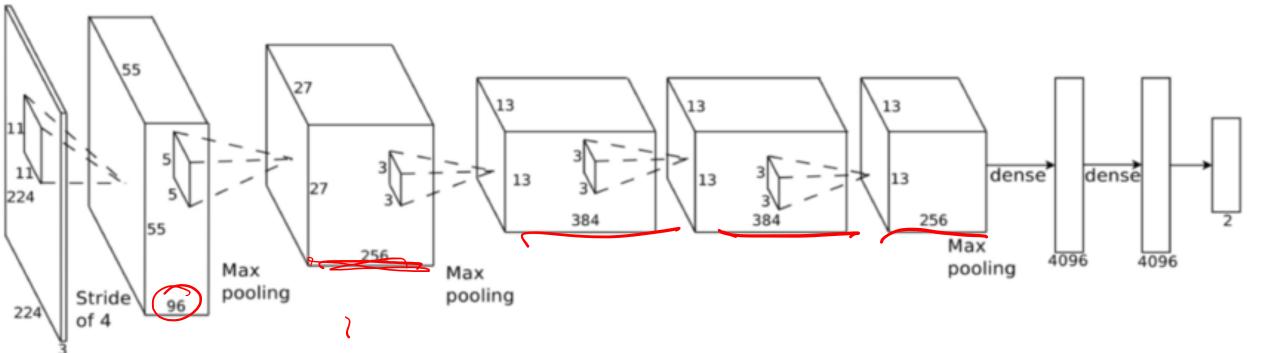
# **Final Project**

## After this lab, you'll be able to...

- If you want
  - Vectorize loops using the OpenMP `simd` directive.
  - Interpret the output of gcc to understand where it successfully vectorizes code.
  - Modify code to improve vectorizability
- Gain more practice applying other optimizations to a larger CNN model



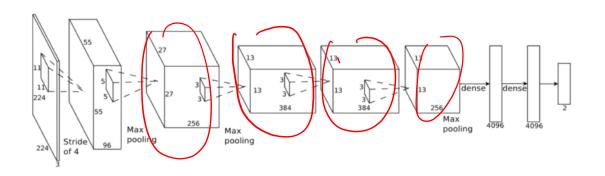
## **Alex Net**



- The most famous neural network
- Started the current AI crazy
- Built for the imagenet competition and destroyed everyone.
- Huge (at the time)
  - ← 60 million weights
  - 20 Canela-style layers
  - 2 weeks to train on two GPUS



## In this lab: Mininet

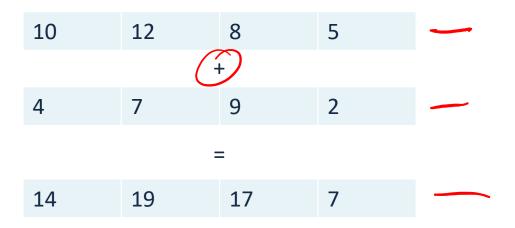


- 1/4 the size of AlexNet
- 128x128 pixel RGB images
- 590MB of weights

## SIMD: Single Instruction Multiple Data

Ve cton

- A single instruction operates on multiple data values (I.e., a 'vector')
  - 1 instruction
  - 4 additions





## SIMD: Single Instruction Multiple Data

A single instruction operates on multiple data values (I.e., a 'vector')

- 1 instruction
- 4 additions at once!
- CPI = 1, Cycles/addition = 0.25

10	12	8	5				
+							
4	7	9	2				
=							
14	19	17	7				



### **How To Use SIMD**

- Option 1: OpenMP Open multiprocessing)
  - "#pragma omp simd"
  - Somewhat portable across compilers
- Option 2: gcc 03
  - But 4 Shoulds steeld Rely on gcc's auto-vectorizer (turned on by default)
    - Not 'portable' because it's transparent
    - Same internal implementation as "omp simd"
    - Doesn't handle long vectors only leath=2
- Option 3.1: By hand compiler "intrinsic"
- Option 3.2: By hand gcc support vector data types
- Option 3.3: inline assembly
- I'll talk about option 3 in class tomorrow.



