Preclass 01: Linear Regression

[SCS4049] Machine Learning and Data Science

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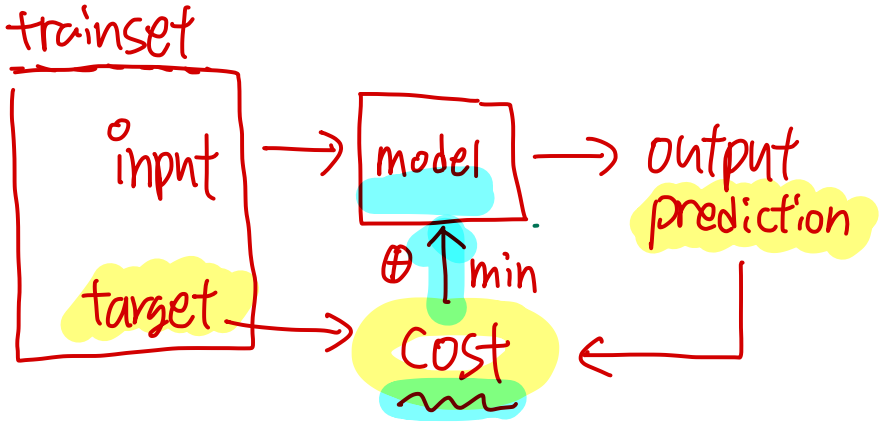
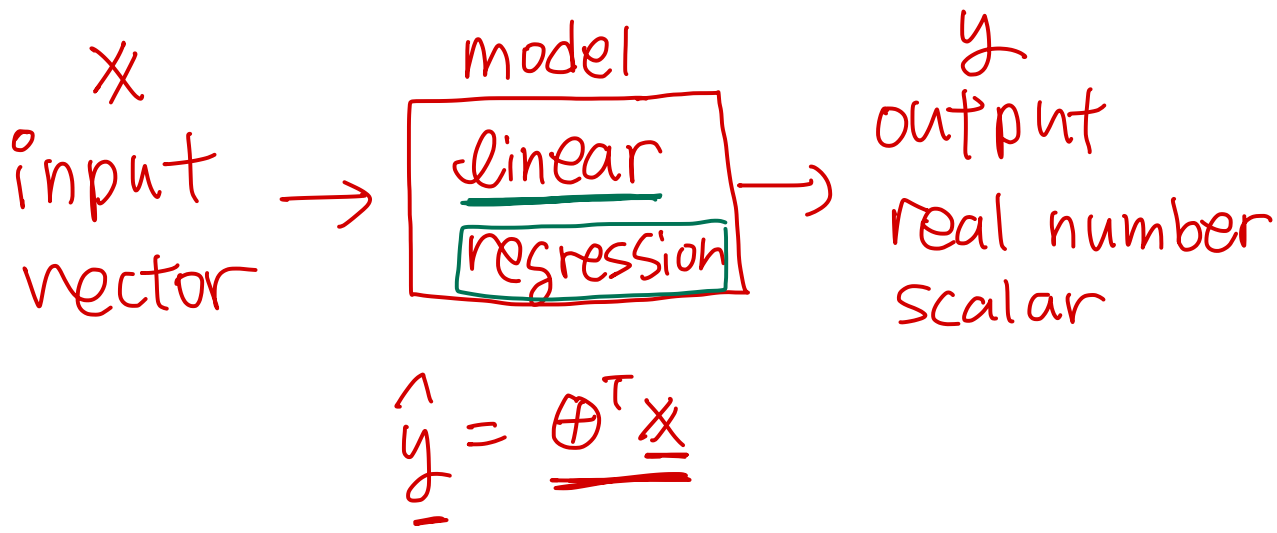




Linear regression

Linear regression

output y ← prediction $\hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \cdots + \theta_n x_n$

$= \theta^T x = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix} \cdot \begin{bmatrix} 1 \\ x_1 \\ \vdots \\ x_n \end{bmatrix}$

Linear model

$$\hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \cdots + \theta_n x_n \quad (1)$$

In this equation,

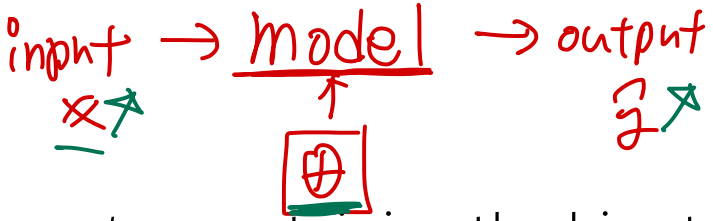
- $\hat{y}$ is the predicted value (for true y)
- n is the number of features, input의 feature 개수
- x_i is the i-th feature value
- θ_j is the j-th model parameter
  including the bias term θ_0 and the feature weights $\theta_1, \theta_2, ..., \theta_n$

Linear regression

This can be written much more concisely using a vectorized form,

$$\hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \cdots + \theta_n x_n \tag{2}$$

$$= \boldsymbol{\theta}^T \mathbf{x} \tag{3}$$



In this equation,

- $\boldsymbol{\theta}$ is the model's *parameter vector*, containing the bias term θ_0 and the feature weights θ_1 to θ_n
- $\mathbf{x}$ is the instance's *feature vector*, containing x_0 to x_n always equal to 1
- $\boldsymbol{\theta} \cdot \mathbf{x}$ is the dot product of the vectors $\boldsymbol{\theta}$ and $\mathbf{x}$, which is of course equal to $\theta_0 x_0 + \theta_1 x_1 + \cdots + \theta_n x_n$

