

ROMS-Tools: A Python Package for Preparing and Analyzing ROMS Simulations

Nora Loose¹, Tom Nicholas², Scott Eilerman¹, Christopher McBride¹, Sam Maticka¹, Dafydd Stephenson¹, Scott Bachman¹, Pierre Damien³, Ulla Heede¹, Alicia Karspeck¹, Matt Long¹, Jeroen Molemaker³, and Abigale Wyatt¹

¹ [C]Worthy LLC, Boulder, CO, United States ² Earthmover ³ University of California, Los Angeles, CA, United States

DOI: [10.xxxxxx/draft](https://doi.org/10.xxxxxx/draft)

Software

- [Review](#)
- [Repository](#)
- [Archive](#)

Editor: [Open Journals](#)

Reviewers:

- [@openjournals](#)

Submitted: 01 January 1970

Published: unpublished

License

Authors of papers retain copyright and release the work under a

Creative Commons Attribution 4.0

International License ([CC BY 4.0](#))

Summary

The ocean shapes Earth's climate and sustains marine ecosystems by circulating vast amounts of heat, oxygen, carbon, and nutrients, while exchanging heat and gases with the atmosphere. To understand these complex dynamics and processes, scientists rely on ocean models, powerful computer simulations of physical circulation and biogeochemical (BGC) dynamics. These models represent the ocean on a grid of cells, where higher resolution (more, smaller cells) provides greater detail but requires significantly more computing power. While global ocean models simulate the entire ocean, **regional ocean models** focus computational resources on a specific area to achieve much higher resolution. This increased resolution enables regional ocean models to explicitly resolve fine-scale processes like mesoscale (10-100 km) and submesoscale (0.1-10 km) features, tidal dynamics, coastal currents, upwelling, and detailed BGC cycles. Capturing these processes is essential for applications in environmental management, fisheries, and for assessing regional impacts of climate change.

A widely used regional ocean model is the **Regional Ocean Modeling System (ROMS)** (Shchepetkin & McWilliams, 2005). To connect physical circulation with ecosystem dynamics and the ocean carbon cycle, ROMS can be coupled to a BGC model, for example the Marine Biogeochemistry Library (MARBL) (Long et al., 2021). This coupled framework allows researchers to explore how physical processes drive ecosystem dynamics, such as how nutrient-rich waters from upwelling fuel the phytoplankton blooms that form the base of the marine food web (Gruber et al., 2006).

Yet configuring a regional ocean model like ROMS-MARBL remains a major challenge. Generating the required input files is time-consuming, error-prone, and difficult to reproduce, creating a bottleneck for both new and experienced researchers. The Python package ROMS-Tools addresses this challenge by providing an efficient, user-friendly, and reproducible workflow to generate all required inputs, including:

- Model Grid:** A customizable, curvilinear grid that can be rotated to align with coastlines and with a terrain-following vertical coordinate.
- Bathymetry and Land Mask:** High-resolution seafloor depth from **SRTM15** (Tozer et al., 2019) and a corresponding land-sea mask from **Natural Earth**.
- Initial Conditions and Boundary Forcing:** Physical state variables (temperature, velocities, etc.) from **GLORYS** (Lellouche et al., 2021) and BGC fields (e.g., alkalinity) from hybrid observational-model sources.
- Atmospheric Forcing:** Meteorological drivers (wind, radiation, precipitation) from **ERA5** (Hersbach et al., 2020) and surface BGC forcing (pCO₂, dust, nitrogen deposition) from hybrid observational-model sources.

- 44 ■ **Tidal Forcing:** Tidal potential, elevation, and velocities derived from TPXO (Egbert & Erofeeva, 2002) including corrections for self-attraction and loading (SAL).
- 45
- 46 ■ **River Forcing:** Freshwater runoff from Dai & Trenberth (Dai & Trenberth, 2002) or custom user-provided files.
- 47
- 48 ■ **CDR Forcing:** Flexible user-defined tracers for Carbon Dioxide Removal (CDR) or other interventions.
- 49

