Experiment 6

Student Name: Avil saini UID: 22BET101380

Branch: IT Section/Group: 22BET_IOT-702/B
Semester: 6th Date of Performance: 28/02/25

Subject Name: Advance Programming-II **Subject Code:** 22ITP-367

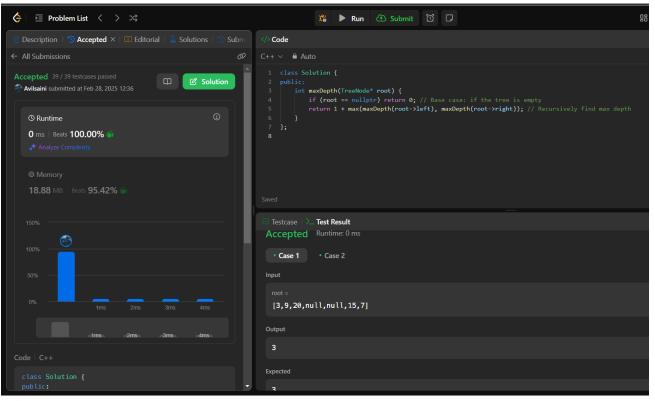
Problem: 1.6.1: Maximum Depth of Binary Tree

Problem Statement: Given the root of a **binary tree**, return its **maximum depth**. The **maximum depth** is the number of nodes along the **longest path** from the root down to the farthest leaf node.

1. Objective: Find the **maximum depth** of a binary tree using **recursion**.



3.Result



•

Problem 1.6.2: Validate Binary Search Tree

Problem Statement: Given the root of a binary tree, determine if it is a valid Binary Search Tree (BST).

A BST must satisfy the following properties:

The left subtree of a node contains only nodes with values less than the node's value.

The right subtree of a node contains only nodes with values greater than the node's value.

Both the left and right subtrees must also be BSTs.

1. Objective: Check if the given tree is a valid BST using recursion and range validation.

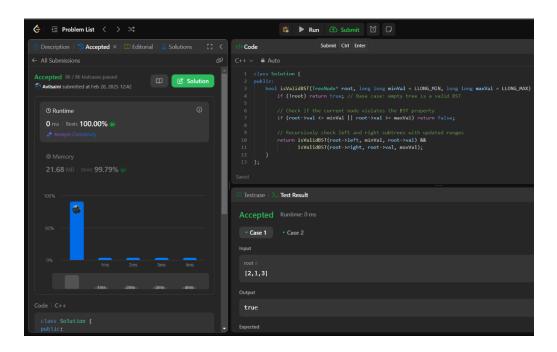
2. Code:

```
class Solution {
public:
   bool isValidBST(TreeNode* root, long long minVal = LLONG_MIN, long
long maxVal = LLONG_MAX) {
    if (!root) return true; // Base case: empty tree is a valid BST

    // Check if the current node violates the BST property
    if (root->val <= minVal || root->val >= maxVal) return false;

    // Recursively check left and right subtrees with updated ranges
    return isValidBST(root->left, minVal, root->val) &&
        isValidBST(root->right, root->val, maxVal);
    }
};
```

Result:



Problem 1.6.3: Kth Largest Element in an Array

Problem Statement: Given an integer array nums and an integer k, return the kth largest element in the array.

Note: It is the kth largest element in sorted order, not the kth distinct element.

