

Causal Bayesian Networks

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Causal Bayesian Networks

Today:

- Causal Bayesian Networks
- How do we reason about independence in Bayesian Networks?

Review: Distributions of Discrete R.V.s

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Joint

$$P(X = x, Y = y)$$

Single number

"Probability that
 $X = x$ and $Y = y$ "

Shorthand: $P(x, y)$

$$P(X, Y)$$

A table

"Joint distribution of
 X and Y "

Review: Distributions of Discrete R.V.s

Joint	$P(X = x, Y = y)$ Shorthand: $P(x, y)$	Single number	"Probability that $X = x$ and $Y = y$ "
	$P(X, Y)$	A table	"Joint distribution of X and Y "
Conditional	$P(X = x \mid Y = y)$ Shorthand: $P(x \mid y)$	Single number	"Probability that $X = x$ if $Y = y$ "
	$P(X \mid Y)$	A collection of tables for each y	"Conditional distribution of X given Y "

Review: Distributions of Discrete R.V.s

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	$P(X \mid Y)$	A collection of tables for each y	"Conditional distribution of X given Y "
Marginal	$P(X = x)$ Shorthand: $P(x)$	Single number	"Probability that $X = x$ "
	$P(X)$	A table	"Marginal distribution of X "

Causal Bayesian Networks

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1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.

Causal Bayesian Networks

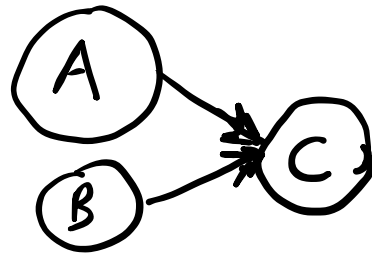
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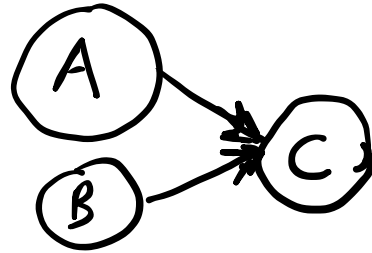
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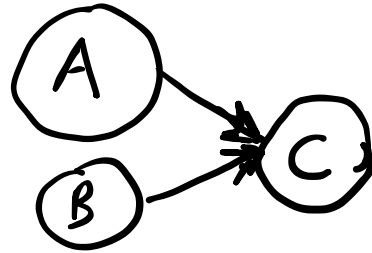


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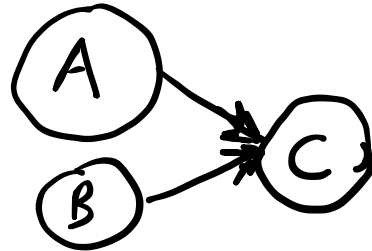
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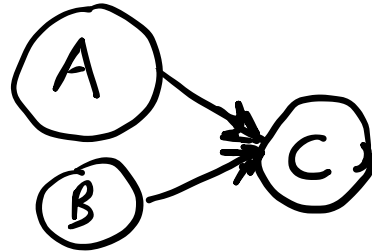
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$$P(C \mid A, B)$$

$$P(A)$$

$$P(B)$$

In a *Causal Bayesian Network*, arrows denote causation.



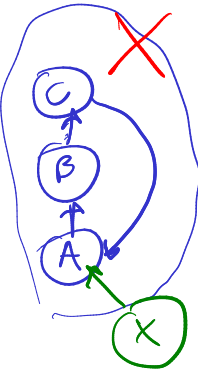
B is a result of A (and some aleatory uncertainty)

$$\rightarrow P(B \mid A) \leftarrow \text{"dynamics of system"}$$

$$P(A)$$

$$P(X_{k+1} \mid X_k, U_k)$$

$$X_{k+1} = f(X_k, U_k, W_k)$$



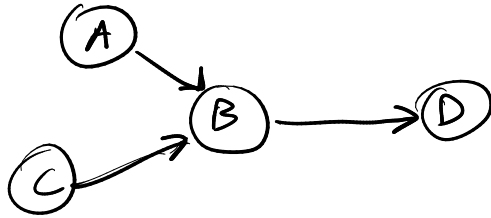
Chain rule for Bayesian Networks

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$$P(X_1, X_2 \dots X_n)$$

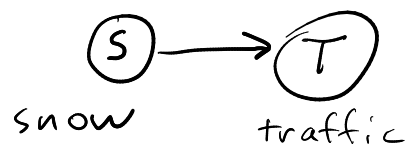
Joint

$$P(X_{1:n}) = \prod_{i=1}^n P(X_i \mid \text{pa}(X_i))$$



$$P(A, B, C, D) = P(A) P(B \mid A, C) P(C) P(D \mid B)$$

Simple Causal Bayes Net Example



$$\begin{aligned}
 P(S=1) &= 0.1 \\
 P(T=1|S=0) &= 0.2 \\
 P(T=1|S=1) &= 0.7
 \end{aligned}
 \quad \left. \vphantom{\begin{aligned} P(S=1) \\ P(T=1|S=0) \\ P(T=1|S=1) \end{aligned}} \right\} 3 \text{ parameters}$$

observe snow, traffic? $\Rightarrow P(T=1|S=1) = 0.7$
 $S=1 \quad P(T=1|S=1)$

observe traffic, snow? $\Rightarrow P(S=1|T=1) = \frac{P(S=1, T=1)}{P(T=1)} = \frac{P(T=1|S=1)P(S=1)}{\sum_s P(T=1|S=s)P(S=s)}$
 $T=1 \quad P(S=1|T=1)$

$$\begin{aligned}
 &= \frac{0.07}{0.2 \cdot 0.9 + 0.7 \cdot 0.1} \\
 &= 0.28
 \end{aligned}$$

"Information can flow up or down edges"

Naive Inference on Bayes Nets

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Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

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Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$

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Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$ C is a "hidden variable"

1. $P(A, B = b, C) = P(B = b \mid C) P(C \mid A) P(A).$

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1. $P(A, B = b, C) = P(B = b \mid C) P(C \mid A) P(A).$

2. Marginalize over hidden and query variables to get

$$P(A = a, B = b) = \sum_c P(A = a, B = b, C = c)$$

and

$$P(B = b) = \sum_{a,c} P(A = a, B = b, C = c)$$

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Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$

C is a "hidden variable"

1. $P(A, B = b, C) = P(B = b \mid C) P(C \mid A) P(A)$. \leftarrow Chain Rule
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$$P(A = a, B = b) = \sum_c P(A = a, B = b, C = c)$$

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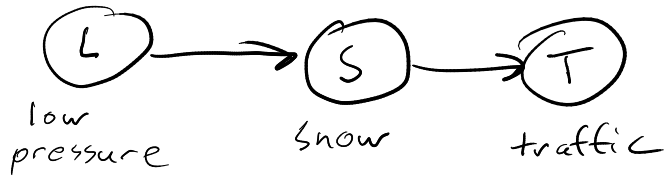
$$P(B = b) = \sum_{a,c} P(A = a, B = b, C = c)$$

$$3. P(A = a \mid B = b) = \frac{P(A=a, B=b)}{P(B=b)}$$

(Book introduces unnormalized "factors", but process is the same.)

