

Causal Bayesian Networks

Causal Bayesian Networks

Today:

- Causal Bayesian Networks
- How do we reason about independence in Bayesian Networks?

Review: Distributions of Discrete R.V.s

Review: Distributions of Discrete R.V.s

Joint

$$P(X = x, Y = y)$$

Shorthand: $P(x, y)$

Single number

"Probability that
 $X = x$ and $Y = y$ "

$$P(X, Y)$$

A table

"Joint distribution of
 X and Y "

Review: Distributions of Discrete R.V.s

Joint

$$P(X = x, Y = y)$$

Shorthand: $P(x, y)$

Single number

"Probability that
 $X = x \text{ and } Y = y$ "

$$P(X, Y)$$

A table

"Joint distribution of
 $X \text{ and } Y$ "

Conditional

$$P(X = x | Y = y)$$

Shorthand: $P(x | y)$

Single number

"Probability that
 $X = x \text{ if } Y = y$ "

$$P(X | Y)$$

A collection of tables
for each y

"Conditional distribution
of X given Y "

Review: Distributions of Discrete R.V.s

Joint

$$P(X = x, Y = y)$$

Shorthand: $P(x, y)$

Single number

"Probability that
 $X = x \text{ and } Y = y$ "

$$P(X, Y)$$

A table

"Joint distribution of
 $X \text{ and } Y$ "

Conditional

$$P(X = x | Y = y)$$

Shorthand: $P(x | y)$

Single number

"Probability that
 $X = x \text{ if } Y = y$ "

$$P(X | Y)$$

A collection of tables
for each y

"Conditional distribution
of X given Y "

Marginal

$$P(X = x)$$

Shorthand: $P(x)$

Single number

"Probability that
 $X = x$ "

$$P(X)$$

A table

"Marginal
distribution of X "

Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.

Causal Bayesian Networks

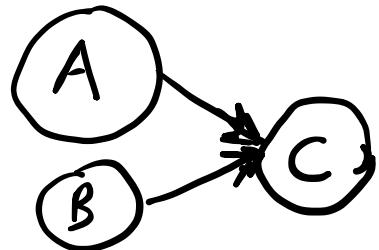
A *Bayesian Network* compactly represents a joint probability distributions using two components:

1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.
2. **Parameters:** Numerical values that determine a conditional distribution at each node

Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

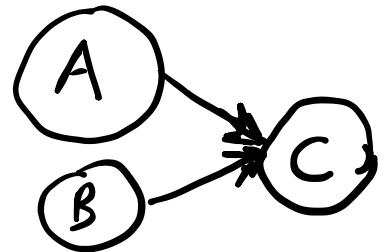
1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.
2. **Parameters:** Numerical values that determine a conditional distribution at each node



Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.
2. **Parameters:** Numerical values that determine a conditional distribution at each node

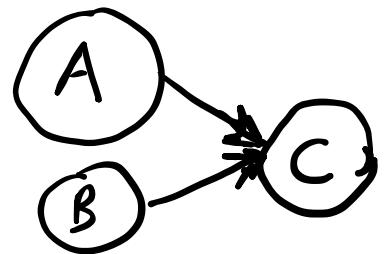


At each node, $P(X \mid pa(X))$

Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.
2. **Parameters:** Numerical values that determine a conditional distribution at each node



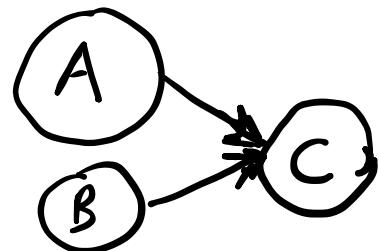
At each node, $P(X \mid pa(X))$

In a *Causal Bayesian Network*, arrows denote causation.

Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.
2. **Parameters:** Numerical values that determine a conditional distribution at each node



At each node, $P(X \mid pa(X))$

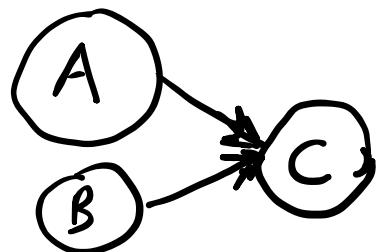
In a *Causal Bayesian Network*, arrows denote causation.



Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.
2. **Parameters:** Numerical values that determine a conditional distribution at each node



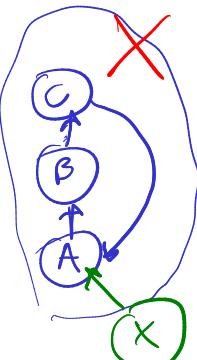
At each node, $P(X | pa(X))$
 $P(C | A, B)$
 $P(A)$
 $P(B)$

In a *Causal Bayesian Network*, arrows denote causation.



B is a result of A (and some aleatory uncertainty)
 $\rightarrow P(B | A) \leftarrow$ "dynamics of system"
 $P(A)$

$$P(x_{k+1} | x_k, u_k)$$
$$x_{k+1} = f(x_k, u_k, w_k)$$



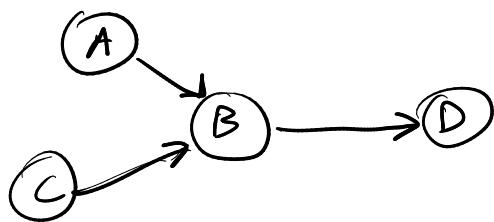
Chain rule for Bayesian Networks

Chain rule for Bayesian Networks

$$P(x_1, x_2 \dots x_n)$$

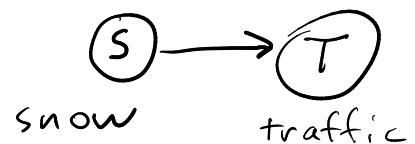
Joint

$$P(X_{1:n}) = \prod_{i=1}^n P(X_i | \text{pa}(X_i))$$



$$P(A, B, C, D) = \underbrace{P(A) P(B | A, C) P(C) P(D | B)}$$

Simple Causal Bayes Net Example



$$\begin{aligned} P(S=1) &= 0.1 \\ P(T=1 | S=0) &= 0.2 \\ P(T=1 | S=1) &= 0.7 \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} 3 \text{ parameters}$$

observe snow, traffic? $\Rightarrow P(T=1 | S=1) = 0.7$
 $S=1 \quad P(T=1 | S=1)$

$$\begin{aligned} \text{observe traffic, snow?} \quad T=1 \quad P(S=1 | T=1) &= \frac{P(S=1 | T=1)}{P(T=1)} = \frac{P(T=1 | S=1) P(S=1)}{\sum_s P(T=1 | S=s) P(S=s)} \\ &= \frac{0.07}{0.2 \cdot 0.9 + 0.7 \cdot 0.1} \\ &= 0.28 \end{aligned}$$

"Information can flow up or down edges"

Naive Inference on Bayes Nets

(Book introduces unnormalized "factors", but process is the same.)

Naive Inference on Bayes Nets

Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

Naive Inference on Bayes Nets

Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$

(Book introduces unnormalized "factors", but process is the same.)

Naive Inference on Bayes Nets

Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$

C is a "hidden variable"

Naive Inference on Bayes Nets

Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$ C is a "hidden variable"

1. $P(A, B = b, C) = P(B = b \mid C) P(C \mid A) P(A).$

(Book introduces unnormalized "factors", but process is the same.)

Naive Inference on Bayes Nets

Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$

C is a "hidden variable"

1. $P(A, B = b, C) = P(B = b \mid C) P(C \mid A) P(A).$
2. Marginalize over hidden and query variables to get

$$P(A = a, B = b) = \sum_c P(A = a, B = b, C = c)$$

and

$$P(B = b) = \sum_{a,c} P(A = a, B = b, C = c)$$

(Book introduces unnormalized "factors", but process is the same.)

