

A Multi-Class Classifier for Weapon Threats Detection in Images

Cao Peng (collect dataset, run code, write poster), Cao Qin (collect dataset, run code, write poster),

Fang Junyuan (dataset, write majority of poster, design, code and train machine learning model), Qin Guorui (collect and review most of dataset, write majority of poster, design, code and train machine learning model)

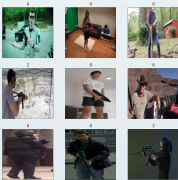
Dataset

Data collection

For each of the 3 categories mentioned above, we collected and labelled 500 images manually, which are actually screenshots taken from a collection of videos. We also spent a huge amount of efforts to replace duplicate images or obscure images in order to ensure that each image is clear with only a single human and as little background as possible.

Data pre-processing

We created the training and validation batched dataset (batch size 16) using tensorflow built preprocessing functions, and resized every image to a fixed size of 256×256 . Then, we applied data augmentation techniques to training dataset, including random flip, rotation, and zoom, to obtain a larger and more diverse data set. Lastly, normalization is applied to both training and validation sets with appropriate mean and variance values.

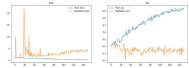


[examples of collected images]

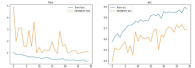


[examples of augmented images]

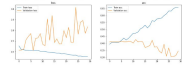
Baseline without batch normalization



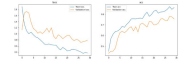
Baseline with batch normalization



Improved model without batch normalization

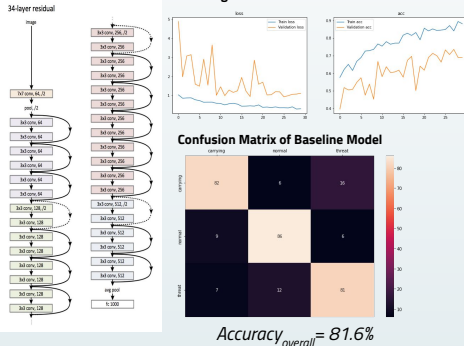


Improved model(drop out 0.5) with batch normalization



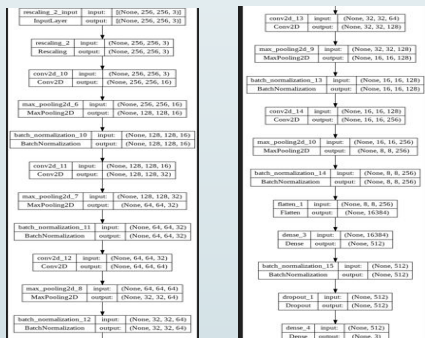
Baseline Model(ResNet with Batch normalization+dropout)

Learning Curve of Baseline Model

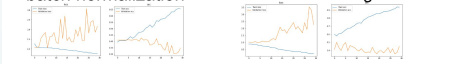


Improved Model

To fit our small dataset, we applied smaller number of convolutional layers.



Improved model without batch normalization but augmentation

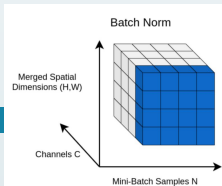
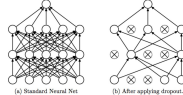


To Prevent Overfitting

Because the dataset is rather small, overfitting is the major challenge for us in the training process.

Dropout

We apply drop out between the last 2 dense layers to prevent all neurons synchronously optimize their weights to reduce overfitting.



Batch Normalization

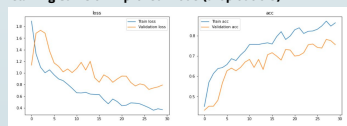
We apply batch normalization after each max pooling layer in turn to reduce the dependence on the gradients on the scale of parameters or the initial values.(increase level of generalization, improve the accuracy and reduce overfitting)

Performance

Learning Curve of Improved Model(drop out 0.1)



Learning Curve of Improved Model(drop out 0.5)



Confusion Matrix of improved model, drop out 0.1



$$\begin{aligned} \text{Accuracy}_{\text{normal}} &= 78.8\% & \text{Accuracy}_{\text{carrying}} &= 60.0\% \\ \text{Accuracy}_{\text{threat}} &= 69.3\% & \text{Accuracy}_{\text{overall}} &= 69.5\% \end{aligned}$$

Confusion Matrix of improved model, drop out 0.5 (Final model)



$$\begin{aligned} \text{Accuracy}_{\text{normal}} &= 85.1\% & \text{Accuracy}_{\text{carrying}} &= 92.3\% \\ \text{Accuracy}_{\text{threat}} &= 69.0\% & \text{Accuracy}_{\text{overall}} &= 82.3\% > 81.6\% \end{aligned}$$

Conclusion

The main focus of our model designing is about reducing the chance of overfitting, given the limited datasets (1500 images for 3 classes), compared with 50000 images for cifar-10, which are clearly augmented and grouped.

Our method works well, because the number of convolutional layers is appropriately chosen, especially, it is not over expressive. Also, the use of techniques after each convolutional layer and between layers with many weights to reduce overfitting is effective. Both reasons leads to a more successful model than the baseline model.