	28	700	75W	28W	40W	92	--	34	28 MiB	4	256 GiB (host) + 8 GiB x 4	861W	290W	384W

Performance/Rooflines

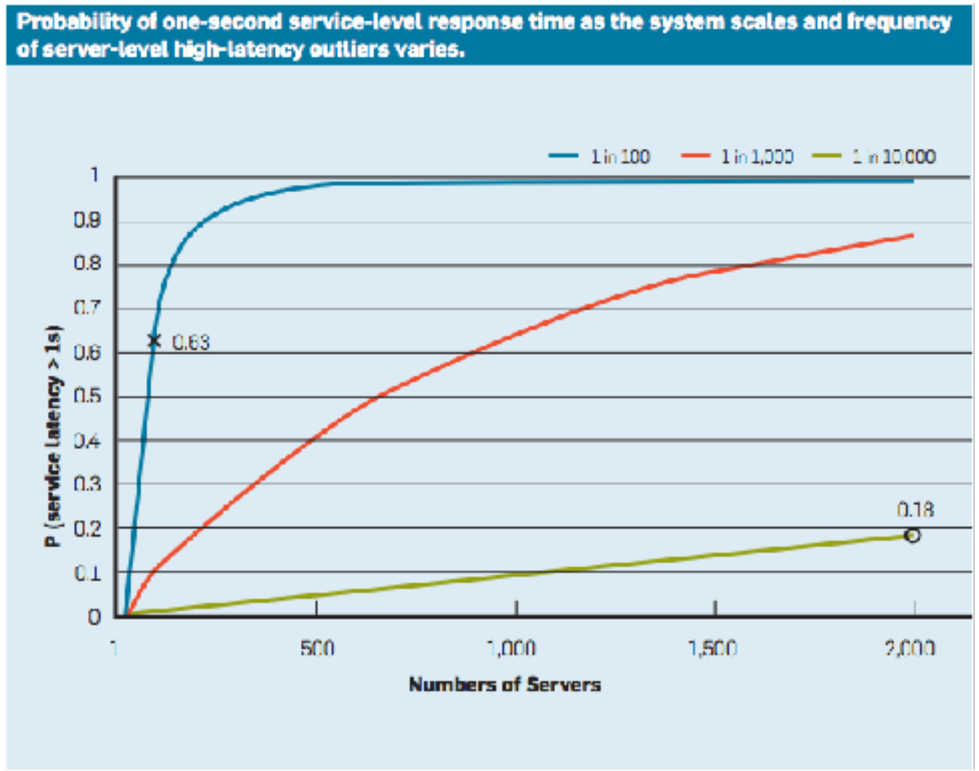


Tail latencies

Type	*Batch*	*99th% Response*	*Inf/s (IPS)*	*% Max IPS*
CPU	16	7.2 ms	5,482	42%
CPU	64	21.3 ms	13,194	100%
GPU	16	6.7 ms	13,461	37%
GPU	64	8.3 ms	36,465	100%
TPU	200	7.0 ms	225,000	80%
TPU	250	10.0 ms	280,000	100%

Table 4. 99-th% response time and per die throughput (IPS) for MLP0 as batch size varies for MLP0. The longest allowable latency is 7 ms. For the GPU and TPU, the maximum MLP0 throughput is limited by the host server overhead. Larger batch sizes increase throughput, but as the text explains, their longer response times exceed the limit, so CPUs and GPUs must use less-efficient, smaller batch sizes (16 vs. 200).

Tail latencies



- Tail Latency == 1 in X servers being slow
- Why is this bad? – Each user request now needs several servers – Changes of experience tail is much higher
- If 99% of the server's response time is 10ms, but 1% of them take 1 second to response
  - If the user only needs one, the mean is OK
  - If the user needs 100 partitions from 100 servers, 63% of the requests takes more than 1 seconds.

Tail latency

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What NVIDIA says

https://blogs.nvidia.com/blog/2017/04/10/ai-drives-rise-accelerated-computing-datacenter/

	K80 2012	TPU 2015	P40 2016
Inferences/Sec <10ms latency	1/13X	1X	2X
Training TOPS	6 FP32	NA	12 FP32
Inference TOPS	6 FP32	90 INT8	48 INT8
On-chip Memory	16 MB	24 MB	11 MB
Power	300W	75W	250W
Bandwidth	320 GB/S		

While Google and NVIDIA chose different development paths, there were several themes common to both our approaches. Specifically:

- AI requires accelerated computing. Accelerators provide the significant data processing necessary to keep up with the growing demands of deep learning in an era when Moore's law is slowing.
- Tensor processing is at the core of delivering performance for deep learning training and inference.
- Tensor processing is a major new workload enterprises must consider when building modern data centers.
- Accelerating tensor processing can dramatically reduce the cost of building modern data centers.

7.10 Fallacies and Pitfalls

In these early days of both DSAs and DNNs, fallacies abound.

Fallacy *It costs $100 million to design a custom chip.*

Figure 7.51 shows a graph from an article that debunks the widely quoted $100-million myth that it was "only" $50 million, with most of the cost being salaries (Olofsson, 2011). Note that the author's estimate is for sophisticated processors that include features that DSAs by definition omit, so even if there were no improvement to the development process, you would expect the cost of a DSA design to be less.

Why are we more optimistic six years later, when, if anything, mask costs are even higher for the smaller process technologies?

First, software is the largest category, at almost a third of the cost. The availability of applications written in domain-specific languages allows the compilers to do most of the work of porting the applications to your DSA, as we saw for the TPU and Pixel Visual Core. The open RISC-V instruction set will also help reduce the cost of getting system software as well as cut the large IP costs.

Mask and fabrication costs can be saved by having multiple projects share a single reticle. As long as you have a small chip, amazingly enough, for $30,000 anyone can get 100 untested parts in 28-nm TSMC technology (Patterson and Nikolić, 2015).

