

# CS 725: Foundations of Machine Learning

OVERVIEW OF PROBABILITY THEORY FOR ML

August 16, 2020

# A review of probability theory

- Sample space( $S$ ): A sample space is defined as a set of all possible outcomes of an experiment. (For now *discrete*.)

Example of an experiment: a coin pair toss;  $S = \{HH, HT, TH, TT\}$ .

- Event ( $E$ ) : An event is any subset of the sample space. i.e.,  $E \subseteq S$ .

Often we describe events using “conditions.” E.g., the event that the two coin tosses are the same,  $E_{\text{same}} = \{HH, TT\}$ .

Events can be combined using logical operations on these conditions. E.g., “the two coin tosses are the same **or** the second one is  $T$ ”:

$$E = \{HH, TT\} \cup \{HT, TT\} = \{HH, TT, HT\}.$$

- **Probability distribution**,  $p$ : A function  $p : S \rightarrow [0, 1]$  s.t.

$$\forall x \in S, 0 \leq p(x) \leq 1, \sum_{x \in S} p(x) = 1.$$

# A review of probability theory

- Probability of an Event: The total weight assigned to all the outcomes in the event by a given probability distribution.

$$\Pr(E) = \sum_{x \in E} p(x)$$

- Note:
  - $\Pr(S) = 1$  and  $\Pr(\emptyset) = 0$
  - $\Pr(\overline{E}) = 1 - \Pr(E)$ , where  $\overline{E} = S \setminus E$
  - $\Pr(E_1 \cup E_2) = \Pr(E_1) + \Pr(E_2) - \Pr(E_1 \cap E_2)$
  - If  $E_1, E_2, \dots, E_n$  are pairwise disjoint events, then

$$\Pr\left(\bigcup_{i=1}^n E_i\right) = \sum_{i=1}^n \Pr(E_i)$$

# A review of probability theory

- Conditional Probability: For events  $E_1, E_2$  (s.t.  $\Pr(E_2) > 0$ ), define

$$\Pr(E_1|E_2) = \frac{\Pr(E_1 \cap E_2)}{\Pr(E_2)}$$

- Bayes' Rule, named after Thomas Bayes (1701-1761):

$$\Pr(A|B) = \frac{\Pr(B|A) \Pr(A)}{\Pr(B)},$$

provided  $\Pr(A), \Pr(B) > 0$ .

## Using Bayes' Rule

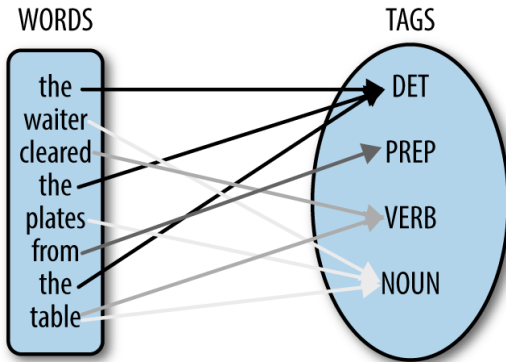
A lab test has a probability 0.95 of detecting a disease when applied to a person suffering from said disease, and a probability 0.10 of giving a false positive when applied to a non-sufferer. If 0.5% of the population are sufferers, what is the probability of a test on a random individual being positive?

## Example - Part of Speech

POS tagging is a popular Natural Language Processing (**NLP**) problem

**Input:** A set of n-words

**Output:** Part-of-speech (POS) tag for each word



Assuming each word is independently drawn from a fixed vocabulary, find the probability that a sentence of length  $m$  contains a 'noun' given that it contains a 'verb'. Say the probability that a word is of POS type 'k' is  $p_k$ .

