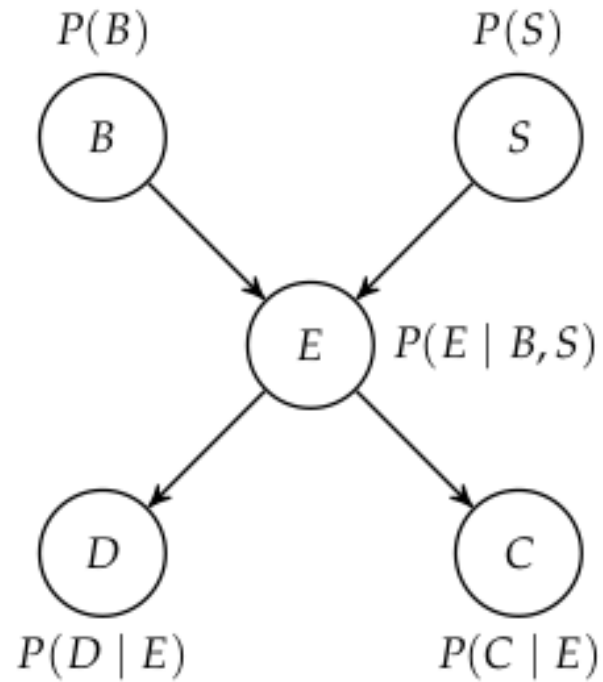


# Bayesian Network Learning

- Last time:
  - Conditional independence in Bayesian Networks
  - Sampling from Bayesian Networks
- Today:
  - Given a **Bayesian Network** and some **values**, how do we calculate the probability of **other values**?
  - Given **data**, how do we **fit** a Bayesian network?

# Bayesian Network



**Structure**

**Parameters**

$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

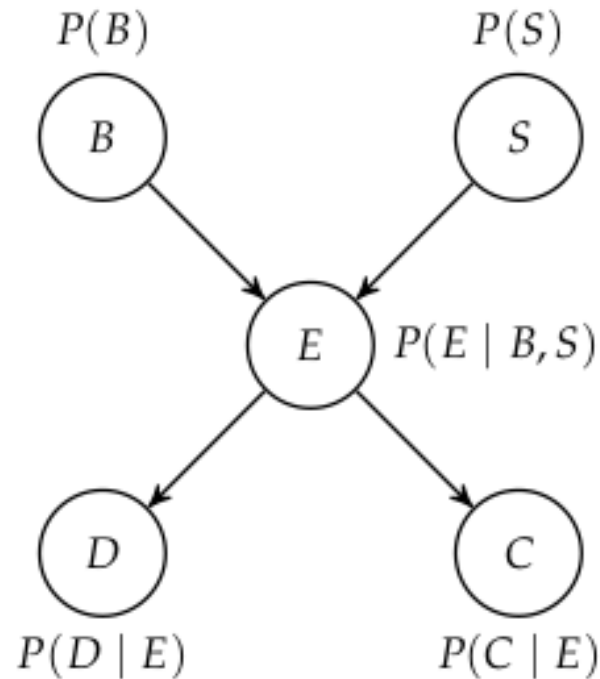
# Inference

## Inputs

- Bayesian network structure
- Bayesian network parameters
- Values of *evidence variables*

## Outputs

- Posterior distribution of *query variables*



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

Given that you have detected a trajectory deviation, and the battery has not failed what is the probability of a solar panel failure?

