

¹ ROMS-Tools: A Python Package for Preparing and ² Analyzing ROMS Simulations

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⁹ Summary

¹⁰ The ocean shapes Earth's climate and sustains marine ecosystems by circulating vast amounts
¹¹ of heat, oxygen, carbon, and nutrients, while exchanging heat and gases with the atmosphere.
¹² To understand these complex dynamics and processes, scientists rely on ocean models, powerful
¹³ computer simulations of physical circulation and biogeochemical (BGC) dynamics. These
¹⁴ models represent the ocean on a grid of cells, where higher resolution (more, smaller cells)
¹⁵ provides greater detail but requires significantly more computing power. While global ocean
¹⁶ models simulate the entire ocean, **regional ocean models** focus computational resources on a
¹⁷ specific area to achieve much higher resolution. This increased resolution enables regional ocean
¹⁸ models to explicitly resolve fine-scale processes like mesoscale (10–100 km) and submesoscale
¹⁹ (0.1–10 km) features, tidal dynamics, coastal currents, upwelling, and detailed BGC cycles.
²⁰ Capturing these processes is essential for applications in environmental management, fisheries,
²¹ and for assessing regional impacts of climate change.

²² A widely used regional ocean model is the **Regional Ocean Modeling System (ROMS)**
²³ ([Shchepetkin & McWilliams, 2005](#)). To connect physical circulation with ecosystem dynamics
²⁴ and the ocean carbon cycle, ROMS can be coupled to a BGC model, for example the Marine
²⁵ Biogeochemistry Library (MARBL) ([Long et al., 2021](#)). This coupled framework allows
²⁶ researchers to explore how physical processes drive ecosystem dynamics, such as how nutrient-
²⁷ rich waters from upwelling fuel the phytoplankton blooms that form the base of the marine
²⁸ food web ([Gruber et al., 2006](#)).

²⁹ Yet configuring a regional ocean model like ROMS-MARBL remains a major challenge. Generating
³⁰ the required input files is time-consuming, error-prone, and difficult to reproduce, creating
³¹ a bottleneck for both new and experienced researchers. The Python package ROMS-Tools
³² addresses this challenge by providing an efficient, user-friendly, and reproducible workflow to
³³ generate all required inputs, including:

- ³⁴ ▪ **Model Grid:** A customizable, curvilinear grid that can be rotated to align with coastlines
and with a terrain-following vertical coordinate.
- ³⁵ ▪ **Bathymetry and Land Mask:** High-resolution seafloor depth from **SRTM15** ([Tozer et
al., 2019](#)) and a corresponding land-sea mask from **Natural Earth**.
- ³⁶ ▪ **Initial Conditions and Boundary Forcing:** Physical state variables (temperature, velocities,
etc.) from **GLORYS** ([Lellouche et al., 2021](#)) and BGC fields (e.g., alkalinity) from hybrid
observational-model sources.
- ³⁷ ▪ **Atmospheric Forcing:** Meteorological drivers (wind, radiation, precipitation) from ERA5
([Hersbach et al., 2020](#)) and surface BGC forcing (pCO₂, dust, nitrogen deposition) from
hybrid observational-model sources.

- 44 ▪ **Tidal Forcing:** Tidal potential, elevation, and velocities derived from **TPXO** ([Egbert &](#)
45 [Erofeeva, 2002](#)) including corrections for self-attraction and loading (SAL).
- 46 ▪ **River Forcing:** Freshwater runoff from **Dai & Trenberth** ([Dai & Trenberth, 2002](#)) or
47 custom user-provided files.
- 48 ▪ **CDR Forcing:** Flexible user-defined tracers for Carbon Dioxide Removal (CDR) or other
49 interventions.

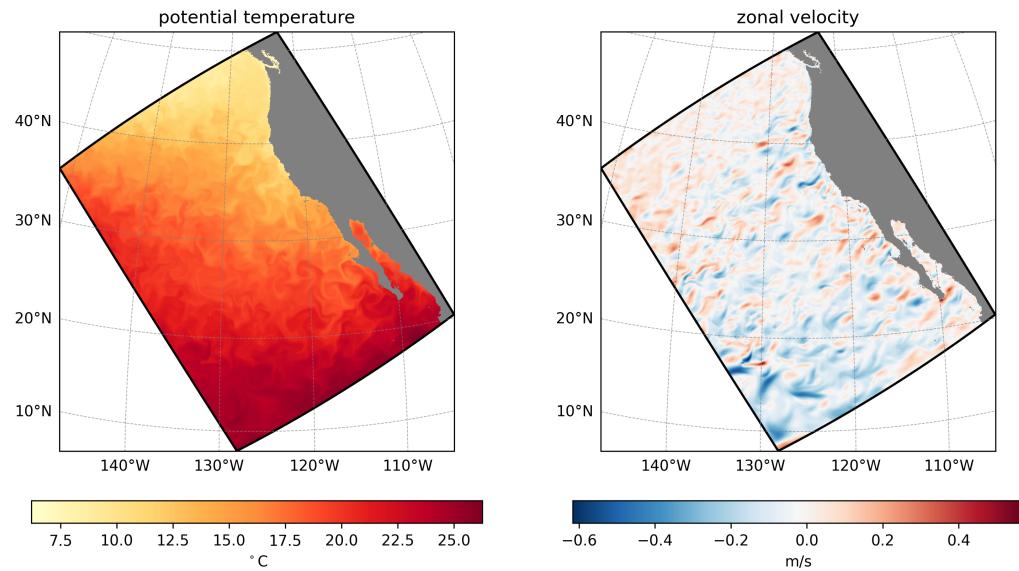


Figure 1: Surface initial conditions for the California Current System created with ROMS-Tools from GLORYS. Left: potential temperature. Right: zonal velocity. Shown for January 1, 2000.