# x86 Vectors (AVX instructions)

- Our processor support 128 and 256-bit vectors
- They can be divided into vectors of different sizes
  - 16 or 32 8-bit ints
  - 8 or 16 16-bit ints
  - 4 or 8 32-bit ints
  - 2 or 4 64-bit ints
  - 4 or 8 32-bit floats
  - 2 or 4 64-bit floats



### SSE/AVX Registers

## Yet More x86 Registers

**Integer Registers** 

16bit	32bit	64bit	Description	
AX	EAX	RAX	The accumulator register	
ВХ	EBX	RBX	The base register	
CX	ECX	RCX	The counter	
DX	EDX	RDX	The data register	
SP	ESP	RSP	Stack pointer	
ВР	EBP	RBP	Points to the base of the stack frame	
	R <i>n</i>	R <i>n</i> D	(n = 815) General purpose registers	
SI	ESI	RSI	Source index for string operations	
DI	EDI	RDI	Destination index for string operations	
IP	EIP	RIP	Instruction Pointer	
FLAGS			Condition codes	

#### **MMX** Registers

x87 name	MMX name	Description
ST7	MM7	
ST6	MM6	
ST5	MM5	– 64 bit each.
ST4	MM4	MMX: 1 double- or single-precision
ST3	MM3	floating point value.
ST2	MM2	x87: 32, 64, or 80bits
ST1	MM1	
ST0	MM0	

AVX-512 names 512 bits	AVX names 256 bits	SSE names 128 bits
ZMM0	YMM0	XMM0
ZMMI	YMMI	XMMI
ZMM2	YMM2	XMM2
ZMM3	YMM3	XMM3
ZMM4	YMM4	XMM4
ZMM5	YMM5	XMM5
ZMM6	YMM6	XMM6
ZMM7	YMM7	XMM7
ZMM8	YMM8	XMM8
ZMM9	YMM9	XMM9
ZMM10	YMM10	XMMI0
ZMMII	YMM11	XMMII
ZMM12	YMM12	XMM12
ZMM13	YMM13	XMM13
ZMM14	YMM14	XMM14
ZMM15	YMM15	XMM15

- Each XMM/YMM/ZMM register can hold
  - 8, 16, 32, 64, or 128-bit integers (totaling 128 bits)
    - e.g., 16 x 8-bit int or 4 x 32-bit int or 2 x 64-bit int.
  - 32 or 64-bit FP totaling 128 (XMM), 256 (YMM), or 512 (ZMM) bits.
    - e.g., 16 x 32-bit int in ZMM0

## **Vector Operations**

#### Math

- +, -, \*, /, etc.
- Example: "vaddps (%rsi, %rax,4), %ymm0, %ymm1"
  - 'v' == AVX prefix
  - 'p' == packed (i.e., vector)
  - 's' == single-precision (32-bit float)
  - 'ymm0' and 'ymm1' name 256-bit registers, so it adds vectors of 8 32-bit floats
  - 3 arguments!!! The source is not overwritten!!! It's a miracle!!!

### Load/store

- Versions of 'mov' can load whole vectors from memory
- Example: `vmovups %ymm0 (%rdx, %rax, 4)`
  - 'v' == AVX prefix
  - 'u' == unaligned (i.e, address can be anything)
  - 'p' == packed (i.e., vector)
  - 's' == single-precision (32-bit float)
  - 'ymm0' names a 256-bit register, so it stores 8 floats



# **Vectorizing a loop**

- "Vectorize" means
  - Try to execute multiple iterations at once using a vector operations.
- Many corner cases
  - What if the loop bounds aren't a multiple of the vector size?
  - What if there's control in the loop?
  - What if the access's aren't "unit stride" (to consecutive memory locations).



## **Auto-vectorization**

- "#pragma omp simd"
  - Vectorize the following loop.
- gcc -O3
  - Gcc has auto-vectorization support turned on with -O3
  - Seems to be the same as 'omp simd'
- Many things will prevent auto-vectorization
  - Control in the loop body (different 'slots' undergo different operations)
  - If consecutive iteration don't access consecutive memory locations.
- Manual vectorization can be more effective, but it's hard.