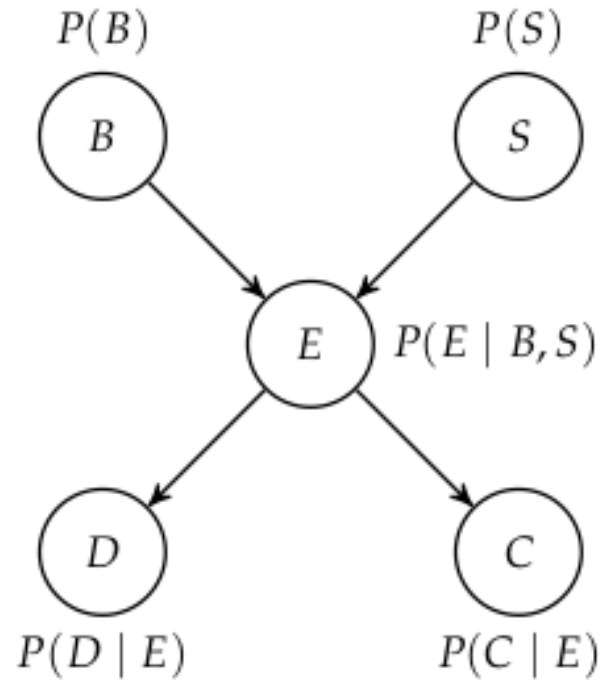
$$P(S = 1 \mid D = 1, B = 0)$$

Exact

Approximate

# Exact Inference

# Exact Inference



B battery failure  
S solar panel failure  
E electrical system failure  
D trajectory deviation  
C communication loss

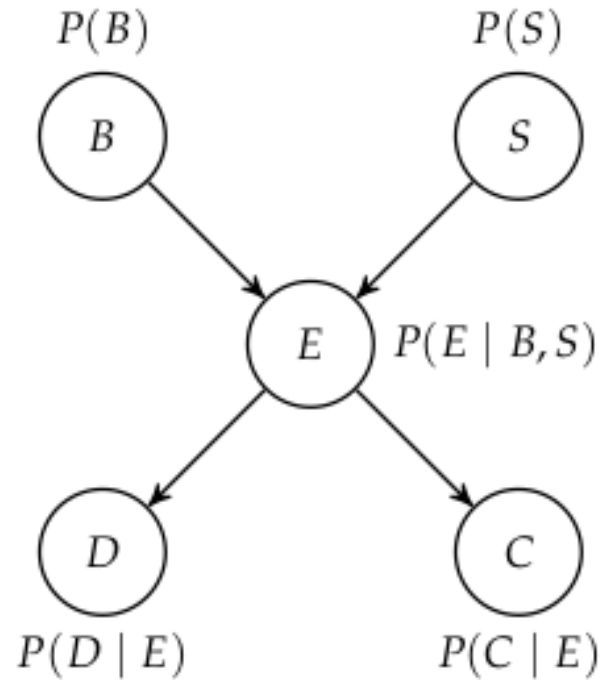
$$P(S=1 \mid D=1, B=0) = \frac{P(S=1, D=1, B=0)}{P(D=1, B=0)}$$

$$P(S=1, D=1, B=0) = \sum_{e,c} P(B=0, S=1, E=e, D=1, C=c)$$

$$\begin{aligned} &P(B=0, S=1, E, D=1, C) \\ &= P(B=0) P(S=1) P(E \mid B=0, S=1) P(D=1 \mid E) P(C=1 \mid E) \end{aligned}$$

$2^5 = 32$  possible assignments,  
but quickly gets too large

# Exact Inference



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

## Product

$X$	$Y$	$\phi_1(X, Y)$
0	0	0.3
0	1	0.4
1	0	0.2
1	1	0.1

$Y$	$Z$	$\phi_2(Y, Z)$
0	0	0.2
0	1	0.0
1	0	0.3
1	1	0.5

$X$	$Y$	$Z$	$\phi_3(X, Y, Z)$
0	0	0	0.06
0	0	1	0.00
0	1	0	0.12
0	1	1	0.20
1	0	0	0.04
1	0	1	0.00
1	1	0	0.03
1	1	1	0.05

```

struct ExactInference end

function infer(M::ExactInference, bn, query, evidence)
     $\phi$  = prod(bn.factors)
     $\phi$  = condition( $\phi$ , evidence)
    for name in setdiff(variablenames( $\phi$ ), query)
         $\phi$  = marginalize( $\phi$ , name)
    end
    return normalize!( $\phi$ )
end
  
```

## Condition

$X$	$Y$	$Z$	$\phi(X, Y, Z)$
0	0	0	0.08
0	0	1	0.31
0	1	0	0.09
0	1	1	0.37
1	0	0	0.01
1	0	1	0.05
1	1	0	0.02
1	1	1	0.07

