

TECHNICAL UNIVERSITY OF CRETE

DIPLOMA THESIS

Design and Implementation of a Low Cost Embedded System for Localization of Drones Flying in Swarms

Author:

Christos SPYRIDAKIS

Thesis Committee:

Prof. Apostolos DOLLAS (Supervisor)

Asst. Prof. Eftychios KOUTROULIS

Asst. Prof. Panagiotis PARTSINEVELOS



*A thesis submitted in fulfillment of the requirements
for the diploma of Electrical and Computer Engineer
in the*

School of Electrical and Computer Engineering
Microprocessor and Hardware Laboratory

November 23, 2020

TECHNICAL UNIVERSITY OF CRETE

Abstract

School of Electrical and Computer Engineering

Electrical and Computer Engineer

**Design and Implementation of a Low Cost Embedded System for
Localization of Drones Flying in Swarms**

by Christos SPYRIDAKIS

TODO: English . . .

ΠΟΛΥΤΕΧΝΕΙΟ ΚΡΗΤΗΣ

Περίληψη

Σχολή Ηλεκτρολόγων Μηχανικών και Μηχανικών Υπολογιστών

Ηλεκτρολόγος Μηχανικός και Μηχανικός Υπολογιστών

Σχεδίαση και Υλοποίηση Ενσωματωμένου Συστήματος Χαμηλού
Κόστους για Εύρεση Θέσης μη Επανδρωμένων Αεροσκαφών που
Πετούν σε Σχηματισμό

από τον Χρήστο ΣΠΤΡΙΔΑΚΗ

TODO: Ελληνικά ...

Acknowledgements

TODO: Add Acknowledgements

Contents

Abstract	iii
Abstract	v
Acknowledgements	vii
Contents	ix
List of Figures	xi
List of Tables	xiii
List of Algorithms	xv
Physical Constants	xvii
List of Symbols	xix
List of Abbreviations	xxi
1 Introduction	1
1.1 Motivation	1
1.2 Scientific Goals and Contributions	1
1.3 Thesis Outline	1
2 Theoretical Background	3
3 Related Work	5
3.1 Thesis Approach	5
4 Design Features and Implementation	7
5 Applications and Usage Examples	9
6 Experiments and Results	11

List of Figures

List of Tables

List of Algorithms

Physical Constants

Speed of Light $c_0 = 2.997\,924\,58 \times 10^8 \text{ m s}^{-1}$ (exact)

List of Symbols

a	distance	m
ω	angular frequency	rad

List of Abbreviations

MCU	Micro Controller Unit
MPU	Micro Processor Unit
UAV	Unmanned Aerial Vehicle
VTOL	Vertically Hover, Take-off, and Land
ESC	Electronic Speed Control
IMU	Intertial Measurement Unit
GPS	Global Positioning System
FPV	First Person View
WSN	Wireless Sensor Networks
UGV	Unmanned Ground Vehicle
MAV	Micro Aerial Vehicle

*Dedicated to those people who have helped me be the
person I am today...*

Chapter 1

Introduction

1.1 Motivation

1.2 Scientific Goals and Contributions

1.3 Thesis Outline

- Chapter 2 - Theoretical Background:
- Chapter 3 - Related Work:
- Chapter 4 - Design Features and Implementation:
- Chapter 5 - Applications and Usage Examples:
- Chapter 6 - Experiments and Results:
- Chapter 7 - Conclusions and Future Work:

Chapter 2

Theoretical Background

"Let no one ignorant of
geometry enter"

Plato

Chapter 3

Related Work

“This is where technology is
now, imagine where we can go
in the future”

Timothy Chung

3.1 Thesis Approach

This should be the last section

Chapter 4

Design Features and Implementation

”

Chapter 5

Applications and Usage Examples

Chapter 6

Experiments and Results

Chapter 7

Conclusions and Future Work