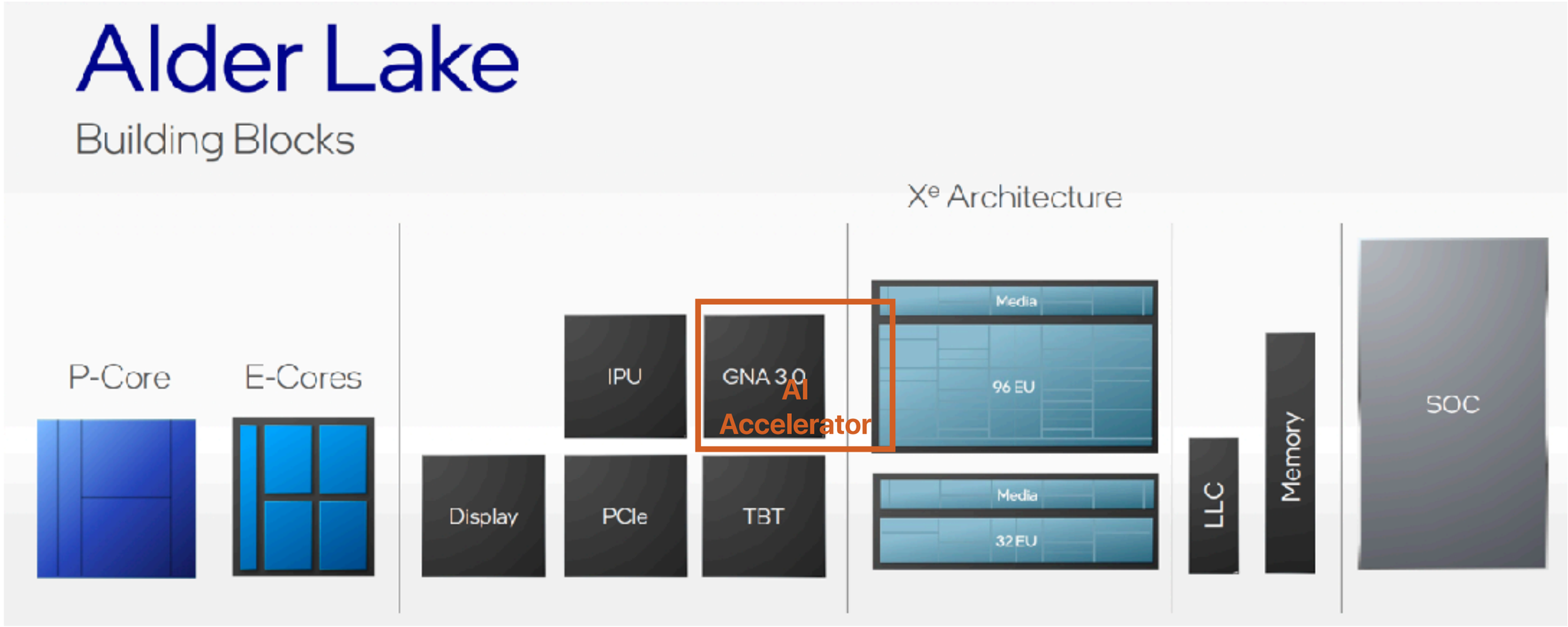
Fallacies & Pitfalls

- Fallacy: NN inference applications in data centers value throughput as much as response time.
- Fallacy: The K80 GPU architecture is a good match to NN inference — GPU is throughput oriented
- Pitfall: For NN hardware, Inferences Per Second (IPS) is an inaccurate summary performance metric — it's simply the inverse of the complexity of the typical inference in the application (e.g., the number, size, and type of NN layers)
- Fallacy: The K80 GPU results would be much better if Boost mode were enabled — Boost mode increased the clock rate by a factor of up to 1.6—from 560 to 875 MHz—which increased performance by 1.4X, but it also raised power by 1.3X. The net gain in performance/Watt is 1.1X, and thus Boost mode would have a minor impact on LSTM1
- Fallacy: CPU and GPU results would be comparable to the TPU if we used them more efficiently or compared to newer versions.

Fallacies & Pitfalls

- Pitfall: Architects have neglected important NN tasks.
  - CNNs constitute only about 5% of the representative NN workload for Google. More attention should be paid to MLPs and LSTMs. Repeating history, it's similar to when many architects concentrated on floating- point performance when most mainstream workloads turned out to be dominated by integer operations.
- Pitfall: Performance counters added as an afterthought for NN hardware.
- Fallacy: After two years of software tuning, the only path left to increase TPU performance is hardware upgrades.
- Pitfall: Being ignorant of architecture history when designing a domain-specific architecture
  - Systolic arrays
  - Decoupled-access/execute
  - CISC instructions

Modern processors also contain “accelerators”

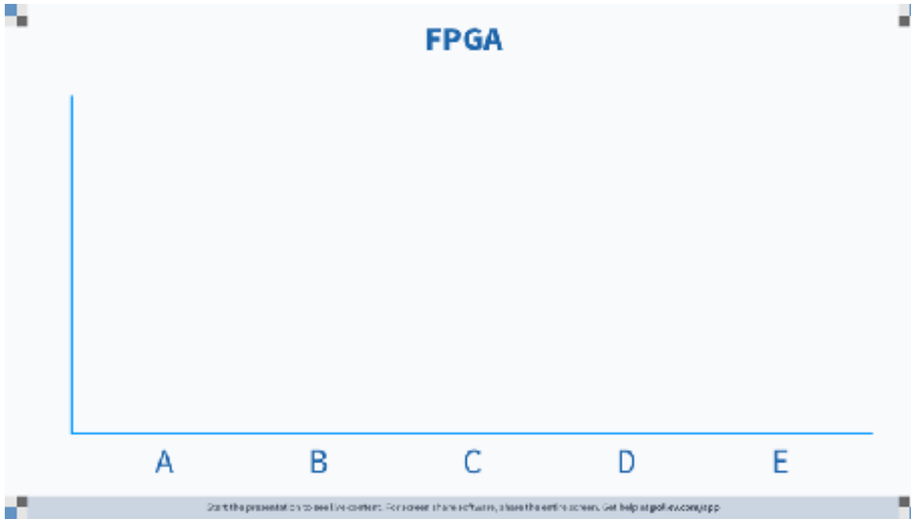


A Cloud-Scale Acceleration Architecture

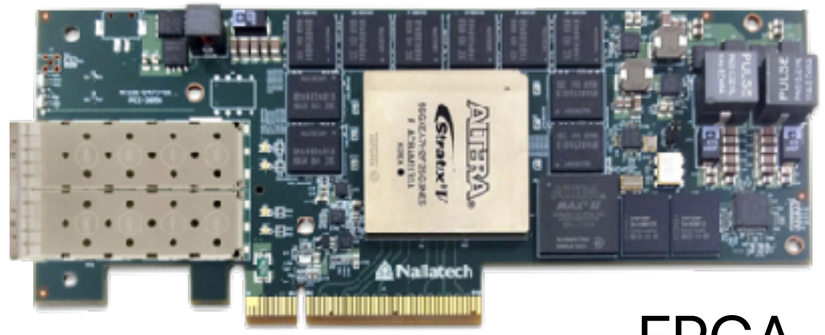
Adrian Caulfield, Eric Chung, Andrew Putnam, Hari Angepat, Jeremy Fowers, Michael Haselman, Stephen Heil, Matt Humphrey, Puneet Kaur, Joo-Young Kim, Daniel Lo, Todd Massengill, Kalin Ovtcharov, Michael Papamichael, Lisa Woods, Sitaram Lanka, Derek Chiou, Doug Burger
Microsoft

Why FPGAs?