Conditional Independence in Bayes Nets

"Chain"



$T \perp L \mid S$?
Yes

Definition of cond. indep.

$$P(T, L \mid S) = P(T \mid S) P(L \mid S)$$

$$P(T \mid S) = P(T \mid S, L)$$

$$P(T \mid S) \stackrel{?}{=} P(T \mid S, L)$$

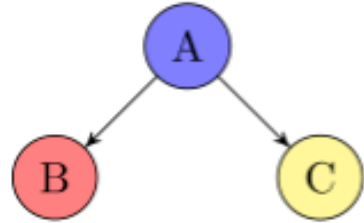
$$= \frac{P(T, S, L)}{P(S, L)}$$

$$= \frac{P(T \mid S) \cancel{P(S \mid L)} \cancel{P(L)}}{\sum_{+} \cancel{P(T_{+} \mid S)} \cancel{P(S \mid L)} \cancel{P(L)}}$$

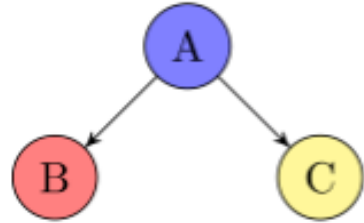
$$= P(T \mid S)$$

Conditional Independence: Fork

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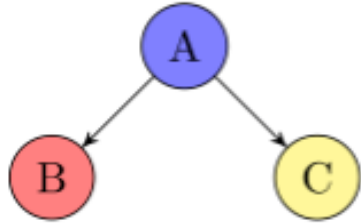


Conditional Independence: Fork



$B \perp C \mid A ?$

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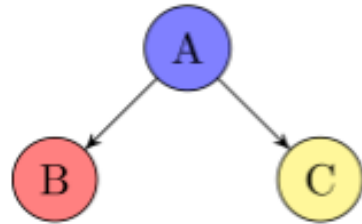


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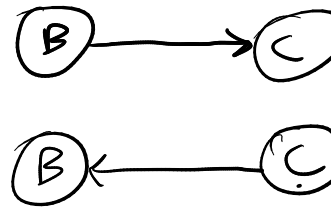
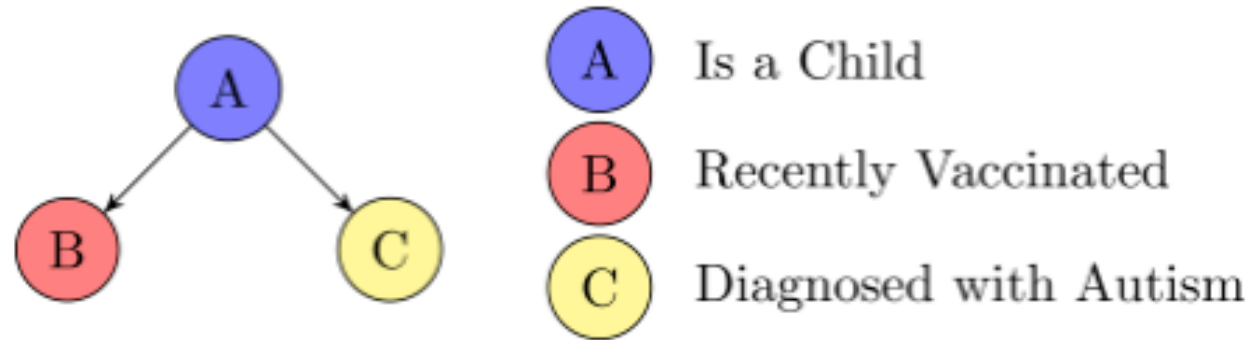


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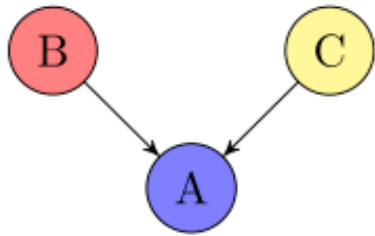
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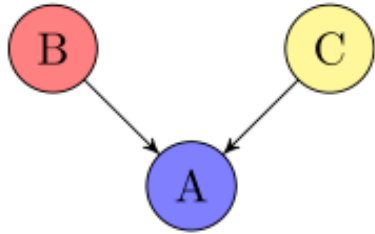


Conditional Independence: Inverted Fork

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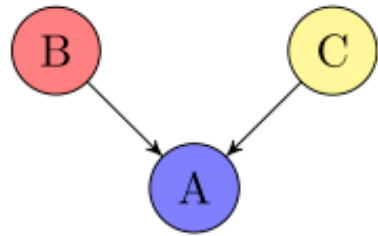
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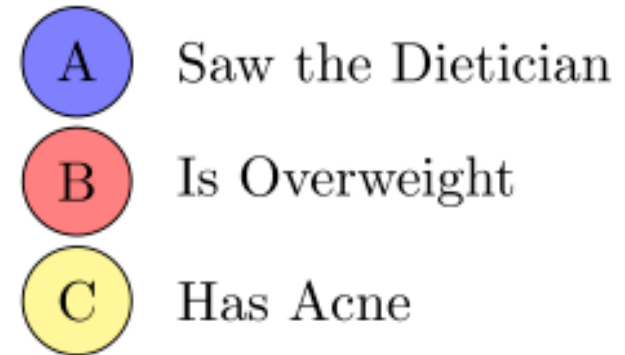
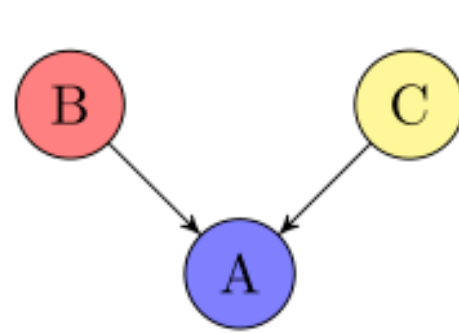
$$B \perp C \mid A ?$$

