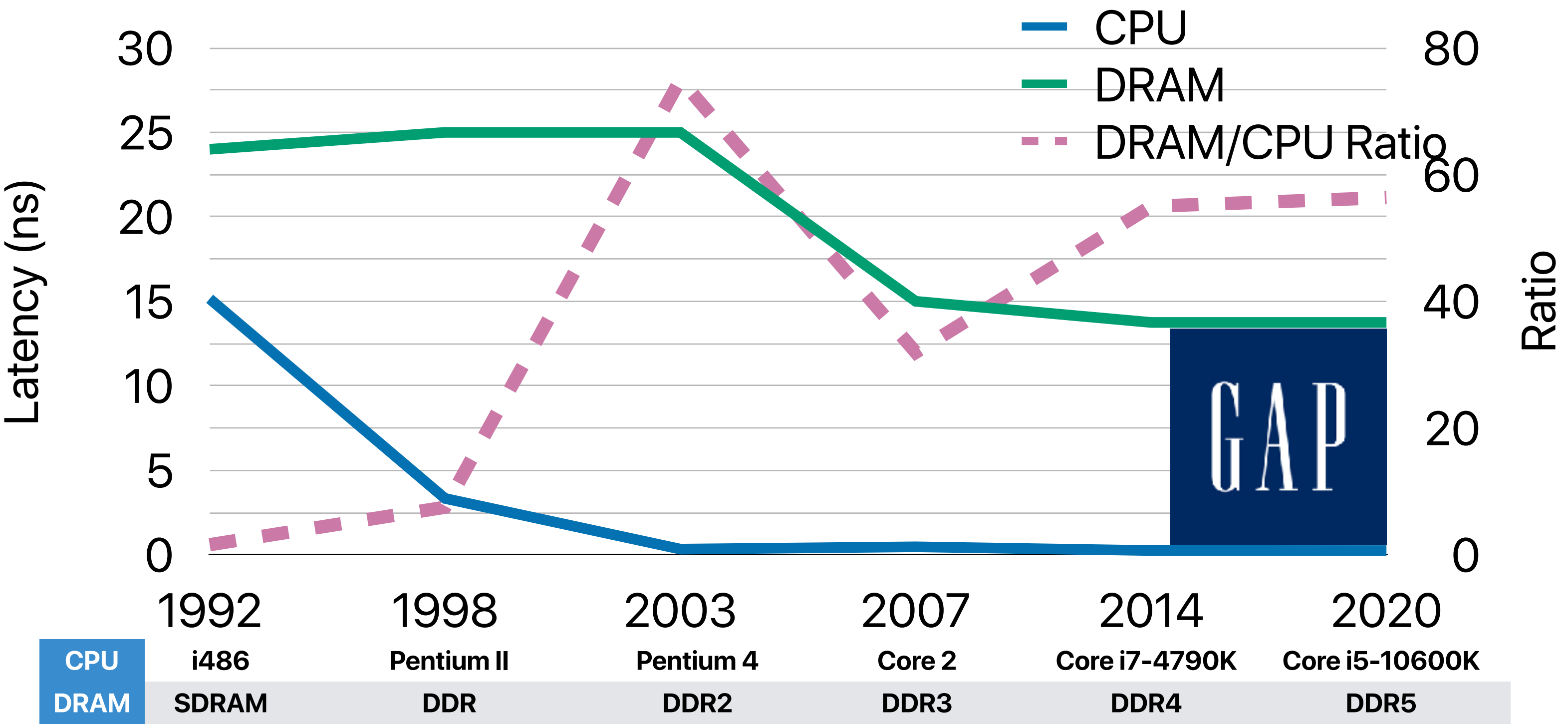


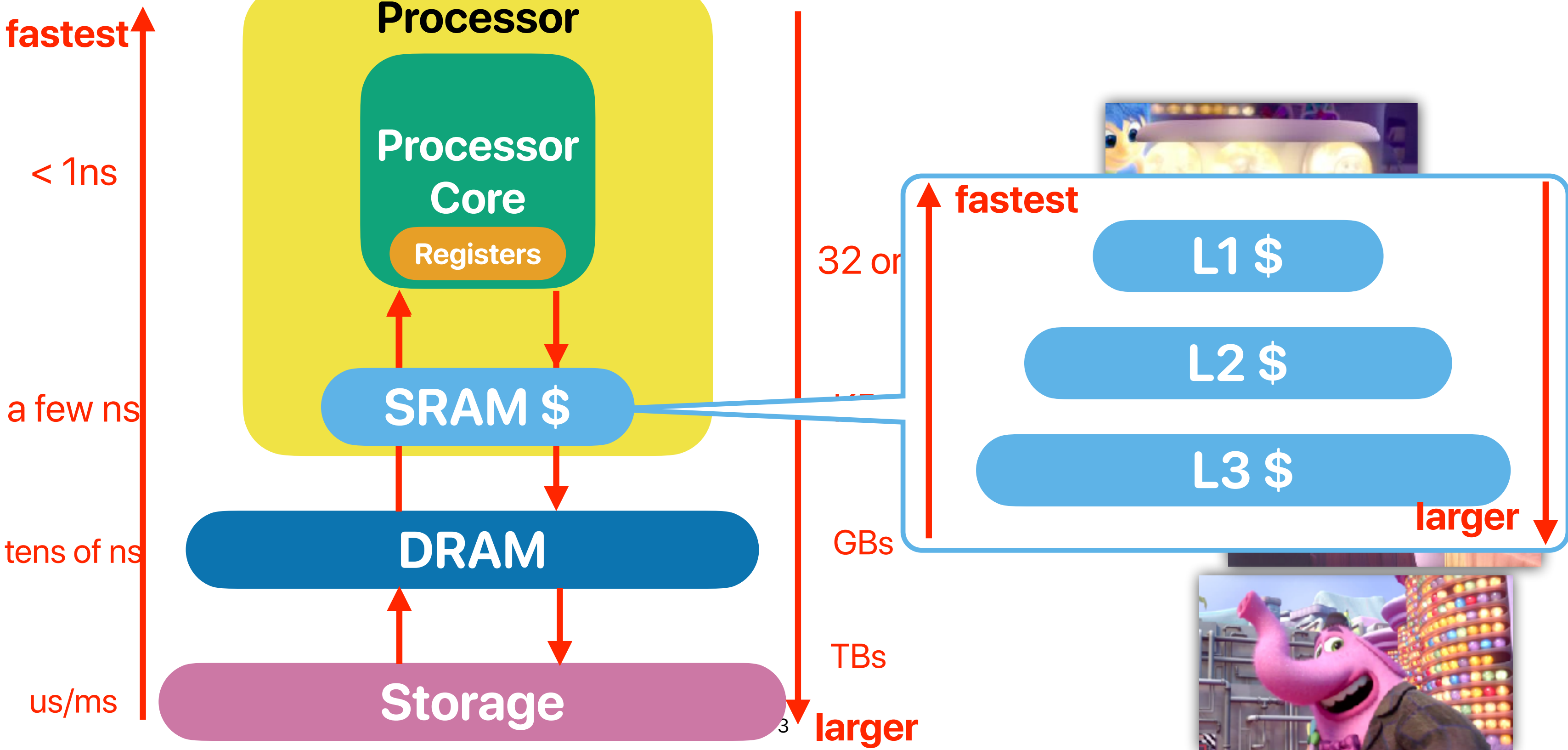
Virtual Memory: Just an Illusion

Hung-Wei Tseng

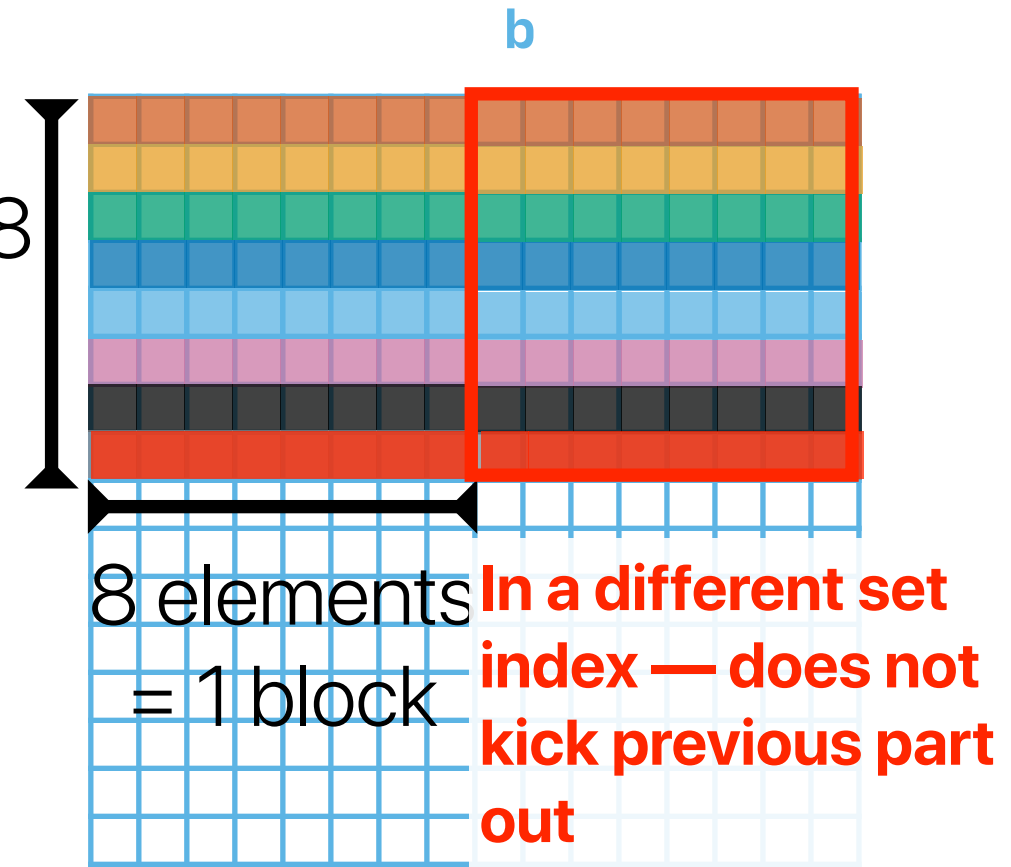
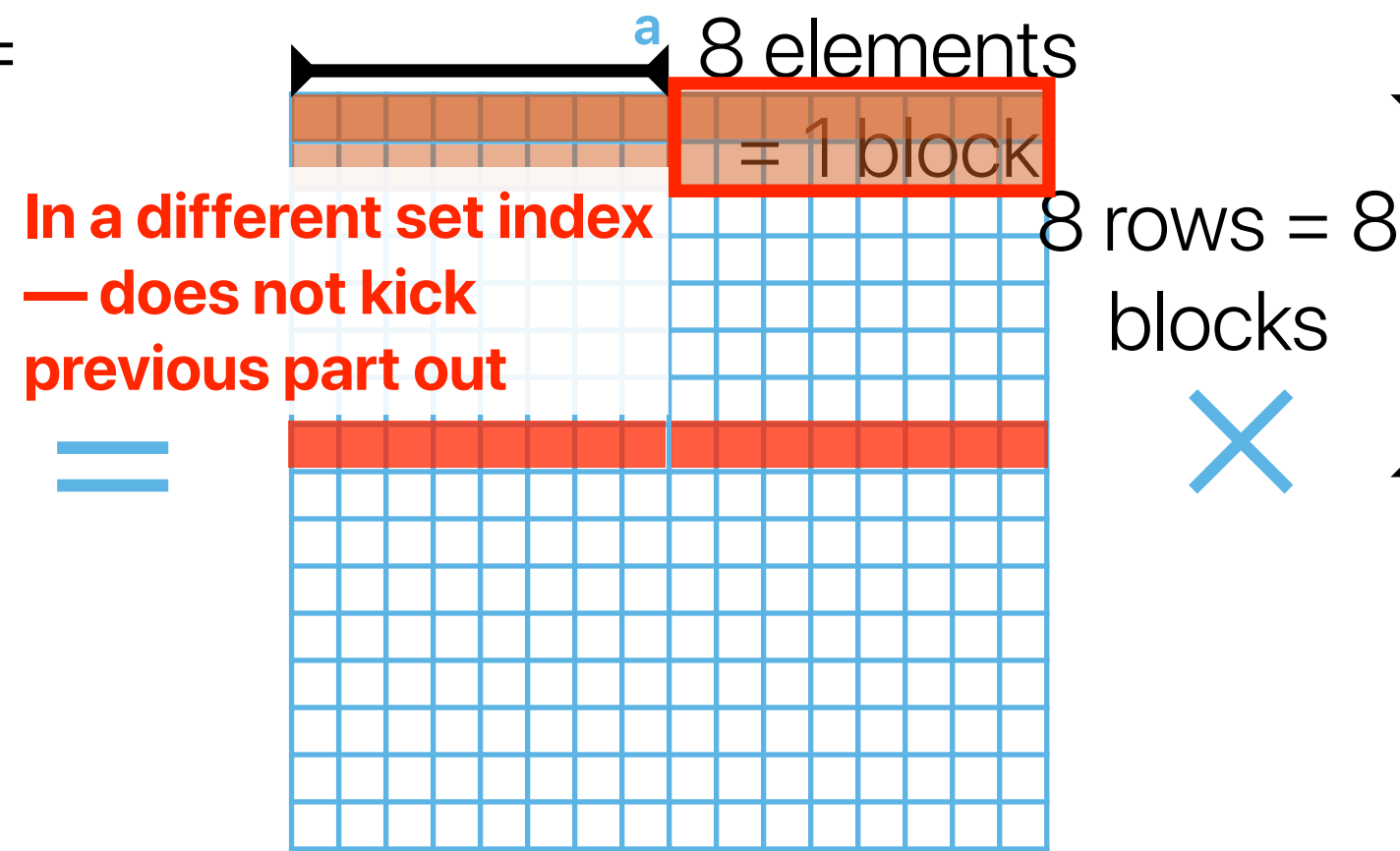
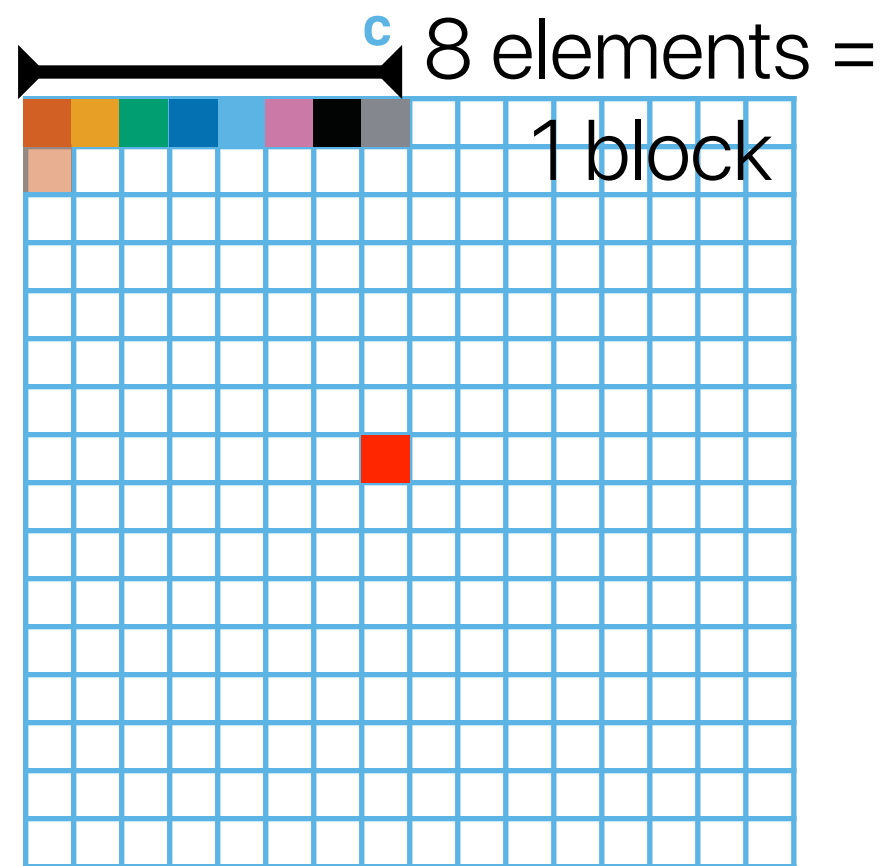
Recap: the "latency" gap between CPU and DRAM



Recap: Memory Hierarchy



Tiling/Blocking Algorithm for Transposed Matrix Multiplications



```
// Transpose matrix b into b_t
for(i = 0; i < ARRAY_SIZE; i+=(ARRAY_SIZE/n)) {
    for(j = 0; j < ARRAY_SIZE; j+=(ARRAY_SIZE/n)) {
        b_t[i][j] += b[j][i];
    }
}

for(i = 0; i < M; i+=tile_size)
    for(j = 0; j < K; j+=tile_size)
        for(k = 0; k < N; k+=tile_size)
            for(ii = i; ii < i+tile_size; ii++)
                for(jj = j; jj < j+tile_size; jj++)
                    for(kk = k; kk < k+tile_size; kk++)
                        c[ii][jj] += a[ii][kk]*b_t[jj][kk];
```

We can make the "tile_size" larger without interfacing conflict misses

Takeaways: Optimizing cache performance through hardware

- There is no optimal cache configurations — trade-offs are everywhere
 - Increasing C — (+): capacity misses; (-): cost, access time, power
 - Increasing A — (+): conflict misses; (-): access time, power
 - Increasing B — (+): compulsory misses; (-): miss penalty
- Adding a small buffer alongside the L1 cache can —
 - Virtually add an associative set to frequently used data structures