- Which of the following is the main reason why Microsoft adopts FPGAs instead of the alternatives chosen by their rivals?
  A. Cost
  B. Performance
  C. Scalability
  D. Flexibility
  E. Easier to program



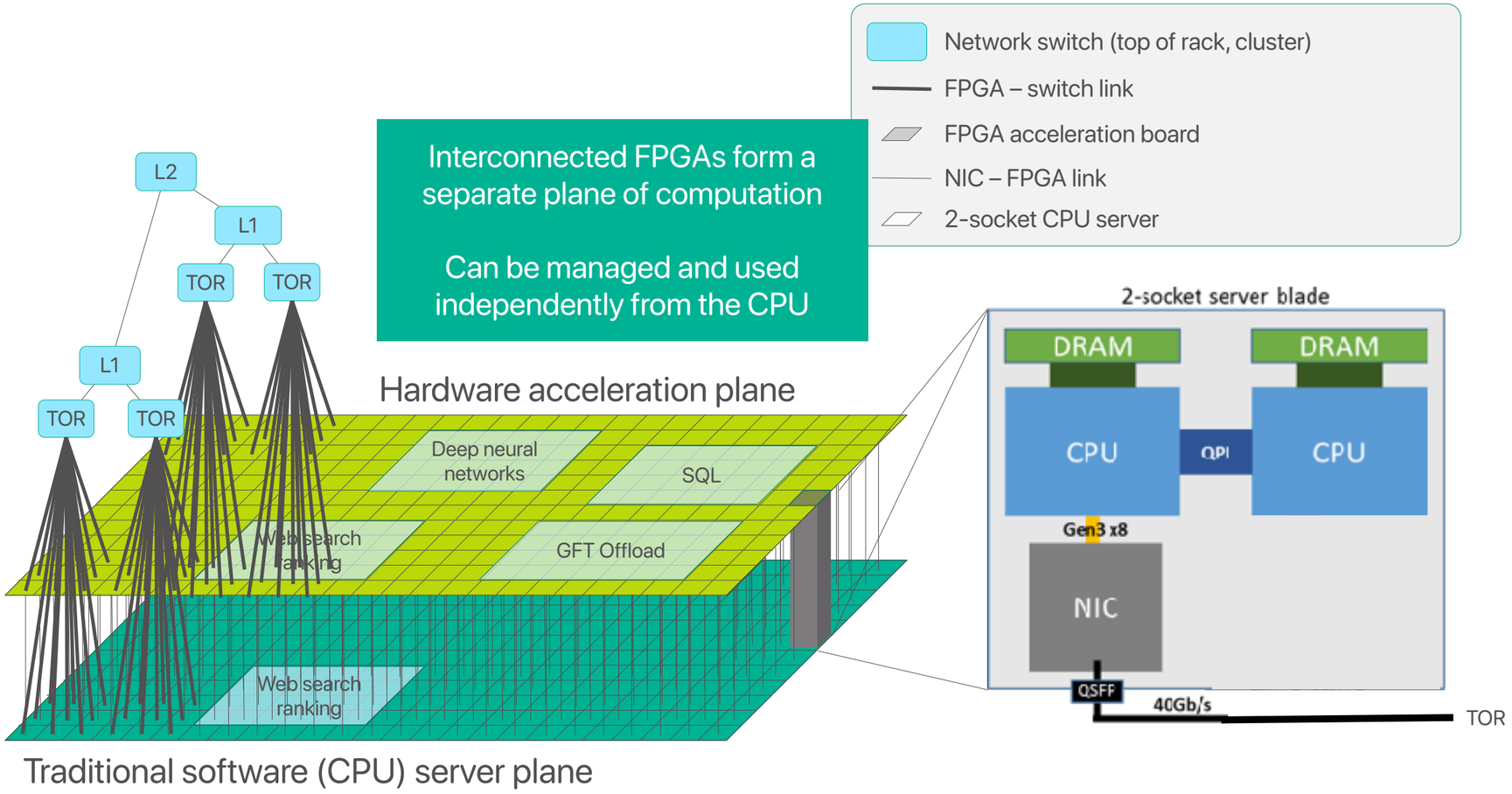
FPGA



FPGA

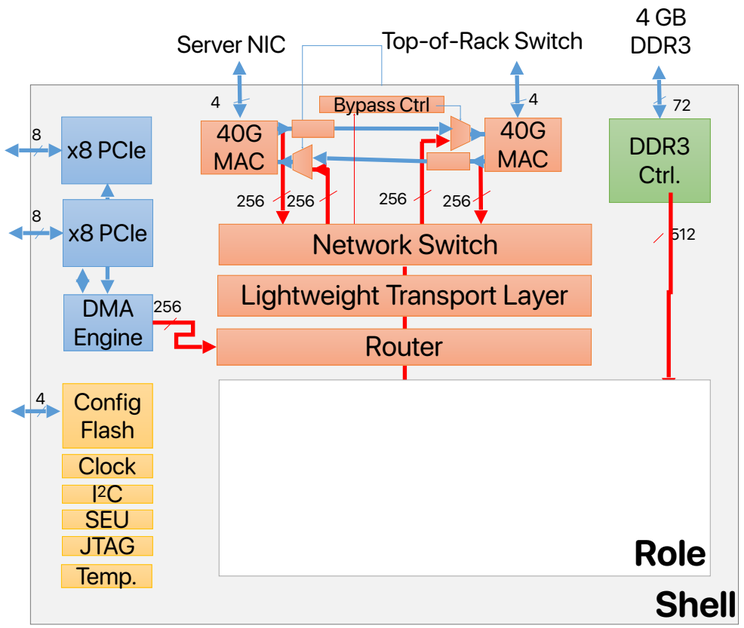
- Field Programmable Gate Array
  - An array of “Lookup tables (LUTs)”
  - Reconfigurable wires or say interconnects of LUTs
  - Registers
- An LUT
  - Accepts a few inputs
  - Has SRAM memory cells that store all possible outputs
  - Generates outputs according to the given inputs
- As a result, you may use FPGAs to emulate any kind of gates or logic combinations, and create an ASIC-like processor