  
 $Y = 1$ 
  

$X$	$Z$	$\phi(X, Z)$
0	0	0.09
0	1	0.37
1	0	0.02
1	1	0.07

## Marginalize

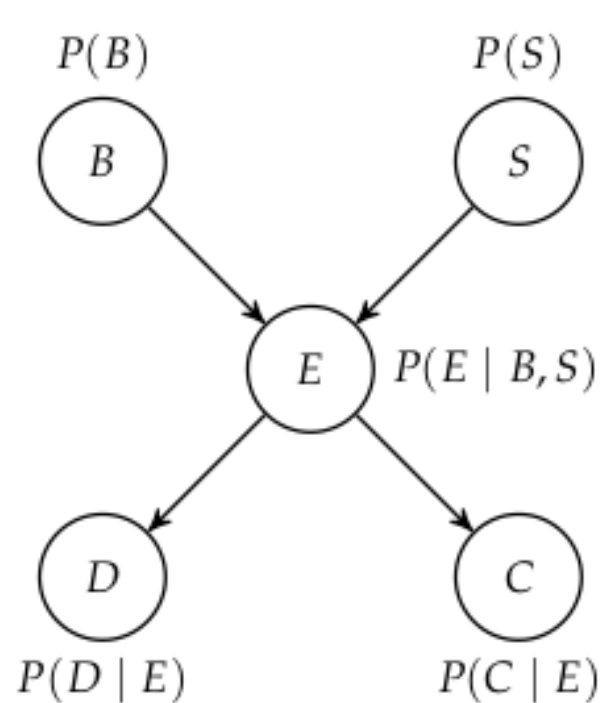
$X$	$Y$	$Z$	$\phi(X, Y, Z)$
0	0	0	0.08
0	0	1	0.31
0	1	0	0.09
0	1	1	0.37
1	0	0	0.01
1	0	1	0.05
1	1	0	0.02
1	1	1	0.07

$X$	$Z$	$\phi(X, Z)$
0	0	0.17
0	1	0.68
1	0	0.03
1	1	0.12

$2^5 = 32$  possible assignments,  
 but quickly gets too large

# Exact Inference: Variable Elimination



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$P(B | d^1, c^1)$$

Start with

$$\phi_1(B), \phi_2(S), \phi_3(E, B, S), \phi_4(D, E), \phi_5(C, E)$$

Eliminate  $D$  and  $C$  (evidence) to get  $\phi_6(E)$  and  $\phi_7(E)$

Eliminate  $E$

$$\phi_8(B, S) = \sum_e \phi_3(e, B, S) \phi_6(e) \phi_7(e)$$

Eliminate  $S$

$$\phi_9(B) = \sum_s \phi_2(s) \phi_8(B, s)$$

$$P(B | d^1, c^1) \propto \phi_1(B) \sum_s \left( \phi_2(s) \sum_e \left( \phi_3(e | B, s) \phi_4(d^1 | e) \phi_5(c^1 | e) \right) \right)$$

VS

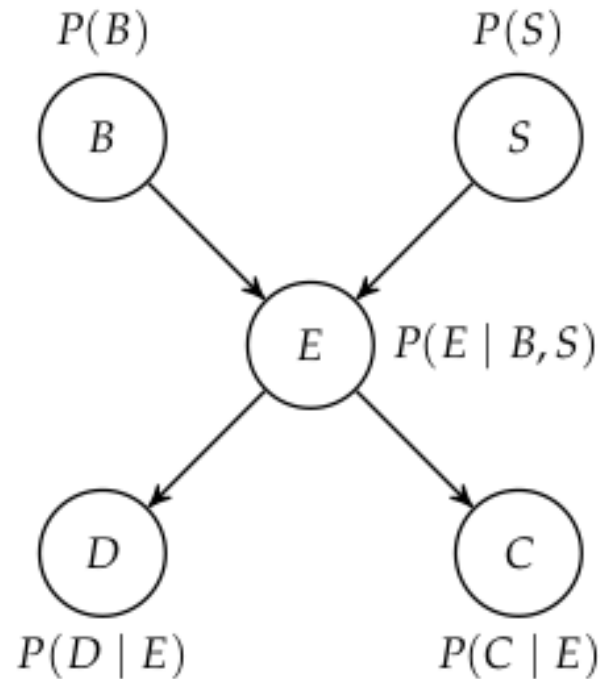
$$P(B | d^1, c^1) \propto \sum_s \sum_e \phi_1(B) \phi_2(s) \phi_3(e | B, s) \phi_4(d^1 | e) \phi_5(c^1 | e)$$