Inconclusive
based on structure

Conditional Independence: Inverted Fork

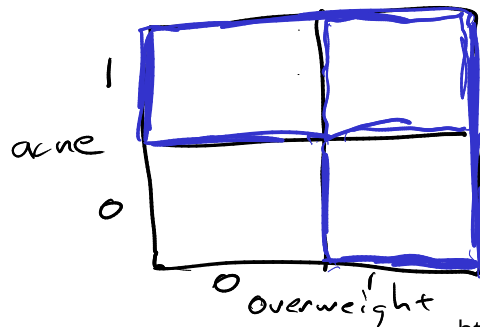


$B \perp C \mid A ?$



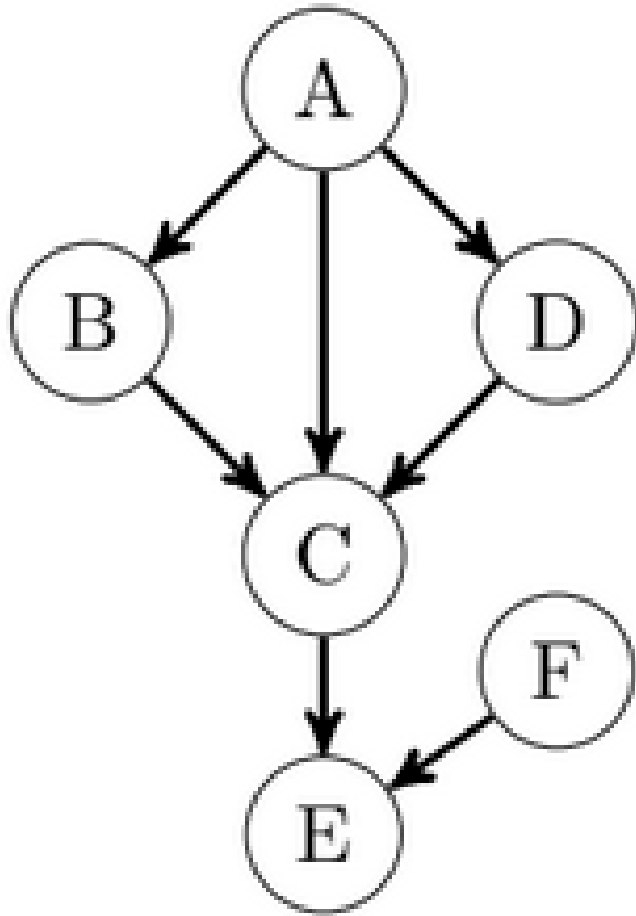
Assume $B \perp C$

Does not imply that $B \perp C \mid A$



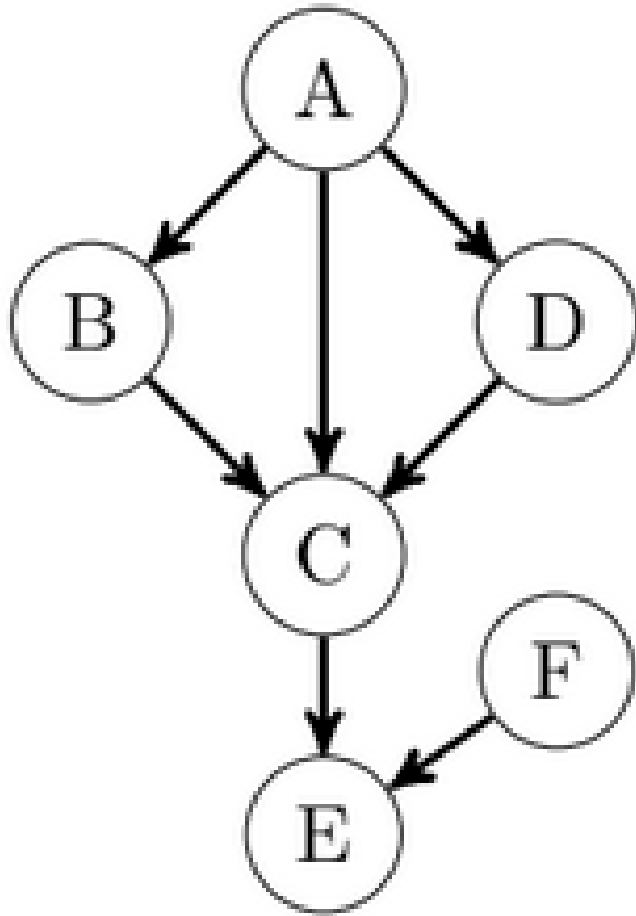
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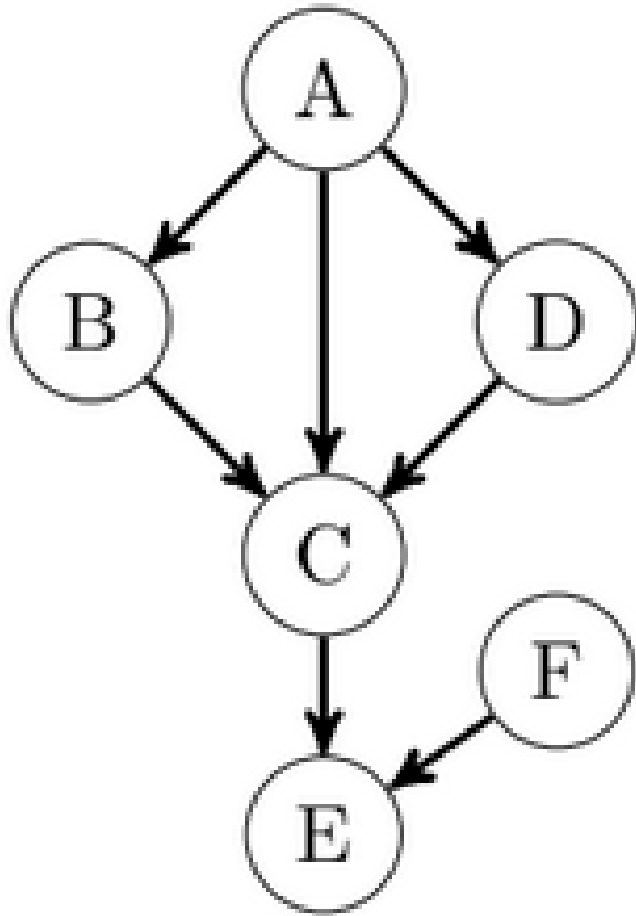
$(B \perp D \mid A) ?$



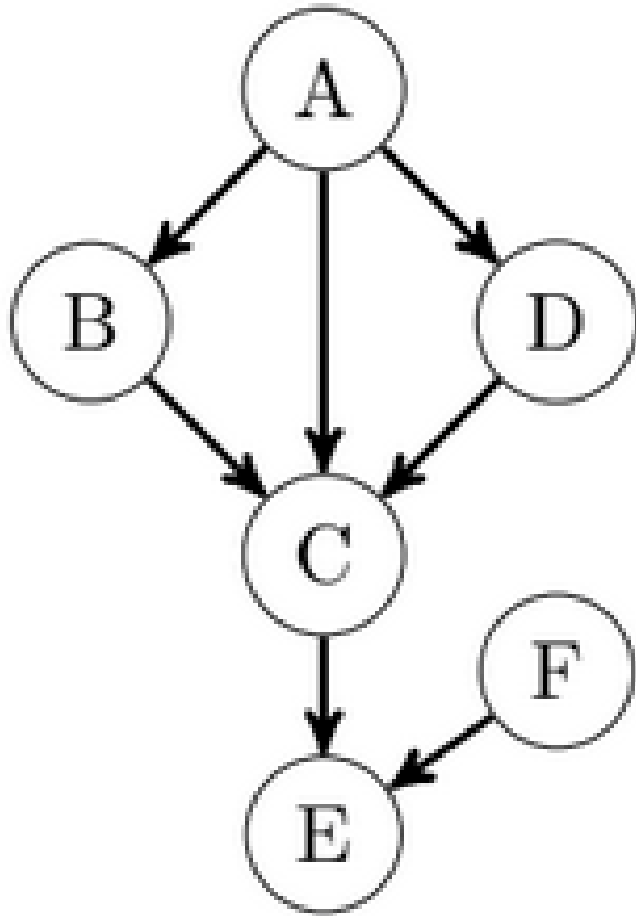
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More Complex Example