50 An example of the generated inputs is shown in Figure [Figure 1](#), which illustrates surface initial
51 conditions for the California Current System created with ROMS-Tools.

52 While generating input files, ROMS-Tools automates several complex intermediate processing
53 steps. It efficiently fills land values in the input data via an algebraic multigrid method using
54 `pyamg` ([Bell et al., 2023](#)). It then performs horizontal and vertical regridding from standard
55 lat-lon-depth grids to the model's curvilinear grid with terrain-following vertical coordinate
56 using libraries like `xarray` ([Hoyer & Hamman, 2017](#)) and `xgcm` ([Busecke & contributors, 2025](#)).
57 The workflow also applies bathymetry smoothing to reduce pressure-gradient errors, handles
58 longitude conversions (between -180° to 180° and 0° to 360°), and formats all NetCDF outputs
59 with the metadata expected by ROMS-MARBL. Currently, ROMS-Tools fully supports UCLA-
60 ROMS ([Molemaker & contributors, 2025](#)); support for other versions, such as Rutgers ROMS
61 ([Arango & contributors, 2024](#)), may be added in the future with community contributions. A
62 notable feature is the ability to stream ERA5 data directly from the cloud, so users do not need
63 to download the data beforehand. ROMS-Tools offers functionality for partitioning input files,
64 a requirement for parallelized ROMS simulations across multiple nodes. Additionally, it can
65 recombine the partitioned model output files. For analysis, the package includes postprocessing
66 utilities for generating plots, performing specialized tasks useful for CDR monitoring, reporting,
67 and verification, and regridding model output from the native ROMS grid to a standard
68 lat-lon-depth grid using `xesmf` ([Zhuang et al., 2023](#)).

69 ROMS-Tools is designed to support modern, reproducible workflows. It is easily installable via
70 Conda and PyPI and can be run interactively from Jupyter Notebooks. To ensure reproducibility
71 and facilitate collaboration, each workflow is defined in a simple YAML configuration file.
72 These compact, text-based YAML files can be version-controlled and easily shared, eliminating
73 the need to transfer large NetCDF files between researchers. For performance, the package
74 is integrated with dask ([Dask Development Team, 2016](#)) to enable efficient, out-of-core

75 computations on large datasets. Finally, to guarantee reliability, the software is rigorously
76 tested with continuous integration (CI) and supported by comprehensive documentation.

77 Statement of need

78 Setting up a regional ocean model is a major undertaking. It requires generating a wide range
79 of complex input files, including the model grid, initial and boundary conditions, and forcing
80 from the atmosphere, tides, and rivers. Traditionally, this work has depended on a patchwork
81 of custom scripts and lab-specific workflows, a fragmented approach that is time-consuming,
82 error-prone, and difficult to reproduce. These challenges slow down science, create a steep
83 barrier to entry for new researchers, and limit collaboration across groups.

84 Within the ROMS community, the preprocessing landscape has been shaped by tools like
85 pyroms ([Hedstrom & contributors, 2023](#)). While pyroms has long provided valuable low-level
86 utilities, it also presents challenges for new users. Installation can be cumbersome due to its
87 Python and Fortran dependencies, and its inconsistent API and limited documentation make it
88 harder to learn. The package was not designed with reproducible workflows in mind, and it lacks
89 tests, continuous integration, and support for modern Python tools such as xarray and dask.
90 Since development of pyroms has largely ceased, its suitability for new projects is increasingly
91 limited. Importantly, tools from other modeling communities cannot simply be adapted, since
92 each ocean model has distinct structural requirements. For example, the new regional-mom6
93 package ([Barnes et al., 2024](#)), developed for MOM6 ([Adcroft et al., 2019](#)), cannot be used
94 to generate ROMS inputs, because ROMS employs a terrain-following vertical coordinate
95 system that requires a fundamentally different regridding approach, whereas MOM6 accepts
96 inputs on arbitrary depth levels. Several other differences further prevent cross-compatibility.
97 Together, these limitations underscored the need for a modern, maintainable, and reproducible
98 tool designed specifically for ROMS.

99 ROMS-Tools was developed to meet this need. It draws on the legacy of the UCLA MATLAB
100 preprocessing scripts ([Molemaker, 2024](#)), which encapsulate decades of community expertise
101 in configuring regional ocean model inputs. While many of the core algorithms and design
102 principles are retained, ROMS-Tools reimplements them in Python, where it modernizes the
103 workflow, adopts object-oriented programming, and improves reproducibility. In some cases,
104 it diverges from the MATLAB implementation to take advantage of new methods or better
105 integration with the modern Python ecosystem. By streamlining input generation and analysis,
106 ROMS-Tools reduces technical overhead, lowers the barrier to entry, and enables scientists to
107 focus on research rather than data preparation. While designed for ocean modelers developing
108 new domains, the package is also gaining traction in the Carbon Dioxide Removal (CDR)
109 community, where it enables testing of different climate intervention scenarios within existing,
110 well-validated model setups.

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