

# <sup>1</sup> ROMS-Tools: Reproducible Preprocessing and Analysis for ROMS Simulations

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DOI: [10.xxxxxx/draft](https://doi.org/10.xxxxxx/draft)

## Software

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Submitted: 01 January 1970

Published: unpublished

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## <sup>9</sup> Summary

<sup>10</sup> The ocean regulates Earth's climate and sustains marine ecosystems by circulating and storing heat, carbon, oxygen, and nutrients, while exchanging gases with the atmosphere. Scientists <sup>11</sup> study these processes using ocean models, which simulate the ocean on a grid. **Regional** <sup>12</sup> **ocean models** focus computational resources on a limited geographical area with fine grid <sup>13</sup> spacing, resolving fine-scale phenomena such as mesoscale and submesoscale features, tidal <sup>14</sup> dynamics, coastal currents, upwelling, and detailed biogeochemical (BGC) processes. A widely <sup>15</sup> used regional ocean model is the **Regional Ocean Modeling System (ROMS)** ([Shchepetkin & <sup>16</sup> McWilliams, 2005](#)). ROMS has been coupled to the Marine Biogeochemistry Library (MARBL) <sup>17</sup> ([Long et al., 2021](#); [Molemaker & contributors, 2025a](#)) to link physical and BGC processes. <sup>18</sup> ROMS-MARBL supports research on environmental management, fisheries, regional climate <sup>19</sup> impacts, and ocean-based carbon dioxide removal (CDR) strategies.

<sup>20</sup> Configuring a regional ocean model like ROMS-MARBL is technically challenging. Setting up <sup>21</sup> a model requires initializing and forcing it with oceanic and atmospheric data from multiple <sup>22</sup> external sources in diverse formats, which can reach several petabytes for global datasets. <sup>23</sup> These data must be subsetted, processed, and mapped onto the target domain's geometry, <sup>24</sup> producing input datasets of 10–100 terabytes for large regional models. Generating these <sup>25</sup> input files is time-consuming, error-prone, and hard to reproduce, creating a bottleneck for <sup>26</sup> both new and experienced users. The Python package ROMS-Tools addresses this challenge <sup>27</sup> by providing efficient, task-backed ([Dask Development Team, 2016](#)), user-friendly tools that <sup>28</sup> can be installed via Conda or PyPI and run interactively from Jupyter notebooks. It supports <sup>29</sup> creating regional grids, preprocessing all required model inputs, and postprocessing and analysis. <sup>30</sup> Current capabilities are fully compatible with UCLA-ROMS ([Molemaker & contributors, 2025a, <sup>31</sup> 2025b](#)), with potential support for other ROMS versions, such as Rutgers ROMS ([Arango & <sup>32</sup> contributors, 2024](#)), in the future.

## <sup>34</sup> Input Data and Preprocessing

<sup>35</sup> ROMS-Tools generates the following input files for ROMS-MARBL:

- <sup>36</sup> 1. **Model Grid:** Customizable, curvilinear, and orthogonal grid designed to maintain a nearly <sup>37</sup> uniform horizontal resolution across the domain. The grid is rotatable to align with <sup>38</sup> coastlines and features a terrain-following vertical coordinate.
- <sup>39</sup> 2. **Bathymetry:** Derived from **SRTM15** ([Tozer et al., 2019](#)).
- <sup>40</sup> 3. **Land Mask:** Inferred from coastlines provided by **Natural Earth** or the Global Self-<sup>41</sup> consistent, Hierarchical, High-resolution Geography (**GSHHG**) Database ([Wessel &](#)

Smith, 1996).

