

Causal Bayesian Networks

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Today:

- Causal Bayesian Networks
- How do we reason about independence in Bayesian Networks?

Review: Distributions of Discrete R.V.s

Joint

$$P(X = x, Y = y)$$

Single number

"Probability that
 $X = x \text{ and } Y = y$ "

Shorthand: $P(x, y)$

$$P(X, Y)$$

A table

"Joint distribution of
 $X \text{ and } Y$ "

Conditional

$$P(X = x | Y = y)$$

Single number

"Probability that
 $X = x \text{ if } Y = y$ "

Shorthand: $P(x | y)$

$$P(X | Y)$$

A collection of tables
for each y

"Conditional distribution
of X given Y "

Marginal

$$P(X = x)$$

Single number

"Probability that
 $X = x$ "

Shorthand: $P(x)$

$$P(X)$$

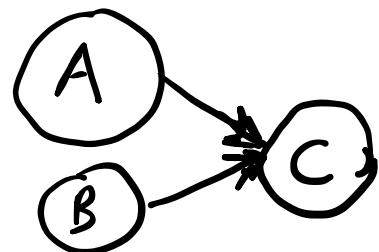
A table

"Marginal
distribution of X "

Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.
2. **Parameters:** Numerical values that determine a conditional distribution at each node



At each node, $P(X \mid pa(X))$

In a *Causal Bayesian Network*, arrows denote causation.



B is a result of A (and some aleatory uncertainty)

Chain rule for Bayesian Networks

$$P(X_{1:n}) = \prod_{i=1}^n P(X_i \mid \text{pa}(X_i))$$

Simple Causal Bayes Net Example

Naive Inference on Bayes Nets

Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$ C is a "hidden variable"

1. $P(A, B = b, C) = P(B = b \mid C) P(C \mid A) P(A).$
2. Marginalize over hidden and query variables to get

$$P(A = a, B = b) = \sum_c P(A = a, B = b, C = c)$$

and

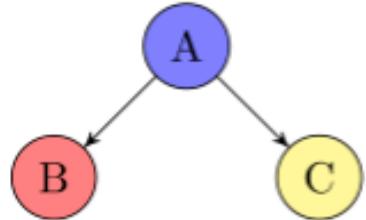
$$P(B = b) = \sum_{a,c} P(A = a, B = b, C = c)$$

$$3. P(A = a \mid B = b) = \frac{P(A=a, B=b)}{P(B=b)}$$

(Book introduces unnormalized "factors", but process is the same.)

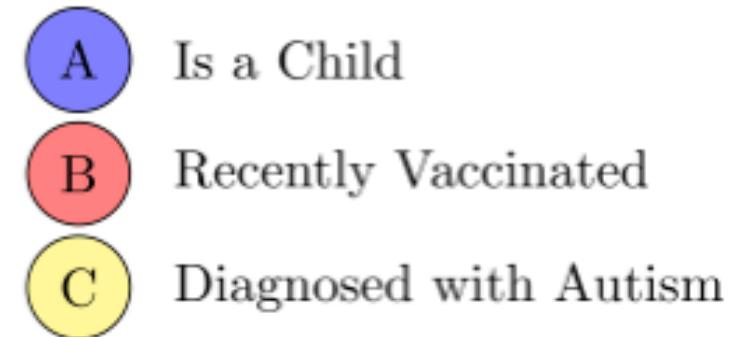
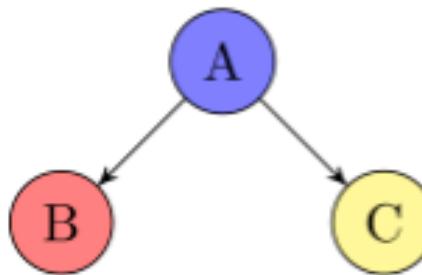
Conditional Independence in Bayes Nets

Conditional Independence: Fork

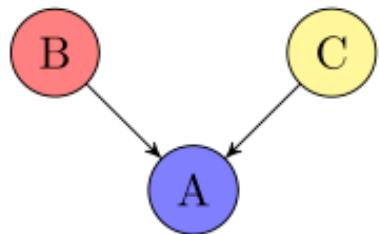


$B \perp C | A ?$

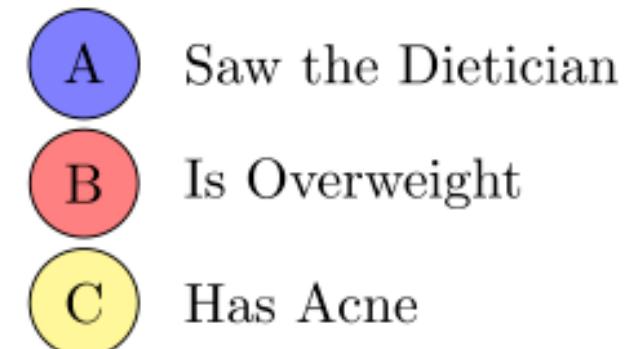
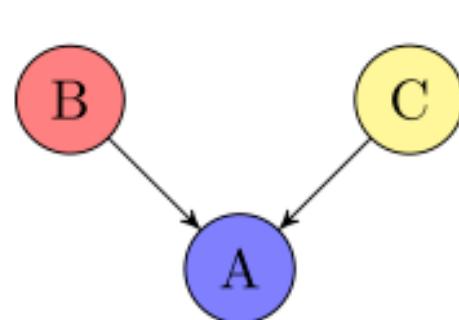
Yes