Choosing  
optimal order  
is NP-hard

# Approximate Inference



# Approximate Inference: Direct Sampling



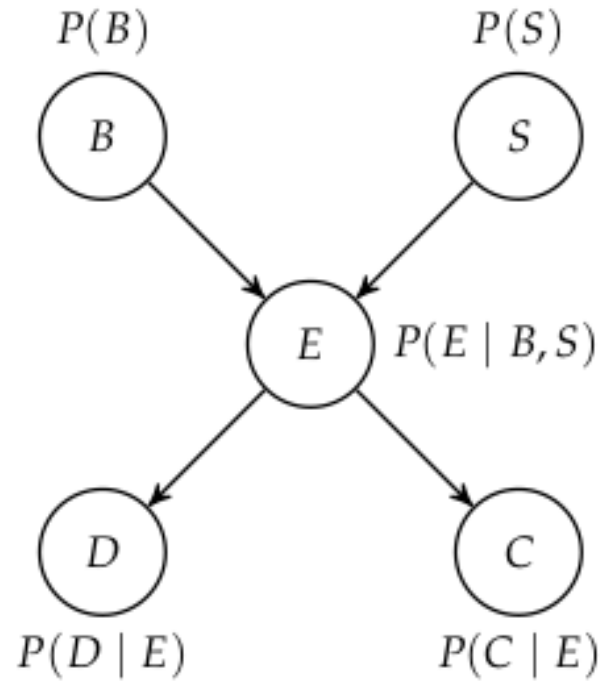
$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

$$P(b^1 | d^1, c^1) \approx \frac{\sum_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i (d^{(i)} = 1 \wedge c^{(i)} = 1)}$$

$B$	$S$	$E$	$D$	$C$	
0	0	1	1	0	
0	0	0	0	0	
1	0	1	0	0	
1	0	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	
0	0	0	0	1	
0	1	1	1	1	←
0	0	0	0	0	
0	0	0	1	0	

Analogous to **unweighted particle filtering**

# Approximate Inference: Weighted Sampling



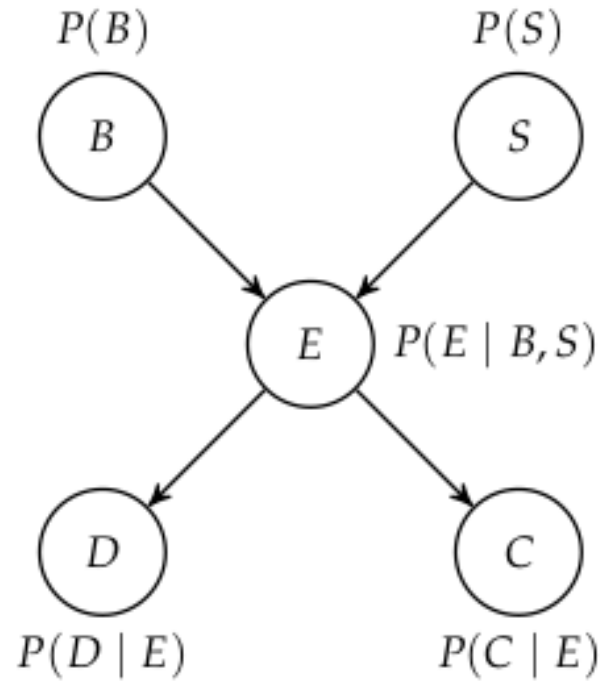
*B* battery failure  
*S* solar panel failure  
*E* electrical system failure  
*D* trajectory deviation  
*C* communication loss

$$\begin{aligned}
 P(b^1 | d^1, c^1) &\approx \frac{\sum_i w_i (b^{(i)} = 1 \wedge d^{(i)} = 1 \wedge c^{(i)} = 1)}{\sum_i w_i (d^{(i)} = 1 \wedge c^{(i)} = 1)} \\
 &= \frac{\sum_i w_i (b^{(i)} = 1)}{\sum_i w_i}
 \end{aligned}$$

