

CURM Quaternion Stuff

Fall 2020

Benjamin Rempfer

Introduction and Background:

I will first introduce the definition of \mathbb{H} , the field of quaternions as to build towards a quaternion-valued metric space. Each element $h \in \mathbb{H}$ is defined as $h = a + bi + cj + dk$ where $a, b, c, d \in \mathbb{R}$ and i, j, k are symbols following the equality, $i^2 = j^2 = k^2 = ijk = -1$. These symbols are imaginary much like i is the imaginary component of complex numbers. There are many surprisingly pragmatic applications of quaternions in physics and programming. I even found mention of so-called 'bi-quaternions' in special relativity. The norm of a quaternion is defined as $|h| = \sqrt{a^2 + b^2 + c^2 + d^2}$. The trouble with proving Theorem 1 in Dr. Thompson's paper comes in the extension of Denjoy-Wolff due to the lack of a simple derivative to work with. We have to use left and right derivatives because quaternions are non-commutative. Getting a Cauchy's Integral Formula will be quite difficult, but I think it might be possible.

Partial Ordering of \mathbb{H}

In order to have a quaternion-valued metric space we must first have some kind of ordering to the set \mathbb{H} . This comes in the paper titled *Fixed Point Theorems in Quaternion-Valued Metric Spaces*. The partial order \preceq on \mathbb{H} is given as follows, $h_1 \preceq h_2 \iff \text{Re}(h_1) \leq \text{Re}(h_2) \wedge \text{Im}_i(h_1) \leq \text{Im}_i(h_2) \wedge \text{Im}_j(h_1) \leq \text{Im}_j(h_2) \wedge \text{Im}_k(h_1) \leq \text{Im}_k(h_2)$.

Quaternion-Valued Metric Space

Let S be a nonempty set. $d_{\mathbb{H}}$ is a quaternion valued metric on S , and $(S, d_{\mathbb{H}})$ is a quaternion-valued metric space if and only if these three properties hold:

- (1) $0 \preceq d_{\mathbb{H}}(x, y)$ for all $x, y \in S$ and $d_{\mathbb{H}}(x, y) = 0$ if and only if $x = y$,
- (2) $d_{\mathbb{H}}(x, y) = d_{\mathbb{H}}(y, x)$ for all $x, y \in S$,
- (3) $d_{\mathbb{H}}(x, y) \preceq d_{\mathbb{H}}(x, z) + d_{\mathbb{H}}(z, y)$ for all $x, y, z \in S$.

Theorem 1: *Suppose $\phi : \mathbb{D} \rightarrow \mathbb{D}$ is analytic and continuous on $\partial\mathbb{D}$. If the Denjoy-Wolff point a of ϕ is in \mathbb{D} , then $\phi_n \rightarrow a$ uniformly if and only if there is $N > 0$ such that $\phi_N(\overline{\mathbb{D}}) \subset \mathbb{D}$.*

Proof. The direction that is trivial due to Denjoy-Wolff in the given context is no longer easy in this new quaternion-valued setting. This gives me a feeling of much unease. Nonetheless, I will accomplish the other direction by a neat trick with inequalities.

Let M be the minimum distance along any basis direction between a and the unit ball. For a given real number $\epsilon > 0$, let $q = \frac{\epsilon}{2} + i\frac{\epsilon}{2} + j\frac{\epsilon}{2} + k\frac{\epsilon}{2}$. For $\epsilon = \frac{M}{2}$, there exists $N > 0$ such that $|d_{\mathbb{H}}(\phi_N(h), a)| < |q| = \epsilon$, $\forall h \in \mathbb{D}$. Assume for contradiction that $\phi_N(h_1) = h_2$, $|h_1| = |h_2| = 1$. Then, since ϕ_N is continuous there exists $\delta > 0$ such that $|d_{\mathbb{H}}(h_1, h)| < |q| < \delta \implies |d_{\mathbb{H}}(h_2, \phi_N(h))| < |q| < \epsilon$. Thus, $M \leq |d_{\mathbb{H}}(h_2, a)| \leq |d_{\mathbb{H}}(h_2, \phi_N(h))| + |d_{\mathbb{H}}(\phi_N(h), a)| < 2|q| < 2\epsilon = M$. This is not true, so the proof is valid by contradiction. \square

Disclaimer: this technique feels very hand-wavy and I definitely need to put more details in.