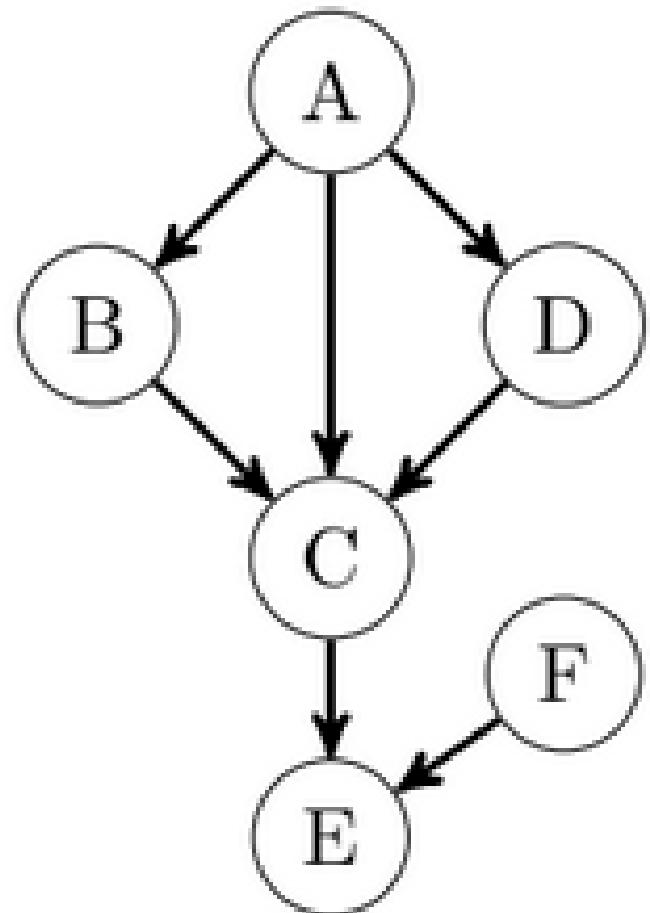
Conditional Independence: Inverted Fork



$B \perp C \mid A ?$



More Complex Example



$(B \perp D \mid A)$?

Yes!

$(B \perp D \mid E)$?

Inconclusive

Why is this relevant to decision making?

d-Separation

Let \mathcal{C} be a set of random variables.

An undirected *path* between A and B is *d-separated* by \mathcal{C} if any of the following exist along the path:

Separators (a.k.a "inactive triples"):

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
 2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
 3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .
- Also:
- d-separated = "inactive"
 - not d-separated = "active"

Break

$B \leftarrow A \rightarrow C \leftarrow D$

$B \leftarrow C \rightarrow A \leftarrow D$

Are these paths d-separated by $\mathcal{C} = \{C\}$?

d-Separation for Bayes Nets

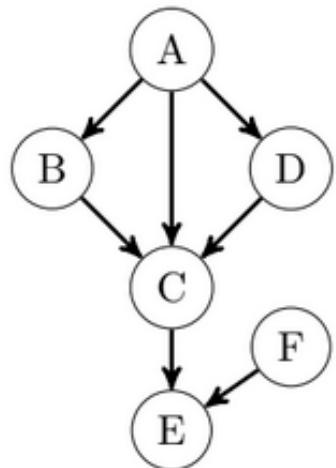
We say that A and B are *d-separated* by \mathcal{C} if all acyclic paths between A and B are d-separated by \mathcal{C} .

If A and B are d-separated by \mathcal{C} then $A \perp B | \mathcal{C}$

In other words, if there is any active path w.r.t. \mathcal{C} between A and B , we *cannot* conclude that $A \perp B | \mathcal{C}$ based on the structure alone.

Proving Conditional Independence

1. Enumerate all (non-cyclic) paths between nodes in question
2. Check all paths for d-separation
3. If all paths d-separated, then CE



Example: $(B \perp D \mid C, E)$?

