

① Object detection, tracking and counting system.

Required Tools:-

① Object detection - YOLO v8

② Tracking - Byte track

③ Counting - Supervision.

Use Case:- Counting cars on a street

NOTE:- ① Use GPU

② Use input video

[CHANGE]

③ Use stable version
of YOLO v8

Date: / /

④ Get Byte track

⑤ Install Roboflow's Supervision

⑥ Load pretrained YOLOv8.pt model

↓
Be specific

of 0.1.0
version

⑦ a new video can be
generated → Train YOLOv8

via pip
package.

from scratch
on ^{your} custom dataset.

Tricky Part :-

⑦ Use Supervision to recreate the
inference loop

⑧ "How do I run the model on every frame of the video?"



use YOLOv8 model i.e. imported from
python SDK to run inference
inside that loop.

⑧ Get a frame generator

↓
Generate frames from input video,
(one by one)

⑨ Optional: Show a single frame

→ Both the functions are available
in OpenCV library.

⑩ Output of this will give numpy array of
a frame.

⑪ Optional: If you want to check
whether YOLOv8 detects
vehicles in a single
frame.
→ (with bounding boxes
around the vehicles)

optional
⑫ To check the confidence of these

boxes are Conf

* Idea:- Will the ^{vehicle 1} ~~be~~ with ^{vehicle 2} hit
Date: / /

optional

(12) To check which bounding box maps to which class of yolo v8, use .cls

(14) NOTE:- Supervision is a general purpose library
So, convert what you will get from Yolo v8 to an object that is understandable by supervision.

detections

(15) ~~BoxAnnotator~~ ^{This class of} supervision used to display bounding boxes on the frames.

(16) Annotate frame with these detections.

O/P Frame → vehicles
→ boxes around vehicles
→ Confidence score.



(17) Optional: If we want to pass classId/label i.e. car, truck etc. in place of confidence score of that box. Then pass labels, or take both classId and Confidence.

or class name.

Classnames dict:

(18) Uptill here, it is for a single frame.

Now, apply this method for the whole video.

(19) So, we need to loop through all frames coming from input video.

(20) Save all those processed frames in the form of the video.

→ This happens with a class named 'VideoSink' of supervision



21) VideoSink needs two arguments

1. instance of video info class

2. path to output file

video
resolution

fps

total
frame
count

22) Get this video information first,
only then use videoSink.

import video info from supervision.

23) Optional :- Use tqdm, i.e. a
python package that is used
for checking the progress of processing.

* OBJECT DETECTION IN VIDEO
DONE HERE. *

GOING FOR TRACKING THE VEHICLES

24

Byte tracker

Create an instance
of bytetracker
before ~~over~~ main for loop,

SIDE NOTE

A code block inserted
to solve the calibration
issue b/w YOLOV5 and
Bytetracker.

Use that instance inside the
for loop to get the tracker
id's.

25 Update Labels alongwith tracker id.

26 Process the video

* * TRACKING DONE HERE **

GOING FOR COUNTING

26 MAKE A LINE

27 COUNT the objects crossing
that line.

26.1THINK ABOUT THE LOCATION
OF THE LINE.

Line_Start

Line_End

26.2Use a class called as
'POINT' from
Supersession library26.3These two points used in a
constructor called as line counter.26.4display that line → another
annotator required.27.1We need to let the line
know where are the detections
so that it can determine
whether or not it got
crossed by them and27.2Annotate the line_counter at
the inside end of for loop.So it can be aware about current counter
values.