# RVOS: End-to-End Recurrent Network for Video Object Segmentation







Miriam Bellver











#### Summary

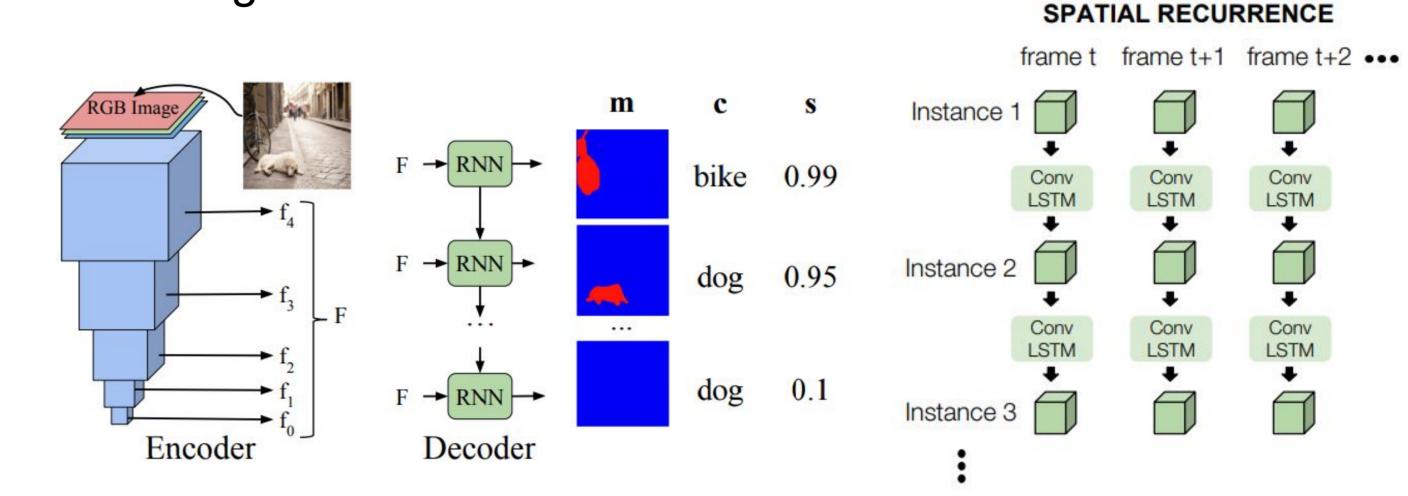
Multiple object video object segmentation is a challenging task, specially for the zero-shot case, when no object mask is given at the initial frame and the model has to find the objects to be segmented along the sequence. In our work, we propose a Recurrent network for multiple object Video Object Segmentation (RVOS) that is fully end-to-end trainable. Our model incorporates recurrence on two different domains: (i) the **spatial**, which allows to discover the different object instances within a frame, and (ii) the temporal, which allows to keep the coherence of the segmented objects along time.

### Previous work: Spatial Recurrence

#### Recurrent Semantic Instance Segmentation (RSIS)

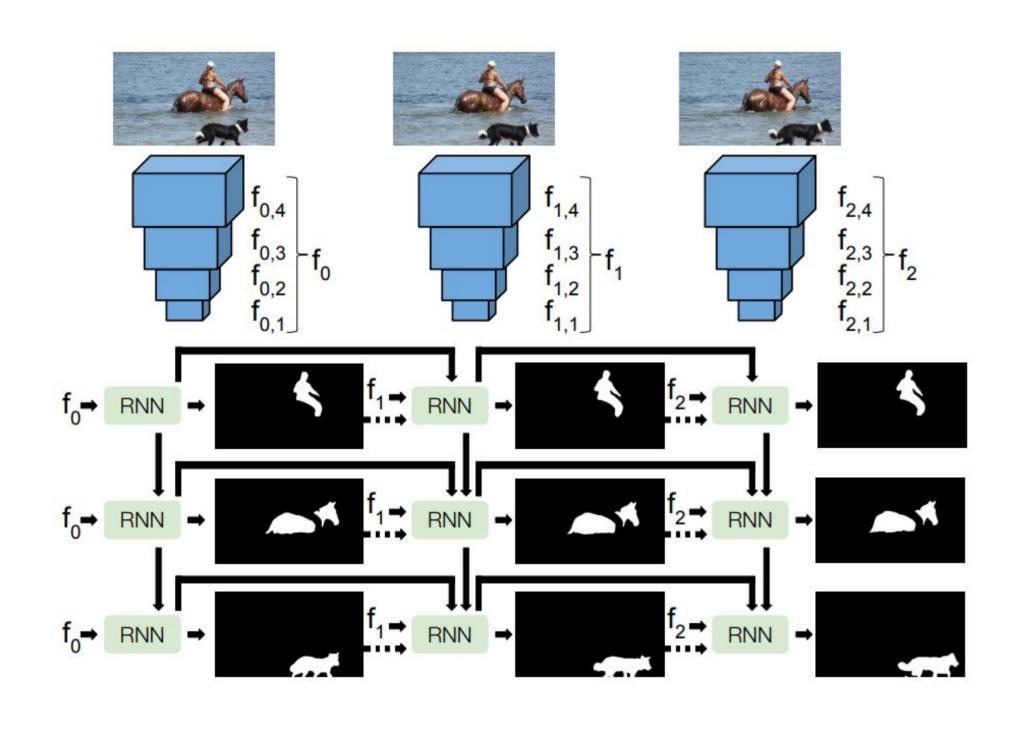
Carles

 Model based on spatial recurrence for instance segmentation in images



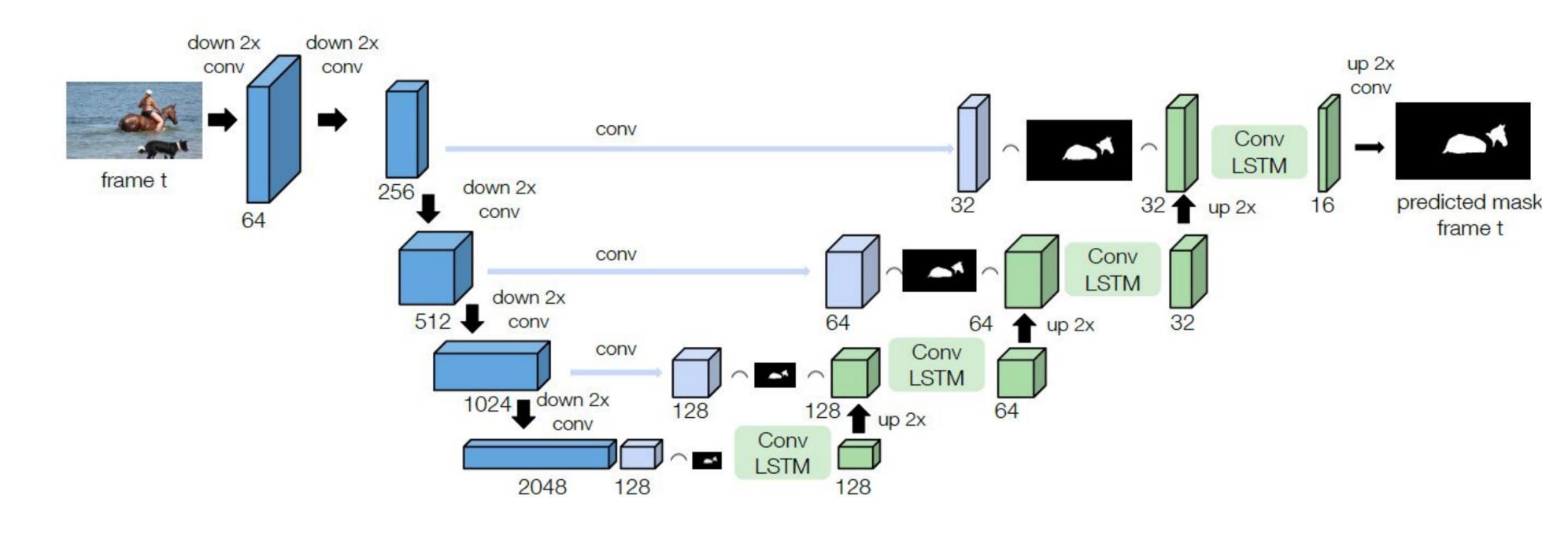
#### Proposed Model: Spatio-temporal Recurrence

We propose to extend RSIS (spatial recurrent model for images) to RVOS (spatio-temporal recurrent model for videos):



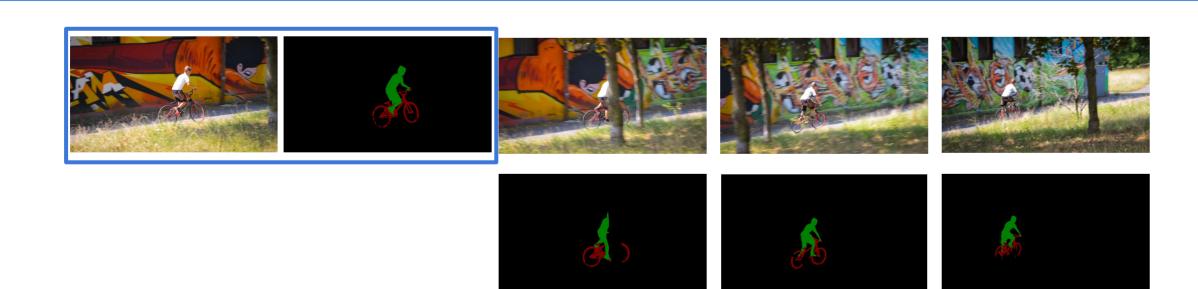
YOUTUBE-VOS

**DAVIS 2017** 



## Experimental Results

#### **ONE-SHOT VIDEO OBJECT SEGMENTATION**

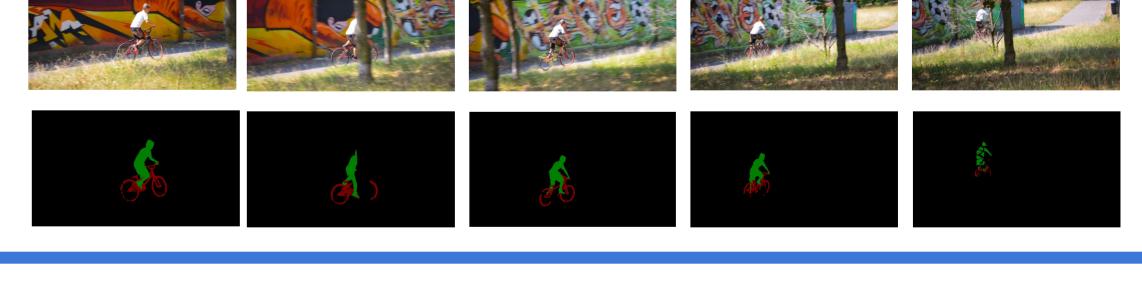


			YouTube-VOS one-shot				
	OL	$J_{seen}$	$J_{unseen}$	$F_{seen}$	$F_{unseen}$	Inference time (s/frame)	
OSVOS [3]	1	59.8	54.2	60.5	60.7	10	
MaskTrack [20]	1	59.9	45.0	59.5	47.9	12	
OnAVOS [30]	1	60.1	46.6	62.7	51.4	13	
S2S w/o OL [33]	X	66.7	48.2	65.5	50.3	0.160	
OSMN [34]	X	60.0	40.6	60.1	44.0	0.065	
RVOS-Mask-ST+	X	63.6	45.5	67.2	51.0	0.044	

You	Tube-VC	OS one-sho	ot
unseen	$F_{seen}$	$F_{unseen}$	Inference time (s/frame)
<b>54.2</b> 45.0 46.6	60.5 59.5 <b>62.7</b>	<b>60.7</b> 47.9 51.4	10 12 13
<b>48.2</b> 40.6 45.5	65.5 60.1 <b>67.2</b>	50.3 44.0 <b>51.0</b>	0.160 0.065 <b>0.044</b>

Ι	<b>DAVIS-2017 one-shot</b> <i>J</i>	
		177
	7.0	54.8
	19.9	55.7
5	52.9	62.1
6	54.5	70.5
3	37.7	44.9
4	12.9	44.2
4	6.4	50.6
4	18.0	52.6

# ZERO-SHOT VIDEO OBJECT SEGMENTATION



	$J_{seen}$	ouTube-VC $J_{unseen}$	OS zero-s $F_{seen}$	shot $F_{unseen}$
RVOS-S	40.8	19.9	43.9	23.2
RVOS-T	37.1	20.2	38.7	21.6
RVOS-ST	44.7	21.2	45.0	23.9

<del>-</del>	DAVIS-2017 zero-shot			R			
	J	F		, i	J		
RVOS-ST (pre) RVOS-ST (ft)	21.7 <b>23.0</b>	27.3 <b>29.9</b>	11-11-				
			Immer aut der s	immer ouf der s	immer auf der Sie	Immer auf der Siegerse	Immer auf der Siegerse

OL

✓ 64.5

OSVOS [3]

CINM [2]

OSMN [34]

FAVOS [4]

RVOS-Mask-ST+ (pre)

RVOS-Mask-ST+ (ft)

OnAVOS [30]

OSVOS-S [17]









