



Research Institute for Future Media Computing Institute of Computer Vision
未来媒体技术与研究所 计算机视觉研究所



多媒体系统导论

Fundamentals of Multimedia System

授课教师：文嘉俊

邮箱：wenjiajun@szu.edu.cn

2022年春季课程

■ Outline of Lecture 08

- ◆ Introduction-简介
- ◆ Distortion Measures-失真度量
- ◆ The Rate-Distortion Theory-比率失真理论
- ◆ Quantization-量化
 - Uniform Scalar Quantization-均匀标量量化
 - Nonuniform Scalar Quantization-非均匀标量量化
 - Vector Quantization-向量量化
- ◆ Transform Coding-变换编码
- ◆ Wavelet-Based Coding-小波编码
- ◆ Experiments-实验

Introduction-简介

◆ What is lossy compression-什么是有损编码

Compression program	Compression ratio			
	Lena	Football	F-18	Flowers
Lossless JPEG	1.45	1.54	2.29	1.26
Optimal lossless JPEG	1.49	1.67	2.71	1.33
compress (LZW)	0.86	1.24	2.21	0.87
gzip (LZ77)	1.08	1.36	3.10	1.05
gzip-9 (optimal LZ77)	1.08	1.36	3.13	1.05
pack (Huffman coding)	1.02	1.12	1.19	1.00



Introduction-简介

◆ What is lossy compression-什么是有损编码

- Lossless compression algorithms do not deliver compression ratios that are high enough. Hence, most multimedia compression algorithms are *lossy*-无损编码压缩率不高，多媒体应用需较高压缩率.
- **Lossy Compression:** The compressed data is not the same as the original data, but a *close approximation* of it-不完全相同，但感知上近似.
- Yields a much *higher compression ratio* than that of lossless compression-较高压缩率.

Introduction-简介

◆ What is lossy compression-什么是有损编码



Distortion Measures-失真度量

◆ Distortion measures in image

- A *distortion measure* is a mathematical quantity that specifies *how close* an approximation is to its original, using some distortion criteria-近似程度的数学量化.
- **Mean square error (MSE)** -均方差(平均像素差异):

$$\sigma^2 = \frac{1}{N} \sum_{i=1}^N (x_i - y_i)^2$$

原始值
解压值

- **Signal to Noise Rate (SNR)**-信噪比:

$$SNR = 10 \log_{10} \frac{\sigma_x^2}{\sigma_d^2}$$

原数据均方
均方差

- **Peak signal to noise ratio (PSNR)**-峰值信噪比:

$$PSNR = 10 \log_{10} \frac{x_{peak}^2}{\sigma_d^2}$$

原始数据最大值

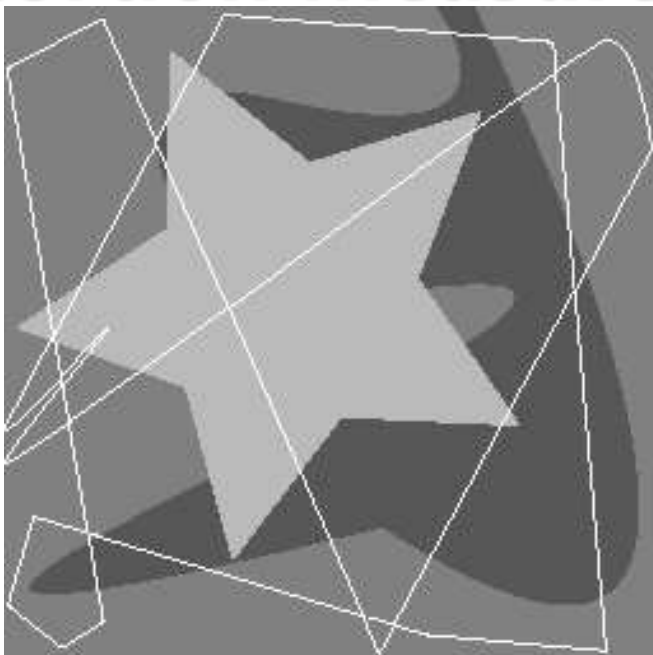
Distortion Measures-失真度量

◆ Distortion measures in image

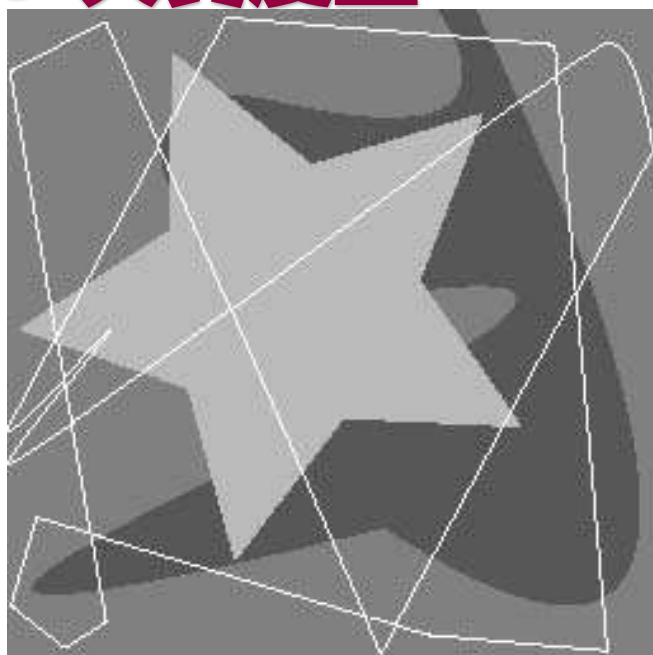
- 例：已知原数据和经过压缩与解压缩之后得到的数据为
- 原始数据：{12 12 12 12 12 8 8 12 }
- 处理数据：{12 12 12 8 12 8 12 12}。
- 请分别计算MSE、SNR和PSNR的值。
- $\sigma^2 = \frac{1}{N} \sum_{i=1}^N (x_i - y_i)^2$, $1/8 * [(12-8)^2 + (8-12)^2] = 4$
- $SNR = 10 \log_{10} \frac{\sigma_x^2}{\sigma_d^2}$, $10 * \log_{10} [(6 * 12^2 + 2 * 8^2) / 8 / 4] \approx 14.91$
- $PSNR = 10 \log_{10} \frac{x_{peak}^2}{\sigma_d^2}$, $10 * \log_{10} [12^2 / 4] \approx 15.563$

Distortion Measures-失真度量

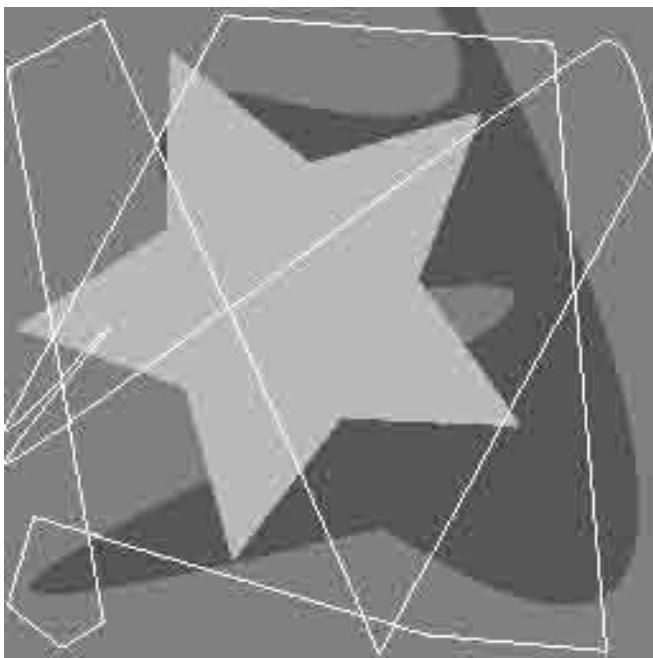
原图像



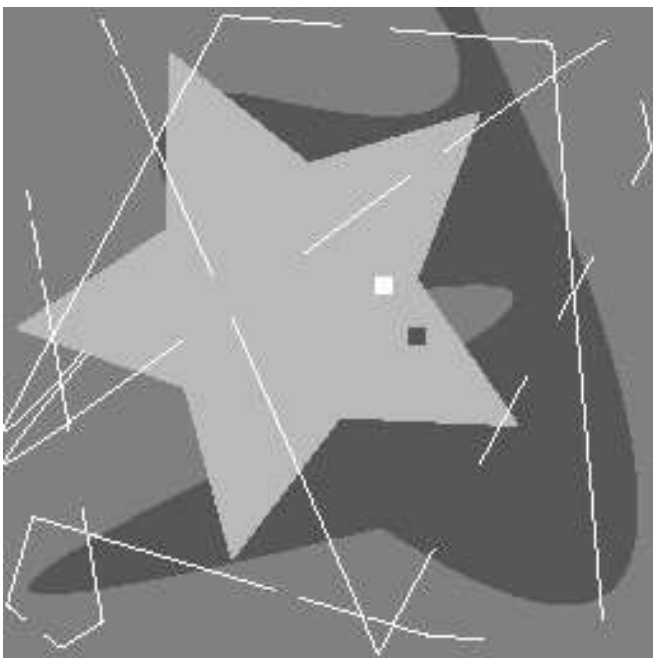
均方根误差
5.17



均方根误差
15.67



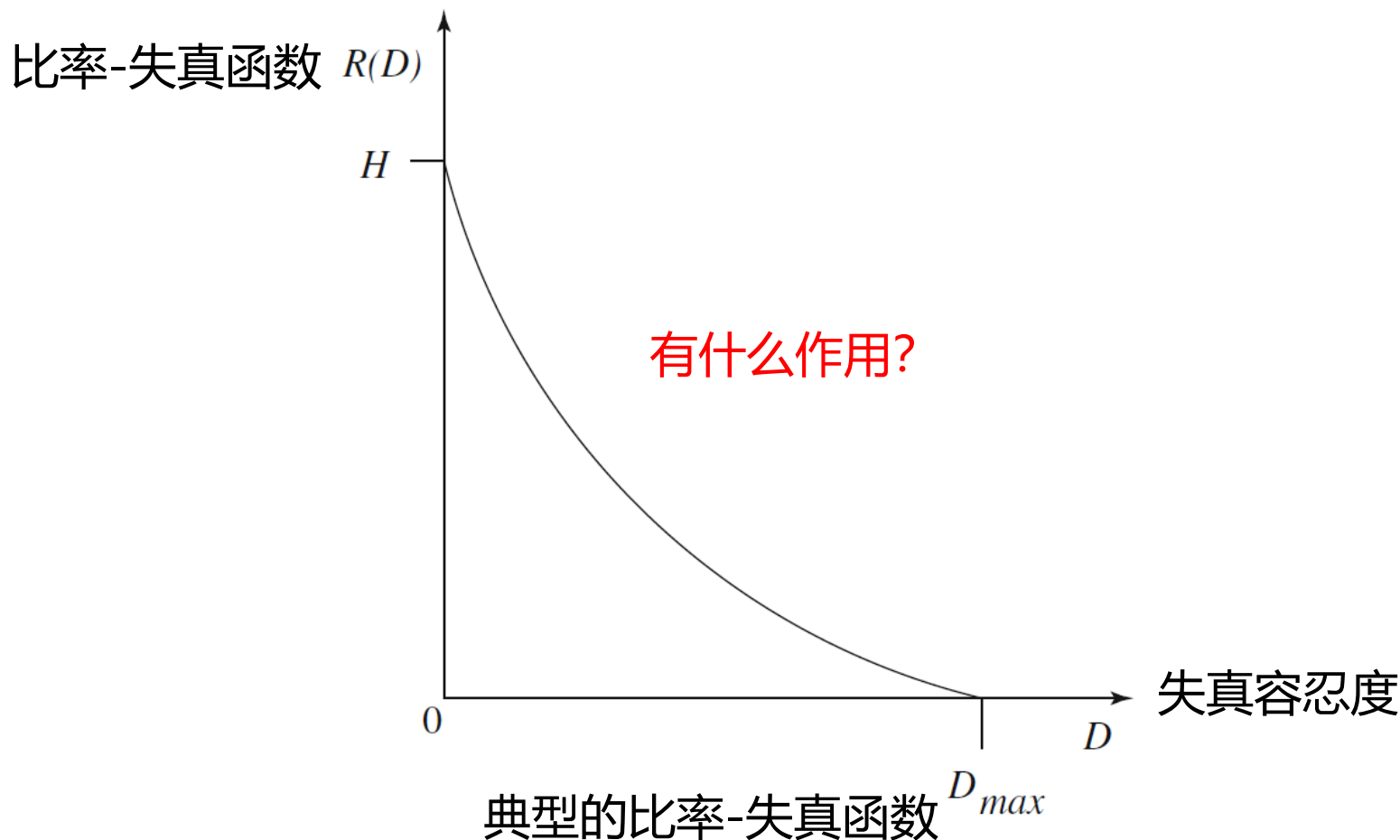
均方根误差
14.17



The Rate-Distortion Theory-比率失真理论

◆ Tradeoffs between Rate and Distortion-平衡

- Rate is the average number of bits required to represent each source symbol-位数vs失真.