Linear regression

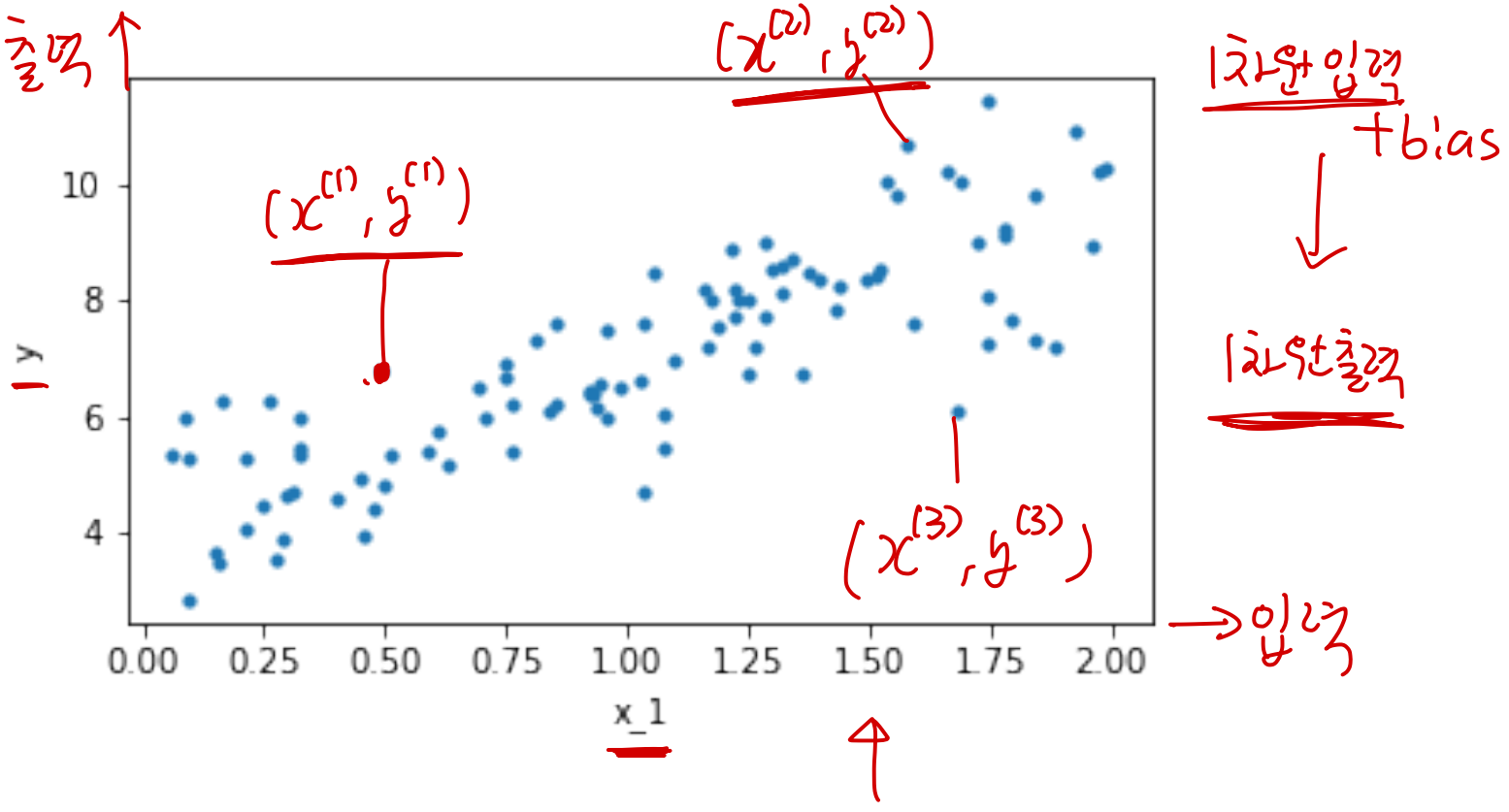


Figure 1: Linear regression: training dataset

Generating training dataset

$$y \approx \theta_0 + \theta_1 x \tag{4}$$

$$y = \theta_0 + \theta_1 x + \epsilon \text{ where } \epsilon \sim \mathcal{N}(0, \sigma^2) \tag{5}$$