Configurable cloud



Gen2 shell

- Foundation for all accelerators
  - Includes PCIe, Networking and DDR IP
  - Common, well tested platform for development
- Lightweight Transport Layer
  - Reliable FPGA-to-FPGA Networking
  - Ack/Nack protocol, retransmit buffers
  - Optimized for lossless network
  - Minimized resource usage

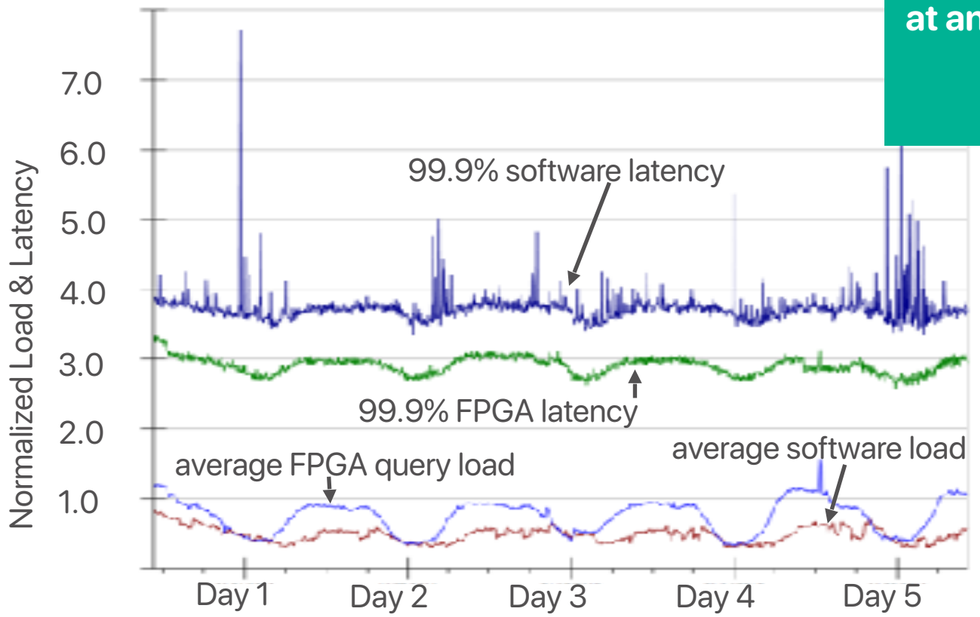


Use cases

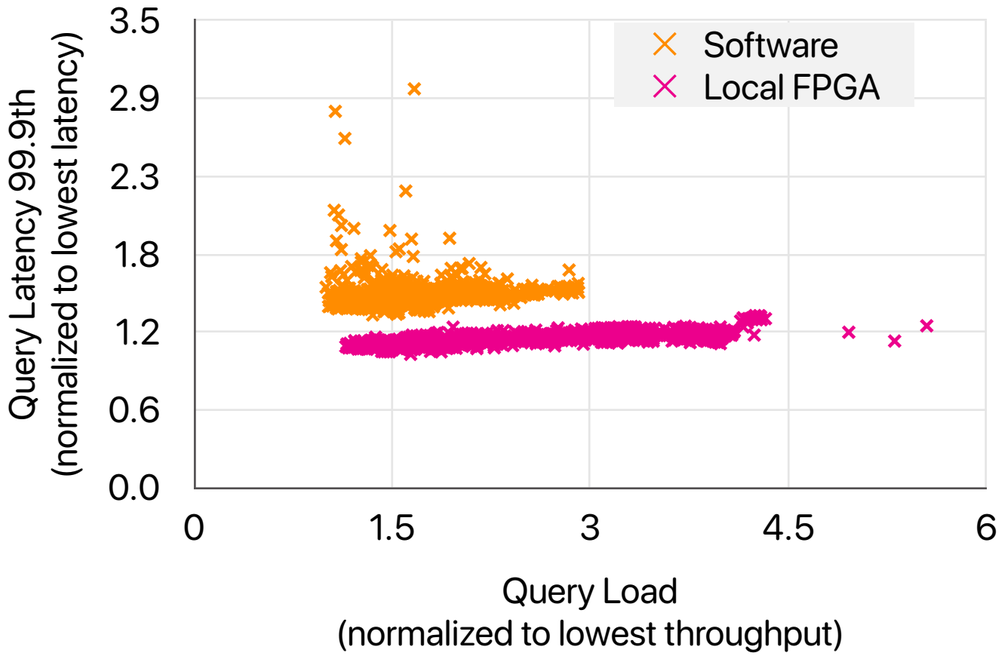
- Local: Great service acceleration
- Infrastructure: Fastest cloud network
- Remote: Reconfigurable app fabric (DNNs)

5 day bed-level latency

- Lower & more consistent 99.9th tail latency
- In production for years



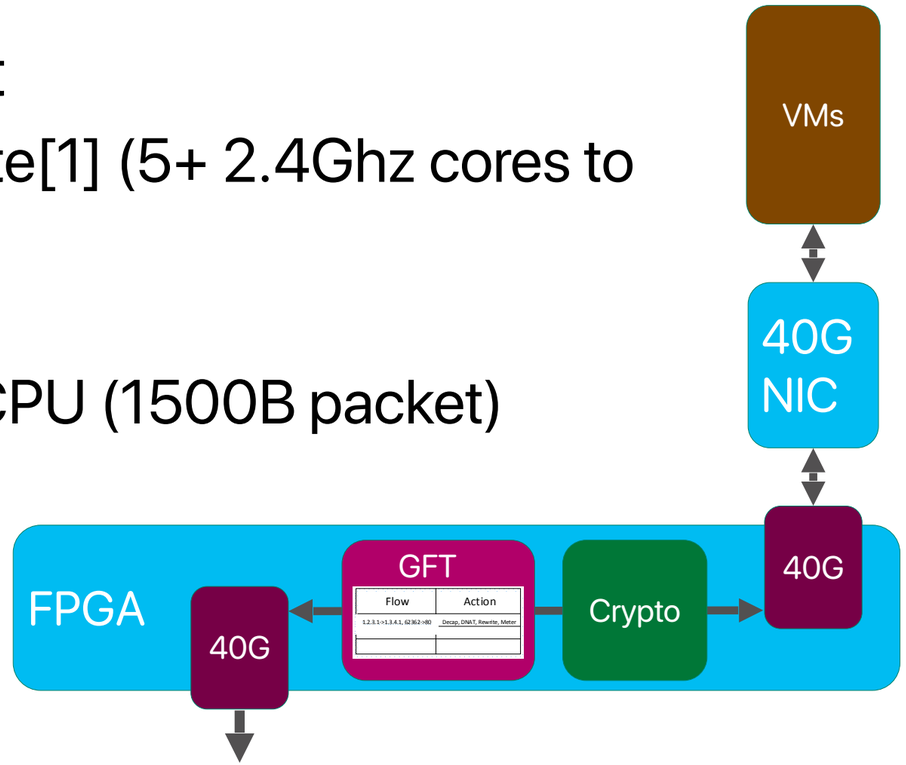
Even at 2× query load, accelerated ranking has lower latency than software **at any load**