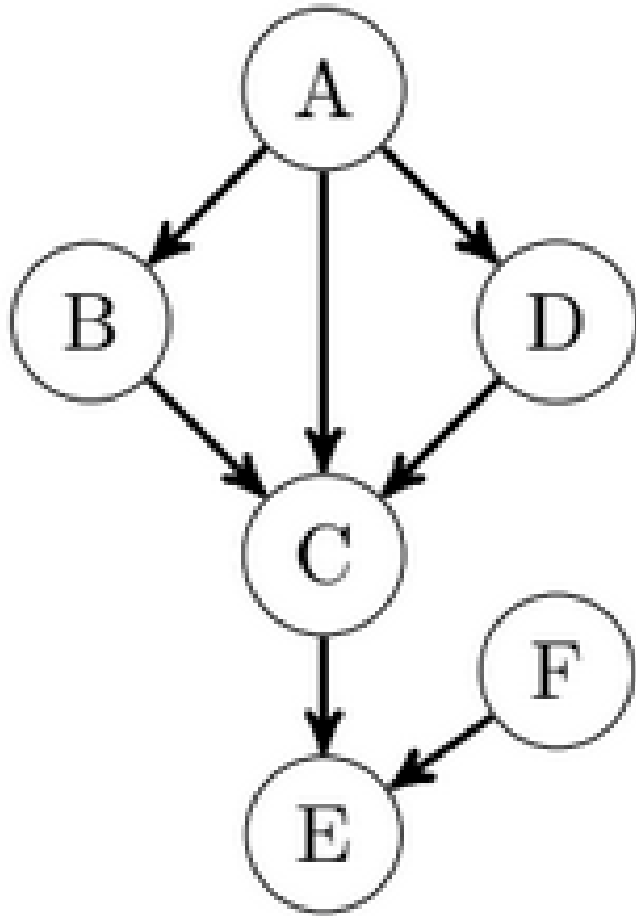


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Yes!

$(B \perp D \mid E) ?$

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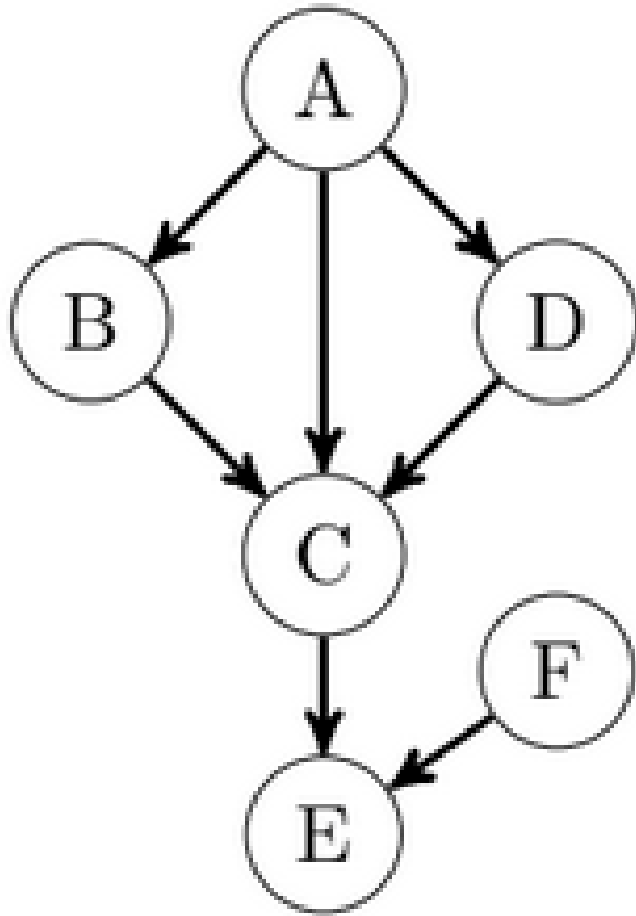
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Why is this relevant to decision making?

d-Separation

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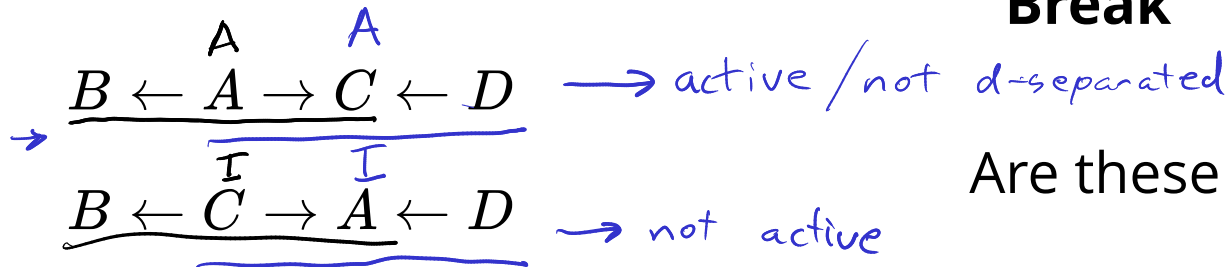
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Are these paths d-separated by $\mathcal{C} = \{C\}$?

d-Separation for Bayes Nets

*short for "directionally separated"

d-Separation for Bayes Nets

We say that A and B are *d-separated* by C if all acyclic paths between A and B are d-separated by C .

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We say that A and B are *d-separated* by \mathcal{C} if all acyclic paths between A and B are d-separated by \mathcal{C} .

If A and B are d-separated by \mathcal{C} then $A \perp B \mid \mathcal{C}$

d-Separation for Bayes Nets

We say that A and B are *d-separated* by \mathcal{C} if all ^{undirected} acyclic paths between A and B are d-separated by \mathcal{C} .

If A and B are d-separated by \mathcal{C} then $A \perp B \mid \mathcal{C}$

In other words, if there is any active path w.r.t. \mathcal{C} between A and B , we *cannot* conclude that $A \perp B \mid \mathcal{C}$ based on the structure alone.