 - Prefetched blocks won't cause conflict misses
- Software Optimization
 - Data layout — capacity miss, conflict miss, compulsory miss
 - Loop interchange — conflict/capacity miss
 - Loop fission — conflict miss — when \$ has limited way associativity
 - Loop fusion — capacity miss — when \$ has enough way associativity
 - Blocking/tiling — capacity miss, conflict miss
 - Matrix transpose (a technique changes layout) — conflict misses
 - Using registers whenever possible — reduce memory accesses!
- Software-control, architectural-supported approach
 - Prefetching instructions
 - Adding a tag-less, programmable small buffer alongside the L1 cache can reduce power consumption

Let's dig into this code

```
int main(int argc, char *argv[])
{
    int i,j;
    double **a;
    double sum=0, average;
    int dim=32768;
    if(argc < 2)
    {
        fprintf(stderr, "Usage: %s dimension\n",argv[0]);
        exit(1);
    }
    dim = atoi(argv[1]);
    a = (double **)malloc(sizeof(double *)*dim);
    for(i = 0 ; i < dim; i++)
        a[i] = (double *)malloc(sizeof(double)*dim);
    for(i = 0 ; i < dim; i++)
        for(j = 0 ; j < dim; j++)
            a[i][j] = rand();
    for(i = 0 ; i < dim; i++)
        for(j = 0 ; j < dim; j++)
            sum+=a[i][j];
    average = sum/(dim*dim);
    fprintf(stderr,"average: %lf\n",average);
    for(i = 0 ; i < dim; i++)
        free(a[i]);
    free(a);
    return 0;
}
```



What will happen?