Accelerated networking

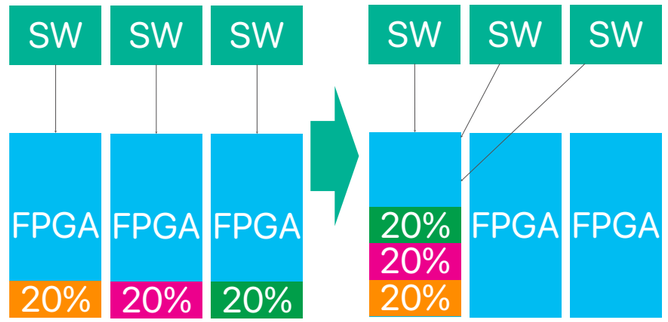
- Software defined networking
  - Generic Flow Table (GFT) rule based packet rewriting
  - 10x latency reduction vs software, CPU load now <1 core
  - 25Gb/s throughput at 25µs latency – the fastest cloud network

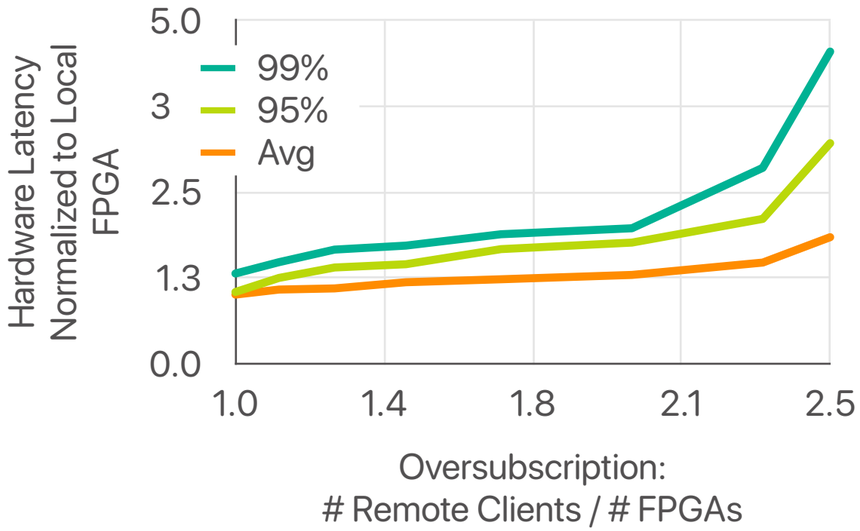
- Capable of 40 Gb line rate encrypt and decrypt
  - On Haswell, AES GCM-128 costs 1.26 cycles/byte[1] (5+ 2.4Ghz cores to sustain 40Gb/s)
  - CBC and other algorithms are more expensive
  - AES CBC-128-SHA1 is 11µs in FPGA vs 4µs on CPU (1500B packet)
  - Higher latency, but significant CPU savings



Shared DNN

- Economics: consolidation
  - Most accelerators have more throughput than a single host requires
  - Share excess capacity, use fewer instances
  - Frees up FPGAs for other use services
- DNN accelerator
  - Sustains 2.5x busy clients in microbenchmark, before queuing delay drives latency up





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  A. Cost
  B. Performance
  C. Scalability
  D. Flexibility
  E. Easier to program

Why FPGA?

This model offers significant flexibility. From the local perspective, the FPGA is used as a compute or a network accelerator. From the global perspective, the FPGAs can be managed as a large-scale pool of resources, with acceleration

hyperscale infrastructure. The acceleration system we describe is sufficiently flexible to cover three scenarios: local compute acceleration (through PCIe), network acceleration, and global application acceleration, through configuration as pools of remotely accessible FPGAs. Local acceleration handles high-

These programmable architectures allow for hardware homogeneity while allowing fungibility via softwa[illegible]ifferent services. They must be highly *flexible* at the [illegible]stem [illegible]

Flexible

This paper described Configurable Clouds, a datacenter-scale acceleration architecture, based on FPGAs, that is both scalable and flexible. By putting in FPGA cards both in I/O

In addition to architectural requirements that provide sufficient flexibility to justify scale production deployment, there are also physical restrictions in current infrastructures that

Summary: What makes a configurable cloud?

- Local, infrastructure and remote acceleration
  - Gen1 showed significant gains even for complex services (~2x for Bing)
  - Needs to have clear benefit for majority of servers: infrastructure
- Economics must work
  - What works at small scale doesn’t always work at hyperscale and vice versa
  - Little tolerance for superfluous costs
  - Minimized complexity and risk in deployment and maintenance
- Must be flexible
  - Support simple, local accelerators and complex, shared accelerators at the same time
  - Rapid deployment of new protocols, algorithms and services across the cloud

Final words

Conclusion

- Computer architecture is now more important than you could ever imagine
- Being a “programmer” is easy. You need to know architecture a lot to be a “performance programmer”
  - Branch prediction
  - Cache
- Multicore era — to get your multithreaded program correct and perform well, you need to take care of coherence and consistency
- We’re now in the “dark silicon era”
  - Single-core isn’t getting any faster
  - Multi-core doesn’t scale anymore
  - We will see more and more ASICs
  - You need to write more “system-level” programs to use these new ASICs.

One more thing...