Cost function

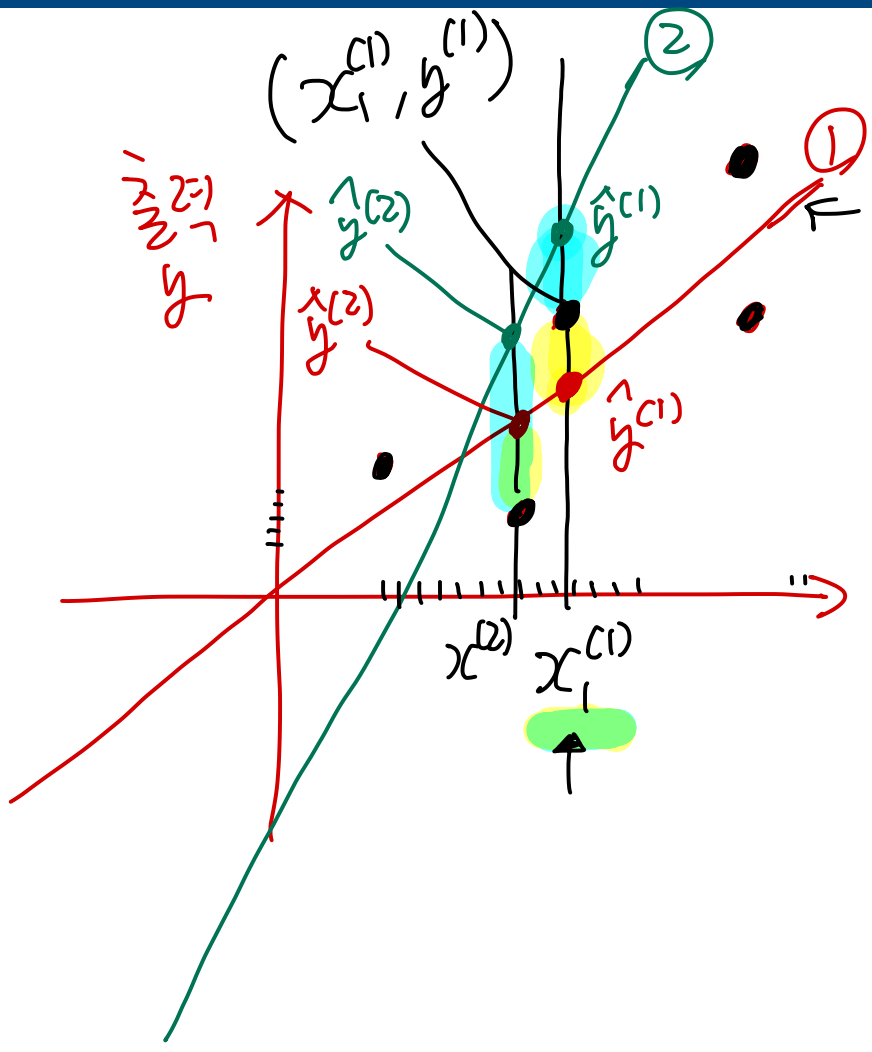
That's the linear regression model – but how do we train it?

Recall that training a model means setting its parameters so that the model best fits the training set.

We first need a measure of how well (or poorly) the model fits the training data.

The most common performance measure of a regression model is the Root Mean Square Error (RMSE).

$$\mathrm{RMSE}(\mathbf{X}, \boldsymbol{\theta}) = \sqrt{\frac{1}{m}\sum_{i=1}^{m}\left(y^{(i)} - \boldsymbol{\theta}^T\mathbf{x}^{(i)}\right)^2} \tag{6}$$

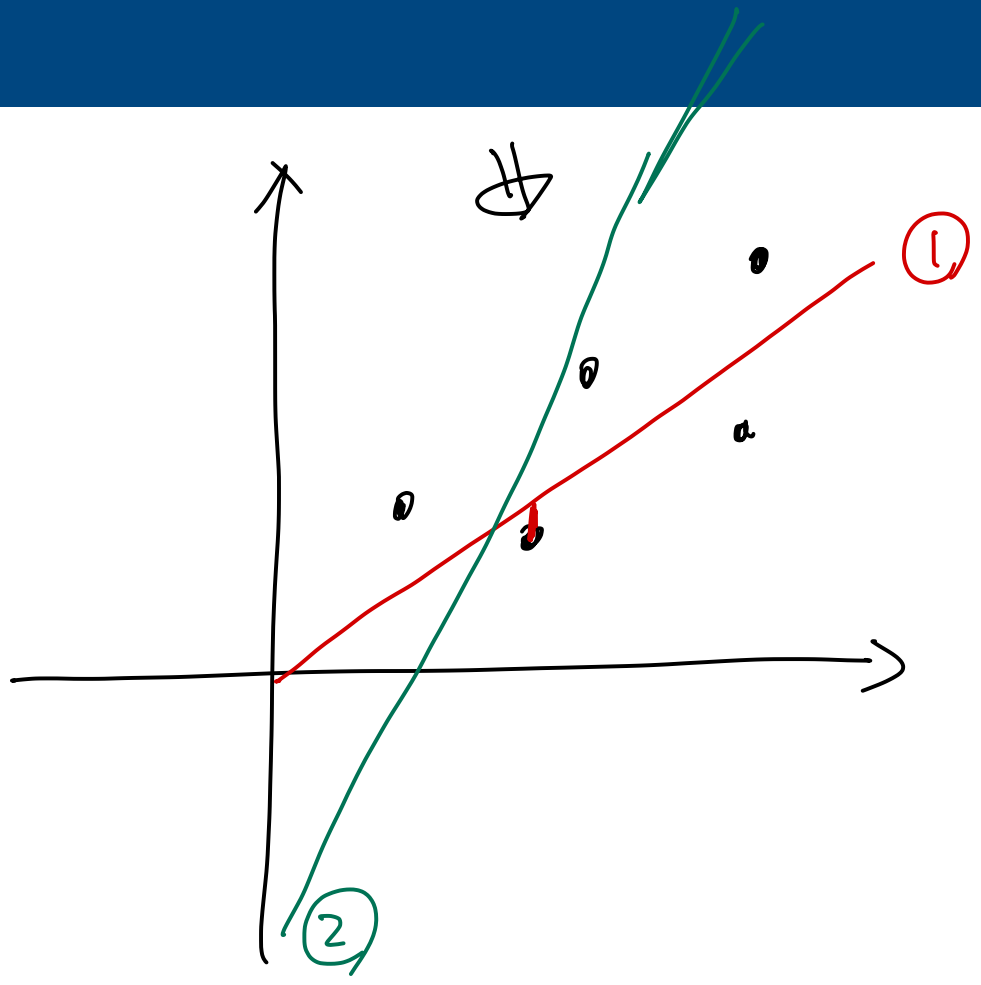


$$\hat{y} = \theta_0 + \theta_1 x_1$$

① $\theta = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

② $\theta = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$

$$\text{error}^{2(i)} = (\underset{\text{참값}}{y^{(i)}} - \underset{\text{예측값}}{\hat{y}^{(i)}})^2 \geq 0$$



$$\sum_{i=1}^{5} error^{(i)2}$$

$$= \sum_{i=1}^{5} \left(y^{(i)} - \hat{y}^{(i)}\right)^2$$

① $\Sigma 1^2 = 20$

② $\Sigma 1^2 = 100$

직관적 Var. ① ≤ ②

$\Sigma error^2$

① ≤ ②

Cost function

regression problem에서 사용되는 measure, error index cost function.