Naive Inference on Bayes Nets

Bayes Net with 3 Random Variables: $A \rightarrow C \rightarrow B$

Want to find $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$

C is a "hidden variable"

1. $P(A, B = b, C) = P(B = b \mid C) P(C \mid A) P(A).$ ← Chain Rule
2. Marginalize over hidden and query variables to get

$$P(A = a, B = b) = \sum_c P(A = a, B = b, C = c)$$

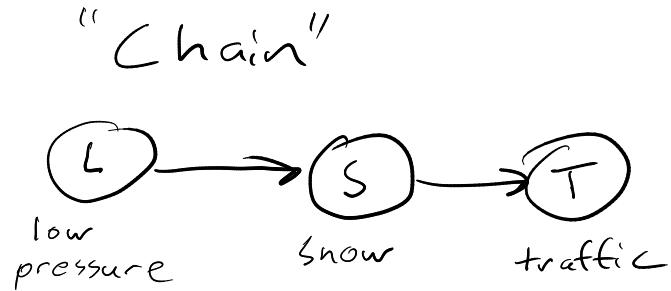
and

$$P(B = b) = \sum_{a,c} P(A = a, B = b, C = c)$$

$$3. P(A = a \mid B = b) = \frac{P(A=a, B=b)}{P(B=b)}$$

(Book introduces unnormalized "factors", but process is the same.)

Conditional Independence in Bayes Nets



$T \perp\!\!\!\perp L | S ?$

Yes

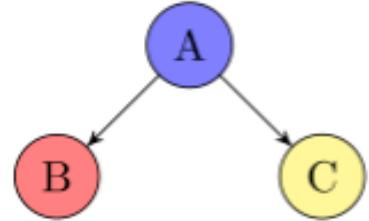
Definition of cond. indep.

$$P(T, L | S) = P(T | S) P(L | S)$$
$$P(T | S) = P(T | S, L)$$

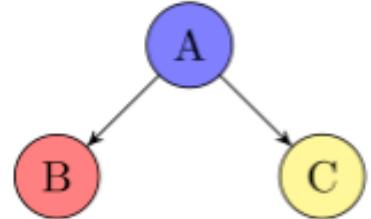
$$\begin{aligned} P(T | S) &\stackrel{?}{=} P(T | S, L) \\ &= \frac{P(T, S, L)}{P(S, L)} \\ &= \frac{P(T | S) P(S | L) P(L)}{\sum_{\neg L} P(T | S) P(S | L) P(\neg L)} \\ &= P(T | S) \end{aligned}$$

Conditional Independence: Fork

Conditional Independence: Fork

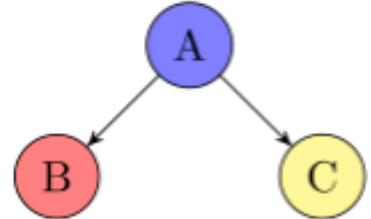


Conditional Independence: Fork



$B \perp C \mid A ?$

Conditional Independence: Fork

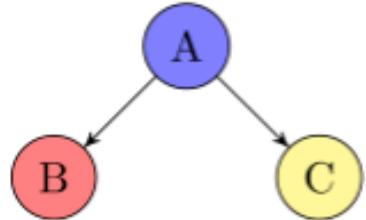


$$B \perp C \mid A ?$$

Yes

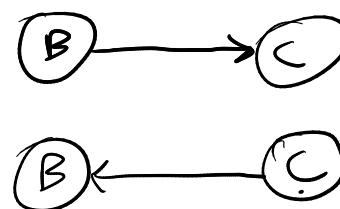
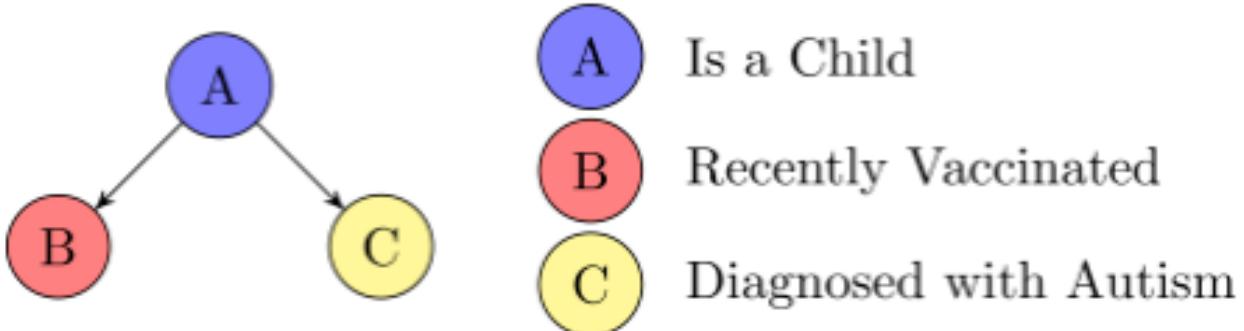


Conditional Independence: Fork



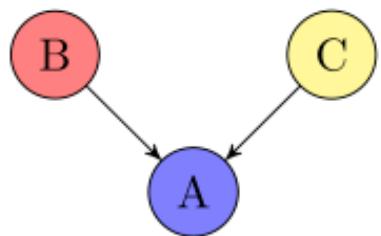
$B \perp C | A ?$

Yes

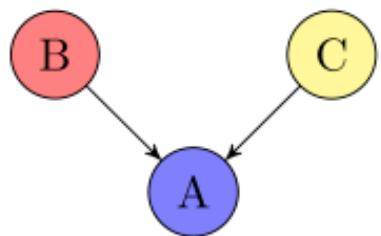


Conditional Independence: Inverted Fork

Conditional Independence: Inverted Fork



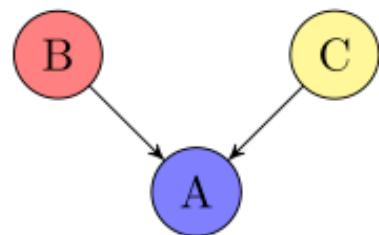
Conditional Independence: Inverted Fork



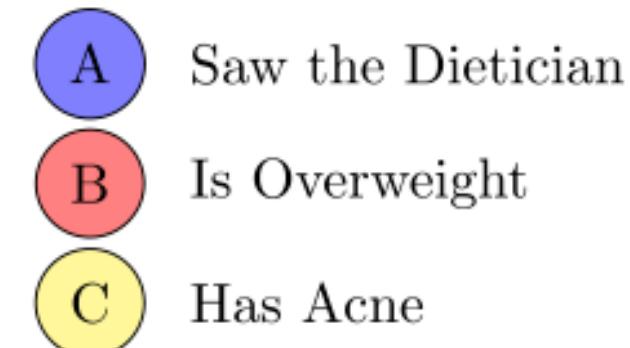
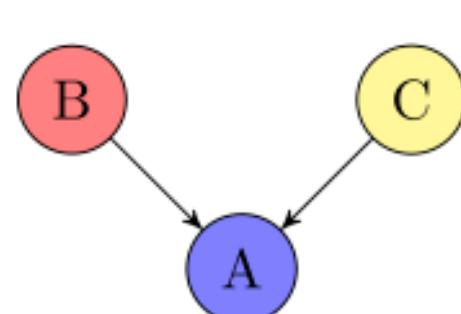
$$B \perp C \mid A ?$$