- If we execute the code on the right-hand side code on a machine with only 8 GB of physical memory installed and the dim is **33000** (requires $33000 \times 33000 \times 8$ bytes ~ **8.12 GB** memory at least), What will happen?
 - A. The program will crash in one of the malloc function call
 - B. The program will crash due to a "segmentation fault" that caused by accessing NULL pointer
 - C. The program will be killed automatically by the OS as it uses more than installed physical main memory
 - D. The program will finish without any issue

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        a[i] = (double *)malloc(sizeof(double)*dim);
    for(i = 0 ; i < dim; i++)
        for(j = 0 ; j < dim; j++)
            a[i][j] = rand();
    for(i = 0 ; i < dim; i++)
        for(j = 0 ; j < dim; j++)
            sum+=a[i][j];
    average = sum/(dim*dim);
    fprintf(stderr,"average: %lf\n",average);
    for(i = 0 ; i < dim; i++)
        free(a[i]);
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```
#define _GNU_SOURCE
#include <unistd.h>
#include <stdio.h>
#include <stdlib.h>
#include <assert.h>
#include <sched.h>
#include <sys/syscall.h>
#include <time.h>

double a;

int main(int argc, char *argv[])
{
    int i, number_of_total_processes=4;
    number_of_total_processes = atoi(argv[1]);
    // Create processes
    for(i = 0; i< number_of_total_processes-1 && fork(); i++);
    // Generate rand seed
    srand((int)time(NULL)+(int)getpid());
    a = rand();
    fprintf(stderr, "\nProcess %d. Value of a is %lf and address of a is %p\n",getpid(), a, &a);
    sleep(10);
    fprintf(stderr, "\nProcess %d. Value of a is %lf and address of a is %p\n",getpid(), a, &a);
    return 0;
}
```



Consider the following code ...

- Consider the case when we run 4 instances of the given program at the same time on modern machines, how many statements correct?

- ① The printed "address of a" is the same for every running instances
- ② The printed "address of a" is different for each instance
- ③ All running instances will print the same value of a for the first printf
- ④ Each instance will print a different value of a for the first printf
- ⑤ For the fprintf of 10 Seconds later, each running instance will print the same value from it's last run
- ⑥ For the fprintf of 10 Seconds later, each running instance will print a different value from it's last run

- A. 0
B. 1
C. 2
D. 3
E. 4

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#include <unistd.h>
#include <stdio.h>
#include <stdlib.h>
#include <assert.h>
#include <sched.h>
#include <sys/syscall.h>
#include <time.h>
#include <stdint.h>

double a = 0;

int main(int argc, char *argv[])
{
    uint64_t i, number_of_total_processes=4, p;
    if(argc < 2)
    {
        fprintf(stderr, "Usage: %s number_of_processes\n", argv[0]);
        exit(1);
    }
    number_of_total_processes = atoi(argv[1]);
    for(i = 0; i < number_of_total_processes-1 && fork(); i++);
    srand((int)time(NULL)+(int)getpid());
    a = rand();
    fprintf(stderr, "\nProcess %d: Value of a is %lf and address of a is %p\n", (int)getpid(), a, &a);
    sleep(10);
    fprintf(stderr, "\n10 Seconds Later -- Process %d: Value of a is %lf and address of a is %p\n", (int)getpid(), a, &a);
    return 0;
}
```



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    return 0;
}
```

Outline

- Virtual memory
- Architectural support for virtual memory

Virtual Memory

Demo revisited

&a = 0x5da1e73ef030

Process A

**Process A's
Virtual
Memory Space**

Process B

**Process B's
Virtual
Memory Space**

```
#define _GNU_SOURCE
#include <unistd.h>
#include <stdio.h>
#include <stdlib.h>
#include <assert.h>
#include <sched.h>
#include <sys/syscall.h>
#include <time.h>
#include <stdint.h>
```