We need to find the value of $\boldsymbol{\theta}$ that minimizes the RMSE. In practice, it is simpler to minimize the sum of squared error (SSE) than the MSE or the RMSE.

$$\hat{\boldsymbol{\theta}} = \arg\min \mathrm{RMSE}(\mathbf{X}, \boldsymbol{\theta}) = \arg\min \sqrt{\frac{1}{m}\sum_{i=1}^{m}\left(y^{(i)} - \boldsymbol{\theta}^T\mathbf{x}^{(i)}\right)^2} \tag{7}$$

$$= \arg\min \mathrm{MSE}(\mathbf{X}, \boldsymbol{\theta}) \quad = \arg\min \frac{1}{m}\sum_{i=1}^{m}\left(y^{(i)} - \boldsymbol{\theta}^T\mathbf{x}^{(i)}\right)^2 \tag{8}$$

sum of squared error

$$= \arg\min \mathrm{SSE}(\mathbf{X}, \boldsymbol{\theta}) \quad = \arg\min \sum_{i=1}^{m}\left(y^{(i)} - \boldsymbol{\theta}^T\mathbf{x}^{(i)}\right)^2 \tag{9}$$

$\boldsymbol{\theta}$

$(\mathbf{X}, y, \boldsymbol{\theta})$

$y^{(i)}$

Design matrix

Design matrix (regressor matrix, model matrix, data matrix)

- 훈련 데이터(sample, example)이 m개
- feature vector $\mathbf{x}$의 차원이 n일 때,
- m개의 sample을 row vector로 한 design matrix $\mathbf{X}$로 표시할 수 있음

$$\mathbf{y} = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix} \qquad \boldsymbol{\theta} = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix} \tag{10}$$

$$\mathbf{X} = \begin{bmatrix} \text{1st sample } \mathbf{x}^{(1),T} \\ \text{2nd sample } \mathbf{x}^{(2),T} \\ \cdots \\ \text{m-th sample } \mathbf{x}^{(m),T} \end{bmatrix} = \begin{bmatrix} 1 & x_1^{(1)} & x_2^{(1)} & \cdots & x_n^{(1)} \\ 1 & x_1^{(2)} & x_2^{(2)} & \cdots & x_n^{(2)} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & x_1^{(m)} & x_2^{(m)} & \cdots & x_n^{(m)} \end{bmatrix} \tag{11}$$

model $\hat{y} = \theta^T x$

training dataset $(x^{(1)}, y^{(1)})$ $(x^{(2)}, y^{(2)})$ $(x^{(3)}, y^{(3)})$ ..... $(x^{(m)}, y^{(m)})$

↓

model prediction

$\hat{y}^{(1)} = \theta^T x^{(1)}$

$\hat{y}^{(2)} = \theta^T x^{(2)}$

$\hat{y}^{(3)} = \theta^T x^{(3)}$

⋮

$\hat{y}^{(m)} = \theta^T x^{(m)}$

$SSE = (y^{(1)} - \theta^T x^{(1)})^2 + (y^{(2)} - \theta^T x^{(2)})^2 + (y^{(3)} - \theta^T x^{(3)})^2 + \vdots + (y^{(m)} - \theta^T x^{(m)})^2$

X $m \times n$ design matrix $= \begin{bmatrix} - (x^{(1)})^T - \\ - (x^{(2)})^T - \\ - (x^{(3)})^T - \\ \vdots \\ - (x^{(m)})^T - \end{bmatrix}$

$y_{m \times 1} = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix}$

$\hat{y}_{m \times 1} = \begin{bmatrix} \hat{y}^{(1)} \\ \hat{y}^{(2)} \\ \vdots \\ \hat{y}^{(m)} \end{bmatrix} = X_{m \times n} \, \theta_{n \times 1} = \begin{bmatrix} - (x^{(1)})^T - \\ - (x^{(2)})^T - \\ \vdots \\ - (x^{(m)})^T - \end{bmatrix} \theta$

$$SSE(\theta) = \sum \left(y^{(i)} - \theta^T x^{(i)} \right)^2 \Leftarrow$$

$$= \left\| \underline{y} - \hat{\underline{y}} \right\|_2^2$$

$$= \left\| \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix} - \begin{bmatrix} \hat{y}^{(1)} \\ \vdots \\ \hat{y}^{(m)} \end{bmatrix} \right\|_2^2$$

$$= \left\| \begin{bmatrix} y^{(1)} - \hat{y}^{(1)} \\ \vdots \\ y^{(m)} - \hat{y}^{(m)} \end{bmatrix} \right\|_2^2$$

$$SSE(\theta) = \| y - \hat{y} \|_2^2 = \| y - X\theta \|_2^2$$

Design matrix

그러면, $\hat{y} = \boldsymbol{\theta}^T \mathbf{x}$의 m개의 sample에 대해 다음과 같이 표현할 수 있음

