Multi-Input Multi-Output Electric Motor Signal Prediction using Neural Networks

Sagar Verma

Centre de Vision Numérique, Centralesupélec, Gif-sur-Yvette

December, 2018

Table Of Contents

- 1. Dataset
- 2. Experiments
- 3. Results
- 4. Questions

What we discussed in the last meeting?

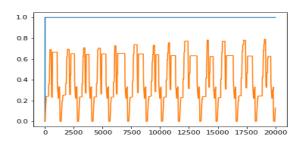
- 1. Problem definition
- 2. Neural networks introduction
- 3. Early results on public dataset
- 4. Error in predicting impulse peeks
- 5. Prediction scaling problem

Dataset Description

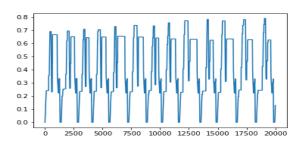
- 1. Single experiment
- 2. 1200 seconds long
- 3. Simulink dq-frame model is used

Dataset

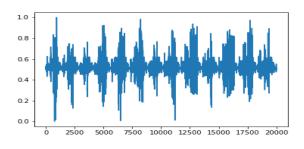
Voltages



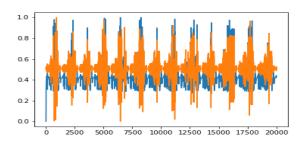
Dataset Stator Pulse



Dataset Speed

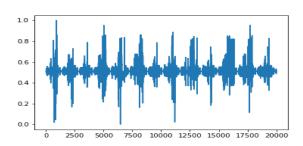


Dataset Currents



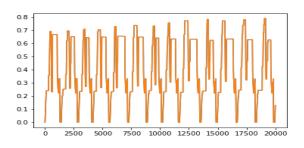
Dataset

Torque



Dataset

Voltage2 and Stator Pulse



Dataset Train-Test Split

- 1. Single experiment
- 2. Biased if the split is 0-800s and 800-1200s
- 3. Random sampling
 - 3.1 Take window w with stride s
 - 3.2 Randomply sample windows
 - 3.3 Train-test cover whole data
 - 3.4 No overlaping b/w train-test

Input selection

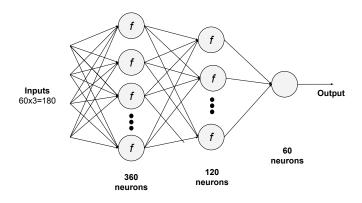
- 1. Use simulking for downsampling
- 2. Stride s = 1,5,10; Works best at stride 1
- 3. Windows sizes that matter, $5 \le w < 10$ and $10 \le w \le 100$
- 4. Ignore voltage 1
- 5. Use either voltage 2 or stator pulse

Output selection

- 1. Don't predict all time steps
- 2. Predict first, middle or last time step
- 3. Middle works better

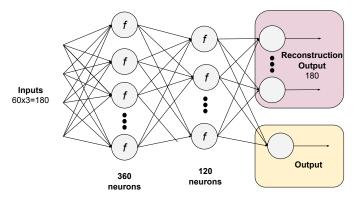
ANN for signal prediction

- 1. Three outputs, three networks.
- 2. Input: $w \times 3$ 1-D vector, Output: 1 middle value
- 3. Activation, f: Leaky Relu



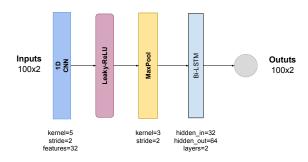
ANN with auxiliary task

- 1. Also reconstruct input signal.
- 2. Three outputs, three networks.
- 3. Input: $w \times 3$ 2-D vector, Output1: 1, output2: $w \times 3$ 2-D vector
- 4. Activation, f: Leaky Relu



Convolution network

- 1. CNN and ANN works better then RNN (Miller et al. 2018).
- 2. Kernels capture $w \leq 10$
- 3. Channel featurization, correlate voltage2 and speed
- 4. Three outputs, three networks.
- 5. Input: $w \times 3$ 2-D vector, Output: 1
- 6. Activation, f: Leaky Relu (in conv)



Results Best Model

Model	w	Current1	Current2	Torque
ANN	100	0.223	0.197	0.101
ANN Aux	100	0.192	0.182	0.112
CNN	100	0.107	0.104	0.091

Table: MSE of different models.

Results

Example Outputs

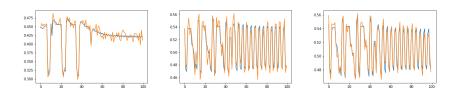


Figure: Left to right: current1, current2, and torque, orange color: predicted

Questions

- 1. Is data very simple?
- 2. When voltage 1 is not constant?
- 3. When Voltage 2 and stator pulse are not same?
- 4. Can signals be grouped into some classes?
- 5. Visual evaluations?
- 6. Other evaluation metrics?
- 7. Predict future(causal)?

Thank you!