```
double a = 0;
```

```
int main(int argc, char *argv[])
{
    uint64_t i, number_of_total_processes=4, p;
    if(argc < 2)
    {
        fprintf(stderr, "Usage: %s number_of_processes\n", argv[0]);
        exit(1);
    }
    number_of_total_processes = atoi(argv[1]);
    for(i = 0; i< number_of_total_processes-1 && fork(); i++);
    srand((int)time(NULL)+(int)getpid());
    a = rand();
    fprintf(stderr, "\nProcess %d: Value of a is %lf and address of a is %p\n", (int)getpid(), a, &a);
    sleep(10);
    fprintf(stderr, "\n10 Seconds Later -- Process %d: Value of a is %lf and address of a is %p\n", (int)getpid(), a, &a);
    return 0;
}
```

Why Virtual memory?

- Allowing multiple applications to share physical main memory
 - Memory protection/isolation among programs/processes is automatically achieved
- Allowing applications to work even the installed physical memory or available physical memory is smaller than the working set of the application
 - Programmer does not need to worry about the physical memory capacity of different machines — make compiled program compatible
 - Multiple programs can work concurrently even though their total memory demand is larger than the installed physical memory



Program A

0f00bb27	00c2e800
509cbd23	00000008
00005d24	00c2f000
0000bd24	00000008
2ca422a0	00c2f800
130020e4	00000008
00003d24	00c30000
2ca4e2b3	00000008



Program B

0f00bb27	00c2e800
509cbd23	00000008
00005d24	00c2f000
0000bd24	00000008
2ca422a0	00c2f800
130020e4	00000008
00003d24	00c30000
2ca4e2b3	00000008

Processor

Virtual memory

PC for A

PC for A

load



PC for B

PC for B

load

load



This approach is called demand paging + swapping

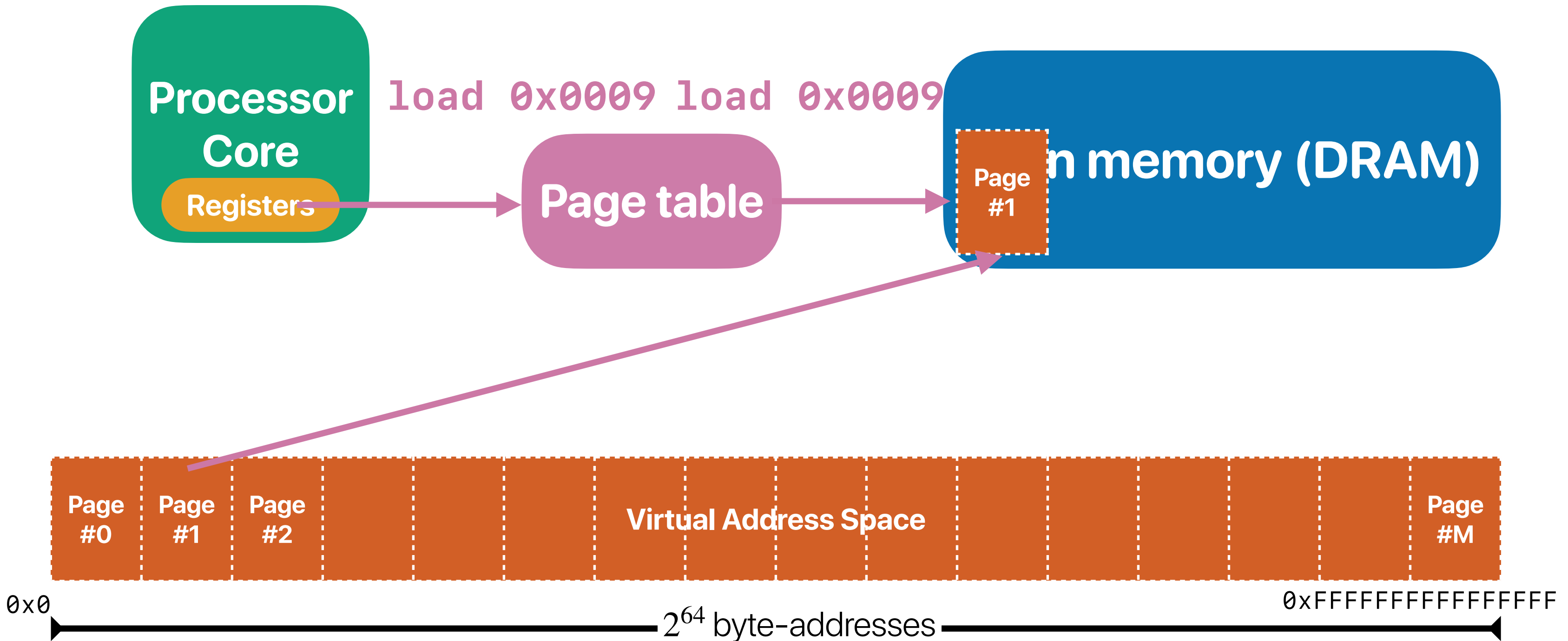
00c2f800	00c2e800
00000008	00000008
00c30000	00c2f000
00000008	00000008
2ca422a0	00c2e800
130020e4	00000008
00003d24	00c2f000
2ca4e2b3	00000008
0f00bb27	2ca422a0
509cbd23	130020e4
00005d24	00003d24
0000bd24	2ca4e2b3

Physical Memory



Swap

Demand paging — another angle



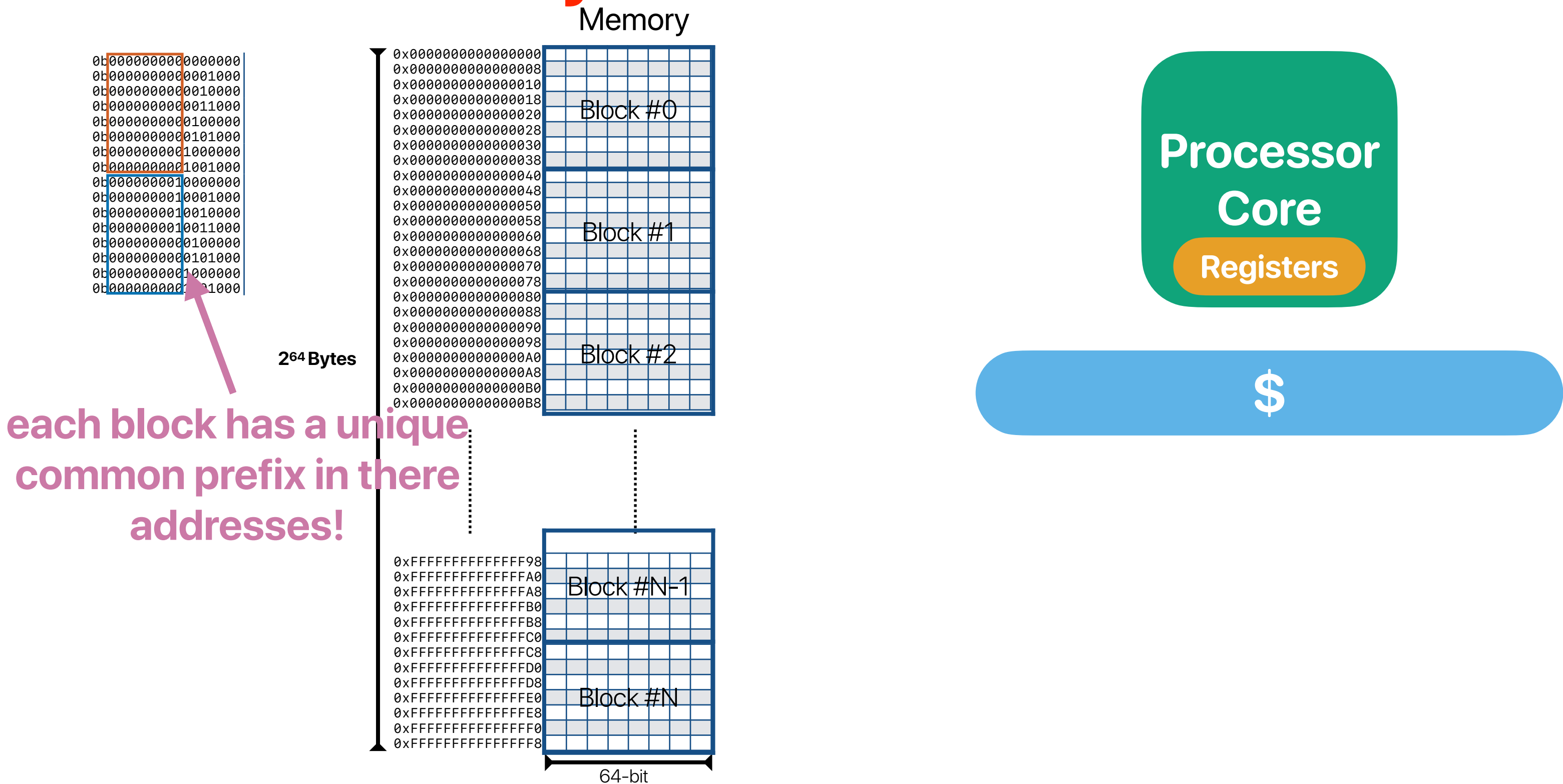
Virtual memory

