

#### University of Palestine



#### **Computer Graphics**

**ITGD3107** 

**Assistant Professor** 

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#### **ITGD3107 Computer Graphics**

Chapter 9-10

Three Dimensional Concepts and Object Representations

### Object Representation

- Graphics scenes can contain many different kinds of objects and material surfaces
  - Trees, flowers, clouds, rocks, water, bricks, wood paneling, rubber, paper, steel, glass, plastic and cloth
- So it may not be surprising that there is no single method that we can use to describe all the characteristics of these different shapes/materials

### Object Representation

• Scene = an assembly of one or more models

- A model contains
  - Structural description: Geometry of the shape
  - Surface description: Appearance and light

# 3D Object Representations

- Boundary representation
  - A set of surfaces that separate the object interior from the environment
  - Eg) Polyhedra, curved boundary surfaces
- Space-partitioning
  - Partitioning the spatial region into a set of small, non overlapping, contiguous solids (usually cubes)
  - Eg) Volumetric data, trees
- Procedural methods
  - Fractals, shape grammars
- Constructive solid geometry
- Physically-based modeling

#### Issues in Model Selection

- Computational cost
  - Storage space
  - Model construction time
  - Display time
- Effectiveness in modeling the desired phenomena
  - Geometry
    - Looks good for image synthesis
    - Accuracy for simulation
  - Appearance
    - Looks / Accuracy

#### Issues in Model Selection

- Implementation complexity
  - The number of primitives
  - The complexity of each primitives
- Ease of acquiring (or creating) data
- Ease of manipulation
  - Operations on models
- Ease of animation
  - Match to simulator
  - Cost of conversion
  - Physics of motion

### Polyhedra

- A polyhedron is a 3D solid which consists of a collection of polygons, usually joined at their edges
- The inside of the solid is divided by the polygons from the outside of the solid

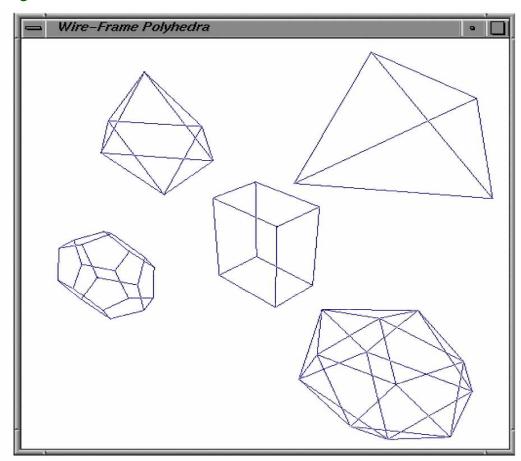


Figure 8-1

A perspective view of the five GLUT polyhedra, scaled and positioned within a display window by procedure displayWirePolyhedra.

## Polyhedra

- Euler formula
  - Determines the validity of planar graphs

$$V - E + F = 2$$

- V: The number of vertices
- − E: The number of edges
- F: The number of faces

# Polyhedra

- Euler-Poincare formula
  - Generalizes the Euler formula for arbitrary dimension and genus
  - Polyhedra in three-dimension space follows

$$V - E + F - L = 2(S - G)$$

- L: The number of Inner loops
- S: The number of shells
- G: The number of holds

# Functional Representation

• Explicit surfaces z = f(x, y)

$$z = f(x, y)$$

Implicit surfaces

$$f(x, y, z) = 0$$

- Parametric surfaces
- (x(t), y(t), z(t)) for  $t \in [a,b]$ Issues
  - Representation power
  - Easy to render
  - Easy to manipulate (translate, rotate, and deform)

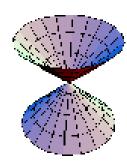
#### Implicit Surfaces

- Quadric surfaces
  - Implicit second-order polynomial equations
- Superquadric surfaces
  - A generalization of quadric surfaces
- Blobby objects (metaballs)
  - A collection of spherical density functions