4. **Physical Ocean Conditions:** Initial and open boundary conditions for sea surface height, temperature, salinity, and velocities derived from the 1/12° Global Ocean Physics Reanalysis (**GLORYS**) ([Lellouche et al., 2021](#)).
  5. **BGC Ocean Conditions:** Initial and open boundary conditions for dissolved inorganic carbon, alkalinity, and other biogeochemical tracers from Community Earth System Model (**CESM**) output ([Yeager et al., 2022](#)) or hybrid observational-model sources ([Garcia et al., 2019](#); [Huang et al., 2022](#); [Lauvset et al., 2016](#); [Yang et al., 2020](#); [Yeager et al., 2022](#))
  6. **Meteorological forcing:** Wind, radiation, precipitation, and air temperature/humidity processed from the global 1/4° ECMWF Reanalysis v5 (**ERA5**) ([Hersbach et al., 2020](#)) with optional corrections for radiation bias and coastal wind.
  7. **BGC surface forcing:** Partial pressure of carbon dioxide, as well as iron, dust, and nitrogen deposition from **CESM** output ([Yeager et al., 2022](#)) or hybrid observational-model sources ([Hamilton et al., 2022](#); [Kok et al., 2021](#); [Landschützer et al., 2016](#); [Yeager et al., 2022](#)).
  8. **Tidal Forcing:** Tidal potential, elevation, and velocities derived from **TPXO** ([Egbert & Erofeeva, 2002](#)) including self-attraction and loading (SAL) corrections.
  9. **River Forcing:** Freshwater runoff derived from **Dai & Trenberth** ([Dai & Trenberth, 2002](#)) or user-provided custom files.
  10. **CDR Forcing:** User-defined interventions that inject BGC tracers at point sources or as larger-scale Gaussian perturbations, designed to simulate CDR interventions. The CDR forcing provides an external forcing term prescribed as volume and tracer fluxes (e.g., alkalinity for ocean alkalinity enhancement, iron for iron fertilization, or other BGC constituents). Users can specify the magnitude, spatial footprint, and time dependence of the forcing, enabling flexible representation of CDR interventions.

Some source datasets are accessed automatically by the package, including Natural Earth, Dai & Trenberth runoff, and ERA5 meteorology, while users must manually download SRTM15, GSHHG, GLORYS, the BGC datasets, and TPXO tidal files. Although these are the datasets currently supported, the package's modular design makes it straightforward to add new sources in the future.

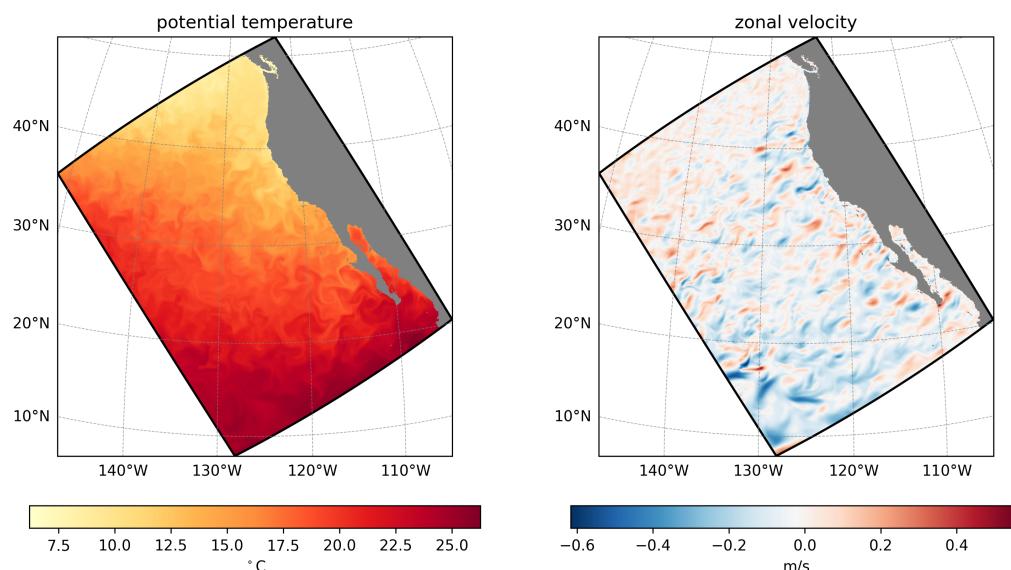
To generate the model inputs, ROMS-Tools automates several intermediate processing steps, including:

- **Bathymetry processing:** The bathymetry is smoothed in two stages, first across the entire model domain and then locally in areas with steep slopes, to ensure local steepness ratios do not exceed a prescribed threshold in order to reduce pressure-gradient errors. A minimum depth is enforced to prevent water levels from becoming negative during large tidal excursions.
  - **Mask definition:** The land-sea mask is generated by comparing the ROMS grid's horizontal coordinates with a coastline dataset using the `regionmask` package ([Hauser et al., 2024](#)). Enclosed basins are subsequently filled with land.
  - **Land value handling:** Land values are filled via an algebraic multigrid method using `pyamg` ([Bell et al., 2023](#)) prior to horizontal regridding. This extends ocean values into land areas to resolve discrepancies between source data and ROMS land masks, preventing land-originating values from appearing in ocean cells.
  - **Regridding:** Ocean and atmospheric fields are horizontally and vertically regridded from standard latitude-longitude-depth grids to the model's curvilinear grid with a terrain-following vertical coordinate using `xarray` ([Hoyer & Hamman, 2017](#)). Optional sea surface height corrections can be applied, and velocities are rotated to align with the curvilinear ROMS grid.
  - **Longitude conventions:** ROMS-Tools handles differences in longitude conventions, converting between  $[-180^\circ, 180^\circ]$  and  $[0^\circ, 360^\circ]$  as needed.
  - **River locations:** Rivers that fall within the model domain are automatically identified

95 and relocated to the nearest coastal grid cell. Rivers that need to be shifted manually or  
 96 span multiple cells can be configured by the user.