Logistics

- The final exam will be held at
  BRNHL B118 (not the classroom for lectures)
  6/15/2023 11:30 a.m. – 2:30 p.m
- Similar to the midterm, but more time and about 1.5x longer
- Two of the problem sets will be comprehensive exam questions
- You should **arrive earlier**
  - Each of you will have to pick up the test from the TA first and have a seat assigned by the TA randomly — if you arrive late or start late because you did not get the test on time, you still have to turn in before 2:30p
  - We will do ID check as the last time
  - You cannot change your seating once assigned
  - You cannot bring any outside material. Scratch paper is not allowed
  - You need to prepare your own calculator if you think it's necessary — exchanging during the examine is not allowed

Sample Final

Format of the final

- Multiple choices (15 questions)
  - They’re like your clicker/midterm multiple choices questions
  - Cumulative, don’t forget your midterm and midterm review
- Free answer and open-ended questions * 2 problem sets, 8 questions in total
  - Two of them are also MSCS comprehensive exam questions
  - Explain your answer clearly and “correctly”. If you include “incorrect” information in your answer, it’s going to hurt your grade
  - May not have a standard answer. You need to understand the concepts to provide a good answer
  - You should review your assignments carefully

Multiple choices

How many dependencies do we have?

- How many pairs of data dependences are there in the following x86 instructions?

```
movl    (%rdi), %eax
xorl    (%rsi), %eax
movl    %eax, (%rdi)
xorl    (%rsi), %eax
movl    %eax, (%rsi)
xorl    %eax, (%rdi)
```

A. 1
B. 2
C. 3
D. 4
E. 5

The effect of code optimization

- By reordering which pair of the following instruction stream can we eliminate all stalls without affecting the correctness of the code?

① `movl (%rdi), %ecx`
② `addl %ecx, %eax`
③ `addq $4, %rdi`
④ `cmpq %rdx, %rdi`
⑤ `jne .L3`
⑥ `ret`

A. (1) & (2)
B. (2) & (3)
C. (3) & (4)
D. (4) & (5)
E. None of the pairs can be reordered

CMP advantages

- How many of the following are advantages of CMP over traditional superscalar processor
  - ① CMP can provide better energy-efficiency within the same area
  - ② CMP can deliver better instruction throughput within the same die area (chip size)
  - ③ CMP can achieve better ILP for each running thread
  - ④ CMP can improve the performance of a single-threaded application without modifying code
  - A. 0
  - B. 1
  - C. 2
  - D. 3
  - E. 4

What about “linked list”

- Assume the current PC is already at instruction (1) and this linked list has only three nodes. This processor can fetch and issue 2 instructions per cycle, with exactly the same register renaming hardware and pipeline as we showed previously.
  Which of the following C state of the
  code snippet determines the
  performance?

```
A.do {
B.     number_of_nodes++;
C.     current = current->next;
D.} while ( current != NULL );
```

Amdahl's Law on Multicore Architectures

- Regarding Amdahl's Law on multicore architectures, how many of the following statements is/are correct?
  - ① If we have unlimited parallelism, the performance of each parallel piece does not matter as long as the performance slowdown in each piece is bounded
  - ② With unlimited amount of parallel hardware units, single-core performance does not matter anymore
  - ③ With unlimited amount of parallel hardware units, the maximum speedup will be bounded by the fraction of parallel parts
  - ④ With unlimited amount of parallel hardware units, the effect of scheduling and data exchange overhead is minor

  A. 0
  B. 1
  C. 2
  D. 3
  E. 4

Virtual indexed, physical tagged cache limits the cache size

- If you want to build a virtual indexed, physical tagged cache with 32KB capacity, which of the following configuration is possible? Assume the system use 4K pages.
  A. 32B blocks, 2-way
  B. 32B blocks, 4-way
  C. 64B blocks, 4-way
  D. 64B blocks, 8-way

Power & Energy

- Regarding power and energy, how many of the following statements are correct?
  - ① Lowering the power consumption helps extending the battery life
  - ② Lowering the power consumption helps reducing the heat generation
  - ③ Lowering the energy consumption helps reducing the electricity bill
  - ④ A CPU with 10% utilization can still consume 33% of the peak power
  - A. 0
  - B. 1
  - C. 2
  - D. 3
  - E. 4

Why is D better than C?

- How many of the following statements explains the main reason why B outperforms C with compiler optimizations
  - ① D has lower dynamic instruction count than C
  - ② D has significantly lower branch mis-prediction rate than C
  - ③ D has significantly fewer branch instructions than C
  - ④ D can incur fewer memory accesses than C

A. 0
B. 1
C. 2
D. 3
E. 4

C

```
inline int popcount(uint64_t x) {
      int c = 0;
      int table[16] = {0, 1, 1, 2, 1,
2, 2, 3, 1, 2, 2, 3, 2, 3, 3, 4};
      while(x)      {
          c += table[(x & 0xF)];
          x = x >> 4;
      }
      return c;
}
```

D

```
inline int popcount(uint64_t x) {
      int c = 0;
      int table[16] = {0, 1, 1, 2, 1,
2, 2, 3, 1, 2, 2, 3, 2, 3, 3, 4};
      for (uint64_t i = 0; i < 16; i++)
      {
          c += table[(x & 0xF)];
          x = x >> 4;
      }
      return c;
 }
```

Demo revisited

- Why the performance is better when option is not “0”
  - ① The amount of dynamic instructions needs to execute is a lot smaller
  - ② The amount of branch instructions to execute is smaller
  - ③ The amount of branch mis-predictions is smaller
  - ④ The amount of data accesses is smaller

A. 0
B. 1
C. 2
D. 3
E. 4

```
if(option)
    std::sort(data, data + arraySize);

for (unsigned i = 0; i < 100000; ++i) {
    int threshold = std::rand();
    for (unsigned i = 0; i < arraySize; ++i) {
        if (data[i] >= threshold)
            sum ++;
    }
}
```

What if the code look like this?

- D-L1 Cache configuration of NVIDIA Tegra X1
  - Size 64KB, 4-way set associativity, 64B block, LRU policy, write-allocate, write-back, and assuming 64-bit address.

```
int a[16384], b[16384], c[16384];
/* c = 0x10000, a = 0x20000, b = 0x30000 */
for(i = 0; i < 512; i++)
    c[i] = a[i]; //load a and then store to c
for(i = 0; i < 512; i++)
    c[i] += b[i]; //load b, load c, add, and then store to c
```

What's the data cache miss rate for this code?