<i>B</i>	<i>S</i>	<i>E</i>	<i>D</i>	<i>C</i>	Weight
1	0	1	1	1	$P(d^1   e^1)P(c^1   e^1)$
0	1	1	1	1	$P(d^1   e^1)P(c^1   e^1)$
0	0	0	1	1	$P(d^1   e^0)P(c^1   e^0)$
0	0	0	1	1	$P(d^1   e^0)P(c^1   e^0)$
0	0	1	1	1	$P(d^1   e^1)P(c^1   e^1)$

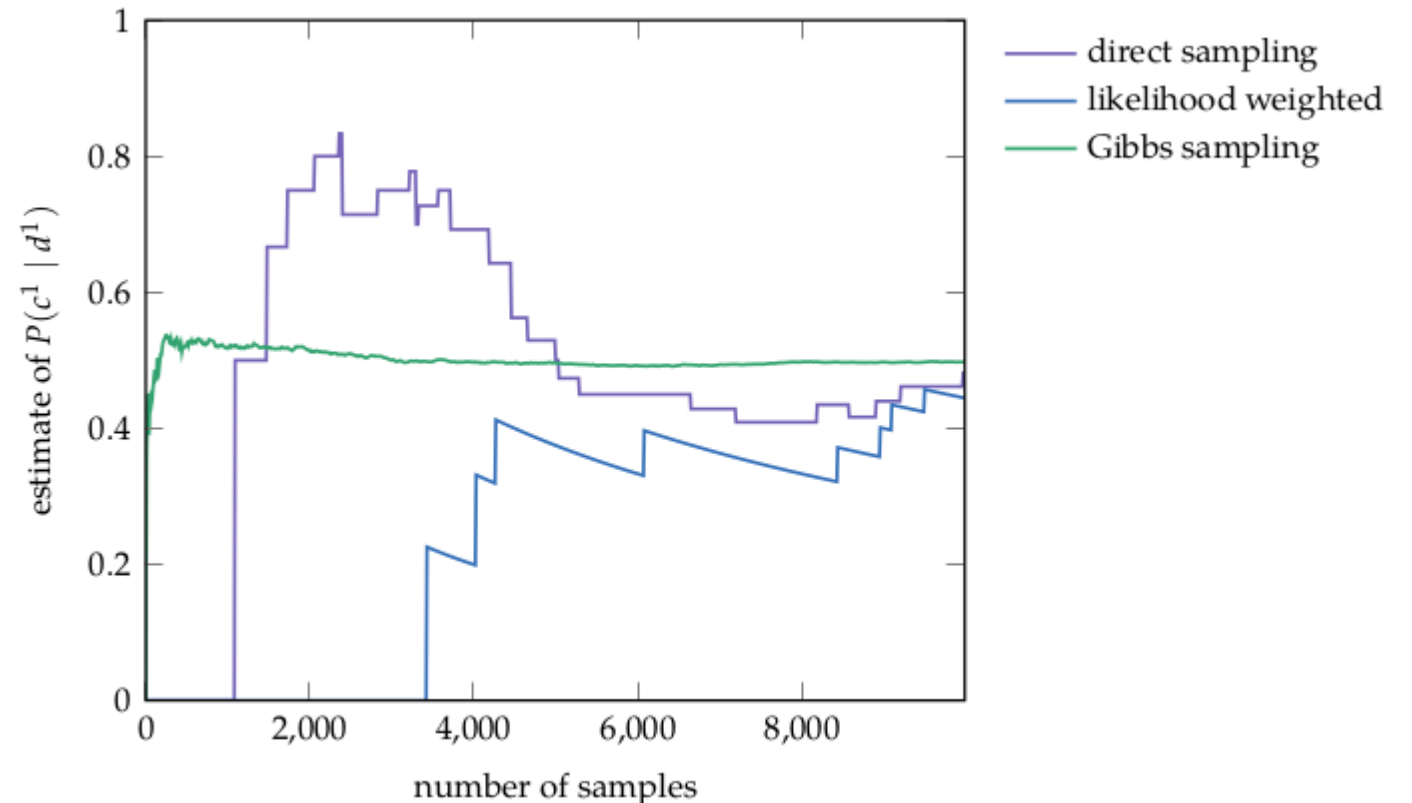
Analogous to **weighted particle filtering**