- An **abstraction** of memory space available for programs/software/programmer
- Programs execute using virtual memory address
- The operating system and hardware work together to handle the mapping between virtual memory addresses and real/physical memory addresses
- Virtual memory organizes memory locations into "**pages**"

Demand paging + Swapping

- **Paging:** partition virtual/physical memory spaces into fix-sized pages
- **Page fault:** when the requested page cannot be found in the physical memory — created the demand of allocating pages!
- **Demand paging:** Allocate a physical memory page for a virtual memory page when the virtual page is needed (page fault occurs)
- **Swapping:** use secondary storage to store pages not in DRAM

Partition memory addresses into fix-sized chunks



Demand paging + Swapping v.s. caching

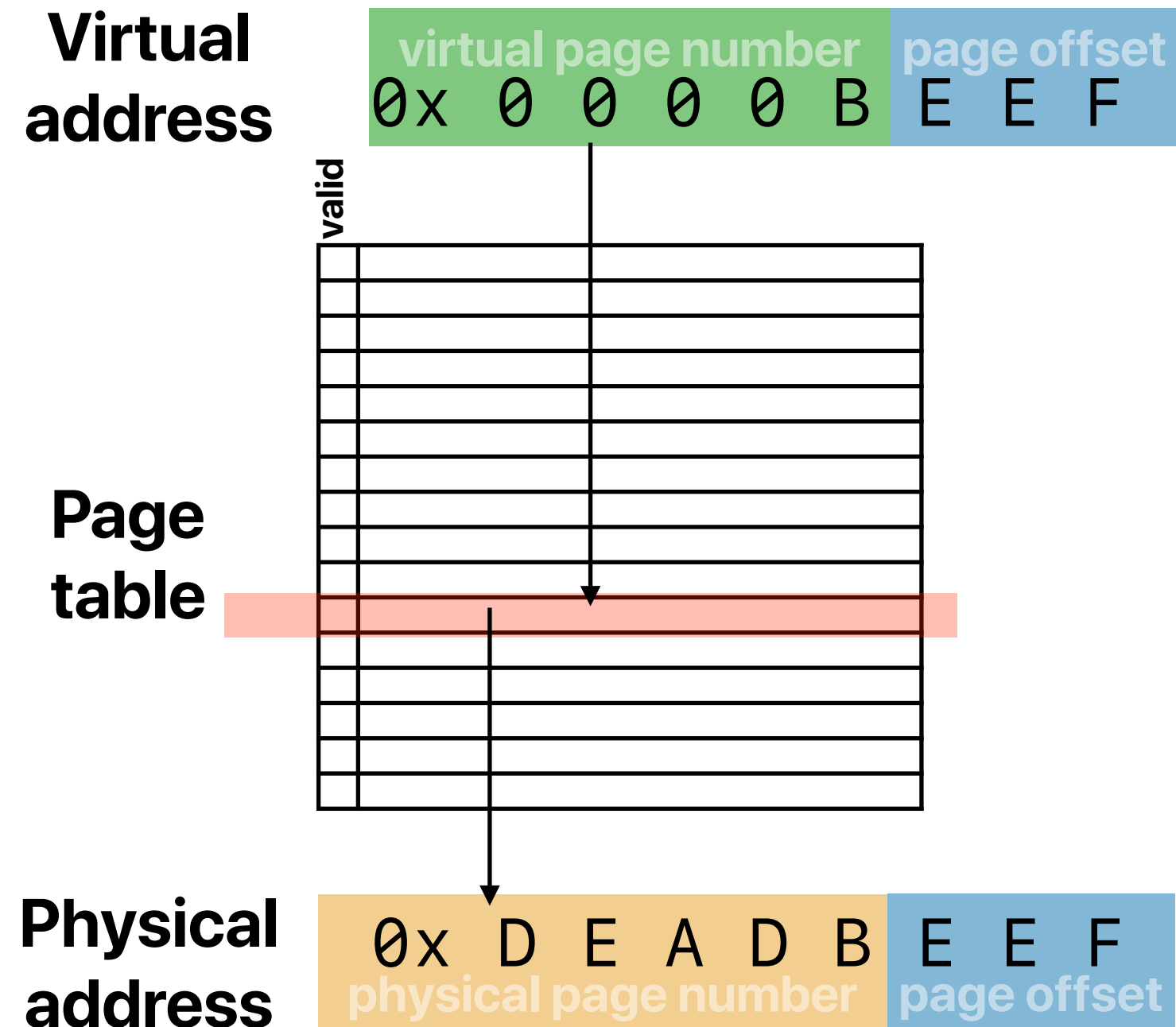
- Treating physical main memory as a “cache” of virtual memory
- The block size is the “page size”
- The page table is the “tag array”
- It’s a “fully-associate” cache — a virtual page can go anywhere in the physical main memory
- The storage serves as the lower level memory hierarchy for physical main memory

Takeaways: Virtual Memory

- Virtual memory is essential to support the success of software industry

Address translation

- Processor receives virtual addresses from the running code, main memory uses physical memory addresses
- Virtual address space is organized into "pages"
- The system references the **page table** to translate addresses
 - Each process has its own page table
 - The page table content is maintained by OS





Size of page table

- Assume that we have **64-bit** virtual address space, each page is 4KB, each page table entry is 8 Bytes, what magnitude in size is the page table for a process?
 - A. MB — 2^{20} Bytes
 - B. GB — 2^{30} Bytes
 - C. TB — 2^{40} Bytes
 - D. PB — 2^{50} Bytes
 - E. EB — 2^{60} Bytes

A screenshot of a poll interface. It shows five horizontal input boxes, each preceded by a letter (A, B, C, D, E) in a small font. The boxes are empty, suggesting a multiple-choice or open-ended poll where users can select or enter an answer.

