

X-Ray Image Segmentation of the Hip Joint

Segmentation of the hip joint space based on a radial projection originating from the center of the femoral head

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INTRODUCTION

Osteoarthritis (OA) is a growing health problem. In 2021, 1.589.600 people were estimated to have OA in the Netherlands [1]

X-ray images are often used in the diagnosing process.

- The minimum distance between the bones in the hip joint, the minimum joint space width (JSW), is most strongly associated with OA in X-ray images [2].
- For knee OA multiple-JSW has been proven to be even stronger associated [3].
- This might also be the case for hip OA.
- Accurate segmentation of joint space is required to calculate the joint space profile.

A radial projection of an image maps circular lines to straight lines.

The aim of this research was to investigate how the joint space profile can be segmented most accurately from a radial projection originating from the center of the femoral head by comparing multiple noise filtering and edge-finding algorithms.

METHODOLOGY

- Comparison of multiple denoising filters
- Comparison of multiple edge-finding algorithms
- Development of custom edge-finding algorithm

See the figure 1 for the full pipeline.

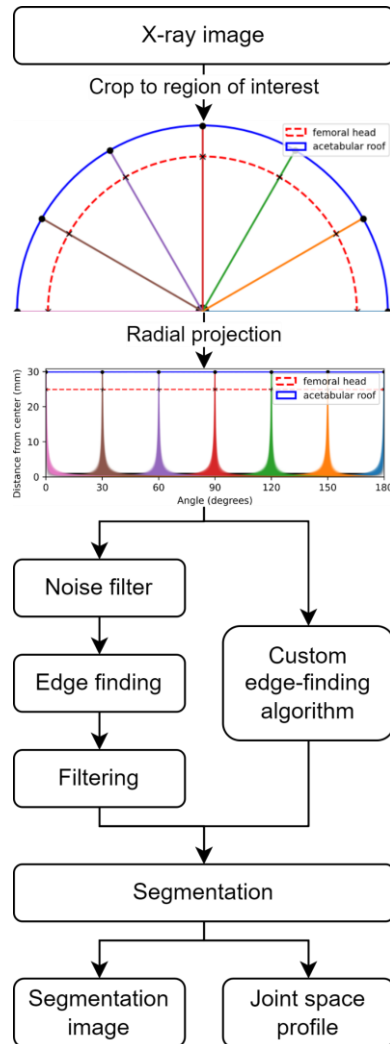


Figure 1, segmentation pipeline

EXPERIMENTAL SETUP

Output of algorithms are compared to landmark points created by BoneFinder [4].

Custom edge-finding algorithm:

- Finds the strongest gradients. Those correspond to the edges of the femoral head and acetabular roof.
- Uses moving average to smoothen out outliers.

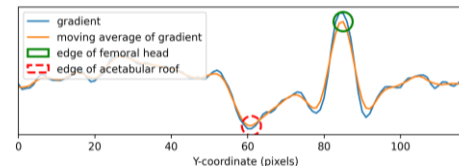


Figure 2, gradient of intensities & selected peaks

RESULTS & DISCUSSION

Best performing algorithms:

- Custom edge-finding algorithm
- Difference of Gaussians followed by minimum cross entropy thresholding

Points of improvement:

- Roughness of edges
- Detection start of femoral head

Can be used:

- To measure (minimum) JSW automatically and consistently.
- In research if full joint space is a better estimator for hip OA than minimum JSW.

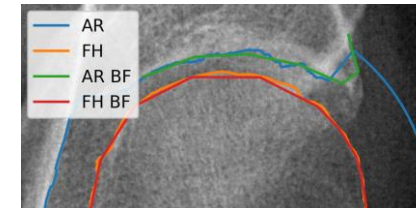


Figure 3, segmentation using custom edge-finding algorithm

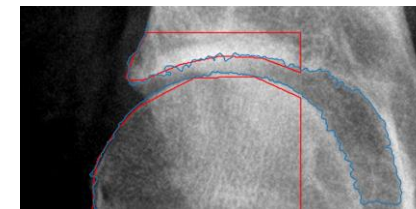


Figure 4, segmentation using difference of Gaussians and minimum cross entropy thresholding

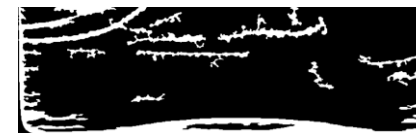


Figure 5, edges missing in segmentation

CONCLUSION

Difference of Gaussians followed by minimum cross entropy thresholding:

- Gives reasonably good results.
- Small blobs are removed, which are sometimes also part of the actual edge. This results in an incomplete segmentation.
- Edges are too rough

Custom edge-finding algorithm:

- Most reliable and consistent results since it always outputs an edge for the femoral head and acetabular roof.
- Most accurate for weight-bearing part of femoral head.
- Larger errors at lateral side of femoral head due to irregularities in density and shape.
- Start of acetabulum is often incorrect due to not having the a strong edge.

Other noise removing and edge-preserving filters do not work well with X-ray images:

- Keep too much noise.
- Smoothen out the actual edges.

References

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