

Author: Jokūbas de Kort J.V.P.deKort@student.TUDelft.nl

Supervisors:
Hayley Hung (H.Hung@TUDelft.nl),
Stephanie Tan (S.Tan-1@TUDelft.nl),
Jose Vargas-Quiros
(J.D.VargasQuiros@TUDelft.nl)

Render of a Midge [1]

#### 1. Background

- Sensor device created by Socially Perceptive Computing Lab
- Analyses group behaviour
- Sensors:
  - o Inertial Measurement Unit (IMU) (1-228 Hz)
  - Microphone:
    - Low Frequency (LF) & Mono/Stereo
    - High frequency (HF) & Mono/Stereo
  - Bluetooth Low Energy (BLE): Scan Interval & Scan Window

#### 2. Research Question

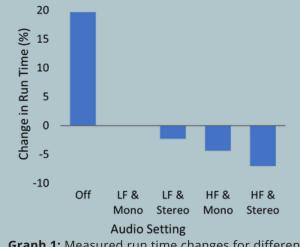
What are the maximum sampling frequencies the Midge's sensors can operate at whilst not exceeding data storage and battery limitations in a given time frame?

#### 3. Methodology

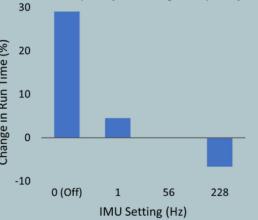
- Measure if external factors influence battery consumption and data generation
- Run Midges at different settings to analyse run times
- Use run time data to find the amount of data being generated for different settings
- Extrapolate expected values for intermediate frequencies by analysing the data from the experiments

## EFFECTS OF CHANGING THE MIDGE'S RECORDING SETTINGS ON BATTERY LIFE AND STORAGE

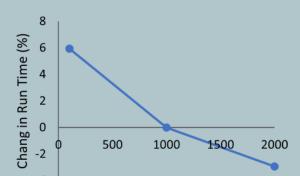
4. Results



**Graph 1:** Measured run time changes for different microphone settings compared to LF Mono baseline LF = low frequency, HF = high frequency

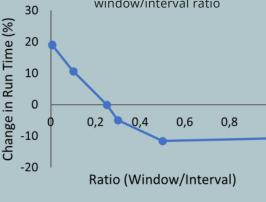


**Graph 2:** Measured run time changes for different IMU settings compared to baseline of 56Hz



Graph 3: Measured run time changes compared to baseline for different BLE interval settings from data with the same window/interval ratio

Interval (ms)



**Graph 4:** Measured run time changes compared to baseline for different window/interval ratio's with a fixed interval

### MB generated per minute for each component:

- IMU: 1.46KB per sensor at 1 HZ (scales linearly to sampling frequency)
  - Accelerometer (1-228Hz)
  - Gyroscope (1-228Hz)
  - Magnetomer (1-76Hz)
  - Gyroscope (56-228Hz)
- Microphone:
  - o LF: 149.5KB
  - LF & Stereo: 149.5KB
  - HF: 2.33MB
  - HF & Stereo: 2.33MB
- BLE: window 250, interval
  - 1 Midge within range:0.4KB
  - 7 Midges within range:5.5KB

# **TU** Delft

#### 6. Limitations

- Uncontrollable room temperature
- Limited testing time:
  - Small sample size
  - Large range of bluetooth settings
  - Combination of settings
- Small amount of Midges

#### 7. Conclusion

- Midge on default settings lasts 29-34 hours
- No combinations of settings wil exceed storage limitations before battery runs out except HF
- Compared to (default) baseline settings:
  - ~5% run time can be gained/lost through changing IMU sampling frequencies
  - HF will run ~7% shorter (when not limited by storage)
  - LF stereo recording lasts ~2% shorter
  - HF stereo recording lasts ~10% shorter
- BLE settings need further testing

#### 8. References

[1] https://github.com/TUDelft-SPC-Lab/spcl\_midge\_hardware/blob/master/Medi a/v2.3.jpg

#### 5. Formulae

Battery Run Time:

IMU:  $1 - \left(On\left(2 \times 10^{-6} \times IMU^2 - 1 \times 10^{-3} \times IMU + 4.62 \times 10^{-2}\right) + (1 - On) \times -2.977 \times 10^{-1}\right)$ 

LF/HF:  $7.67 \times 10^{-2} \times MIC^2 - 2.735 \times 10^{-1} \times MIC + 1.1968$ Mono/Stereo:  $1 - MS \times (7.1 \times 10^{-3} \times MIC^2 + 2.09 \times 10^{-2} \times MIC)$ 

**BLE:**  $Min\left(\left(1-\left(6.567\times10^{-1}\times\left(\frac{WIN}{INT}\right)^2-9.634\times10^{-1}\times\left(\frac{WIN}{INT}\right)+1.949\times10^{-1}\right)\right)\times\left(1+\left(5\times10^{-5}\times INT-5.8\times10^{-2}\right)\right),1.19\right)$ 

Multiplying the above four formulae with each other and a baseline time of a Midge gives an estimation of total run time

#### Amount of data recorded per minute in MB excluding BLE:

 $MIC \times ((2 - MIC) \times 1.5 \times 10^{-1} + (MIC - 1) \times 2.37) + 2 \times 1.46 \times 10^{-3} \times IMU + Min(IMU, 76) \times 1.46 \times 10^{-3} \times Max(IMU, 56) \times 1.46 \times 10^{-3}$ On = 0 for IMU off, 1 for IMU on. IMU = sampling frequency of IMU (Hz). MIC = 0 for off, 1 for LF, 2 for HF.

MS= 0 for Mono, 1 for Stereo. WIN = scan window (ms). Interval = scan interval (ms)