Proving Conditional Independence

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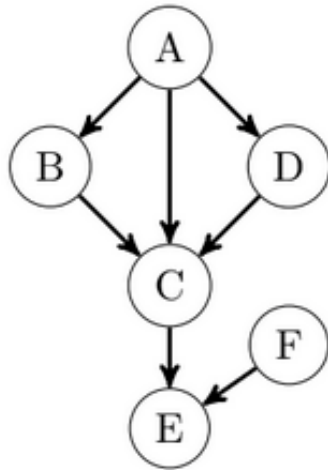
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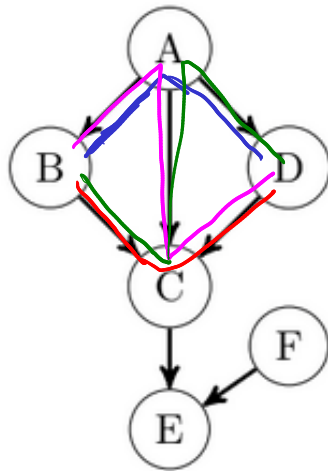


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Example: $(B \perp D \mid \overbrace{C, E}^{\mathcal{C}}) ?$

$B \leftarrow A \rightarrow D$

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$B \rightarrow C \leftarrow A \rightarrow D$

active \longrightarrow inconclusive

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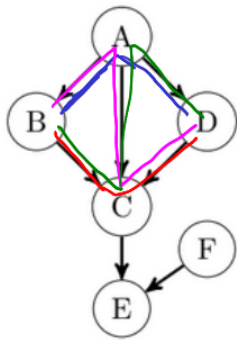
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The *Markov Blanket* of \mathcal{X} is the minimal set of nodes that, if their values were known, would make \mathcal{X} conditionally independent of all other nodes.

A Markov blanket of a particular node consists of its parents, its children, and the other parents of its children.

If \mathcal{B} is the Markov blanket of \mathcal{X} , you can treat analyze $\mathcal{B} \cup \mathcal{X}$ alone, and ignore any other nodes.



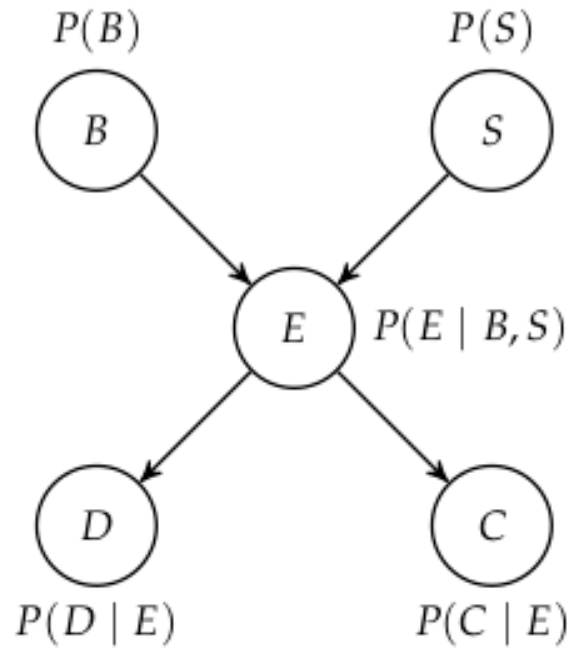
What is the Markov Blanket of $\{E, F\}$?

C ✓

Exercise

1. The path contains a *chain* $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. The path contains a *fork* $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. The path contains an *inverted fork* (v-structure) $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Exercise

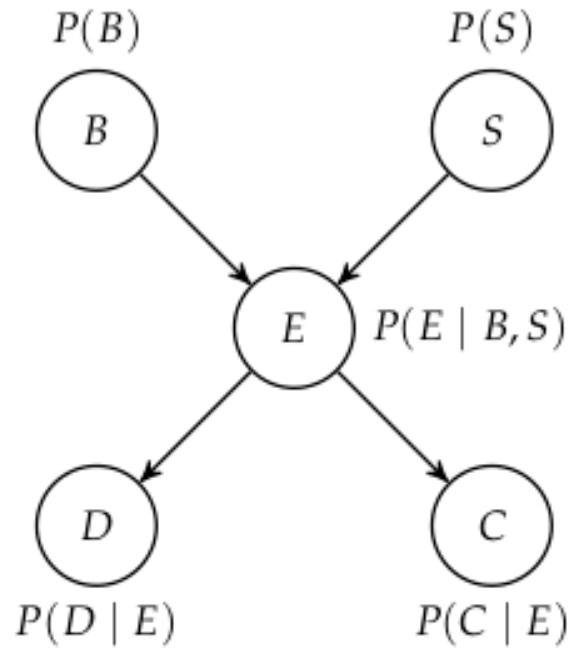


B battery failure
 S solar panel failure
 E electrical system failure
 D trajectory deviation
 C communication loss

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Exercise

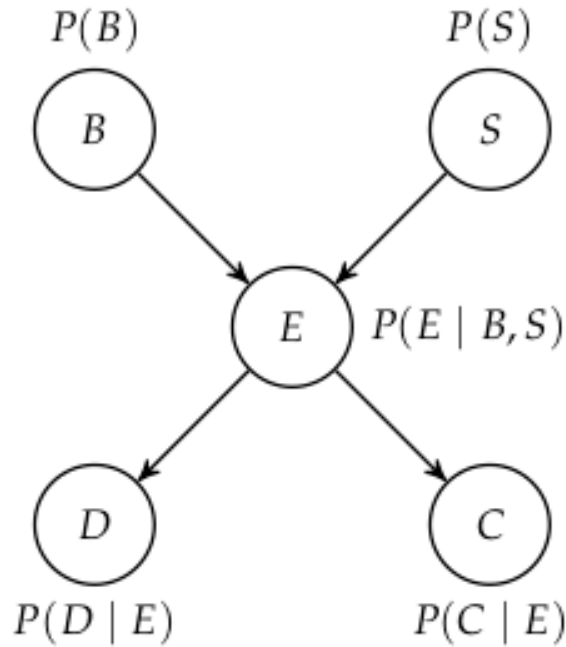
$$D \perp C \mid B ?$$



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Exercise



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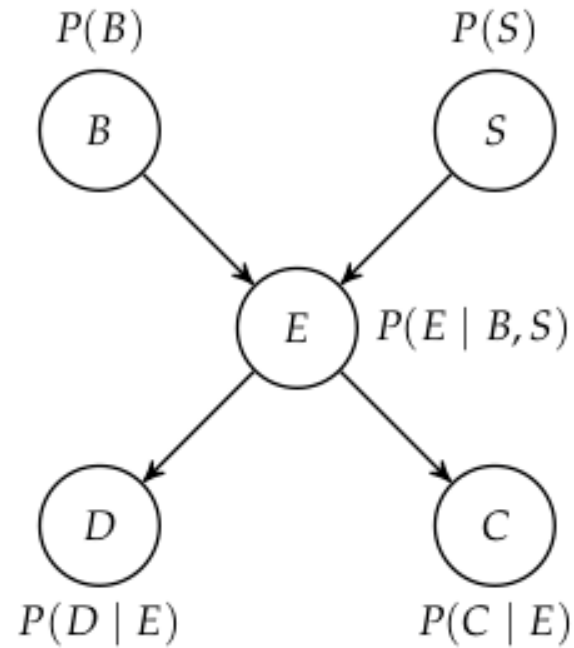
$$D \perp C \mid B ?$$