$$\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta} \tag{12}$$

$$\begin{bmatrix} \hat{y}^{(1)} \\ \hat{y}^{(2)} \\ \vdots \\ \hat{y}^{(m)} \end{bmatrix} = \begin{bmatrix} 1 & x_1^{(1)} & x_2^{(1)} & \cdots & x_n^{(1)} \\ 1 & x_1^{(2)} & x_2^{(2)} & \cdots & x_n^{(2)} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & x_1^{(m)} & x_2^{(m)} & \cdots & x_n^{(m)} \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix} \tag{13}$$

$$\begin{bmatrix} \hat{y}^{(1)} \\ \hat{y}^{(2)} \\ \vdots \\ \hat{y}^{(m)} \end{bmatrix} = \begin{bmatrix} \text{——} & \mathbf{x}^{(1),T} & \text{——} \\ \text{——} & \mathbf{x}^{(2),T} & \text{——} \\ & \vdots & \\ \text{——} & \mathbf{x}^{(m),T} & \text{——} \end{bmatrix} \boldsymbol{\theta} \tag{14}$$

$$\hat{\theta} = \arg\min_{\theta} SSE(\theta)$$

① Normal equation ⇐ direct solution
closed form
고등학교 때 적분으로 직접 구함.

② Gradient descent ⇐ 미분, 근사적으로 찾음

Geometric approach

Design matrix $\mathbf{X}$의 각 열을 $\vec{\mathbf{x}}_j$라고 하면

$$\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta} = \begin{bmatrix} | & | & & | \\ \mathbf{1} & \mathbf{x}_1 & \cdots & \mathbf{x}_n \\ | & | & & | \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix} \tag{15}$$

$$= \theta_0 \mathbf{1} + \theta_1 \mathbf{x}_1 + \theta_2 \mathbf{x}_2 + \cdots + \theta_n \mathbf{x}_n \tag{16}$$

즉, $\hat{\mathbf{y}}$는 $\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_n$이 생성하는 hyperplane, i.e., $\text{span}\{\mathbf{1}, \mathbf{x}_1, \cdots, \mathbf{x}_n\}$ 상에 존재함

Residual 또는 error의 크기 $\|\mathbf{y} - \hat{\mathbf{y}}\|$를 최소화 하려면? 위의 hyperplane과 error $\mathbf{y} - \hat{\mathbf{y}}$가 서로 수직(orthogonal)해야함

Geometric approach

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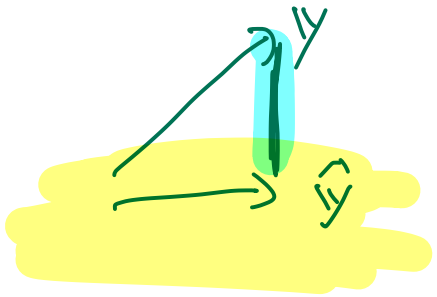
즉, 모든 column vector에 대해서

$\mathbf{X}$의 column들 = $\mathbf{x}_1, \mathbf{x}_2, \cdots, \mathbf{x}_n$

$$\mathbf{x}_j^T(\mathbf{y} - \hat{\mathbf{y}}) = 0 \tag{17}$$



이 성립해야 함

전체 m개의 sample에 대해서

$$\mathbf{X}^T(\mathbf{y} - \mathbf{X}\boldsymbol{\theta}) = \mathbf{0} \implies \mathbf{X}^T\mathbf{X}\boldsymbol{\theta} = \mathbf{X}^T\mathbf{y} \tag{18}$$

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} \tag{19}$$

$\Leftarrow$ normal equation.

$\hat{\theta} = (X^TX)^{-1}X^Ty \iff \hat{\theta} = \text{argmin}\, SSE(\theta)$

Geometric approach

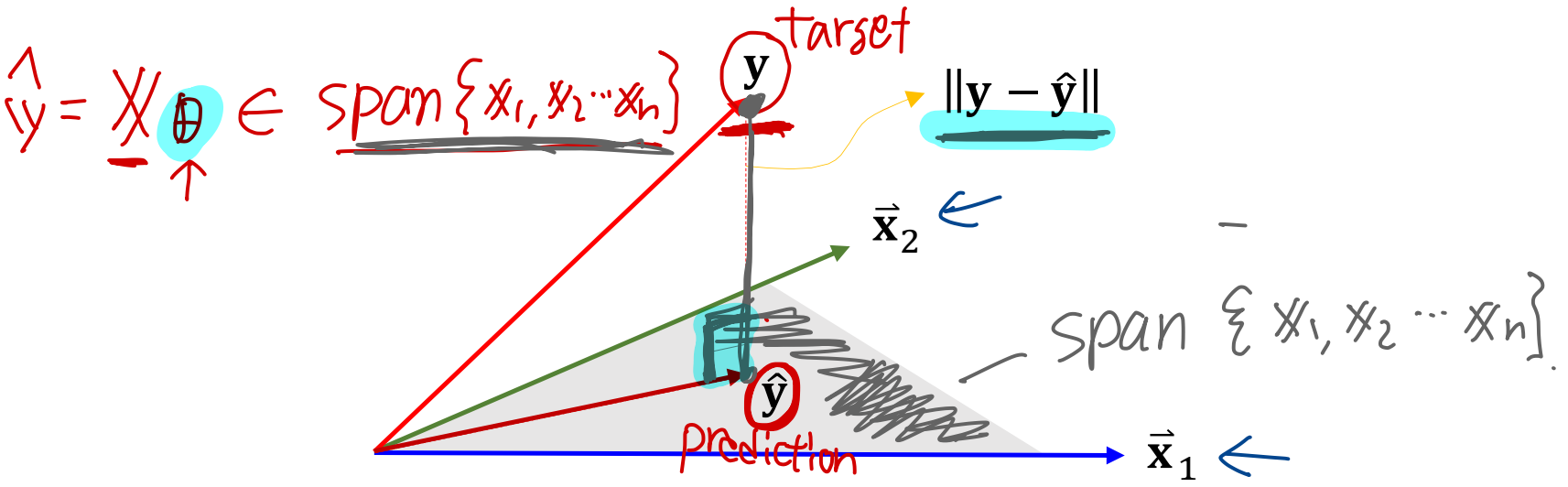


Figure 2: Normal equation: geometric interpretation

Normal equation

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} \tag{20}$$

Projection matrix

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\theta}} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} \tag{21}$$