# Approximate Inference: Gibbs Sampling



$B$  battery failure  
 $S$  solar panel failure  
 $E$  electrical system failure  
 $D$  trajectory deviation  
 $C$  communication loss

## Markov Chain Monte Carlo (MCMC)



# Learning

# Bayesian Network Learning

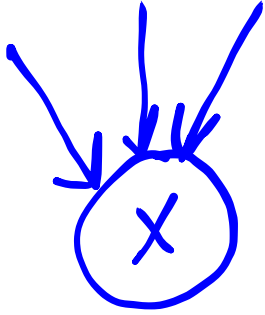
## Inputs

- Data,  $D$
- Priors (?)

## Outputs

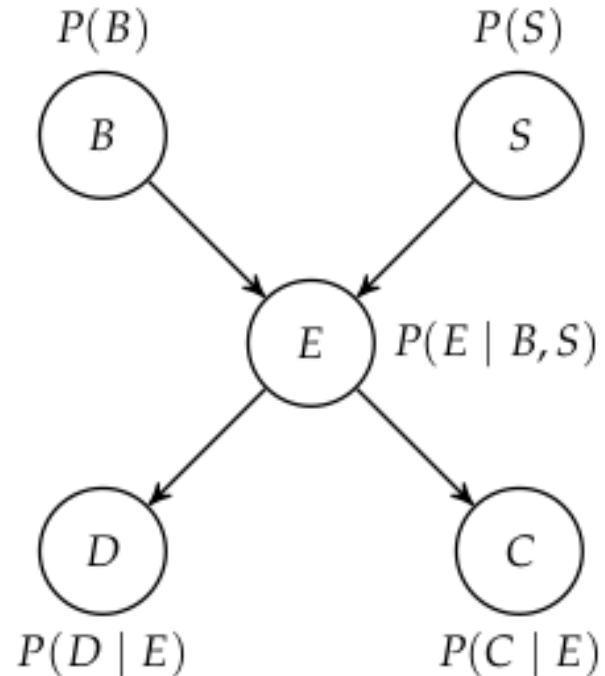
- Bayesian network structure,  $G$
- Bayesian network parameters,  $\theta$

# Counting Parameters



For discrete R.V.s:

$$\dim(\theta_X) = (|\text{support}(X)| - 1) \prod_{Y \in \text{Pa}(X)} |\text{support}(Y)|$$



# Structure Learning Example

# Parameter Learning

## Maximum Likelihood

$$\hat{\theta} = \arg \max_{\theta} P(D \mid \theta)$$

$$P(D \mid \theta) = \prod_i P(o_i \mid \theta)$$

$$\hat{\theta} = \arg \max_{\theta} \sum_i \log P(o_i \mid \theta)$$

Multinomial:

$$\hat{\theta}_i = \frac{n_i}{\sum_{j=1}^k n_j}$$

## Bayesian

$$\hat{\theta} = \mathbb{E}_{\theta \sim p(\cdot \mid D)}[\theta] = \int \theta p(\theta \mid D) \mathrm{d}\theta$$

Multinomial:

$$p(\theta_{1:n} \mid \alpha_{1:n}, m_{1:n}) = \text{Dir}(\theta_{1:n} \mid \alpha_1 + m_1, \dots, \alpha_n + m_n)$$