$$D \perp C \mid E ?$$

1. The path contains a *chain* $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
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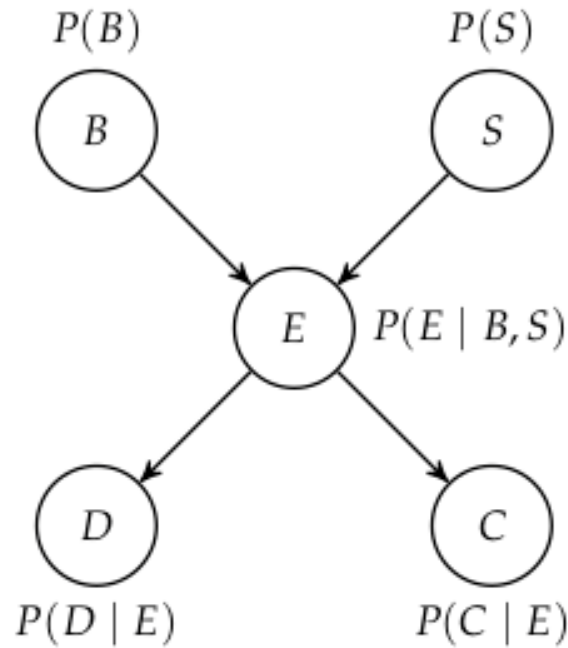
Approximate Inference

Approximate Inference: Direct Sampling



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 E electrical system failure
 D trajectory deviation
 C communication loss

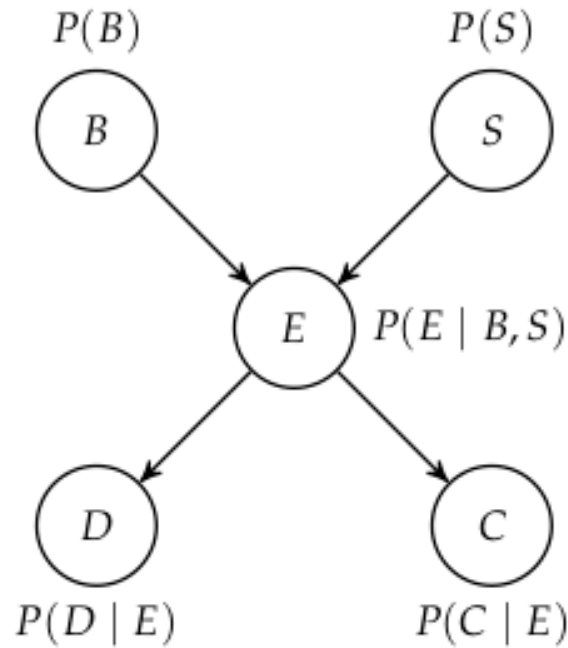
Approximate Inference: Direct Sampling



$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

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Approximate Inference: Direct Sampling

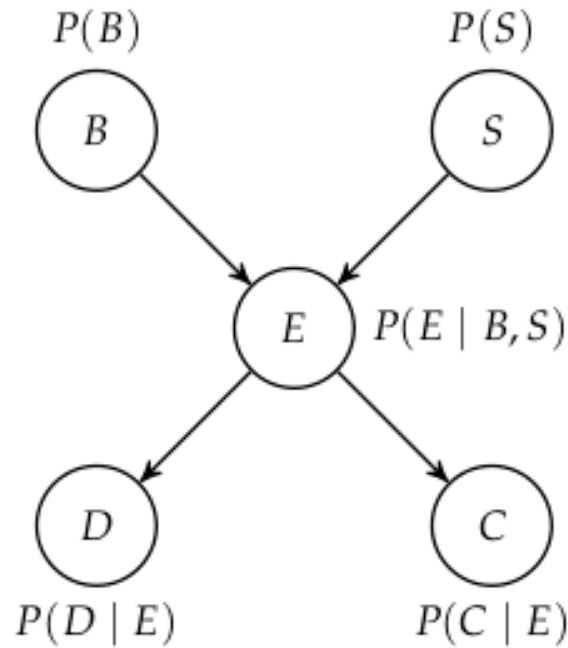


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B	S	E	D	C	
0	0	1	1	0	
0	0	0	0	0	
1	0	1	0	0	
1	0	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	
0	0	0	0	1	
0	1	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	

Approximate Inference: Direct Sampling



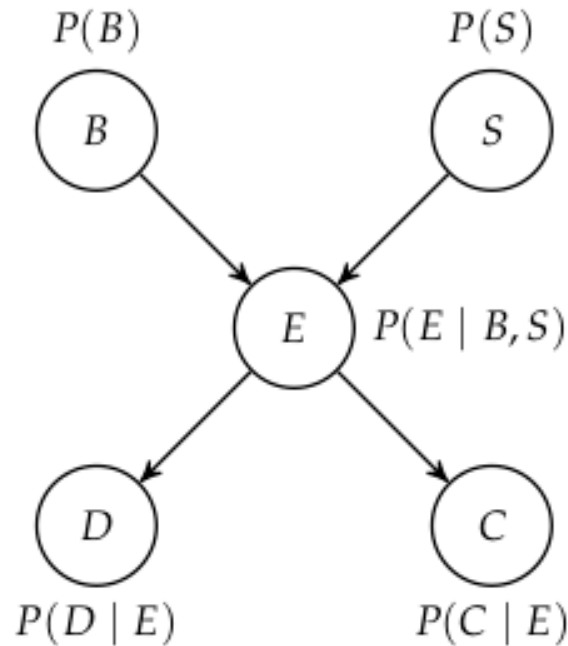
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$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

B	S	E	D	C	
0	0	1	1	0	
0	0	0	0	0	
1	0	1	0	0	
1	0	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	
0	0	0	0	1	
0	1	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	

Analogous to

Approximate Inference: Direct Sampling



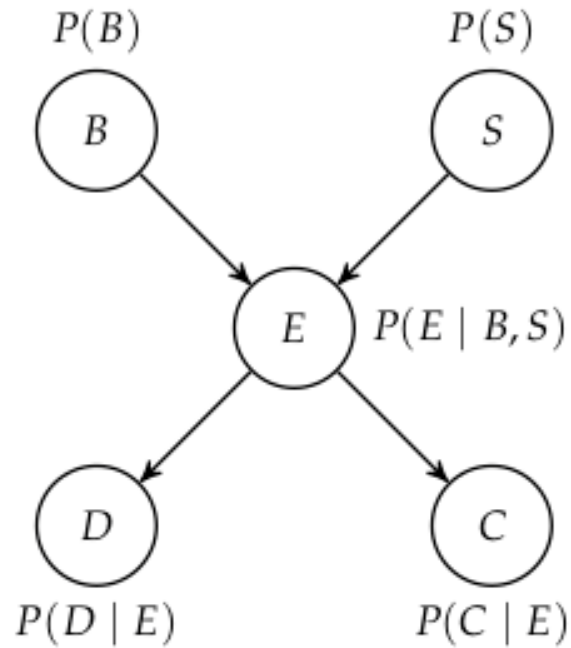
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B	S	E	D	C	
0	0	1	1	0	
0	0	0	0	0	
1	0	1	0	0	
1	0	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	
0	0	0	0	1	
0	1	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	