$$\min \|y - \hat{y}\|_2^2 \iff (y - \hat{y}) \perp \text{span}\{x_1 \cdots x_n\}$$

Analytic approach

Sum of squared error (SSE)

$$\text{SSE} = \sum_{i=1}^{m} (y^{(i)} - \hat{y}^{(i)})^2 \tag{22}$$

$$= \|\mathbf{y} - \hat{\mathbf{y}}\|^2 = (\mathbf{y} - \hat{\mathbf{y}})^T (\mathbf{y} - \hat{\mathbf{y}}) \tag{23}$$

Using $\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta}$

$$\text{SSE}(\boldsymbol{\theta}) = \mathbf{y}^T\mathbf{y} - 2\mathbf{y}^T\mathbf{X}\boldsymbol{\theta} + (\mathbf{X}\boldsymbol{\theta})^T(\mathbf{X}\boldsymbol{\theta}) = \mathbf{y}^T\mathbf{y} - 2\mathbf{y}^T\mathbf{X}\boldsymbol{\theta} + \boldsymbol{\theta}^T\mathbf{X}^T\mathbf{X}\boldsymbol{\theta} \tag{24}$$

$$\frac{\partial \text{SSE}(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = 2(\mathbf{X}^T\mathbf{X}\boldsymbol{\theta} - \mathbf{X}\mathbf{y}) = 0 \implies \mathbf{X}^T\mathbf{X}\boldsymbol{\theta} = \mathbf{X}^T\mathbf{y} \tag{25}$$

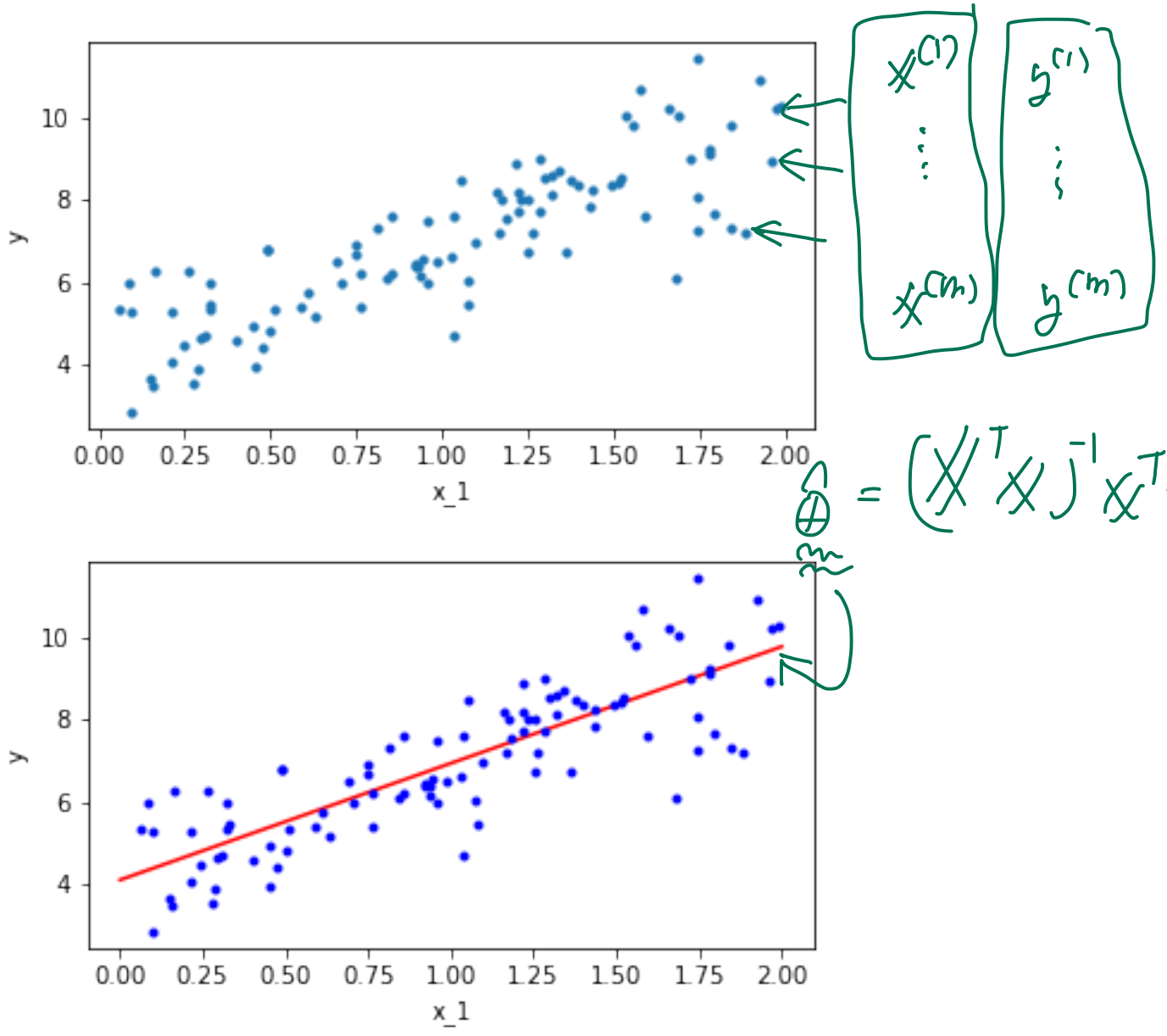
Hence, we have

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} \tag{26}$$

normal equation

$$\hat{\mathbf{y}} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} \tag{27}$$