Size of page table

- Assume that we have **64-bit** virtual address space, each page is 4KB, each page table entry is 8 Bytes, what magnitude in size is the page table for a process?

A. MB — 2^{20} Bytes

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C. TB — 2^{40} Bytes

D. PB — 2^{50} Bytes

E. EB — 2^{60} Bytes

$$\frac{2^{64} \text{ Bytes}}{4 \text{ KB}} \times 8 \text{ Bytes} = 2^{55} \text{ Bytes} = 32 \text{ PB}$$

If you still don't know why — you need to take CS202

Conventional page table

0x0

0xFFFFFFFFFFFFFFFF

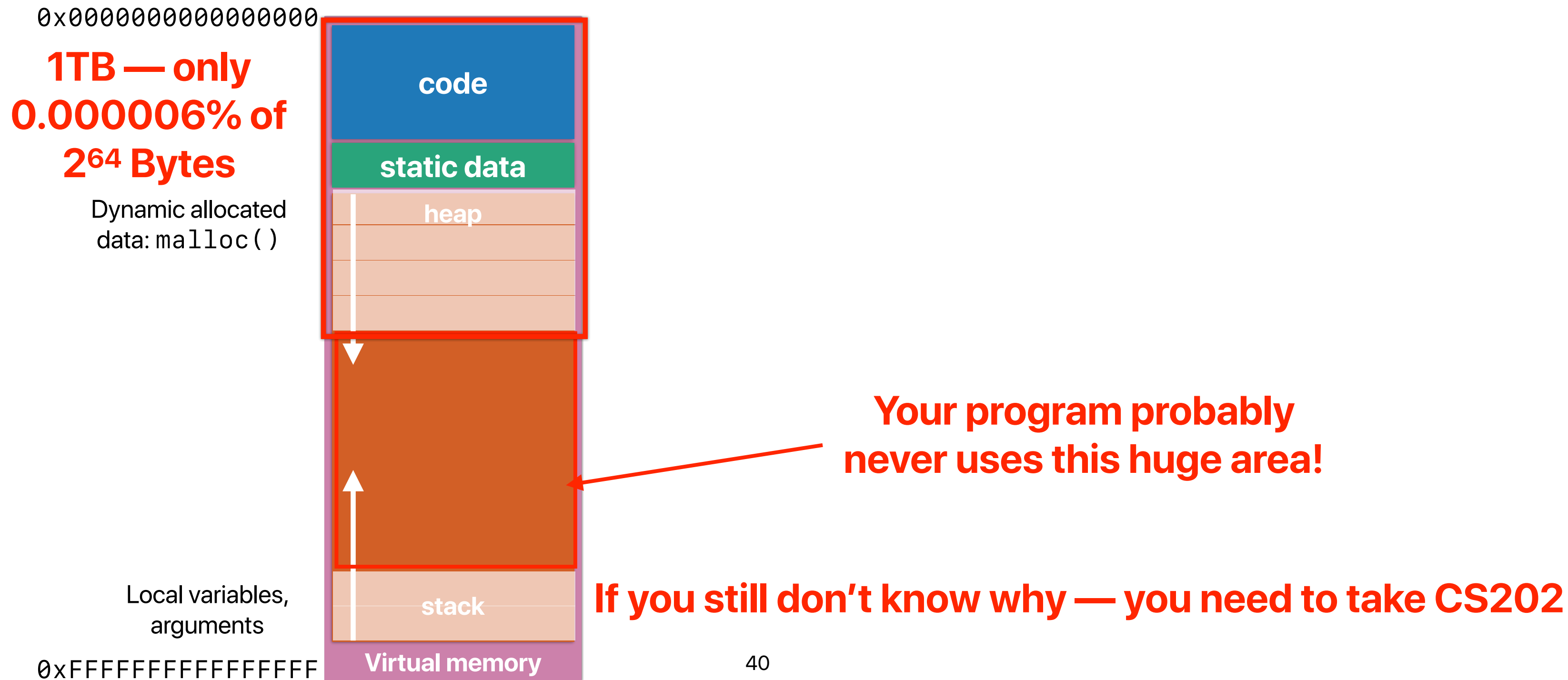
Virtual Address Space

- must be consecutive in the physical memory
- need a big segment! — difficult to find a spot
- simply too big to fit in memory if address space is large!

$\frac{2^{64} B}{2^{12} B}$ page table entries/leaf nodes



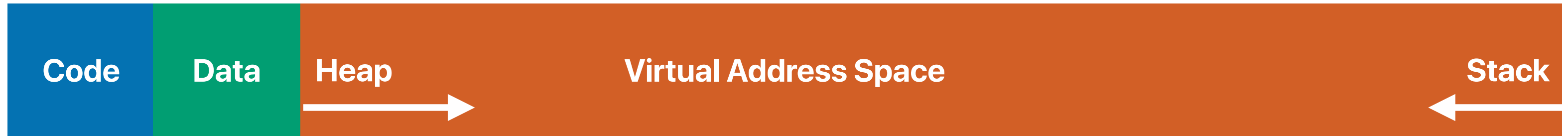
Do we really need a large table?



"Paged" page table

0x0

0xFFFFFFFFFFFFFFFF

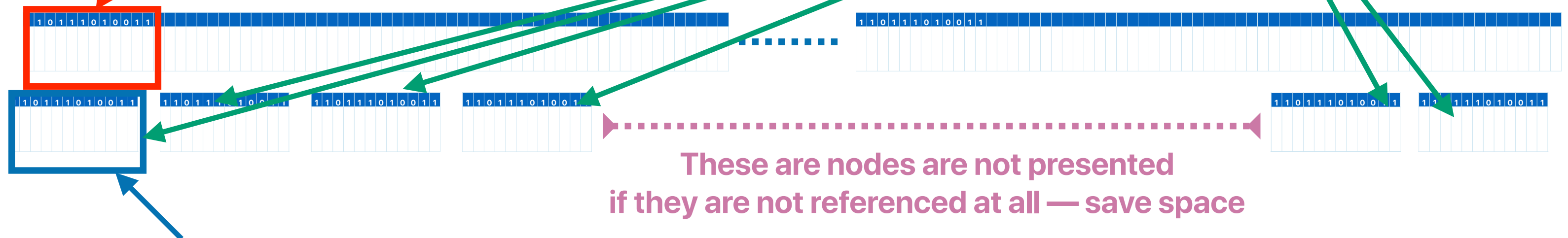


Break up entries into pages!
Each of these occupies exactly a page

$$\frac{2^{12} B}{2^3 B} = 2^9 \text{ PTEs per node}$$

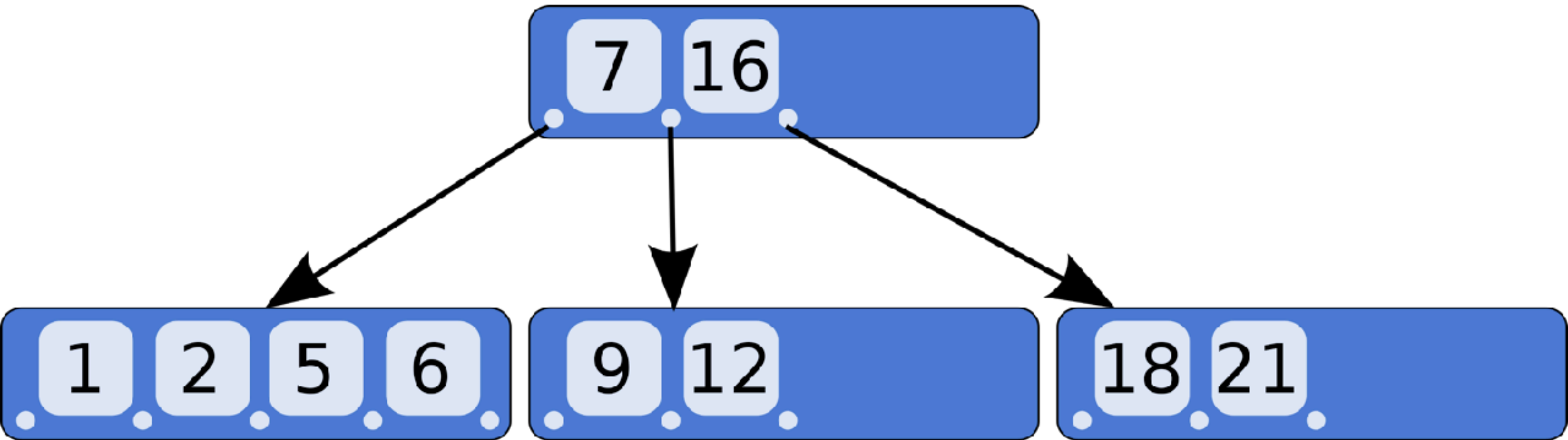
Otherwise, you always need to find more than one consecutive pages — difficult!

Question:
These nodes are spread out,
how to locate them in the memory?



Allocate page table entry nodes "on demand"

B-tree

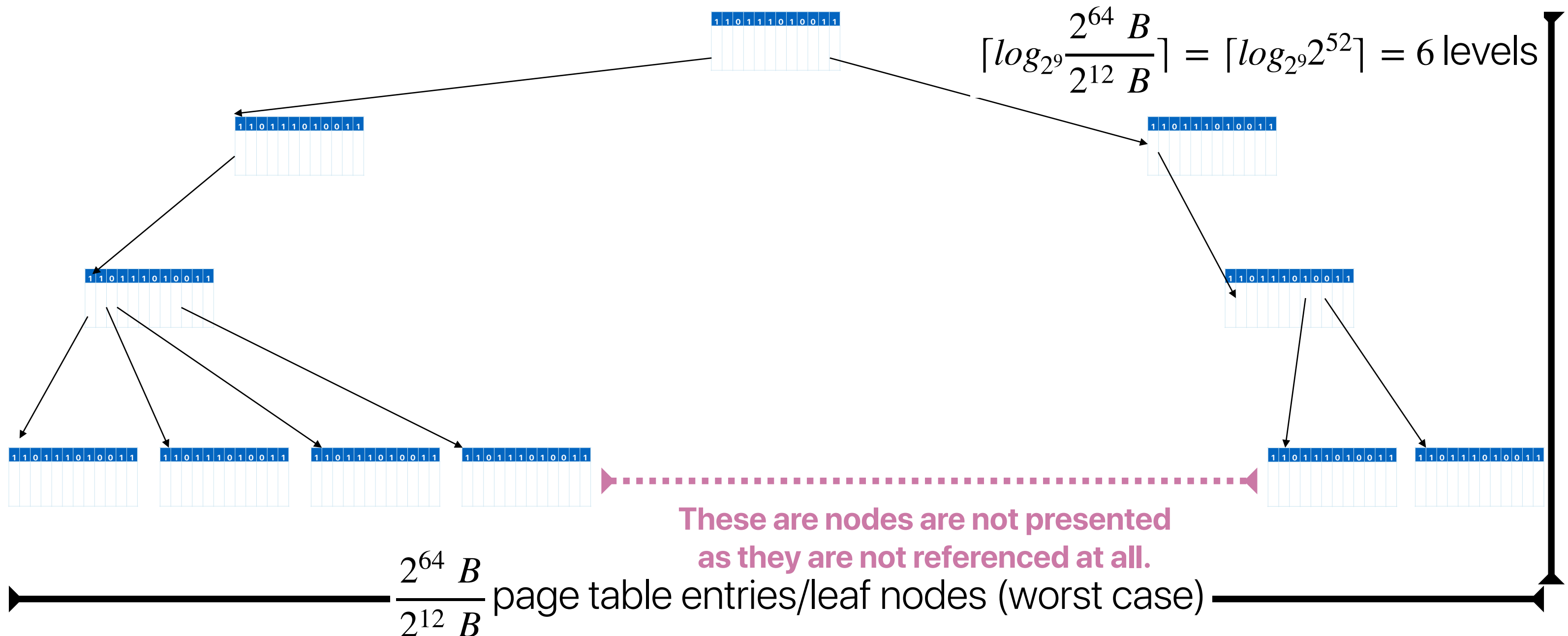
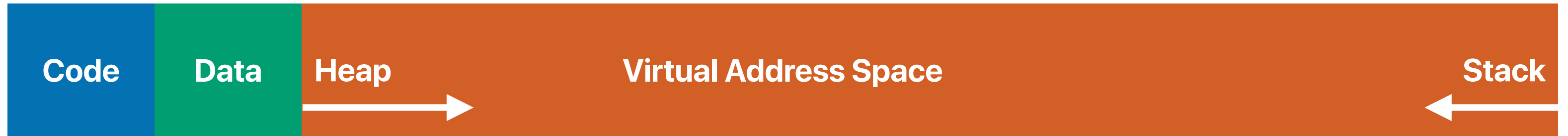


<https://en.wikipedia.org/wiki/B-tree#/media/File:B-tree.svg>

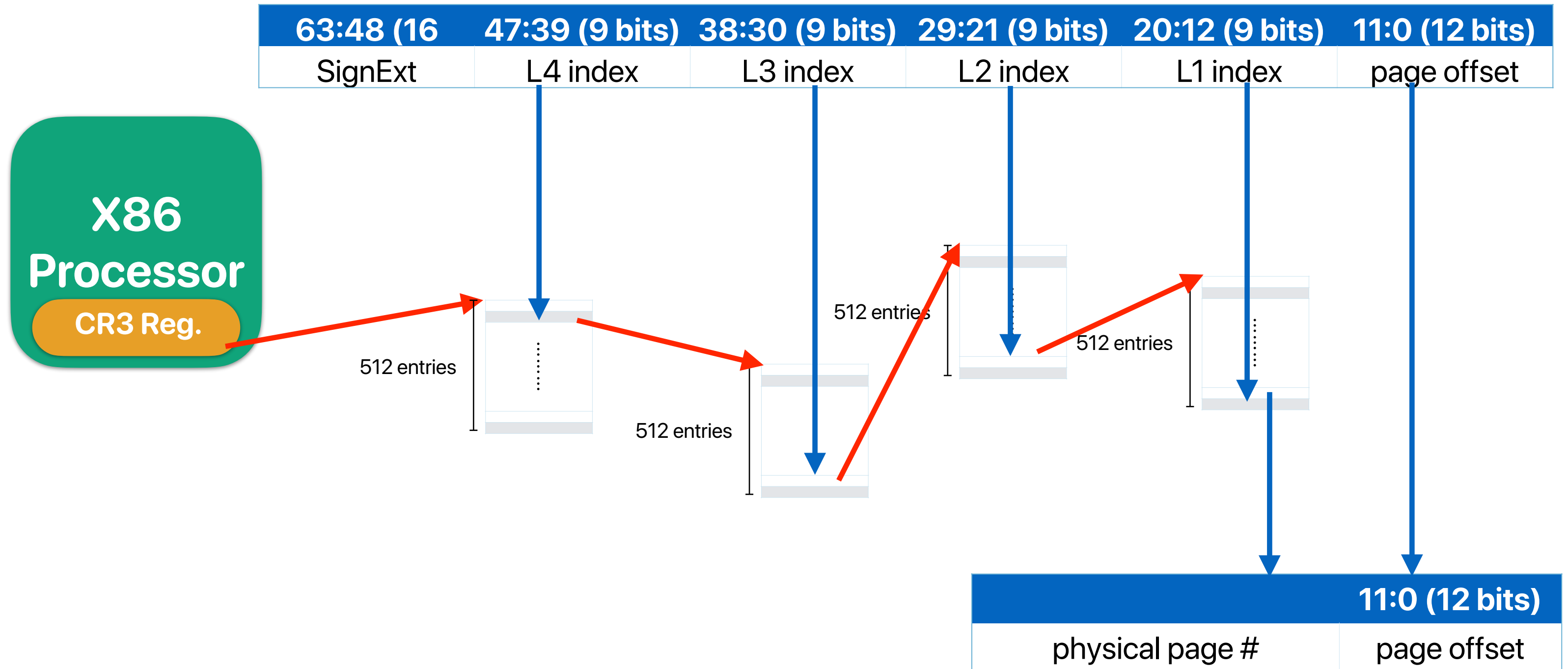
Hierarchical Page Table

0x0

0xFFFFFFFFFFFFFFFF



Address translation in x86-64



Takeaways: Virtual Memory

- Virtual memory is essential to support the success of software industry
- To reduce the page table size, we introduced hierarchical page table data structure

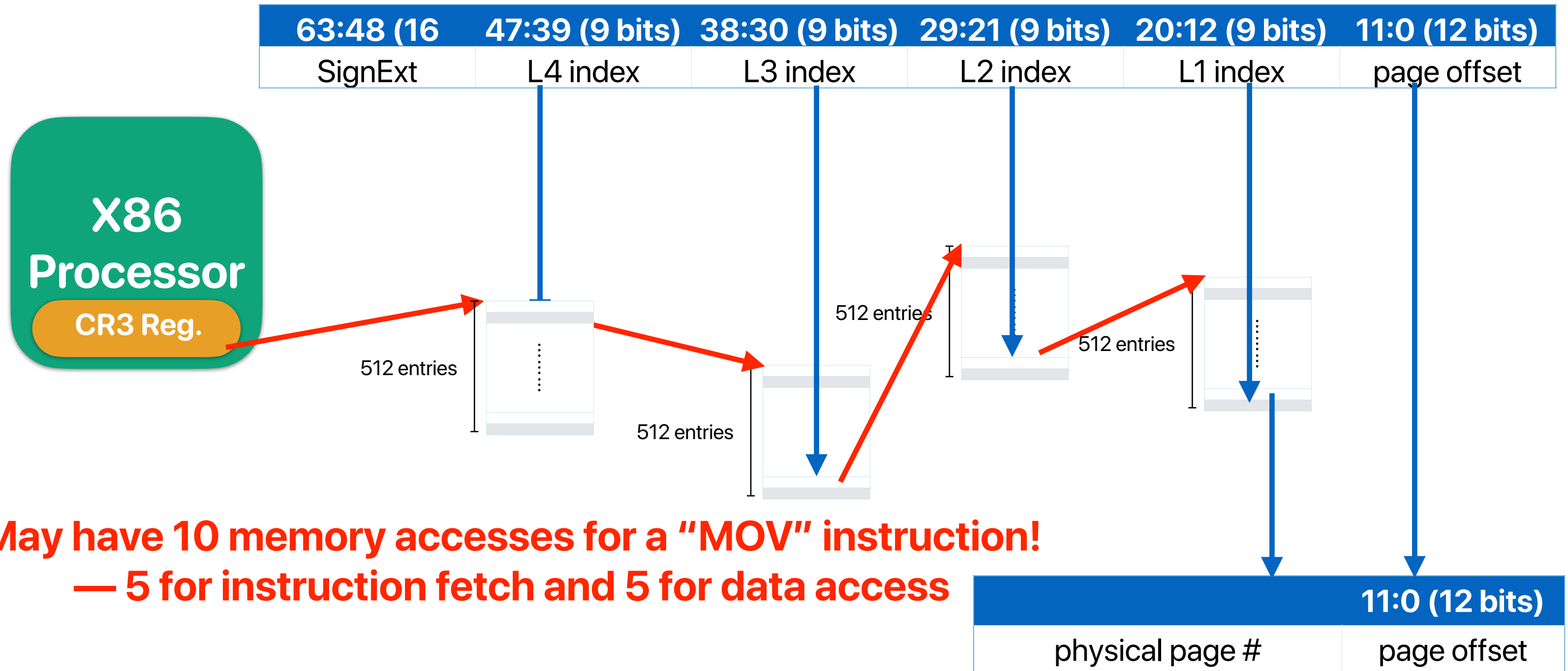


When we have virtual memory...

- If an x86 processor supports virtual memory through the basic format of the page table as shown in the previous slide, how many memory accesses can a **mov** instruction that access data memory once incur?