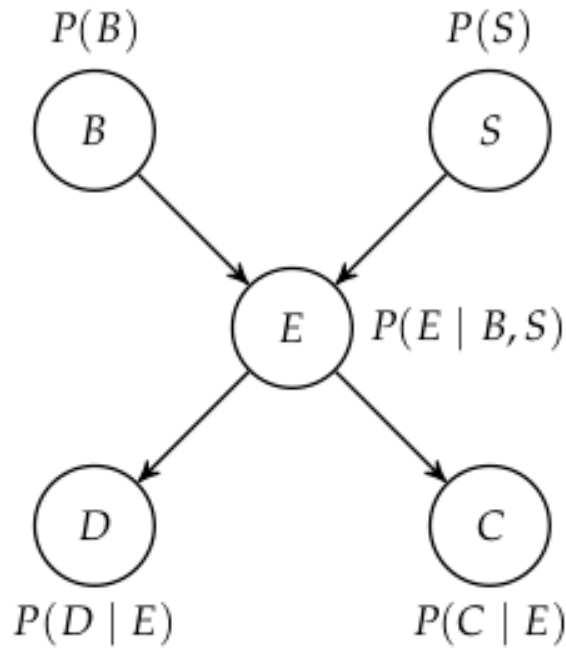
Analogous to **unweighted particle filtering**

Approximate Inference: Weighted Sampling



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 C communication loss

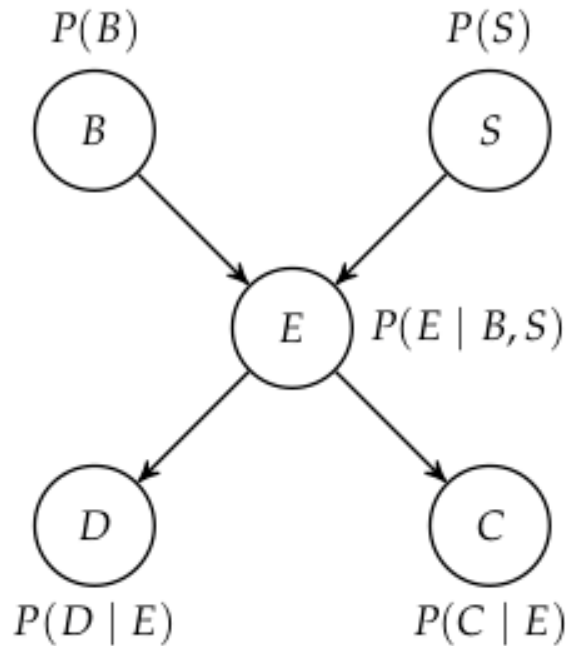
Approximate Inference: Weighted Sampling



$$\begin{aligned} P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\ &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i} \end{aligned}$$

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Approximate Inference: Weighted Sampling

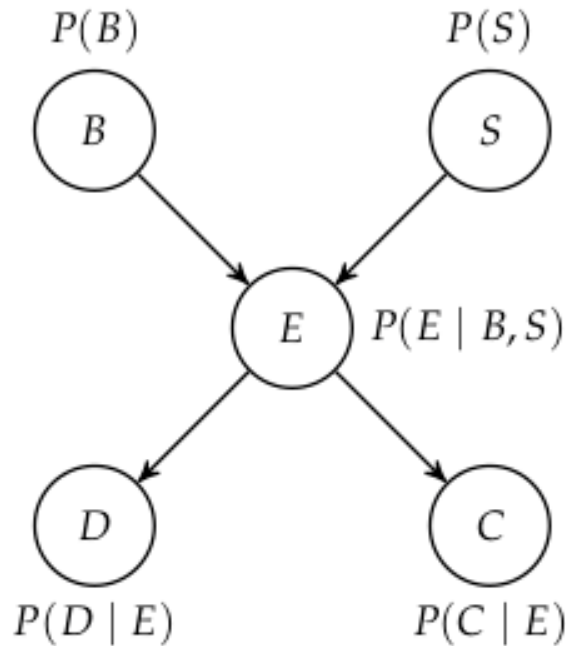


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$$\begin{aligned}
 P(b^1 \mid d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

<i>B</i>	<i>S</i>	<i>E</i>	<i>D</i>	<i>C</i>	Weight
1	0	1	1	1	$P(d^1 \mid e^1)P(c^1 \mid e^1)$
0	1	1	1	1	$P(d^1 \mid e^1)P(c^1 \mid e^1)$
0	0	0	1	1	$P(d^1 \mid e^0)P(c^1 \mid e^0)$
0	0	0	1	1	$P(d^1 \mid e^0)P(c^1 \mid e^0)$
0	0	1	1	1	$P(d^1 \mid e^1)P(c^1 \mid e^1)$

Approximate Inference: Weighted Sampling



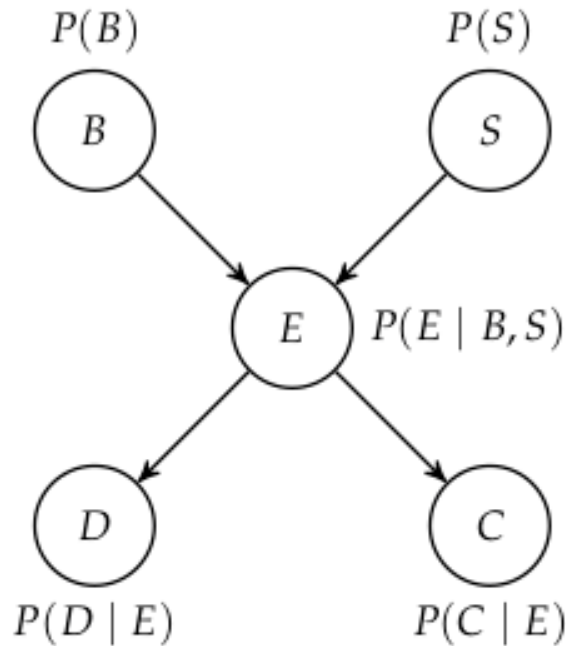
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$$\begin{aligned}
 P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

<i>B</i>	<i>S</i>	<i>E</i>	<i>D</i>	<i>C</i>	Weight
1	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	1	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$