Closed from solution



Computational complexity

Normal equation의 계산

- Normal equation에 의한 예측치 $\hat{\mathbf{y}}$

$$\hat{\mathbf{y}} = \mathbf{X}(\mathbf{X}^T\mathbf{X})^{-1}\mathbf{X}^T\mathbf{y} \tag{28}$$

- $\mathbf{X} \in \mathcal{R}^{m \times n}$
- $\mathbf{X}^T\mathbf{X} \in \mathcal{R}^{n \times n}$
- $(\mathbf{X}^T\mathbf{X})^{-1}$ 의 계산 복잡도 = $O(n^{2.4}) \sim O(n^3)$
- Feature 수의 약 세제곱으로 계산 시간이 증가

Gradient descent

Batch gradient descent

Linear regression model $\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta}$

$$J(\boldsymbol{\theta}) = \mathrm{SSE}(\boldsymbol{\theta}) = \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|^2 \tag{29}$$

$$\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = 2\mathbf{X}^T(\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) \tag{30}$$

$$\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \begin{bmatrix} \frac{\partial}{\partial \theta_1} J(\boldsymbol{\theta}) \\ \frac{\partial}{\partial \theta_2} J(\boldsymbol{\theta}) \\ \vdots \\ \frac{\partial}{\partial \theta_n} J(\boldsymbol{\theta}) \end{bmatrix} = \begin{bmatrix} 2\sum_{i=1}^m x_1^{(i)} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)}\right) \\ 2\sum_{i=1}^m x_2^{(i)} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)}\right) \\ \vdots \\ 2\sum_{i=1}^m x_n^{(i)} \left(\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)}\right) \end{bmatrix} \tag{31}$$

Gradient descent step

$$\boldsymbol{\theta}^{t+1} = \boldsymbol{\theta}^t - \eta \nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}^t) \tag{32}$$

where iteration number t and $\boldsymbol{\theta}$ arbitrary initial value

Batch gradient descent

Batch gradient descent에서

$$\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = 2\mathbf{X}^T(\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) \tag{33}$$

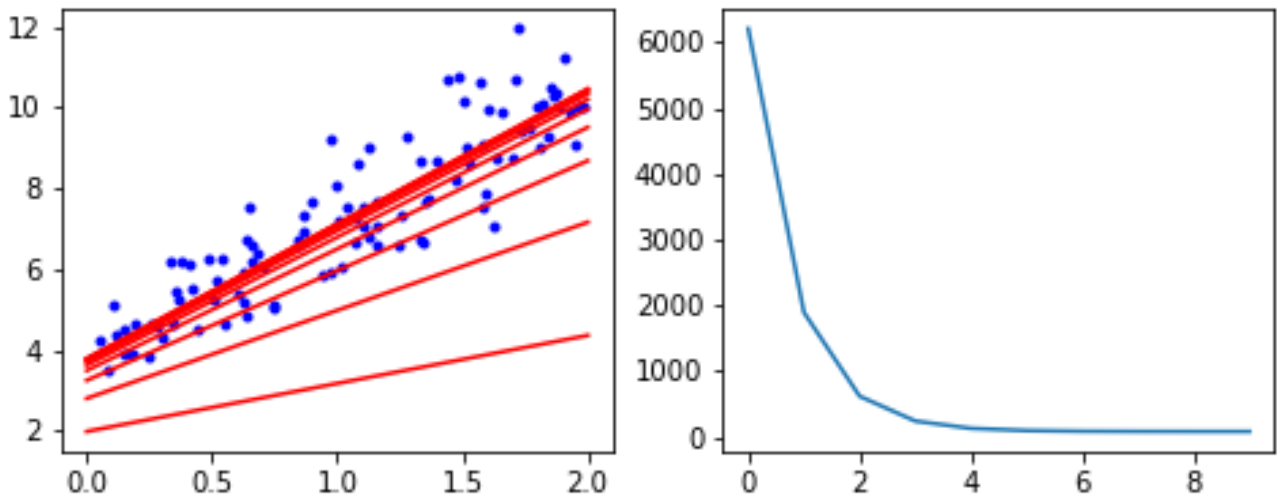
$$= 2 \begin{bmatrix} \mathbf{x}^{(1)} & \mathbf{x}^{(2)} & \cdots & \mathbf{x}2^{(m)} \end{bmatrix} \begin{bmatrix} \boldsymbol{\theta}^T\mathbf{x}^{(1)} - y^{(1)} \\ \boldsymbol{\theta}^T\mathbf{x}^{(2)} - y^{(2)} \\ \vdots \\ \boldsymbol{\theta}^T\mathbf{x}^{(m)} - y^{(m)} \end{bmatrix} \tag{34}$$

$$= 2\sum_{i=1}^{m} \mathbf{x}^{(i)} \left(\boldsymbol{\theta}^T\mathbf{x}^{(i)} - y^{(i)} \right) \tag{35}$$