A. 6.25%
B. 56.25%
C. 66.67%
D. 68.75%
E. 100%

What kind(s) of misses can matrix transpose remove?

- By transposing a matrix, the performance of matrix multiplication can be further improved. What kind(s) of cache misses does matrix transpose help to remove?

Block

```
for(i = 0; i < ARRAY_SIZE; i+=(ARRAY_SIZE/n)) {
  for(j = 0; j < ARRAY_SIZE; j+=(ARRAY_SIZE/n)) {
    for(k = 0; k < ARRAY_SIZE; k+=(ARRAY_SIZE/n)) {
      for(ii = i; ii < i+(ARRAY_SIZE/n); ii++)
        for(jj = j; jj < j+(ARRAY_SIZE/n); jj++)
          for(kk = k; kk < k+(ARRAY_SIZE/n); kk++)
            c[ii][jj] += a[ii][kk]*b[kk][jj];
    }
  }
}
```

A. Compulsory miss
B. Capacity miss
C. Conflict miss
D. Capacity & conflict miss
E. Compulsory & conflict miss

Block + Transpose

```
// Transpose matrix b into b_t
for(i = 0; i < ARRAY_SIZE; i+=(ARRAY_SIZE/n)) {
  for(j = 0; j < ARRAY_SIZE; j+=(ARRAY_SIZE/n)) {
      b_t[i][j] += b[j][i];
  }
}


for(i = 0; i < ARRAY_SIZE; i+=(ARRAY_SIZE/n)) {
  for(j = 0; j < ARRAY_SIZE; j+=(ARRAY_SIZE/n)) {
    for(k = 0; k < ARRAY_SIZE; k+=(ARRAY_SIZE/n)) {
        for(ii = i; ii < i+(ARRAY_SIZE/n); ii++)
          for(jj = j; jj < j+(ARRAY_SIZE/n); jj++)
            for(kk = k; kk < k+(ARRAY_SIZE/n); kk++
              // Compute on b_t
              c[ii][jj] += a[ii][kk]*b_t[jj][kk];
    }
  }
}
```

Summary of Optimizations

- Regarding the following cache optimizations, how many of them would help improve miss rate?
  - ① Non-blocking/pipelined/multibanked cache
  - ② Critical word first and early restart
  - ③ Prefetching
  - ④ Write buffer

  A. 0
  B. 1
  C. 2
  D. 3
  E. 4

What data structure is performing better

	Array of objects	object of arrays

	`struct grades`
	`{`
	`  int id;`
	`  double *homework;`
	`  double average;`
	`};`
		`struct grades`
		`{`
		`  int *id;`
		`  double **homework;`
		`  double *average;`
		`};`

average of each homework	`for(i=0;i<homework_items; i++)`
	`{`
	`gradesheet[total_number_students].homework[i] = 0.0;`
	`  for(j=0;j<total_number_students;j++)`
	`gradesheet[total_number_students].homework[i]`
	`+=gradesheet[j].homework[i];`
	`  gradesheet[total_number_students].homework[i] /=`
	`(double)total_number_students;`
	`}`
		`for(i = 0;i < homework_items; i++)`
		`{`
		`  gradesheet.homework[i][total_number_students] = 0.0;`
		`  for(j = 0; j <total_number_students;j++)`
		`  {`
		`  gradesheet.homework[i][total_number_students] +=`
		`gradesheet.homework[i][j];`
		`  }`
		`  gradesheet.homework[i][total_number_students] /=`
		`total_number_students;`
		`}`

- Considering your workload would like to calculate the average score of **one of the homework** for **all students**, which data structure would deliver better performance?
  A. Array of objects
  B. Object of arrays

Cache coherency

- Assuming that we are running the following code on a CMP with a cache coherency protocol, how many of the following outputs are possible? (a is initialized to 0 as assume we will output more than 10 numbers)

thread 1	thread 2
`while(1)` `  printf("%d ",a);`	`while(1)` `  a++;`

① 0 1 2 3 4 5 6 7 8 9
② 1 2 5 9 3 6 8 10 12 13
③ 1 1 1 1 1 1 1 64 100
④ 1 1 1 1 1 1 1 1 1 100

A. 0
B. 1
C. 2
D. 3
E. 4

Performance comparison

- Comparing implementations of thread_vadd — L and R, please identify which one will be performing better and why

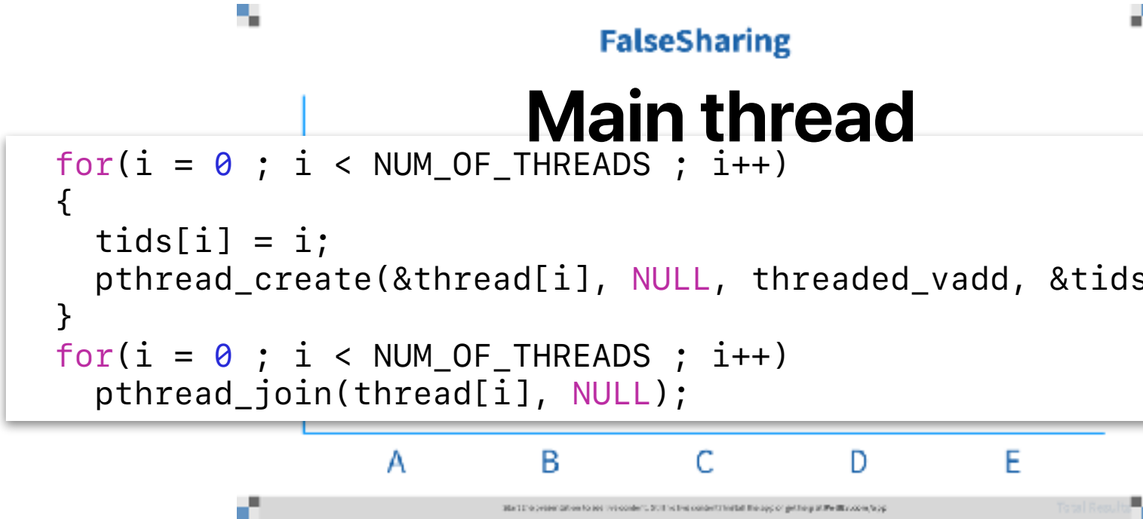
Version L

```
void *threaded_vadd(void *thread_id)
{
  int tid = *(int *)thread_id;
  int i;
  for(i=tid;i<ARRAY_SIZE;i+=NUM_OF_THREADS)
  {
        c[i] = a[i] + b[i];
  }
  return NULL;
}
```