97 **▪ Data streaming:** ERA5 atmospheric data can be accessed directly from the cloud,  
 98 removing the need for users to pre-download large datasets locally. Similar streaming  
 99 capabilities may be implemented for other datasets in the future.

100 Users can quickly design and visualize regional grids and inspect all input fields with built-in  
 101 plotting utilities. An example of surface initial conditions generated for a California Current  
 102 System simulation at 5 km horizontal grid spacing is shown in [Figure 1](#).



**Figure 1:** Surface initial conditions for the California Current System created with ROMS-Tools from GLORYS. Left: potential temperature. Right: zonal velocity. Shown for January 1, 2000.

### 103 Postprocessing and Analysis

104 ROMS-Tools provides tools for postprocessing and analyzing ROMS-MARBL output, including  
 105 regridding from the native curvilinear, terrain-following grid to a standard latitude-longitude-  
 106 depth grid using `xesmf` ([Zhuang et al., 2023](#)) and built-in plotting on both grids. The analysis  
 107 layer also includes specialized utilities for evaluating carbon dioxide removal (CDR) interventions,  
 108 such as generating carbon uptake and efficiency curves.

### 109 Statement of Need

110 Setting up a regional ocean model is a major technical undertaking. Traditionally, this  
 111 work relied on a patchwork of custom scripts and lab-specific workflows, which can be time-  
 112 consuming, error-prone, and difficult to reproduce. These challenges slow down science, create  
 113 a steep barrier to entry for new researchers, and limit collaboration across groups.

114 Within the ROMS community, the preprocessing landscape has been shaped by tools like `pyroms`  
 115 ([Hedstrom & contributors, 2023](#)). While providing valuable low-level utilities, `pyroms` presents  
 116 challenges for new users: installation is cumbersome due to Python/Fortran dependencies, the  
 117 API is inconsistent, documentation is limited, and it lacks tests, CI, and support for modern  
 118 Python tools like `xarray` and `dask`. Since active development has largely ceased, its suitability  
 119 for new projects, such as CDR simulations, is limited.

120 Tools from other modeling communities cannot simply be adopted, since each ocean model  
 121 has distinct structural requirements. For example, the new regional-`mom6` package ([Barnes](#)

et al., 2024), developed for the Modular Ocean Model v6 (MOM6) (Adcroft et al., 2019), cannot be used to generate ROMS inputs, because ROMS employs a terrain-following vertical coordinate system that requires a specialized vertical regridding approach, whereas MOM6 accepts inputs on arbitrary depth levels and does not require vertical regridding at all. Several other differences further prevent cross-compatibility. Together, these limitations underscored the need for a modern, maintainable, and reproducible tool designed specifically for ROMS.<sup>1</sup>

ROMS-Tools was developed to meet this need. It draws on the legacy of the MATLAB preprocessing scripts developed at UCLA (Molemaker, 2024), which encapsulate decades of expertise in configuring regional ocean model inputs. While many of the core algorithms and design principles are retained, ROMS-Tools provides an open-source Python implementation of these MATLAB tools using an object-oriented programming paradigm. This implementation enables a modernized workflow driven by high-level user API calls, enhancing reproducibility, reducing the potential for user errors, and supporting extensibility for additional features, forcing datasets, and use cases. In some cases, ROMS-Tools diverges from the MATLAB implementation to take advantage of new methods or better integration with the modern Python ecosystem. By streamlining input generation and analysis, ROMS-Tools reduces technical overhead, lowers the barrier to entry, and enables scientists to focus on research rather than data preparation.

## Software Design

ROMS-Tools is designed to balance **ease of use, flexibility, reproducibility, and scalability** in regional ocean modeling workflows, providing both high-level user interfaces and a modular, extensible architecture that supports efficient data handling, customizable workflows, and scalable computation.