그러므로 이 gradient vector의 j번째 component는

$$\frac{\partial}{\partial \theta_j} J(\boldsymbol{\theta}) = 2\sum_{i=1}^{m} x_j^{(i)} \left(\boldsymbol{\theta}^T\mathbf{x}^{(i)} - y^{(i)} \right) \tag{36}$$

Batch gradient descent



Batch gradient descent: computational complexity

Batch gradient descent algorithm

- 매 스텝마다 batch 전체에 대한 계산 필요
- 데이터셋이 커지면 속도가 느려짐
- Normal equation: feature 수에 따라 계산 속도가 지수적으로 느려짐
- Gradient descent: feature 수가 늘어도 크게 변하지 않음

Learning rate

- Hyperparameter인 학습률(learning rate) η가 너무 작은 경우 시간이 오래 걸림
- 너무 큰 경우 최적해를 지나쳐 해를 찾지 못할 수 있음

Learning schedule

- Constant learning rate
  - 보통 0.1, 0.01부터 시작하여 여러 가지 값으로 시험해보며 범위를 좁혀 나감
- Time-based decay

$$\eta = \frac{\eta_0}{(1 + kt)} \tag{37}$$

η_0 : 학습률 초기값, k : hyperparameter, t : iteration

- Step decay
  - 정해진 epoch마다 학습률을 줄이는 방법
  - 예: 5 epoch마다 반으로, 20 epoch마다 1/10로
  - Epoch: 훈련 데이터셋 전체를 모두 사용할 때 = 한 epoch
- Exponential decay

$$\eta = \eta_0 e^{-kt} \tag{38}$$

η_0 : 학습률 초기값, k : hyperparameter, t : iteration

Stochastic gradient descent

For our linear regression model $\hat{y} = \boldsymbol{\theta}^T \mathbf{x}$

$$J(\boldsymbol{\theta}) = \mathrm{SSE}(\boldsymbol{\theta}) = \sum_{i=1}^{m} \left(\mathbf{y}^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 = \sum_{i=1}^{m} J_i(\boldsymbol{\theta}) \tag{39}$$

$$\boldsymbol{\theta}^{t+1} = \boldsymbol{\theta}^t - 2\eta \left(y^{(t)} - (\boldsymbol{\theta}^t)^T \mathbf{x}^{(t)} \right) \mathbf{x}^{(t)} \tag{40}$$

- 무작위로 선택한 한 개의 sample에 대해서만 gradient를 계산하여 parameter를 update
- sequential learning or online learning
- 대규모 데이터셋을 처리하는데 유리
- 선택하는 사례의 무작위성으로 움직임이 불규칙
- BGD에 비해 local optimum에서 쉽게 빠져나올 수 있음
- 최적해에 도달하지만 지속적으로 요동
- BGD와 마찬가지로 global optimum이라는 보장이 없음

Mini-batch gradient descent

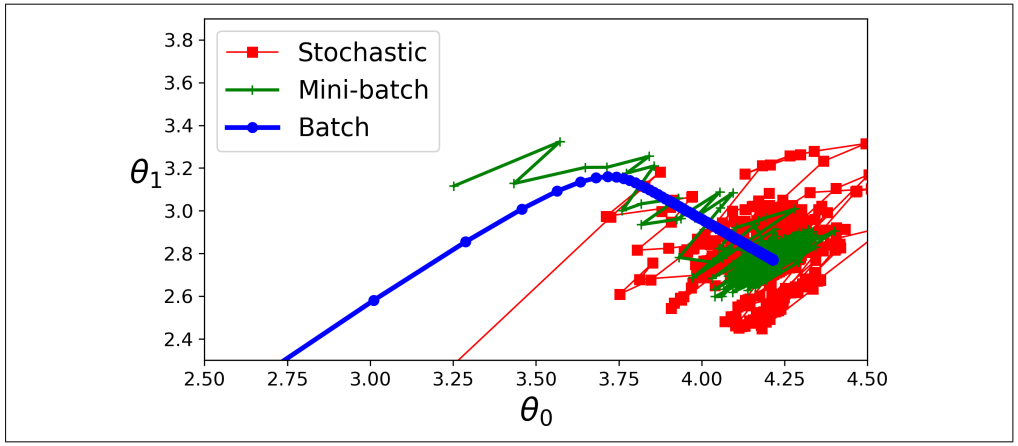


Figure 4-11. Gradient Descent paths in parameter space

- 훈련 데이터셋을 작은 크기의 무작위 부분 집합으로 나누어서 gradient를 구하는 방법
- 예 100,000개의 데이터 = (mini-batch size 100) × (1,000 mini-batches)
- Batch gradient descent와 stochastic gradient descent(SGD)의 절충
- SGD보다 불규칙한 움직임이 덜함
- SGD보다 local minimum에서 빠져나오기가 상대적으로 더 어려움
- GPU를 통한 매트릭스 연산의 속도를 높일 수 있음

Linear regression comparison

Table 4-1. Comparison of algorithms for Linear Regression

Algorithm	Large *m*	Out-of-core support	Large *n*	Hyperparams	Scaling required	Scikit-Learn
Normal Equation	Fast	No	Slow	0	No	n/a
SVD	Fast	No	Slow	0	No	`LinearRegression`
Batch GD	Slow	No	Fast	2	Yes	`SGDRegressor`
Stochastic GD	Fast	Yes	Fast	≥2	Yes	`SGDRegressor`
Mini-batch GD	Fast	Yes	Fast	≥2	Yes	`SGDRegressor`

There is almost no difference after training: all these algorithms end up with very similar models and make predictions in exactly the same way.