Outline of Lecture 08

- ◆ Introduction-简介
- ◆ Distortion Measures-失真度量
- ◆ The Rate-Distortion Theory-比率失真理论
- ◆ Quantization-量化
 - Uniform Scalar Quantization-均匀标量量化
 - Nonuniform Scalar Quantization-非均匀标量量化
 - Vector Quantization-向量量化
- ◆ Transform Coding-变换编码
- ◆ Wavelet-Based Coding-小波编码
- ◆ Experiments-实验



Quantization-量化

◆ Further understanding quantization

- Quantization is the heart of any lossy scheme-量化是任何有损方案的核心.
- Reduce the number of distinct output values to a much smaller set-不同输出值的数量减少到一个更小的集合.
- Main source of the “loss” in lossy compression-信息损失主要来源.
- $f: \{0, 1, 2, \dots, 32, \dots, 64, \dots, 94, \dots, 128, \dots, 192, \dots, 255\}$
- $f': \{0, \qquad \qquad \qquad 64, \qquad \qquad \qquad 128, \qquad 192, \qquad 255\}$
- Uniform/nonuniform scalar quantization-均匀/非均匀
- Vector quantization-向量量化(LZW编码)



Quantization-量化

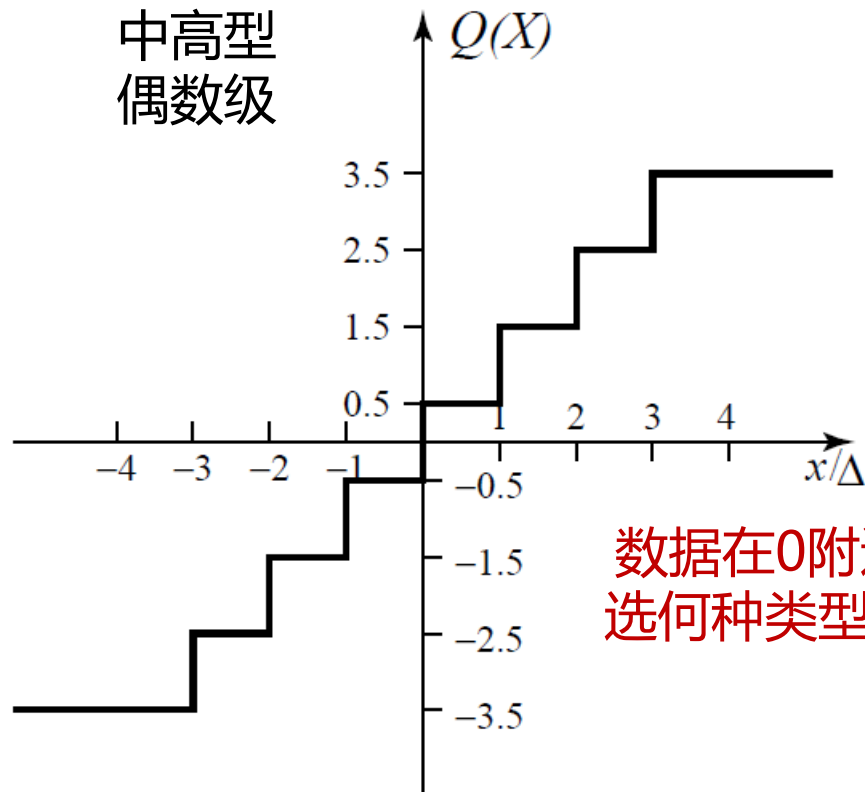
◆ Uniform Scalar Quantization-均匀标量量化

- A uniform scalar quantizer partitions the domain of input values into equally spaced intervals, except possibly at the two outer intervals-输入值的域划分为等间隔的区间.
- The endpoints of partition intervals are called the quantizer's decision boundaries-区间端点称决策边界.
- The length of each interval is referred to as the *step size*, denoted by the symbol Δ -区间长短称为步长.
- Two types of uniform scalar quantizers: *Midrise* and *Midtread* Quantizers-中高型和中宽型均匀量化器
- The goal for the design of a successful uniform quantizer is to **minimize the distortion** for a given source input with a desired number of output values by adjusting the *step size* Δ to match the input -调整步长, 匹配输入, 最小化失真.



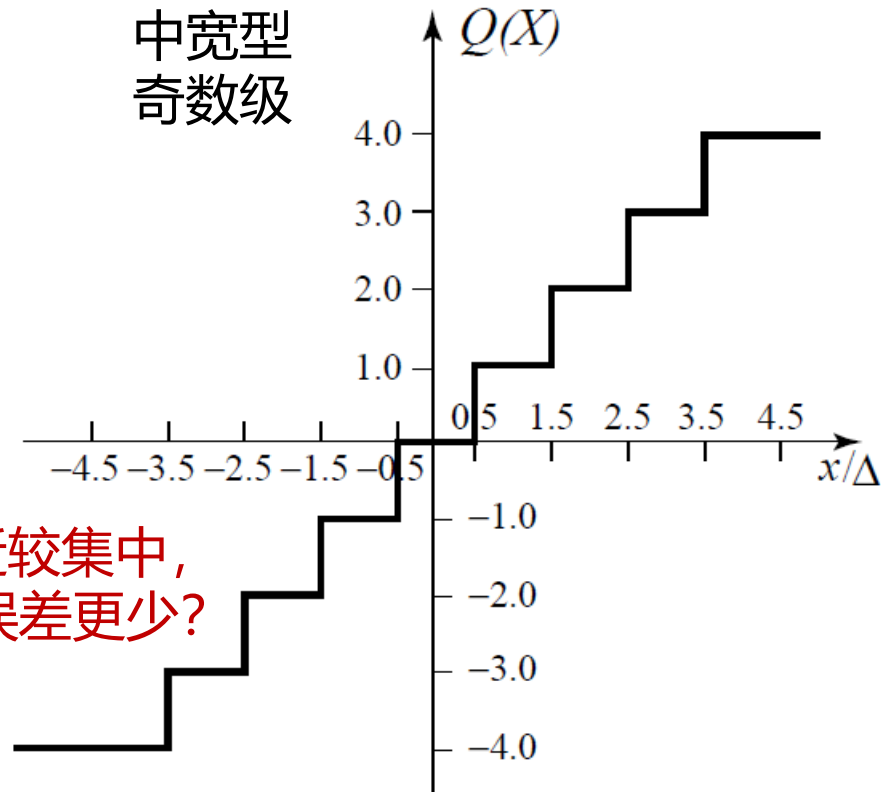
Quantization-量化

◆ Uniform Scalar Quantization-均匀标量量化



$$Q_{\text{midrise}}(x) = \lceil x \rceil - 0.5$$

(a)



$$Q_{\text{midtread}}(x) = \lfloor x + 0.5 \rfloor$$

(b)

数据在0附近较集中，
选何种类型误差更少？

Uniform Scalar Quantizers: (a) Midrise, (b) Midtread



Quantization-量化

◆ Uniform Scalar Quantization-均匀标量量化

- Performance of an M level quantizer. Let $B = \{b_0, b_1, \dots, b_M\}$ be the set of *decision boundaries* and $Y = \{y_1, y_2, \dots, y_M\}$ be the set of *output values*.
- Suppose the input is uniformly distributed in the interval $[-X_{max}, X_{max}]$. The rate of the quantizer is:

$$R = \lceil \log M \rceil$$

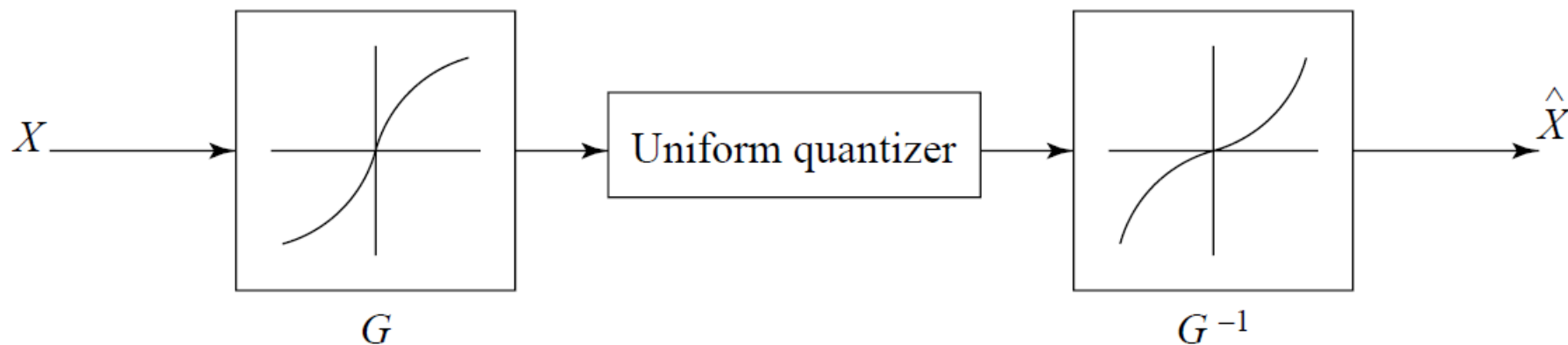
- If the quantizer is n bits, $M = 2^n$, then:

$$\begin{aligned} SQNR &= 10 \log_{10} \left(\frac{\sigma_x^2}{\sigma_d^2} \right) \\ &= 10 \log_{10} \left(\frac{(2X_{max})^2}{12} \cdot \frac{12}{\Delta^2} \right) \\ &= 10 \log_{10} M^2 = 20n \log_{10} 2 \\ &= 6.02n \text{ (dB)}. \end{aligned}$$



Quantization-量化

- ◆ Nonuniform Scalar Quantization-非均匀标量量化
 - *Nonuniform quantization is **nonlinear***-非线性
 - *Companded quantization: a compander consists of a compressor function G , a uniform quantizer, and an expander function G^{-1}* -压缩扩展量化器



μ 律和A律压缩扩展器



Quantization-量化

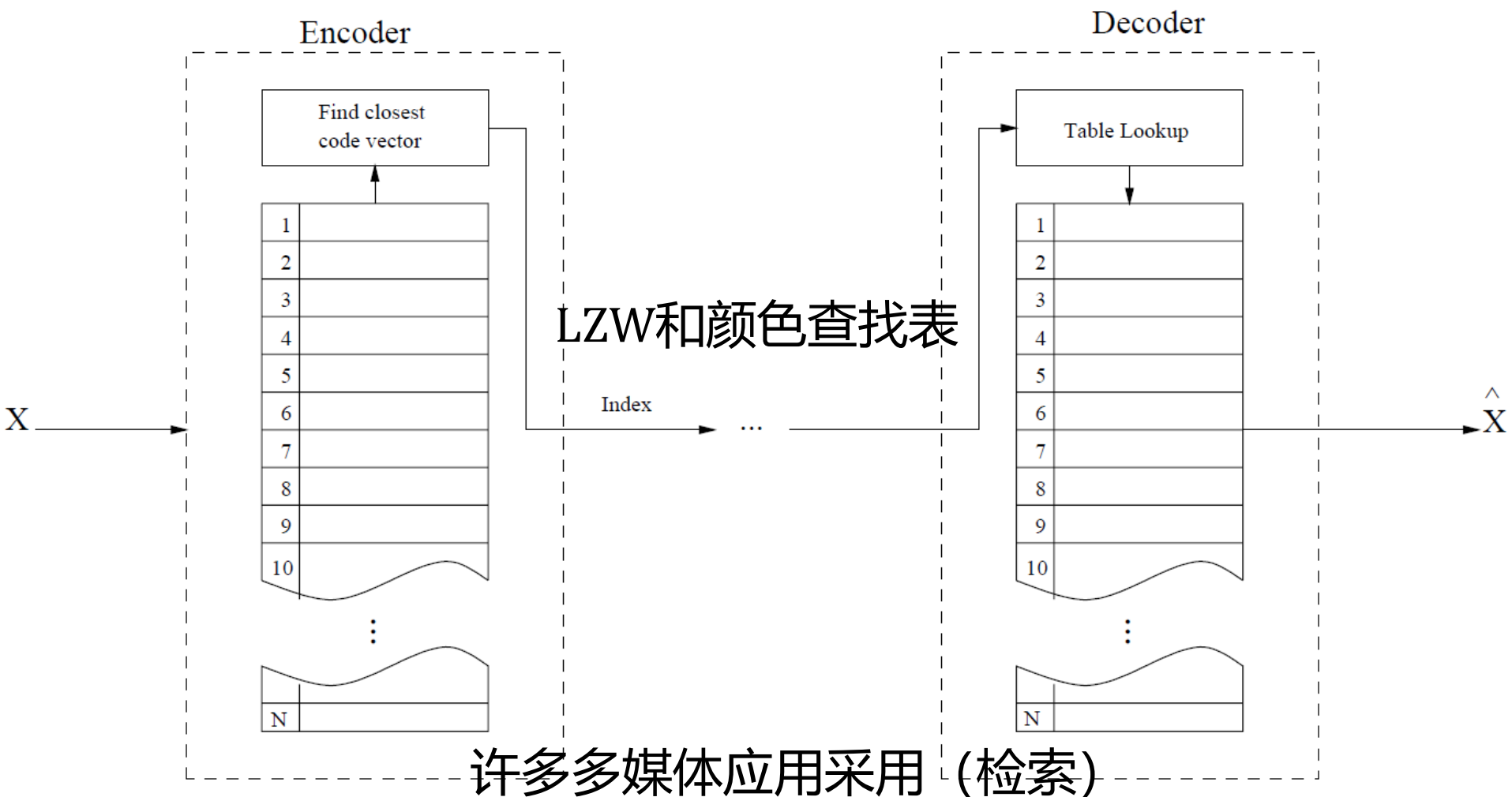
◆ Vector Quantization-向量量化

- According to Shannon's original work on information theory, any compression system performs better if it operates on *vectors* or *groups of samples* rather than individual symbols or samples-非单个样本更好.
- Form vectors of input samples by simply concatenating a number of consecutive samples into a single vector-一系列样本形成向量.
- Instead of single reconstruction values as in scalar quantization, in VQ code vectors with n components are used. A collection of these code vectors form the codebook-向量量化码有 n 个分量，向量码的集合形成码本.