**Solution:**

- Let  $A_k$  be the event that the sentence contains POS type 'k'

$$\Pr(A_k) = 1 - (1 - p_k)^m$$

where  $(1 - p_k)^m$  is the probability that all  $m$  words are not of POS type 'k'.

$$\Pr(A_{noun} \mid A_{verb}) = \frac{\Pr(A_{noun} \cap A_{verb})}{\Pr(A_{verb})}$$

$$\begin{aligned}
\Pr(A_j \cap A_k) &= 1 - \Pr(\overline{A_j} \cap \overline{A_k}) \\
&= 1 - \Pr(\overline{A_j} \cup \overline{A_k})
\end{aligned} \tag{1}$$

We know that  $\Pr(A \cup B) = \Pr(A) + \Pr(B) - \Pr(A \cap B)$ . Now, we need  $\Pr(\overline{A_j} \cap \overline{A_k})$ . This refers to the event that neither tag  $k$  nor tag  $j$  are present. Thus,  $\Pr(\overline{A_j} \cap \overline{A_k}) = (1 - (p_j + p_k))^m$ . Using this in Equation 1, we get

$$\begin{aligned}
\Pr(A_j \cap A_k) &= 1 - \Pr(\overline{A_j}) - \Pr(\overline{A_k}) + (1 - (p_j + p_k))^m \\
&= 1 - (1 - p_j)^m - (1 - p_k)^m + (1 - (p_j + p_k))^m
\end{aligned}$$

**Final answer:**

$$\Pr(A_{noun} \mid A_{verb}) = \frac{1 - (1 - p_{noun})^m - (1 - p_{verb})^m + (1 - p_{noun} - p_{verb})^m}{1 - (1 - p_{verb})^m}$$



# Random Variable

- Random variable ( $X$ ) : A variable that takes values from  $S$  according to a probability distribution.

E.g.,  $S = \{H, T\}$  and  $\Pr(X = H) = 2/3$ ,  $\Pr(X = T) = 1/3$ .

- Jointly distributed random variables:  $X, Y$  take values from sets  $S_1, S_2$  respectively, according to a distribution over  $S_1 \times S_2$ . (Generalizes to more than 2 random variables.)

E.g.,  $S_1 = S_2 = \{H, T\}$  and

$\Pr((X, Y) = (H, H)) = 1/3$ ,  $\Pr((X, Y) = (H, T)) = 1/3$ ,

$\Pr((X, Y) = (T, T)) = 1/6$ ,  $\Pr((X, Y) = (T, H)) = 1/6$ .

- Marginal Distribution: For  $x \in S_1$ ,  $\Pr(X = x) = \sum_{y \in S_2} \Pr((X, Y) = (x, y))$ .

Similarly, marginal distribution of  $Y$  can be computed.

# Independence of Random Variables

- For notational convenience:  $\Pr((X, Y) = (x, y))$  abbreviated as  $p(x, y)$ ,  $\Pr(X = x|Y = y)$  as  $p(x|y)$  and so on.
- $X, Y$  are said to be **independent** ( $X \perp\!\!\!\perp Y$ ) iff for all  $x, y$ , the events  $X = x$  and  $Y = y$  are independent. i.e.,  $p(x, y) = p(x)p(y)$ .
- $X, Y$  are said to be **conditionally independent** given  $Z$  iff for all  $x, y, z$  (with  $p(z) > 0$ ),  $p(x, y|z) = p(x|z)p(y|z)$ .

# Continuous Random Variables

Unlike discrete random variables which can take *finitely many* different values, **continuous random variables** can take on *infinitely many* values.

If the sample space for a continuous random variable is the set of all reals (i.e.  $x \in \mathbb{R}$ ), then

$$\int_{-\infty}^{\infty} p(x) dx = 1$$

where  $p(x)$  is referred to as the **probability density function (PDF)**.

Examples of commonly used continuous distributions:

Uniform distribution:

$$p(x) = \begin{cases} \frac{1}{b-a} & \text{if } a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$$

Gaussian distribution (mean  $\mu$ , variance  $\sigma^2$ ):  $p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left\{ -\frac{(x-\mu)^2}{2\sigma^2} \right\}$