- A. 2
 - B. 4
 - C. 6
 - D. 8
 - E. 10

A
B
C
D
E

Address translation in x86-64

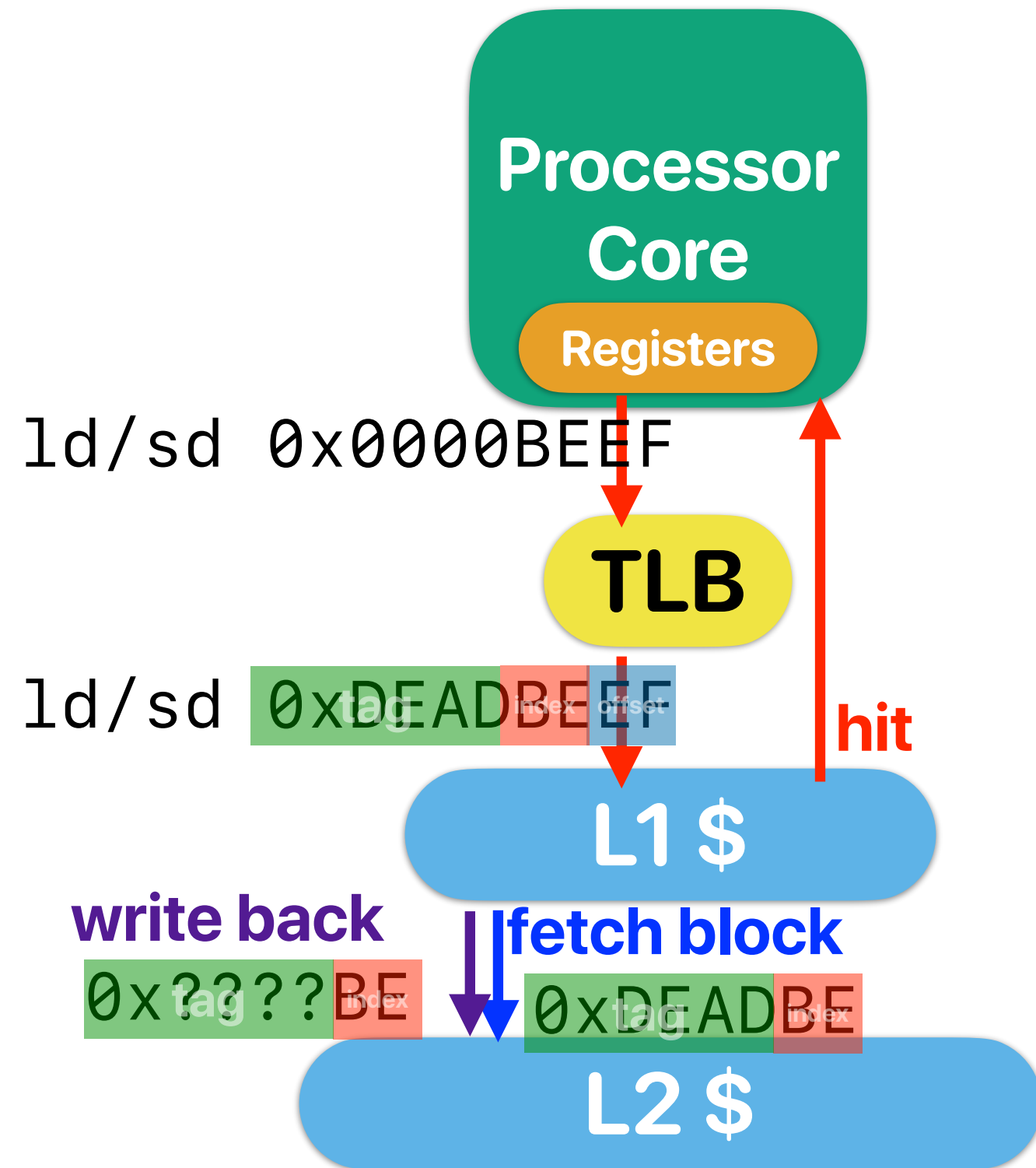


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 - C. 6
 - D. 8
 - E. 10

Avoiding the address translation overhead

TLB: Translation Look-aside Buffer



- TLB — a small SRAM stores frequently used page table entries
- Good — A lot faster than having everything going to the DRAM
- Bad — Still on the critical path

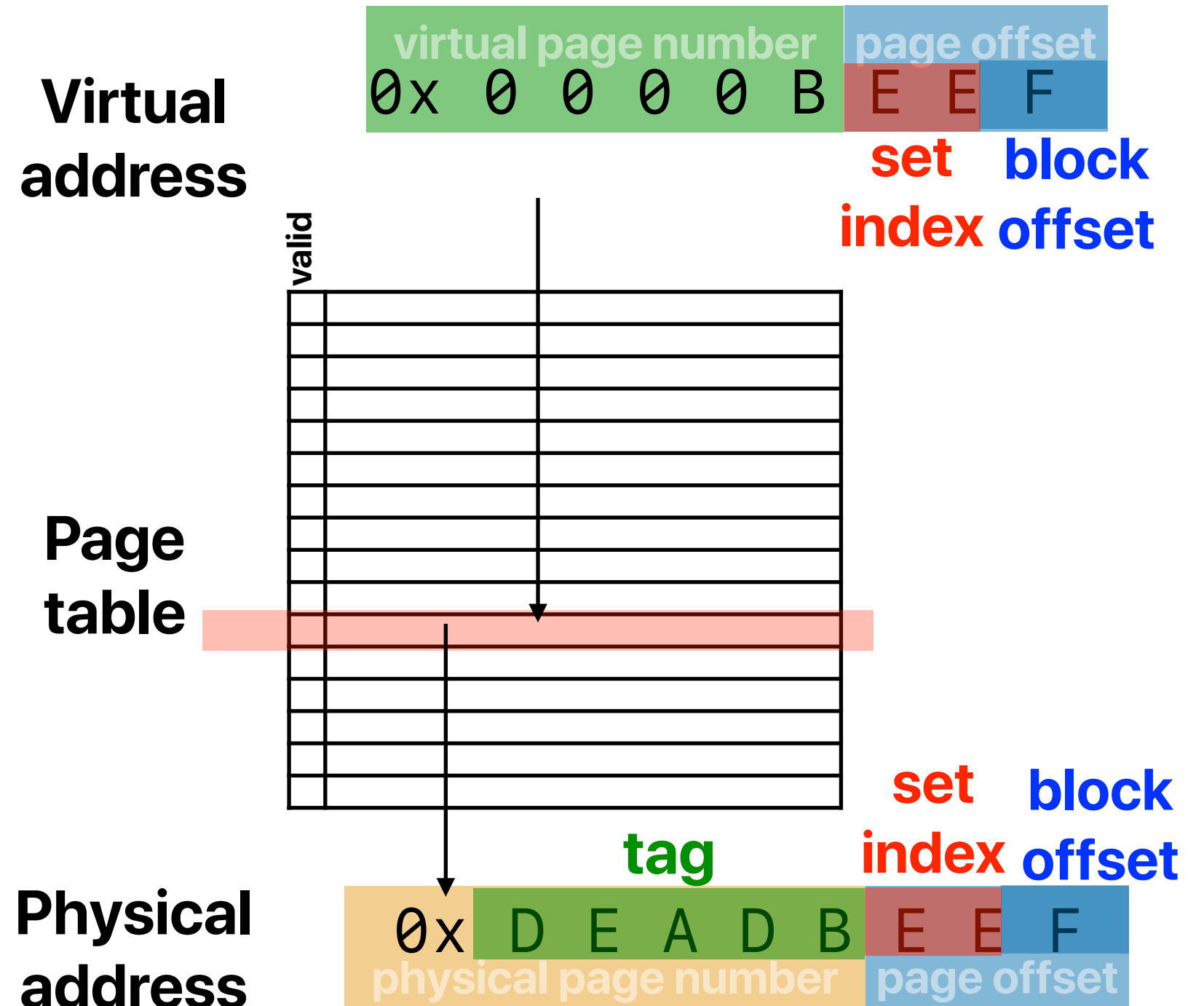
TLB + Virtual cache

- L1 \$ accepts virtual address — you don't need to translate
- Good — you can access both TLB and L1-\$ at the same time and physical address is only needed if L1-\$ misses
- Bad — it doesn't work in practice
 - Many applications have the same virtual address but should be pointing different **physical addresses**
 - An application can have "aliasing virtual addresses" pointing to the same **physical address**



Virtually indexed, physically tagged cache

- Can we find physical address directly in the virtual address — Not everything — but the page offset isn't changing!
- Can we indexing the cache using the "partial physical address"?
 - Yes — Just make set index + block set to be exactly the page offset



Virtually indexed, physically tagged cache

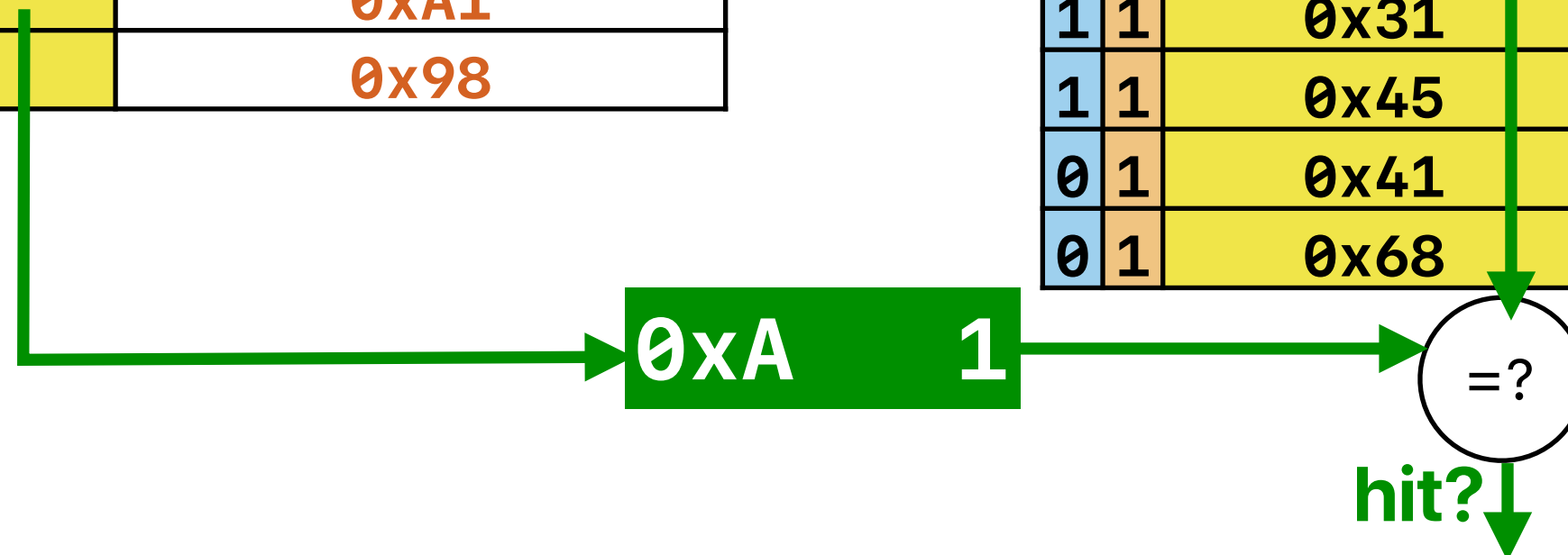
memory address:

0x0	8	2	4
		set	block

memory address: 0b0000100000100100

V	virtual page #	physical page #
1	0x29	0x45
1	0xDE	0x68
1	0x10	0xA1
0	0x8A	0x98

V D		tag	data
1	1	0x00	AABBCCDDEEGGFFHH
1	1	0x10	IIJJKKLLMMNNOOPP
1	0	0xA1	QQRRSSTTUUVVWWXX
0	1	0x10	YYZZAABBCCDDEEFF
1	1	0x31	AABBCCDDEEGGFFHH
1	1	0x45	IIJJKKLLMMNNOOPP
0	1	0x41	QQRRSSTTUUVVWWXX
0	1	0x68	YYZZAABBCCDDEEFF



Virtually indexed, physically tagged cache

- If page size is 4KB —

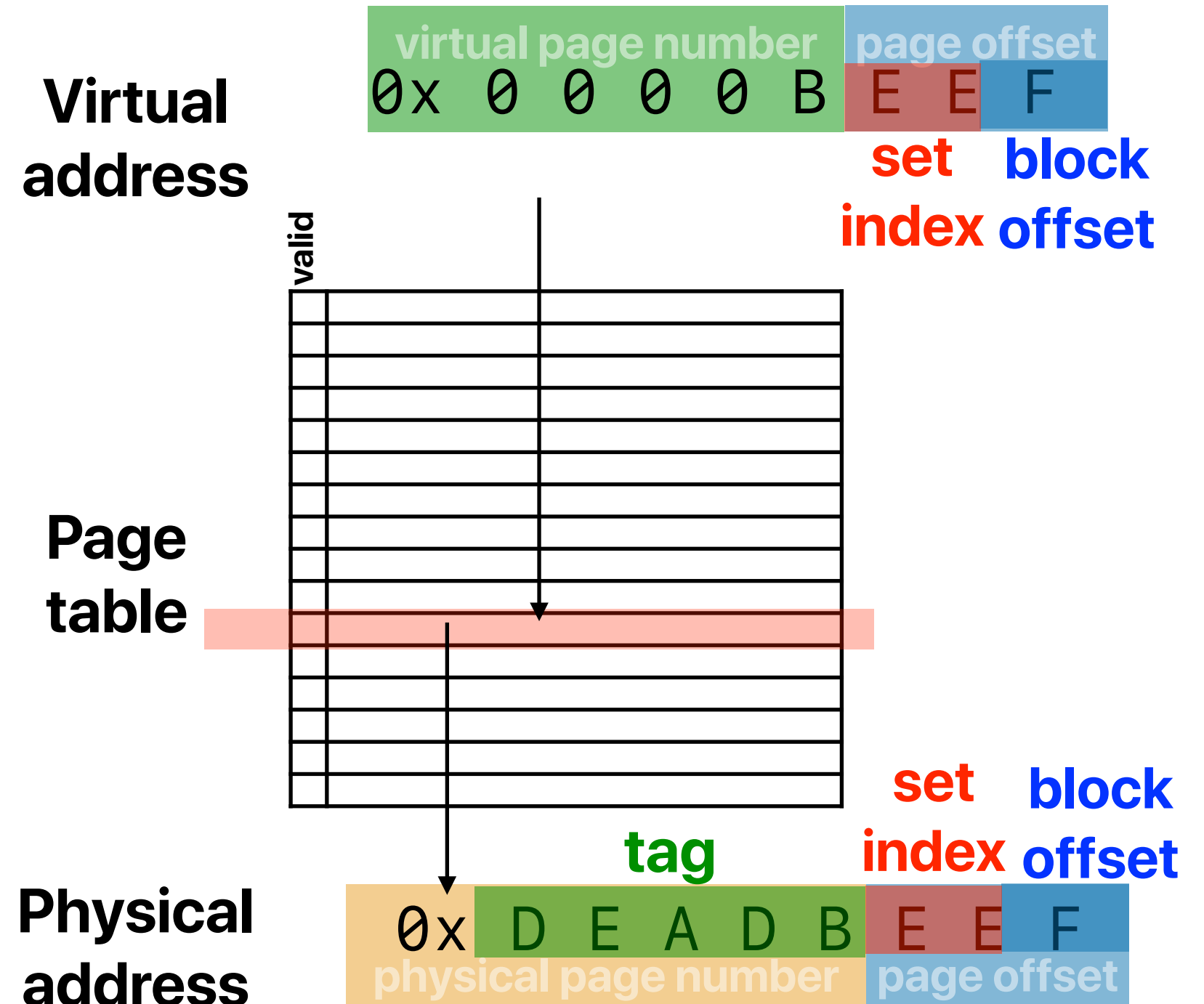
$$lg(B) + lg(S) = lg(4096) = 12$$

$$C = ABS$$

$$C = A \times 2^{12}$$

if $A = 1$

$$C = 4KB$$





Virtual indexed, physical tagged cache limits the cache size