Quantization-量化

◆ Vector Quantization-向量量化



Basic vector quantization procedure

Outline of Lecture 08

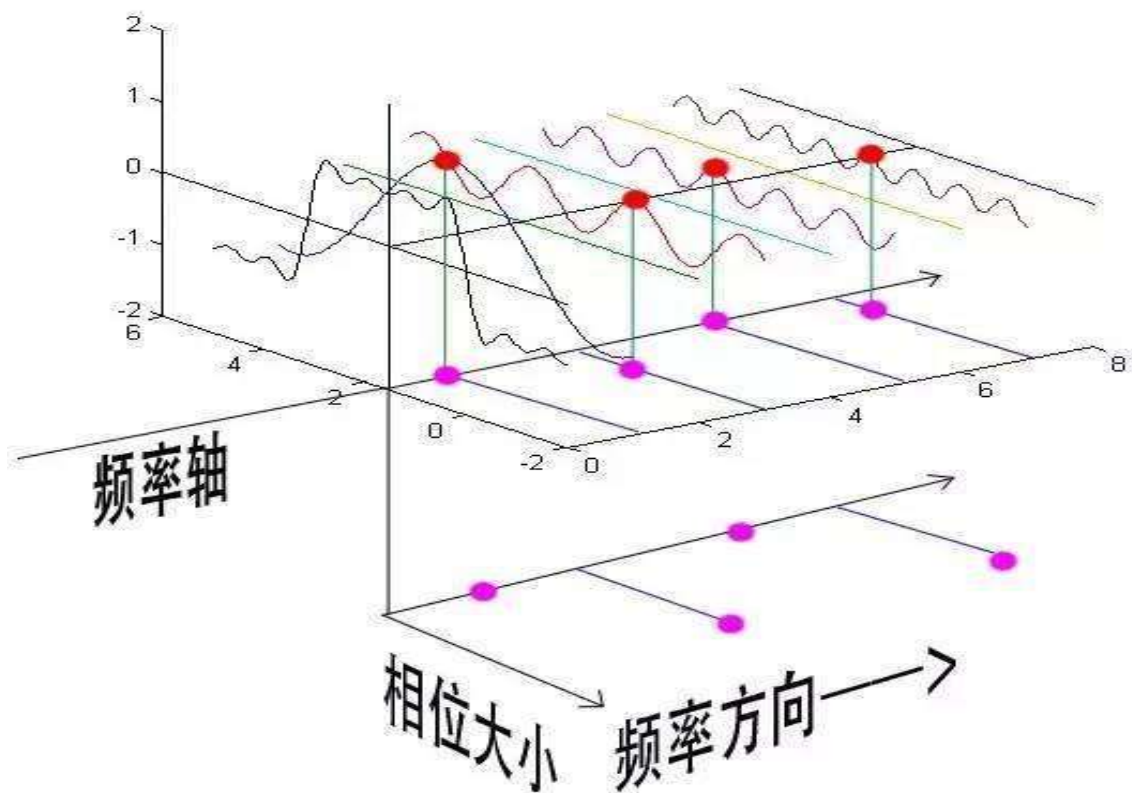
- ◆ Introduction-简介
- ◆ Distortion Measures-失真度量
- ◆ The Rate-Distortion Theory-比率失真理论
- ◆ Quantization-量化
 - Uniform Scalar Quantization-均匀标量量化
 - Nonuniform Scalar Quantization-非均匀标量量化
 - Vector Quantization-向量量化
- ◆ Transform Coding-变换编码
- ◆ Wavelet-Based Coding-小波编码
- ◆ Experiments-实验

Transform Coding-变换编码

- ◆ The rationale behind transform coding-动机
 - Coding vectors is more efficient than coding scalar-向量编码更有效.
 - If Y is the result of a linear transform T of the input vector X , i.e. $Y=T(X)$ in such a way that the components of Y are much *less correlated*, then Y can be coded more efficiently than X -对线性变换 T 后的 Y 进行编码比原数据 X 更有效——变换编码原理.
 - If most information is accurately described by **the first few components** of a transformed vector, then the remaining components can be coarsely quantized, or even **set to zero**, with little signal distortion-大部分信息集中在前几个分量，其它分量可能更粗精度量化，甚至置0.

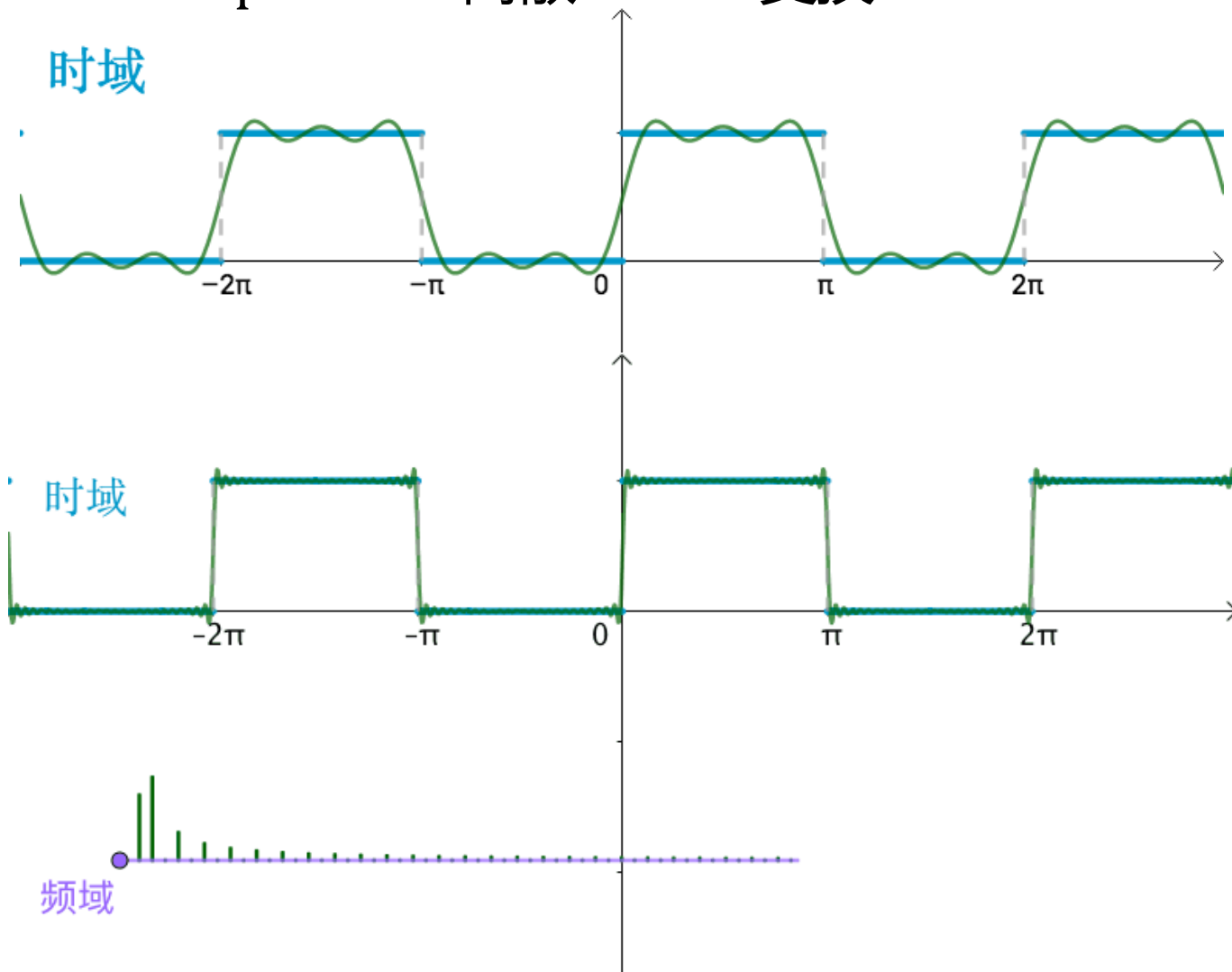
Transform Coding-变换编码

- ◆ The rationale behind transform coding-动机
 - An example: DFT-离散Fourier变换.



Transform Coding-变换编码

- ◆ The rationale behind transform coding-动机
 - An example: DFT-离散Fourier变换.



Transform Coding-变换编码

- ◆ Discrete Cosine Transform (DCT)-离散余弦变换
 - **Spatial frequency** indicates how many times pixel values change across an image block-图像块像素值变化通过空间频率反映.
 - The DCT formalizes this notion with a measure of how much the *image contents change* in correspondence to **the number of cycles of a cosine wave** per block-余弦函数反映图像内容变化.
 - The role of the DCT is to decompose the original signal into its **DC** and **AC** components; the role of the IDCT is to reconstruct (re-compose) the signal- DCT分解原始信号为直流DC分量和交流AC分量, IDCT为逆变换.

Transform Coding-变换编码

◆ Definition of DCT-离散余弦变换定义

- Given an input function $f(i, j)$ over two integer variables i and j (a piece of an image), the 2D DCT transforms it into a new function $F(u, v)$, with integer u and v running over the same range as i and j . The general definition of the transform is-图像像素 $f(i, j)$:

$$F(u, v) = \frac{2C(u)C(v)}{\sqrt{MN}} \sum_{i=0}^{M-1} \sum_{j=0}^{N-1} \cos \frac{(2i+1) \cdot u\pi}{2M} \cdot \cos \frac{(2j+1) \cdot v\pi}{2N} \cdot f(i, j)$$

$$i, u = 0, 1, \dots, M-1, j, v = 0, 1, \dots, N-1,$$

$$C(\xi) = \begin{cases} \frac{\sqrt{2}}{2}, & \xi = 0 \\ 1, & \text{others} \end{cases}$$

Transform Coding-变换编码

◆ 2D DCT and IDCT-二维离散余弦变换及逆变换

- In the JPEG image compression standard (see Chap. 9), an image block is defined to have dimension $M = N = 8$. Therefore, the definitions for the 2D DCT and its inverse (IDCT) are as follows-JPEG图像压缩二维DCT和IDCT:

$$F(u, v) = \frac{C(u)C(v)}{4} \sum_{i=0}^7 \sum_{j=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot \cos \frac{(2j+1) \cdot v\pi}{16} \cdot f(i, j)$$

$$\tilde{f}(i, j) = \sum_{u=0}^7 \sum_{v=0}^7 \frac{C(u)C(v)}{4} \cdot \cos \frac{(2i+1) \cdot u\pi}{16} \cdot \cos \frac{(2j+1) \cdot v\pi}{16} \cdot F(u, v)$$

$$i, u = 0, 1, \dots, 7, j, v = 0, 1, \dots, 7, C(\xi) = \begin{cases} \frac{\sqrt{2}}{2}, & \xi = 0 \\ 1, & \text{others} \end{cases}$$

Transform Coding-变换编码

- ◆ 1D DCT and IDCT-一维离散余弦变换及逆变换
 - **1D Discrete Cosine Transform (1D DCT)-一维DCT**

$$F(u) = \frac{C(u)}{2} \sum_{i=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot f(i), \quad i, u = 0, 1, \dots, 7$$

- **1D Inverse Discrete Cosine Transform (1D IDCT)-一维逆DCT**

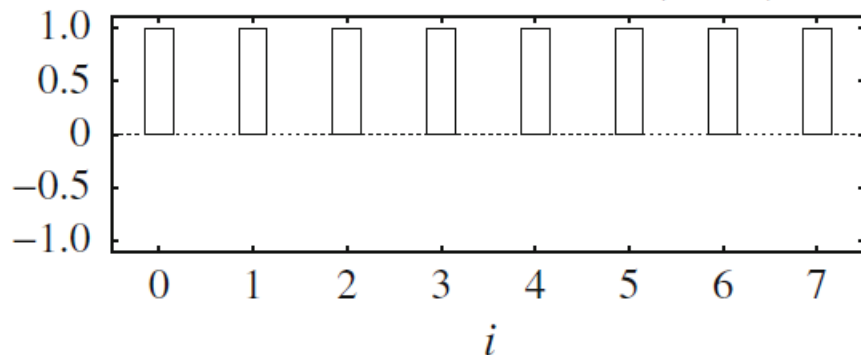
$$\tilde{f}(i) = \sum_{u=0}^7 \frac{C(u)}{2} \cdot \cos \frac{(2i+1) \cdot u\pi}{16} \cdot F(u), \quad i, u = 0, 1, \dots, 7$$