### Quadric surfaces

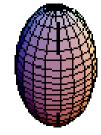
• Double cones

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 0$$

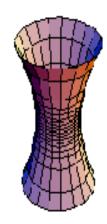


• Ellipsoids

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

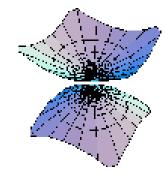


• Hyperboloids of one sh  $\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$ 



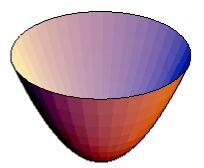
Hyperboloids of two sheets

$$\frac{z^2}{c^2} - \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$



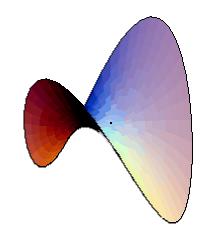
#### Quadric surfaces

• Elliptic parabolo  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z}{c}$ 



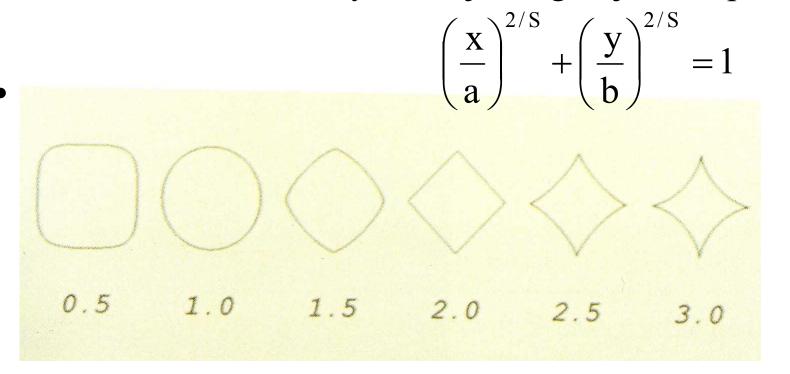
Hyperbolic paraboloids

$$\frac{y^2}{h^2} - \frac{x^2}{a^2} = \frac{z}{c}$$



## Superquadrics

- A generalization of quadric surfaces, formed by incorporating additional parameters into quadric equations
  - Increased flexibility for adjusting object shapes

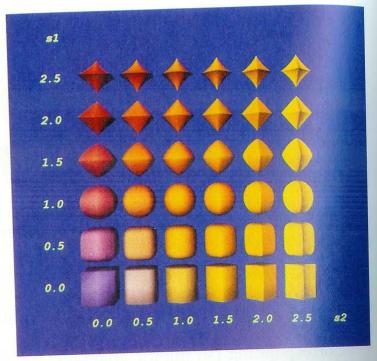


# Superquadrics

Superellipsoid

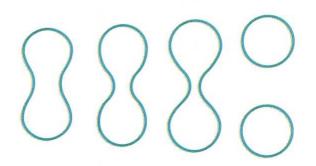
$$\left[ \left( \frac{x}{a} \right)^{2/S_1} + \left( \frac{y}{b} \right)^{2/S_2} \right]^{S_2/S_1} + \left( \frac{x}{c} \right)^{2/S_1} = 1$$

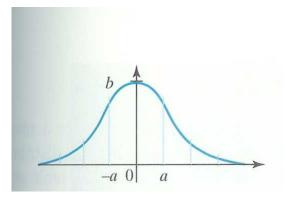
**FIGURE 8-7** Superellipsoids plotted with values for parameters  $s_1$  and  $s_2$  ranging from 0.0 to 2.5 and with  $r_x = r_y = r_z$ .