Analogous to

Approximate Inference: Weighted Sampling



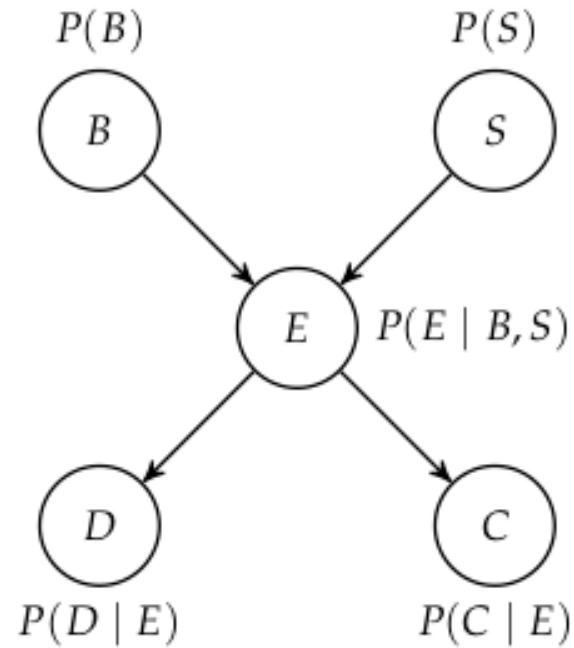
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0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
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Analogous to **weighted particle filtering**

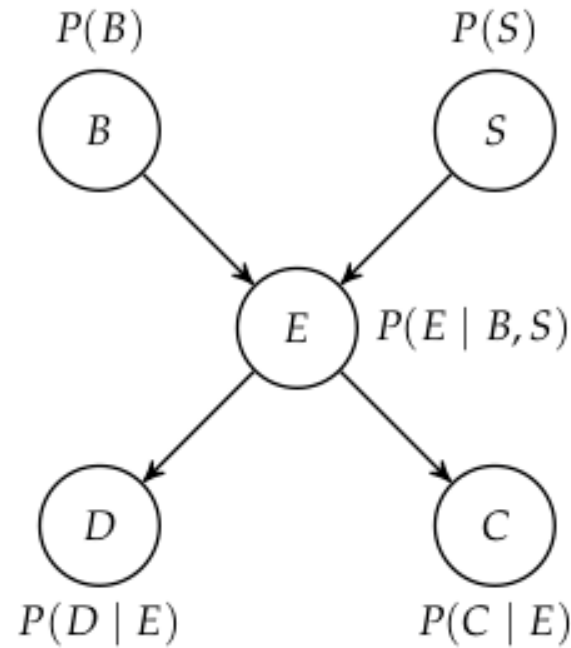
Approximate Inference: Gibbs Sampling



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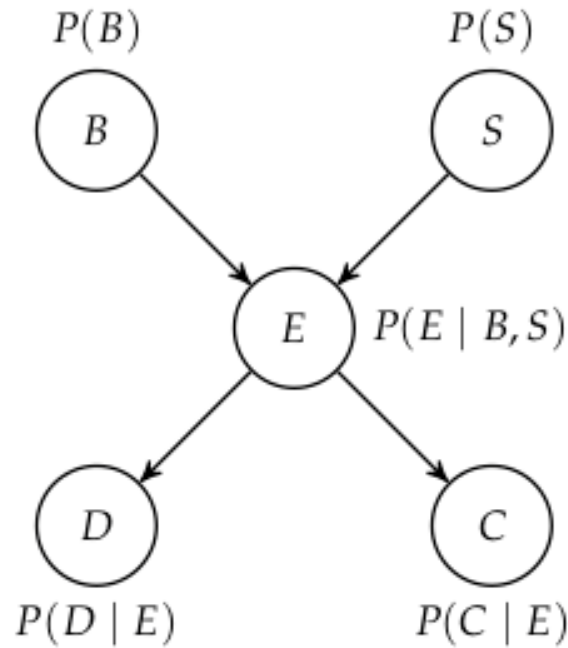
Approximate Inference: Gibbs Sampling

Markov Chain Monte Carlo (MCMC)



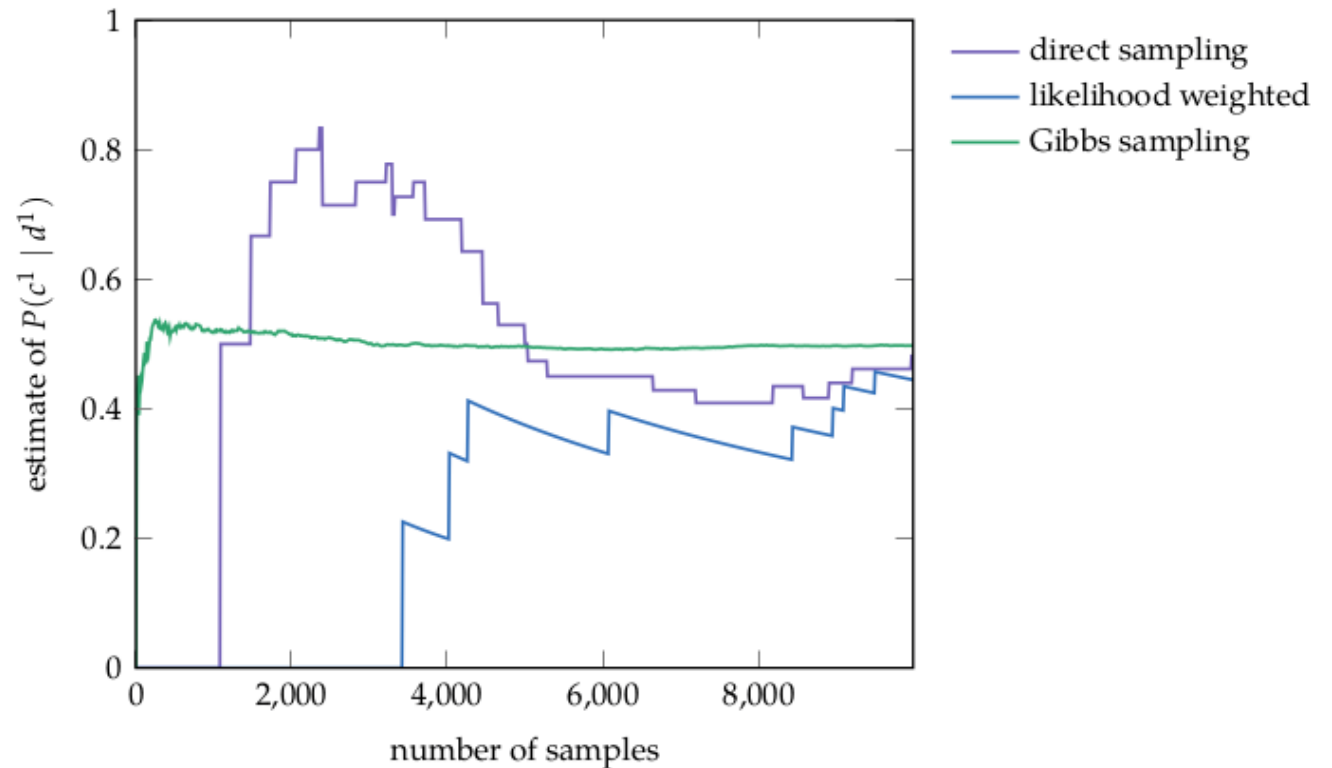
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Markov Chain Monte Carlo (MCMC)



Recap