

# Causal Bayesian Networks

# Causal Bayesian Networks

**Today:**

- Causal Bayesian Networks
- How do we reason about independence in Bayesian Networks?

# Review: Distributions of Discrete R.V.s

**Joint**

$$P(X = x, Y = y)$$

Single number

"Probability that  
 $X = x \text{ and } Y = y$ "

Shorthand:  $P(x, y)$

$$P(X, Y)$$

A table

"Joint distribution of  
 $X \text{ and } Y$ "

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**Conditional**

$$P(X = x | Y = y)$$

Single number

"Probability that  
 $X = x \text{ if } Y = y$ "

Shorthand:  $P(x | y)$

$$P(X | Y)$$

A collection of tables  
for each  $y$

"Conditional distribution  
of  $X$  given  $Y$ "

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**Marginal**

$$P(X = x)$$

Single number

"Probability that  
 $X = x$ "

Shorthand:  $P(x)$

$$P(X)$$

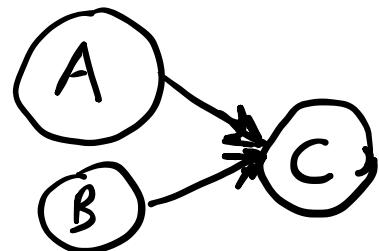
A table

"Marginal  
distribution of  $X$ "

# Causal Bayesian Networks

A *Bayesian Network* compactly represents a joint probability distributions using two components:

1. **Structure:** a directed acyclic graph (DAG), where each node is a R.V.
2. **Parameters:** Numerical values that determine a conditional distribution at each node



At each node,  $P(X \mid pa(X))$

In a *Causal Bayesian Network*, arrows denote causation.



$B$  is a result of  $A$  (and some aleatory uncertainty)

# Chain rule for Bayesian Networks

$$P(X_{1:n}) = \prod_{i=1}^n P(X_i \mid \text{pa}(X_i))$$

# Simple Causal Bayes Net Example

# Naive Inference on Bayes Nets

Bayes Net with 3 Random Variables:  $A \rightarrow C \rightarrow B$

Want to find  $P(\underbrace{A = a}_{\text{query}} \mid \underbrace{B = b}_{\text{evidence}})$

$C$  is a "hidden variable"

1.  $P(A, B = b, C) = P(B = b \mid C) P(C \mid A) P(A).$
2. Marginalize over hidden and query variables to get

$$P(A = a, B = b) = \sum_c P(A = a, B = b, C = c)$$

and

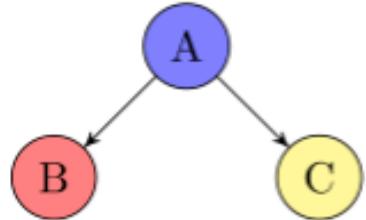
$$P(B = b) = \sum_{a,c} P(A = a, B = b, C = c)$$

$$3. P(A = a \mid B = b) = \frac{P(A=a, B=b)}{P(B=b)}$$

(Book introduces unnormalized "factors", but process is the same.)

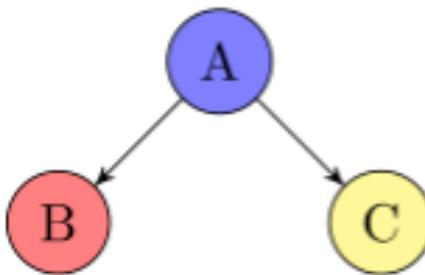
# Conditional Independence in Bayes Nets