Transform Coding-变换编码

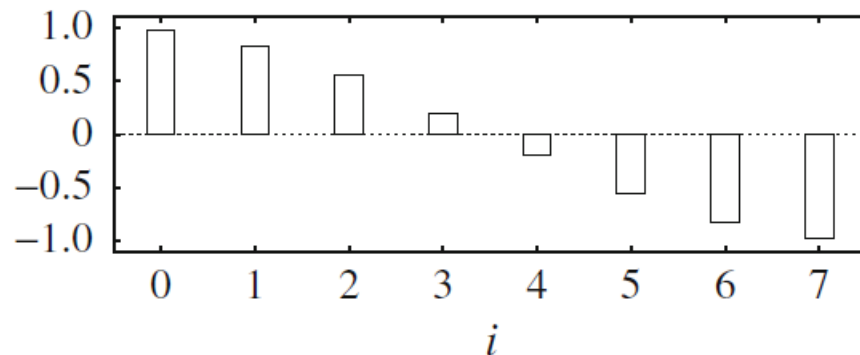
◆ 1D DCT basis functions-一维DCT基函数

$$F(u) = \frac{C(u)}{2} \sum_{i=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot f(i), \quad i, u = 0, 1, \dots, 7$$

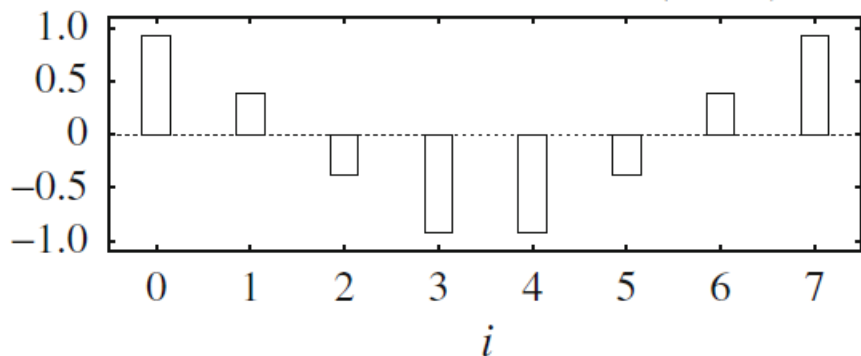
The 0th basis function ($u = 0$)



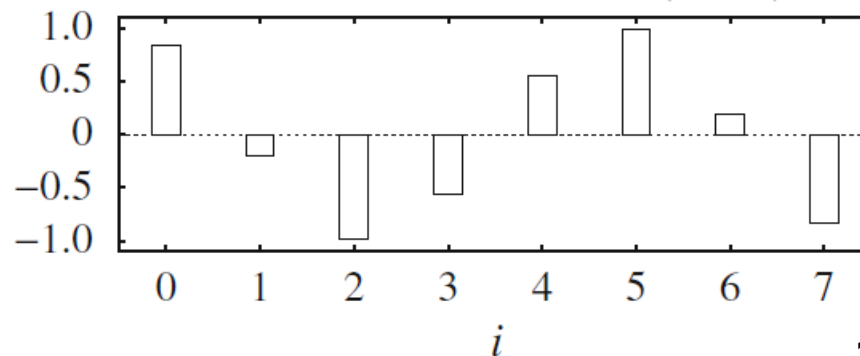
The 1st basis function ($u = 1$)



The 2nd basis function ($u = 2$)



The 3rd basis function ($u = 3$)

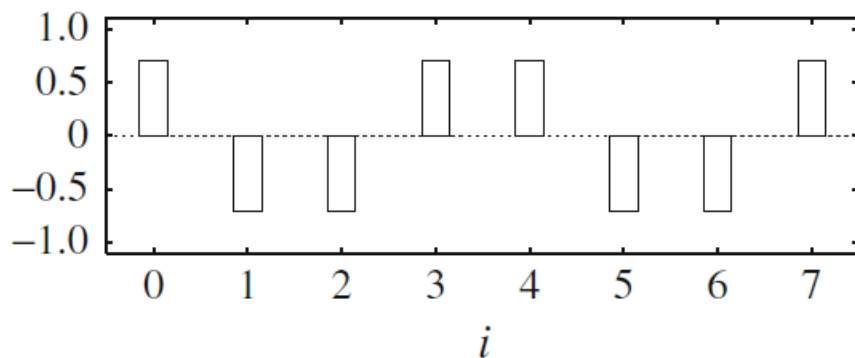


Transform Coding-变换编码

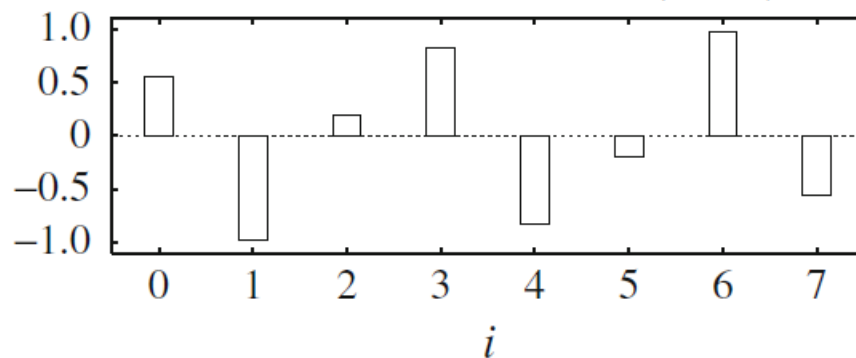
◆ 1D DCT basis functions-一维DCT基函数

$$F(u) = \frac{C(u)}{2} \sum_{i=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot f(i), \quad i, u = 0, 1, \dots, 7$$

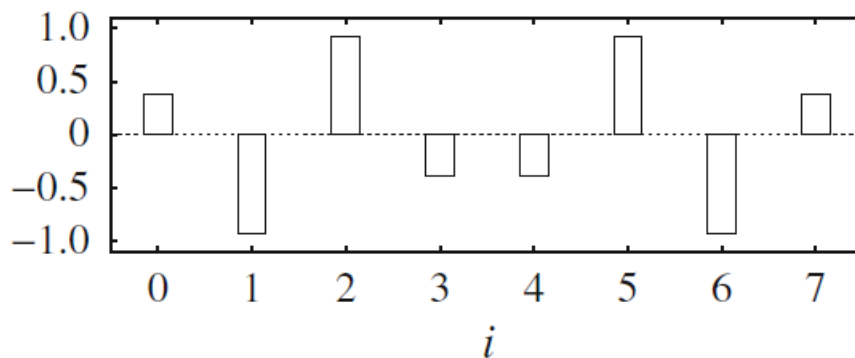
The 4th basis function ($u = 4$)



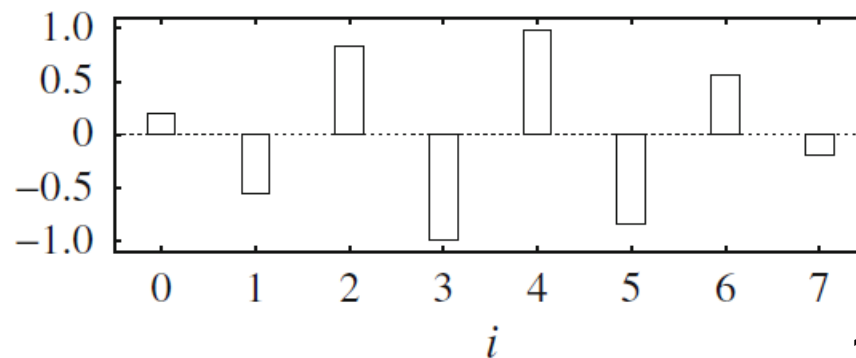
The 5th basis function ($u = 5$)



The 6th basis function ($u = 6$)



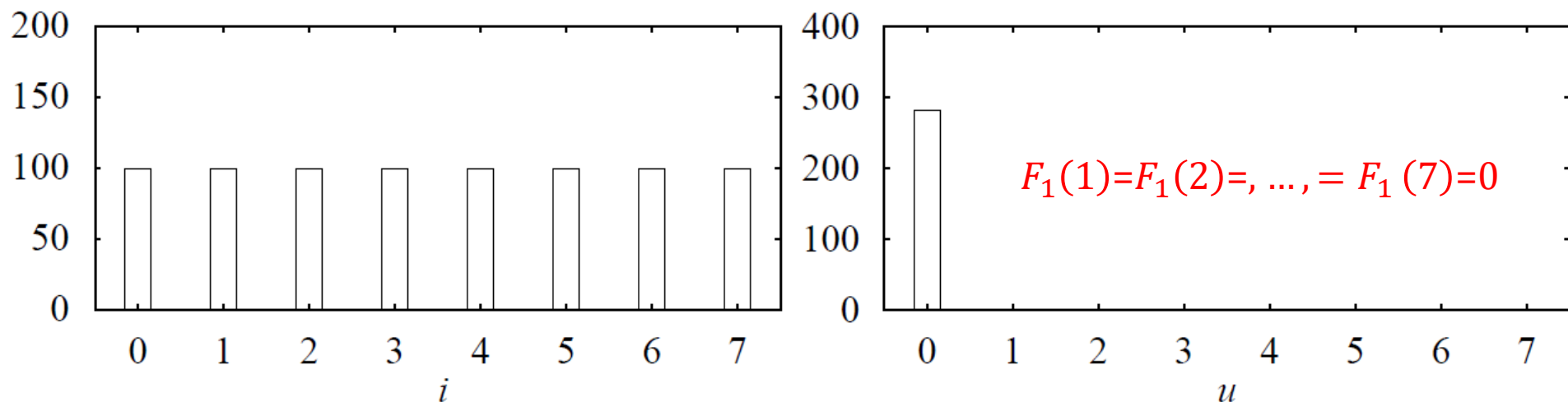
The 7th basis function ($u = 7$)



Transform Coding-变换编码

◆ 1D DCT -一维离散余弦变换

- Example: $f_1 = \{100, 100, 100, 100, 100, 100, 100, 100\}$



$$F(u) = \frac{C(u)}{2} \sum_{i=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot f(i)$$

$$F_1(0) = \frac{\sqrt{2}}{2} \cdot \frac{1}{2} (1 \cdot 100 + 1 \cdot 100 + 1 \cdot 100 + 1 \cdot 100 + 1 \cdot 100 + 1 \cdot 100 + 1 \cdot 100 + 1 \cdot 100) \approx 283$$

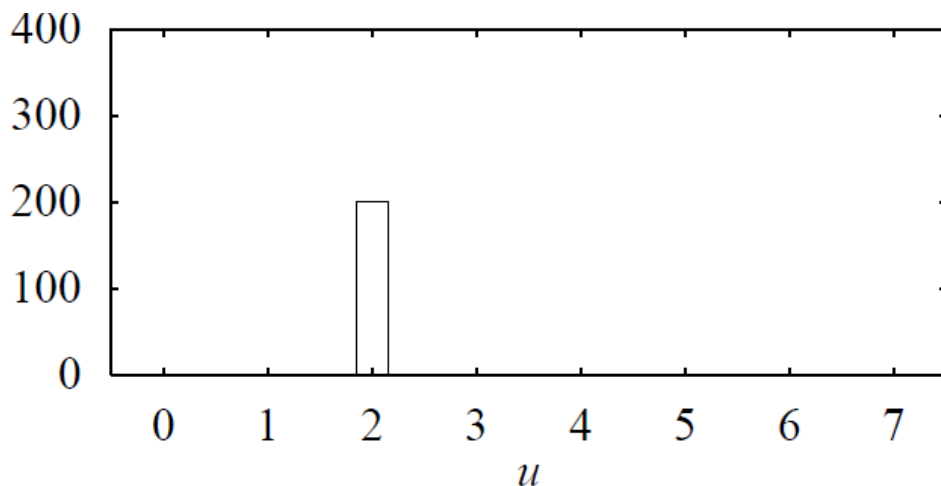
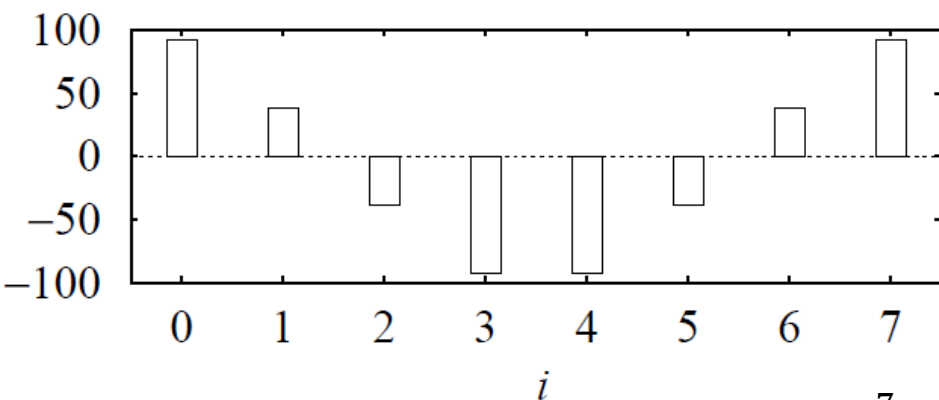
$$F_1(1) = \frac{1}{2} \left(\cos \frac{\pi}{16} \cdot 100 + \cos \frac{3\pi}{16} \cdot 100 + \cos \frac{5\pi}{16} \cdot 100 + \cos \frac{7\pi}{16} \cdot 100 + \cos \frac{9\pi}{16} \cdot 100 + \cos \frac{11\pi}{16} \cdot 100 + \cos \frac{13\pi}{16} \cdot 100 + \cos \frac{15\pi}{16} \cdot 100 \right) = 0$$