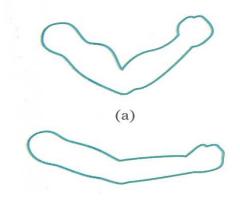
# Blobby Objects

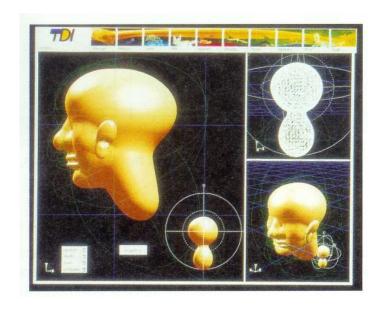
• A collection of density functions





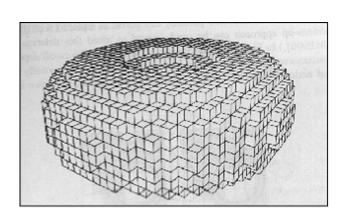
• Equi-density surfaces

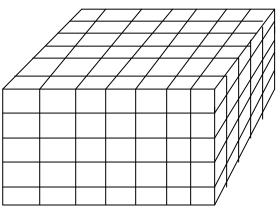




# Spatial Partitioning

- Volume data
  - Use identical cells (voxels)
  - Space-filling tesselation with cubes or parallelopipeds
  - Expensive storage but simple data structure
  - Useful for medical imaging: volume visualization





# Spatial Partitioning

#### Octrees

- Partition space into 8 cubes, recursively
- Increase space efficiency of solid tesselations

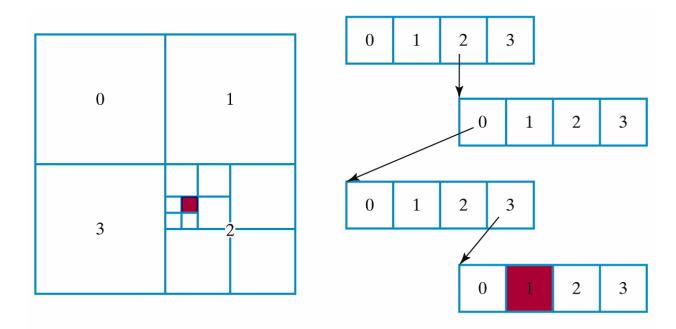
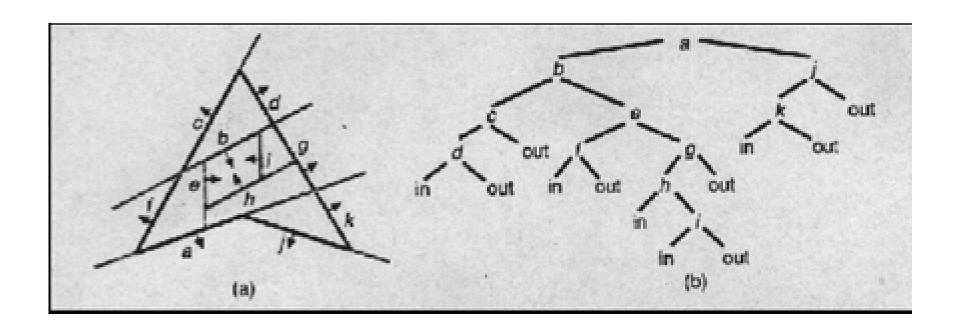


Figure 8-65

Quadtree representation for a square region of the xy plane that contains a single foreground-color area on a solid-color background.

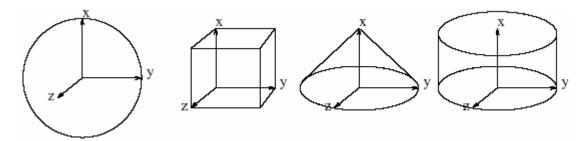
# Spatial Partitioning

- Binary Space Partitioning (BSP) trees
  - Subdivide a scene into two sections at each step with a plane that can be at any position and orientation

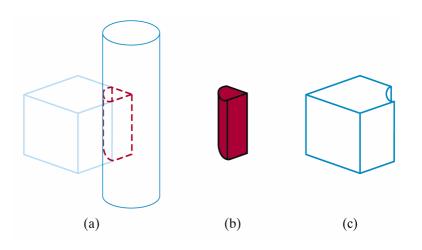


### Constructive Solid Geometry

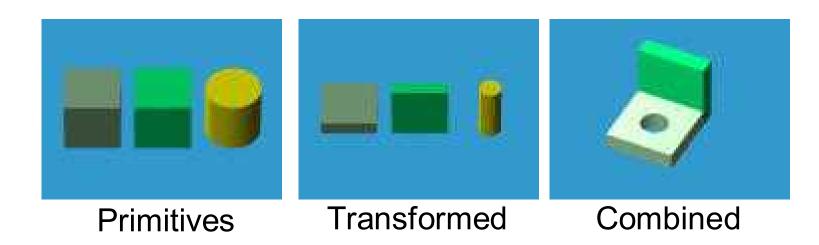
- Recursively combine simple primitives by boolean operations
  - Simple primitives