# Conditional Independence: Fork



$B \perp C | A ?$

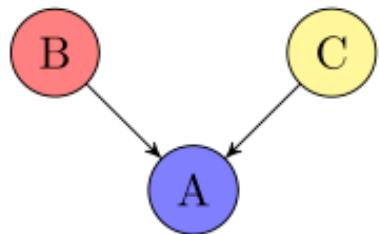
Yes



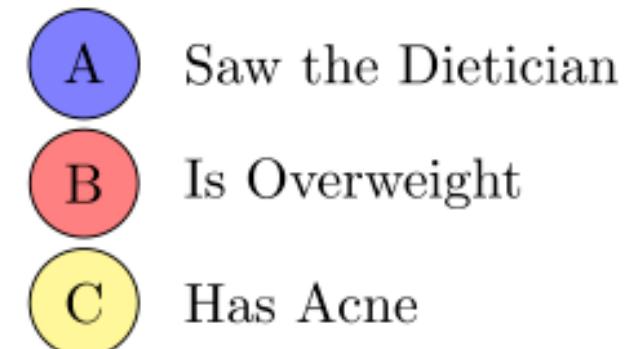
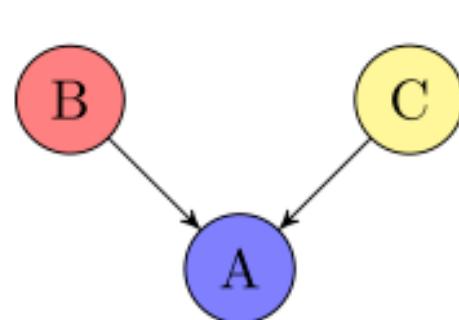
A  
B  
C

Is a Child  
Recently Vaccinated  
Diagnosed with Autism

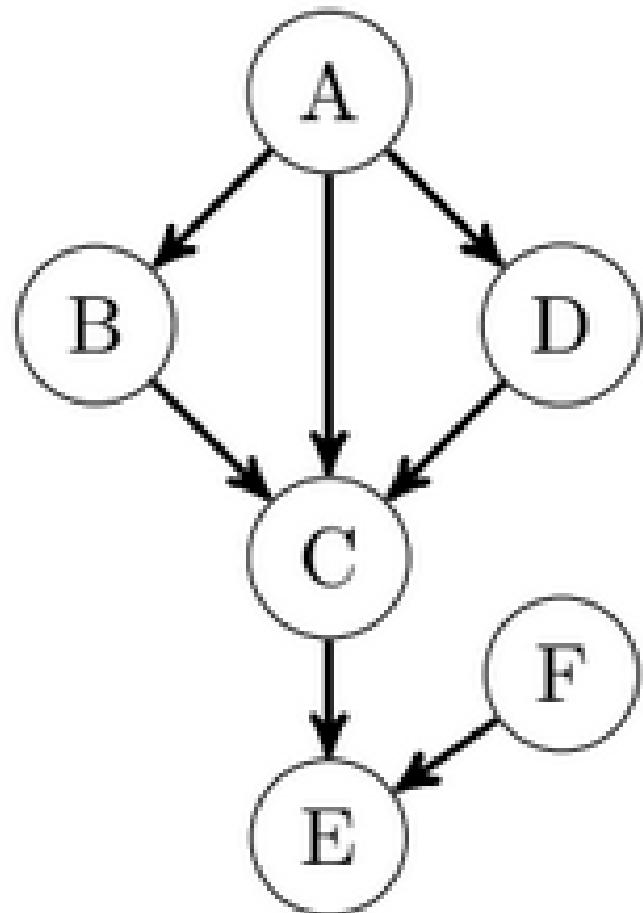
# Conditional Independence: Inverted Fork



$B \perp C \mid A ?$



# More Complex Example



$(B \perp D \mid A)$  ?

Yes!

$(B \perp D \mid E)$  ?

Inconclusive

Why is this relevant to decision making?

# d-Separation

Let  $\mathcal{C}$  be a set of random variables.

An undirected *path* between  $A$  and  $B$  is *d-separated* by  $\mathcal{C}$  if any of the following exist along the path:

**Separators** (a.k.a "inactive triples"):

1. **Chain:**  $X \rightarrow Y \rightarrow Z$  such that  $Y \in \mathcal{C}$
  2. **Fork:**  $X \leftarrow Y \rightarrow Z$  such that  $Y \in \mathcal{C}$
  3. **Inverted Fork (v-structure):**  $X \rightarrow Y \leftarrow Z$  such that  $Y \notin \mathcal{C}$  and no descendant of  $Y$  is in  $\mathcal{C}$ .
- Also:
- d-separated = "inactive"
  - not d-separated = "active"

## Break

$B \leftarrow A \rightarrow C \leftarrow D$

$B \leftarrow C \rightarrow A \leftarrow D$

Are these paths d-separated by  $\mathcal{C} = \{C\}$ ?