Transform Coding-变换编码

◆ 1D DCT-一维离散余弦变换

- Example: f_2

包含AC分量的变化信号



$$F(u) = \frac{C(u)}{2} \sum_{i=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot f(i)$$

$$F_2(0) = 0$$

$$F_2(2) = 200$$

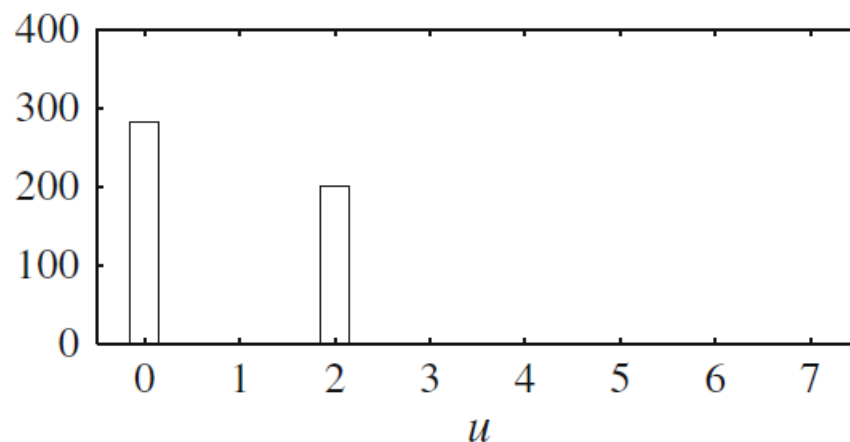
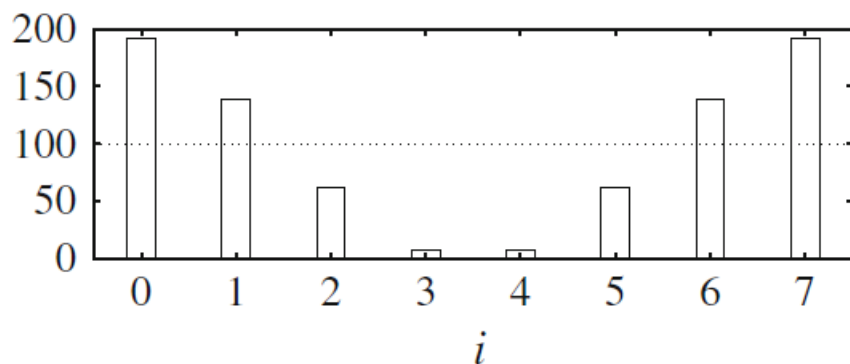
$$F_2(1) = F_3(3) = \dots = F_3(7) = 0$$

Transform Coding-变换编码

◆ 1D DCT-一维离散余弦变换

- Example: $f_3 = f_1 + f_2$

包含DC+AC分量的变化信号



$$F(u) = \frac{C(u)}{2} \sum_{i=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot f(i)$$

$$F_3(0) \approx 283$$

$$F_3(2) = 200$$

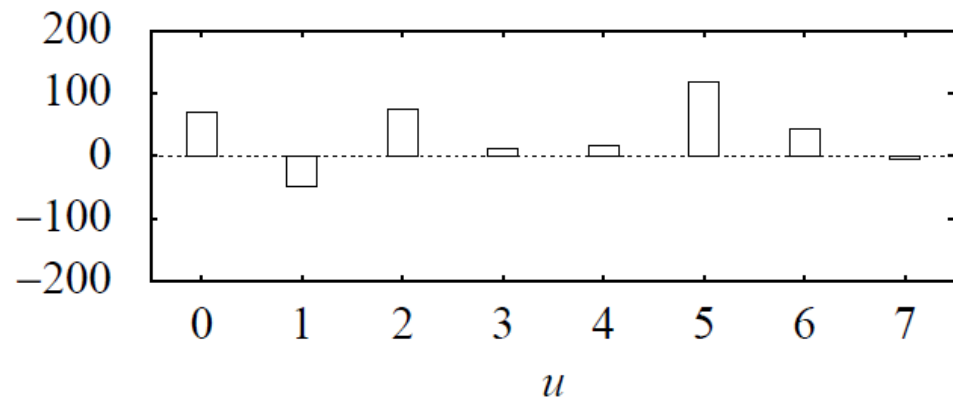
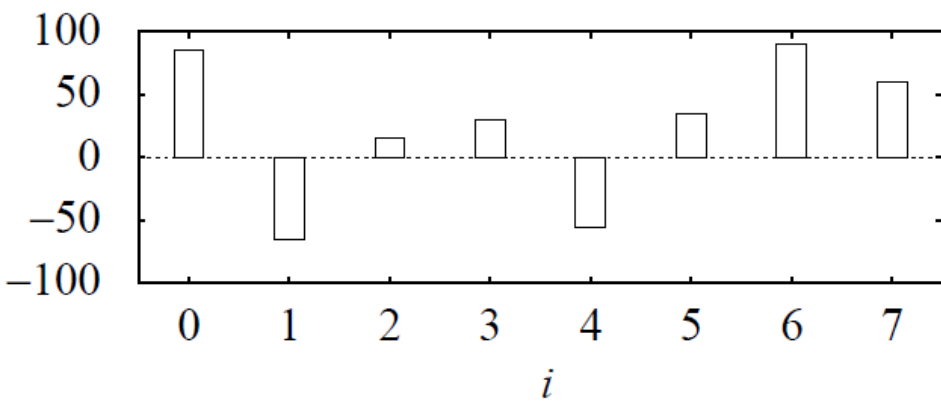
$$F_3(1) = F_3(3) = \dots = F_3(7) = 0$$

Transform Coding-变换编码

◆ 1D DCT-一维离散余弦变换

- Example: $f_4 = \{85, -65, 15, 30, -56, 35, 90, 60\}$

任意变化信号



$F_4(u): \{69, -49, 74, 11, 16, 117, 44, -5\}$

Transform Coding-变换编码

◆ 1D DCT-一维离散余弦变换

- The characteristics of the DCT can be summarized as follows-离散余弦变换特性总结:
- The DCT produces the spatial frequency spectrum $F(u)$ corresponding to the spatial signal $f(i)$ -空间信号 $f(i)$ 的频谱 $F(u)$.
- The 0th DCT coefficient $F(0)$ is the DC component of the signal $f(i)$ - $F(0)$ 是直流分量, 与**信号的平均值**对应 $F(0) = \frac{\sqrt{2}}{2} \cdot \frac{1}{2} \cdot 8 \cdot f_{avg} = 2\sqrt{2} \cdot f_{avg}$
- Other seven DCT coefficients reflect the various changing (i.e., AC) components of the signal $f(i)$ at different frequencies-其它系数反映信号不同频率的AC分量.
- The DCT is a linear transform-离散余弦变换是线性变换.

Transform Coding-变换编码

◆ 1D IDCT-一维离散余弦逆变换

- Example: $f_4 = \{85, -65, 15, 30, -56, 35, 90, 60\}$
- $F_4(u): \{69, -49, 74, 11, 16, 117, 44, -5\}$

$$\tilde{f}(i) = \sum_{u=0}^7 \frac{C(u)}{2} \cdot \cos \frac{(2i+1) \cdot u\pi}{16} \cdot F(u)$$

$$\text{Iteration 0: } \tilde{f}(i) = \frac{C(0)}{2} \cdot \cos 0 \cdot F(0) = \frac{\sqrt{2}}{2 \cdot 2} \cdot 1 \cdot 69 \approx 24.3.$$

$$\begin{aligned} \text{Iteration 1: } \tilde{f}(i) &= \frac{C(0)}{2} \cdot \cos 0 \cdot F(0) + \frac{C(1)}{2} \cdot \cos \frac{(2i+1)\pi}{16} \cdot F(1) \\ &\approx 24.3 + \frac{1}{2} \cdot (-49) \cdot \cos \frac{(2i+1)\pi}{16} \approx 24.3 - 24.5 \cdot \cos \frac{(2i+1)\pi}{16}. \end{aligned}$$

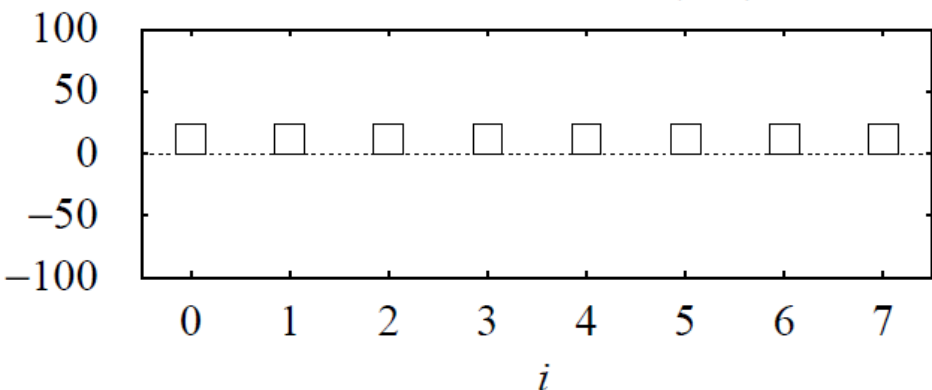
$$\begin{aligned} \text{Iteration 2: } \tilde{f}(i) &= \frac{C(0)}{2} \cdot \cos 0 \cdot F(0) + \frac{C(1)}{2} \cdot \cos \frac{(2i+1)\pi}{16} \cdot F(1) + \frac{C(2)}{2} \cdot \cos \frac{(2i+1)\pi}{8} \cdot F(2) \\ &\approx 24.3 - 24.5 \cdot \cos \frac{(2i+1)\pi}{16} + 37 \cdot \cos \frac{(2i+1)\pi}{8}. \end{aligned}$$

Transform Coding-变换编码

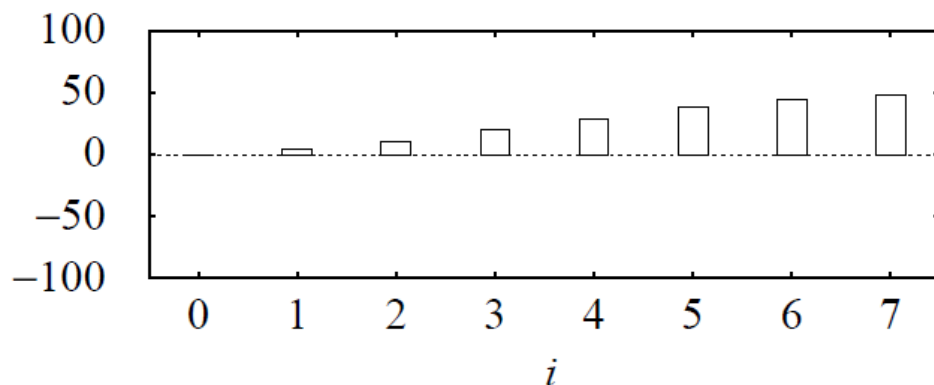
◆ 1D IDCT-一维离散余弦逆变换

- Example: $f_4 = \{85, -65, 15, 30, -56, 35, 90, 60\}$
- $F_4(u): \{69, -49, 74, 11, 16, 117, 44, -5\}$

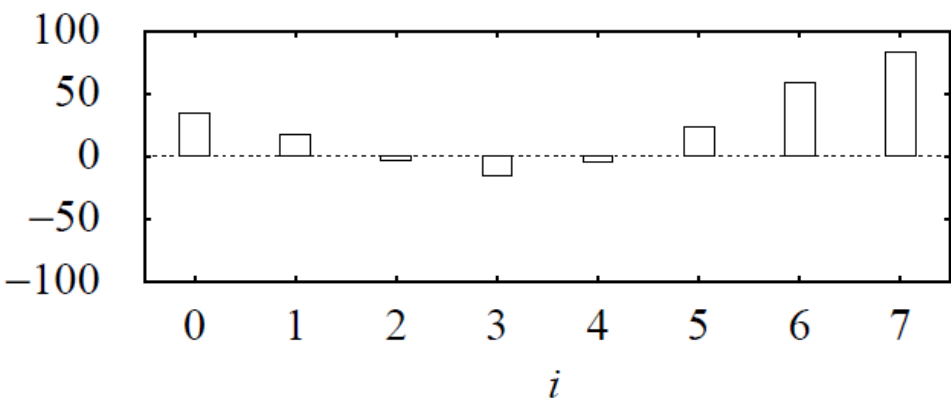
After 0th iteration (DC)



