Preclass 01: Linear Regression

[SCS4049] Machine Learning and Data Science

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input vector -> linear regression -> output scalar

Linear regression

Linear regression

Linear model

$$\hat{y} = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n \tag{1}$$

In this equation,

- \hat{y} is the predicted value (for true y)
- *n* is the number of features
- x_i is the *i*-th feature value
- θ_j is the j-th model parameter/weight including the bias term θ_0 and the feature weights $\theta_1, \theta_2, ..., \theta_n$

Linear regression

This can be written much more concisely using a vectorized form,

$$\hat{\mathbf{y}} = \theta_0 + \theta_1 \mathbf{x}_1 + \theta_2 \mathbf{x}_2 + \dots + \theta_n \mathbf{x}_n \tag{2}$$

$$= \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x} = \begin{bmatrix} \theta_{o} \\ \theta_{i} \\ \vdots \\ \theta_{n} \end{bmatrix} \cdot \begin{bmatrix} \mathbf{x}_{i} \\ \mathbf{x}_{n} \end{bmatrix} = \theta \cdot \mathbf{x} \tag{3}$$

In this equation,

- θ is the model's parameter vector, containing the bias term θ_0 and the feature weights θ_1 to θ_n = parameter
- \mathbf{x} is the instance's feature vector, containing x_0 to x_n always equal to 1 = input
- $\theta \cdot \mathbf{x}$ is the dot product of the vectors θ and \mathbf{x} , which is of course equal to $\theta_0 x_0 + \theta_1 x_1 + \cdots + \theta_n x_n$

Linear regression

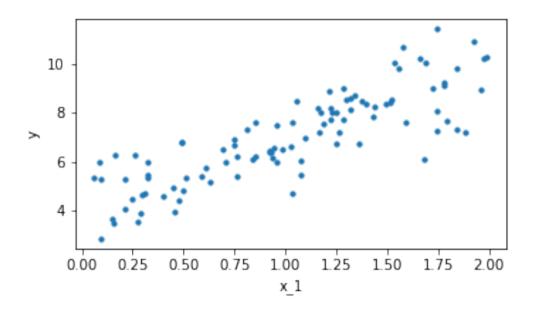


Figure 1: Linear regression: training dataset

Generating training dataset

$$y \approx \theta_0 + \theta_1 x$$
 (4)
 $y = \theta_0 + \theta_1 x + \epsilon \text{ where } \epsilon \sim \mathcal{N}(0, \sigma^2)$ (5)

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Cost function

That's the linear regression model – but how do we train it?

Recall that training a model means setting its parameters so that the model best fits the training set.

We first need a measure of how well (or poorly) the model fits the training data.

The most common performance measure of a regression model is the Root Mean Square Error (RMSE).

$$RMSE(\mathbf{X}, \boldsymbol{\theta}) = \sqrt{\frac{1}{m} \sum_{i=1}^{m} \left(y^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2}}$$
 (6)

Cost function

We need to find the value of θ that minimizes the RMSE. In practice, it is simpler to minimize the sum of squared error (SSE) than the MSE or the RMSE.

$$\hat{\boldsymbol{\theta}} = \arg\min_{\text{NSE}(\mathbf{X}, \boldsymbol{\theta})} = \arg\min_{\text{Voute Mean}} \sqrt{\frac{1}{m} \sum_{i=1}^{m} \left(y^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^2}$$
 (7)

$$= \arg\min \operatorname{MSE}(\mathbf{X}, \boldsymbol{\theta}) = \arg\min \frac{1}{m} \sum_{i=1}^{m} \left(y^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2}$$
(8)

[Mean of Squared Eight

$$= \arg\min \operatorname{SSE}(\mathbf{X}, \boldsymbol{\theta}) = \arg\min \sum_{i=1}^{m} \left(y^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2}$$

$$= \arg\min \operatorname{SSE}(\mathbf{X}, \boldsymbol{\theta}) = \operatorname{arg min} \sum_{i=1}^{m} \left(y^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2}$$
(9)

Design matrix

Design matrix (regressor matrix, model matrix, data matrix)

- · 훈련 데이터(sample, example)이 m개
- · feature vector x의 차원이 n일 때,
- · m개의 sample을 row vector로 한 design matrix **X**로 표시할 수 있음

$$\mathbf{y} = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix} \qquad \boldsymbol{\theta} = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_n \end{bmatrix}$$
(10)

$$\mathbf{X} = \begin{bmatrix} \text{1st sample } \mathbf{x}^{(1),T} \\ \text{2nd sample } \mathbf{x}^{(2),T} \\ \cdots \\ \text{m-th sample } \mathbf{x}^{(m),T} \end{bmatrix} = \begin{bmatrix} 1 & x_1^{(1)} & x_2^{(1)} & \cdots & x_n^{(1)} \\ 1 & x_1^{(2)} & x_2^{(2)} & \cdots & x_n^{(2)} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & x_1^{(m)} & x_2^{(m)} & \cdots & x_n^{(m)} \end{bmatrix}$$
 (11)