Inconclusive
based on structure

Conditional Independence: Inverted Fork

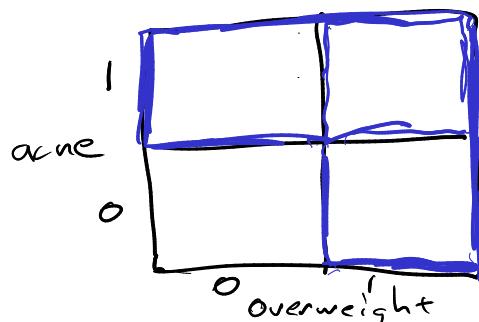


$B \perp C \mid A ?$



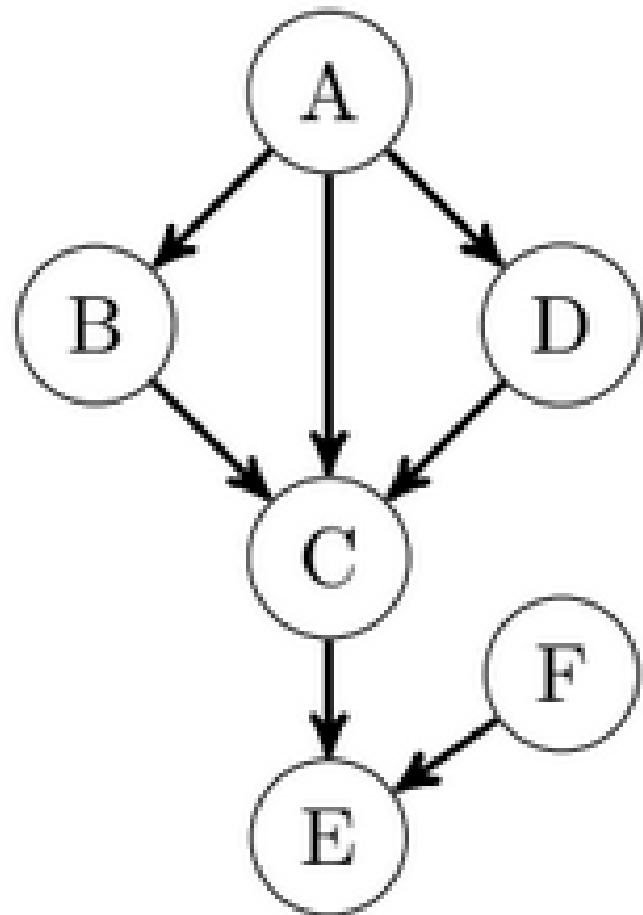
Assume $B \perp C$

Does not imply that $B \perp C \mid A$



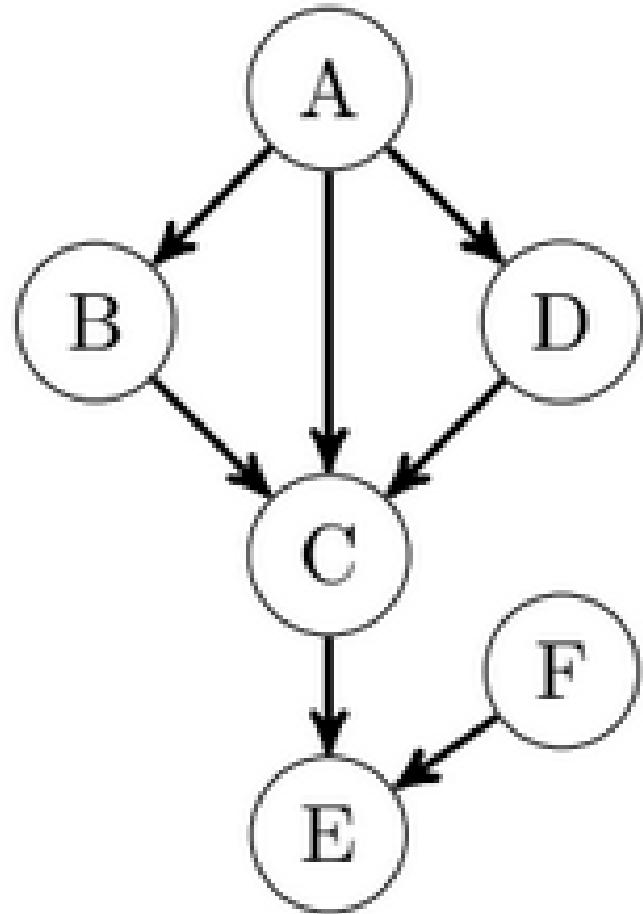
More Complex Example

More Complex Example



More Complex Example

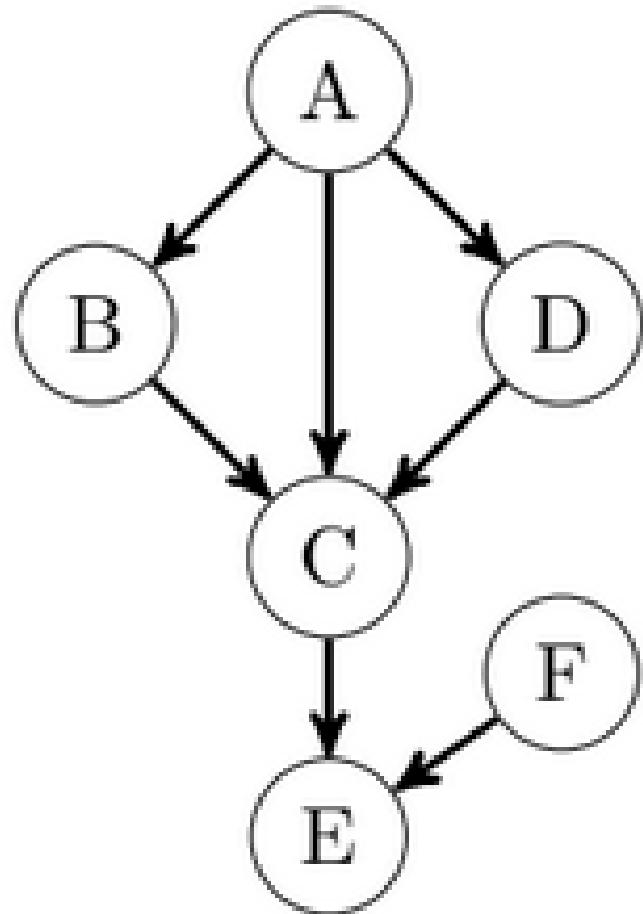
$(B \perp D \mid A) ?$



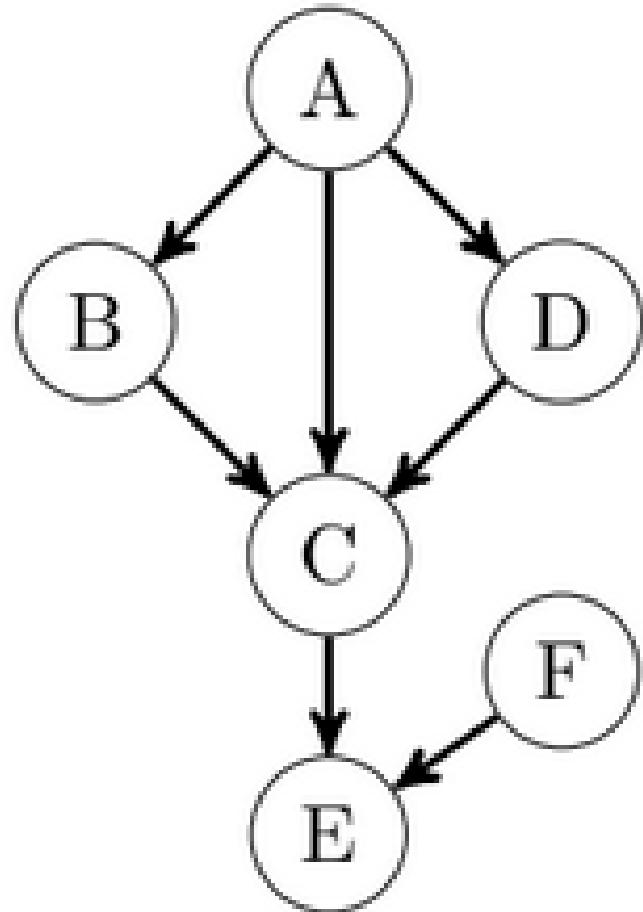
More Complex Example

$(B \perp D \mid A) ?$

Yes!