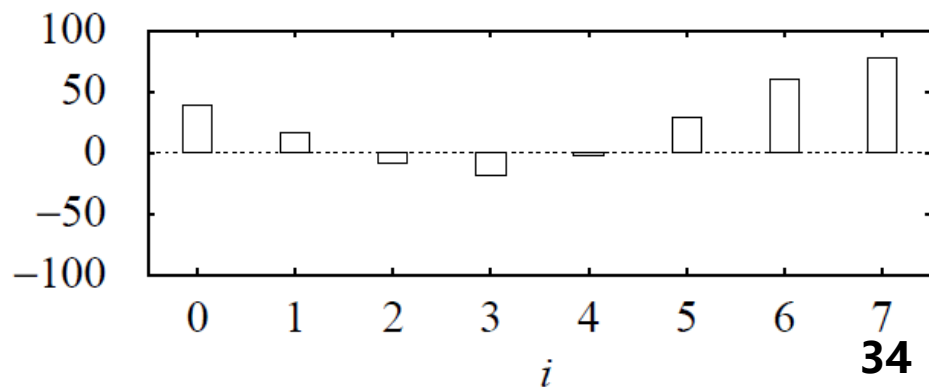
After 1st iteration (DC + AC1)



After 2nd iteration (DC + AC1 + AC2)



After 3rd iteration (DC + AC1 + AC2 + AC3)



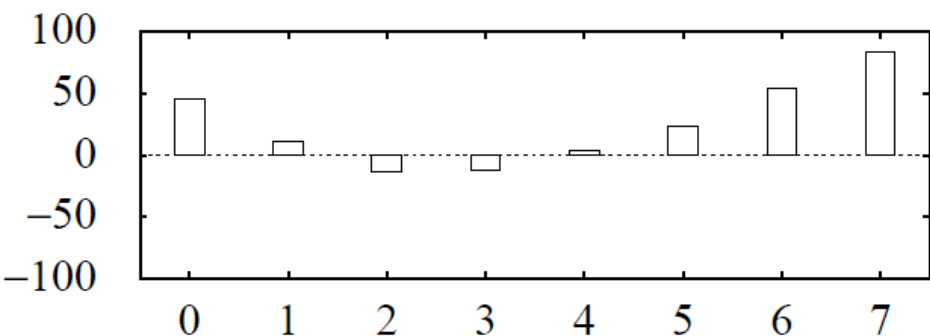
Transform Coding-变换编码

◆ 1D IDCT-一维离散余弦逆变换

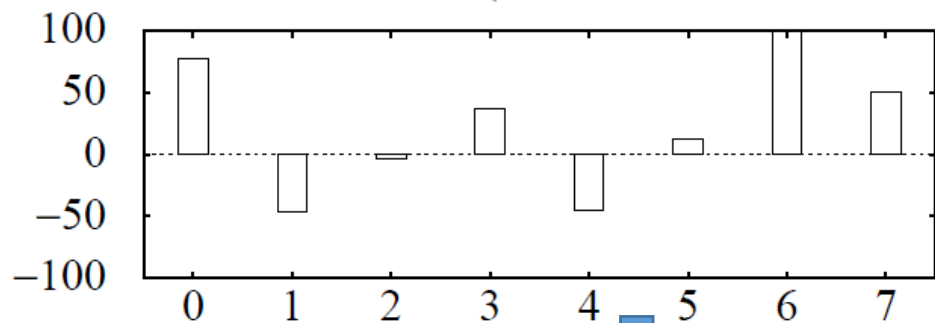
- Example: $f_4 = \{85, -65, 15, 30, -56, 35, 90, 60\}$

- $F_4(u): \{69, -49, 74, 11, 16, 117, 44, -5\}$

After 4th iteration (DC + AC1 + ... + AC4)

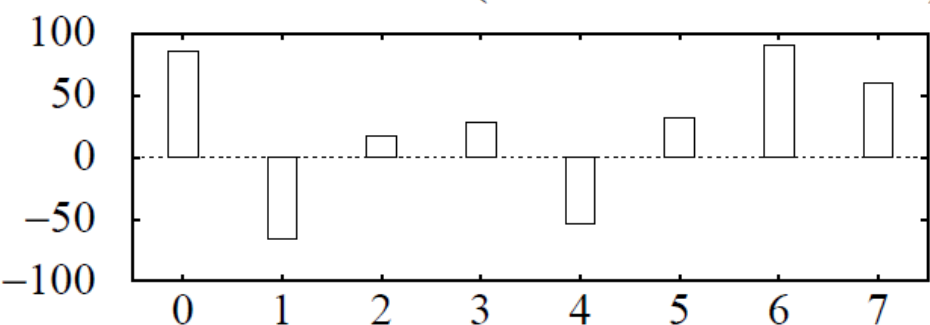


After 5th iteration (DC + AC1 + ... + AC5)

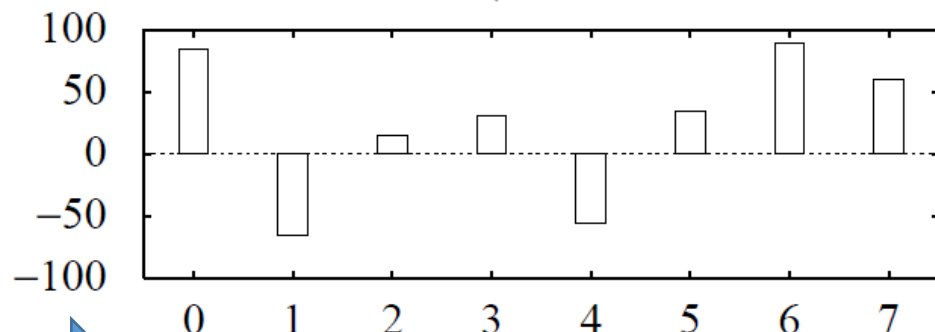


$\tilde{f}(i): \{85, -65, 15, 30, -56, 35, 90, 60\}$.

After 6th iteration (DC + AC1 + ... + AC6)



After 7th iteration (DC + AC1 + ... + AC7)



Transform Coding-变换编码

◆ The Cosine Basis Functions-余弦基函数

- Function $B_p(i)$ and $B_q(i)$ are **orthogonal**, if-正交

$$\sum_i [B_p(i) \cdot B_q(i)] = 0, \text{ if } p \neq q$$

- Function $B_p(i)$ and $B_q(i)$ are **orthonormal**, if-标准正交

$$\sum_i [B_p(i) \cdot B_q(i)] = 1, \text{ if } p = q$$

- 欧氏空间坐标系: $(1,0,0)$, $(0,1,0)$, $(0,0,1)$ 是一个标准正交基,

Transform Coding-变换编码

◆ The Cosine Basis Functions-余弦基函数

- With **orthogonal** property, the signal is not amplified during the transform. When the same basis function is used in both the transformation and its inverse, we will get (approximately) the same signal back-正交特性保持变换过程信号不放大, 基函数相同, 逆变换后信号近似相同.

$$\sum_{i=0}^7 \left[\cos \frac{(2i+1) \cdot p\pi}{16} \cdot \cos \frac{(2i+1) \cdot q\pi}{16} \right] = 0, p \neq q$$

$$\sum_{i=0}^7 \left[\frac{C(p)}{2} \cos \frac{(2i+1) \cdot p\pi}{16} \cdot \frac{C(q)}{2} \cos \frac{(2i+1) \cdot q\pi}{16} \right] = 1, p = q$$

标准化参数

Transform Coding-变换编码

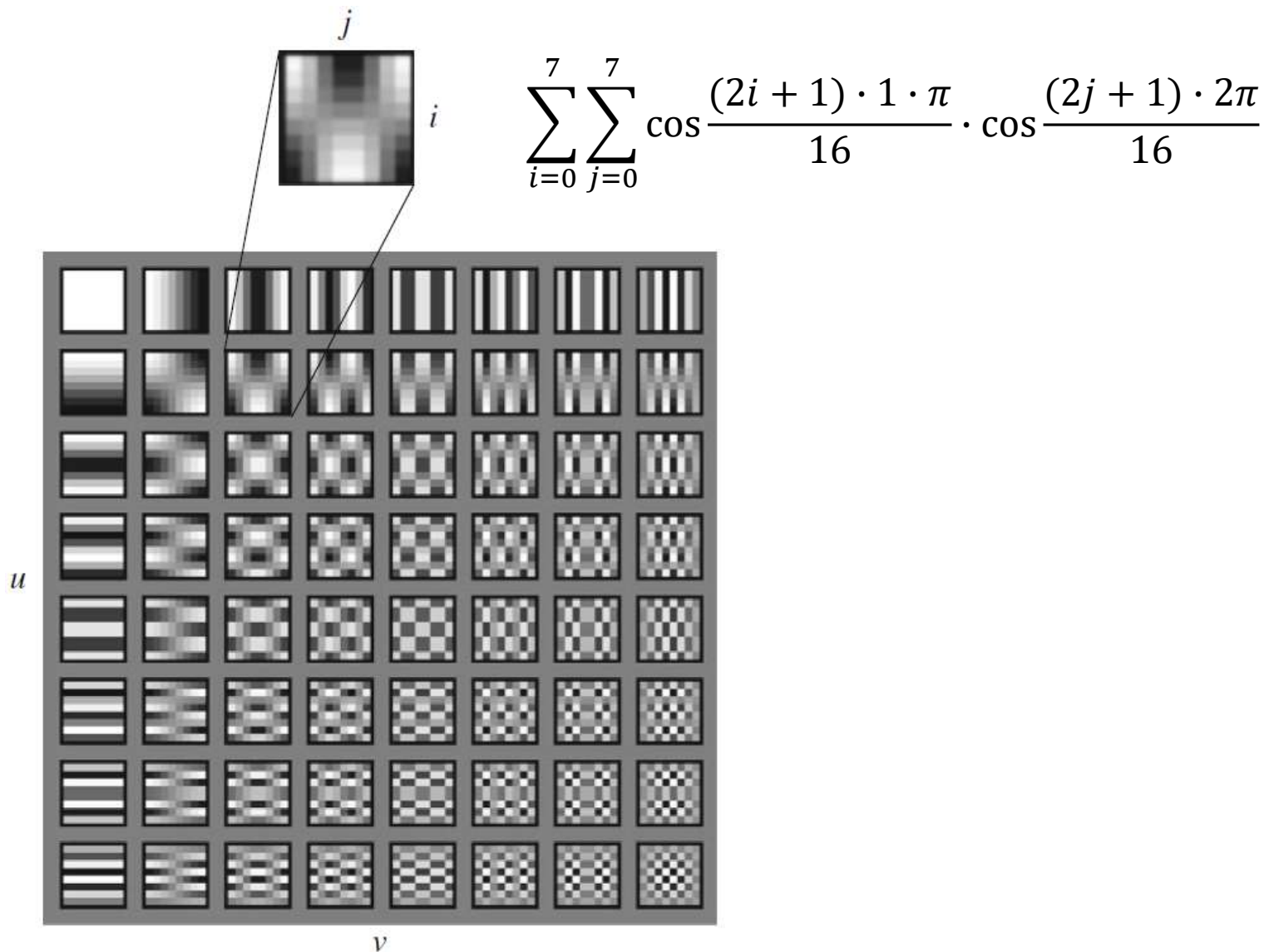
◆ 2D Basis Functions-2D基函数

- For two-dimensional DCT functions, we use the basis depicted as 8×8 image. For a particular pair of u and v , the respective basis function is-具体的对 (u, v) 相应基函数:

$$F(u, v) = \frac{C(u)C(v)}{4} \sum_{i=0}^7 \sum_{j=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot \cos \frac{(2j+1) \cdot v\pi}{16} \cdot f(i, j)$$

Transform Coding-变换编码

◆ 2D Basis Functions-2D基函数



Transform Coding-变换编码

◆ 2D Separable Basis-2D可分离函数

- For speed, 2D DCT coefficients—*factorization* into two 1D DCT transforms-二维转换成两个一维DCT加快速度-先列后行.

$$G(u, j) = \frac{C(u)}{2} \sum_{i=0}^7 \cos \frac{(2i+1) \cdot u\pi}{16} \cdot f(i, j)$$

$$F(u, v) = \frac{C(v)}{2} \sum_{j=0}^7 \cos \frac{(2j+1) \cdot v\pi}{16} \cdot G(u, j)$$

Transform Coding-变换编码

◆ 2D DCT-Matrix Implementation-矩阵实现

- The above factorization of a 2D DCT into two 1D DCTs can be implemented by two consecutive matrix multiplications-二维转换矩阵乘法实现.

$$F(u, v) = \mathbf{T} \cdot f(i, j) \cdot \mathbf{T}^T$$

DCT矩阵

$$\mathbf{T}_8 = \begin{bmatrix} \frac{1}{2\sqrt{2}} & \frac{1}{2\sqrt{2}} & \frac{1}{2\sqrt{2}} & \cdots & \frac{1}{2\sqrt{2}} \\ \frac{1}{2} \cdot \cos \frac{\pi}{16} & \frac{1}{2} \cdot \cos \frac{3\pi}{16} & \frac{1}{2} \cdot \cos \frac{5\pi}{16} & \cdots & \frac{1}{2} \cdot \cos \frac{15\pi}{16} \\ \frac{1}{2} \cdot \cos \frac{\pi}{8} & \frac{1}{2} \cdot \cos \frac{3\pi}{8} & \frac{1}{2} \cdot \cos \frac{5\pi}{8} & \cdots & \frac{1}{2} \cdot \cos \frac{15\pi}{8} \\ \frac{1}{2} \cdot \cos \frac{3\pi}{16} & \frac{1}{2} \cdot \cos \frac{9\pi}{16} & \frac{1}{2} \cdot \cos \frac{15\pi}{16} & \cdots & \frac{1}{2} \cdot \cos \frac{45\pi}{16} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{1}{2} \cdot \cos \frac{7\pi}{16} & \frac{1}{2} \cdot \cos \frac{21\pi}{16} & \frac{1}{2} \cdot \cos \frac{35\pi}{16} & \cdots & \frac{1}{2} \cdot \cos \frac{105\pi}{16} \end{bmatrix} \begin{matrix} \text{DC} \\ \text{AC1} \\ \text{AC2} \\ \text{AC3} \\ \\ \text{AC7} \end{matrix}$$