# d-Separation for Bayes Nets

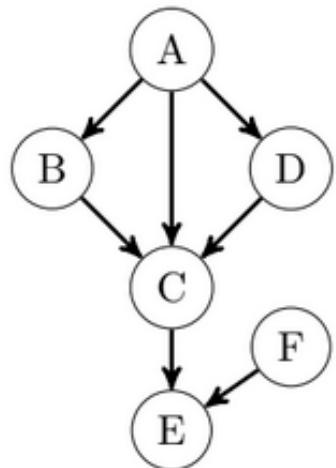
We say that  $A$  and  $B$  are *d-separated* by  $\mathcal{C}$  if all acyclic paths between  $A$  and  $B$  are d-separated by  $\mathcal{C}$ .

If  $A$  and  $B$  are d-separated by  $\mathcal{C}$  then  $A \perp B | \mathcal{C}$

In other words, if there is any active path w.r.t.  $\mathcal{C}$  between  $A$  and  $B$ , we *cannot* conclude that  $A \perp B | \mathcal{C}$  based on the structure alone.

# Proving Conditional Independence

1. Enumerate all (non-cyclic) paths between nodes in question
2. Check all paths for d-separation
3. If all paths d-separated, then CE



Example:  $(B \perp D \mid C, E)$  ?

## Separators

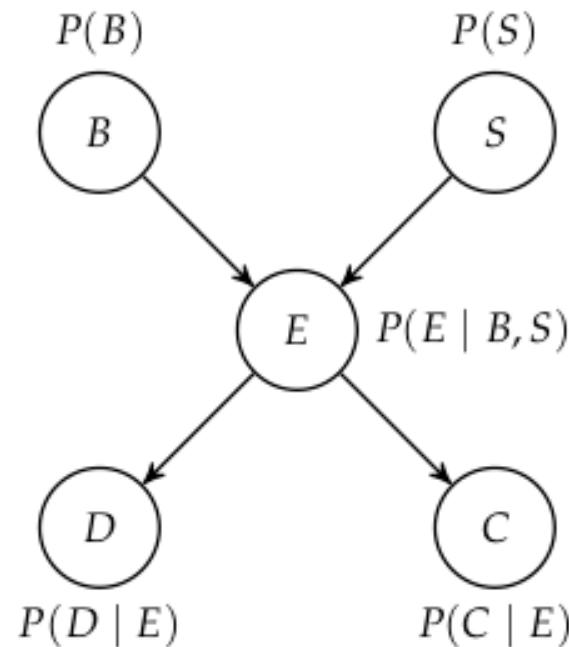
1. **Chain:**  $X \rightarrow Y \rightarrow Z$  such that  $Y \in \mathcal{C}$
2. **Fork:**  $X \leftarrow Y \rightarrow Z$  such that  $Y \in \mathcal{C}$
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# Markov Blanket

The *Markov Blanket* of  $\mathcal{X}$  is the minimal set of nodes that, if their values were known, would make  $\mathcal{X}$  conditionally independent of all other nodes.

A Markov blanket of a particular node consists of its parents, its children, and the other parents of its children.

If  $\mathcal{B}$  is the Markov blanket of  $\mathcal{X}$ , you can treat analyze  $\mathcal{B} \cup \mathcal{X}$  alone, and ignore any other nodes.



