Competitive Programming Library

Too bad to be Accepted

Contents

1 Dynamic Programming **1**

2 Bit Manipulation **2**

3 Algorithms **2**

4 Data Structures **3**

4.1 Strings 3

4.1.1 Trie (Prefix Tree) 3

4.2 Range Queries 3

4.2.1 Segment Tree 3

4.2.2 Sparse Table 4

5 Counting Principles **5**

5.1 nCr 5

5.1.1 Fast nCr 5

6 Graph Theory **5**

6.1 Dijkstra Algorithm 5

1 Dynamic Programming

2 Bit Manipulation

3 Algorithms

4 Data Structures

4.1 Strings

4.1.1 Trie (Prefix Tree)

Basic Implementation

```
#define MAX_CHAR 26

struct TrieNode {
    TrieNode *pTrieNode[MAX_CHAR]{};
    bool isWord;

    TrieNode() {
        isWord = false;
        fill(pTrieNode, pTrieNode + 26, (TrieNode *) NULL);
    }

    virtual ~TrieNode() = default;
};

class Trie {
private:
    TrieNode *root;
public:
    Trie() {
        root = new TrieNode();
    }

    virtual ~Trie() = default;

    TrieNode *getTrieNode() {
        return this->root;
    }

    void insert(const string &word) {
        TrieNode *current = root;
        for (char c: word) {
            int i = c - 'a';
            if (current->pTrieNode[i] == nullptr)
                current->pTrieNode[i] = new TrieNode();
            current = current->pTrieNode[i];
        }
        current->isWord = true;
    }

    bool search(const string &word) {
        TrieNode *current = root;
        int ch = 0;
        for (char c: word) {
            ch = c - 'a';
            if (current->pTrieNode[ch] == nullptr)
                return false;
            current = current->pTrieNode[ch];
        }
        return current->isWord;
    }

    bool startsWith(const string &prefix) {
        TrieNode *current = root;
        int ch = 0;
        for (char c: prefix) {
            ch = c - 'a';
            if (current->pTrieNode[ch] == nullptr)
                return false;
            current = current->pTrieNode[ch];
        }
        return true;
    }
};
```

4.2 Range Queries

4.2.1 Segment Tree

Basic Implementation

```
struct Node {
    long long val;
};

struct SegTree {
private:
    const Node NEUTRAL = {INT_MIN};

    static Node merge(const Node& x1, const Node& x2) {
        return {x1.val + x2.val};
```

```
    }

    void set(const int& idx, const int& val, int x, int lx, int rx) {
        if (rx - lx == 1) return void(values[x].val = val);

        int mid = (rx + lx) / 2;

        if (idx < mid)
            set(idx, val, 2 * x + 1, lx, mid);
        else
            set(idx, val, 2 * x + 2, mid, rx);

        values[x] = merge(values[2 * x + 1], values[2 * x + 2]);
    }

    Node query(const int& l, const int& r, int x, int lx, int rx) {
        if (lx >= r || l >= rx) return NEUTRAL;
        if (lx >= l && rx <= r) return values[x];

        int mid = (rx + lx) / 2;

        return merge(query(l, r, 2 * x + 1, lx, mid), query(l, r, 2 * x +
            2, mid, rx));
    }

public:
    int size{};
    vector<Node> values;


#warning ["not implemented yet"];
    void build() {}

    void init(int _size) {
        size = 1;
        while (size < _size) size *= 2;
        values.assign(2 * size, NEUTRAL);
    }

    void set(int idx, int val) {
        set(idx, val, 0, 0, size);
    }

    Node query(const int& l, const int& r) {
        return query(l, r, 0, 0, size);
    }
};
```

4.2.2 Sparse Table

5 Counting Principles

5.1 nCr

$$C(n,k) = \frac{n!}{(n-k)!k!} = \frac{n*(n-1)*(n-2)*...*(n-k+1)}{k!}$$

5.1.1 Fast nCr

$$C(n,k) = \frac{n*(n-1)*(n-2)*...*(n-k+1)}{1*2*3*...*k} = \prod_{i=0}^{k-1}\frac{n-i}{i+1} = \prod_{i=0}^{k-1}(n-i)(i+$$

Fast nCr

```
int nCr(const int& n, const int& r) {
    double res = 1;
    for (int i = 1; i <= r; ++i)
        res = res * (n - r + i) / i;
    return (int)(res + 0.01);
}
```

6 Graph Theory

6.1 Dijkstra Algorithm

```
#define INF (1e18) // for int defined as ll

int n, m;
vector<vector<pair<int, int>>> adj;
vector<int> cost;
vector<int> parent;

void dijkstra(int startNode = 1) {
    priority_queue<pair<ll, int>, vector<pair<ll, int>>,
   greater<>> pq;

    cost[startNode] = 0;
    pq.emplace(0, startNode);

    while (!pq.empty()) {
        int u = pq.top().second;
        ll d = pq.top().first;
        pq.pop();

        if (d > cost[u]) continue;

        for (auto &p: adj[u]) {
            int v = p.first;
            int w = p.second;
            if (cost[v] > cost[u] + w) {
                cost[v] = cost[u] + w;
                parent[v] = u;
                pq.emplace(cost[v], v);
            }
        }
    }
}

void run_test_case(int testNum) {
    cin >> n >> m;

    adj.assign(n + 1, {});
    cost.assign(n + 1, INF);
    parent.assign(n + 1, -1);
```

```
    while (m--) {
        // Read Edges
    }

    dijkstra();

    if (cost[n] == INF) {
        cout << -1 << el; // not connected {Depends on you
   use case}
        return;
    }

    stack<int> ans;
    for (int v = n; v != -1; v = parent[v]) ans.push(v);

    while (!ans.empty()) { // printing the path
        cout << ans.top() << ' ';
        ans.pop();
    }
    cout << el;
}
```

Dijkstra Implementation