Transform Coding-变换编码

◆ 2D IDCT-Matrix Implementation-逆变换实现

- Reconstruct $f(i, j)$ from $F(u, v)$ losslessly by matrix multiplications - 二维逆变换矩阵乘法实现.

$$f(i, j) = \mathbf{T}^T \cdot F(u, v) \cdot \mathbf{T}$$

- The DCT-matrix \mathbf{T} is orthogonal, therefore, $\mathbf{T}^T = \mathbf{T}^{-1}$
- How to drive this formula-如何推导?

$$f(i, j) = \mathbf{T}^{-1} \cdot \mathbf{T} \cdot f(i, j) \cdot \mathbf{T}^T \cdot (\mathbf{T}^T)^{-1}$$

$$F(u, v) = \mathbf{T} \cdot f(i, j) \cdot \mathbf{T}^T$$

$$f(i, j) = \mathbf{T}^{-1} \cdot F(u, v) \cdot (\mathbf{T}^T)^{-1}$$

$$f(i, j) = \mathbf{T}^T \cdot F(u, v) \cdot \mathbf{T}$$

Transform Coding-变换编码

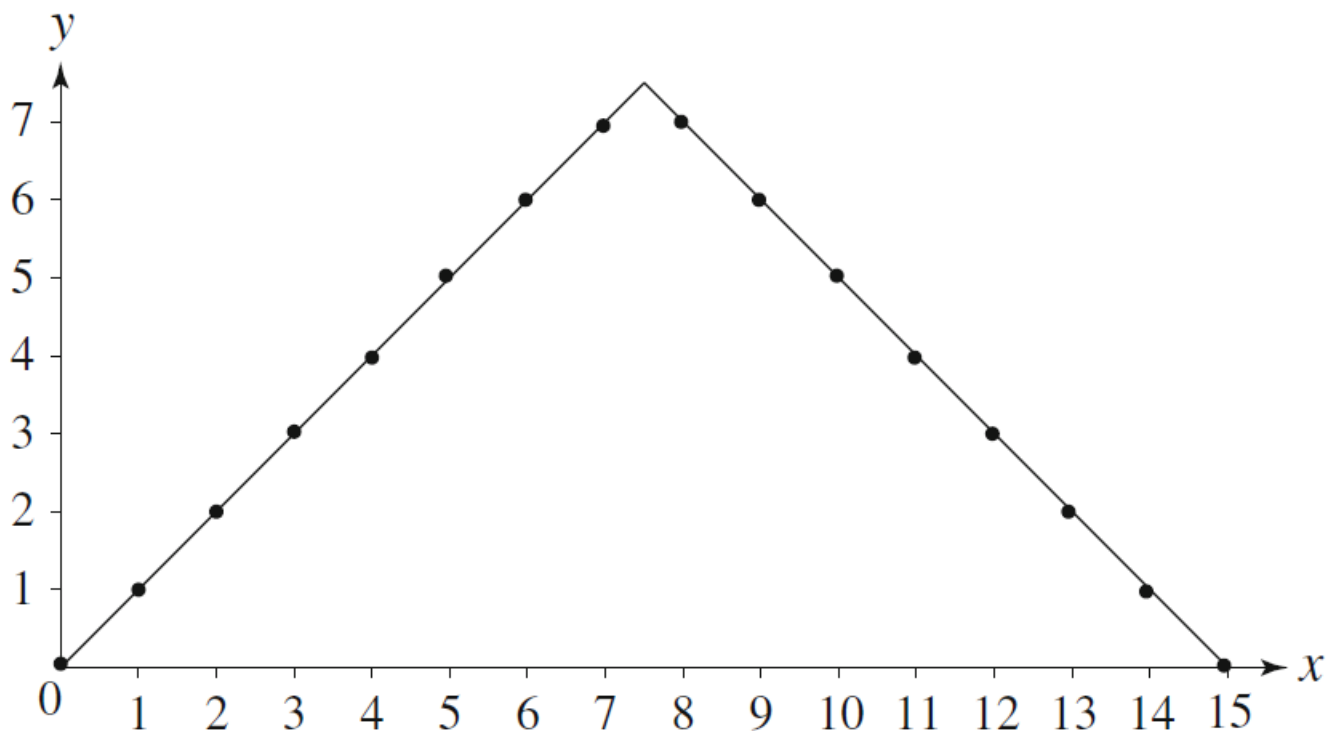
- ◆ Comparison of DCT and DFT-与Fourier比较
 - DFT-离散傅里叶变换

$$F_{\omega} = \sum_{x=0}^7 f_x \cdot e^{-\frac{2\pi i \omega x}{8}}$$

$$F_{\omega} = \sum_{x=0}^7 f_x \cdot \cos\left(\frac{2\pi \omega x}{8}\right) - i \sum_{x=0}^7 f_x \cdot \sin\left(\frac{2\pi \omega x}{8}\right)$$
$$e^{ix} = \cos(x) + i\sin(x)$$

Transform Coding-变换编码

◆ Comparison of DCT and DFT-与Fourier比较



Symmetric extension of the ramp function-对称斜坡函数

Transform Coding-变换编码

◆ Comparison of DCT and DFT-与Fourier比较

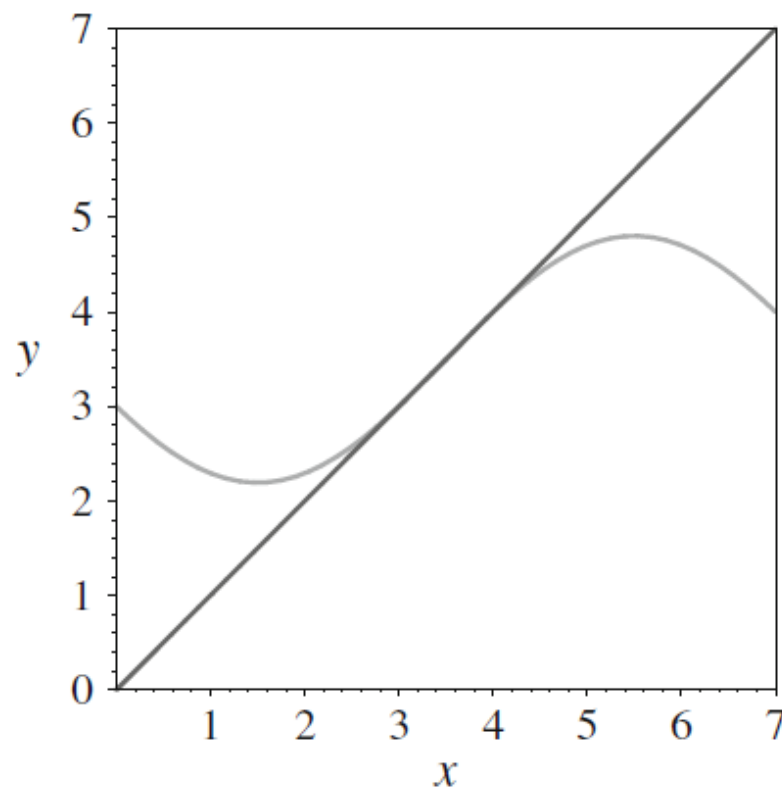
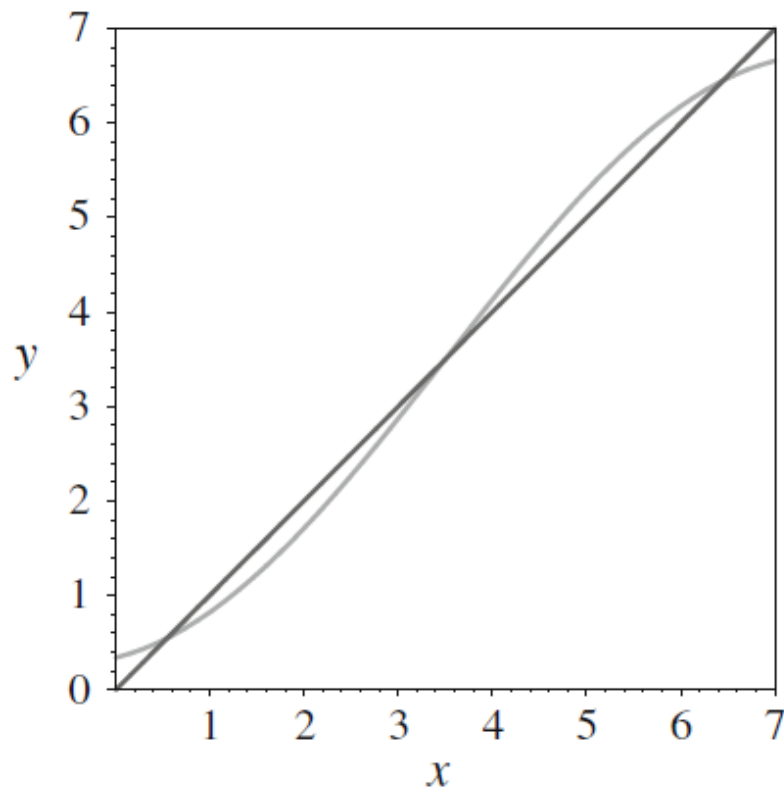
Ramp	DCT	DFT
0	9.90	28.00
1	-6.44	-4.00
2	0.00	9.66
3	-0.67	-4.00
4	0.00	4.00
5	-0.20	-4.00
6	0.00	1.66
7	-0.51	-4.00

DCT and DFT coefficients of the ramp function

DCT前几个系数包含更多的信息

Transform Coding-变换编码

◆ Comparison of DCT and DFT-与Fourier比较



Approximation of the ramp function: (a) 3 Term DCT Approximation, (b) 3 Term DFT Approximation.

Outline of Lecture 08

- ◆ Introduction-简介
- ◆ Distortion Measures-失真度量
- ◆ The Rate-Distortion Theory-比率失真理论
- ◆ Quantization-量化
 - Uniform Scalar Quantization-均匀标量量化
 - Nonuniform Scalar Quantization-非均匀标量量化
 - Vector Quantization-向量量化
- ◆ Transform Coding-变换编码
- ◆ Wavelet-Based Coding-小波编码
- ◆ Experiments-实验

Transform Coding-变换编码

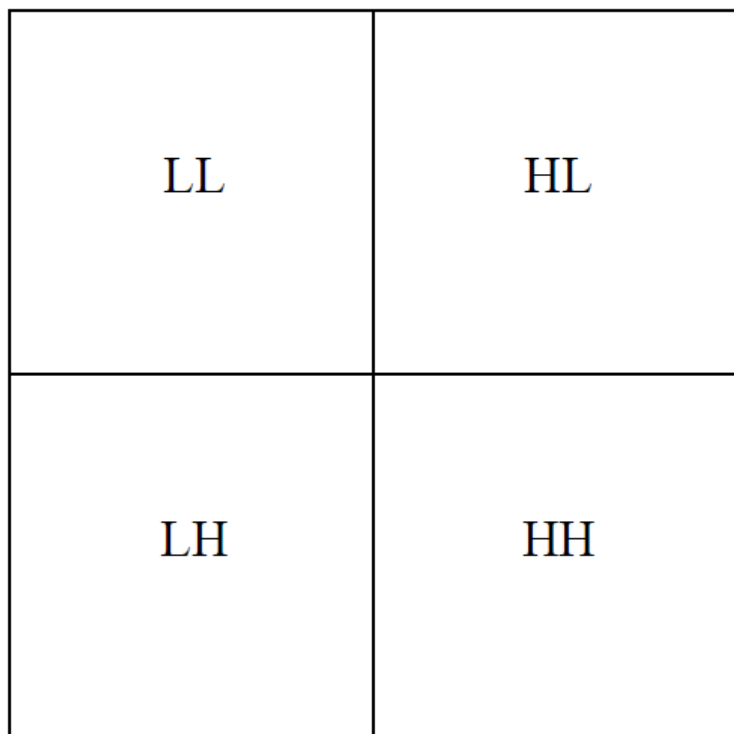
◆ Wavelet-Based Coding-小波编码

- The objective of the wavelet transform is to decompose the input signal into components that are easier to deal with, have *special interpretations*, or have some components that can be thresholded away, for compression purposes-小波变换.
- We want to be able to at least approximately reconstruct the original signal given these components.
- The basis functions of the wavelet transform are localized in both time and frequency.
- There are two types of wavelet transforms: *the continuous wavelet transform* (CWT) and *the discrete wavelet transform* (DWT)-连续和离散小波.