Design matrix

그러면, $\hat{y} = \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}$ 의 m개의 sample에 대해 다음과 같이 표현할 수 있음

$$SSE(\theta) = \left\| \begin{array}{c} y - \hat{y} \end{array} \right\|_{2}^{2} = \left\| \begin{bmatrix} y^{(i)} \\ y^{(i)} \end{bmatrix} - \begin{bmatrix} \hat{y}^{(i)} \\ \hat{y}^{(i)} \end{bmatrix} \right\|_{2}^{2} \Rightarrow 2 \text{ florately At } [\frac{1}{2}]$$

$$= \left| \left| \begin{array}{c} \cancel{y} - \widehat{\cancel{y}} \end{array} \right| \right|_{2}^{2} = \left| \left| \begin{array}{c} \cancel{y} - \cancel{y} \cdot \theta \end{array} \right| \right|_{2}^{2}$$

Normal equation → 해를 대수적으로 직접 수함

Geometric approach

즉, $\hat{\mathbf{y}}$ 는 $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$ 이 생성하는 hyperplane, i.e., $\mathrm{span}\{\mathbf{1}, \mathbf{x}_1, \dots, \mathbf{x}_n\}$ 상에 존재함

Residual 또는 error의 크기 $\|\mathbf{y} - \hat{\mathbf{y}}\|$ 를 최소화 하려면? 위의 hyperplane과 error $\mathbf{y} - \hat{\mathbf{y}}$ 가 서로 수직(orthogonal)해야함

Geometric approach

Residual 또는 error의 크기 $\|\mathbf{y} - \hat{\mathbf{y}}\|$ 를 최소화 하려면? 위의 hyperplane과 error $\mathbf{v} - \hat{\mathbf{v}}$ 가 서로 수직(orthogonal)해야함

즉, 모든 column vector에 대해서

design matrixel
$$\mathbf{x}_{j}^{T}(\mathbf{y} - \hat{\mathbf{y}}) = 0$$
 (17)

이 성립해야 함

전체 m개의 sample에 대해서

$$\mathbf{X}^{\mathsf{T}}(\mathbf{y} - \mathbf{X}\boldsymbol{\theta}) = 0 \implies \mathbf{X}^{\mathsf{T}}\mathbf{X}\boldsymbol{\theta} = \mathbf{X}^{\mathsf{T}}\mathbf{y}$$
 (18)

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y} \tag{19}$$

Geometric approach

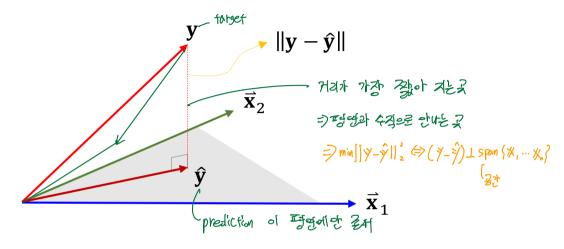


Figure 2: Normal equation: geometric interpretation

Normal equation

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y} \tag{20}$$

Projection matrix

$$\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\theta}} = \mathbf{X}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$$
 (21)

Analytic approach

Sum of squared error (SSE)

$$SSE = \sum_{i=1}^{m} (y^{(i)} - \hat{y}^{(i)})^2$$
 (22)

$$= \|\mathbf{y} - \hat{\mathbf{y}}\|^2 = (\mathbf{y} - \hat{\mathbf{y}})^{\mathsf{T}} (\mathbf{y} - \hat{\mathbf{y}})$$
(23)

Using $\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta}$

$$SSE(\boldsymbol{\theta}) = \mathbf{y}^{\mathsf{T}}\mathbf{y} - 2\mathbf{y}^{\mathsf{T}}\mathbf{X}\boldsymbol{\theta} + (\mathbf{X}\boldsymbol{\theta})^{\mathsf{T}}(\mathbf{X}\boldsymbol{\theta}) = \mathbf{y}^{\mathsf{T}}\mathbf{y} - 2\mathbf{y}^{\mathsf{T}}\mathbf{X}\boldsymbol{\theta} + \boldsymbol{\theta}^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}\mathbf{X}\boldsymbol{\theta}$$
(24)