Version R

```
void *threaded_vadd(void *thread_id)
{
  int tid = *(int *)thread_id;
  int i;
  for(i=tid*(ARRAY_SIZE/NUM_OF_THREADS);i<(tid+1)*(ARRAY_SIZE/NUM_OF_THREADS);i++)
  {
      c[i] = a[i] + b[i];
  }
  return NULL;
}
```

A. L is better, because the cache miss rate is lower
B. R is better, because the cache miss rate is lower
C. L is better, because the instruction count is lower
D. R is better, because the instruction count is lower
E. Both are about the same



Free-answer questions

Register renaming

- For the following C code:

```
do {
    number_of_nodes++;
    current = current->next;
} while ( current != NULL );
```

- Assume we have a dual-fetch, dual-issue, out-of-order pipeline where
  - INT ALU takes 1 cycle
  - MEM pipeline: 4 cycles in total
  - BR takes 1 cycle to resolve
- If the loop is taken twice, how many cycles it takes to issue all instructions?
- If the loop is taken 100 times, what's the average CPI?

Best cache configuration

- Consider the following code. Integers and pointers are both 4 bytes.

```
struct List {
    List * next;
    int data;
}

void foo(List *head) {
    List * cur = head;
    while(cur->next) {
        cur = cur->next;
    }
}
```

- For a given total cache size, what cache line size will provide the best performance for this code? (hint: Your answer should not depend on the number of lines or the associativity of the cache.)

Reverse caching

- Below, we have given you four different sequences of addresses generated by a program running on a processor with a data cache. Cache hit ratio for each sequence is also shown below. Assuming that the cache is initially empty at the beginning of each sequence, find out the following parameters of the processor's data cache (ensure that you sufficiently explain your answer)
  - Associativity (1, 2, or 4 ways)
  - Block size (1, 2, 4, 8, 16, or 32 bytes)
  - Total cache size (256B, or 512B)
  - Replacement policy (LRU or FIFO)

1. Address Sequence 1: [0, 2, 4, 8, 16, 32] Hit Ratio: 0.33
2. Address Sequence 2: [0, 512, 1024, 1536, 2048, 1536, 1024, 512, 0] Hit Ratio: 0.33
3. Address Sequence 3: [0, 64, 128, 256, 512, 256, 128, 64, 0] Hit Ratio: 0.33
4. Address Sequence 4: [0, 512, 1024, 0, 1536, 0, 2048, 512] Hit Ratio: 0.25

Open-ended questions

Code and cache miss rate

- Assume my cache has 16KB capacity, 16 byte block size and is 2-way set associative. Integers are 4 bytes. Give the C code for a loop that has a very poor hit rate in this cache but whose hit rate raises to almost 100% if we double the capacity to 32KB.

Branch predictions

- Increasing the size of a branch predictor typically reduces the chances of "aliasing" -- two branches sharing the same predictor. Usually, sharing results in negative interference (decreased prediction accuracy), but sometimes it can result in positive interference. Assuming a PC-indexed table of 2-bit predictors
  - Give an example of two branches (eg, show the T, N patterns for each, and how they are interleaved) that would result in positive interference (increased overall prediction accuracy).
  - Give an example of two branches that would result in negative interference.
  - Explain why most of the time you would expect to see negative interference with real code.

SMT v.s. CMP

- Both CMP & SMT exploit thread-level or task-level parallelism. Assuming both application X and application Y have similar instruction combination, say 60% ALU, 20% load/store, and 20% branches. Consider two processors:

  P1: CMP with a 2-issue pipeline on each core. Each core has a private L1 32KB D-cache

  P2: SMT with a 4-issue pipeline. 64KB L1 D-cache

  Which one do you think is better?

  A. P1
  B. P2

Other open-ended questions

- Given the instruction front-end is decoupled from the backend of the pipeline ALUs, do you think ISA still affect performance?
  - Emily Blem, Jaikrishnan Menon, and Karthikeyan Sankaralingam. 2013. Power struggles: Revisiting the RISC vs. CISC debate on contemporary ARM and x86 architectures. In Proceedings of the 2013 IEEE 19th International Symposium on High Performance Computer Architecture (HPCA) (HPCA '13). https://minds.wisconsin.edu/handle/1793/64923
  - Ashish Venkat and Dean M. Tullsen. 2014. Harnessing ISA diversity: design of a heterogeneous-ISA chip multiprocessor. In Proceeding of the 41st annual international symposium on Computer architecuture (ISCA '14). http://www.cs.virginia.edu/venkat/papers/isca2014.pdf
- What features in modern processor architecture enable the potential of "Meltdown and Spectre" attacks? Should we live without those features? How to solve these security issues?
  - M. D. Hill, J. Masters, P. Ranganathan, P. Turner and J. L. Hennessy, "On the Spectre and Meltdown Processor Security Vulnerabilities," in IEEE Micro, vol. 39, no. 2. http://pages.cs.wisc.edu/~markhill/papers/ieeemicro19_spectre_meltdown_2019_01_30
- What compiler optimizations would not be effective given OoO execution hardware?

Other open-ended questions

- Can you name and briefly describe a few “trends” in the dark silicon era?
- If you’re asked to design a machine learning hardware, what will you do?
- If you’re asked to build an Xeon Phi type processor where each core also has many-way SMT, are you going to give the processor more cache or better branch predictor?
- Can we focus on improving the throughput of computing instead of latency? Can you give an example on what type of applications will not work well in this way
- Pros and cons for branch prediction using perceptrons?

Announcement

- Assignment #4 due this Thursday
- iEVAL, until 6/9
  - Please fill the survey to let us know your opinion!
  - Don’t forget to take a screenshot of your submission and submit through iLearn — it counts as a **full credit notebook assignment**
  - **We will drop your lowest 2 notebook assignment grades**
  - **Still only one programming assignment will be dropped**
- Final Exam
  - The final exam will be held at
    BRNHL B118 (not the classroom for lectures)
    6/15/2023 11:30 a.m. – 2:30 p.m
  - Similar to the midterm, but more time and about 1.5x longer
  - Two of the problem sets will be comprehensive exam questions
- Last office hours
  - Hung-Wei Tseng: 6/12 3p-4p, 6/14 3:30p-4:30p
  - Kuan-Chieh Hsu: 6/13 3:30p-4:30p, 6/14 10:30a-11:30a

Computer Science & Engineering

203

Finale