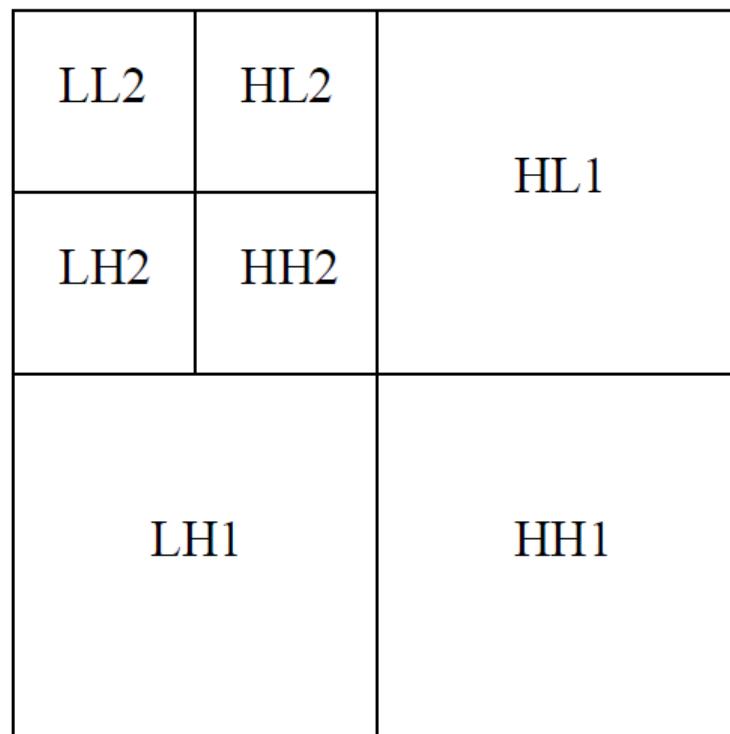
Transform Coding-变换编码

◆ Wavelet-Based Coding-小波编码

- *The discrete wavelet transform (DWT).*



(a)



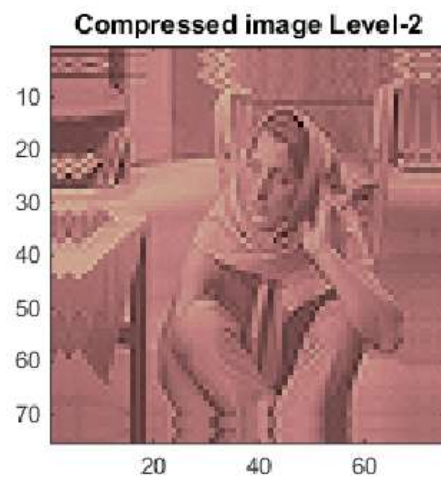
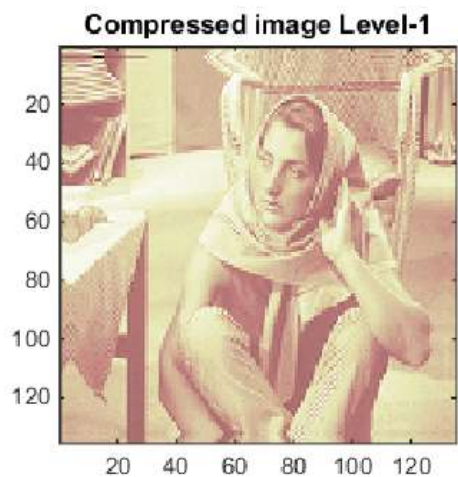
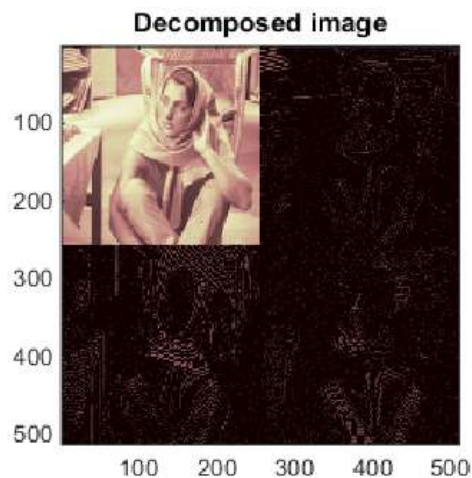
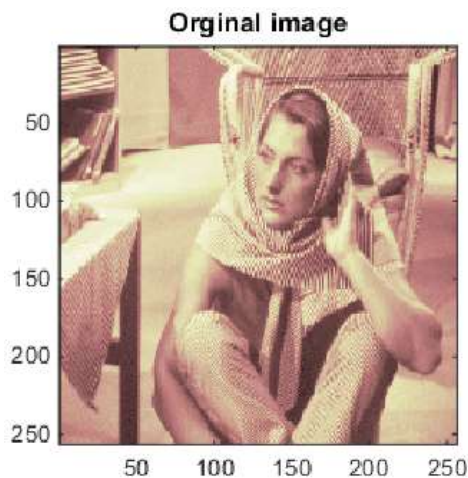
(b)

The two-dimensional discrete wavelet transform (a) One level transform, (b) two level transform.

Transform Coding-变换编码

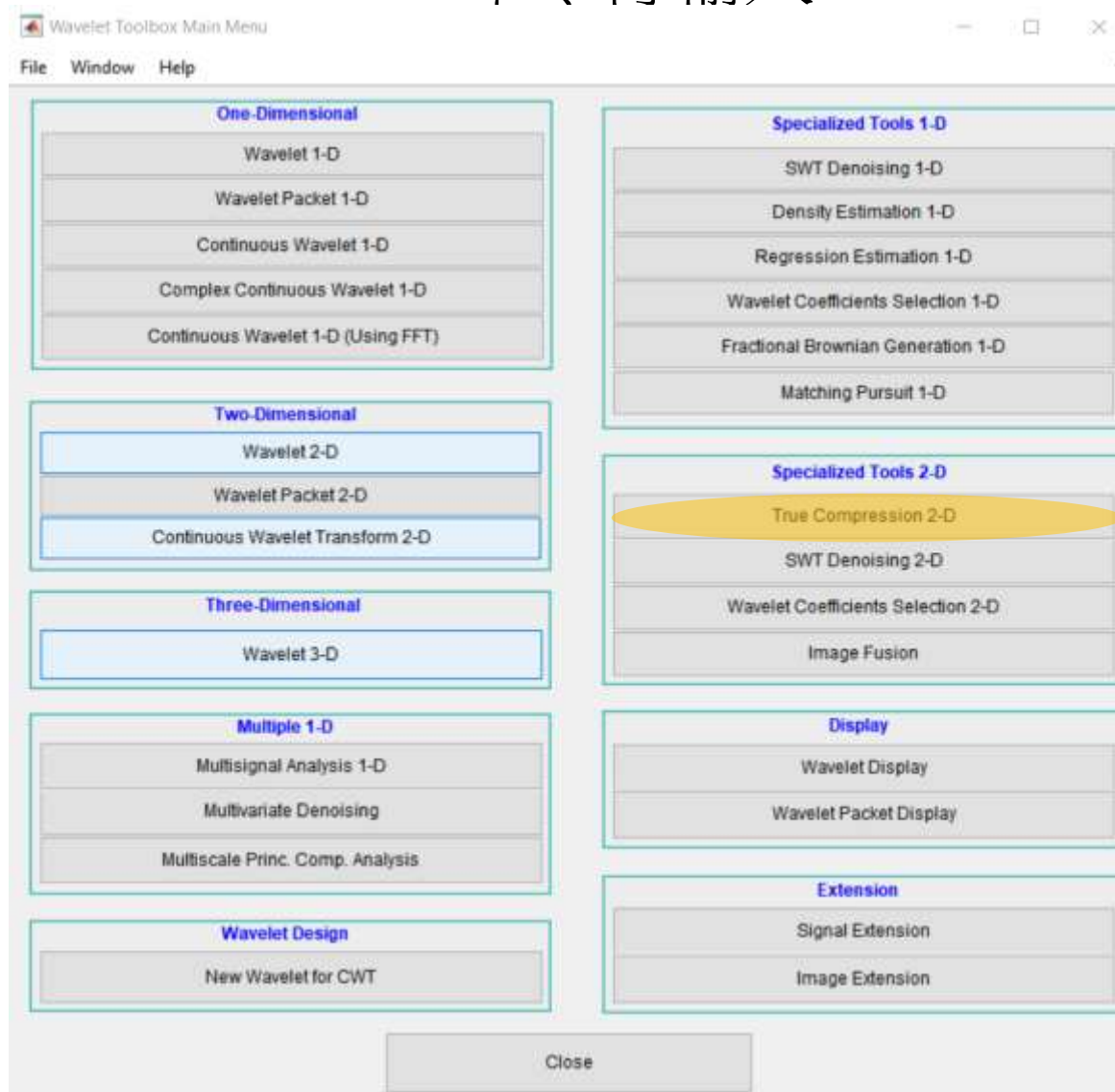
◆ Wavelet-Based Coding-小波编码

- *The discrete wavelet transform (DWT).*



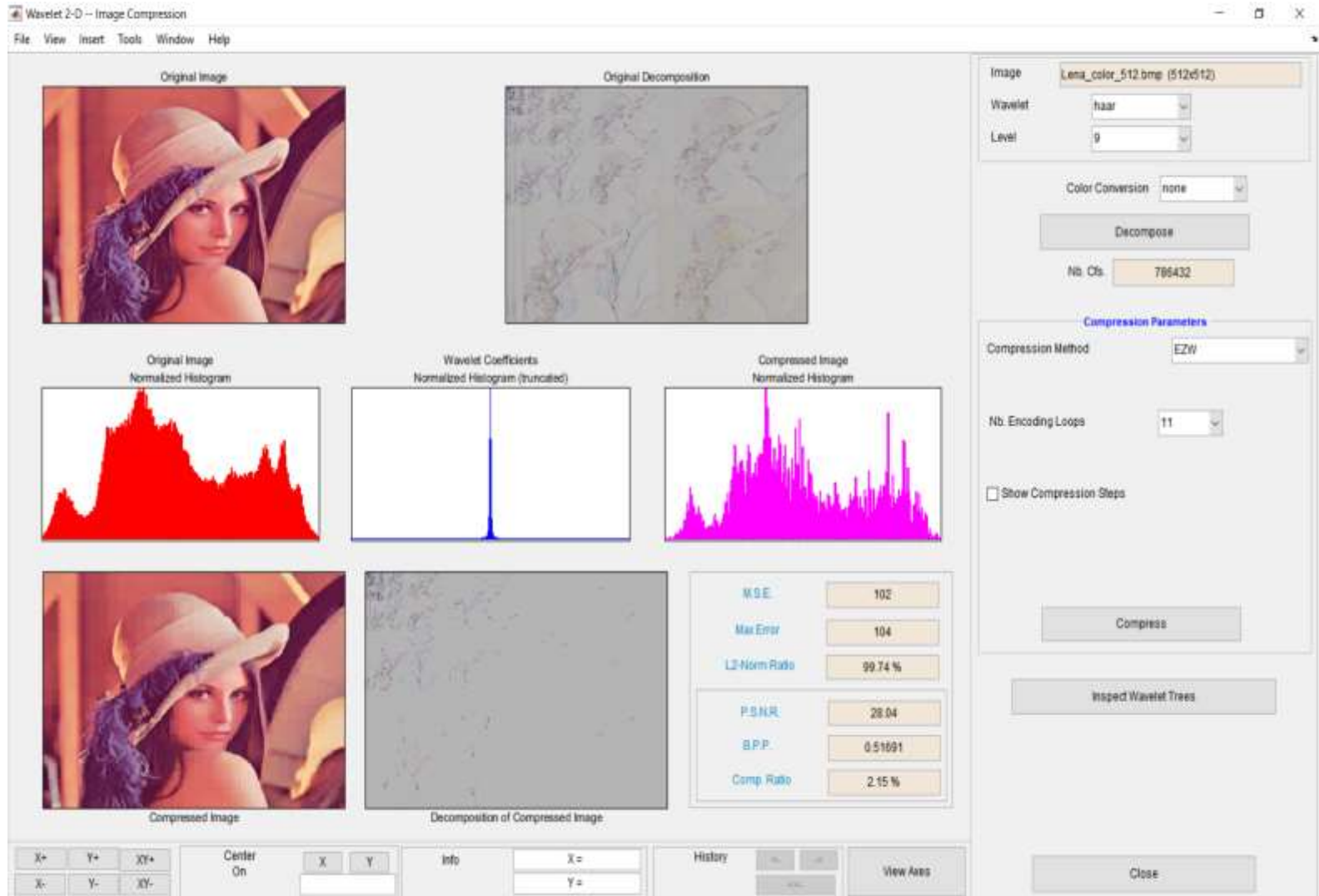
Experiments & Class Assignments

◆ Experiments-Matlab命令行输入: "wavemenu"



Experiments & Class Assignments

◆ Experiments-Matlab命令行输入: "wavemenu"



Experiments & Class Assignments

◆ Experiments

- DCT Coding--*ch08_dct_demo.m*
- Wavelet Coding--*ch08_dwt_demo.m*

◆ Class Assignments

- 1、已知原来的数据为{12 16 16 12 12 8 8 12 }、经过压缩与解压缩之后得到的数据为{12 12 12 8 12 8 12 12}。请分别计算MSE、SNR和PSNR的值，请写出计算过程，其中 $\log_{10}(32) \approx 1.505$, $\log_{10}(19) \approx 1.279$.
- 2、输入信号为 $f(i)=[0 \ 10 \ 20 \ 30 \ 40 \ 50 \ 60 \ 70]$ ，请计算该信号的一维离散余弦变换的 $F(0)$.
- 3、变换编码的基本原理是什么？