More Complex Example

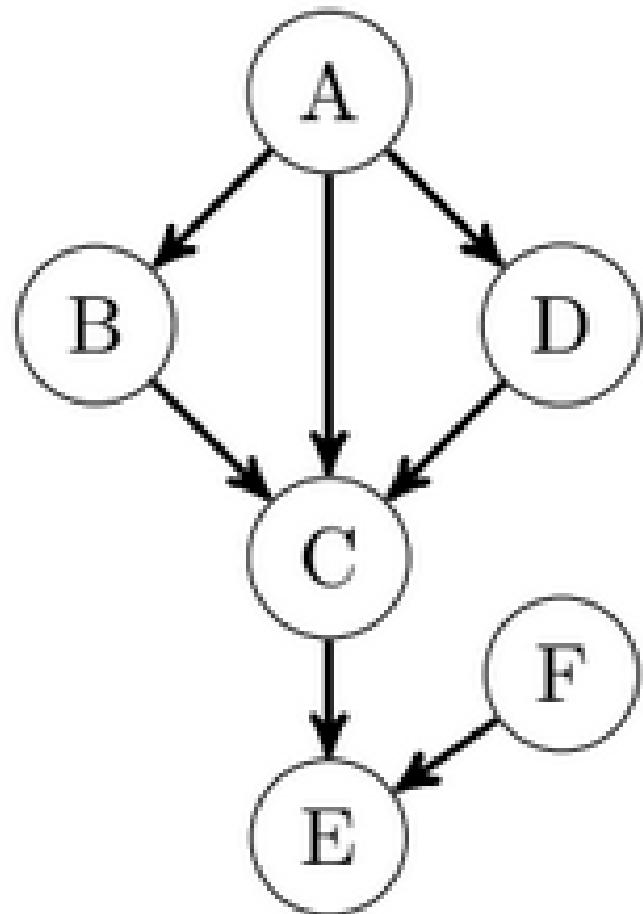


$(B \perp D \mid A) ?$

Yes!

$(B \perp D \mid E) ?$

More Complex Example



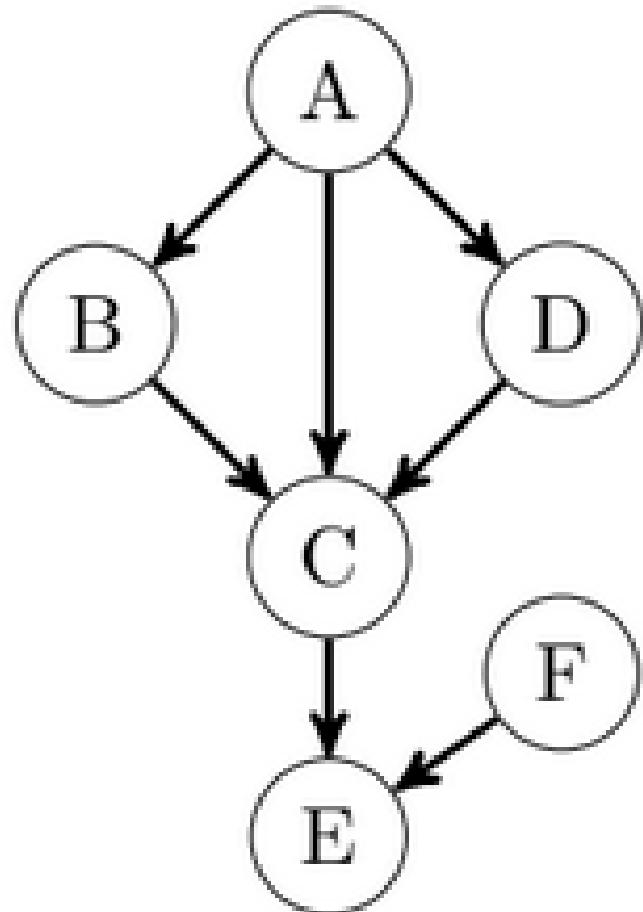
$(B \perp D \mid A) ?$

Yes!

$(B \perp D \mid E) ?$

Inconclusive

More Complex Example



$(B \perp D \mid A)$?

Yes!

$(B \perp D \mid E)$?

Inconclusive

Why is this relevant to decision making?

d-Separation

d-Separation

Let \mathcal{C} be a set of random variables.

d-Separation

Let \mathcal{C} be a set of random variables.

An undirected *path* between A and B is *d-separated* by \mathcal{C} if any of the following exist along the path:

d-Separation

Let \mathcal{C} be a set of random variables.

An undirected *path* between A and B is *d-separated* by \mathcal{C} if any of the following exist along the path:

Also:

- d-separated = "inactive"
- not d-separated = "active"

d-Separation

Let \mathcal{C} be a set of random variables.

An undirected *path* between A and B is *d-separated* by \mathcal{C} if any of the following exist along the path:

Separators (a.k.a "inactive triples"):

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Also:

- d-separated = "inactive"
- not d-separated = "active"

d-Separation

Let \mathcal{C} be a set of random variables.

An undirected *path* between A and B is *d-separated* by \mathcal{C} if any of the following exist along the path:

Separators (a.k.a "inactive triples"):

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Also:

- d-separated = "inactive"
- not d-separated = "active"

Break

d-Separation

Let \mathcal{C} be a set of random variables.

An undirected *path* between A and B is *d-separated* by \mathcal{C} if any of the following exist along the path:

Separators (a.k.a "inactive triples"):

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Also:

- d-separated = "inactive"
- not d-separated = "active"

Break

$B \leftarrow A \rightarrow C \leftarrow D$

d-Separation

Let \mathcal{C} be a set of random variables.

An undirected *path* between A and B is *d-separated* by \mathcal{C} if any of the following exist along the path:

Separators (a.k.a "inactive triples"):

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Also:

- d-separated = "inactive"
- not d-separated = "active"

Break

$$B \leftarrow A \rightarrow C \leftarrow D$$

$$B \leftarrow C \rightarrow A \leftarrow D$$

d-Separation

Let \mathcal{C} be a set of random variables.

An undirected *path* between A and B is *d-separated* by \mathcal{C} if any of the following exist along the path:

Separators (a.k.a "inactive triples"):

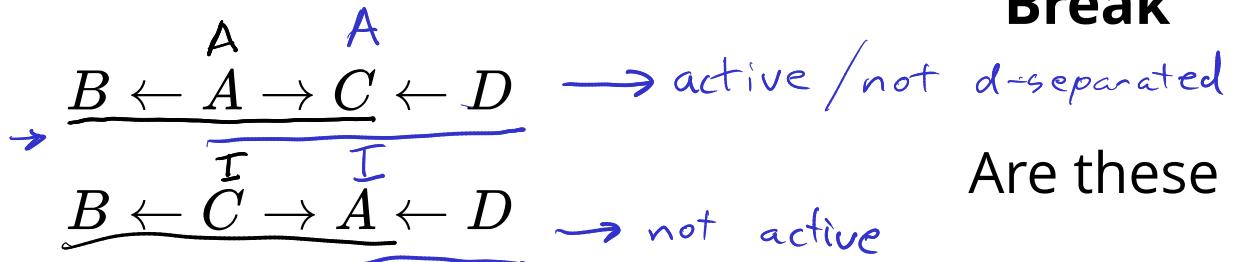
1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$

2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$

3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Also:

- d-separated = "inactive"
- not d-separated = "active"



Break

Are these paths d-separated by $\mathcal{C} = \{C\}$?

d-Separation for Bayes Nets

*short for "directionally separated"

d-Separation for Bayes Nets

We say that A and B are *d-separated* by \mathcal{C} if all acyclic paths between A and B are d-separated by \mathcal{C} .

*short for "directionally separated"

d-Separation for Bayes Nets

We say that A and B are *d-separated* by \mathcal{C} if all acyclic paths between A and B are d-separated by \mathcal{C} .

If A and B are d-separated by \mathcal{C} then $A \perp B \mid \mathcal{C}$

*short for "directionally separated"

d-Separation for Bayes Nets

We say that A and B are *d-separated* by \mathcal{C} if all ^{undirected} acyclic paths between A and B are d-separated by \mathcal{C} .