Separators

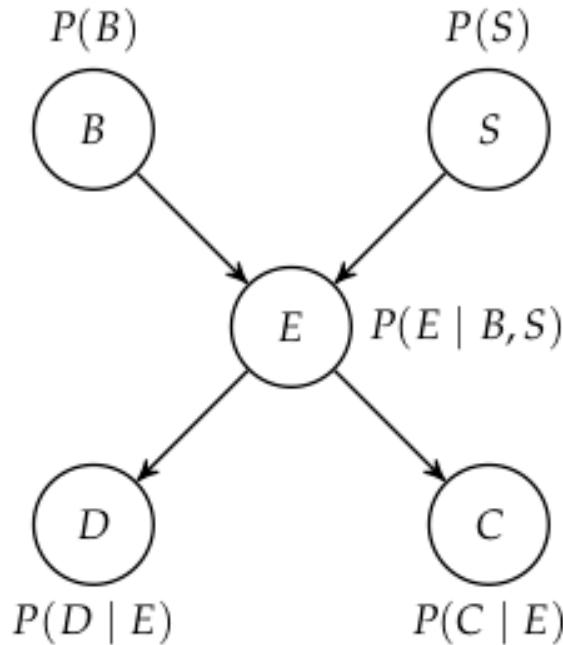
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Markov Blanket

The *Markov Blanket* of \mathcal{X} is the minimal set of nodes that, if their values were known, would make \mathcal{X} conditionally independent of all other nodes.

A Markov blanket of a particular node consists of its parents, its children, and the other parents of its children.

If \mathcal{B} is the Markov blanket of \mathcal{X} , you can treat analyze $\mathcal{B} \cup \mathcal{X}$ alone, and ignore any other nodes.



B battery failure

S solar panel failure

E electrical system failure

D trajectory deviation

C communication loss

Exercise

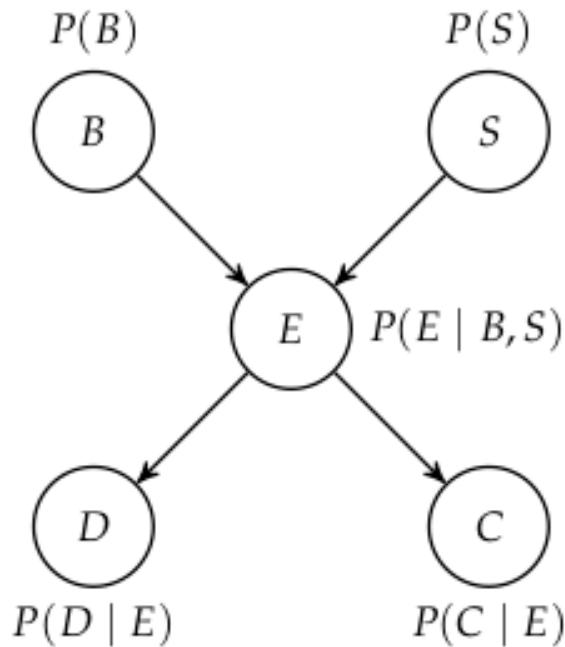
$$D \perp C \mid B ?$$

$$D \perp C \mid E ?$$

1. The path contains a *chain* $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. The path contains a *fork* $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. The path contains an *inverted fork* (v-structure) $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Approximate Inference

Approximate Inference: Direct Sampling



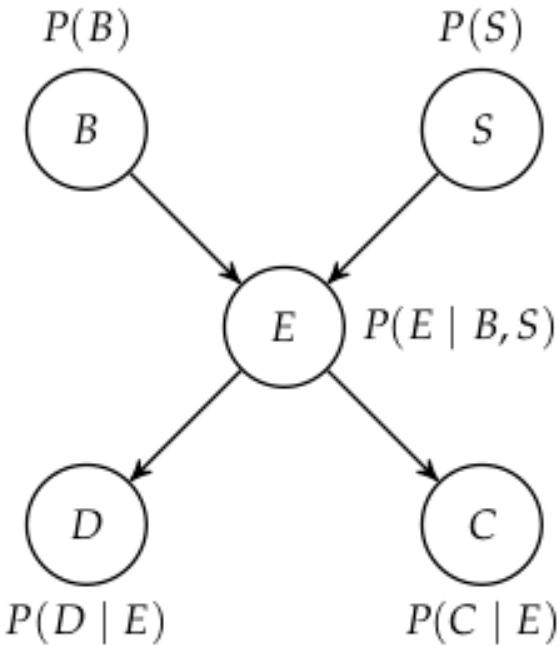
B battery failure
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$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