# CSE 141L - Final Project

**Discussion Section** 

### Overview

- Understanding GCC Auto Vectorization Module
- Walk through Tier 1
- Tier 2: Single Instruction Multiple Data (SIMD)
- Hints for Tier 3 (a brief review)
- Convolution & activate
- Convolution & calc\_grads

### GCC Auto-Vectorization Module

- What is vectorization?
  - Perform one operation on multiple elements of a vector
  - Chunk-wise processing instead of element wise
  - Can improve computing time

### Motivation

- Utilize the CPU's vectorization features (vector registers and operations)
- Produce fast and small binaries

### GCC Auto-Vectorization Module

- Compiler does the vectorization for you! But,
  - Must verify that the optimization is legal
  - Optimization is beneficial
- -ftree-vectorize -fopt-info-vec-all in config.env
- Alternatively: AUTO\_VEC = yes
- Enabled by -O3 and greater optimizations by default
  - Only -fopt-info-vec-all needed for feedback

### GCC Auto-Vectorization Module

- Limitations
  - Countable loops
  - No backward loop-carried dependencies
  - Straight-line code (only one control flow: no if else)
  - Loop to be vectorized must be the innermost loop if nested

### Demonstration: Auto-Vectorization Module

```
void fix weights() {
tdsize old in size = in.size;
in.size.x = in.size.x * in.size.y * in.size.z;
in.size.y = 1;
in.size.z = 1;
for ( int b = 0; b < out.size.b; b++ ) {
    for ( int n = 0; n < weights.size.y; n++ ) {</pre>
        for ( int i = 0; i < weights.size.x; i++ ) {</pre>
            double& w = weights( i, n, 0 );
            double m = (act_grad(n, 0, 0, b) + old_act_grad(n, 0, 0, b) * MOMENTUM);
            double g weight = w - (LEARNING RATE * m * in(i, 0, 0, b) + LEARNING RATE * WEIGHT DECAY * w);
            w = g weight;
        old act grad(n, 0, 0, b) = act grad(n, 0, 0, b) + old act grad(n, 0, 0, b) * MOMENTUM;
in.size = old in size;
```

### Demonstration: Auto-Vectorization Module

```
_void calc grads( const tensor t<double>& grad next layer ) {
    memset( grads out.data, 0, grads out.size.x * grads out.size.y * grads out.size.z * sizeof( double ) );
    grads out.size.x = grads out.size.x * grads out.size.y * grads out.size.z;
    grads out.size.y = 1;
    grads out.size.z = 1;
    for ( int b = 0; b < out.size.b; b++ ) {</pre>
             for ( int n = 0; n < activator input.size.x; n++ ){</pre>
                     double ad = activator derivative ( activator input (n, 0, 0, b) );
                     //std::cout << ad:
                     double ng = grad next layer(n, 0, 0, b);
                     //std::cout << ng;
                     act grad (n, 0, 0, b) = ad * ng;
    for ( int b = 0; b < out.size.b; b++ ) {
             for ( int i = 0; i < qrads out.size.x; <math>i++ ) {
                     for ( int n = 0; n < out.size.x; n++ ) {
                             grads out(i, 0, 0, b) += act grad(n, 0, 0, b) * weights(i, n, 0);
    grads out.size = in.size;
```

### Demonstration: Auto-Vectorization Module

```
lvoid calc grads( const tensor t<double>& grad next layer ) {
             memset( grads out.data, 0, grads out.size.x * grads out.size.y * grads out.size.z * sizeof( double ) );
             grads out.size.x = grads out.size.x * grads out.size.y * grads out.size.z;
             grads out.size.y = 1;
             grads out.size.z = 1;
             for ( int b = 0; b < out.size.b; b++ ) {
                     for ( int n = 0; n < activator input.size.x; n++ ){</pre>
                             double ad = activator derivative ( activator input (n, 0, 0, b) );
                             double ng = grad next layer(n, 0, 0, b);
                             act grad (n, 0, 0, b) = ad * ng;
             // Reorder loops and tile on n
             for ( int nn = 0; nn < out.size.x; nn+=BLOCK SIZE ) {</pre>
                     for ( int b = 0; b < out.size.b; b++ ) {</pre>
                         for ( int i = 0; i < grads out.size.x; i++ ) {</pre>
                             for ( int n = nn; n < nn + BLOCK SIZE && n < out.size.x; n++ ) {</pre>
                                              grads out(i, 0, 0, b) += act grad(n, 0, 0, b) * weights(i, n, 0);
             grads out.size = in.size;
```