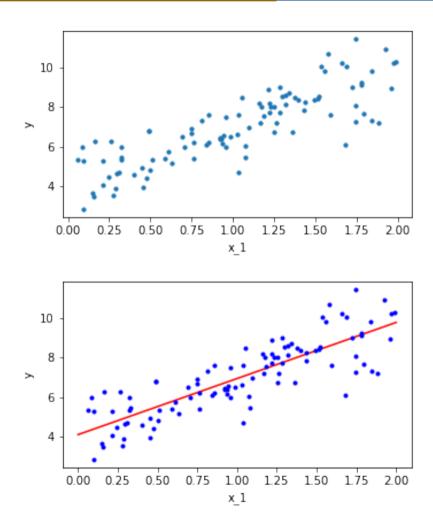
$$\frac{\partial SSE(\boldsymbol{\theta})}{\partial \boldsymbol{\theta}} = 2(\mathbf{X}^{\mathsf{T}}\mathbf{X}\boldsymbol{\theta} - \mathbf{X}\mathbf{y}) = 0 \implies \mathbf{X}^{\mathsf{T}}\mathbf{X}\boldsymbol{\theta} = \mathbf{X}^{\mathsf{T}}\mathbf{y}$$
(25)

Hence, we have

$$\hat{\boldsymbol{\theta}} = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y} \tag{26}$$

$$\hat{\mathbf{y}} = \mathbf{X} (\mathbf{X}^\mathsf{T} \mathbf{X})^{-1} \mathbf{X}^\mathsf{T} \mathbf{y} \tag{27}$$

Closed from solution



Computational complexity

Normal equation의 계산

・Normal equation에 의한 예측치 $\hat{\mathbf{y}}$

$$\hat{\mathbf{y}} = \mathbf{X}(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y} \tag{28}$$

- $\mathbf{X} \in \mathcal{R}^{m \times n}$
- · $\mathbf{X}^{\mathsf{T}}\mathbf{X} \in \mathcal{R}^{\mathsf{n} \times \mathsf{n}}$
- $(\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}$ 의 계산 복잡도 = $O(n^{2.4}) \sim O(n^3)$
- · Feature 수의 약 세제곱으로 계산 시간이 증가

Gradient descent

Batch gradient descent

Linear regression model $\hat{\mathbf{y}} = \mathbf{X}\boldsymbol{\theta}$

$$J(\boldsymbol{\theta}) = SSE(\boldsymbol{\theta}) = \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|^2$$
 (29)

$$\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = 2\mathbf{X}^{\mathsf{T}} (\mathbf{X}\boldsymbol{\theta} - \mathbf{y})$$
(30)

$$\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \begin{bmatrix} \frac{\partial}{\partial \theta_{1}} J(\boldsymbol{\theta}) \\ \frac{\partial}{\partial \theta_{2}} J(\boldsymbol{\theta}) \\ \vdots \\ \frac{\partial}{\partial \theta_{n}} J(\boldsymbol{\theta}) \end{bmatrix} = \begin{bmatrix} 2 \sum_{i=1}^{m} X_{1}^{(i)} \left(\boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} - y^{(i)} \right) \\ 2 \sum_{i=1}^{m} X_{2}^{(i)} \left(\boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} - y^{(i)} \right) \\ \vdots \\ 2 \sum_{i=1}^{m} X_{n}^{(i)} \left(\boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} - y^{(i)} \right) \end{bmatrix}$$
(31)

Gradient descent step

$$\boldsymbol{\theta}^{t+1} = \boldsymbol{\theta}^t - \eta \nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}^t) \tag{32}$$

where iteration number t and $oldsymbol{ heta}$ arbitrary initial value

Batch gradient descent

Batch gradient descent에서

$$\frac{\partial}{\partial \boldsymbol{\theta}} J(\boldsymbol{\theta}) = 2\mathbf{X}^{\mathsf{T}} (\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) \tag{33}$$

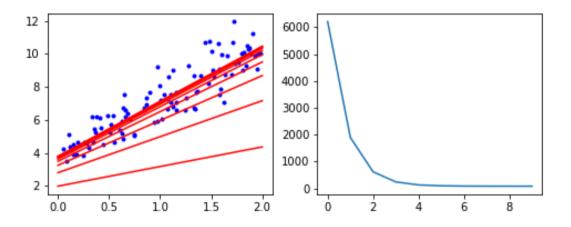
$$= 2 \begin{bmatrix} \mathbf{x}^{(1)} & \mathbf{x}^{(2)} & \cdots & \mathbf{x}^{(m)} \end{bmatrix} \begin{bmatrix} \boldsymbol{\theta}^{T} \mathbf{x}^{(1)} - y^{(1)} \\ \boldsymbol{\theta}^{T} \mathbf{x}^{(2)} - y^{(2)} \\ \vdots \\ \boldsymbol{\theta}^{T} \mathbf{x}^{(m)} - y^{(m)} \end{bmatrix}$$
(34)

$$=2\sum_{i=1}^{m}\mathbf{x}^{(i)}\left(\boldsymbol{\theta}^{\mathsf{T}}\mathbf{x}^{(i)}-y^{(i)}\right) \tag{35}$$