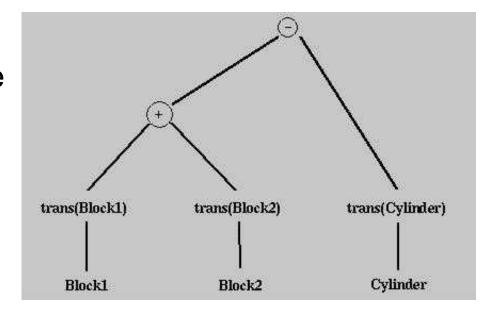
- Transform or deform
- Tree structure



### Constructive Solid Geometry

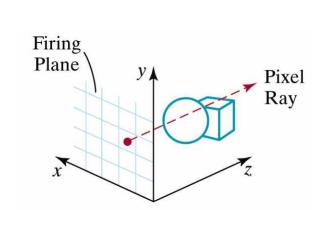


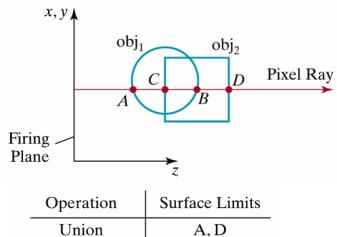
Tree structure



### Constructive Solid Geometry

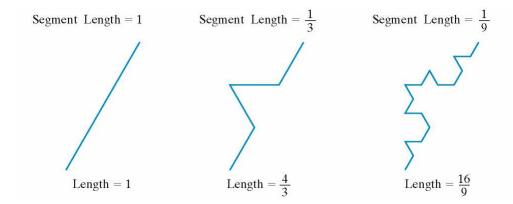
- Ray-casting methods for rendering CSG objects
  - Cast a ray through each pixel
  - Perform boolean operations along each ray



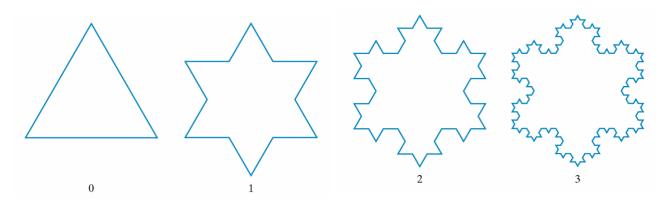


Operation	Surface Limits
Union Intersection Difference $(obj_2 - obj_1)$	A, D C, B B, D

- Self-similar fractals
  - Substitution



- Example: Koch curve



• Substitution rules



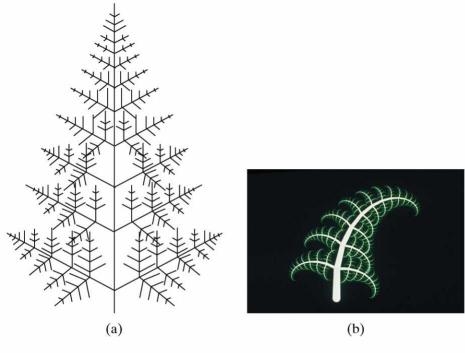


Figure 8-76

Self-similar constructions for a fern. (*Courtesy of Peter Oppenheimer, Computer Graphics Lab, New York Institute of Technology.*)

• Terrain by random perturbation





• Natural scenes with trees, flowers, and grass

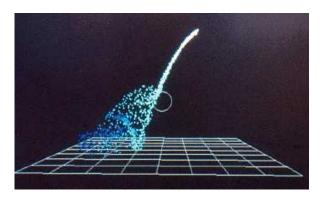


# Physically Based Modeling

Particle systems

Shape description is combined with physical

simulation









# Physically Based Modeling

• Procedural modeling + physically based simulation