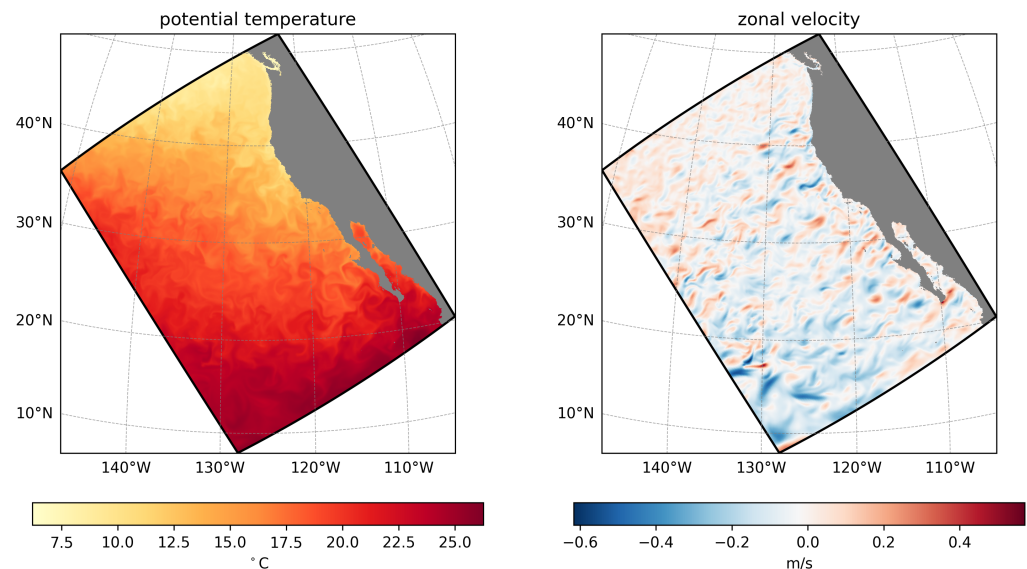


Figure 1: Surface initial conditions for the California Current System created with ROMS-Tools from GLORYS. Left: potential temperature. Right: zonal velocity. Shown for January 1, 2000.

50 An example of the generated inputs is shown in Figure Figure 1, which illustrates surface initial
51 conditions for the California Current System created with ROMS-Tools.

52 While generating input files, ROMS-Tools automates several complex intermediate processing
53 steps. It efficiently fills land values in the input data via an algebraic multigrid method using
54 pyang (Bell et al., 2023). It then performs horizontal and vertical regridding from standard
55 lat-lon-depth grids to the model's curvilinear grid with terrain-following vertical coordinate
56 using libraries like xarray (Hoyer & Hamman, 2017) and xgcm (Busecke & contributors, 2025).
57 The workflow also applies bathymetry smoothing to reduce pressure-gradient errors, handles
58 longitude conversions (between -180° to 180° and 0° to 360°), and formats all NetCDF outputs
59 with the metadata expected by ROMS-MARBL. Currently, ROMS-Tools fully supports UCLA-
60 ROMS (Molemaker & contributors, 2025); support for other versions, such as Rutgers ROMS
61 (Arango & contributors, 2024), may be added in the future with community contributions. A
62 notable feature is the ability to stream ERA5 data directly from the cloud, so users do not need
63 to download the data beforehand. ROMS-Tools offers functionality for partitioning input files,
64 a requirement for parallelized ROMS simulations across multiple nodes. Additionally, it can
65 recombine the partitioned model output files. For analysis, the package includes postprocessing
66 utilities for generating plots, performing specialized tasks useful for CDR monitoring, reporting,
67 and verification, and regridding model output from the native ROMS grid to a standard
68 lat-lon-depth grid using xesmf (Zhuang et al., 2023).

69 ROMS-Tools is designed to support modern, reproducible workflows. It is easily installable via
70 Conda and PyPI and can be run interactively from Jupyter Notebooks. To ensure reproducibility
71 and facilitate collaboration, each workflow is defined in a simple YAML configuration file.
72 These compact, text-based YAML files can be version-controlled and easily shared, eliminating
73 the need to transfer large NetCDF files between researchers. For performance, the package
74 is integrated with dask (Dask Development Team, 2016) to enable efficient, out-of-core

75 computations on large datasets. Finally, to guarantee reliability, the software is rigorously
76 tested with continuous integration (CI) and supported by comprehensive documentation.

77 Statement of need

78 Setting up a regional ocean model is a major undertaking. It requires generating a wide range
79 of complex input files, including the model grid, initial and boundary conditions, and forcing
80 from the atmosphere, tides, and rivers. Traditionally, this work has depended on a patchwork
81 of custom scripts and lab-specific workflows, a fragmented approach that is time-consuming,
82 error-prone, and difficult to reproduce. These challenges slow down science, create a steep
83 barrier to entry for new researchers, and limit collaboration across groups.