$B$  battery failure

$S$  solar panel failure

$E$  electrical system failure

$D$  trajectory deviation

$C$  communication loss

# Exercise

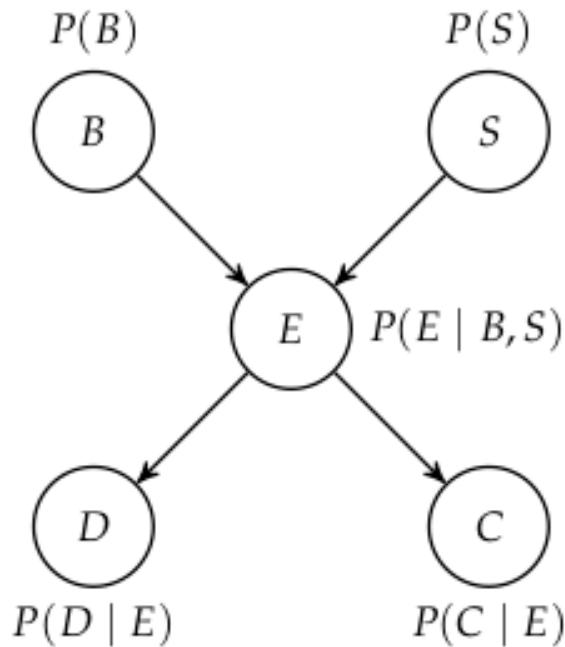
$$D \perp C \mid B ?$$

$$D \perp C \mid E ?$$

1. The path contains a *chain*  $X \rightarrow Y \rightarrow Z$  such that  $Y \in \mathcal{C}$
2. The path contains a *fork*  $X \leftarrow Y \rightarrow Z$  such that  $Y \in \mathcal{C}$
3. The path contains an *inverted fork* (v-structure)  $X \rightarrow Y \leftarrow Z$  such that  $Y \notin \mathcal{C}$  and no descendant of  $Y$  is in  $\mathcal{C}$ .

# Approximate Inference

# Approximate Inference: Direct Sampling



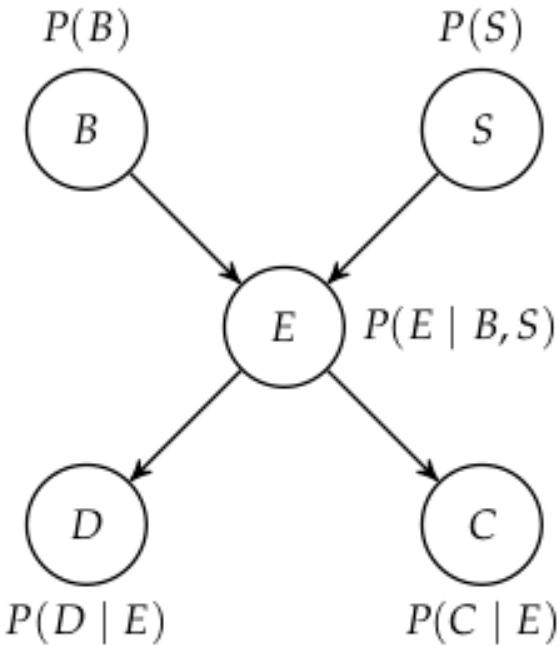
B battery failure  
S solar panel failure  
E electrical system failure  
D trajectory deviation  
C communication loss

$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

B	S	E	D	C
0	0	1	1	0
0	0	0	0	0
1	0	1	0	0
1	0	1	1	1
0	0	0	0	0
0	0	0	1	0
0	0	0	0	1
0	1	1	1	1
0	0	0	0	0
0	0	0	1	0

Analogous to **unweighted particle filtering**

# Approximate Inference: Weighted Sampling



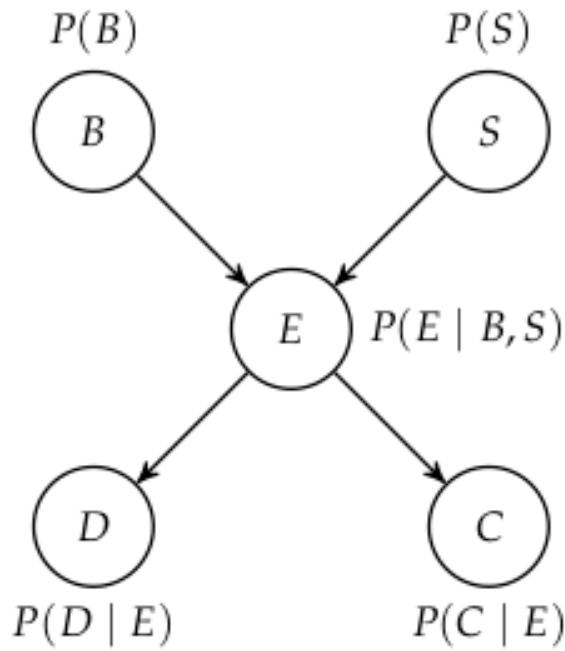
$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$\begin{aligned}
 P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