그러므로 이 gradient vector의 j번째 component는

$$\frac{\partial}{\partial \theta_i} J(\boldsymbol{\theta}) = 2 \sum_{i=1}^m x_j^{(i)} \left(\boldsymbol{\theta}^\mathsf{T} \mathbf{x}^{(i)} - y^{(i)} \right)$$
 (36)

Batch gradient descent



Batch gradient descent: computational complexity

Batch gradient descent algorithm

- · 매 스텝마다 batch 전체에 대한 계산 필요
- ·데이터셋이 커지면 속도가 느려짐
- · Normal equation: feature 수에 따라 계산 속도가 지수적으로 느려짐
- · Gradient descent: feature 수가 늘어도 크게 변하지 않음

Learning rate

- ・Hyperparameter인 학습률(learning rate) η 가 너무 작은 경우 시간이 오래 걸림
- · 너무 큰 경우 최적해를 지나쳐 해를 찾지 못할 수 있음

Learning schedule

- Constant learning rate
 - 보통 0.1, 0.01부터 시작하여 여러 가지 값으로 시험해보며 범위를 좁혀 나감
- Time-based decay

$$\eta = \frac{\eta_0}{(1+kt)} \tag{37}$$

 η_0 : 학습률 초기값, k: hyperparameter, t: iteration

- Step decay
 - 정해진 epoch마다 학습률을 줄이는 방법
 - 예: 5 epoch마다 반으로, 20 epoch마다 1/10로
 - Epoch: 훈련 데이터셋 전체를 모두 사용할 때 = 한 epoch
- Exponential decay

$$\eta = \eta_0 e^{-kt} \tag{38}$$

 η_0 : 학습률 초기값, k: hyperparameter, t: iteration

Stochastic gradient descent

For our linear regression model $\hat{y} = \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}$

$$J(\boldsymbol{\theta}) = SSE(\boldsymbol{\theta}) = \sum_{i=1}^{m} \left(\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2} = \sum_{i=1}^{m} J_{i}(\boldsymbol{\theta})$$
(39)

$$\boldsymbol{\theta}^{t+1} = \boldsymbol{\theta}^{t} - 2\eta \left(\mathbf{y}^{(t)} - (\boldsymbol{\theta}^{t})^{\mathsf{T}} \mathbf{x}^{(t)} \right) \mathbf{x}^{(t)}$$
 (40)

- · 무작위로 선택한 한 개의 sample에 대해서만 gradient를 계산하여 parameter를 update
- sequential learning or online learning
- · 대규모 데이터셋을 처리하는데 유리
- ㆍ 선택하는 사례의 무작위성으로 움직임이 불규칙
- · BGD에 비해 local optimum에서 쉽게 빠져나올 수 있음
- ㆍ 최적해에 도달하지만 지속적으로 요동
- · BGD와 마찬가지로 global optimum이라는 보장이 없음

Mini-batch gradient descent

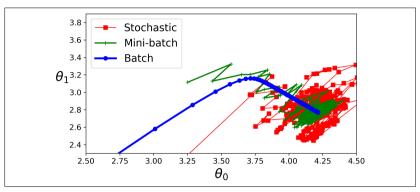


Figure 4-11. Gradient Descent paths in parameter space

- · 훈련 데이터셋을 작은 크기의 무작위 부분 집합으로 나누어서 gradient 를 구하는 방법
- 예 100,000개의 데이터 = (mini-batch size 100) × (1,000 mini-batches)
- · Batch gradient descent와 stochastic gradient descent(SGD)의 절충
- · SGD보다 불규칙한 움직임이 덜함
- · SGD보다 local minimum에서 빠져나오기가 상대적으로 더 어려움
- · GPU를 통한 매트릭스 연산의 속도를 높일 수 있음

Linear regression comparison

Table 4-1. Comparison of algorithms for Linear Regression

Algorithm	Large m	Out-of-core support	Large n	Hyperparams	Scaling required	Scikit-Learn
Normal Equation	Fast	No	Slow	0	No	n/a
SVD	Fast	No	Slow	0	No	LinearRegression
Batch GD	Slow	No	Fast	2	Yes	SGDRegressor
Stochastic GD	Fast	Yes	Fast	≥2	Yes	SGDRegressor
Mini-batch GD	Fast	Yes	Fast	≥2	Yes	SGDRegressor



There is almost no difference after training: all these algorithms end up with very similar models and make predictions in exactly the same way.