84 Within the ROMS community, the preprocessing landscape has been shaped by tools like
85 `pyroms` (Hedstrom & contributors, 2023). While `pyroms` has long provided valuable low-level
86 utilities, it also presents challenges for new users. Installation can be cumbersome due to its
87 Python and Fortran dependencies, and its inconsistent API and limited documentation make it
88 harder to learn. The package was not designed with reproducible workflows in mind, and it lacks
89 tests, continuous integration, and support for modern Python tools such as `xarray` and `dask`.
90 Since development of `pyroms` has largely ceased, its suitability for new projects is increasingly
91 limited. Importantly, tools from other modeling communities cannot simply be adapted, since
92 each ocean model has distinct structural requirements. For example, the new regional-mom6
93 package (Barnes et al., 2024), developed for MOM6 (Adcroft et al., 2019), cannot be used
94 to generate ROMS inputs, because ROMS employs a terrain-following vertical coordinate
95 system that requires a fundamentally different regridding approach, whereas MOM6 accepts
96 inputs on arbitrary depth levels. Several other differences further prevent cross-compatibility.
97 Together, these limitations underscored the need for a modern, maintainable, and reproducible
98 tool designed specifically for ROMS.

99 ROMS-Tools was developed to meet this need. It draws on the legacy of the UCLA MATLAB
100 preprocessing scripts (Molemaker, 2024), which encapsulate decades of community expertise
101 in configuring regional ocean model inputs. While many of the core algorithms and design
102 principles are retained, ROMS-Tools reimplements them in Python, where it modernizes the
103 workflow, adopts object-oriented programming, and improves reproducibility. In some cases,
104 it diverges from the MATLAB implementation to take advantage of new methods or better
105 integration with the modern Python ecosystem. By streamlining input generation and analysis,
106 ROMS-Tools reduces technical overhead, lowers the barrier to entry, and enables scientists to
107 focus on research rather than data preparation. While designed for ocean modelers developing
108 new domains, the package is also gaining traction in the Carbon Dioxide Removal (CDR)
109 community, where it enables testing of different climate intervention scenarios within existing,
110 well-validated model setups.

111 Acknowledgements

112 Acknowledgement of any financial support.

113 References

- 114 Adcroft, A., Anderson, W., Balaji, V., Blanton, C., Bushuk, M., Dufour, C. O., Dunne, J.
115 P., Griffies, S. M., Hallberg, R., Harrison, M. J., Held, I. M., Jansen, M. F., John, J. G.,
116 Krasting, J. P., Langenhorst, A. R., Legg, S., Liang, Z., McHugh, C., Radhakrishnan,
117 A., ... Zhang, R. (2019). The GFDL Global Ocean and Sea Ice Model OM4.0: Model
118 Description and Simulation Features. *Journal of Advances in Modeling Earth Systems*,
119 11(10), 3167–3211. <https://doi.org/10.1029/2019MS001726>