$B$	$S$	$E$	$D$	$C$	Weight
1	0	1	1	1	$P(d^1   e^1)P(c^1   e^1)$
0	1	1	1	1	$P(d^1   e^1)P(c^1   e^1)$
0	0	0	1	1	$P(d^1   e^0)P(c^1   e^0)$
0	0	0	1	1	$P(d^1   e^0)P(c^1   e^0)$
0	0	1	1	1	$P(d^1   e^1)P(c^1   e^1)$

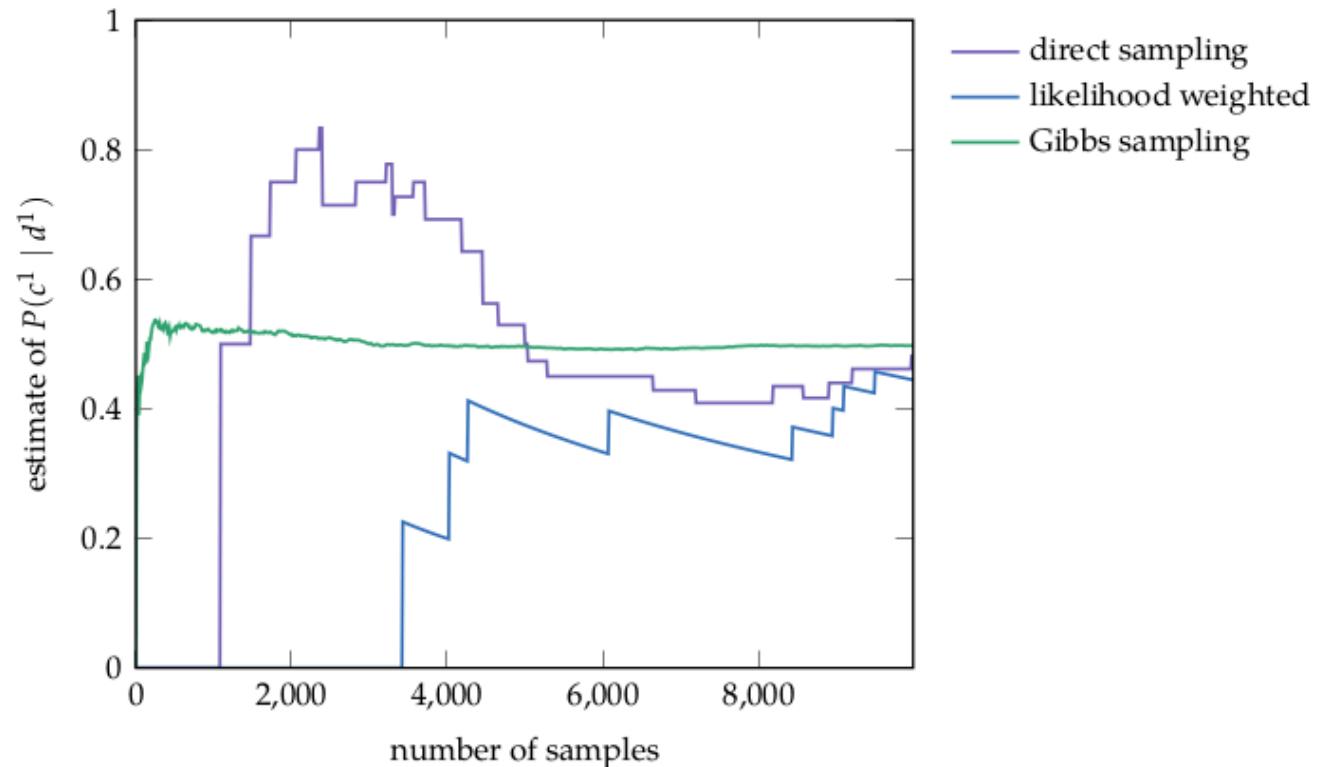
Analogous to **weighted particle filtering**

# Approximate Inference: Gibbs Sampling



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

Markov Chain Monte Carlo (MCMC)



# Recap