If A and B are d-separated by \mathcal{C} then $A \perp B | \mathcal{C}$

In other words, if there is any active path w.r.t. \mathcal{C} between A and B , we *cannot* conclude that $A \perp B | \mathcal{C}$ based on the structure alone.

Proving Conditional Independence

Separators

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Proving Conditional Independence

1. Enumerate all (non-cyclic) paths between nodes in question

Separators

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Proving Conditional Independence

1. Enumerate all (non-cyclic) paths between nodes in question
2. Check all paths for d-separation

Separators

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Proving Conditional Independence

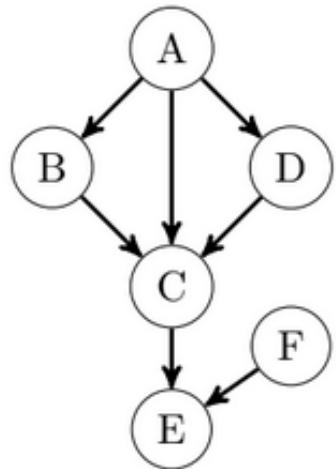
1. Enumerate all (non-cyclic) paths between nodes in question
2. Check all paths for d-separation
3. If all paths d-separated, then CE

Separators

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Proving Conditional Independence

1. Enumerate all (non-cyclic) paths between nodes in question
2. Check all paths for d-separation
3. If all paths d-separated, then CE

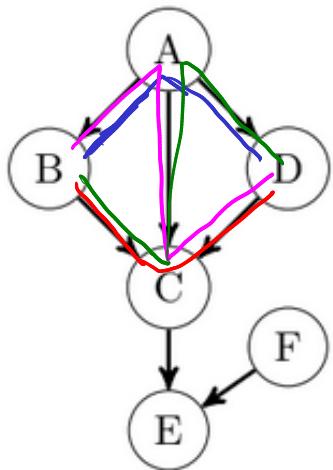


Separators

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Proving Conditional Independence

1. Enumerate all (non-cyclic) paths between nodes in question
2. Check all paths for d-separation
3. If all paths d-separated, then CE



Example: $(B \perp D \mid \{C, E\})$?

$B \leftarrow A \rightarrow D$ active \rightarrow inconclusive

$B \rightarrow C \leftarrow D$

$B \leftarrow A \rightarrow C \leftarrow D$

$B \rightarrow C \leftarrow A \rightarrow D$

Separators

1. **Chain:** $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. **Fork:** $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. **Inverted Fork (v-structure):** $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Markov Blanket

Markov Blanket

The *Markov Blanket* of \mathcal{X} is the minimal set of nodes that, if their values were known, would make \mathcal{X} conditionally independent of all other nodes.

Markov Blanket

The *Markov Blanket* of \mathcal{X} is the minimal set of nodes that, if their values were known, would make \mathcal{X} conditionally independent of all other nodes.

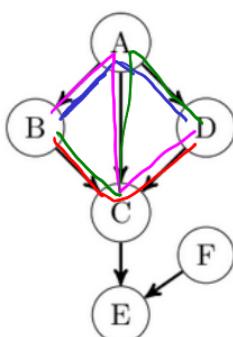
A Markov blanket of a particular node consists of its parents, its children, and the other parents of its children.

Markov Blanket

The *Markov Blanket* of \mathcal{X} is the minimal set of nodes that, if their values were known, would make \mathcal{X} conditionally independent of all other nodes.

A Markov blanket of a particular node consists of its parents, its children, and the other parents of its children.

If \mathcal{B} is the Markov blanket of \mathcal{X} , you can treat analyze $\mathcal{B} \cup \mathcal{X}$ alone, and ignore any other nodes.

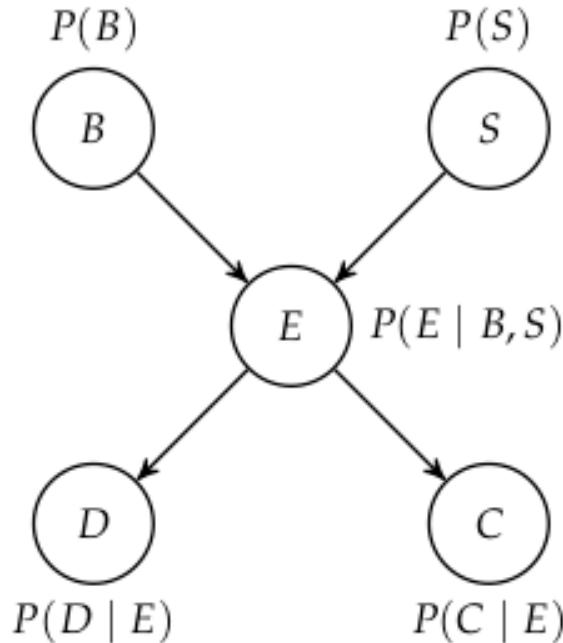


What is the Markov Blanket of $\{E, F\}$?
C ✓

Exercise

1. The path contains a *chain* $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. The path contains a *fork* $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. The path contains an *inverted fork* (v-structure) $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Exercise



B battery failure

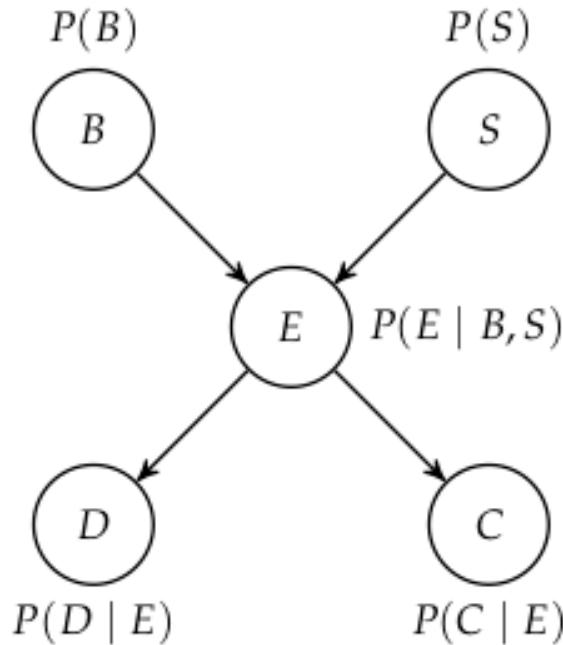
S solar panel failure

E electrical system failure

D trajectory deviation

C communication loss

1. The path contains a *chain* $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. The path contains a *fork* $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. The path contains an *inverted fork* (v-structure) $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .



B battery failure

S solar panel failure

E electrical system failure

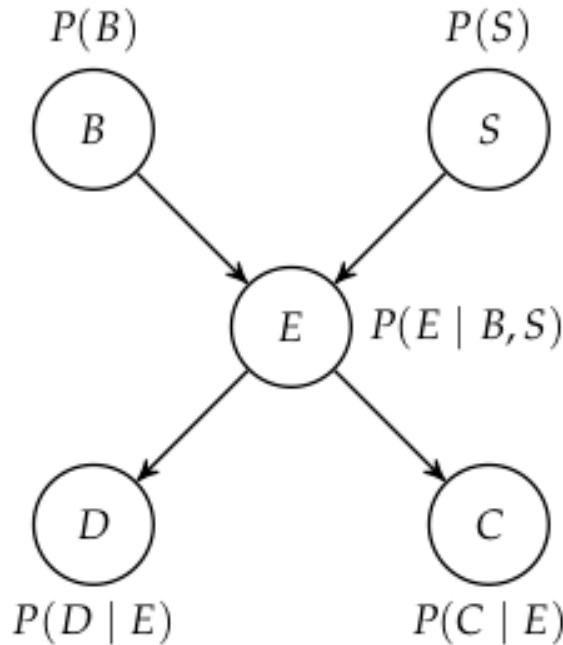
D trajectory deviation

C communication loss

Exercise

$$D \perp C \mid B ?$$

1. The path contains a *chain* $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. The path contains a *fork* $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. The path contains an *inverted fork* (v-structure) $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .



B battery failure

S solar panel failure

E electrical system failure

D trajectory deviation

C communication loss

Exercise

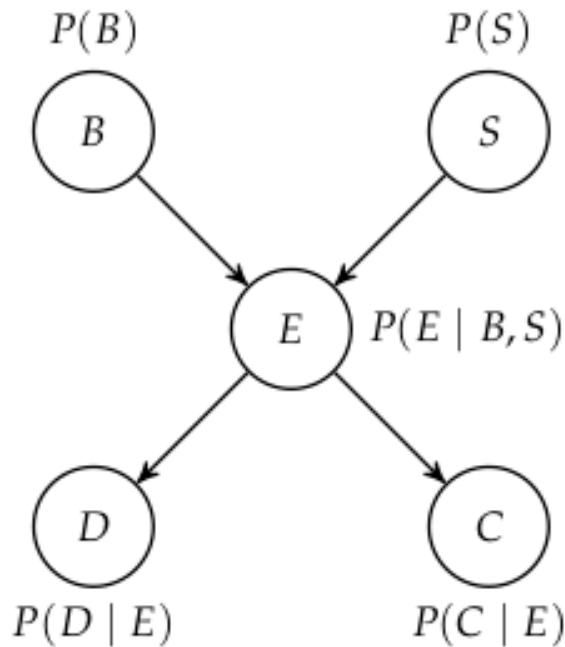
$$D \perp C \mid B ?$$

$$D \perp C \mid E ?$$

1. The path contains a *chain* $X \rightarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
2. The path contains a *fork* $X \leftarrow Y \rightarrow Z$ such that $Y \in \mathcal{C}$
3. The path contains an *inverted fork* (v-structure) $X \rightarrow Y \leftarrow Z$ such that $Y \notin \mathcal{C}$ and no descendant of Y is in \mathcal{C} .

Approximate Inference

Approximate Inference: Direct Sampling



B battery failure

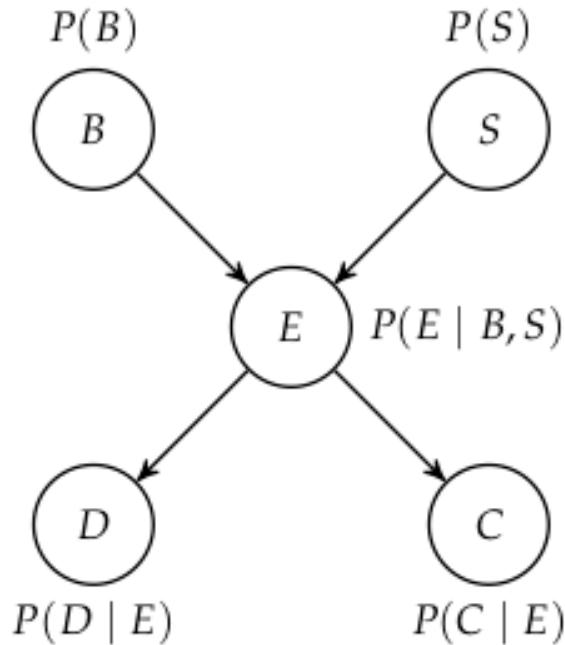
S solar panel failure

E electrical system failure

D trajectory deviation

C communication loss

Approximate Inference: Direct Sampling



$$P(b^1 \mid d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

B battery failure

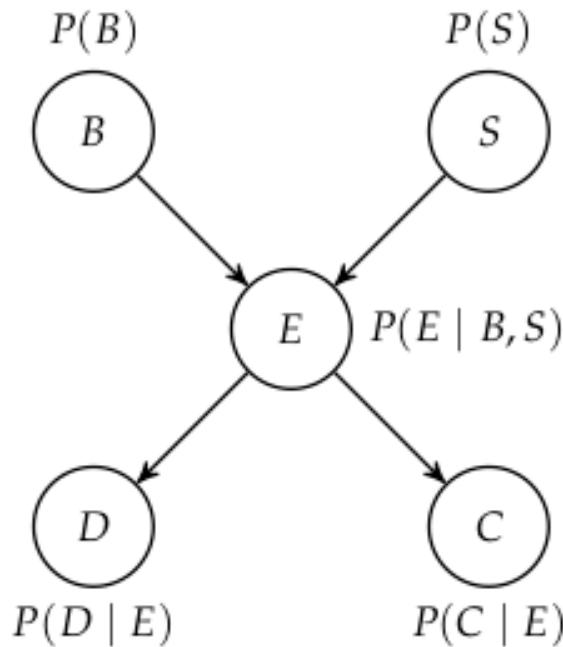
S solar panel failure

E electrical system failure

D trajectory deviation

C communication loss

Approximate Inference: Direct Sampling

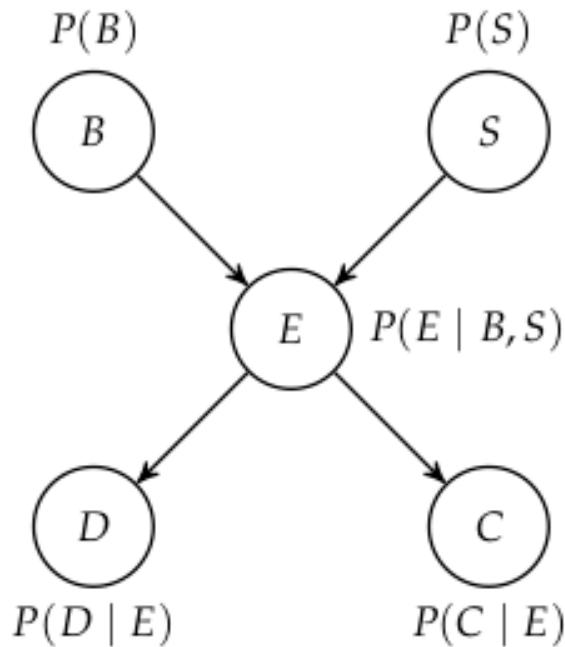


B battery failure
 S solar panel failure
 E electrical system failure
 D trajectory deviation
 C communication loss

$$P(b^1 \mid d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

B	S	E	D	C
0	0	1	1	0
0	0	0	0	0
1	0	1	0	0
1	0	1	1	1
0	0	0	0	0
0	0	0	1	0
0	0	0	0	1
0	1	1	1	1
0	0	0	0	0
0	0	0	1	0

Approximate Inference: Direct Sampling



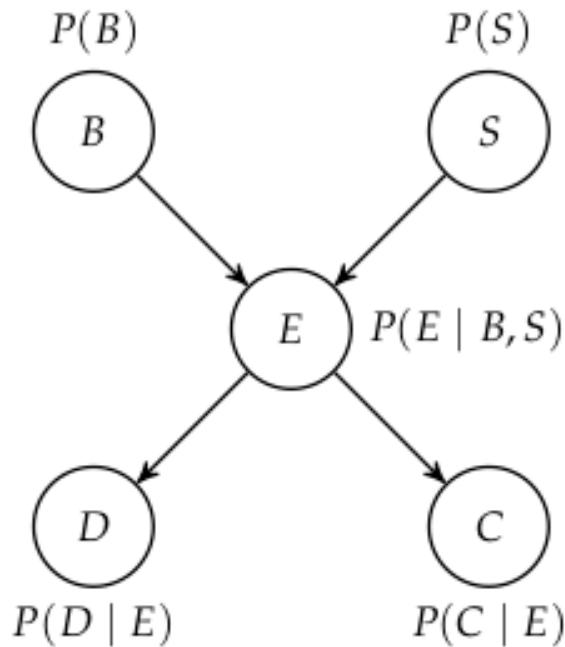
B battery failure
S solar panel failure
E electrical system failure
D trajectory deviation
C communication loss

