#### TECHNICAL UNIVERSITY OF CRETE

#### DIPLOMA THESIS

# Design and Implementation of a Low Cost Embedded System for Localization of Drones Flying in Swarms

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#### TECHNICAL UNIVERSITY OF CRETE

### Abstract

School of Electrical and Computer Engineering

Electrical and Computer Engineer

Design and Implementation of a Low Cost Embedded System for Localization of Drones Flying in Swarms

by Christos Spyridakis

TODO: English ...

#### ΠΟΛΥΤΕΧΝΕΙΟ ΚΡΗΤΗΣ

## Περίληψη

Σχολή Ηλεκτρολόγων Μηχανικών και Μηχανικών Υπολογιστών

Ηλεκτρολόγος Μηχανικός και Μηχανικός Υπολογιστών

Σχεδίαση και Υλοποίηση Ενσωματωμένου Συστήματος Χαμηλού Κόστους για Εύρεση Θέσης μη Επανδρωμένων Αεροσκαφών που Πετούν σε Σχηματισμό

από τον Χρήστο ΣΠΥΡΙΔΑΚΗ

ΤΟΟΟ: Ελληνικά ...

## Acknowledgements

TODO: Add Acknowledgements

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## **Physical Constants**

Speed of Light  $c_0 = 2.99792458 \times 10^8 \,\mathrm{m \, s^{-1}} \; (\mathrm{exact})$ 

xix

# List of Symbols

a distance m

 $\omega$  angular frequency rad

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### List of Abbreviations

MCU Micro Controller Unit

MPU Micro Processor Unit

UAV Unmanned Aerial Vehicle

VTOL Vertically Hover, Take-off, and Land

ESC Electronic Speed Control

IMU Intertial Measurement Unit

GPS Global Positioning System

FPV First Person View

WSN Wireless Sensor Networks

UGV Unmanned Ground Vehicle

MAV Micro Aerial Vehicle

Dedicated to those people who have helped me be the person I am today...

### Introduction

#### 1.1 Motivation

#### 1.2 Scientific Goals and Contributions

TODO

#### 1.3 Thesis Outline

#### TODO

- Chapter 2 Theoretical Background:
- Chapter 3 Related Work:
- Chapter 4 Design Features and Implementation:
- Chapter 5 Applications and Usage Examples:
- Chapter 6 Experiments and Results:
- Chapter 7 Conclusions and Future Work:

## Theoretical Background

"Let no one ignorant of geometry enter"

Plato

## Related Work

"This is where technology is now, imagine where we can go in the future"

Timothy Chung

### 3.1 Thesis Approach

This should be the last section

# Design Features and Implementation

# Applications and Usage Examples

## **Experiments and Results**

### Conclusions and Future Work