### Design Trade-Offs

A central design trade-off in ROMS-Tools is between **automation** and **user control**. Rather than enforcing a fixed workflow, the package exposes key choices, such as physical options (e.g., radiation or wind corrections), interpolation and fill methods, and computational backends. This contrasts with more opinionated frameworks that fix defaults and directory structures to maximize automation. While users make explicit decisions, some steps remain automated to prevent errors; for example, bathymetry smoothing is applied automatically with a non-tunable parameter, since overly small smoothing factors could produce rough bathymetry and crash simulations. This approach balances flexibility and safety, enabling transparent experimentation without exposing users to avoidable pitfalls.

Another key trade-off is between **monolithic workflows** and **incremental, modular steps**. ROMS-Tools uses small, composable components, such as generating initial conditions, boundary forcing, and surface forcing. Each component can be executed, saved, and revisited independently. This avoids unnecessary recomputation when only some inputs change. To ensure reproducibility despite a modular workflow, configuration choices are stored in compact, text-based YAML files. These files are version-controllable, easy to share, and remove the need to transfer large model input NetCDF datasets.

### Architecture and Rationale

At the user-facing level, ROMS-Tools provides high-level objects such as Grid, InitialConditions, and BoundaryForcing. Each object exposes a consistent interface (.ds, .plot(), .save(), .to\_yaml()), so users can always call the same methods in sequence or inspect attributes that are guaranteed to exist. This object-oriented design reduces cognitive overhead and makes workflows predictable and easy to follow.

<sup>1</sup>In the future, packages like ROMS-Tools and regional-mom6 could share a common backbone, with model-specific adaptations layered on top.

167 Internally, ROMS-Tools uses a **layered, modular architecture**. Abstract base classes  
168 (`LatLonDataset`, `ROMSDataset`) handle data ingestion and preprocessing. Source-specific  
169 datasets (e.g., `ERA5Dataset`, `GLORYSDataset`, `SRTMDataset`) inherit from these base classes  
170 and encode dataset-specific conventions, such as variable names, coordinates, and masking.  
171 Common operations, like subdomain selection and lateral filling, are implemented once and  
172 reused across datasets. Adding a new data source usually requires only a small subclass to  
173 define variable mappings while reusing the existing subsetting, filling, regridding, and I/O logic.  
174 This approach keeps changes to the core code minimal.

## 175 Computational and Data Model Choices

176 ROMS-Tools is built on `xarray`, which lets users take advantage of its clear, consistent interface  
177 for exploring and inspecting datasets. The package integrates seamlessly with the broader  
178 Pangeo ecosystem. Optional dask support ([Dask Development Team, 2016](#)) allows workflows  
179 to scale from a laptop to HPC systems, enabling parallel and out-of-core computation for very  
180 large input and output datasets.

## 181 Research Impact Statement

182 ROMS-Tools serves two primary user communities. First, ocean modelers developing new  
183 regional domains rely on it to generate input datasets for ROMS simulations. External users  
184 in this category include researchers at **PNNL**, **WHOI**, **UCLA**, and in **New Zealand and**  
185 **Australia**. Second, researchers in the ocean-based carbon dioxide removal (CDR) community  
186 use ROMS-Tools to set up reproducible ROMS-MARBL simulations of climate intervention  
187 scenarios, with adopters such as **[C]Worthy**, **Carbon to Sea**, **Ebb Carbon**, and **SCCWRP**. All  
188 of these users have contacted the developers directly or consulted offline regarding their use of  
189 the package.

190 Broader engagement is evident from GitHub stars, with users from institutions including the  
191 University of Waikato, NCAR, University of Maryland, National Oceanography Centre, Fathom  
192 Science, McGill University, Gwangju Institute of Science and Technology, UC Santa Cruz,  
193 RedLine Performance Solutions, and Submarine.

194 ROMS-Tools is also integrated into broader workflows, including **C-Star**, an open-source platform  
195 to provide scientifically credible monitoring, reporting, and verification (MRV) for the emerging  
196 marine carbon market.

## 197 AI usage disclosure

198 Generative AI tools were used to assist with writing docstrings and developing tests for the  
199 ROMS-Tools software, to improve the clarity and readability of the documentation, and to  
200 shorten and edit portions of the manuscript text. All AI-assisted content was reviewed and  
201 verified by the authors for technical accuracy and correctness.

## 202 Acknowledgements

203 Development of ROMS-Tools has been supported by ARPA-E (DE-AR0001838) and  
204 philanthropic donations to **[C]Worthy** from the Grantham Foundation for the Environment,  
205 the Chan Zuckerberg Initiative, Founders Pledge, and the Ocean Resilience Climate Alliance.

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