$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

B	S	E	D	C
0	0	1	1	0
0	0	0	0	0
1	0	1	0	0
1	0	1	1	1
0	0	0	0	0
0	0	0	1	0
0	0	0	0	1
0	1	1	1	1
0	0	0	0	0
0	0	0	1	0

Analogous to

Approximate Inference: Direct Sampling



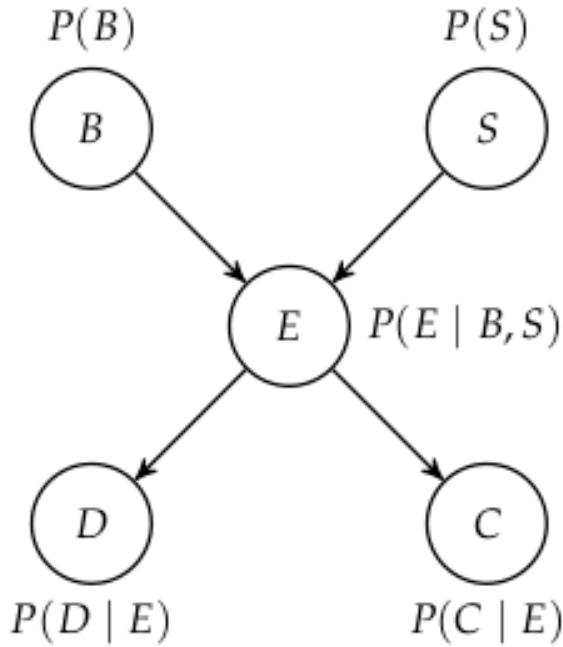
B battery failure
S solar panel failure
E electrical system failure
D trajectory deviation
C communication loss

$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

B	S	E	D	C
0	0	1	1	0
0	0	0	0	0
1	0	1	0	0
1	0	1	1	1
0	0	0	0	0
0	0	0	1	0
0	0	0	0	1
0	1	1	1	1
0	0	0	0	0
0	0	0	1	0

Analogous to **unweighted particle filtering**

Approximate Inference: Weighted Sampling



B battery failure

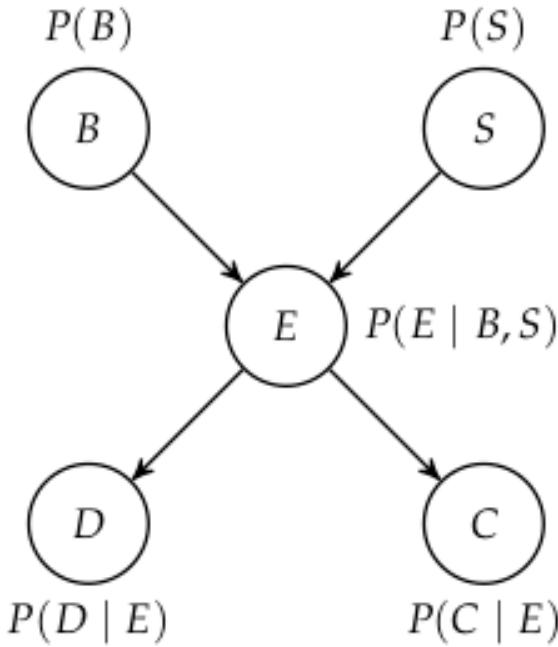
S solar panel failure

E electrical system failure

D trajectory deviation

C communication loss

Approximate Inference: Weighted Sampling



B battery failure

S solar panel failure

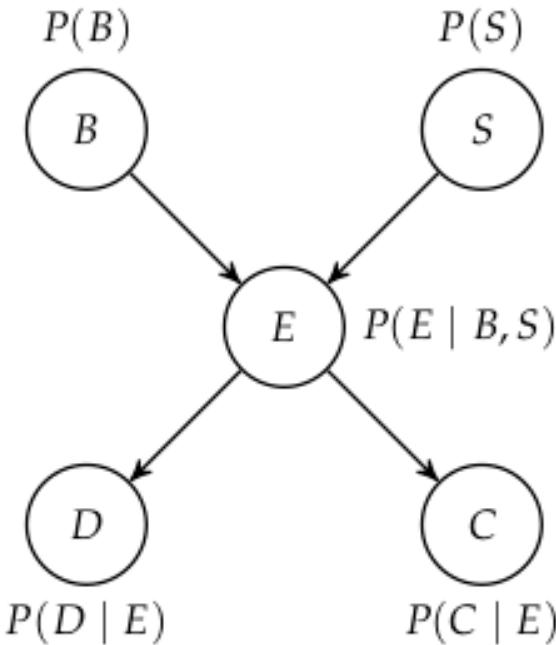
E electrical system failure

D trajectory deviation

C communication loss

$$\begin{aligned}P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\&= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}\end{aligned}$$

Approximate Inference: Weighted Sampling

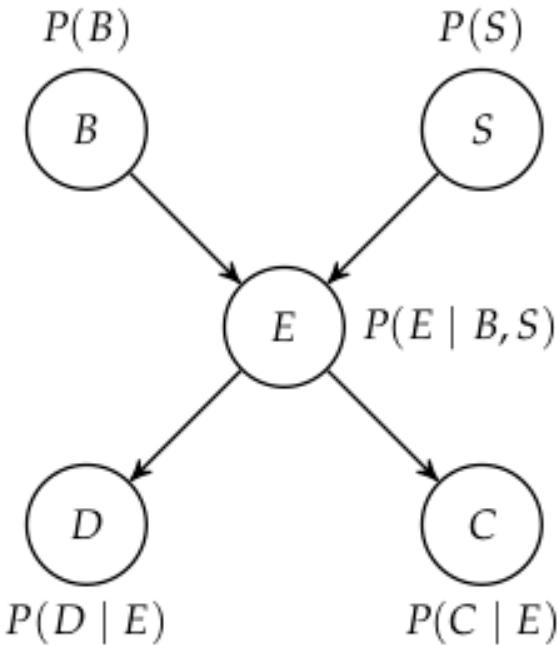


B battery failure
 S solar panel failure
 E electrical system failure
 D trajectory deviation
 C communication loss

$$\begin{aligned}
 P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

B	S	E	D	C	Weight
1	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	1	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$

Approximate Inference: Weighted Sampling



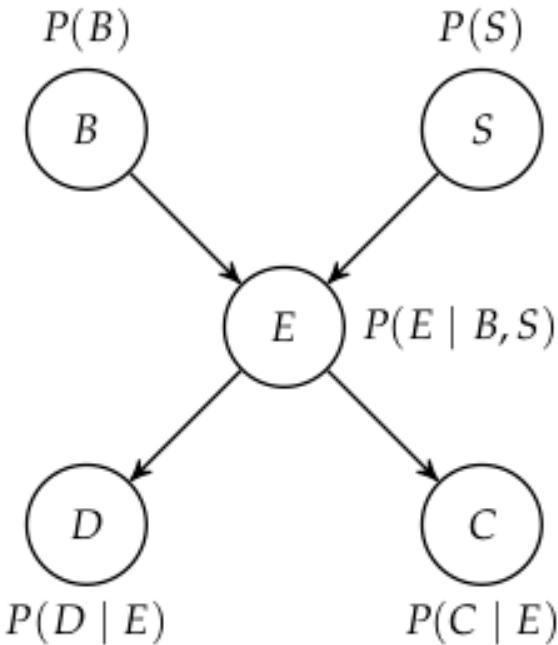
B battery failure
S solar panel failure
E electrical system failure
D trajectory deviation
C communication loss

$$\begin{aligned}P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\&= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}\end{aligned}$$

B	S	E	D	C	Weight
1	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	1	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$