### General Flow for Tier 1

- Loop Reordering on Baseline Implementation to enable auto-vectorization
- Loop Tiling for further performance benefit
- Loop Reordering on tiled code to enable auto-vectorization
- Analysis of speedup due to vectorization

### Tier 2: single instruction multiple data (simd)

```
#pragma omp parallel
    #pragma omp for simd
    for ( int nn = 0; nn < out.size.x; nn+=BLOCK_SIZE ) {</pre>
             for ( int b = 0; b < in.size.y; b++ ) {
                     for ( int n = nn; n < nn + BLOCK SIZE && n < out.size.x; n++ ) {
                              for ( int i = 0; i < in.size.x; i++ ) {
                                      double in val = in(i, b, 0);
                                      double weight_val = weights( i, n, 0 );
                                      double mul_val = in_val * weight_val;
                                      double acc_val = activator_input(n, 0, 0, b) + mul_val;
                                      activator input(n, 0, 0, b) = acc val;
                                 fc layer t::activate() with loop reordering/tiling (cache lab) &
                                 multithreading (threads lab) & vectorization (tutorials)
```

### Tier 3: Some Hints

- Optimization techniques
  - Cache lab: Loop reordering & loop tiling
  - Threads lab: Multithreading
  - Final Project: Tutorial for Vectorization
- Combine multiple optimizations to achieve the speedup
- Some examples from previous labs
  - Multithreading+other optimizations -> tier 1 in threads lab
  - Vectorization -> tier 2 (tutorials)

## conv\_layer\_t::activate

```
void activate( tensor_t<double>& in ) {
    copy input(in);
    for ( int b = 0; b < out.size.b; b++ ) {
            for ( uint filter = 0; filter < filters.size(); filter++ ) {</pre>
                    tensor_t<double>& filter_data = filters[filter];
                    for ( int x = 0; x < out.size.x; x++ ) {
                            for ( int y = 0; y < out.size.y; y++ ) {
                                     point_t mapped(x*stride, y*stride, 0);
                                     double sum = 0;
                                     for ( int i = 0; i < kernel_size; i++ )</pre>
                                             for ( int j = 0; j < kernel_size; j++ )</pre>
                                                     for ( int z = 0; z < in.size.z; z++ ) {
                                                              double f = filter_data( i, j, z );
                                                              double v;
                                                              if (mapped.x + i >= in.size.x ||
                                                              mapped.y + j >= in.size.y) {
                                                                      v = pad;
                                                              } else {
                                                                      v = in(mapped.x + i, mapped.y + j, z, b);
                                                              sum += f*v;
                                     out(x, y, filter, b) = sum;
            }
```

### conv\_layer\_t::calc\_grads

```
void calc_grads(const tensor_t<double>& grad_next_layer ) {
    throw_assert(grad_next_layer.size == out.size, "mismatch input size for calc_grads");
    for ( int b = 0; b < in.size.b; b++ )</pre>
            for ( uint k = 0; k < filter grads.size(); k++ )</pre>
                    for ( int i = 0; i < kernel_size; i++ )</pre>
                             for ( int j = 0; j < kernel_size; j++ )</pre>
                                     for ( int z = 0; z < in.size.z; z++ )
                                             filter grads[k].get( i, j, z, b ).grad = 0;
    for ( int b = 0; b < in.size.b; b++ ) {
            for ( int x = 0; x < in.size.x; x++ ) {
                    for ( int v = 0; v < in.size.v; v++ ) {
                             range_t rn = map_to_output( x, y );
                             for ( int z = 0; z < in.size.z; z++ ) {
                                     double sum error = 0;
                                     for ( int i = rn.min_x; i <= rn.max_x; i++ ) {</pre>
                                             int minx = i * stride;
                                             for ( int j = rn.min_y; j <= rn.max_y; j++ ) {</pre>
                                                     int miny = j * stride;
                                                      for ( int k = rn.min z; k <= rn.max z; k++ ) {
                                                              int w_applied = filters[k].get( x - minx, y - miny, z );
                                                              sum_error += w_applied * grad_next_layer( i, j, k, b );
                                                              filter_grads[k].get( x - minx, y - miny, z, b ).grad += in( x, y, z, b ) * grad_next_layer( i, j, k, b );
                                     grads_out( x, y, z, b ) = sum_error;
            }
```