B	S	E	D	C
0	0	1	1	0
0	0	0	0	0
1	0	1	0	0
1	0	1	1	1
0	0	0	0	0
0	0	0	1	0
0	0	0	0	1
0	1	1	1	1
0	0	0	0	0
0	0	0	1	0

Analogous to **unweighted particle filtering**

Approximate Inference: Weighted Sampling



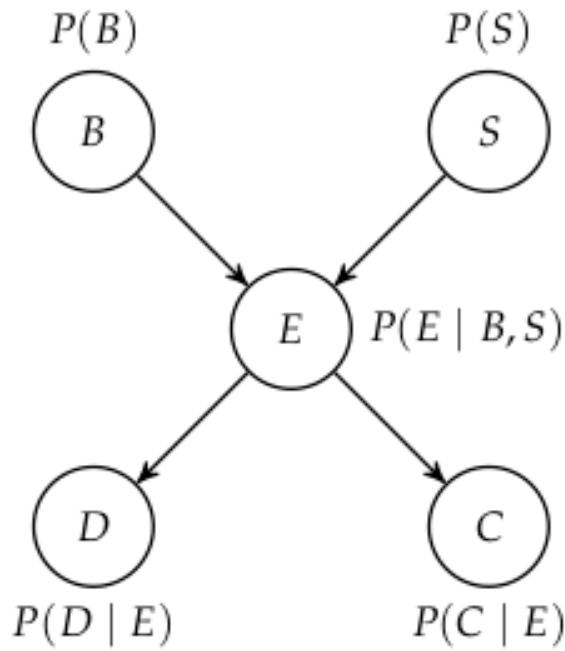
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$$\begin{aligned}
 P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

B	S	E	D	C	Weight
1	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	1	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$

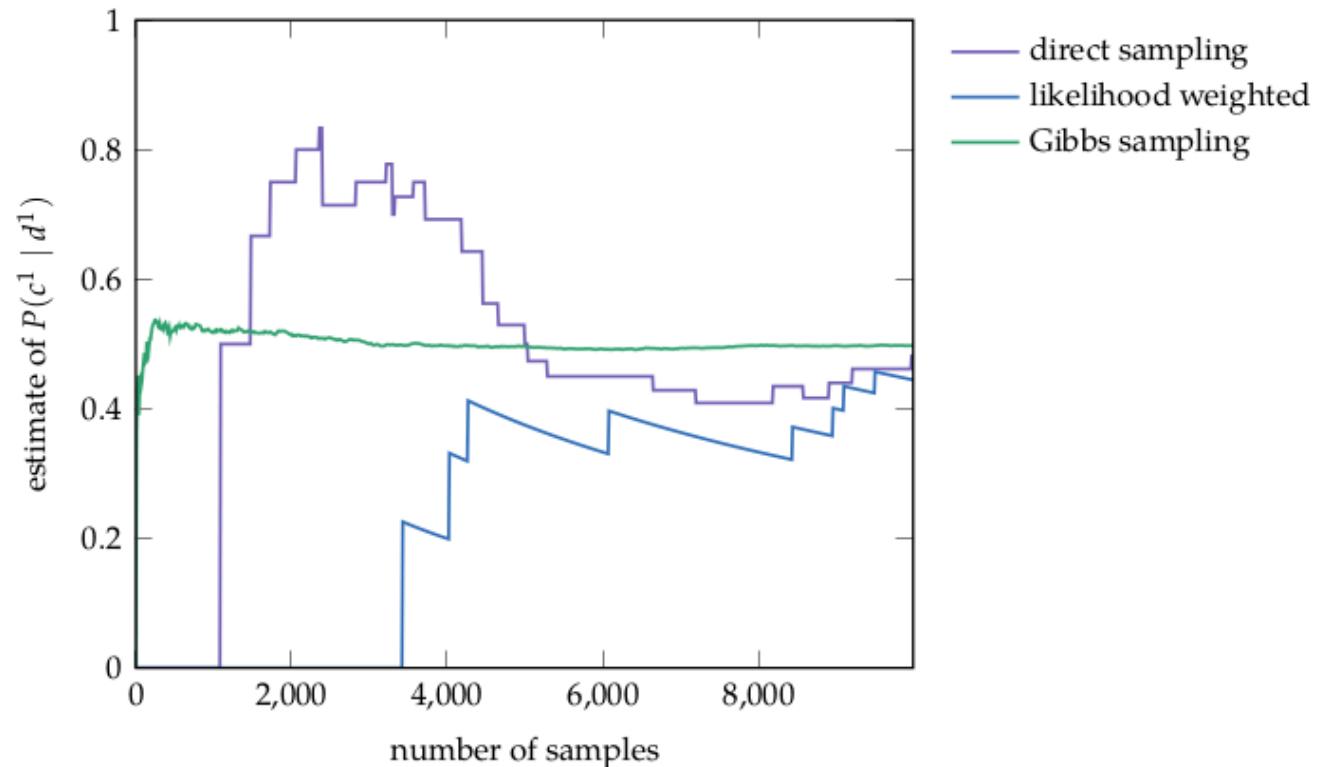
Analogous to **weighted particle filtering**

Approximate Inference: Gibbs Sampling



B battery failure
 S solar panel failure
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Markov Chain Monte Carlo (MCMC)



Recap