Analogous to

Approximate Inference: Weighted Sampling



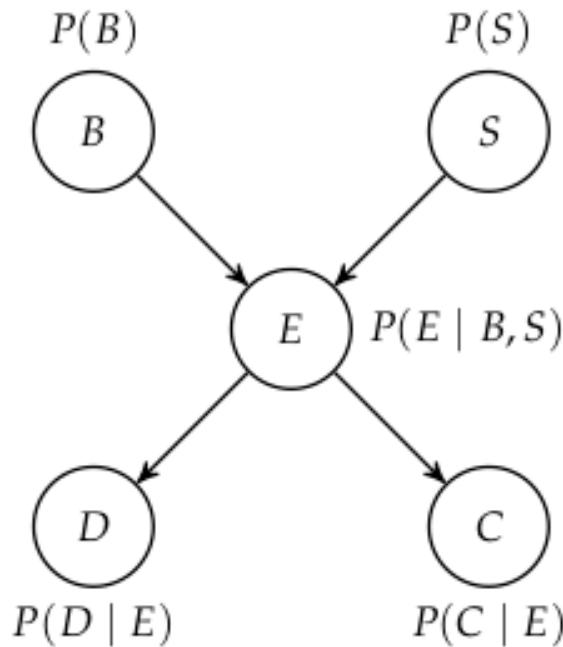
B battery failure
 S solar panel failure
 E electrical system failure
 D trajectory deviation
 C communication loss

$$\begin{aligned}
 P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

B	S	E	D	C	Weight
1	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	1	1	1	1	$P(d^1 e^1)P(c^1 e^1)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	0	1	1	$P(d^1 e^0)P(c^1 e^0)$
0	0	1	1	1	$P(d^1 e^1)P(c^1 e^1)$

Analogous to **weighted particle filtering**

Approximate Inference: Gibbs Sampling



B battery failure

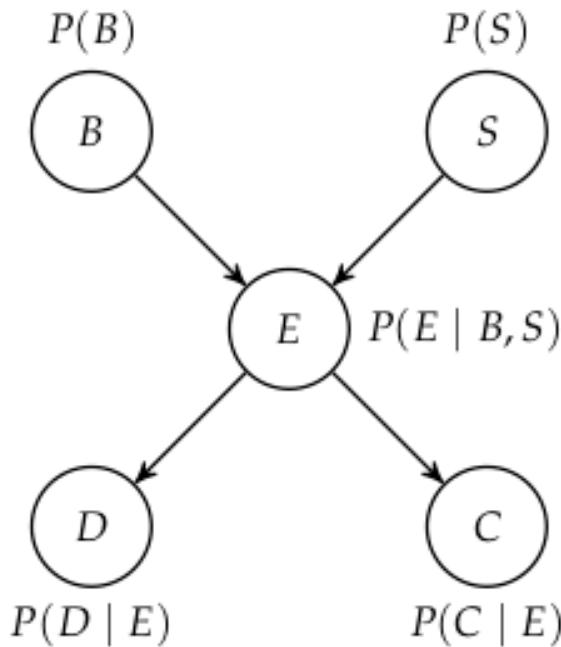
S solar panel failure

E electrical system failure

D trajectory deviation

C communication loss

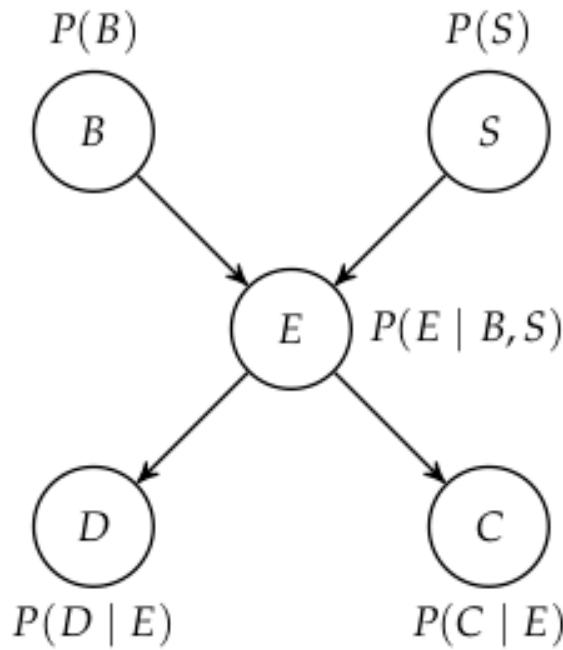
Approximate Inference: Gibbs Sampling



Markov Chain Monte Carlo (MCMC)

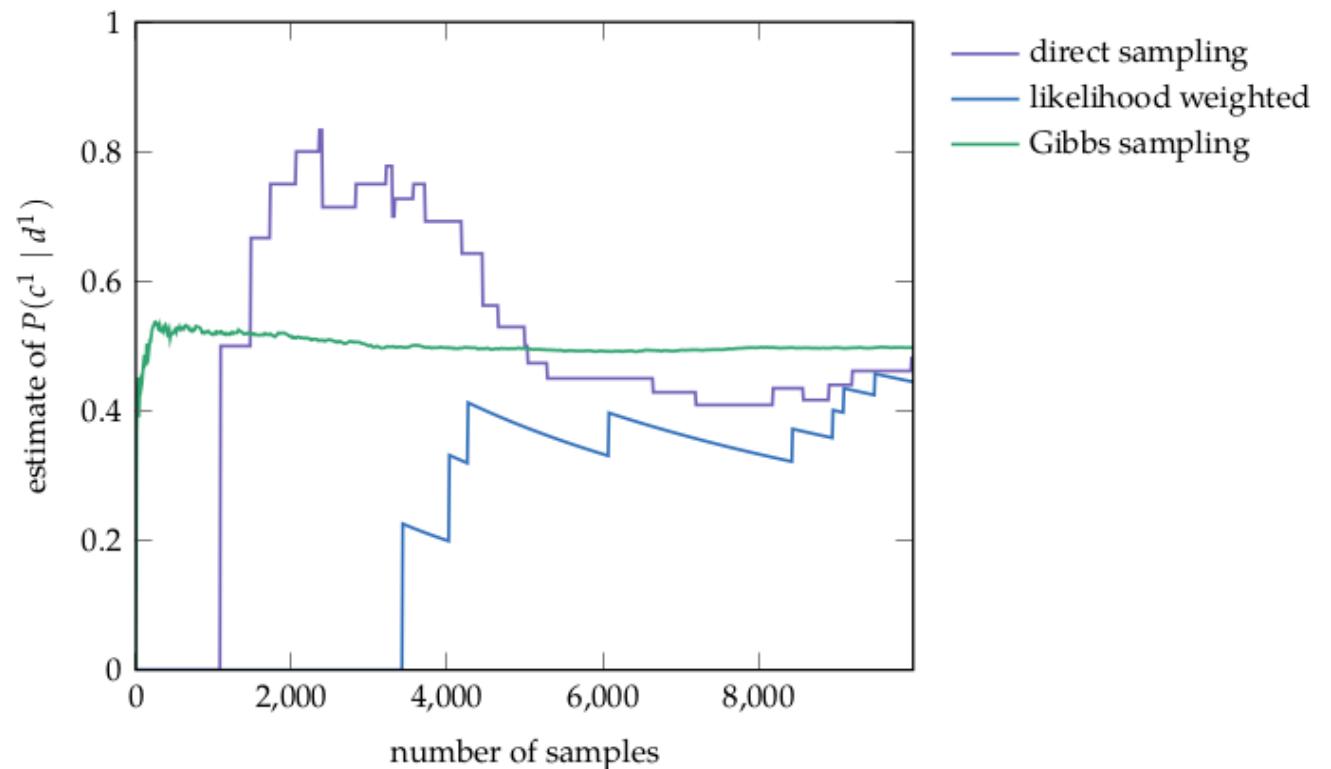
- B battery failure
- S solar panel failure
- E electrical system failure
- D trajectory deviation
- C communication loss

Approximate Inference: Gibbs Sampling



B battery failure
 S solar panel failure
 E electrical system failure
 D trajectory deviation
 C communication loss

Markov Chain Monte Carlo (MCMC)



Recap