1. Objective: Find the **kth largest element** in the array using an efficient approach.

2. Code:

```
#include <unordered_map>
#include <vector>

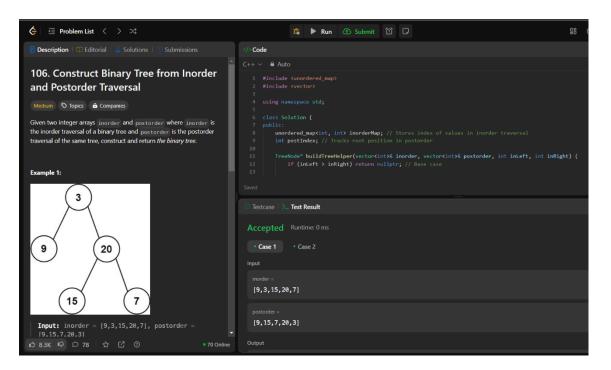
using namespace std;

class Solution {
public:
    unordered_map<int, int> inorderMap; // Stores index of values in inorder traversal
    int postIndex; // Tracks root position in postorder
```

```
TreeNode* buildTreeHelper(vector<int>& inorder, vector<int>&
postorder, int inLeft, int inRight) {
     if (inLeft > inRight) return nullptr; // Base case
     int rootVal = postorder[postIndex--]; // Get root from postorder
     TreeNode* root = new TreeNode(rootVal); // Create root node
     int inIndex = inorderMap[rootVal]; // Get index from inorder map
     // Build right subtree first (since postorder gives root -> right -> left)
     root->right = buildTreeHelper(inorder, postorder, inIndex + 1,
inRight);
     root->left = buildTreeHelper(inorder, postorder, inLeft, inIndex - 1);
     return root;
  }
  TreeNode* buildTree(vector<int>& inorder, vector<int>& postorder) {
     postIndex = postorder.size() - 1; // Start from the last element in
postorder
     // Store inorder indices in a map for O(1) lookup
     for (int i = 0; i < inorder.size(); i++) {
       inorderMap[inorder[i]] = i;
     }
     return buildTreeHelper(inorder, postorder, 0, inorder.size() - 1);
};
```



3. Result:



Problem 1.6.4: Binary Tree Inorder Traversal

Problem Statement: Given the root of a **binary tree**, return its **inorder traversal** (Left \rightarrow Root \rightarrow Right).

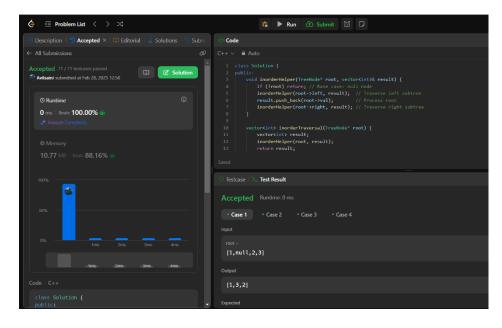
Objective: Traverse a binary tree in inorder sequence (Left \rightarrow Root \rightarrow Right) and return the values in a list.

1. Code:

```
class Solution {
public:
    void inorderHelper(TreeNode* root, vector<int>& result) {
        if (!root) return; // Base case: null node
        inorderHelper(root->left, result); // Traverse left subtree
        result.push_back(root->val); // Process root
        inorderHelper(root->right, result); // Traverse right subtree
    }

    vector<int> inorderTraversal(TreeNode* root) {
        vector<int> result;
        inorderHelper(root, result);
        return result;
    }
};
```

2. Result:



Problem 1.6.5: Populating Next Right Pointers in Each Node

- 1. Problem Statement: Given a perfect binary tree, connect each node's next pointer to its right adjacent node. If there is no right adjacent node, set the next pointer to NULL. The connections should be made in-place, without using extra memory for level-wise traversal.
- 2. Objective: Find the median of two sorted arrays efficiently using binary search.
- 3. Code:

```
#include <queue>
using namespace std;
class Solution {
public:
  Node* connect(Node* root) {
     if (!root) return nullptr; // Base case
     queue<Node*>q;
     q.push(root);
     while (!q.empty()) {
       int size = q.size();
       Node* prev = nullptr;
       for (int i = 0; i < size; i++) {
          Node* curr = q.front();
          q.pop();
          if (prev) prev->next = curr; // Connect previous node to current
          prev = curr;
          if (curr->left) q.push(curr->left);
          if (curr->right) q.push(curr->right);
       prev->next = nullptr; // Last node in the level points to NULL
```

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return root;
}
};
return 0;

4. Result:

