

lm

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0.1 Assignment - 3

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```
In [2]: '''  
        The Leung-Malik (LM) Filter Bank, implementation in python  
  
        T. Leung and J. Malik. Representing and recognizing the visual appearance of  
        materials using three-dimensional textons. International Journal of Computer  
        Vision, 43(1):29-44, June 2001.  
  
        Reference: http://www.robots.ox.ac.uk/~vgg/research/texclass/filters.html  
        '''
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```
import numpy as np  
import cv2  
import matplotlib.pyplot as plt  
import scipy
```

```
In [3]: %matplotlib inline
```

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In [4]: def gaussian1d(sigma, mean, x, ord):  
        x = np.array(x)  
        x_ = x - mean  
        var = sigma**2  
  
        # Gaussian Function  
        g1 = (1/np.sqrt(2*np.pi*var))*(np.exp((-1*x_*x_)/(2*var)))  
  
        if ord == 0:  
            g = g1  
            return g  
        elif ord == 1:  
            g = -g1*((x_)/(var))  
            return g  
        else:  
            g = g1*(((x_*x_) - var)/(var**2))  
            return g
```

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In [5]: def gaussian2d(sup, scales):
        var = scales * scales
        shape = (sup, sup)
        n,m = [(i - 1)/2 for i in shape]
        x,y = np.ogrid[-m:m+1,-n:n+1]
        g = (1/np.sqrt(2*np.pi*var))*np.exp( -(x*x + y*y) / (2*var) )
        return g

In [6]: def log2d(sup, scales):
        var = scales * scales
        shape = (sup, sup)
        n,m = [(i - 1)/2 for i in shape]
        x,y = np.ogrid[-m:m+1,-n:n+1]
        g = (1/np.sqrt(2*np.pi*var))*np.exp( -(x*x + y*y) / (2*var) )
        h = g*((x*x + y*y) - var)/(var**2)
        return h

In [7]: def makefilter(scale, phasex, phasey, pts, sup):

        gx = gaussian1d(3*scale, 0, pts[0,...], phasex)
        gy = gaussian1d(scale, 0, pts[1,...], phasey)

        image = gx*gy

        image = np.reshape(image, (sup, sup))
        return image

In [8]: def makeLMfilters():
        sup = 49
        scalex = np.sqrt(2) * np.array([1,2,3])
        norient = 6
        nrotnv = 12

        nbar = len(scalex)*norient
        nedge = len(scalex)*norient
        nf = nbar+nedge+nrotnv
        F = np.zeros([sup, sup, nf])
        hsup = (sup - 1)/2

        x = [np.arange(-hsup, hsup+1)]
        y = [np.arange(-hsup, hsup+1)]

        [x,y] = np.meshgrid(x,y)

        orgpts = [x.flatten(), y.flatten()]
        orgpts = np.array(orgpts)

        count = 0

```

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for scale in range(len(scalex)):
    for orient in range(norient):
        angle = (np.pi * orient)/norient
        c = np.cos(angle)
        s = np.sin(angle)
        rotpts = [[c+0,-s+0],[s+0,c+0]]
        rotpts = np.array(rotpts)
        rotpts = np.dot(rotpts,orgpts)
        F[:, :,count] = makefilter(scalex[scale], 0, 1, rotpts, sup)
        F[:, :,count+nedge] = makefilter(scalex[scale], 0, 2, rotpts, su
        count = count + 1

count = nbar+nedge
scales = np.sqrt(2) * np.array([1,2,3,4])

for i in range(len(scales)):
    F[:, :,count] = gaussian2d(sup, scales[i])
    count = count + 1

for i in range(len(scales)):
    F[:, :,count] = log2d(sup, scales[i])
    count = count + 1

for i in range(len(scales)):
    F[:, :,count] = log2d(sup, 3*scales[i])
    count = count + 1

return F