$$\frac{\alpha_i}{\sum_{j=1}^n \alpha_j}$$



# Structure Learning

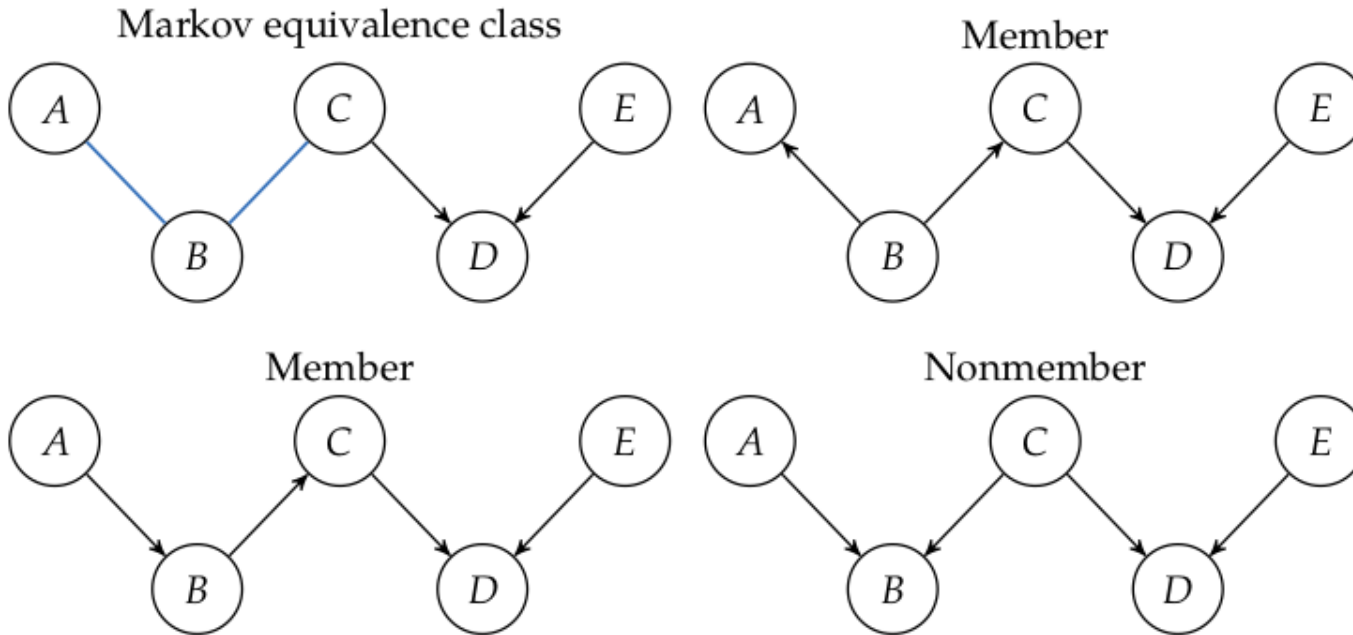
$$\begin{aligned} P(G \mid D) &\propto P(G)P(D \mid G) \\ &= P(G) \int P(D \mid \boldsymbol{\theta}, G) p(\boldsymbol{\theta} \mid G) d\boldsymbol{\theta} \end{aligned}$$

$$P(G \mid D) = P(G) \prod_{i=1}^n \prod_{j=1}^{q_i} \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \prod_{k=1}^{r_i} \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})}$$

$$\begin{aligned} &\log P(G \mid D) \\ &= \log P(G) + \sum_{i=1}^n \sum_{j=1}^{q_i} \left( \log \left( \frac{\Gamma(\alpha_{ij0})}{\Gamma(\alpha_{ij0} + m_{ij0})} \right) + \sum_{k=1}^{r_i} \log \left( \frac{\Gamma(\alpha_{ijk} + m_{ijk})}{\Gamma(\alpha_{ijk})} \right) \right) \end{aligned}$$

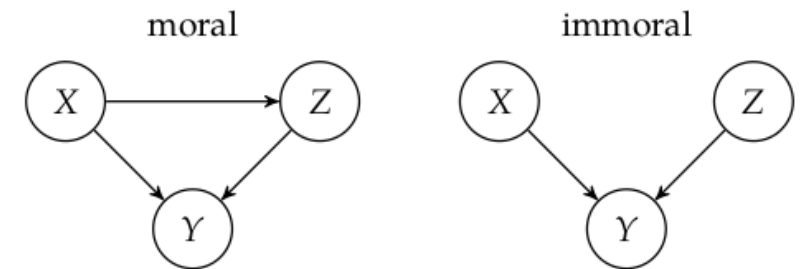
NP-Hard

# Markov Equivalence Class



Markov Equivalent iff

1. Same undirected edges
2. Same set of immoral v-structures



# Recap

**Inference**

**Learning**