- If you want to build a virtual indexed, physical tagged cache with 32KB capacity, which of the following configuration is possible? Assume the operating system use 4K pages.
 - A. 32B blocks, 2-way
 - B. 32B blocks, 4-way
 - C. 64B blocks, 4-way
 - D. 64B blocks, 8-way

A poll interface with four answer options labeled A, B, C, and D, each in a separate input box. The options are: A. 32B blocks, 2-way; B. 32B blocks, 4-way; C. 64B blocks, 4-way; D. 64B blocks, 8-way.

Virtual indexed, physical tagged cache limits the cache size

- If you want to build a virtual indexed, physical tagged cache with 32KB capacity, which of the following configuration is possible? Assume the operating system use 4K pages.

A. 32B blocks, 2-way

B. 32B blocks, 4-way

C. 64B blocks, 4-way

D. 64B blocks, 8-way

$$\lg(B) + \lg(S) = \lg(4096) = 12$$

$$C = ABS$$

$$32KB = A \times 2^{12}$$

$$A = 8$$

Exactly how Core i7 9th
generation configures its own
cache

Takeaways: Virtual Memory

- Virtual memory is essential to support the success of software industry
- To reduce the page table size, we introduced hierarchical page table data structure
- Virtually-indexed, physically tagged cache provides the efficiency for accessing cache and TLB together — but limited cache design

Takeaways: Virtual Memory

- Virtual memory is essential to support the success of software industry
- To reduce the page table size, we introduced hierarchical page table data structure
- Virtually-indexed, physically tagged cache provides the efficiency for accessing cache and TLB together — but limited cache design
- Page table caches & translation caching can help reducing the TLB miss penalty

Announcement

- Assignment #3 due **this Thursday**
- Programming Assignment #2 due **next Thursday**
 - Your grade is based on your speedup
 - You need to achieve 1.2x speedup for 100
- Reading quiz #6 due **next Tuesday** before the lecture
- Midterm will cover the lecture today with a different set of questions starting from tomorrow

Computer Science & Engineering

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