```

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In [9]: F = makeLMfilters()
        print F.shape

```

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(49, 49, 48)

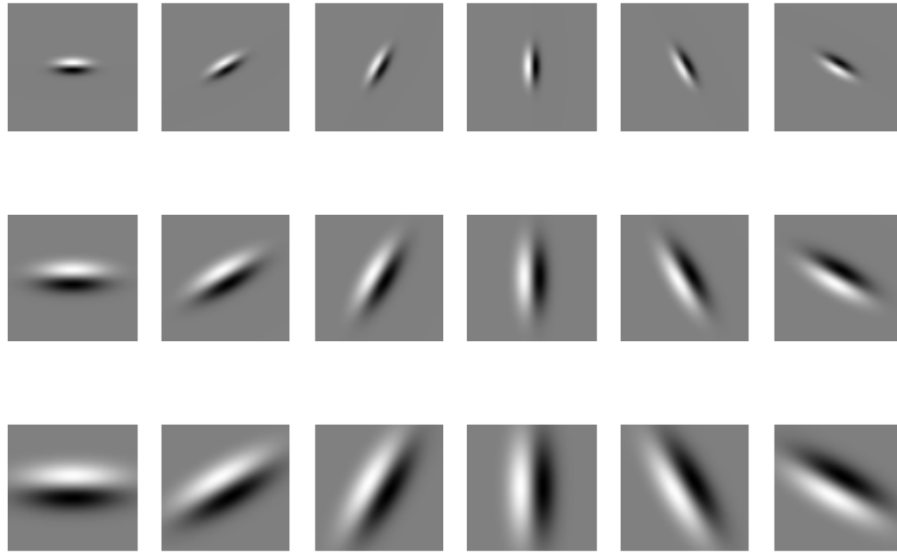
```

0.2 First order derivative Gaussian Filter

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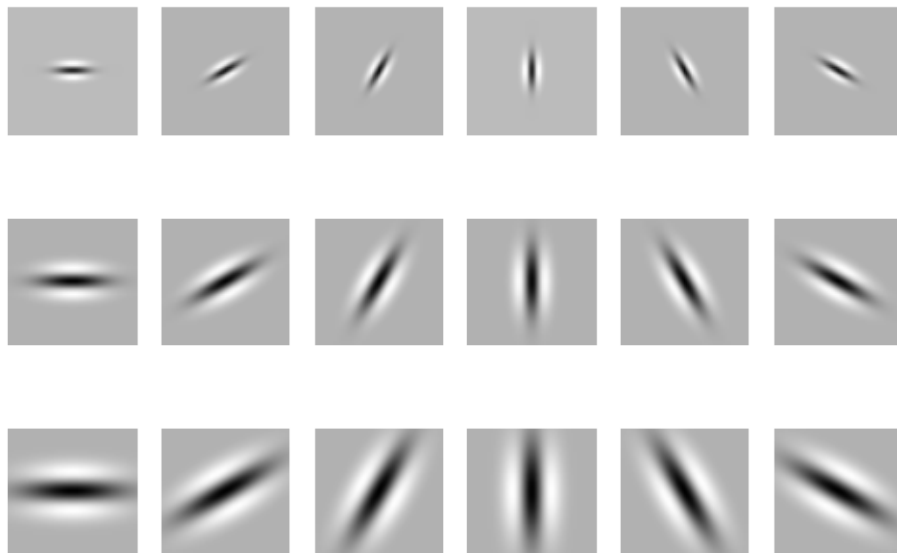
In [10]: for i in range(0,18):
          plt.subplot(3,6,i+1)
          plt.axis('off')
          plt.imshow(F[:, :,i], cmap = 'gray')

```



0.3 Second order derivative Gaussian Filter

```
In [11]: for i in range(0,18):
          plt.subplot(3,6,i+1)
          plt.axis('off')
          plt.imshow(F[:, :, i+18], cmap = 'gray')
```



0.4 Gaussian and Laplacian Filter

```
In [12]: for i in range(0,12):  
          plt.subplot(4,4,i+1)  
          plt.axis('off')  
          plt.imshow(F[:, :, i+36], cmap = 'gray')
```

