



Transformer Encoder $(N \times T \times d)$

- 1) Multi-headed Self Attention
- 2) Layer Norm + Add $\rightarrow \begin{matrix} k \\ v \end{matrix} \} (1 \times d_h)$
- 3) Feed forward MLP layer
- 4) Layer Norm + Add \rightarrow 2-layers $(ReLU / GELU)$
 $\rightarrow d \rightarrow 4d \rightarrow d$

2 versions of VATT

- 1) Modality-specific $(T_a \neq T_t)$
 \rightarrow one encoder per modality
- 2) Modality-agnostic $(T_a = T_t)$
 \rightarrow one encoder is shared

Multimodal Projection Head $(N \times d) \rightarrow (N \times d_{proj})$

- 1) Extract the [CLS] of each modality or average pooling
- 2) Map them with a linear projection to 1D space.
- 3) This map can be of different types
 \rightarrow Hierarchical — "Dog bark" — Multiple layers to classify
 \rightarrow Linear — "Dog" "bark" — One layer to classify

Contrastive Learning

- 1) NCE (Noise Contrastive Estimation) — Audio + Transcript
- 2) MIL-NCE (Multiple Instance Learning NCE) — (1) + Labels

Drop Token

- \rightarrow Randomly drop some patches and corresponding text patches.
- \rightarrow Helps with computational load.
- \rightarrow Especially useful for our long sequences

Longer Data Foresight

- 1) $L_a \uparrow$ $L_t \uparrow$
- 2) $T_a \uparrow$ $T_t \uparrow$
- 3) Can experiment with $\left\{ \begin{array}{l} \text{changes in sample rate} \\ \text{vs} \\ \text{more aggressive drop token} \\ \text{vs} \\ \text{changes in model dimensions} \end{array} \right\}$
- 4) Num-layers \uparrow