- Arango, H., & contributors. (2024). Rutgers ROMS. In *GitHub repository*. GitHub. <https://github.com/myroms/roms>
- Barnes, A. J., Constantinou, N. C., Gibson, A. H., Kiss, A. E., Chapman, C., Reilly, J., Bhagtani, D., & Yang, L. (2024). Regional-mom6: A Python package for automatic generation of regional configurations for the Modular Ocean Model 6. *Journal of Open Source Software*, 9(100), 6857. <https://doi.org/10.21105/joss.06857>
- Bell, N., Olson, L. N., Schroder, J., & Southworth, B. (2023). PyAMG: Algebraic multigrid solvers in python. *Journal of Open Source Software*, 8(87), 5495. <https://doi.org/10.21105/joss.05495>
- Busecke, J., & contributors. (2025). Xgcm. In *GitHub repository*. GitHub. <https://github.com/xgcm/xgcm>
- Dai, A., & Trenberth, K. E. (2002). *Estimates of Freshwater Discharge from Continents: Latitudinal and Seasonal Variations*. https://journals.ametsoc.org/view/journals/hydr/3/6/1525-7541_2002_003_0660_eofdfc_2_0_co_2.xml
- Dask Development Team. (2016). *Dask: Library for dynamic task scheduling*. <http://dask.pydata.org>
- Egbert, G. D., & Erofeeva, S. Y. (2002). Efficient Inverse Modeling of Barotropic Ocean Tides. *Journal of Atmospheric and Oceanic Technology*, 19(2), 183–204. [https://doi.org/10.1175/1520-0426\(2002\)019%3C0183:EIMOBO%3E2.0.CO;2](https://doi.org/10.1175/1520-0426(2002)019%3C0183:EIMOBO%3E2.0.CO;2)
- Gruber, N., Frenzel, H., Doney, S. C., Marchesiello, P., McWilliams, J. C., Moisan, J. R., Oram, J. J., Plattner, G.-K., & Stolzenbach, K. D. (2006). Eddy-resolving simulation of plankton ecosystem dynamics in the California Current System. *Deep Sea Research Part I: Oceanographic Research Papers*, 53(9), 1483–1516. <https://doi.org/10.1016/j.dsr.2006.06.005>
- Hedstrom, K., & contributors. (2023). Pyroms. In *GitHub repository*. GitHub. <https://github.com/ESMG/pyroms>
- Hersbach, H., Bell, B., Berrisford, P., Hirahara, S., Horányi, A., Muñoz-Sabater, J., Nicolas, J., Peubey, C., Radu, R., Schepers, D., Simmons, A., Soci, C., Abdalla, S., Abellan, X., Balsamo, G., Bechtold, P., Biavati, G., Bidlot, J., Bonavita, M., ... Thépaut, J.-N. (2020). The ERA5 global reanalysis. *Quarterly Journal of the Royal Meteorological Society*, 146(730), 1999–2049. <https://doi.org/https://doi.org/10.1002/qj.3803>
- Hoyer, S., & Hamman, J. (2017). Xarray: ND labeled arrays and datasets in python. *Journal of Open Research Software*, 5(1). <https://doi.org/10.5334/jors.148>
- Lellouche, E., Jean-Michel Greiner, Bourdallé-Badie, R., Garric, G., Melet, A., Drévillon, M., Bricaud, C., Hamon, M., Le Galloudec, O., Regnier, C., Candela, T., Testut, C.-E., Gasparin, F., Ruggiero, G., Benkiran, M., Drillet, Y., & Le Traon, P.-Y. (2021). The Copernicus Global 1/12° Oceanic and Sea Ice GLORYS12 Reanalysis. *Frontiers in Earth Science*, 9. <https://doi.org/10.3389/feart.2021.698876>
- Long, M. C., Moore, J. K., Lindsay, K., Levy, M., Doney, S. C., Luo, J. Y., Krumhardt, K. M., Letscher, R. T., Grover, M., & Sylvester, Z. T. (2021). *Simulations With the Marine Biogeochemistry Library (MARBL)*. <https://doi.org/10.1029/2021MS002647>
- Molemaker, J. (2024). UCLA MATLAB tools. In *GitHub repository*. GitHub. <https://github.com/nmolem/ucla-tools>
- Molemaker, J., & contributors. (2025). UCLA-ROMS. In *GitHub repository*. GitHub. <https://github.com/CESR-lab/ucla-roms>
- Shchepetkin, A. F., & McWilliams, J. C. (2005). The regional oceanic modeling system (ROMS): A split-explicit, free-surface, topography-following-coordinate oceanic model.

- 167 *Ocean Modelling*, 9(4), 347–404. <https://doi.org/10.1016/j.ocemod.2004.08.002>
- 168 Tozer, B., Sandwell, D. T., Smith, W. H. F., Olson, C., Beale, J. R., & Wessel, P. (2019).
169 Global Bathymetry and Topography at 15 Arc Sec: SRTM15+. *Earth and Space Science*,
170 6(10), 1847–1864. <https://doi.org/10.1029/2019EA000658>
- 171 Zhuang, J., Dussin, R., Huard, D., Bourgault, P., Banihirwe, A., Raynaud, S., Malevich,
172 B., Schupfner, M., Filipe, Levang, S., Gauthier, C., Jüling, A., Almansi, M., Scott,
173 R., RondeauG, Rasp, S., Smith, T. J., Stachelek, J., Plough, M., & Li, X. (2023).
174 xESMF: Universal regridding for geospatial data. In *GitHub repository*. Zenodo. <https://doi.org/10.5281/zenodo.4294774>
175

DRAFT