Inclass 15: Singular Value Decomposition

[AIX7021] Computer Vision

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2 orthonormal 3 tan.

= Pt row vector \(\frac{1}{2} \) or thonormal.

$$IN = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \qquad IN = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$U = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

TJ: orthogonal

Ch7+34,23/ diagonal matrix = ていたかのけ かり それ, LLのスにらえら [93] [83] [83] 0 1 0

diagonal matrix NXN N27N

Square matrix

$$A = \text{diag} (d_1, d_2, \dots, d_N)$$

$$\text{diag} (ID, I) = \begin{bmatrix} ID & 0 \\ 0 & I \end{bmatrix}$$

$$\text{diag} (A_1, Y_1, -3) = \begin{bmatrix} A_1 & A_2 & A_3 & A_4 & A_$$

$$A = diag(di, dz, \dots, dn)$$

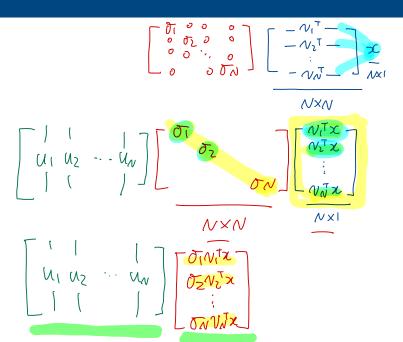
$$A^{-1} = diag(di, dz^{-1}, \dots, dn)$$

Singular value decomposition

Singular value decomposition (SVD) of a given matrix A

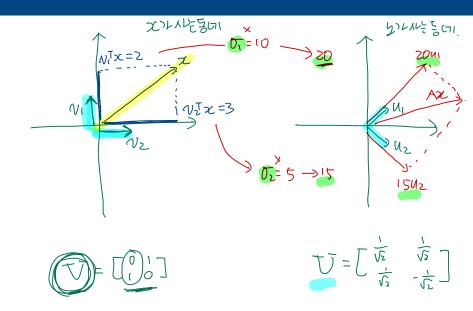
- $\mathbf{A} \in \Re^{m \times n}$, rank $(\mathbf{A}) = r$
- $\cdot \mathbf{U} \in \Re^{m \times r}, \ \mathbf{U}^{\mathsf{T}} \mathbf{U} = \mathbf{I} \longleftarrow$
- $\mathbf{v} \in \Re^{n \times r}, \ \mathbf{V}^T \mathbf{V} = \mathbf{I}$
- $\Sigma = \operatorname{diag}(\sigma_1, ..., \sigma_r)$ where $\sigma_1 \ge \cdots \ge \sigma_r > 0$

$$y = Ax = \left[\begin{array}{c} \left(\sqrt{x} \right) \right] \\ V = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right] \\ = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right] \\ = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right] \\ = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right] \\ = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right] \\ = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right] \\ = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right] \\ = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right] \\ = \left[\begin{array}{c} v_1 & v_2 & \dots & v_N \\ 1 & 1 & \dots & 1 \end{array}\right]$$

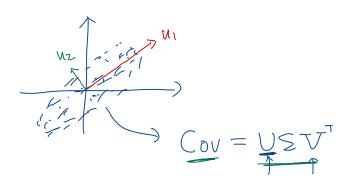


$$y = \frac{1}{1} \left(\frac{\partial_{\tau} v_{\tau}^{T} x}{\partial_{\tau} v_{\tau}^{T} x} \right) + \frac{1}{1} \frac{1}{1} \left(\frac{\partial_{\tau} v_{\tau}^{T} x}{\partial_{\tau} v_{\tau}^{T} x} \right) + \cdots + \frac{1}{1} \frac{1}$$

$$= \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \cdot 10 \cdot 2 + \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \cdot 5 \cdot 3$$



0/1



Singular value decomposition

with
$$\mathbf{U} = \begin{bmatrix} \ | & \ | & \ \mathbf{u}_1 & \mathbf{u}_2 & \cdots & \mathbf{u}_r \ | & \ | & \ | \end{bmatrix}$$
 and $\mathbf{V} = \begin{bmatrix} \ | & \ | & \ | & \ \mathbf{v}_1 & \mathbf{v}_2 & \cdots & \mathbf{v}_r \ | & \ | & \ | & \ | \end{bmatrix}$,

$$\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathsf{T}} = \sum_{k=1}^{\mathsf{r}} \sigma_k \mathbf{u}_k \mathbf{v}_k^{\mathsf{T}}$$
(3)

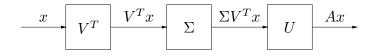
where

- σ_i are the nonzero singular values of **A**
- \cdot \mathbf{v}_i are the right or input singular vectors of \mathbf{A}
- \cdot \mathbf{u}_i are the left or output singular vectors of \mathbf{A}

Interpretations

SVD:

$$\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^{\mathsf{T}} = \sum_{k=1}^{\mathsf{r}} \sigma_k \mathbf{u}_k \mathbf{v}_k^{\mathsf{T}}$$
 (4)



Linear mapping y = Ax can be decomposed as

- compute coefficients of x along input directions $\mathbf{v}_1,...,\mathbf{v}_r$
- scale coefficients by σ_i
- reconstitute along output directions $\mathbf{u}_1,...,\mathbf{u}_r$

difference with eigenvalue decomposition for symmetric ${\bf A}$: input and output directions are different

Geometric interpretation

